Collaboration Pattern: 021

Situation21 1

asNextSituation Situation21_0 hasLocation: Top of rock pile hasObject: Large rock

hasSituation

CP21

hasRemainingTime: 3000
hasUnixTimeStamp: 1724402644
hasCPLabel: Large rocks on top
hasRemainingRocks: 28
hasVictimHarm: 0
hasRoundNumber: 3
hasCPNum: 21

hasRals។ Ase Stamp: 2024-08-23T10:44:04

hasTicksLasted: 546 hasParticipantNumber: 4073

RobotAction21_0

has NextRobotAction

RobotAction21_1
hasObject: Large rock
hasLocation: Top of rock pile
hasAction: Pick up <object> in <location>

hasNextRobotAction

RobotAction21_2
asAction: Drop <object> in <location>
hasLocation: <Right> side of field
hasObject: Large rock

hasHumanAction

HumanAction21_1

HumanAction21_0^{tion}
hasActor: Human
hasAction: Stand still in <location>
hasLocation; < Left>nside of field

HumanAction21 2