Collaboration Pattern: 120

RobotAction120\_2 hasAction: Break <object> in <location>

hasNextRobotAction

RobotAction120\_0 hasAction: Move to <Object>

hasRobotAction

CP120
hasTicksLasted: 368
hasRoundNumber: 3
hasParticipantNumber: 4092
hasUnixTimeStamp: 1720785904
hasRemainingTime: 3000
hasVictimHarm: 600
hasCPLabel: Break big rock
hasRemainingRocks: 7

hasCPNum: 120 hasTimeStamp: 2024-07-12T14:05:04umanAction

has Situation

Situation120\_1

NextSittuation120\_0
hasLocation: Top of rock pile
hasObject: Large rock

HumanAction120 0

\

hasNextHumanAction

HumanAction120 1

hasNextHumanAction

HumanAction120\_2