

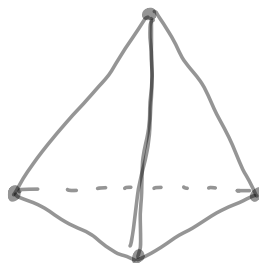
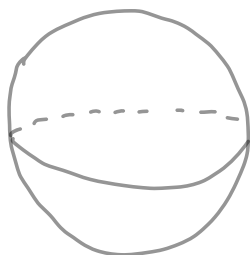
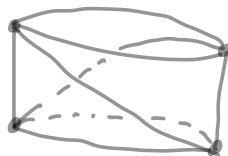
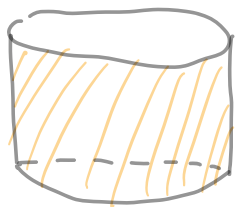
# Morse theory

- Hand-wavy view of
  - How the game of differential topology feels like.
- More careful look at
  - What happens near  $\text{gradient} = 0$   
(Morse lemma)
  - Cartoons and toy examples

# The game of cut and glue



A large part of classical topology concerns how to iteratively construct a good topology space using simple ingredients.



- Triangulations



- "cut - and - paste"

(Anybody played  ?)

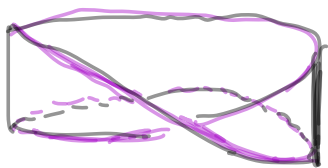
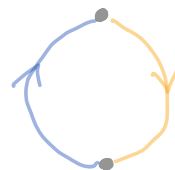
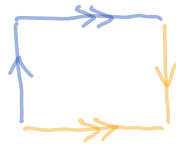
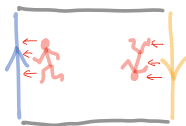
Cylinder :  

Torus :  (  $\stackrel{\text{homeo}}{\simeq}$   , can you see ? )

Exercise :

What are these ?

$\mathbb{RP}^2$

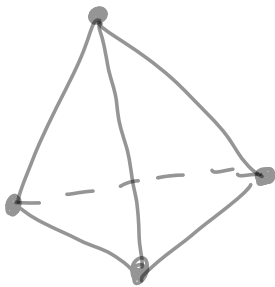


# Euler characteristics

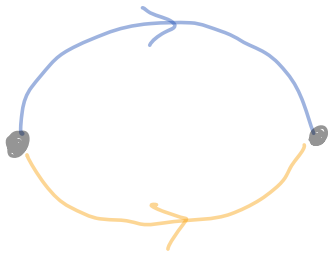
Invariance

$$\chi = \overset{\#\{\text{vertices}\}}{V} - \overset{\#\{\text{edges}\}}{E} + \overset{\#\{\text{faces}\}}{F} \quad \text{only depends}$$

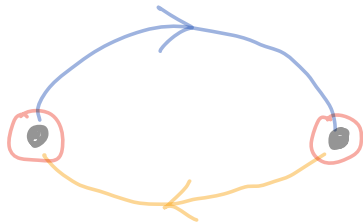
on the topology of the space



$$\chi = 4 - 6 + 4 = 2$$



$$\chi = 2 - 2 + 1 = 1$$



the two are glued to be the same vertex

$$\chi = 1 - 2 + 1 = 0$$

Try others

Take-away:

- Topologists decompose manifolds into unit discs:

vertex :  $D^0$  0-dim "disc"

edge :  $D^1$  1-dim "disc"

face :  $D^2$  2-dim disc

( you can go to higher dim ! )

- Euler characteristic : alternating sum of them  $\Rightarrow$  invariant under homeomorphism

## Gradient flow and Morse lemma

Given a differentiable submanifold

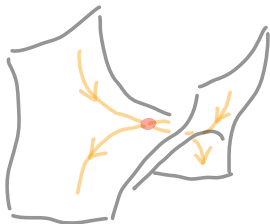
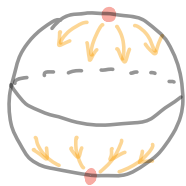
$X \subset \mathbb{R}^N$ , a differentiable function  
 $f: X \rightarrow \mathbb{R}$

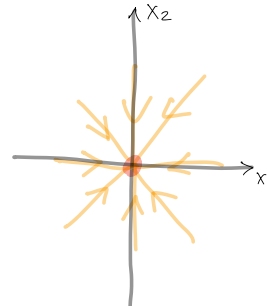
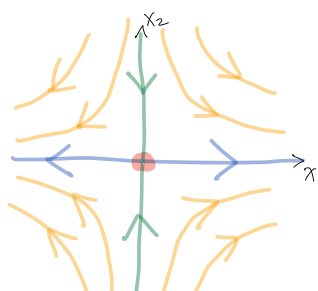
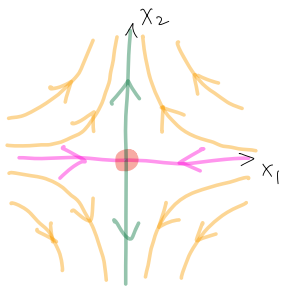
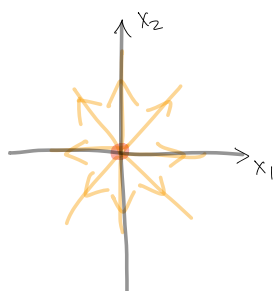
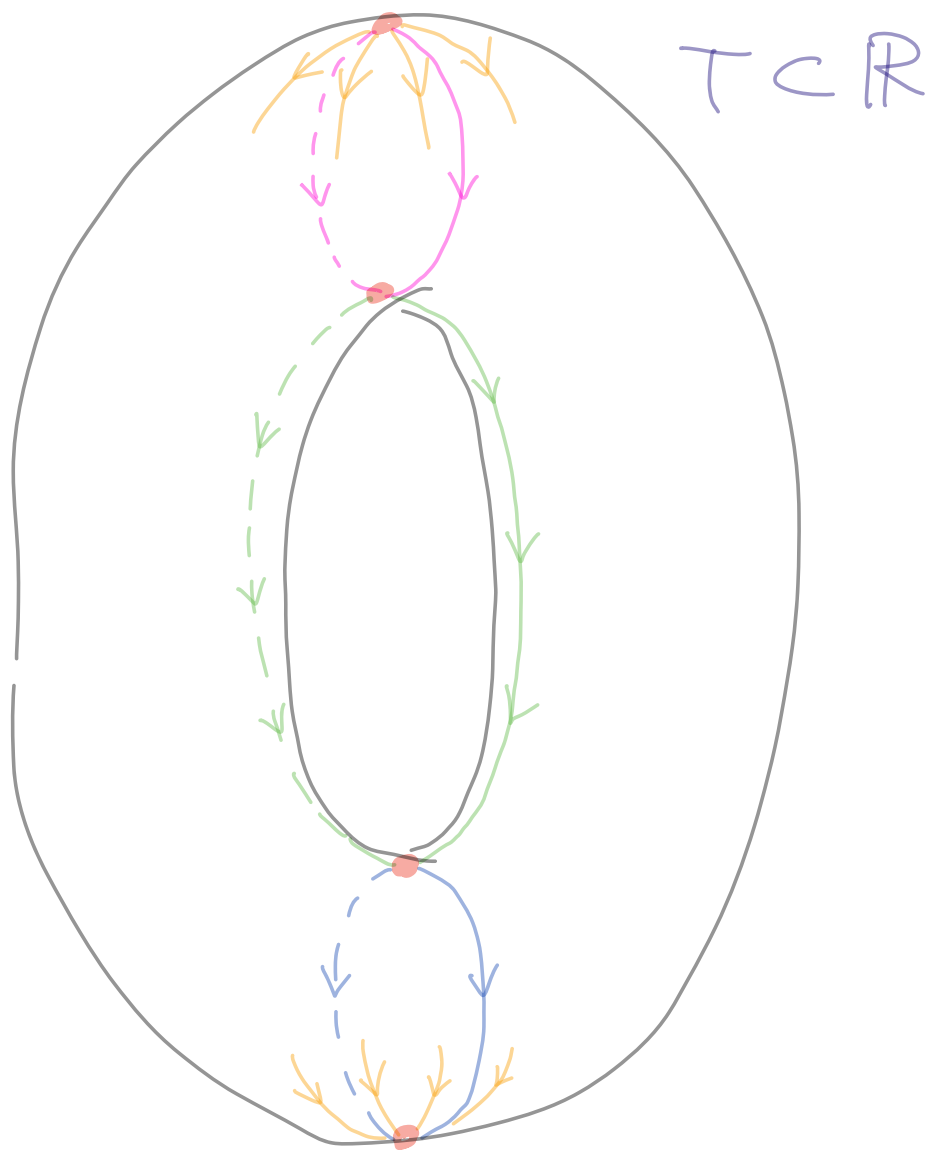
It induces a gradient flow

$\forall x \in X, v \in T_x X,$

$$d_x f(v) = \langle \nabla_x f, v \rangle$$

Critical points :  $x \in X, \nabla_x f = 0$





e.g.

$$f(x_1, x_2) = -x_1^2 - x_2^2$$

$$f(x_1, x_2) = x_1^2 - x_2^2$$

$$f(x_1, x_2) = -x_1^2 + x_2^2$$

$$f(x_1, x_2) = x_1^2 + x_2^2$$

## Hessian:

( Given a local coordinate )

$$f: \mathbb{R}^M \rightarrow \mathbb{R}$$

$$H_f(x) := \left( \frac{\partial^2 f}{\partial x_i \partial x_j} \right)_{1 \leq i, j \leq M}$$

It depends on the local coordinates ,  
but if  $(x_i=0)$  is a critical pt ,  
Jacobian matrix acts on it as

$$J H_f(x) J^T = H_f(y)$$

"Invariant symmetric bilinear form"

"Tensor" ( the real meaning haha )



When there is a change of variable  $y_i = y_i(x_1, \dots, x_M)$ ,  $1 \leq i \leq M$

(adopting Einstein summation)

$$\frac{\partial^2 f}{\partial x_i \partial x_j} = \frac{\partial \left( \frac{\partial f}{\partial y_{i'}} \cdot \frac{\partial y_{i'}}{\partial x_i} \right)}{\partial y_{j'}} \frac{\partial y_{j'}}{\partial x_j}$$

$$= \frac{\partial^2 f}{\partial y_{i'} \partial y_{j'}} \cdot \frac{\partial y_{i'}}{\partial x_i} \frac{\partial y_{j'}}{\partial x_j}$$

$$+ \underbrace{\frac{\partial f}{\partial y_{i'}}}_{=0} \cdot \frac{\partial^2 y_{i'}}{\partial x_i \partial y_{j'}} \frac{\partial y_{j'}}{\partial x_j}$$

Given a matrix  $M$ ,  
 what are unchanged in  $JMJ^T$   
 for nondegenerate  $J$ ?

- rank
- the index

$$M \sim \begin{pmatrix} 0 & \cdots & 0 & & \\ & 0 & & & \\ & & 1 & \cdots & \\ & & & 1 & \cdots \\ & & & & 1 & \cdots \\ & & & & & -1 & \cdots \\ & & & & & & -1 & \cdots \\ & & & & & & & -1 & \cdots \end{pmatrix}$$

$\left. \begin{array}{c} \text{rank} \\ \text{index} \end{array} \right\}$

## Morse function :

$f: X \rightarrow \mathbb{R}$  such that the Hessian at any critical point is nondegenerate.

## Morse lemma :

Given a Morse function

$f: X \rightarrow \mathbb{R}$ , a critical pt  $p \in X$

there exists a coordinate  $x_1, \dots, x_M$

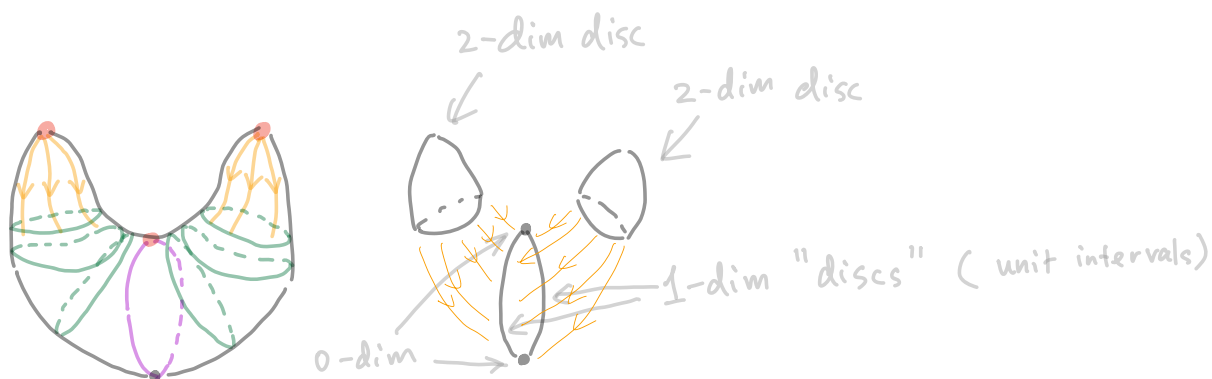
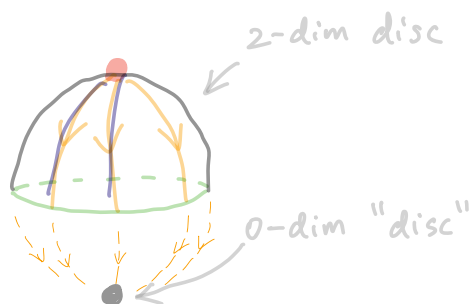
$$f = -x_1^2 - x_2^2 - \dots - x_{\text{ind}(p)}^2 + x_{\text{ind}(p)}^2 + \dots + x_M^2$$

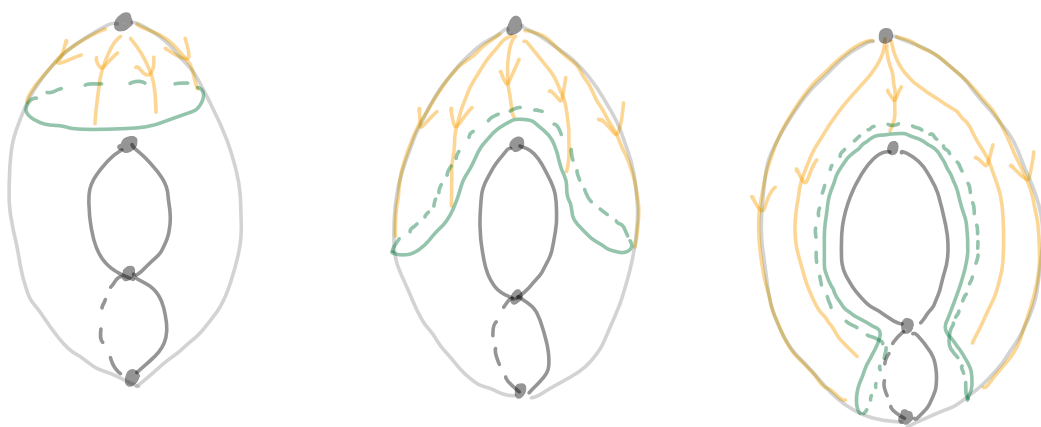
where  $\text{ind}(p) := \text{index of } H_f(p)$

Take-away :  $X$  and  $f$  can be easily described near crit. pt, fully determined by index.

## What's the point here?

- Any submfd  $X \subset \mathbb{R}^N$  admits a Morse function.
- Gradient flow of Morse function induces a decomposition of  $X$  which unveils its topology.

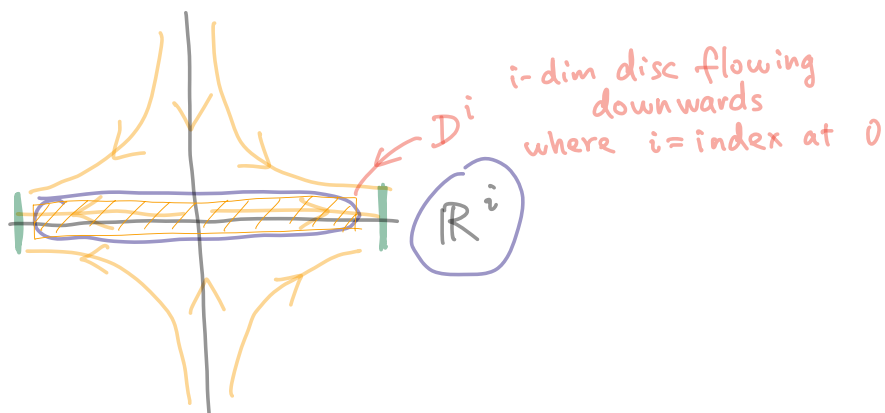




locally

$\mathbb{R}^{n-i}$

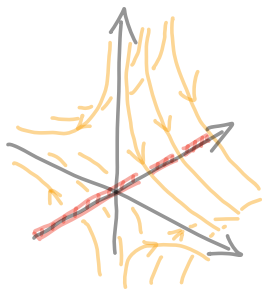
index  $i$



Take-away:

- Index  $i$  at  $p \iff$  Attaching disc  $D^i$  at  $p$
- Euler characteristic = alternating sum of the counts of indices

What happens if Hessian degenerates?



will form critical submanifold!

In other words, "loss valleys"



Some final referencing keywords:

	SLT	differential topology
nondeg. Hessian	regular model	Morse theory
deg. Hessian	singular model	Morse-Bott theory

(There is an infinite dim version, where  
function  $\leftrightarrow$  functional, "Floer theory")