

# Carlo Pescio

An overly simple, C++ idiomatic  
pattern language for message-  
based product families

# Time-proven

- Used many times over ~20y
- Used in small (PIC 32 w/ KB of RAM) embedded systems
- Used in “big” (i7 w/ GB of RAM) embedded systems
- N x 100K units around the world using this stuff 😊

# good design??

- ~~Principles~~
- ~~Patterns~~
- ~~Dogma~~
  - ~~Paradigm~~
  - ~~Method~~
  - ~~Technology~~



Forces -> Response

# Product family



# Product

a subset of a “feature set”

Defined extensionally :  $P = \{ F_1, \dots, F_p \}$

Most likely dynamic over time

- Products can be standard or custom
- $|P|$  is “relevant”

# Product family

a set of products

Defined extensionally :  $F = \{ P_1, \dots, P_f \}$

Dynamic over time

$$| P_i \cap P_j | \approx \frac{\sum | P_i |}{f}$$

-  $| F |$  is “relevant”

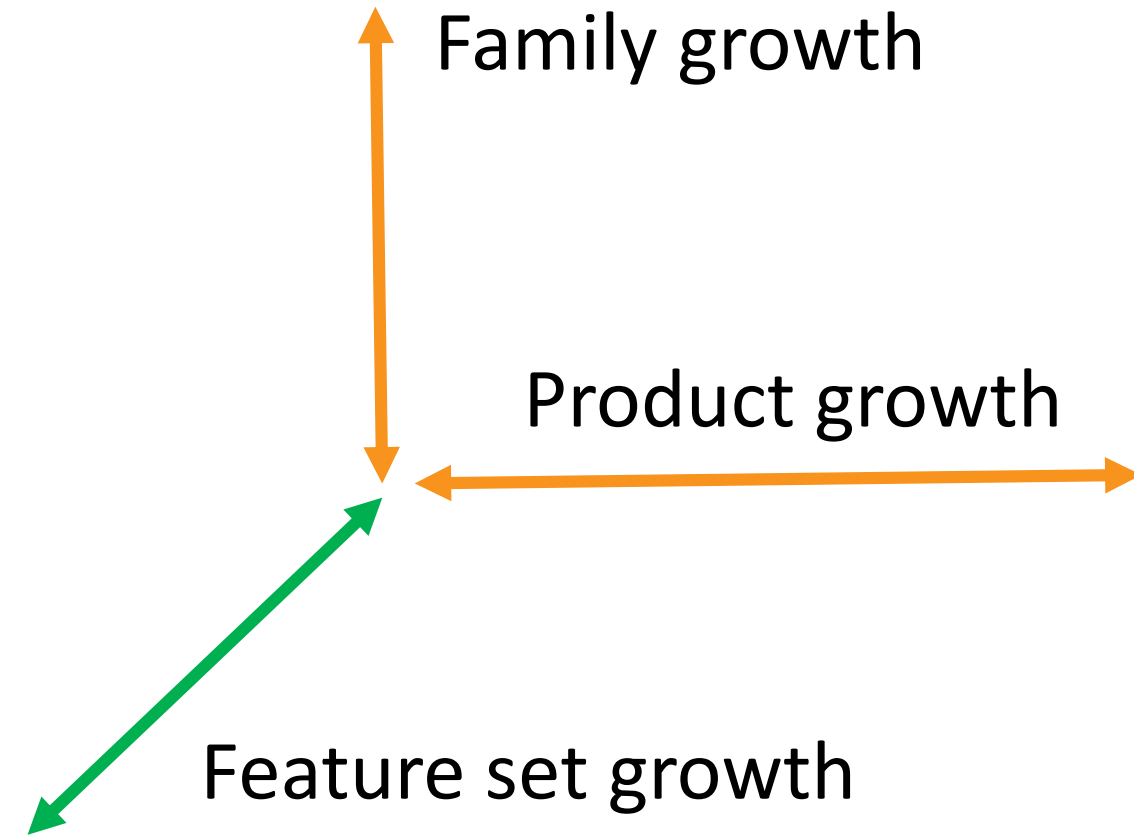
# Approaches

- Many, but mostly:
  - Full-blown + configuration
  - Selected features only

# “expansive force”

“good response”

- New feature -> New code
- Grow / shrink product
  - include / remove file
- Add product to family
  - Choose file set





# “bad response”

Custom code, “feature aware” code for each product

|F| “relevant” => lots of custom artifacts

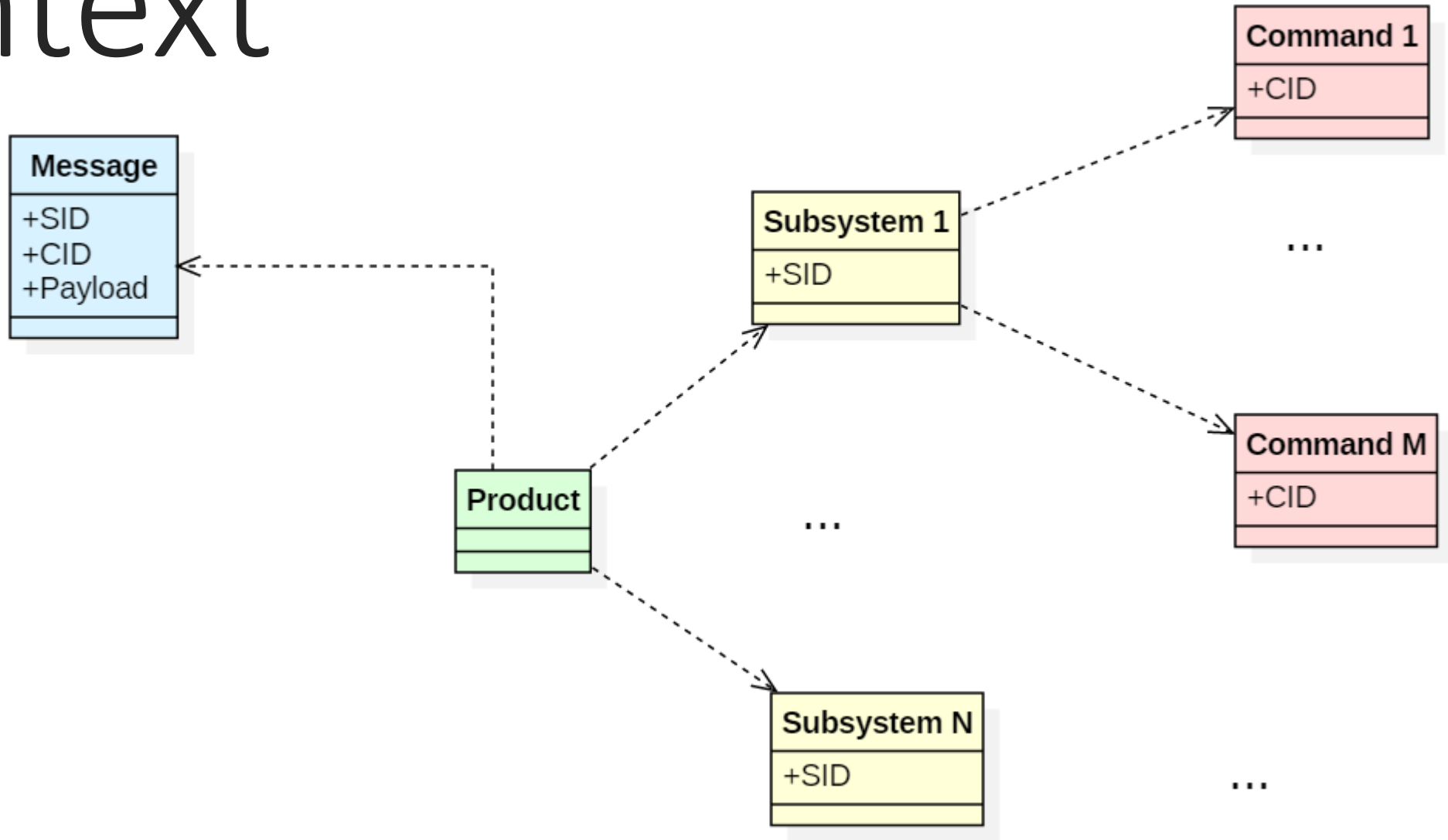
|P| “relevant” => each artifact is “relevant”

$|P_i \cap P_j| \approx \frac{\sum_i |P_i|}{f}$  => custom yet highly similar

|F| and |P| unstable and usually growing => maintenance cost

Common traps: switch/case, pattern matching, case classes, sum types, builders, ... (anything “enumerative” in nature)

# Context



# The ugliness

```
class MessageHandler // or Dispatcher
{
void handle( const Message& m )
{
    switch( m.getSubsystem() )
    {
    case SS1 :
    {
        switch( m.getCommand() )
        {
        case CMD1:
        {
            // now what?
        }
        }
    }
    }
}
```

- Ugly naming
- Can't share among products
- Maintenance black hole
- Same issue with pattern matching

# Half-hearted

I know, I'll use a map of commands!

## MessageHandler

Message -> SID,CID,params

CmdMap : (SID,CID) -> Command

Command -> Execute( params )

Ok, who is filling the map?

- A “main”
- A “factory”
  - still the same problem / shape
- A “configuration file”
  - not idiomatic (reflection?)
  - better for “full-blown”
- [ dynamic loading not available everywhere, e.g. PIC 32]

# A 1<sup>st</sup> idiomatic notion

## Self-instantiating object

Avoid the common trap of a single artifact which knows many objects.

Add a class (artifact) -> Get an object (run-time)

The object is born before main is executed. Avoids threading issues as well.

Idiomatic: can't do this in Java or C#, they only got lazy statics.

# Code: overly simple

```
class SelfCreating
{
private:
    SelfCreating()
    {
        std::cout << "I'm the magical self-creating object" << std::endl;
    }
    static SelfCreating instance;
};
```

```
I'm the magical self-creating object
I'm the main function
-
```

```
#include "SelfCreating.h"

SelfCreating SelfCreating::instance;
```

```
int main()
{
    cout << "I'm the main function" << endl;
    return 0;
}
```

# The self-creating singleton

Useful outside this restricted application.

The C++ idiomatic solution to the real hard question:

*who creates the creator?*    <<    it creates itself (seems just right too)

See:

prototype

abstract factory

factory method

etc.

# Bring in some domain

A command is a self-instantiating, stateless singleton

- Self instantiating: no one needs to “know all the commands”
- Commands register themselves with a catalog  
reversing the dependency
- Being stateless is not strictly necessary, but it’s often the right choice  
commands are ok with being stateless anyway



# A singleton (booooo!!!)

Stateless, immutable, single function -> it's a function (ooohhhhh!!!!)

Added Value: the singleton constructor will register the function in a catalog  
that's the magic functions can't do

But the catalog must be a singleton too, and **born before** (ain't that difficult?)

# Commands & subsystem

Being realistic:

same command code in different subsystems should be ok

Therefore: a command catalog for each subsystem

Therefore: the [concrete] command should know its own subsystem

it's OK, it's the opposite that we do not want (ss->cmd)

# Code: simple enough

```
class Command
{
public:
    virtual ~Command()
    {
    }

    virtual void Process(
        const char* payload) = 0;
};
```

CRTP

(2<sup>nd</sup> Idiomatic notion)

```
template<class SS, class CMD> class
RegisteredCommand : public Command
{
protected:
    RegisteredCommand()
    {
        CommandCatalog<SS::SID>::
            RegisterCommand(CMD::CID, instance);
    }
private:
    // eager singleton - MUST be eager
    static CMD instance;
};

template<class SS, class CMD> CMD
RegisteredCommand<SS, CMD>::instance;
```

# Code: simple enough

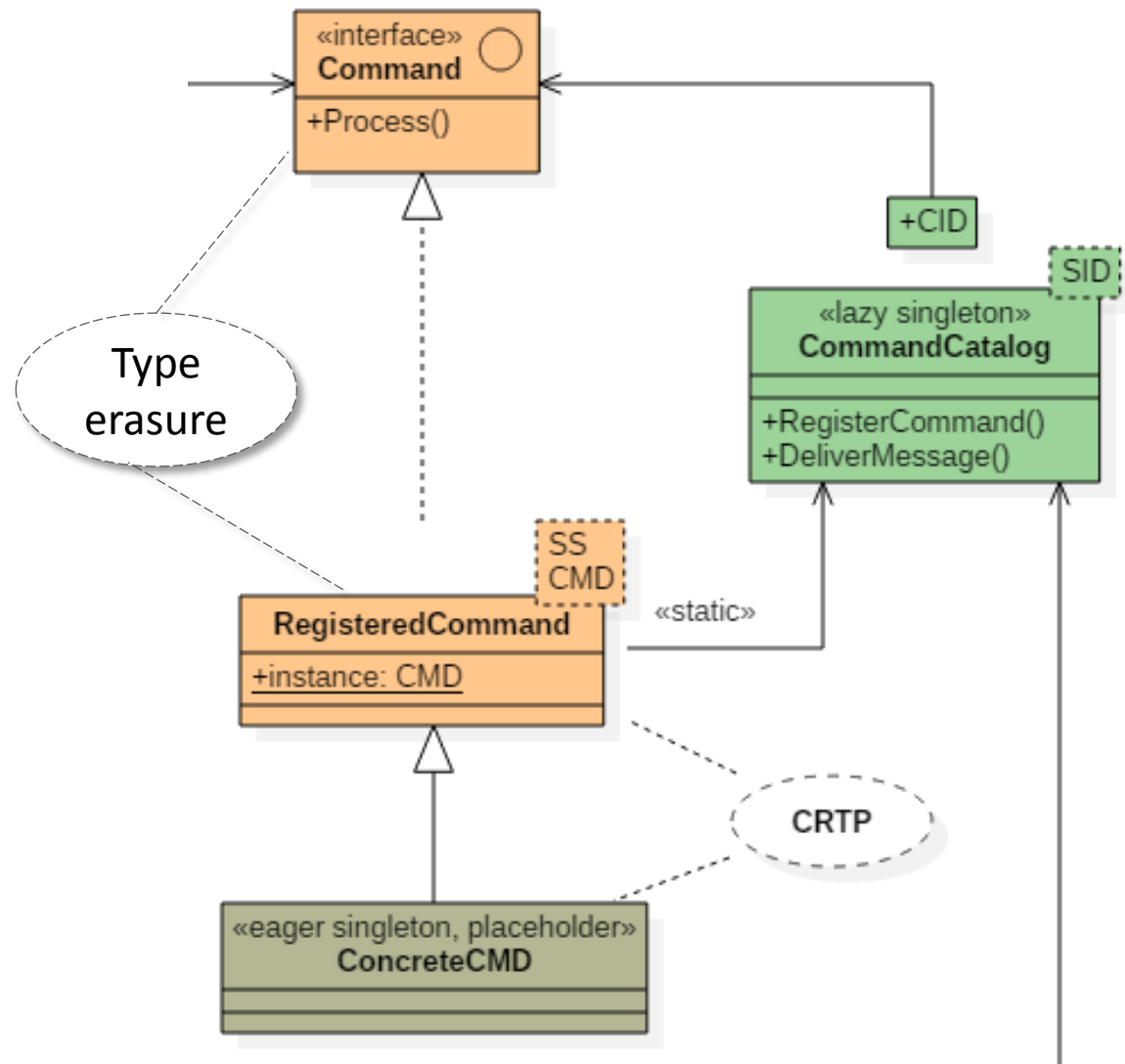
```
class StartEngineCMD : public
    RegisteredCommand< EngineSS, StartEngineCMD >
{
public:
    static const int CID = 2;

    void Process(const char* payload) override;

private:
    friend class RegisteredCommand< EngineSS, StartEngineCMD >;

    StartEngineCMD();
};
```

# UML diagram (in 2017 ?! :-)



# A 3<sup>rd</sup> idiomatic notion

A command *catalog* is a stateful, *semi-immutable* **lazy** singleton

- Lazy: simplest way to solve the initialization order problem  
commands are eagerly created before main is started,  
the first command creates the catalog as well
- The catalog is read-only / immutable when the main is started  
all mutations happen in a single thread before main is called  
**thread-safe, read-only access after that** (don't worry – live happy)

# Code: again, overly simple

```
template< int SID > class CommandCatalog
{
public:
    static void RegisterCommand(int CID, Command& c)
    {
        auto& r = Recipients();
        assert(r.find(CID) == r.end());
        std::pair< int, Command& > p(CID, c);
        r.insert(p);
    }

private:
    static std::map< int, Command& >& Recipients()
    {
        // lazy singleton - MUST be lazy
        static std::map< int, Command& > recipients;
        return recipients;
    }
};

// later
// static bool DeliverMessage(
//     const Message& m)
```

# The haiku

The lazy singleton  
is fully constructed

惰

before the eagerest singleton



# Mocking commands?

Assuming it makes sense – depends on the application  
sometimes mocking hardware resources is a better option

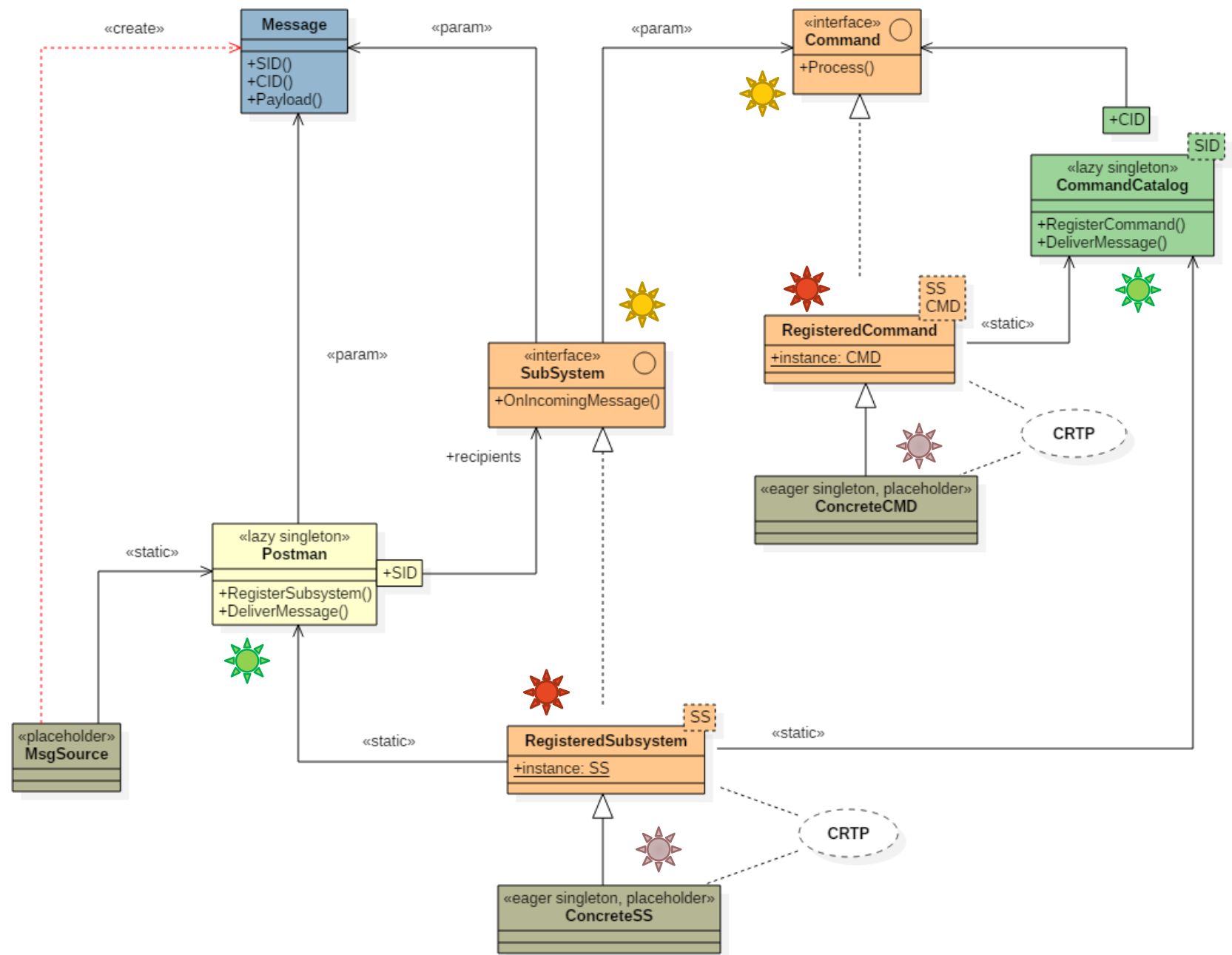
If you want a “test build” vs. a “standard build”  
trivial, just define mock and std commands, use the makefile

If you want to choose at runtime  
create both, register both, enable one [with a command]  
one more template parameter will help 😊

# Rinse and repeat

- Subsystems are self-creating singleton[s] too
- Subsystems register themselves with a postman / catalog  
no one needs to “know all the subsystems”
- The postman is a lazy singleton as well
- See the symmetry: Command<->CommandCatalog, Subsystem<->Postman  
sort of, there is 1 catalog per subsystem, but ok

there : )



# Subsystems responsibilities

- Defines its own address (SID, this is in the sample too)
- Owns exclusive HW resources (e.g. a RS485, some I/O, etc.)
- Usually offers some logic to its own commands
- Is usually **stateful / mutable**: mirrors the state of hw devices

# A mutable singleton!



- In the sample code, it's all synchronous, but in a real system, **a SS will probably have its own message queue and a thread**. N SS could share 1 thread if reasonable.
- **Commands belonging to a SS will be executed in the SS thread.**
  - So even if they call back into the SS, it's still single-threaded.
  - We never need to synchronize (except [maybe] the command queue).
- CMD1 in SS1 can send messages to SS2, using the Postman
  - So it's also an internal communication channel.
- **So, a subsystem is an actor (ooooohhh).**
- What about mocking?? (same as commands...)

# A little more code

```
bool Postman::Deliv
{
    auto r = Recipier
    auto i = r.find(

    if (i != r.end())
        return i->seco

return false;
}
```

```
Delivering StartEngineCMD
StartEngineCMD::Process
```

```
1
Delivering DisableKeyboardCMD
DisableKeyboardCMD::Process
```

```
1
Delivering EnableKeyboardCMD
EnableKeyboardCMD::Process
1
```

```
Delivering invalid command (sid ok cid ko)
0
```

```
Delivering invalid command (sid ko [cid ko])
0
```

```
message(const Message& m)
```

```
);
D());
```

```
n.Payload());
```

# Variations

**Protocol:** encoding, ack/nak, synchronous vs asynchronous answer, etc.

**Threading:** synchronous, 1 thread per SS, 1 thread \* N SS, **N thread \* 1 SS**

**Queuing:** selective coalescence or not.

**Execution:** 1 active command, N active commands, background activity

**Substitution:** Mocking commands, Activable commands, etc.

**“Details”:** splitting payload parsing and execution (stateful commands, cloning).

# Why “a pattern language”

“Many patterns form a language”

File Name	Lines	Statements	Average Statements per Method
Command.h	12	3	0.0
CommandCatalog.h	41	20	4.0
Message.h	31	10	0.8
Postman.cpp	33	17	3.7
Postman.h	15	7	0.0
RegisteredCommand.h	18	7	1.0
RegisteredSubsystem.h	24	10	1.0
Subsystem.h	14	4	0.0

Trying to generalize will turn this short code into the usual abstract monster



# The abstract monster

- Policies everywhere
- Parameters everywhere
- N times longer to account for any possible variability
- Names far removed from domain terminology
- Steep learning curve
- Cross maintenance

VS.

understand the Pattern Language and adapt on your system

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## [Notes on Software Design, Chapter 12: Entanglement](http://www.carlopescio.com/2010/11/notes-on-software-design-chapter-12.html)

<http://www.carlopescio.com/2010/11/notes-on-software-design-chapter-12.html>

## [Notes on Software Design, Chapter 13: On Change](http://www.carlopescio.com/2011/02/notes-on-software-design-chapter-14.html)

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## [Notes on Software Design, Chapter 14: the Enumeration Law](http://www.carlopescio.com/2011/02/notes-on-software-design-chapter-14.html)

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## [On Growth and Software](http://videos.ncrafts.io/video/167699028) (nCrafts, Paris, May 2016)

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