Collaboration Pattern: 171

RobotAction171_3 hasLocation: <Left> side of rock pile
hasAction: Drop <object> in <location>
hasObject: Brown fock object> chasObject> in <location: Move to <Object> RobotAction171 0 hasLocation: <Left> side of rock pile otActioRobotAction171 1 hasActor: Human hasAction: Pick up <object> in hasAction: Move to <Object> hasAction: Pick up <object> in hasObject: Brown rock hasLocation: Top of rock pile hasRobotAction CP171 hasRemainingTime; 3000 hasUnixTimeStamp: 1/21634790 hasCPNum: 171 hasRemainingRocks: 24 hasVictimHarm: 0 hasParticipantNumber: 4097 hasTicksLasted: 1939 hasRoundNumber: 7 hasHumanAction hasTimeStamp: 2024-07-22T09:53:10 Situation171 1 hasCPLabel: brown rock HumanAction171_0 hasSituation hasNextSituation Situation171 0 hasNextHumanAction hasActor: Robot hasLocation: <Left> side of rock pile HumanAction171 1 hasNextHumanAction HumanAction171_2 hasNextHumanAction HumanAction171_3