Collaboration Pattern: 165

Situation165_1

hasNextSituation

Situation165_0
hasObject: Large rock
hasLocation: Top of rock pile

hasSituation

RobotAction165_0
hasAction: Pick up <object> in <location>
hasLocation: <Left> side of rock pile
hasObject: Large rock

hasNextRobotAction

RobotAction165_1

hasNextRobotAction

RobotAction165_2

hasRobotAction

CP165
hasRemainingRocks: 19
hasVictimHarm: 400
hasParticipantNumber: 4097
hasCPNum: 165
hasCPLabel: Large rock
hasTimeStamp: 2024-07-22T09:47:40
hasUnixTimeStamp: 1721634460
hasRoundNumber: 6
hasTicksLasted: 1
hasRemainingTime: 3000

hasHumanAction

HumanAction165_0
hasObject: Large rock
hasAction: Pick up <object> in <location>
hasLocation: <Left> side of rock pile

hasNextHumanAction

HumanAction165_1

hasNextHumanAction

HumanAction165_2