Situation205_0
Situation205<mark>hasOb</mark>ject: Large rock
hasLocation: Top of rock pile

RobotAction205 2

hasNextRobotAction

RobotAction205 1

RobotAction 205_0 hasObject: Large rock hasLocation: Top of rock pile hasAction: Pick up <object> in <location>

hasSituation

hasRobotAction

CP205

hasTicksLasted: 1564 hasCPLabel: PickBigTop hasVictimHarm: 200 hasParticipantNumber: 4099 hasRoundNumber: 6 hasRemainingTime: 3000 hasTimeStamp: 2024-08-07T10:32:50

hasCPNum; 205 hasUnixTimeStamp:\1723019570

hasHumanAction

HumanAction20514manAction205_1