Collaboration Pattern: 181

RobotAction181_2
hasAction: Drop <object> in <location>
hasLocation: <Left> side of field

hasNextRobotAction

RobotAction181_1
hasObject: Large rock
hasAction: Pick up <object> in <location>
hasLocation: On top of <Object>

hasNextRobotAction

RobotAction181_0
hasAction: Move to <Object:
hasObject: Large rock

hasRobotAction

CP181

hasRemainingRocks: 3
hasCPLabel: Unstack large rocks
hasUnixTimeStamp: 1722347447
hasParticipantNumber: 4098
hasRemainingTime: 2993
hasTicksLasted: 442

hasTimeStamp: 2024-07-30T15:50:47 hasVictimHarm: 500

hasCPNum: 181 hasRoundNumber: 4

hasHumanAction

HumanAction181_0

hasNextHumanAction

HumanAction181_1

hasNextHumanAction

HumanAction181_2

Situation181 0

hasSituation

hasObject: Large rock hasLocation; On top of <Object>

hasNextSituation

Situation181_1