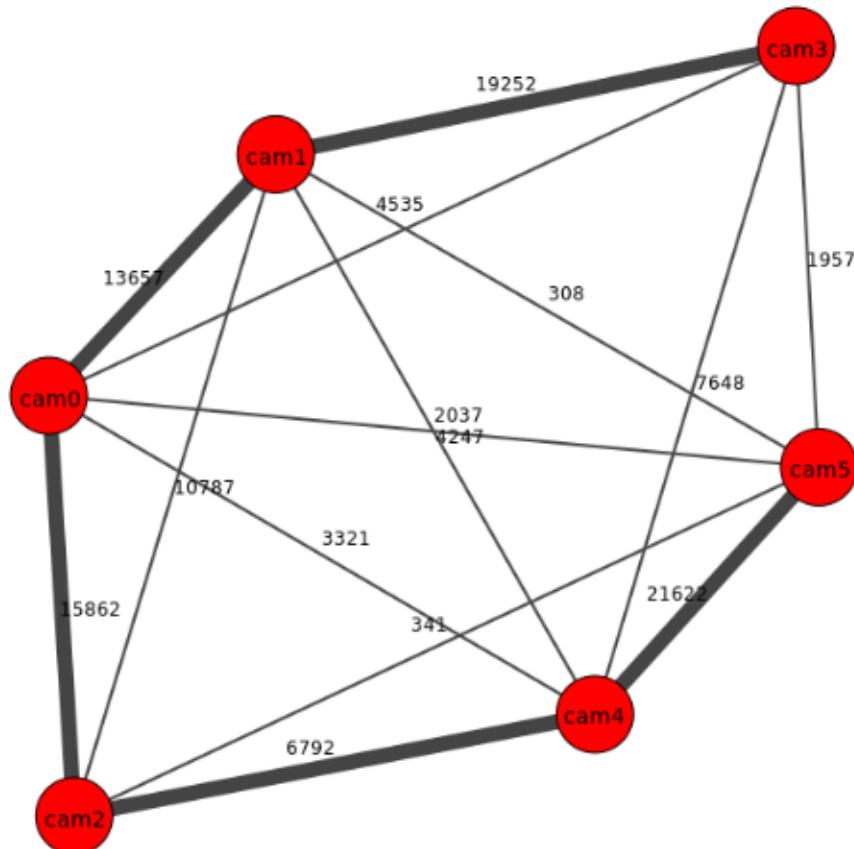
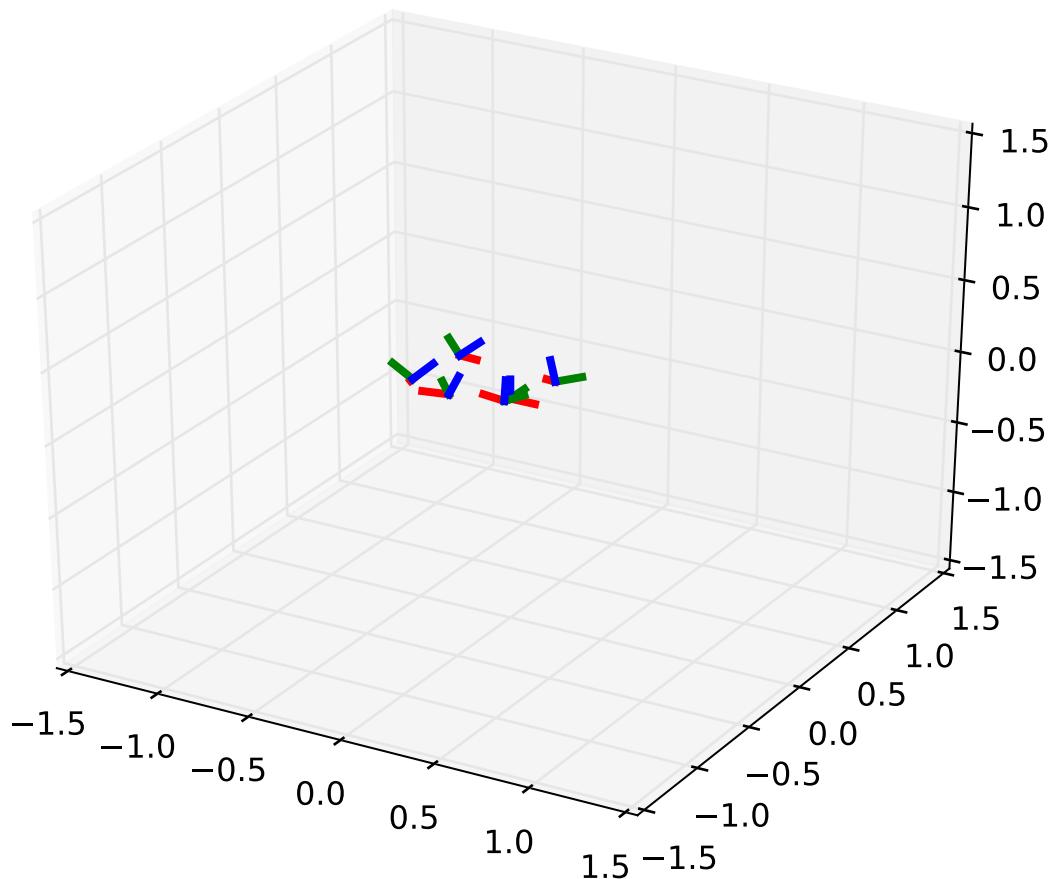


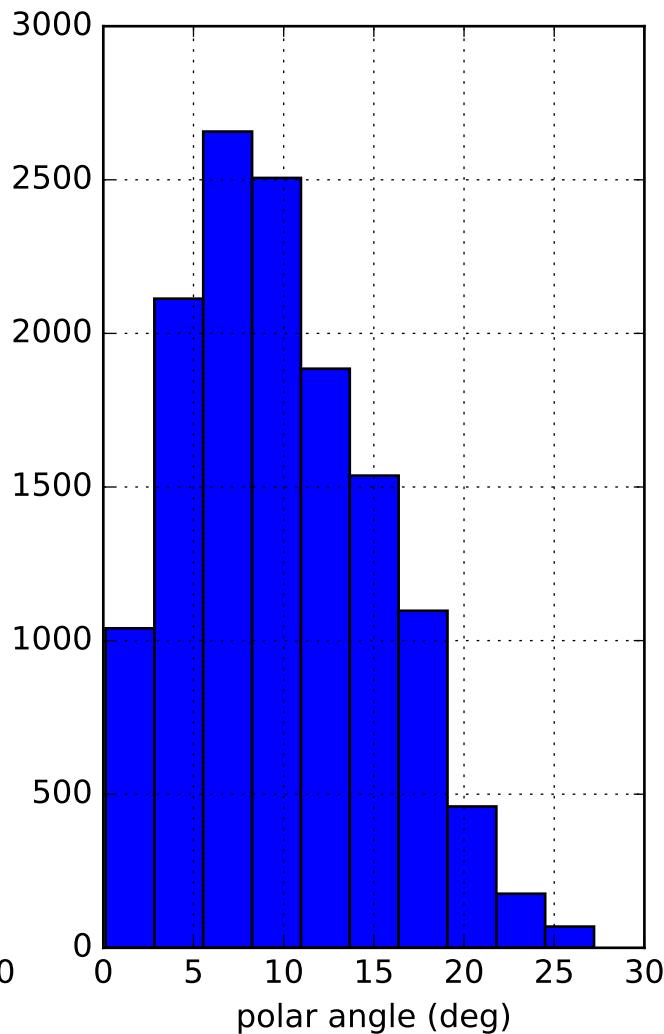
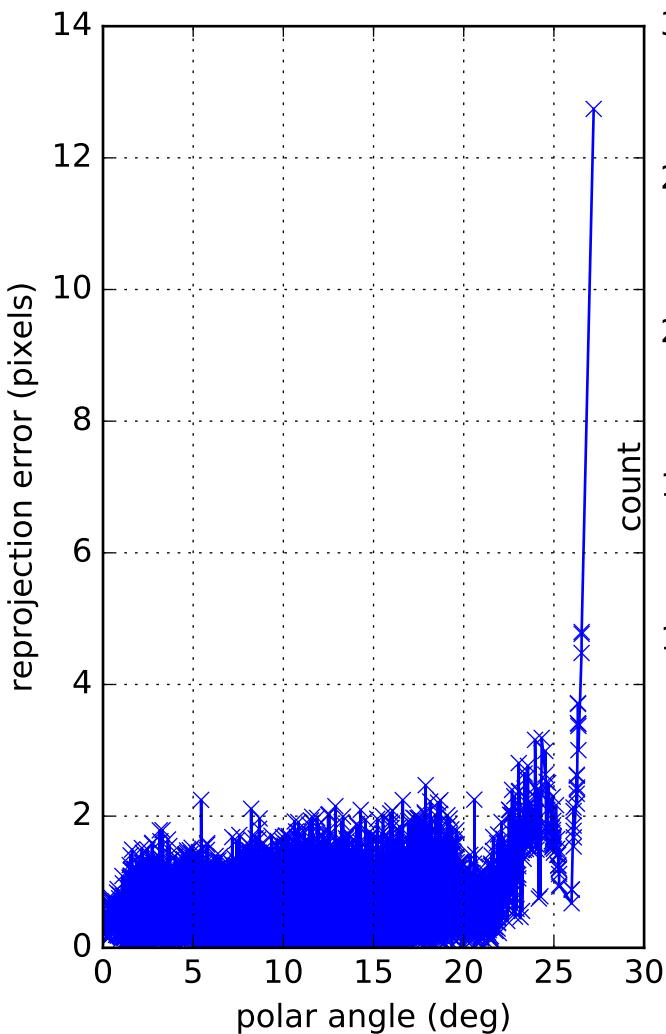
Inter-camera observations graph (edge weight=#mutual obs.)



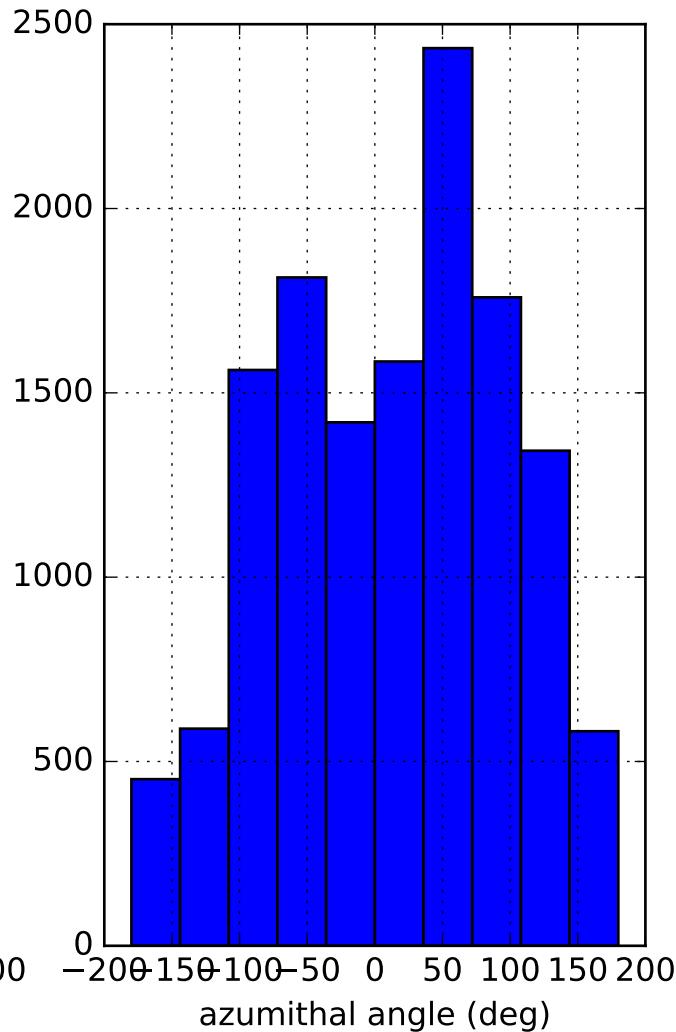
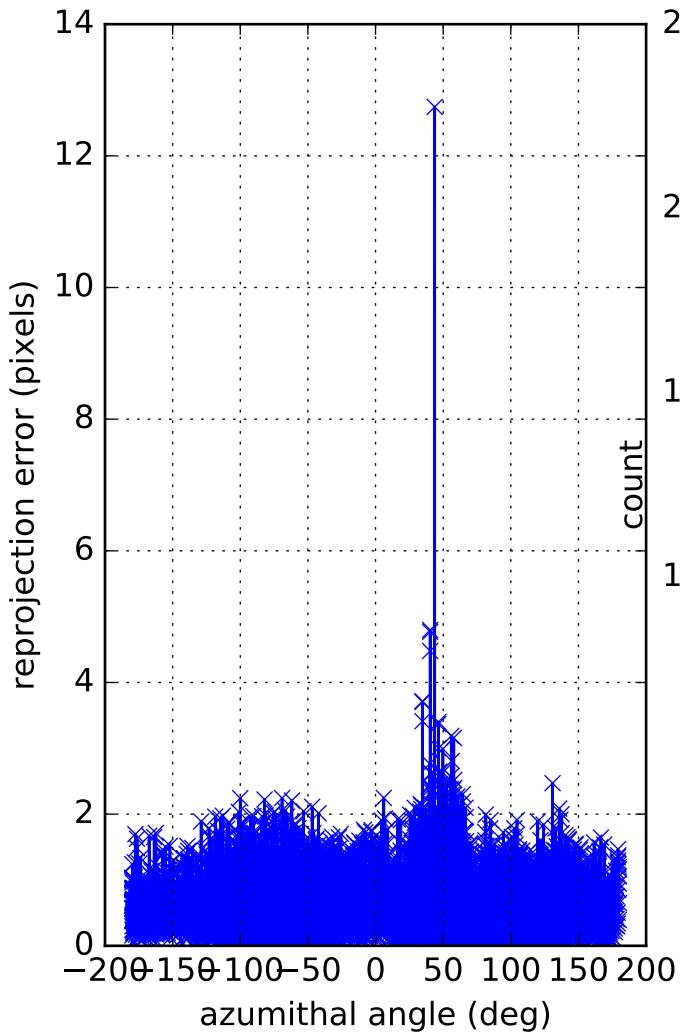
camera system



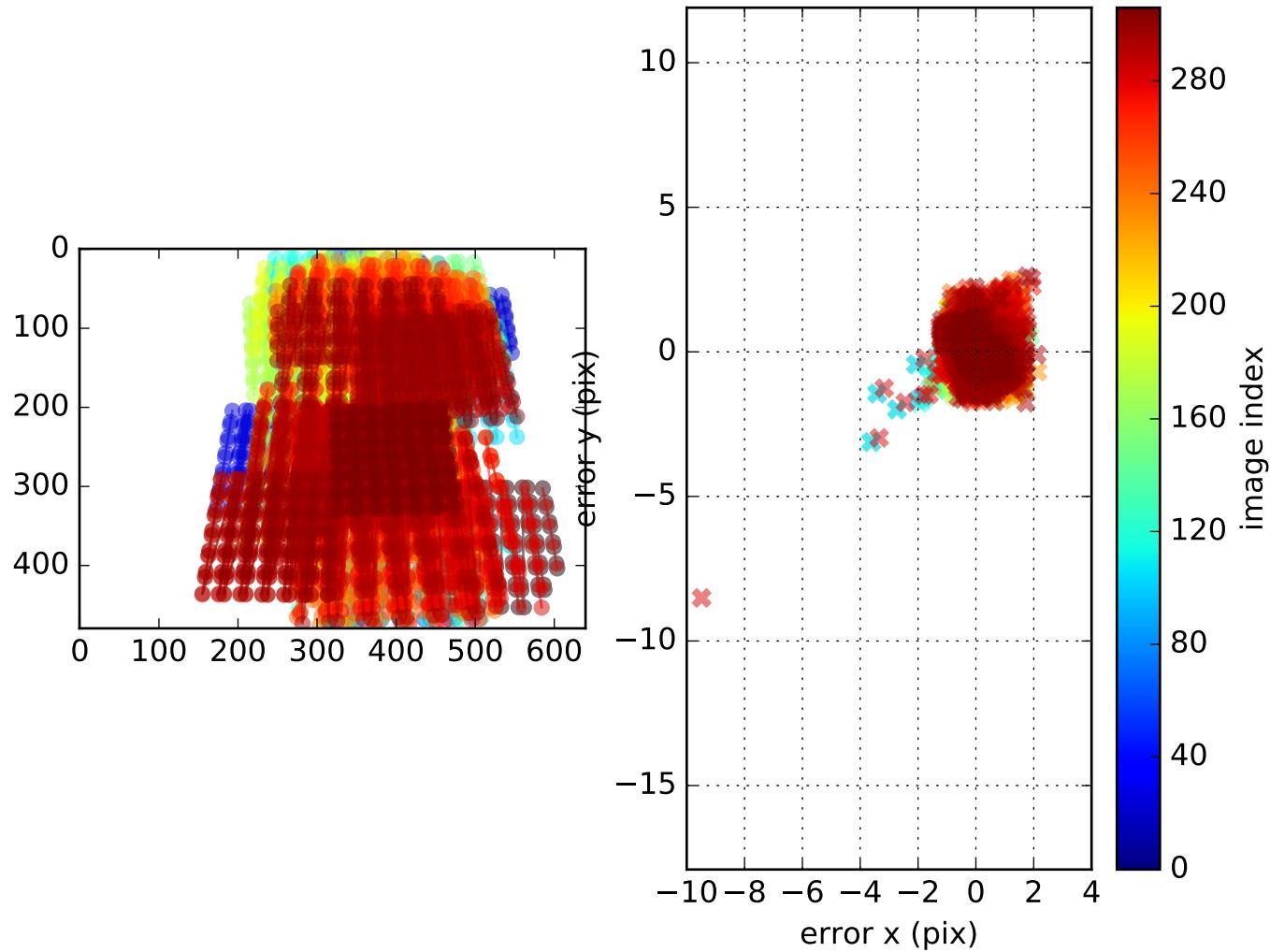
cam0: polar error



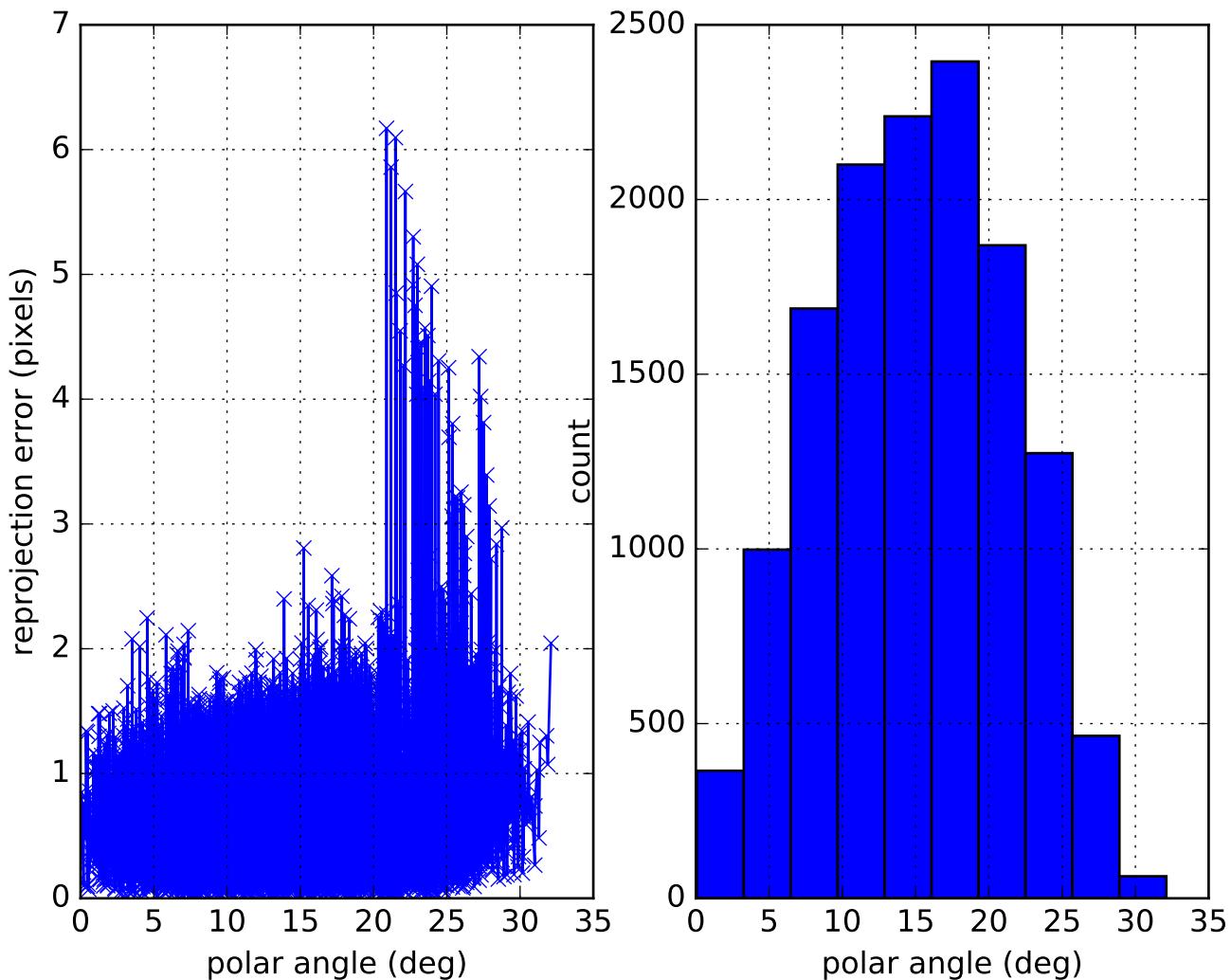
cam0: azimuthal error



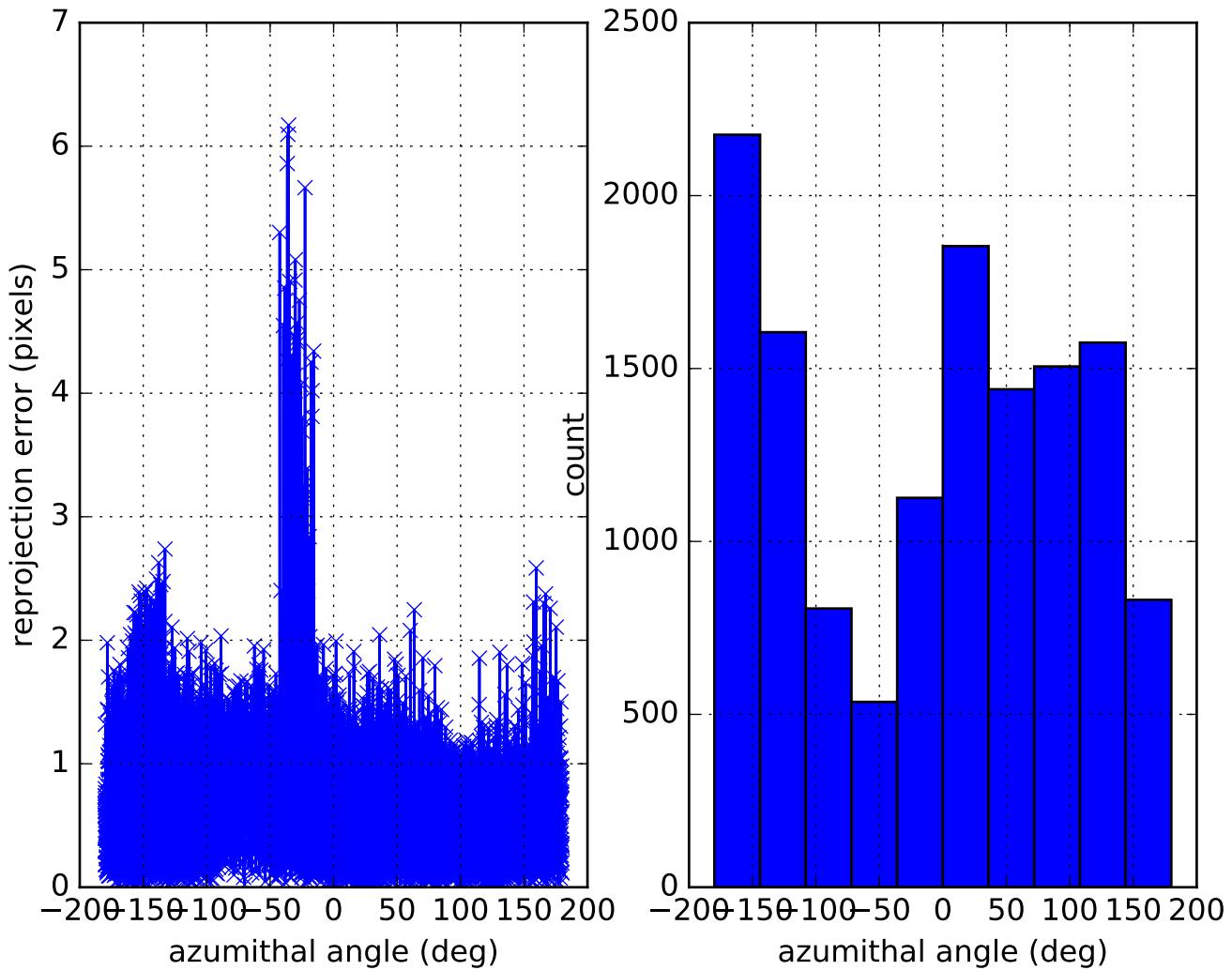
cam0: reprojection errors



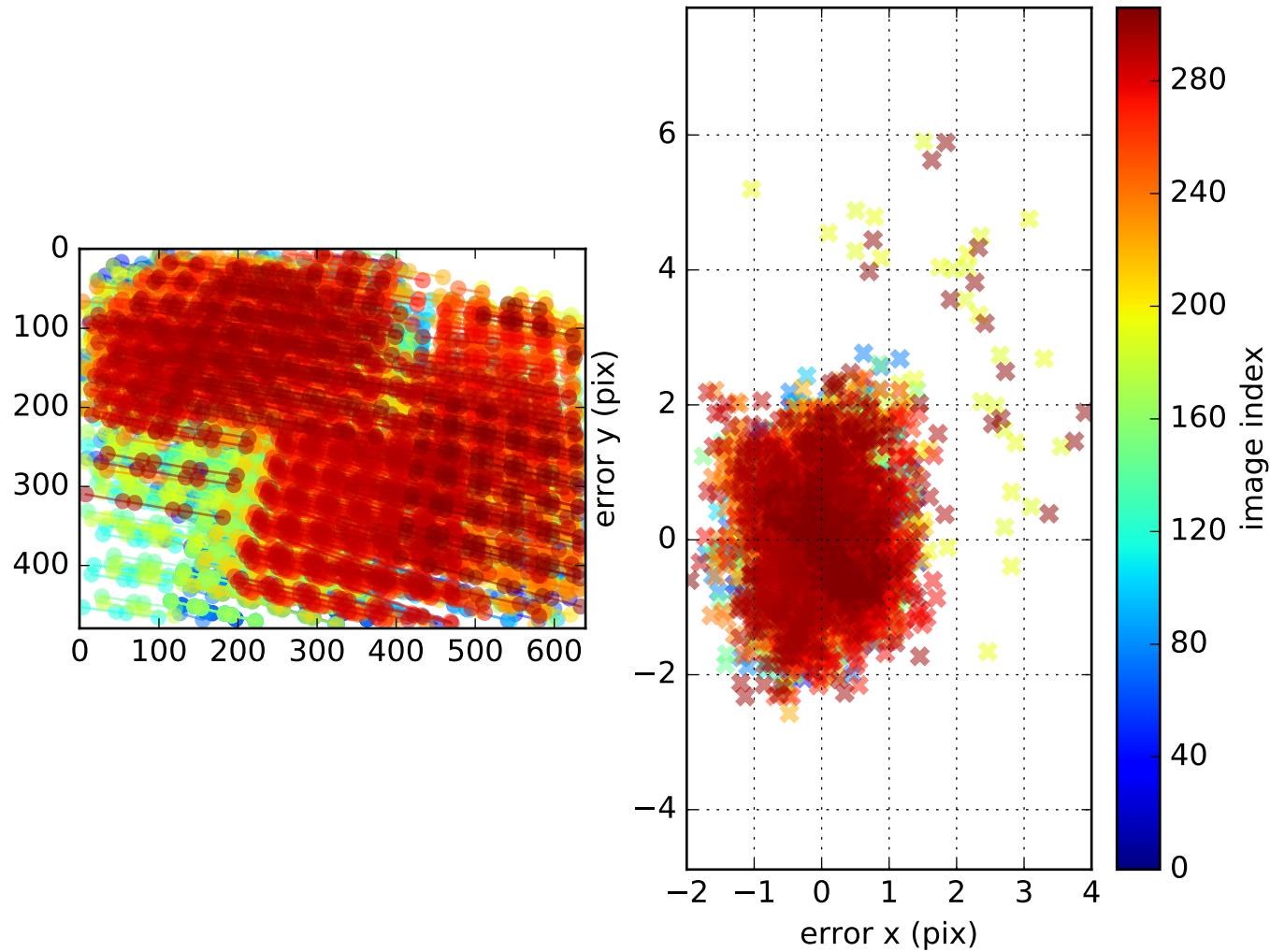
cam1: polar error



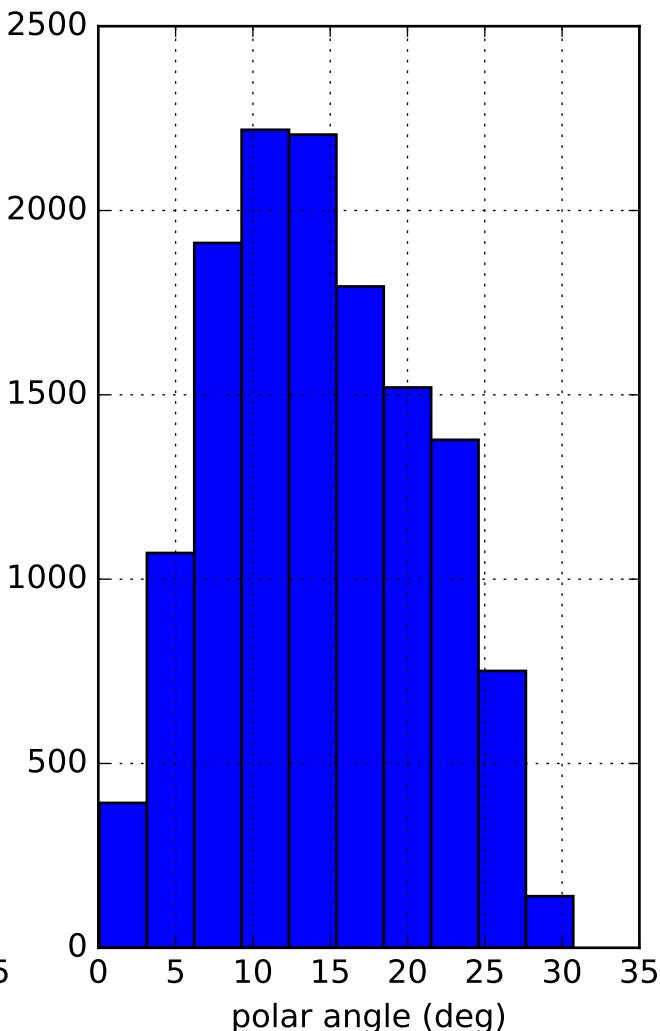
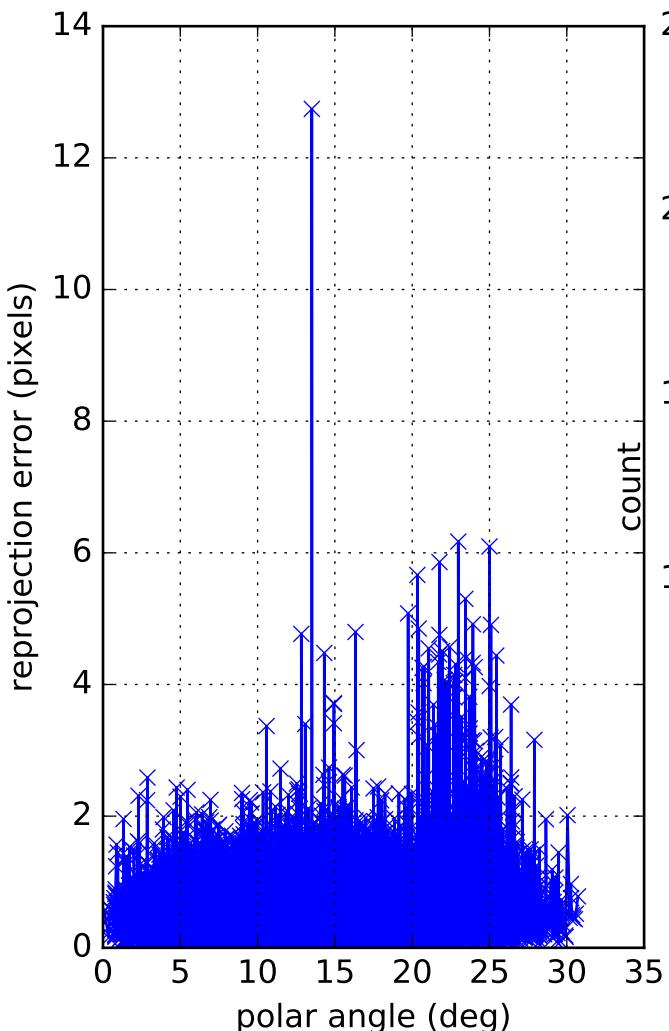
cam1: azimuthal error



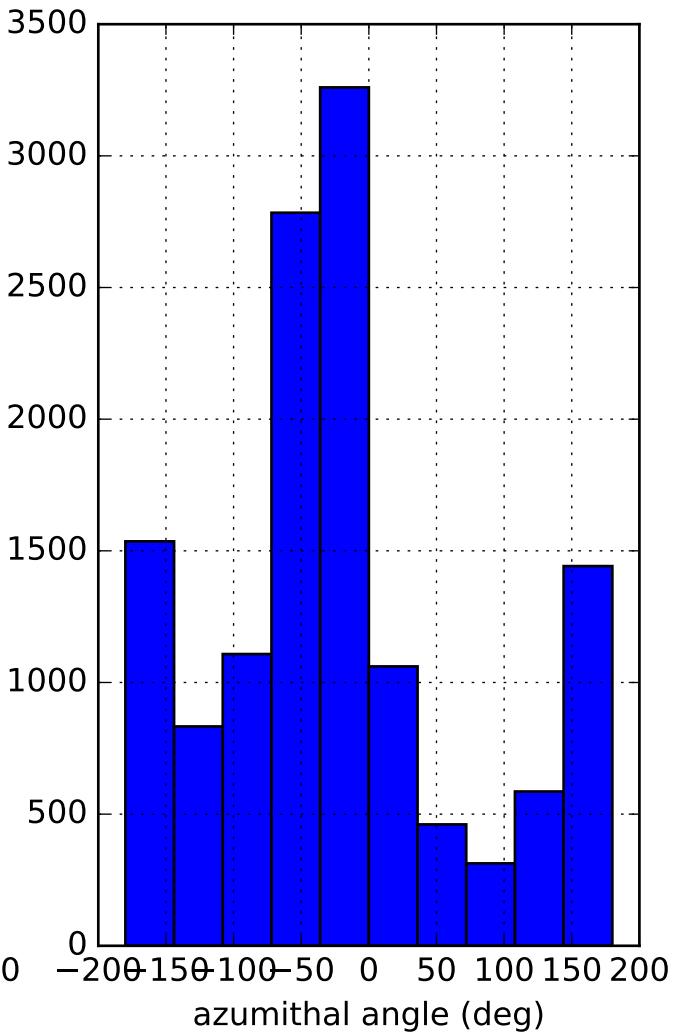
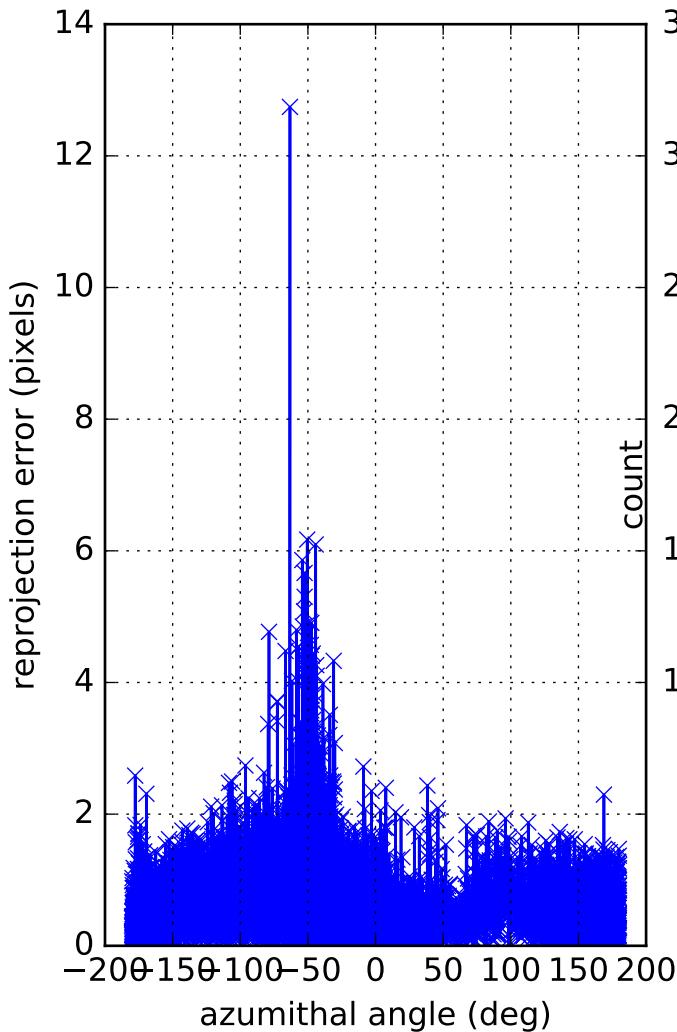
cam1: reprojection errors



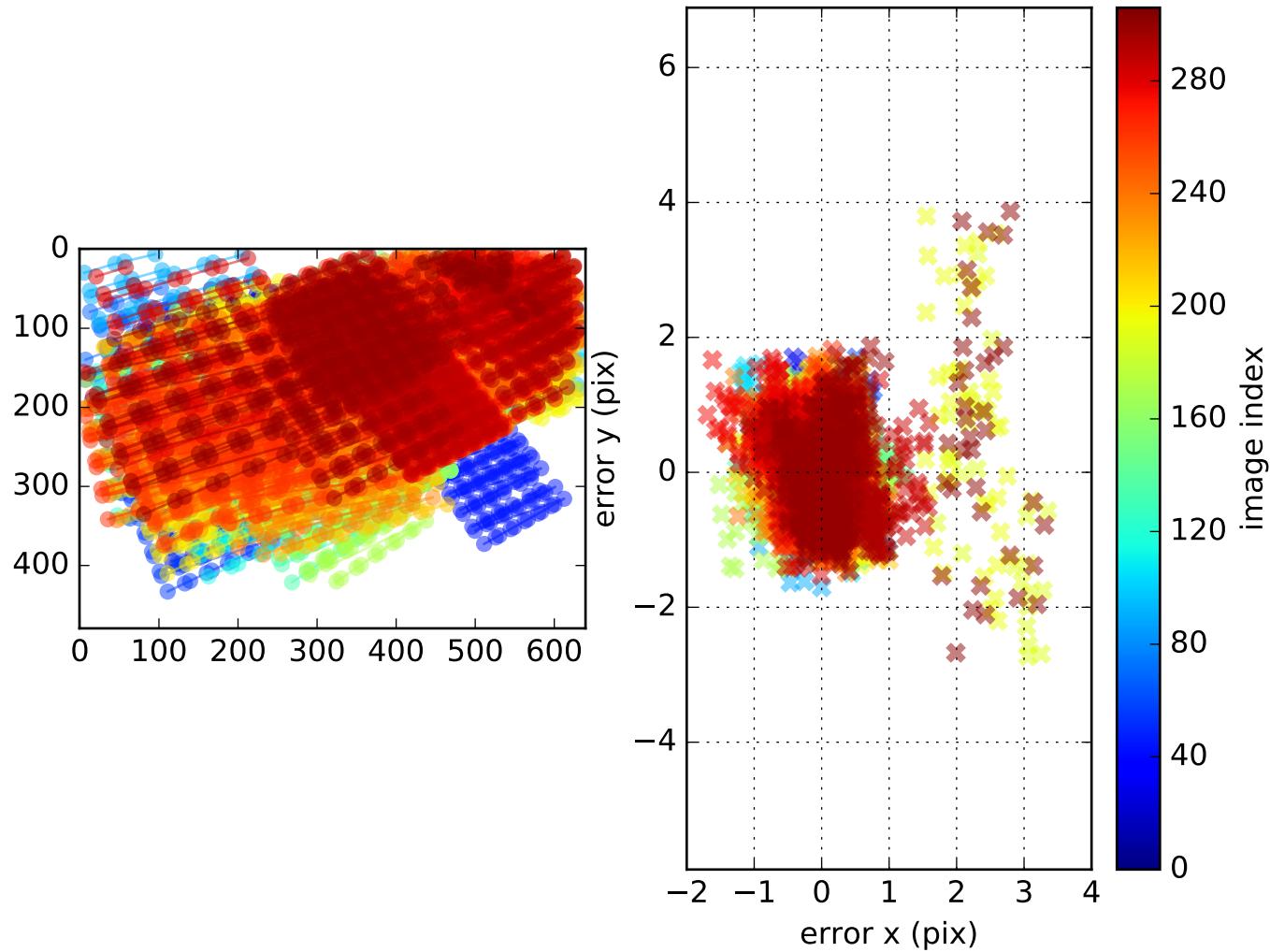
cam2: polar error



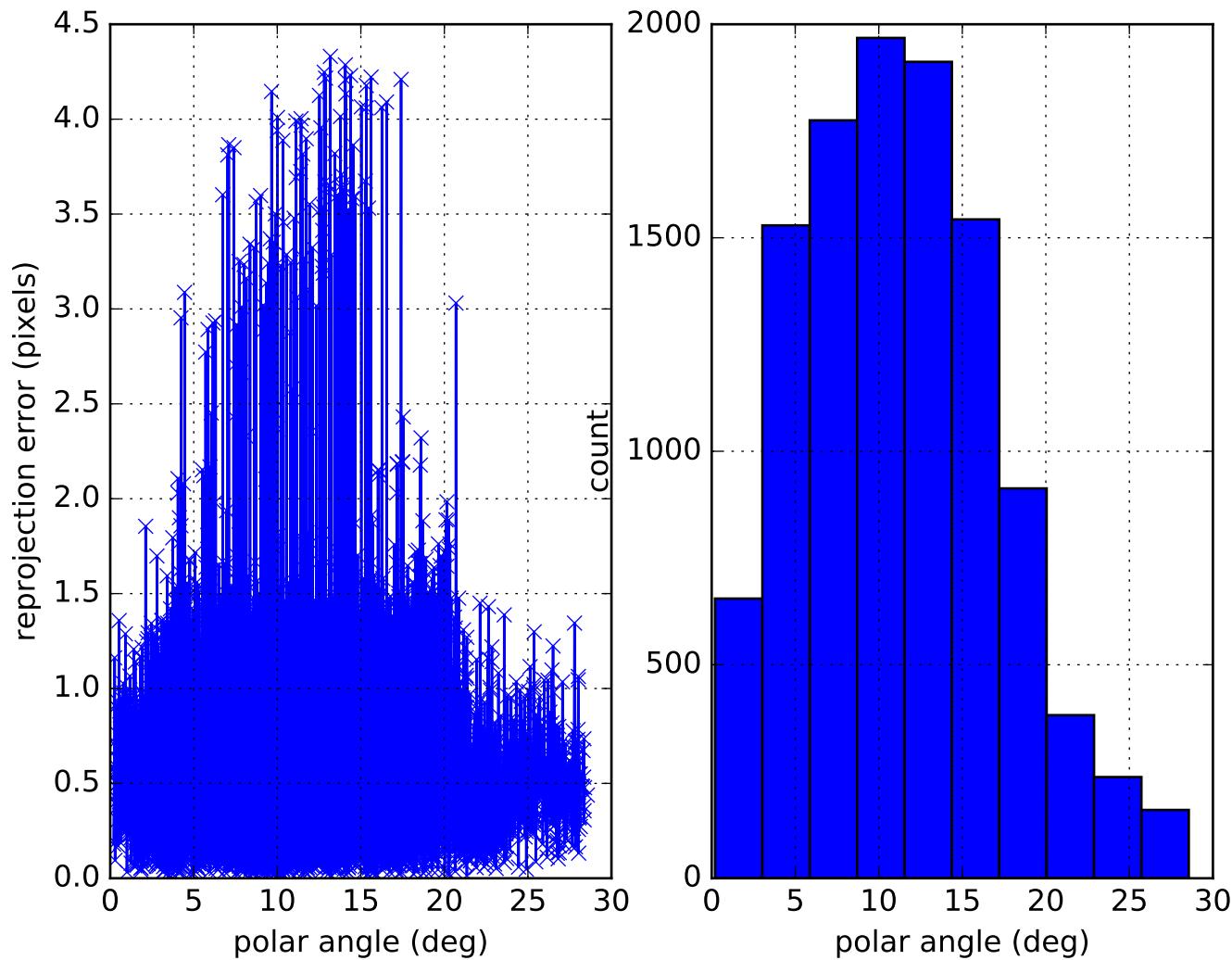
cam2: azimuthal error



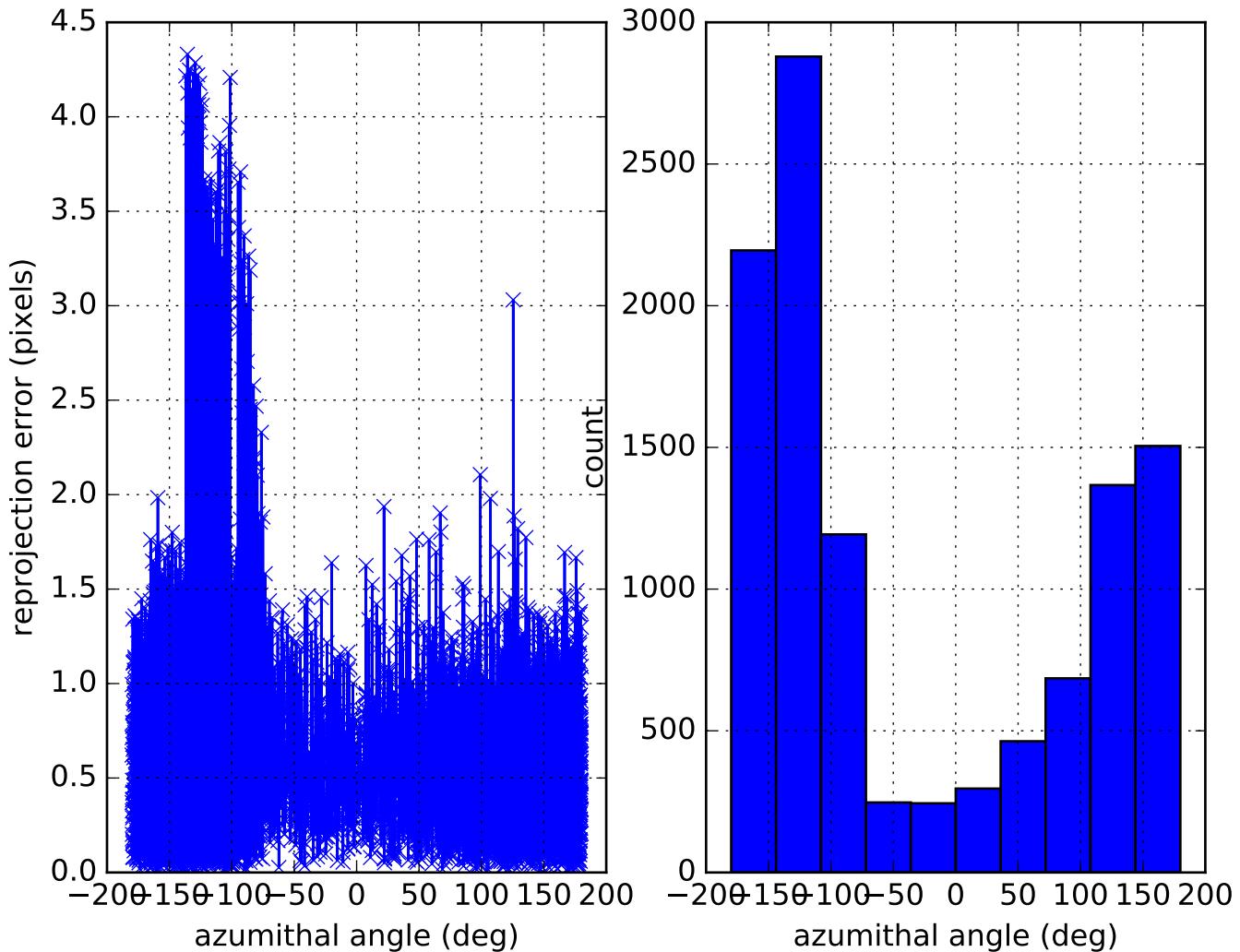
cam2: reprojection errors



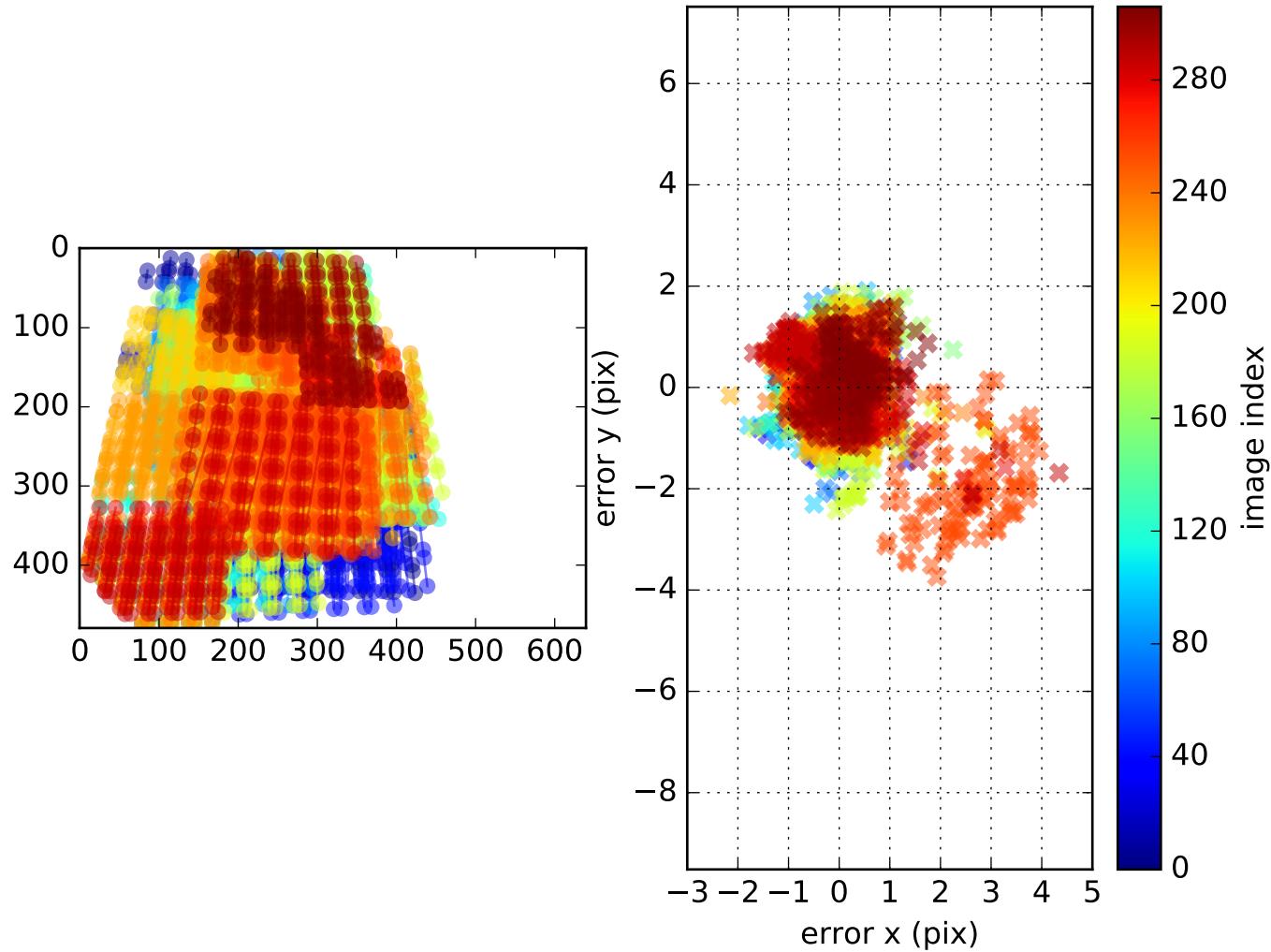
cam3: polar error



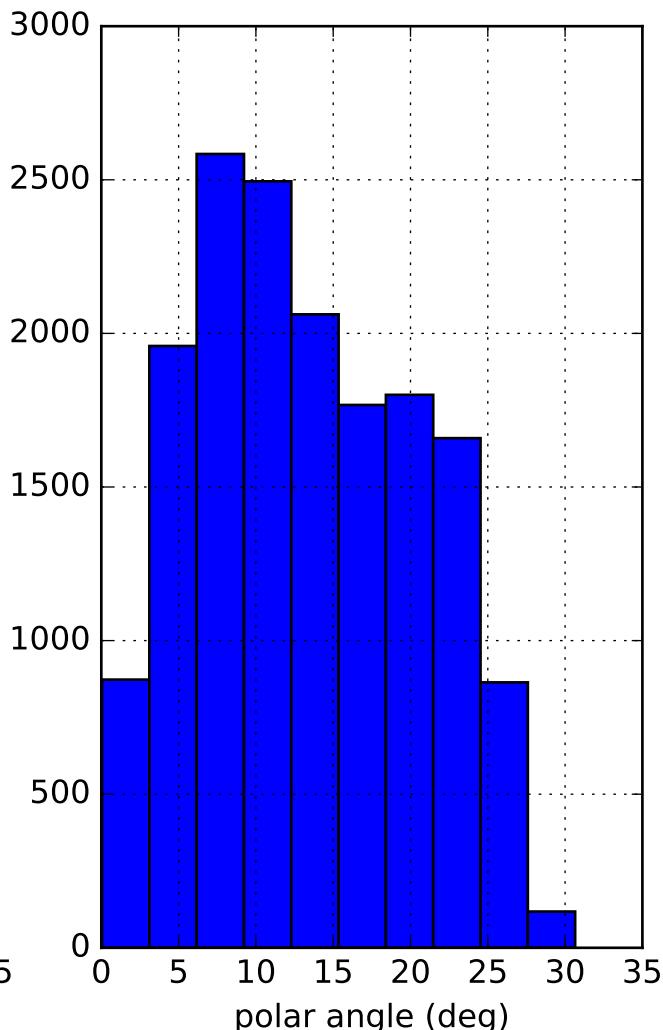
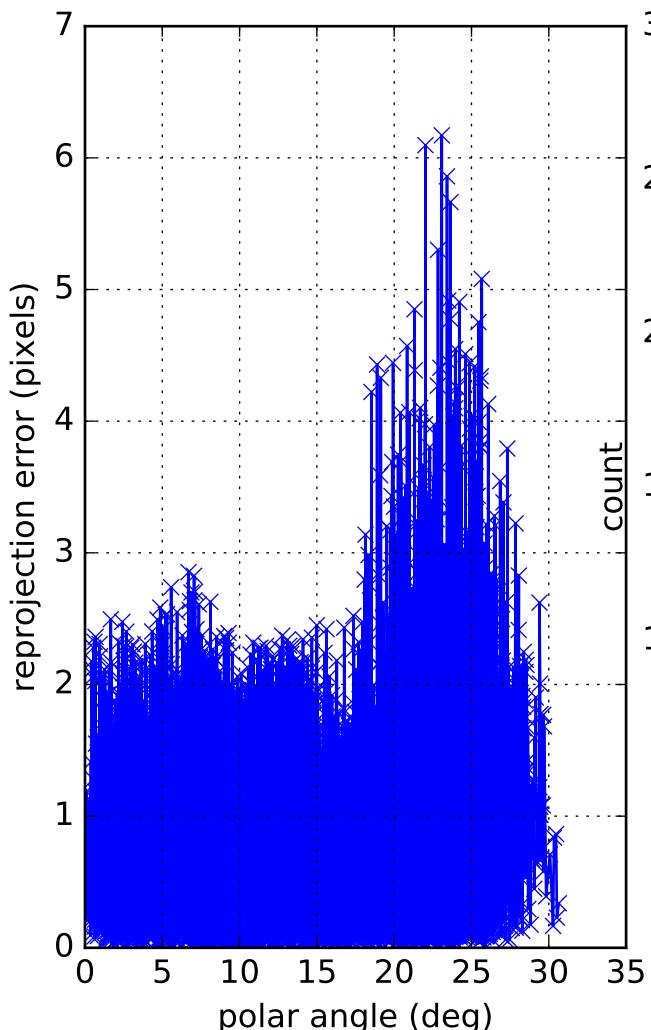
cam3: azimuthal error



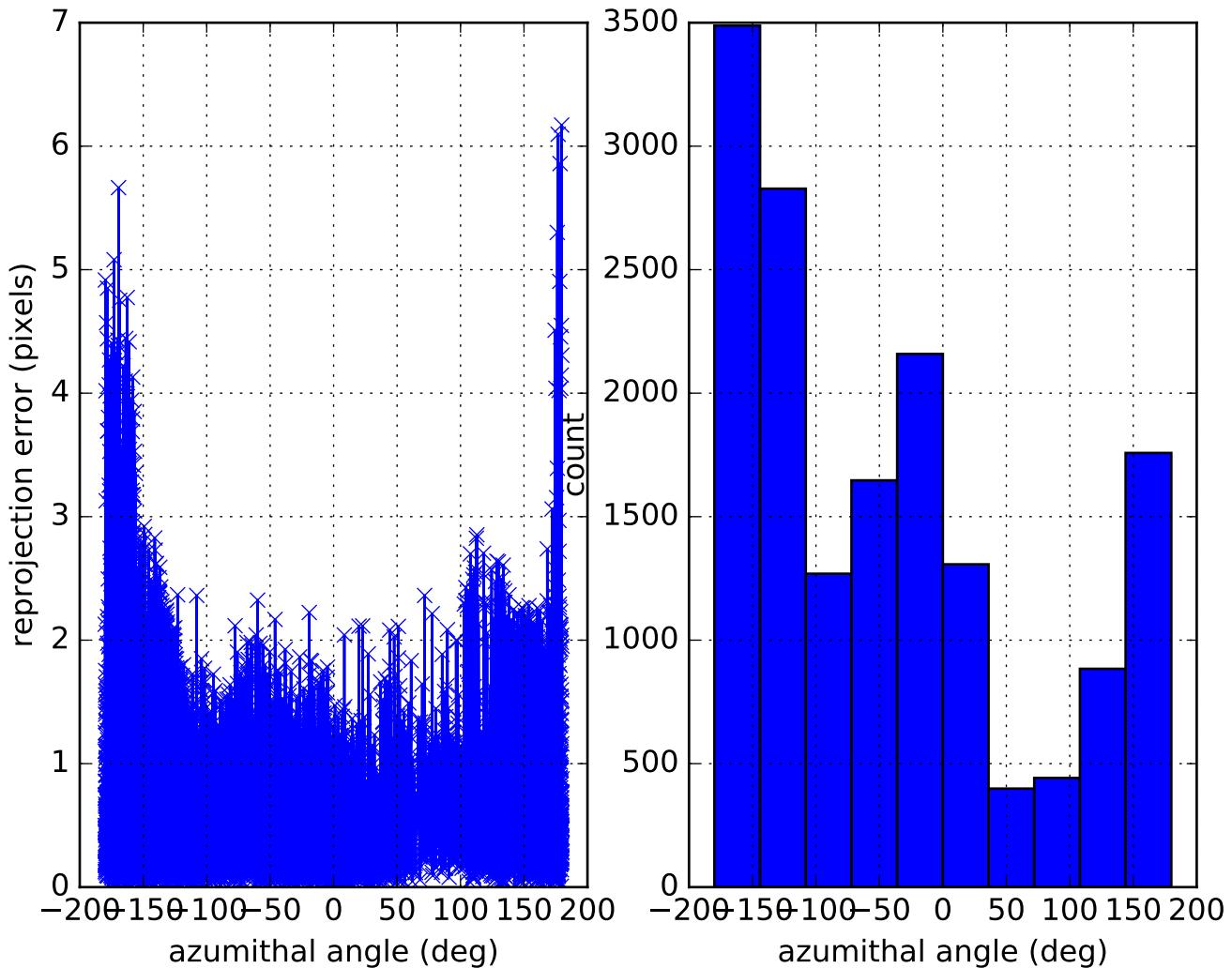
cam3: reprojection errors



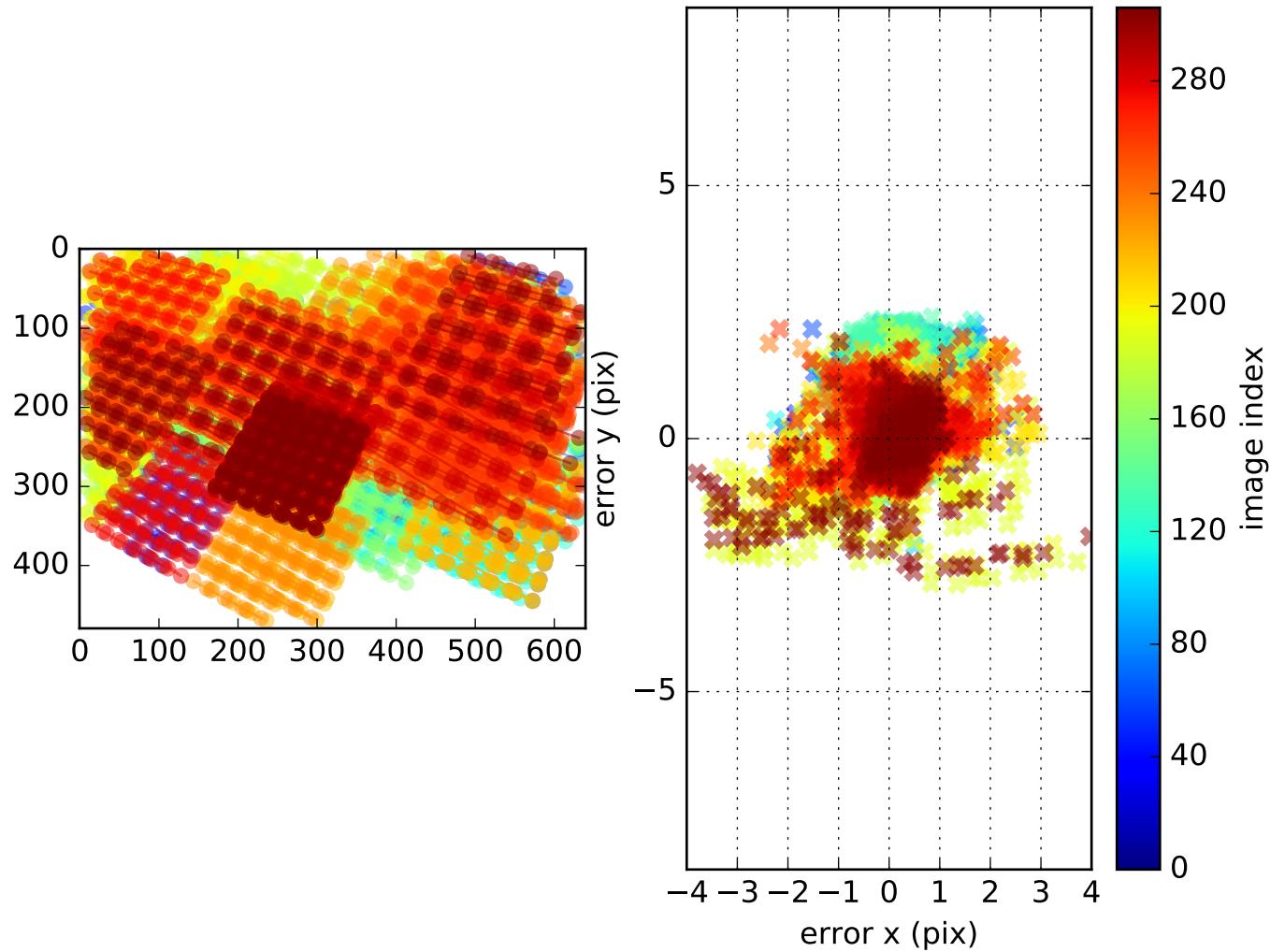
cam4: polar error



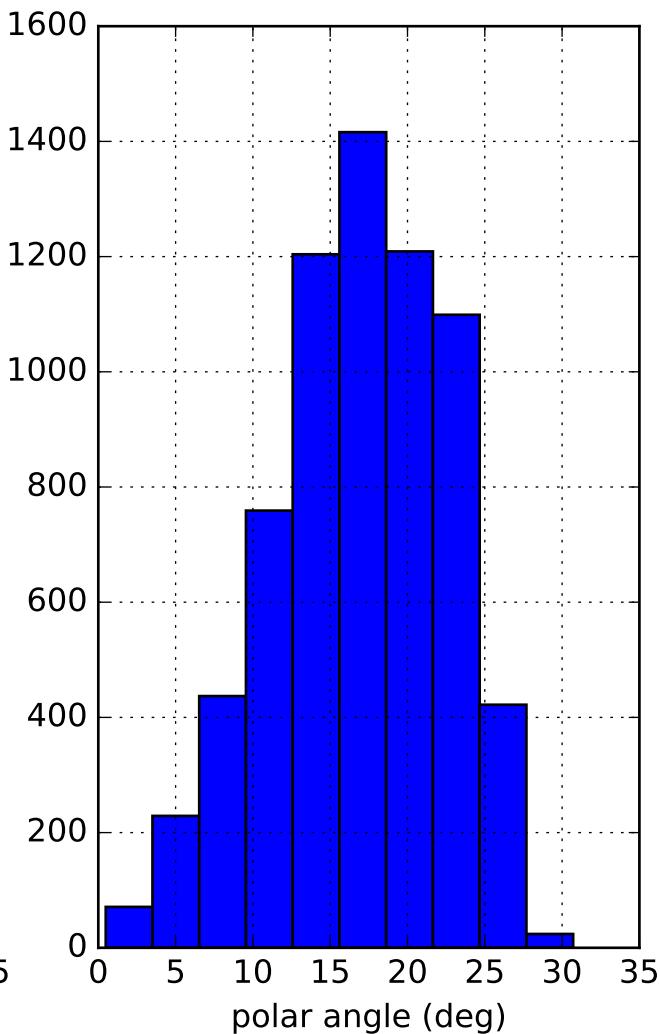
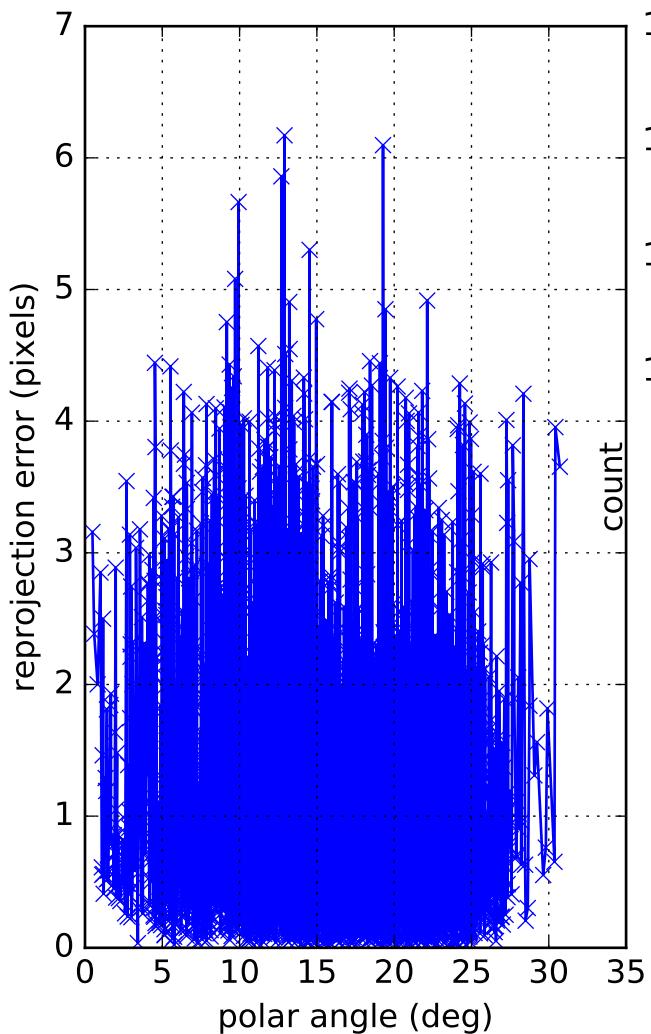
cam4: azimuthal error



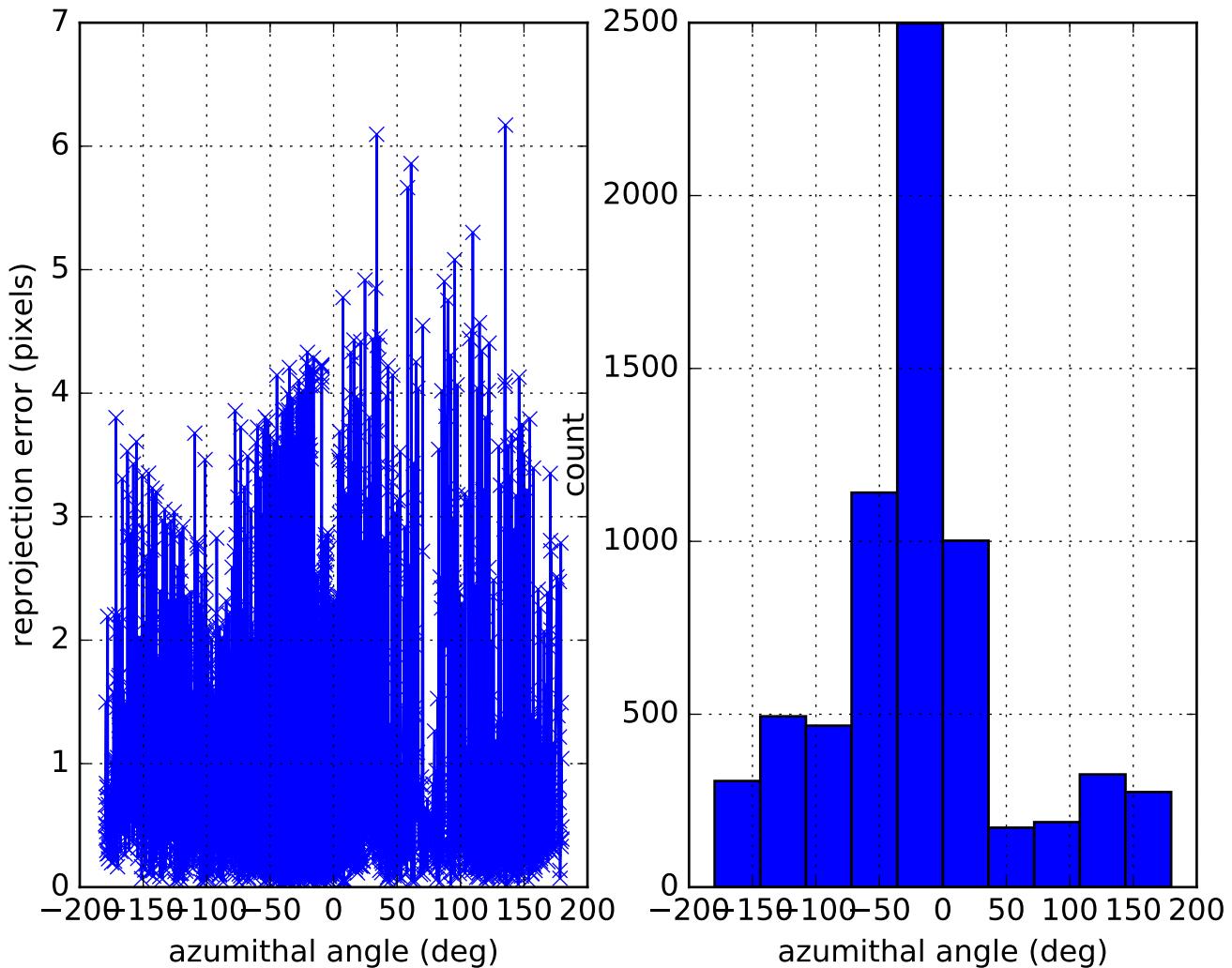
cam4: reprojection errors



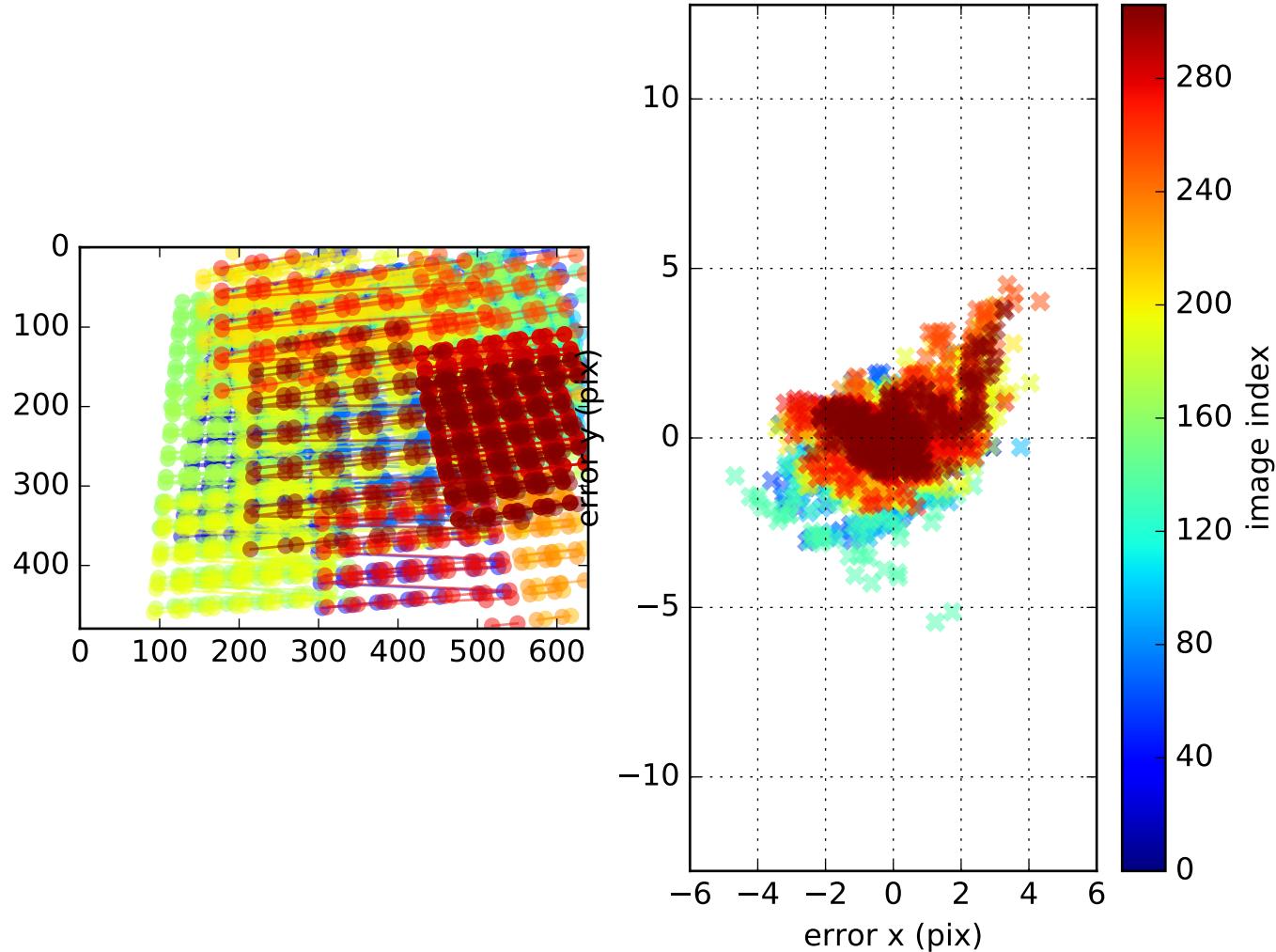
cam5: polar error



cam5: azimuthal error



cam5: reprojection errors



Location of removed outlier corners

