## Collaboration Pattern: 073

RobotAction73 4 hasAction: Drop <object> in <location> hasLocation: <Left> side of field has Object: Large rock RobotAction 73\_3 hasAction: Move to <Location> hasLocation: <Left> side of field hasNextRobotAction RobotAction73 2 hasActor: Human hasObject: Large rock hasLocation: On top of <Actor> hasAction: Pick up <object> in <location> hasNextRobotAction CP73 hasVictimHarm: 0 hasSituation hasTicksLasted: 913 hasRemainingRocks: 28 RobotAction73 1 hasCPNum: 73 hasUnixTimeStamp: 1719925970 asNextRobotAction hasRobotAction hasTimeStamp: 2024-07-02T15:12:50 RobotAction73 0 hasParticipantNumber: 4086 sAction: Move to <Location> hasCPLabel: Large rock on top of pile nasLocation: Top of rock pile hasRoundNumber: 1 hasRemainingTime: 3000 HumanAction73 0 HumanhAstAction: Stand still in <location> hasAction: MovehasLs Catject: Top of rock pile hasObject: Large rock hasNextHumanAction HumanAction73 2 hasNextHumanAction HumanAction73 3 hasNextHumanAction

Situation73\_0 hasLocation: Top of rock pile hasObject: Large rock

hasivextSituation

Situation73 1

HumanAction73\_4