RobotAction11_2 hasAction: Drop <object> in <location> hasObject: Large rock hasLocation: <Right> side of field hasNextRobotAction RobotAction11 1 hasObject: Large rock hasLocation: Top of rock pile hasAction: Pick up <object> in <location hasNextRobotAction RobotAction11 0 hasRobotAction

CP11

hasTicksLasted: 806 hasTimeStamp: 2024-08-29T15:54:42 hasCPLabel: stand still break big rock

hasCPNum: 11 hasRemainingRocks: 16 hasRoundNumber: 6

hasUnixTimeStamp: 1724939682 hasVictimHarm: 100

hasParticipantNumber: 4071 hasRemainingTime: 3000

hasHumanAction

hasSituation

HumanAction11 0 hasLocation: <Right> side of field hasAction: Stand still in <location>

hasNextHumanAction

HumanAction11 1

Situation11 2 hasLocation: Top of rock pile hasObject: Large sock

hasNexthasLocation: <Right> side of field hasActor: Human

hasNextSituation

HumanAction11 2

Situation11_0