Collaboration Pattern: 119

Situation119_1

hasNextSituation

Situation119_0
hasObject: Small rock
hasLocation: Top of rock pile

RobotAction119_2

hasNextRobotAction

RobotAction119_1
hasAction: Pick up <object> in <location>

hasNextRobotAction

hasSituation

RobotAction119_0
hasAction: Move to <Object>

CP119
hasTicksLasted: 2232
hasCPLabel: Something
hasUnixTimeStamp: 1720784792
hasCPNum: 119
hasParticipantNumber: 4092
hasRoundNumber: 1
hasRemainingTime: 3000
hasTimeStamp: 2024-07-12T13:46:32
hasRemainingRocks: 29
hasVictimHarm: 400

hasRobotAction

hasHumanAction

HumanAction119_1
hasAction: Pick up <object> in <location>

hasNextHumanAction

HumanAction119_0
hasAction: Move to <Object>

hasNextHumanAction

HumanAction119_2