## Situation71 1 hasNextSituation Situation71\_0 hasObject: Large rock hasLocation: Top of rock pile hasSituation CP71 hasCPLabel: large rock robot hasUnixTimeStamp: 1717145348 hasVictimHarm: 1000 hasParticipantNumber: 4085 hasRoundNumber: 6 hasRemainingRocks: 17 hasTimeStamp: 2024-05-31T10:49:08 hasRemainingTime: 3000 hasTicksLasted: 25 hasCPNum: 71 hasRobotAction hasHumanAction RobotAction71 0 hasAction: Pick up <object> in <lo RobotAction Next Phas Object: Large rock has Action: Drop < object > in < location > HumanAction71 0 hasNextHumanAction hasObject: Large rock HumanAction71 1 hasLocation: <Left> side of field hasNextHumanAction hasNextRobotAction HumanAction71\_2

RobotAction71\_2