Collaboration Pattern: 161

Situation161_0 hasObject: Large rock hasLocation: Top of rock pile RobotAction161_0
hasObject: Large rock
RobotAction161asAction: Pick up <object> in <location> hasNehtastloctation: <Left> side of rock pile hasSituation hasNextRobotAction Situation161 1 hasRobotAction RobotAction161 2 CP161 hasRemainingTime: 3000 hasRemainingRocks: 24 hasVictimHarm: 0 hasParticipantNumber: 4097 hasTicksLasted: 3018 hasCPLabel: Large rock hasTimeStamp: 2024-07-22T09:23:00 hasUnixTimeStamp: 1721632980 hasRoundNumber: 3 hasCPNum: 161 hasHumanAction HumanAction161_0 hasLocation: <Left> side of rock pile hasObject: Large rock hasAction: Pick up <object> in <location> hasNextHumanAction