Collaboration Pattern: 134

RobotAction134_2
hasAction: Drop <object> in <location>
hasLocation: <Left> side of field
hasObject: Small rock

 $has {\bf NextRobotAction}$

RobotAction134_1
hasAction: Pick up <object> in <locatio
hasObject: Small rock

hasNextRobotAction

RobotAction134_0
hasAction: Move to <Object:
hasObject: Small rock

hasRobotAction

CP134

hasParticipantNumber: 4094
hasRoundNumber: 6
hasCPNum: 134
hasTimeStamp: 2024-07-23T11:59:46
hasRemainingTime: 3000
hasUnixTimeStamp: 1721728786
hasCPLabel: small rock top
hasVictimERT and the 121

hasRemainingRocks: 31 hasTicksLasted: 1184

has Human Action

HumanAction134_0

SNextHumanAction

HumanAction134_1

hasNextHumanAction

HumanAction134 2

hasSituation

Situation134_0 hasLocation: Top of rock pile hasObject: Small rock

hasNextSituation

Situation134_1