Collaboration Pattern: 025

RobotAction25 0 hasAction: Stand still in <location> asNexsRobattAonic < Right> side of field RobotAction25_1 hasNextRobotAction RobotAction25 2 hasRobotAction CP25 hasCPNum: 25 hasUnixTimeStamp: 1724404290 hasVictimHarm: 0 HumanAction25 0 hasTimeStamp: 2024-08-23T11:11:30 hasRoundNumber: 6 hasHumanAction: Pick up <object> in <location> hasLocation: Top of rock pile hasRemainingRocks: 36 hasObject: Small rock hasCPLabel: small rocks on top V2 hasParticipantNumber: 4073 hasRemainingTime: 3000 hasNextHumanAction hasTicksLasted: 744 HumanAction25 1 hasLocation: <Left> side of rock pile hasAction: Drop <object> in <location> hasObject: Small rock hasNextHumanAction hasSituation HumanAction25 2 Situation25 0

hasObject: Smalt sackation 25_1 hasLocation: Top of rock pile