Collaboration Pattern: 168

HumanAction168_2

hasNextHumanAction

HumanAction168_0
hasObject: Large rock
hasAction: Move to <Object>

HumanAction168_1

hasHumanAction

CP168
hasParticipantNumber: 4097
hasTimeStamp: 2024-07-22T09:47:40
hasUnixTimeStamp: 1721634460
hasCPLabel: 3
hasCPNum: 168
hasTicksLasted: 905
hasRoundNumber: 6
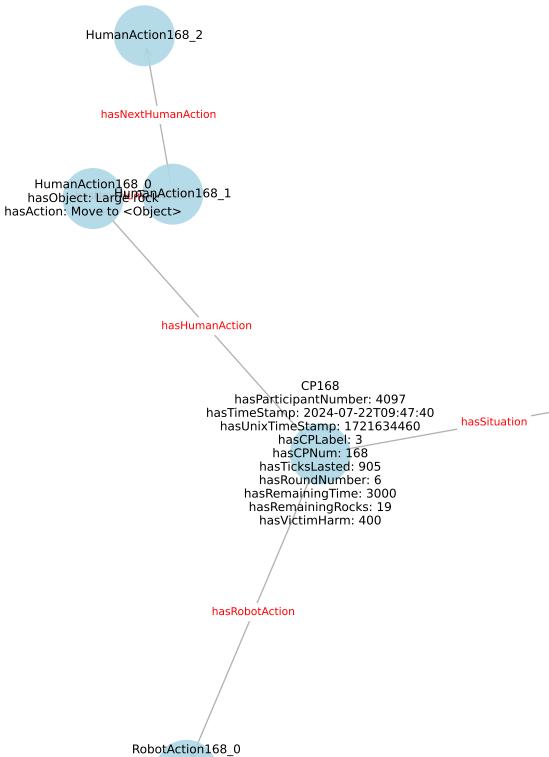hasRemainingTime: 3000
hasRemainingRocks: 19
hasVictimHarm: 400

hasSituation

Situation168_0
hasActor: Robot

hasNextSituation

Situation168_1

hasRobotAction

RobotAction168_0
hasLocation: Bottom of rock pile
hasObject: Large rock
hasAction: Pick up <object> in <location>

RobotAction168_1
hasObject: Large rock
hasNextRobotAction

RobotAction168_2
hasLocation: <Left> side of rock pile
hasAction: Drop <object> in <location>