EAI Math Reading Group

Neural Tangent Kernels

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Outline

- 1. Kernel methods 101
- 2. Neural Tangent Kernel
- 3. Theoretical results

Kernel Functions

A (positive definite) kernel function on X is a symmetric function $k: X imes X o \mathbb{R}$ such that

$$\sum_{i,j=1}^n c_i c_j k(x_i,x_j) \geq 0$$

for any $x_1,\ldots,x_n\in X$, $c_1,\ldots,c_n\in\mathbb{R}$

i.e. the matrix $[k(x_i,x_j)]_{ij}$ is positive definite

Reproducing Kernel Hilbert Spaces

Every p.d. kernel K induces a (unique) Reproducing Kernel Hilbert Space (RKHS) $(H,\langle.\,,.\,
angle_H)$ of functions $X o\mathbb{R}$ with

1.
$$K_x = K(x,.) \in H, orall x \in X$$

2.
$$\langle f, K_x \rangle_H = f(x), \forall f \in H, \forall x \in X$$

Intuition: Kernel methods are essentially equivalent to projecting X to a Hilbert space, via some feature map $\Phi:X\to H$

$$K(x,y) = \langle \Phi(x), \Phi(y)
angle_H$$

Gaussian Processes

A Gaussian Process is a stochastic process $X: \mathbb{X} o \mathbb{R}^d$, such that for any $x_1, \dots, x_n \in \mathbb{X}$,

$$[X(x_1),\ldots,X(x_n)] \sim \mathcal{N}(\mu_{x_1,\ldots,x_n},\Sigma_{x_1,\ldots,x_n})$$

Intuition: "Gaussian distribution" over functions

$$X \sim \mathcal{GP}(\mu, \Sigma)$$

NB. $\Sigma : \mathbb{X} \times \mathbb{X}$ is a p.d. kernel!

Realization function

NB. F only contains the functions of for I to Of

Neural Network

$$f_{ heta}(x) = (arphi^{(L)} \circ \cdots \circ arphi^{(0)})(x)$$

- $ig|ullet arphi^{(\ell)}(x_\ell) = \sigma.\,(ildearphi^{(\ell)})(x_\ell)$
- $oldsymbol{ar{arphi}^{(\ell)}(x_\ell)} = rac{1}{\sqrt{n_\ell}} W^{(\ell)} x_\ell + eta b^{(\ell)}$
- $oldsymbol{ heta} oldsymbol{ heta} = (W^{(0)}, \overset{ extbf{v}}{b^{(0)}}, \ldots, \overset{ extbf{v}}{W^{(L)}}, \overset{ extbf{v}}{b^{(L)}})$
- $ullet W_{ij}^{(\ell)}, b_i^{(\ell)} \sim \mathcal{N}(0,1)$

Tangent 1: Neural Network Gaussian Processes

The induced distribution in ${\mathcal F}$ is a Gaussian Process

$$f_{ heta} \sim \mathcal{GP}(0, K^L)$$

where K^L converges to a deterministic limit as

$$n_0,\dots,n_L o\infty$$

Intuition: The pre-activations of each layer is a sum of Gaussian random variables (the parameters) weighted by the inputs.

Training

Training a model involves minimizing some cost $\mathcal{C}:\mathcal{F} o\mathbb{R}$

Problem:

even if ${\mathcal C}$ is convex in ${\mathcal F}$, the parametrized function ${\mathcal C}\circ F^L$ might not be

Multi-dimensional kernel

symmetric function $K:\mathbb{R}^{n_0} imes\mathbb{R}^{n_0} o\mathbb{R}^{n_L imes n_L}.$

Induced bilinear map on ${\mathcal F}$

$$\langle f,g
angle_K=\mathbb{E}_{x,y\sim p_{in}}[f(x)^TK(x,y)g(y)]$$

K is p.d. with respect to $\|.\|_{p_{in}}$ if

$$\|f\|_{p_{in}}>0 \;\Rightarrow\; \|f\|_K=\sqrt{\langle f,f
angle_K}>0$$

Dual space

$$\mathcal{F}^* = \mathcal{L}(\mathcal{F}, \mathbb{R}) \ \mu \in \mathcal{F}^* \Rightarrow \exists d \in \mathcal{F} ext{ s.t.}$$

$$\mu(f) = \langle d, f
angle_{p_{in}}$$

NB. due to p_{in} , it is *finite* dimensional

Mapping from \mathcal{F}^* to \mathcal{F}

For
$$i\in 1,\ldots,n_L$$
, $x\in \mathbb{R}^{n_0}$, $K_{i,.}(x,.)\in \mathcal{F}$
Define $\Phi_K:\mathcal{F}^* o \mathcal{F}; \mu\mapsto f_\mu$
 $f_{\mu,i}(x)=\mu(K_{i,.}(x,.))=\langle d,K_{i,.}(x,.)
angle_{p_{in}}$

Tangent 2: Functional Derivatives

Let f:X o Y be a map between normed spaces. f is differentiable at $x_0\in X$ if there exists $L\in \mathcal{L}(X,Y)$ s.t. orall arepsilon>0, $\exists \delta>0$

$$\|x-x_0\|_X < \delta \ \Rightarrow \ rac{\|f(x)-f(x_0)-L(x-x_0)\|_Y}{\|x-x_0\|} < arepsilon$$

$$L = Df(x_0)$$

Special case: $f:X o \mathbb{R}$ $Df(x_0)\in \mathcal{L}(X,\mathbb{R})=X^*$ (dual space of X)

$$T^{\times} = f(f, R)$$

$$f_{\text{dual}}$$

$$f_{\text{space}}$$

$$f_{\text{un dion}}$$

$$f_{\text{space}}$$

$$f_{\text{un dion}}$$

$$f_{\text{space}}$$

$$f_{\text{un dion}}$$

$$f_{\text{purameter}}$$

$$f_{\text{purameter}}$$

$$f_{\text{space}}$$

$$f_{\text{purameter}}$$

$$f_{\text{space}}$$

$$f_{\text{space}}$$

$$f_{\text{un dion}}$$

$$f_{\text{un dion$$

Kernel Gradient

$$|
abla_K \mathcal{C}|_{f_0} = \Phi_K(D_{in} \mathcal{C}(f_0))$$

On empirical dataset:

$$|
abla_K \mathcal{C}|_{f_0} = rac{1}{N} \sum_{j=1}^N K(x,x_j) d|_{f_0}(x_j)$$

Kernel gradient descent

 $f(t) \in \mathcal{F}$ follows the *kernel gradient descent* with respect to kernel K iff

$$\partial_t f(t) = -
abla_K \mathcal{C}|_{f(t)}$$

The cost $\mathcal{C}(f(t))$ evolves as

$$\|\partial_t \mathcal{C}|_{f(t)} = -\langle d|_{f(t)},
abla_K \mathcal{C}|_{f(t)}
angle_{p_{in}} = \|d|_{f(t)}\|_K^2$$

- If K is p.d. with respect to $\|.\|_{p_{in}}$, then f converges to a critical point of $\mathcal C$ (which is decreasing).
- ullet If ${\mathcal C}$ is convex and bounded below, f converges to a global minimum.

Example: Random Functions approximation

Given a kernel K, we can approximate it by sampling P random functions $f^{(p)}$ from a distribution whose covariance is given by K:

$$\mathbb{E}[f_k^{(p)}(x)f_{k'}^{(p)}(x')] = K_{kk'}(x,x')$$

Random Linear parametrization F^{lin} :

$$heta \mapsto f_{ heta} = rac{1}{\sqrt{P}} \sum_{p=1}^P heta_p f^{(p)}$$

Example: Random Fourier Features

Example: Random Functions approximation

$$\partial_{ heta_p} f_{ heta} = rac{1}{\sqrt{P}} f^{(p)}$$

Optimizing $C\circ F^{lin}$ via gradient descent yields

$$\partial_t heta_p(t) = -rac{1}{\sqrt{P}} D_{in} C(f_{ heta(t)}) f^{(p)} = -rac{1}{\sqrt{P}} \langle d|_{f_{ heta(t)}}, f^{(p)}
angle_{p_{in}}$$

Example: Random Functions approximation

$$\partial_t f_{ heta(t)} = rac{1}{\sqrt{P}} \sum_{p=1}^P \partial_t heta_p(t) f^{(p)} = -rac{1}{P} \sum_{p=1}^P \langle d|_{f_{ heta(t)}}, f^{(p)}
angle_{p_{in}} f^{(p)}$$

Tangent Kernel

$$ilde{K} = \sum_{p=1}^P \partial_{ heta_p} F^{lin}(heta) \otimes \partial_{ heta_p} F^{lin}(heta) = rac{1}{P} \sum_{p=1}^P f^{(p)} \otimes f^{(p)}$$

Neural Tangent Kernel

For neural networks, the network function follows the kernel gradient descent

$$\partial_t f_{ heta(t)} = -
abla_{\Theta^{(L)}} \mathcal{C}|_{f_{ heta(t)}}$$

with the neural tangent kernel

$$\Theta^{(L)}(heta) = \sum_{p=1}^P \partial_{ heta_p} F^{(L)}(heta) \otimes F^{(L)}(heta)$$

which corresponds to the feature map $x \mapsto
abla_{ heta} f_{ heta}(x)$

Infinite width limit

Training

Suppose parameters are updated in some training direction $d_t \in \mathcal{F}$:

$$\partial_t heta_p(t) = \left\langle \partial_{ heta_p} F^{(L)}(heta(t)), d_t
ight
angle$$

such that $\int_0^T \|d_t\|_{p_{in}} dt$ is stochastically bounded, then as $n_1, \dots, n_L o \infty$

$$\Theta^{(L)}(t) o \Theta^{(L)}_{\infty} \otimes I_{n_L}$$

NB. σ Lipschitz, with bounded second derivative

Positive Definiteness

The NTK is already positive semidefinite.

For positive definiteness, we need the span of $\partial_{ heta_p} F^{(L)}$ to be dense in $(\mathcal{F},\|.\|_{p_{in}})$

NB. The pre-activations of the last layer appear in $\partial_{ heta_p}F^{(L)}$ are dense for many p_{in} and activation functions (by Universal Approximation Theorems)

Example: least-Square regression C(f) = 1 / f / f / pin linear operation analytical Solution: 1 = 1 * + e - t [* - fo] exponential operator $e^{-t\Pi_{5}} \sum_{k=0}^{\infty} \frac{(-t)^{k}\Pi^{k}}{k!}$

If
$$\Pi = \sum_{i} \lambda_{i} \{f^{(i)}, \dots \} f^{(i)}$$
; $e^{-t\Pi} = \sum_{i} e^{-\lambda_{i}t} \{f^{(i)}, \dots \} f^{(i)}$

finite olataset: $\Pi_{f_{i}}(x) = \frac{1}{N} \sum_{i=1}^{N} \sum_{k'=1}^{N} f_{k'}(x_{i}) K_{kk'}(x_{i}, x)$
 \Rightarrow at most Nn_{L} eigenfunctions \Rightarrow Remel PCA

 $(f^{*} - f_{0}) = \Delta_{f}^{\circ} + \Delta_{f}^{\circ} + \dots + \Delta_{f}^{Nn_{L}}$
 $f_{t}^{*} = f^{*} + \Delta_{f}^{\circ} + \sum_{i=1}^{N} e^{-t\lambda_{i}} \Delta_{f}^{\circ}$
 $f_{t}^{*} = f^{*} + \Delta_{f}^{\circ} + \sum_{i=1}^{N} e^{-t\lambda_{i}} \Delta_{f}^{\circ}$
 $f_{t}^{*} = f^{*} + \Delta_{f}^{\circ} + \sum_{i=1}^{N} e^{-t\lambda_{i}} \Delta_{f}^{\circ}$

Probabiliste interpretation taking tox for for the April 5 for 5 Al + (fo(x) - Kx, k K yo) $\int_{\infty,k} (x) = k_{x,k}^T \widetilde{K}^{-1} y^*$ Centered Gaussian MAP estimate for $\int_{0}^{\pi} \int_{0}^{\pi} \int_{0}^{\pi} \left(\int_{0}^{\pi} \left(x_{i} \right) \right) h_{i} dt$ fu ~ GP(0, 00) $K_{x,k} = \left(K_{kk'}(x,x_i)\right)_{i,k'}$ $K = \left(K_{kh'}(x_i,x_i)\right)_{i,k'}$ = Remel Regression estimate

Summary

- Can use (Neural) Tangent Kernel to describe model evolution during training
- Constant limit at infinite width: prove convergence with positive definiteness
- Direct Link between NNs and Kernel methods

Going Further

- NTK for other architectures (see Tensor Programs)
- Predict "maximum effective depth" for given architecture
- Designing activation functions to achieve particular NTK

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