Collaboration Pattern: 140

RobotAction140_2 hasAction: Break <object> in <location>

hasNextRobotAction

RobotAction140_1 hasAction: Move to <Object> hasLocation: Top of rock pile

has NextRobotAction

RobotAction140 0

HumanAction140_0 hasLocation: Above rock pile hasAction: Stand still in <location>

hasRobotAction

hasHumanAction

hasTicksLasted: 2515
hasCPLabel: Breaking large rock pile
hasRemainingRocks: 33
hasParticipantNumber: 4095
hasVictimHarm: 200
hasRoundNumber: 2
hasUnixTimeStamp: 1721632561
hasTimeStamp: 2024-07-22T09:16:01

CP140

hasCPNum: 140 hasRemainingTime: 3000 HumanAction140_1

hasNextHumanAction

hasNextHumanAction

HumanAction140_2

hasSituation

Situation140_0 hasObject: Large rock nasLocation: Top of rock pile

hasNextSituation

Situation140_1