Collaboration Pattern: 137

## Situation137 1

## hasNextSituation

Situation137\_0 hasLocation: Top of rock pile hasObject: Brown rock

hasSituation

hasTimeStamp: 2024-07-23T12:10:32
hasRoundNumber: 7
hasCPLabel: brown rock top
hasCPNum: 137
hasRemainingTime: 3000
hasUnixTimeStamp: 1721729432
hasVictimHarm: 0
hasTicksLasted: 2664
hasParticipantNumber: 4094

hasRemainingRocks: 27

hasHumanAction

hasRobotAction

RobotAction137\_0

:: Move back and forth in <location>
nasLocation: Top of rock pile

hasNextRobotAction

RobotAction137\_1 hasAction: Move to <Object> hasObject: Brown rock

hasNextRobotAction

RobotAction137\_2
hasLocation: Top of rock pile
hasObject: Brown rock
hasAction: Break <object> in <location>
hasNextRobotAction

RobotAction137\_3

HumanAction137 0

NextHumanActi

HumanAction137\_1 hasAction: Move to <Object> hasObject: Brown rock

hasNextHumanAction

HumanAction137\_2
hasLocation: Top of rock pile
hasObject: Brown rock
hasAction: Break <object> in <locati

hasNextHumanAction

HumanAction137\_3