



# selected applications of optical remote sensing

UNIS Glaciology Course

vår 2017



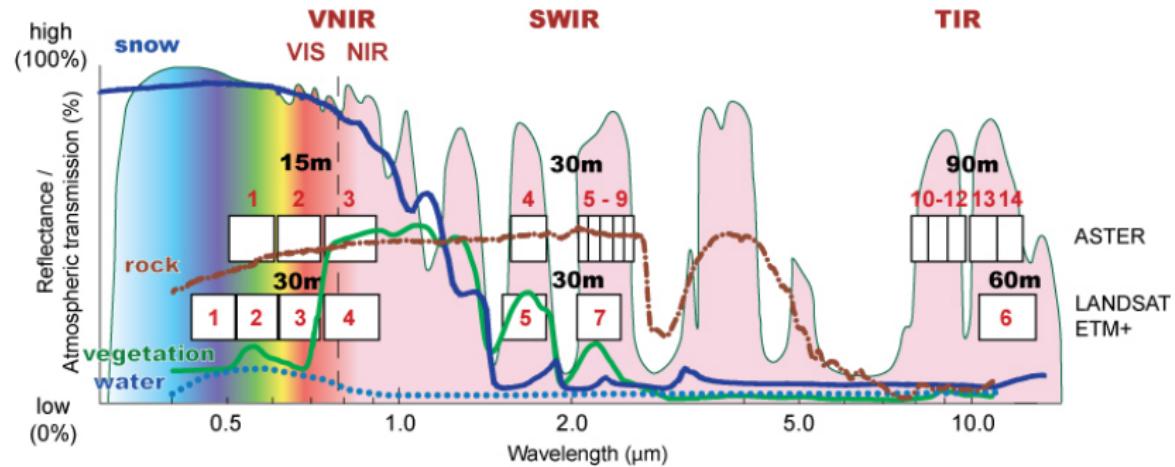
## Today's Topics

- ▶ glacier mapping
- ▶ velocity mapping

## glacier mapping: image classification

- ▶ broadly speaking, we want to **classify** satellite images
- ▶ can do this manually, but:
  - ▶ time-consuming, expensive
  - ▶ user-dependent
- ▶ instead, we look for **automated** approaches, exploiting spectral properties of target material
- ▶ have two basic approaches:
  - ▶ pixel-based approach
  - ▶ object-based approach

# spectral signatures of common materials

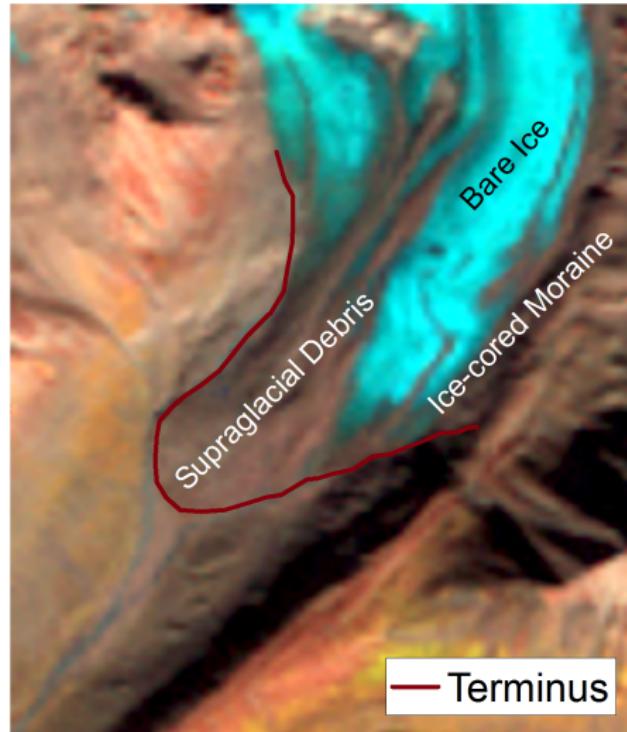


(A. Kääb)

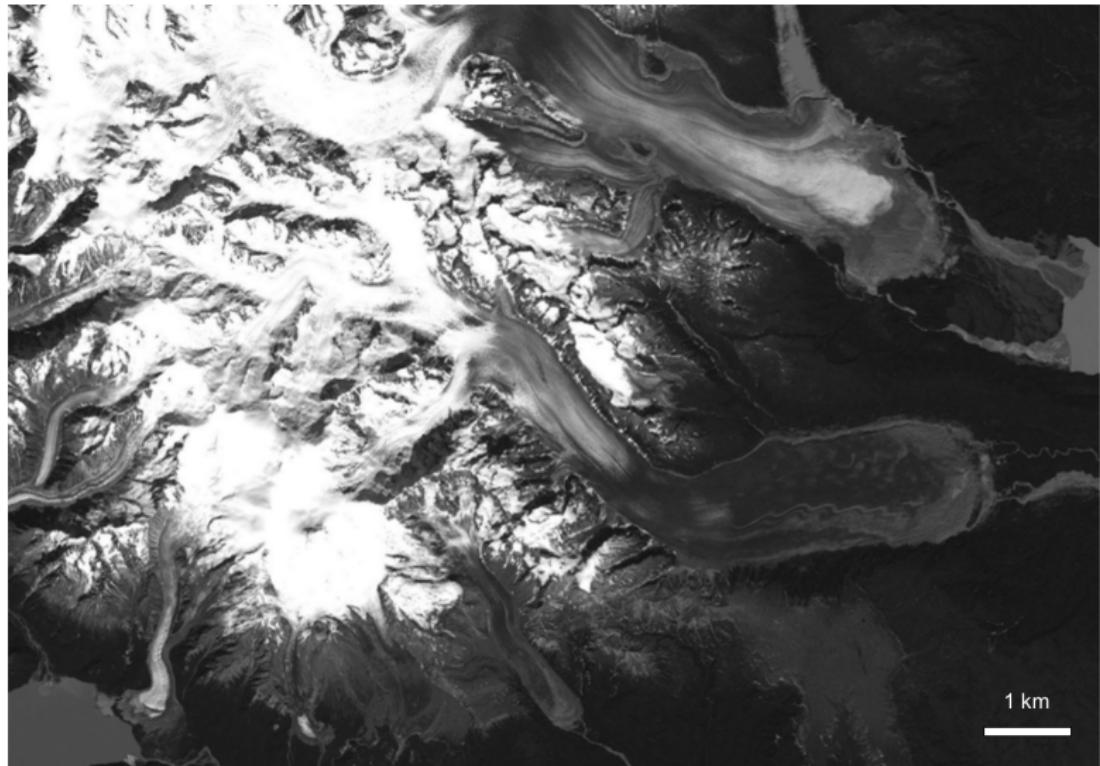
## the debris problem



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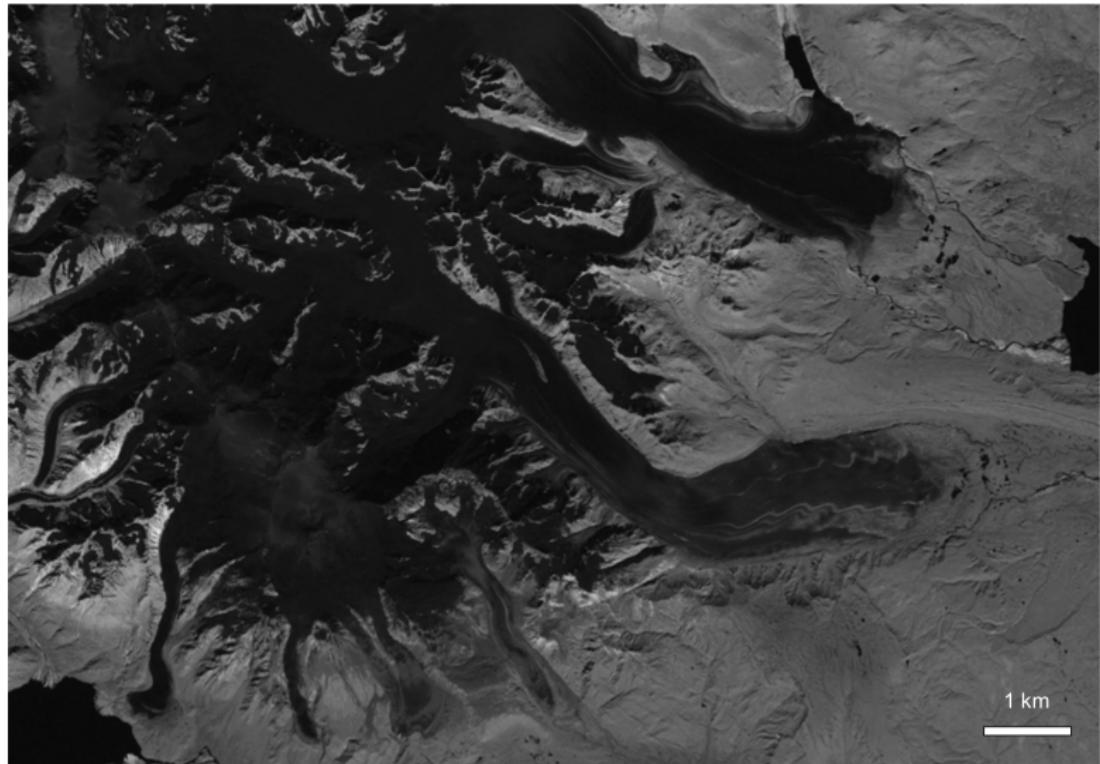
## landsat examples (etm3)



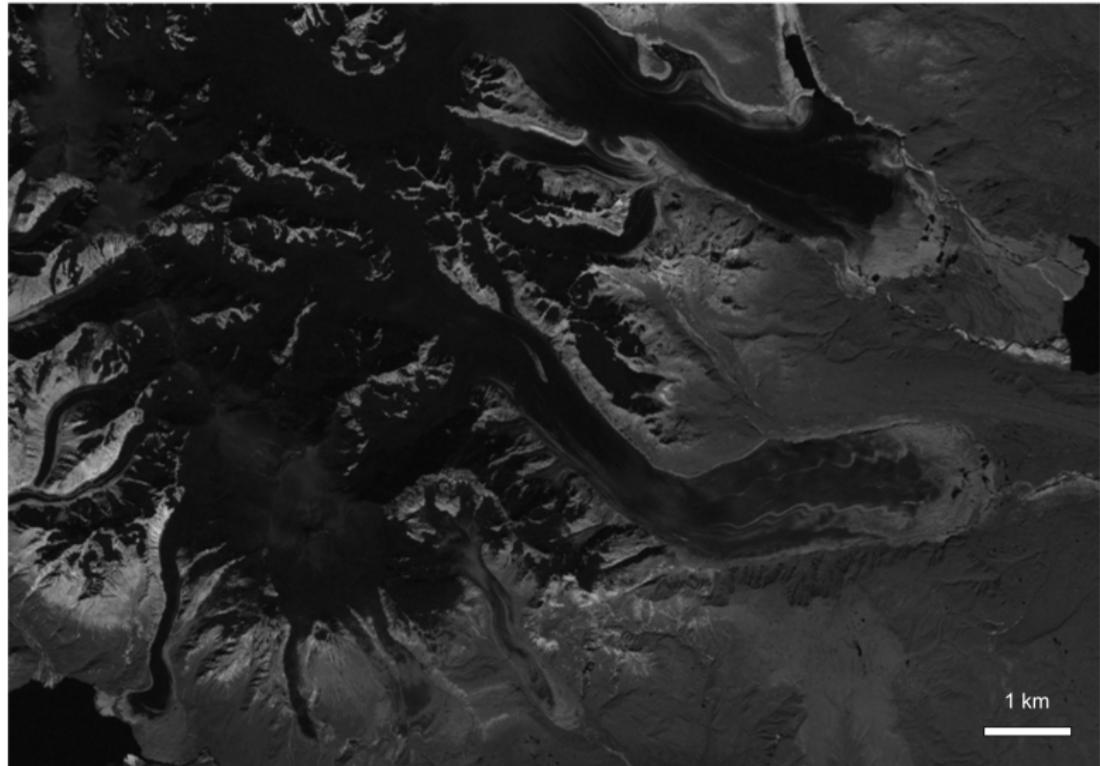
## landsat examples (etm4)



## landsat examples (etm5)



## landsat examples (etm7)

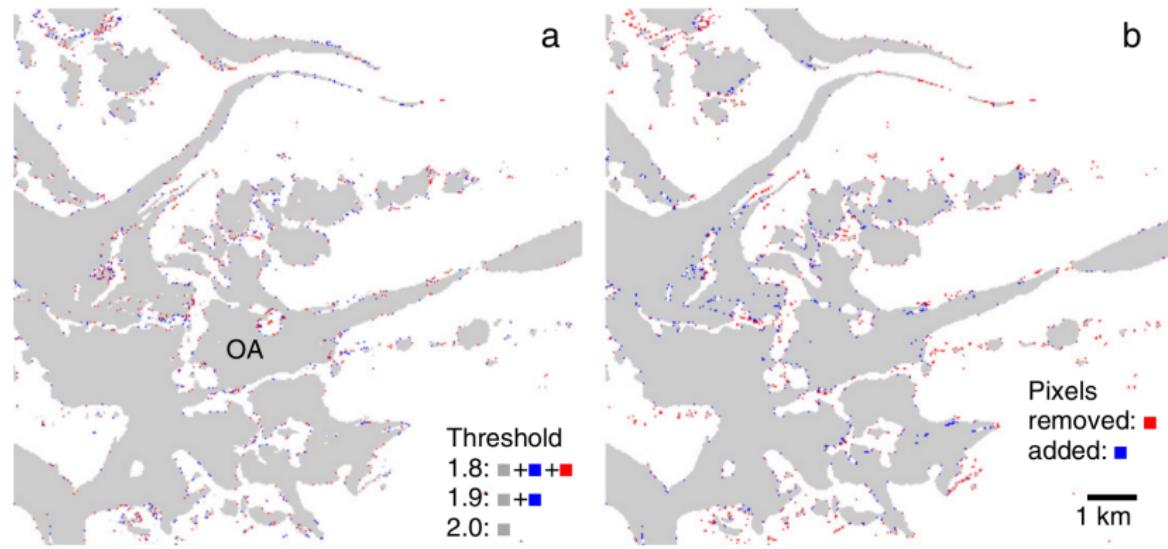


## basic approaches: thresholding

several different approaches proposed, utilized:

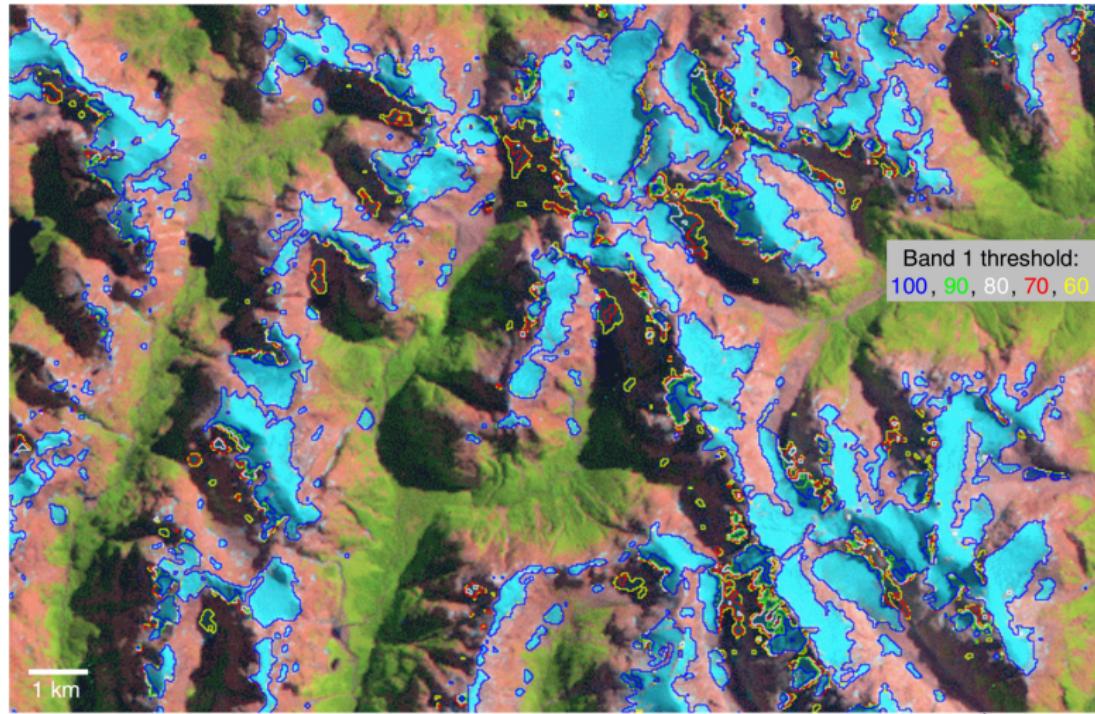
- ▶ ratio of red (TM3) to swir (TM5); requires a blue (TM1) threshold to improve mapping in shadow (scattering), remove water
- ▶ ratio of nir (TM4) to swir (TM5); no TM1 threshold required, does not mistakenly map water surfaces (but can map vegetation in shadow)
- ▶ normalized snow difference index (ndsi) can also be used, but scattering effects have to be considered
- ▶ all of these approaches require manual correction/intervention at some stage (the debris problem)
- ▶ thresholds are, in general, robust, and exact values not so important
- ▶ can still accidentally map perennial snowfields

## threshold mapping



(Paul et al., 2015)

## threshold mapping

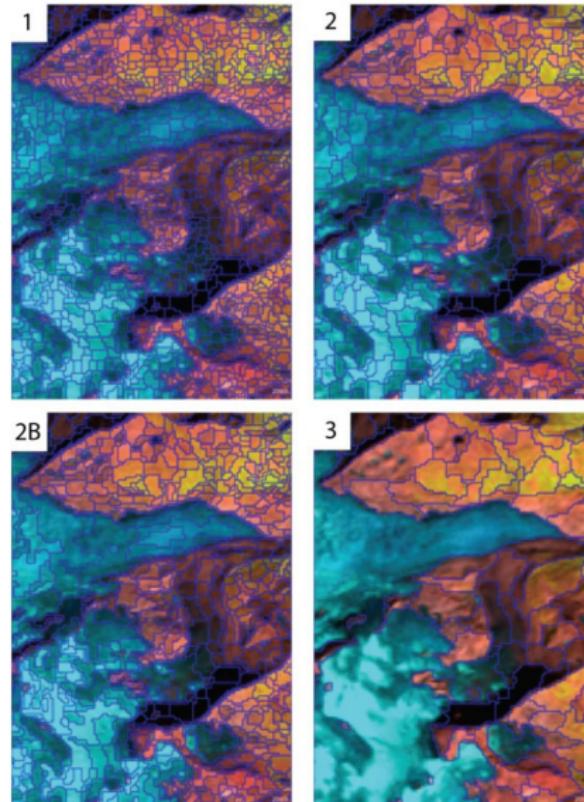


(Paul et al., 2015)

## object-based classification

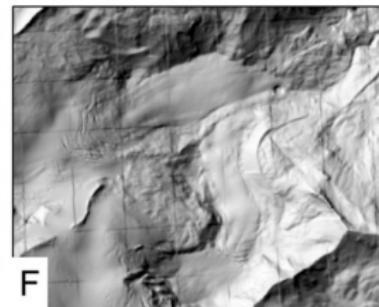
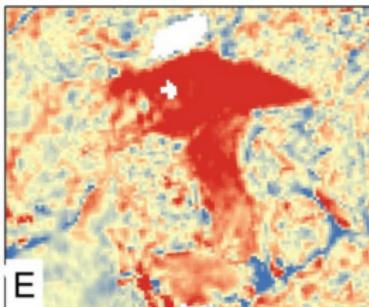
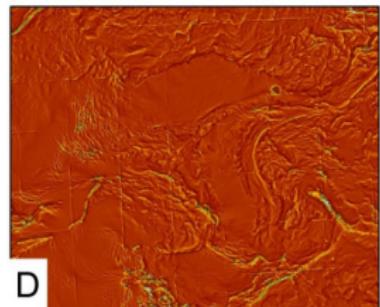
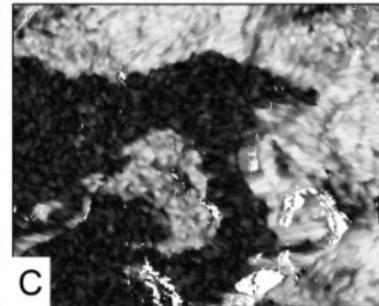
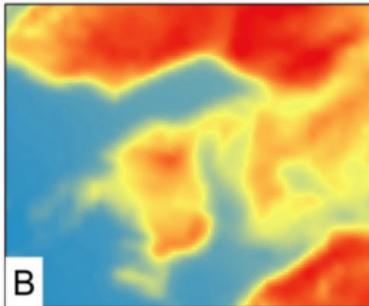
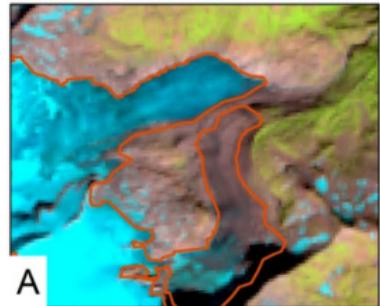
- ▶ basic idea: break images into smaller chunks (“objects”), much like our eyes do
- ▶ this process is called **segmentation**:
- ▶ once we have created objects, can build classification based on object properties:
  - ▶ pixel values in different channels (same as pixel-based methods)
  - ▶ texture, brightness
  - ▶ size, shape
  - ▶ proximity to other objects/classes

## object-based classification



Robson et al., 2016

## object-based classification

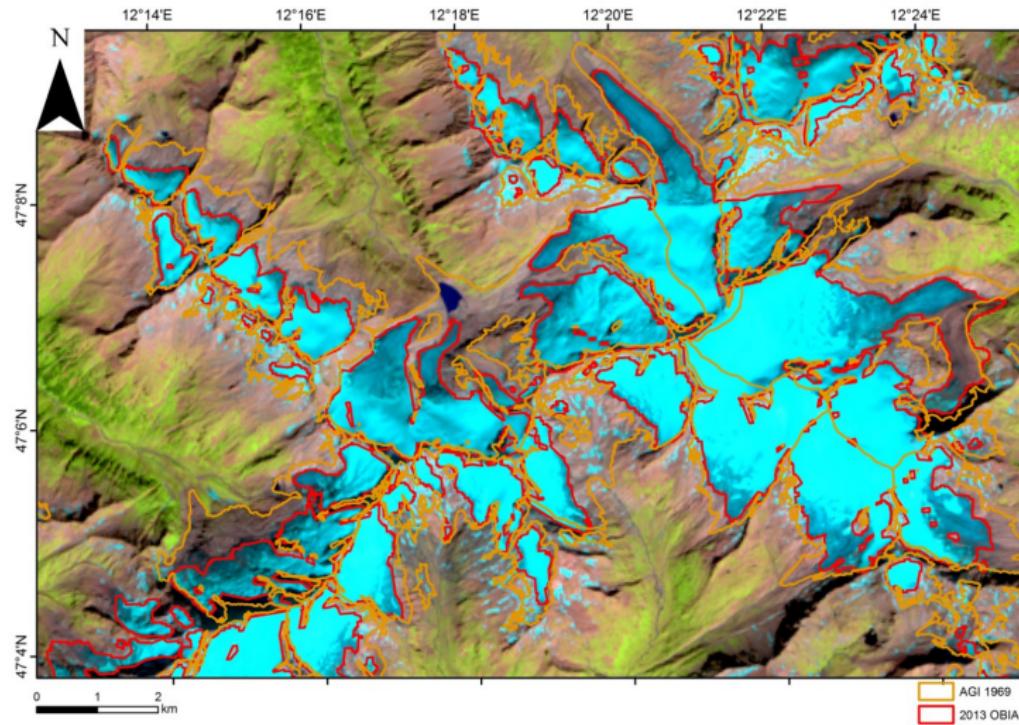


0 1 2 km

Glacier Outline

Robson et al., 2016

## object-based classification



Robson et al., 2016



glaciers move

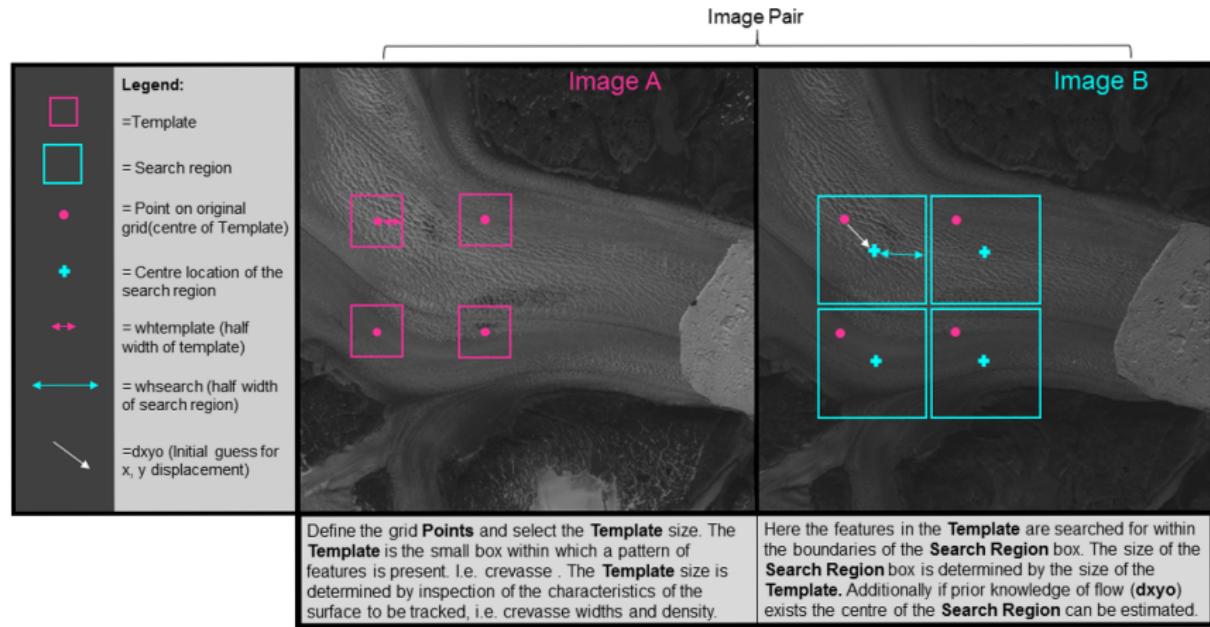
## general requirements

- ▶ two images separated enough in time to see changes (but not so long as to see too much change)
  - ▶ for fast-moving tidewater glaciers, typically  $\leq 50$  days (or much less)
  - ▶ want images from similar times of year, so that changes in snow cover/illumination don't dominate
- ▶ images must be **orthorectified**, preferably using the same DEM
- ▶ images must be from the same sensor/kind of sensor (we're looking for similarity)

## general approach

- ▶ can filter the images (edge filtering, high-pass filter, pc intensity)
- ▶ select sub-scenes of image (chips), compare somehow
  - ▶ normalized cross-correlation
  - ▶ phase correlation (frequency domain)
- ▶ post-processing

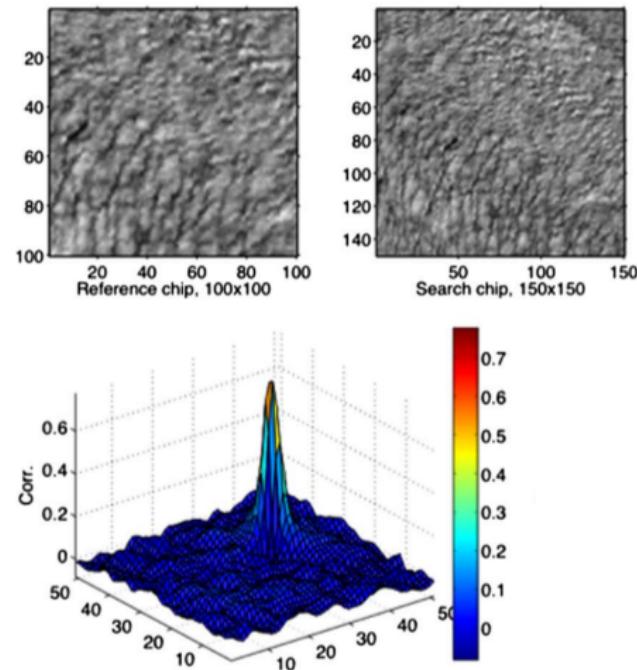
# correlation chips



Define the grid **Points** and select the **Template** size. The **Template** is the small box within which a pattern of features is present. I.e. crevasse . The **Template** size is determined by inspection of the characteristics of the surface to be tracked, i.e. crevasse widths and density.

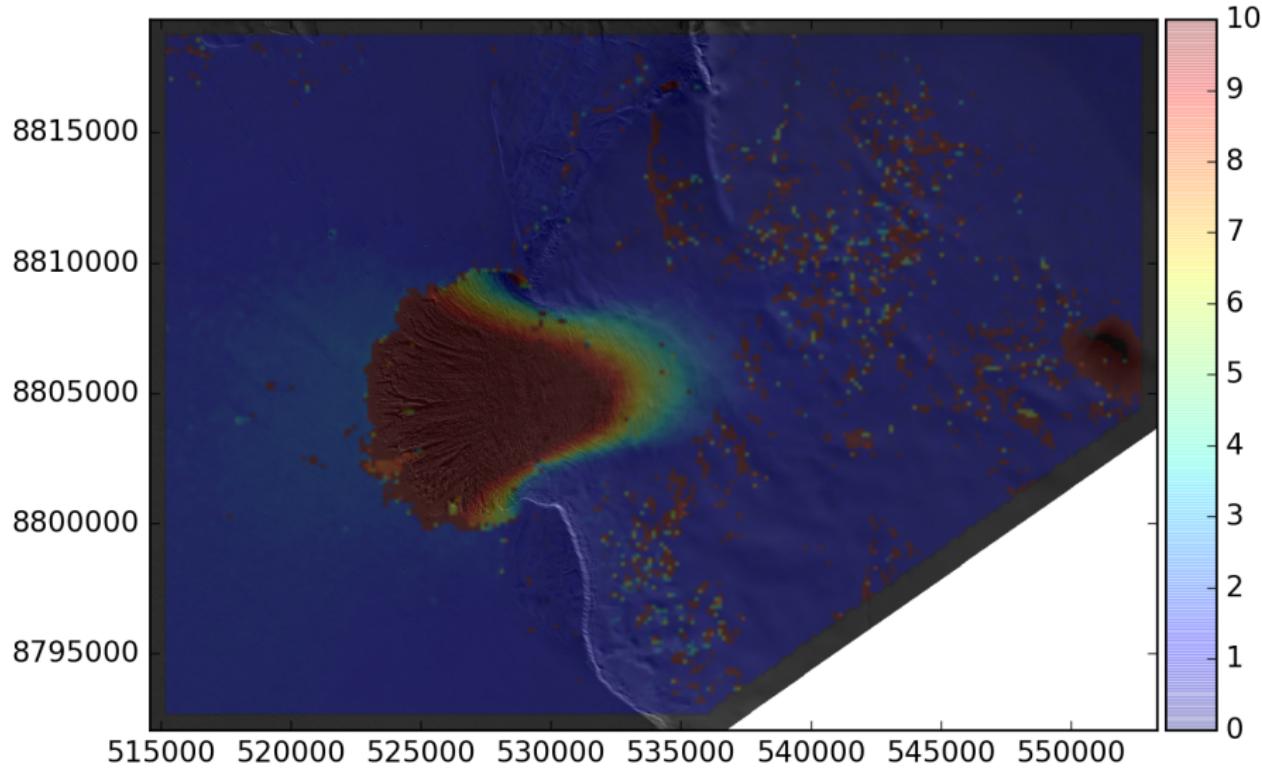
Here the features in the **Template** are searched for within the boundaries of the **Search Region** box. The size of the **Search Region** box is determined by the size of the **Template**. Additionally if prior knowledge of flow (**dxyo**) exists the centre of the **Search Region** can be estimated.

## correlation chips

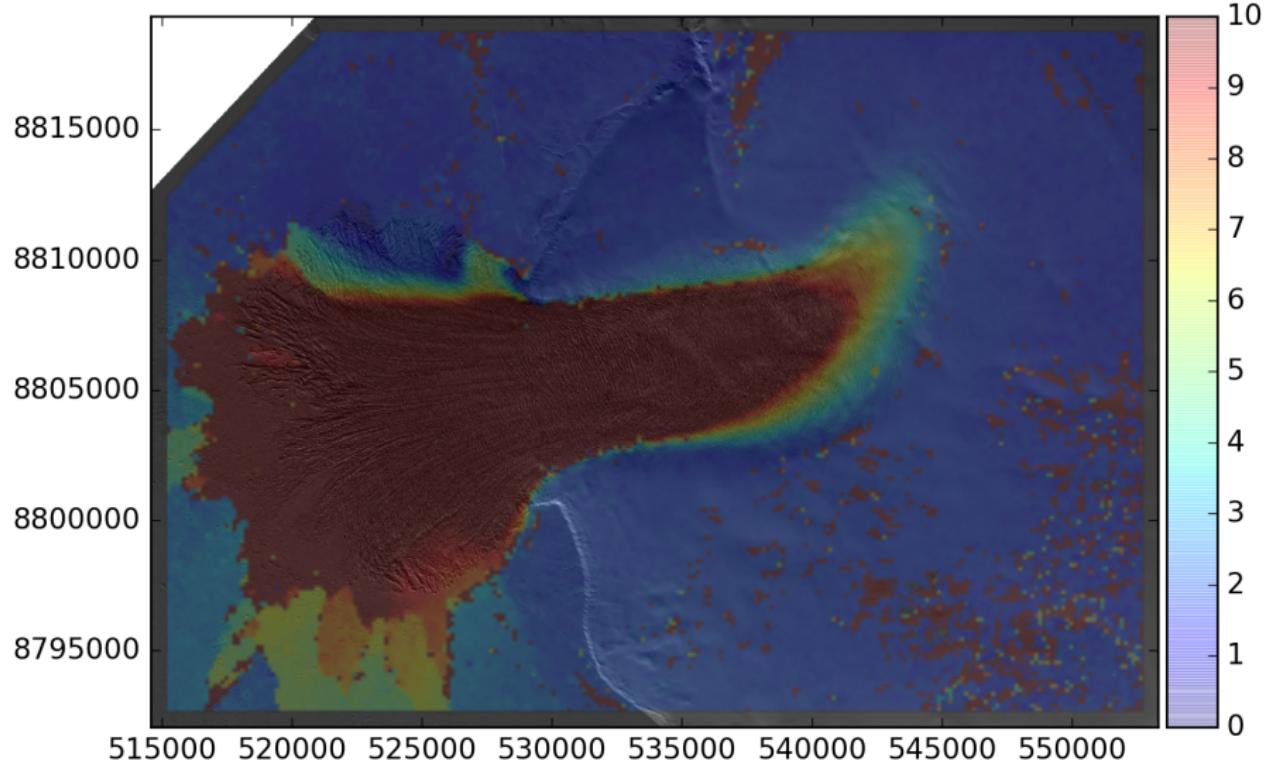


Ahn and Howat, 2011

example results: vavilov ice cap, severnaya zemlya



example results: vavilov ice cap, severnaya zemlya



## filtering

- ▶ errors/spurious matches **will** happen
- ▶ iteratively filter by orientation, magnitude (e.g., Burgess et al., 2012)
- ▶ manual editing (e.g., van Wyk et al., 2012)

## further reading

- ▶ Scambos et al., 1992. *Application of image cross-correlation to the measurement of glacier velocity using satellite image data.* *RSE*, 42(3), 177-186
- ▶ Ahn and Howat, 2011. *Efficient automated glacier surface velocity measurement from repeat images using multi-image/multichip and null exclusion feature tracking.* *IEEE Trans. Geosci. Rem. Sens.*, 49(8), 2838-2846
- ▶ Heid and Kääb, (2012): *Evaluation of existing image matching methods for deriving glacier surface displacements globally from optical satellite imagery.* *RSE*, 118, 339-355.
- ▶ Rosenau et al., 2015. *A processing system to monitor Greenland outlet glacier velocity variations at decadal and seasonal time scales utilizing the Landsat imagery.* *RSE*, 169, 1-19
- ▶ Altena and Kääb, *In Rev., Remote Sensing*



questions?