Collaboration Pattern: 127

RobotAction127_2 hasAction: Drop <object> in <location> hasObject: Small rock RobotAction 27-1 < Left > side of field hasAction: Pick up < object > in < location > hasObject: Small rock hasLocation: Top of rock pile hasNextRobotAction RobotAction127 0 hasLocation: Top of rock pile hasAction: Stand still in <location> hasRobotAction hasSituation CP127 hasRemainingRocks: 0 hasCPLabel: Something hasParticipantNumber: 4092 hasRoundNumber: 7 hasTimeStamp: 2024-07-12T14:47:40 hasTicksLasted: 951 hasVictimHarm: 0 hasCPNum: 127 hasUnixTimeStamp: 1720788460 hasRemainingTime: 1466 hasHumanAction HumanAction127 0

HumanAction127_1

hasNextHumanAction

has NextHuman Action

HumanAction127_2

Situation127 1

hasNextSituation

Situation127_0 hasObject: Small rock hasLocation: Top of rock pile