

REGISTER RENAMING

dynamic scheduling, with out of order completions - must preserve exception behaviour. there must not imprecise exceptions (when program sequence order is not maintained).

to allow out of order execution, ID pipe stay in split into 2 stages.

- ① issue - decode the instruction
- ② check for structural hazards.
- ③ read opers - wait until no data hazards. then read operands.

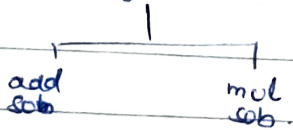
We must be able to distinguish when an instruction begins and when it completes, and in between we have, instr. execution.

dyn. sched.

allows multiple instr. to be executed at the same time

without this capability a major advantage of dynamic scheduling is lost.

this requires multiple functional units and pipeline functional units, integer unit + floating point unit,



or both.

early days - called "scoreboarding" out of order execution, CDC 6600.

TOMASOLO'S ALGO

WAR, WAW, hazards.

handles anti dependencies and output dependencies by effectively renaming registers dynamically.

can be extended for handling dynamic speculative execution. (temporary stored in buffer).

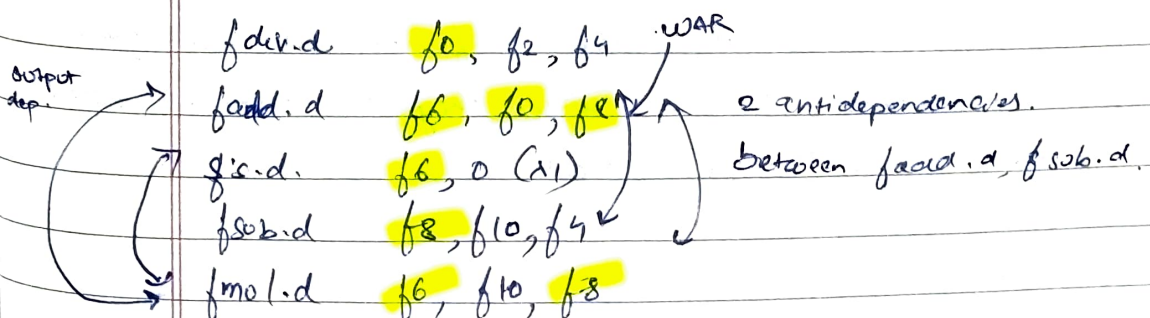
en tomasolo's algo can be extended to handle speculation.

DYNAMIC SCHEDULING USING TOMASOLO'S APPROACH

employed in IBM 360/91 (purely for commercial apps.)
(some models for scientific apps.) FPO ops.

floating point unit has this tomasolo's.

the scheme minimize RAW hazards, and introduces register renaming. this register renaming is to avoid WAW and WAR hazards.



output dependencies between $f_{add,d}$ and $f_{mul,d}$,

WAR hazard in the use of f_8 by $f_{add,d}$ and $f_{sub,d}$,

WAW hazard between $f_{add,d}$ and $f_{mul,d}$,

data.

there are also 3 true dependencies:

- ① between $f_{div,d}$ & $f_{add,d}$
- ② between $f_{sub,d}$ & $f_{mul,d}$
- ③ between $f_{add,d}$ & $f_{f,d}$,

temporary registers: iS and T .

$f_{div,d}$ f_0, f_2, f_4

$f_{add,d}$ S, f_0, f_8

$f_{sub,d}$ $S, O(x_1)$

$f_{f,d}$ T, f_6, f_4

$f_{mul,d}$ f_8, f_{10}, T .

In this scheme, register renaming is provided by reservation stations, reservation stations other than centralized registers file.

- ① hazard detection and execution control are distributed.
- ② results are directly passed to functional units from the reservation stations where they are offered, rather than going through registers.

there are 3 steps in execution. (Tomasso's algo).

- ① issue. (reservation station should be free).
- ② execute. (if both oper. are available, else wait in res. stat.)
- ③ write result. (result will be put on common data bus)

there are 2 fields in the reservation stat.

each reservation station has 7 fields.

Op. ① operation to be carried out (perform) on source operands S_1 and S_2 . Q_j, Q_k .

$Q_j, Q_k \rightarrow$ reservation stations that will produce the

V_j, V_k corresponding source operands.

\rightarrow the value of the source operands

A: \rightarrow used to hold information for the memory address.

Busy: \rightarrow indicates that this reservation station and its accompanying functional units are occupied.

the register file has a field Q_i

- ① fld. $f6, 32(x2)$
- ② fld $f2, 44(x3) \leftarrow$ effective address.
- ③ fmul.d $f0, f2, f4$.
- ④ fsub.d $f8, f2, f6$.
- ⑤ fdiv.d $f10, f0, f6$.
- ⑥ fadd.d $f6, f8, f2$.

INSTRUCTION STATUS

Instruction	issue	execute	write result.
①	✓	✓	✓
②	✓	✓	
③	✓		
④	✓		
⑤	✓		
⑥	✓		

RESERVATION STATIONS

Op name	busy	op	v_j	v_k	q_j	q_k	A
load1	X						
load2	✓	f2f					44 (reg.) ↑ reg.
add1	✓	sub			mem[32[x2]]	load2	
add2	✓	add				add1	load2
add3	X						
mul1	✓	mul			regs[4x4] mem[32[x2]]	load2	
mul2	✓	div			mem[32[x2]]	mul1	

REGISTER STATUS

field.	F0	F2	f4	f6	f8	f10	f12	f14
Q:	mult1	load2		add2	add1	mult2		