# The Classical Measurement Error (MEC) model

#### **Parametrization**

This is an implementation of the classical ME model for a fixed effect. It is best described by an example, let the model be

$$\eta = \beta x + \epsilon$$

where  $\eta$  is the linear predictor,  $\beta$  the effect of the true covariate x with zero mean Gaussian noise  $\epsilon$ . The issue is that x is not observed directly, but only through w, where

$$w = x + u$$

where u is zero mean Gaussian noise. Even though this setup is possible to implement using basic features ("copy" and multiple likelihoods), we provide the following model which reparametrizes the above,

$$\eta = \nu + \epsilon$$

where  $\nu = \beta x$  has the correct distribution depending on various parameters:  $\beta$  has prior  $\pi(\beta)$ , and x is apriori  $\mathcal{N}(\mu_x I, \tau_x I)^1$ . The error is apriori  $u \sim \mathcal{N}(0, \tau_u \mathbf{D})$ , where  $\tau_u$  is the observational precision of the error  $\operatorname{Prec}(u|x)$ ) with possible heteroscedasticy, encoded in the entries  $d_i$  of the diagonal matrix  $\mathbf{D}$ . The vector s contains the fixed scalings  $s = (d_1, \ldots, d_n)$  (with n the number of data points).

# Hyperparameters

This model has 4 hyperparameters,  $\theta = (\theta_1, \theta_2, \theta_3, \theta_4)$  where  $\theta_2$ ,  $\theta_3$  and  $\theta_4$  are default set to be fixed (ie defined to be known). The values of  $\theta_2$ ,  $\theta_3$  and  $\theta_4$  are set to mimic a classical fixed effect, so they will always make sense. To achieve the ME model, please use the appropriate choices for (some of) these parameters!

The hyperparameter specification is as follows:

$$\theta_1 = \beta$$

and the prior is defined on  $\theta_1$ ,

$$\theta_2 = \log(\tau_u)$$

and the prior is defined on  $\theta_2$ ,

$$\theta_3 = \mu_x$$

and the prior is defined on  $\theta_3$ ,

$$\theta_4 = \log(\tau_{\rm x})$$

and the prior is defined on  $\theta_4$ .

### Specification

The MEC is specified inside the f() function as

The w are the observed values of the true but unknown covariates x, with the assumption, that if two or more elements of w are *identical*, then they refer to the same element in the true covariate x. If data points with identical w values belong to different x values (e.g., different individuals), please add a tiny random value to w to make this difference obvious to the model.

The fixed scaling of the observational precision is given in argument scale. If the argument scale is not given, then s is set to 1.

<sup>&</sup>lt;sup>1</sup>Note: The second argument in  $\mathcal{N}(,)$  is the precision not the variance.

# Hyperparameter specification and default values

```
doc Classical measurement error model
hyper
    theta1
        hyperid 2001
        name beta
        short.name b
        prior gaussian
        param 1 0.001
        initial 1
        fixed FALSE
         to.theta function(x) x
        from.theta function(x) x
    theta2
        hyperid 2002
        name prec.u
        short.name prec
        prior loggamma
        param 1 1e-04
        initial 9.21034037197618
        fixed TRUE
         to.theta function(x) log(x)
        from.theta function(x) exp(x)
    theta3
        hyperid 2003
        name mean.x
        short.name mu.x
        prior gaussian
        param 0 1e-04
        initial 0
        fixed TRUE
         to.theta function(x) x
        from.theta function(x) x
    theta4
        hyperid 2004
        name prec.x
        short.name prec.x
        prior loggamma
        param 1 10000
        initial -9.21034037197618
        fixed TRUE
         to.theta function(x) log(x)
```

from.theta function(x) exp(x)

```
constr FALSE
nrow.ncol FALSE
augmented FALSE
aug.factor 1
aug.constr
n.div.by
n.required FALSE
set.default.values FALSE
pdf mec
Example
n = 100
beta = 4
prec.y = 1
prec.u = 1
prec.x = 1
## true unobserved covariate
x = rnorm(n, sd = 1/sqrt(prec.x))
## the observed covariate with heteroscedastic scaling
s = runif(n,min=0.5,max=2)
w = x + rnorm(n, sd = 1/sqrt(prec.u*s))
## regression model using the unobserved 'x'
y = 1 + beta*x + rnorm(n, sd = 1/sqrt(prec.y))
## prior parameters
prior.beta = c(0, 0.0001)
prior.prec.u = c(10, 9)
prior.prec.x = c(10, 9)
prior.prec.y = c(10, 9)
formula = y ~ 1 +
f(w, model="mec", scale=s, values=w,
    hyper = list(
        beta = list(
            prior = "gaussian",
            param = prior.beta,
            fixed = FALSE
        ),
        prec.u = list(
            prior = "loggamma",
            param = prior.prec.u,
            initial = log(prec.u),
            fixed = FALSE
        ),
```

```
prec.x = list(
            prior = "loggamma",
            param = prior.prec.x,
            initial = log(prec.x),
            fixed = FALSE
        ),
        mean.x = list(
            prior = "gaussian",
            initial = 0,
            fixed=TRUE
        )
    )
)
r = inla(formula,
    data = data.frame(y, w, s),
    family = "gaussian",
    control.family = list(
        hyper = list(
            prec = list(param = prior.prec.y,
                initial = log(prec.y),
                fixed=FALSE
        )
    )
)
summary(r)
```

### Notes

- INLA provides the posteriors of  $\nu_i = \beta x_i$  and NOT  $x_i$ .
- The posteriors of  $\nu_i$  come (default) in the order given by the sorted (from low to high) values of w. The entry \$ID gives the mapping.
- The option scale defines the scaling in the same order as argument values. It is therefore adviced to also give argument values when scale is used to be sure that they are consistent.