## Collaboration Pattern: 065

Situation65\_1 hasLocation: Bottom of rock pile hasObject: Large rock

hasNextSituation

Situation65\_0 hasLocation: Top of rock pile hasObject: Brown rock

hasSituation

RobotAction65\_0
hasAction: Pick up <object> in <location>
hasLocation: Bottom of rock pile
hasNextRobotAction

RobotAction65\_1 hasNextRo
hasLocation: <Left> side of field
hasAction: Drop <object> in <location>

hasNextRobot has Object: Large rock

RobotAction65 2

CP65
hasRobotAtas6PNum: 65
hasTicksLasted: 953
hasUnixTimeStamp: 1717409143
hasCPLabel: Brown rock on top
hasParticipantNumber: 4083
hasRoundNumber: 8
hasVictimHarm: 1900
hasRemainingRocks: 0
hasRemainingTime: 2237

hasTimeStamp: 2024-06-03T12:05:43

hasHumanAction

HumanActiondgmanAction65\_0

HumanAction65\_2