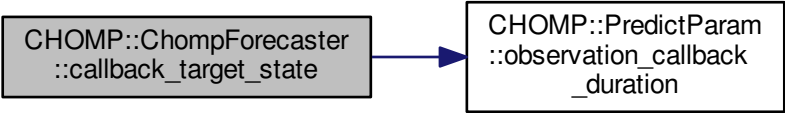


CHOMP::ChompForecaster
::callback_target_state



```
graph LR; A[CHOMP::ChompForecaster::callback_target_state] --> B[CHOMP::PredictParam::observation_callback_duration]
```

CHOMP::PredictParam
::observation_callback
_duration