Collaboration Pattern: 210

RobotAction210 2

hasNextRobotAction

RobotAction210_0
hasAction: Pick up <object > in < location > hasObject: Large rockbotAction210_1

hasRobotAction

CP210
hasParticipantNumber: 4099
hasCPNum: 210
hasVictimHarm: 500
hasRemainingRocks: 8
hasCPLabel: GuidedPickUp
hasUnixTimeStamp: 1723020255
hasTicksLasted: 1156

hasHumanActionasRemainingTime: 2657 hasRoundNumber: 8 hasTimeStamp: 2024-08-07T10:44:15

HumanAction210_0
hasAction: Stand still in <location>
hasObject: Large rock
hasLocation: On top of <Object>
hasNextHumanAction
hasSituation

HumanAction210_1

hasNextHumanAction

Situation210_0
nasLocation: Top of rock pile
hasObject: Brown rock

HumanAction210_2

hasNextSituation

Situation210_1