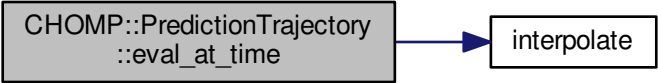


CHOMP::PredictionTrajectory  
::eval\_at\_time



```
graph LR; A[CHOMP::PredictionTrajectory::eval_at_time] --> B[interpolate]
```

interpolate