

Stochastic Local Volatility

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1 The Model

1.1 General description

Let T be a finite time horizon (the final maturity of the deal we want to price, for example) Let S be an asset of drift μ_t under the domestic risk-neutral probability measure. We assume the following dynamics under \mathbb{Q}_d

$$\frac{dS_t}{S_t} = \mu_t dt + \sigma(S_t, t) e^{X_t} dW_t \quad (1)$$

where $(S, t) \mapsto \sigma(S, t)$ is the local volatility function (deterministic function of spot and time, calibrated to the vanilla option market at time 0. We will develop later a methodology to calibrate that function σ . X is an Ornstein-Uhlenbeck process so that :

$$\forall t \in [0, T], \mathbb{E}[e^{2X_t}] = 1 \quad (2)$$

The goal of the stochastic volatility would be to calibrate to the forward smile (to be consistent with the

1.2 Stochastic volatility part

Let us assume that X follows the following dynamics under the domestic risk-neutral probability measure

$$\begin{aligned} dX_t &= (\theta(t) - \lambda X_t) dt + \sigma_X dW_t^X \\ X_0 &= 1 \end{aligned} \quad (3)$$

The coefficients are kept constant for now for simplicity.

We have

$$X_t = e^{-\lambda t} + \int_0^t \theta(s) e^{-\lambda(t-s)} ds + \int_0^t \sigma_X e^{-\lambda(t-s)} dW_s^X \quad (4)$$

Then,

$$\begin{aligned} \exp \left(2e^{-\lambda t} + 2 \int_0^t \theta(s) e^{-\lambda(t-s)} ds + 2 \int_0^t \sigma_X^2 e^{-2\lambda(t-s)} ds \right) &= 1 \\ e^{-\lambda t} + \int_0^t \theta(s) e^{-\lambda(t-s)} ds + \int_0^t \sigma_X^2 e^{-2\lambda(t-s)} ds &= 0 \\ e^{-\lambda t} + \int_0^t \theta(s) e^{\lambda s} ds e^{-\lambda t} + \int_0^t \sigma_X^2 e^{-2\lambda(t-s)} ds &= 0 \\ -\lambda e^{-\lambda t} - \int_0^t \theta(s) e^{\lambda s} ds \lambda e^{-\lambda t} + 2\sigma_X^2 e^{-2\lambda t} + \theta(t) &= 0 \end{aligned}$$

Setting $f(t) = \theta(t) e^{\lambda t}$ it yields

$$\begin{aligned} \lambda \int_0^t f(s) ds + f(t) &= c(t) \\ c(t) &= \lambda - 2\sigma_X^2 e^{-\lambda t} \end{aligned} \quad (5)$$

Then f satisfies the following ODE

$$\begin{aligned} f'(t) + \lambda f(t) &= -2\sigma_X^2 \lambda e^{-\lambda t} \\ f(0) &= \lambda - 2\sigma_X^2 \end{aligned} \quad (6)$$

Then

$$\begin{aligned} f(t) &= C e^{-\lambda t} - 2\sigma_X^2 \lambda t e^{-\lambda t} \\ &= (\lambda - 2\sigma_X^2) e^{-\lambda t} - 2\sigma_X^2 \lambda t e^{-\lambda t} \\ f(t) &= \lambda e^{-\lambda t} - 2\sigma_X^2 (1 + \lambda t) e^{-\lambda t} \end{aligned} \quad (7)$$

Then

$$\theta(t) = \lambda e^{-2\lambda t} - 2\sigma_X^2 (1 + \lambda t) e^{-2\lambda t} \quad (8)$$

The stochastic volatility X can be computed quite easily and be simulated exactly

$$X_t \sim \mathcal{N} \left(e^{-\lambda t} + \int_0^t \theta(s) e^{-\lambda(t-s)} ds, \sigma^2 \frac{1 - e^{-2\lambda t}}{2\lambda} \right) \quad (9)$$

1.3 Calibration of the local volatility

Theorem 1.1 (Markovian Projection). *Put here the theorem of the markovian projection of general volatility models into a local volatility*

In our case, we have

$$\begin{aligned} \sigma_D^2(x, t) &= \mathbb{E} [e^{2X_t} \sigma^2(S_t, t) | S_t = S] \\ &= \mathbb{E} [e^{2X_t} | S_t = S] \sigma^2(S, t) \end{aligned} \quad (10)$$

1.3.1 Calibration via a PDE

Let us introduce the Green function $G(S_0, X_0, t_0; S, X, t)$. Let us set $b(X) = e^X$. G satisfies

$$\frac{\partial G}{\partial T} - \frac{1}{2} \frac{\partial^2}{\partial S^2} (\sigma^2 b^2 S^2 G) - \frac{\partial^2}{\partial X^2} (\sigma_X^2 G) - \frac{\partial^2}{\partial S \partial X} (\rho b \sigma S \sigma_X G) + \frac{\partial}{\partial X} ((\theta - \lambda X) G) + \frac{\partial}{\partial S} (\mu S G) = 0 \quad (11)$$

Let us assume (in relation of the previous section), that

1. σ_X , θ and λ are not functions of X
2. μ is not a function of S
3. ρ is neither a function of S nor X

The calibration PDE degenerates into

$$\frac{\partial G}{\partial T} - \frac{1}{2} e^{2X} \frac{\partial^2}{\partial S^2} (\sigma^2 S^2 G) - \sigma_X^2 \frac{\partial^2}{\partial X^2} (G) - \rho \frac{\partial^2}{\partial S \partial X} (b \sigma S \sigma_X G) + (\theta - \lambda X) \frac{\partial}{\partial X} (G) + \mu \frac{\partial}{\partial S} (S G) = 0 \quad (12)$$

Let us denote by Q the density of S

$$Q(S, t) = \int_{\mathbb{R}} G(S, X, t) dX \quad (13)$$

Then

$$\frac{\partial Q}{\partial t} - \frac{1}{2} \frac{\partial^2}{\partial S^2} \left(\sigma^2 S^2 \int_{\mathbb{R}} e^{2X} G(S, X, t) dX \right) + \mu \frac{\partial}{\partial S} (S Q) = 0 \quad (14)$$

Thus,

$$\frac{\partial Q}{\partial t} - \frac{1}{2} \frac{\partial^2}{\partial S^2} \left(\sigma^2 \frac{\int_{\mathbb{R}} e^{2X} G(S, X, t) dX}{\int_{\mathbb{R}} G(X, S, t) dX} S^2 Q \right) + \mu \frac{\partial}{\partial S} (SG) = 0 \quad (15)$$

We recognize the Dupire equation which defines a local volatility function $\sigma_D(S, t)$

$$\sigma_D^2(S, t) = \sigma^2(S, t) \frac{\int_{\mathbb{R}} e^{2X} G(S, X, t) dX}{\int_{\mathbb{R}} G(X, S, t) dX} \quad (16)$$

which permits to re-write the calibration PDE

$$\begin{aligned} \frac{\partial G}{\partial T} - \frac{1}{2} \frac{\partial^2}{\partial S^2} \left(S^2 e^{2X} \sigma_D^2 \frac{\int_{\mathbb{R}} G(S, X, t) dX}{\int_{\mathbb{R}} e^{2X} G(S, X, t) dX} \right) + \mu \frac{\partial}{\partial S} (SG) - \frac{\sigma_X^2}{2} \frac{\partial^2 G}{\partial X^2} + \frac{\partial}{\partial X} ((\theta - \lambda X)G) \\ - \rho \sigma_X \frac{\partial^2}{\partial S \partial X} \left(e^X S \sigma_D \sqrt{\frac{\int_{\mathbb{R}} G(S, X, t) dX}{\int_{\mathbb{R}} e^{2X} G(S, X, t) dX}} G \right) = 0 \end{aligned} \quad (17)$$

The only SLV models tractables with a PDE calibration are then mono-asset SLV models. We will develop in the following another method which enable us to calibrate via Monte-Carlo SLV Models. However, a Monte-Carlo will have more noise than a PDE calibration.

1.3.2 Calibration by Monte-Carlo

In this section, we will develop a method to calibrate the SLV models in a higher dimension problem using a Monte-Carlo simulation.

2 Solving the SLV calibration PDE

In this section we will develop numerical methods to solve equation (17)

References

- [1] Frédéric Abergel, Rémi Tachet, *A Non-linear integro-differential equation from Mathematical Finance*. AIMS Journal, Version 1, 8 sept 2011