Collaboration Pattern: 016

RobotAction16_2
hasObject: Large rock
location: <Right> side of rock pile
ion: Drop <object> in <location>

hasNextRobotAction

RobotAction16_1
hasLocation: Bottom of rock pile
hasObject: Large rock
hasAction: Pick up <object> in <location>

hasNextRobotAction

RobotAction16_0

hasRobotAction

HumanAction16_0
hasLocation: <Left> side of field
hasAction: Stand still in <location>

hasNextHumanAction

HumanAction16_2

HumanAction16_1

hasNextHumanAction

hasHumanAction

CP16
hasCPLabel: move break big rock bottom
hasParticipantNumber: 4071
hasUnixTimeStamp: 1724940193
hasRemainingTime: 3000
hasRemainingRocks: 19
hasVictimHarm: 0
hasTimeStamp: 2024-08-29T16:03:13
hasRoundNumber: 7
hasCPNum: 16
hasTicksLasted: 250

hasSituation

Situation16_0
hasActor: Human
hasLocation: <Left> side of field

hasNextSituation

Situation16_1
hasLocation: Bottom of rock pile
hasObject: Large rock