

- Boundary value problems.
- Shooting method.
- Equilibrium boundary value method/ Finite difference method.
- Eigenvalue problems.

- Boundary-value problems – involve differential equations with specified boundary conditions: example: one-dimension second order ODE (where  $p$  and  $q$  are some constants)

$$\frac{d^2y}{dx^2} + p\frac{dy}{dx} + q = f(x)$$

with  $y(x_1) = y_1$  and  $y(x_2) = y_2$ .

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- The boundary-value problem is more difficult to solve than the similar initial-value problem with the same differential equation.

- There are three type of boundary conditions for boundary-value problems.

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- The function  $y(x)$  is specified – Dirichlet boundary conditions
- The derivatives  $y'(x)$  is specified – Neumann boundary conditions
- A combination of  $y(x)$  and  $y'(x)$  is specified – mixed boundary conditions

- The shooting method.



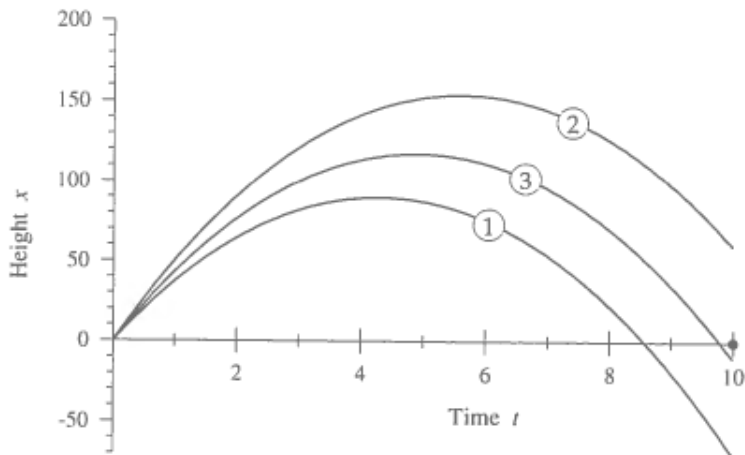
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# The shooting method



Rather than initial position and velocity, initial and final positions are specified. Start with guess velocity and adjust it to get a solution that satisfies the boundary condition.

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- Only boundary condition on one side is used as one of the initial conditions. The additional initial condition is assumed.
- Then an iterative approach is used to vary the assumed initial condition till the boundary condition on the other side is satisfied.

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- Quite often the fourth-order Runge-Kutta is combined with the secant method.

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- Using secant method for root finding:

$$z_{k+1} = z_k - \frac{c_k - y_2}{c_k - c_{k-1}}(z_k - z_{k-1})$$

- Discretizing the continuous solution domain into a discrete finite difference grid.

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- Substituting the FDAs into the ODE to obtain an algebraic finite difference equation.
- Solving the resulting system of algebraic FDEs (for linear ODEs – a system of linear equations)

# The equilibrium boundary-value problem

- Consider a second order, linear, variable coefficient, boundary value problem with Dirichlet boundary conditions:

$$y''(x) + P(x)y'(x) + Q(x)y(x) = F(x)$$

with  $y(x_1) = y_1$  and  $y(x_N) = y_N$

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- Discretizing the domain of  $x$  into  $N$  points  $x_1, x_2, \dots, x_N$
- The second order centered difference approximation for  $y'$  and  $y''$ :

$$y'(x_i) = y'_i = \frac{y_{i+1} - y_{i-1}}{2\Delta x} + \mathcal{O}(\Delta x^2)$$

$$y''(x_i) = y''_i = \frac{y_{i+1} - 2y_i + y_{i-1}}{\Delta x^2} + \mathcal{O}(\Delta x^2)$$

# The equilibrium boundary-value problem

- Substituting this into the differential equation and keeping terms upto order  $\mathcal{O}(\Delta x^2)$ :

$$\frac{y_{i+1} - 2y_i + y_{i-1}}{\Delta x^2} + P_i \left( \frac{y_{i+1} - y_{i-1}}{2\Delta x} + \right) + Q_i y_i = F_i$$

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- Multiplying by  $\Delta x^2$  and rearranging:

$$\left(1 - \frac{\Delta x}{2} P_i\right) y_{i-1} + (-2 + \Delta x^2 Q_i) y_i + \left(1 + \frac{\Delta x}{2} P_i\right) y_{i+1} = \Delta x^2 F_i$$

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- Applying this to all the points on the grid yields a tridiagonal system of equations.
- Number of equations =  $N - 2$  – can solve this easily with a linear equation solver. Need to be careful about imposing boundary condition.

- Example 4th order problem:

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- For first/second derivative:  $i - 1, i, i + 1$   
For third/fourth derivative:  $i - 2, i - 1, i, i + 1, i + 2$
- Leads to a pentadiagonal system.

- Consider a second order, linear, variable coefficient, boundary value problem with Neumann boundary conditions:

$$y''(x) + P(x)y'(x) + Q(x)y(x) = F(x)$$

with  $y(x_1) = y_1$  and  $y'(x_N) = y'_N$

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- The equilibrium method needs some modification:

$$\left(1 - \frac{\Delta x}{2} P_i\right) y_{i-1} + (-2 + \Delta x^2 Q_i) y_i + \left(1 + \frac{\Delta x}{2} P_i\right) y_{i+1} = \Delta x^2 F_i$$

remains the same at all the interior points.

- We also apply this equation to the boundary point:

$$\left(1 - \frac{\Delta x}{2}P_N\right)y_{N-1} + (-2 + \Delta x^2Q_N)y_N + \left(1 + \frac{\Delta x}{2}P_N\right)y_{N+1} = \Delta x^2F_N$$



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- The point  $y_{N+1}$  is outside the domain but:

$$y'_N = \frac{y_{N+1} - y_{N-1}}{2\Delta x}$$
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- Substituting this in the equation for  $N$  point:

$$2y_{N-1} + (-2 + \Delta x^2Q_N)y_N = \Delta x^2F_N - \Delta x(2 + \Delta xP_i)y'_N$$

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- Again a tridiagonal system of equations.

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- Replace  $\infty$  with a large value of  $x$  ( $x = X$ )
- Asymptotic solution at large values of  $x$

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- Problem with the method near the boundaries.. central differencing cannot be applied near the boundaries. So, some forward/backward differencing is used there.

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- With the shooting method, the solution of nonlinear boundary value problems is quite straightforward.
- With the finite differencing, this is much more complicated as the corresponding Finite differencing Equation is non-linear. This leads to a non-linear system of FDE's. Have to use Newton's iteration method to solve these.

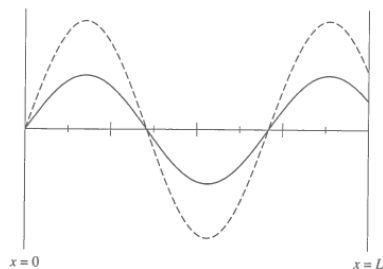
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# Systems of 2nd order boundary value problems

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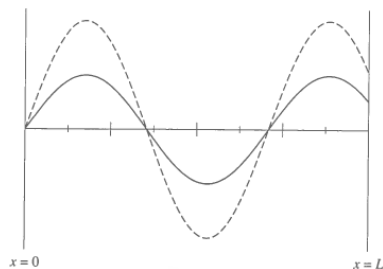
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- By either approach, the solution is quite difficult.



- A special BVP for linear, homogeneous equation. E.g., time-independent Schrödinger equation

$$-\frac{\hbar^2}{2m} \frac{d^2\psi}{dx^2} + V(x)\psi = E\psi.$$

# Eigenvalue problems



- A special BVP for linear, homogeneous equation. E.g., time-independent Schrödinger equation
$$-\frac{\hbar^2}{2m} \frac{d^2\psi}{dx^2} + V(x)\psi = E\psi.$$
- Consider a particle-in-a-box with potential zero within  $[0, L]$  and infinite outside this. BC:  $\psi = 0$  at  $x = 0, L$ . Cannot adjust  $\psi'(0)$  to make  $\psi$  vanish at  $x = L$  for a general  $E$ . Must adjust  $E$  (eigenvalue) to ensure  $\psi(L) = 0$ . Thus, adjust  $E$  and not  $\psi'(0)$  to satisfy the BC.