CMSC 125: Operating Systems

- □ Instructor: **Joseph Anthony C. Hermocilla**
- □ Email: <u>jchermocilla@up.edu.ph</u>
- **Web:** https://jachermocilla.org



Resources

Book: https://pages.cs.wisc.edu/~remzi/OSTEP/

Slides Template:

https://pages.cs.wisc.edu/~remzi/OSTEP/Educators-Slides/Youjip/



Acknowledgement

This lecture slide set was initially developed for Operating System course in Computer Science Dept. at Hanyang University. This lecture slide set is for OSTEP book written by Remzi and Andrea at University of Wisconsin.

4. The Abstraction: The Process

Operating System: Three Easy Pieces

How to provide the illusion of many CPUs?

- Users want to run many programs but we only have a limited of CPUs (ex. 8 cores)
- CPU virtualization
 - The OS can promote the <u>illusion</u> that many virtual CPUs exist
 - How? By juggling programs
 - Time sharing: Running one process, then stopping it and running another
 - The potential cost is performance.
 - Via a mechanism called context-switch



Mechanisms and Policies.. Revisited

Mechanism

- Low-level methods or protocols that implement a functionality
- "how?"
- Example: context-switch

Policy

- Algorithms for making some kinds of decision within the OS
- "which?"
- Example: scheduling policy deciding which program to run first?next?

A Process

A process is a running program.

- □ A **program** itself is "lifeless" just sits on the disk as bunch of instructions (and some data) aka **program image**
- We can **characterize** a process by looking at the different data structures and systems resources it uses or accesses
- What comprises a process?
 - Memory (address space range of addresses that a process can access)
 - Instructions/Code
 - Data
 - Machine state (via Registers)
 - Program counter (Instruction pointer)
 - Stack pointer
 - Frame pointer
 - I/O information list of open files

Process API

These APIs are available on any modern OS

Create

o Create a new process to run a program – fork(), exec()

Destroy

• Halt a runaway process - kill (pid, SIGTERM)

Wait

Wait for a process to stop running – wait (pid)

Miscellaneous Control

• Some kind of method to suspend a process and then resume it — kill(pid, SIGSTOP), kill(pid, SIGCONT)

Status

• Get some status info about a process — cat /proc/pid/status

Process Creation

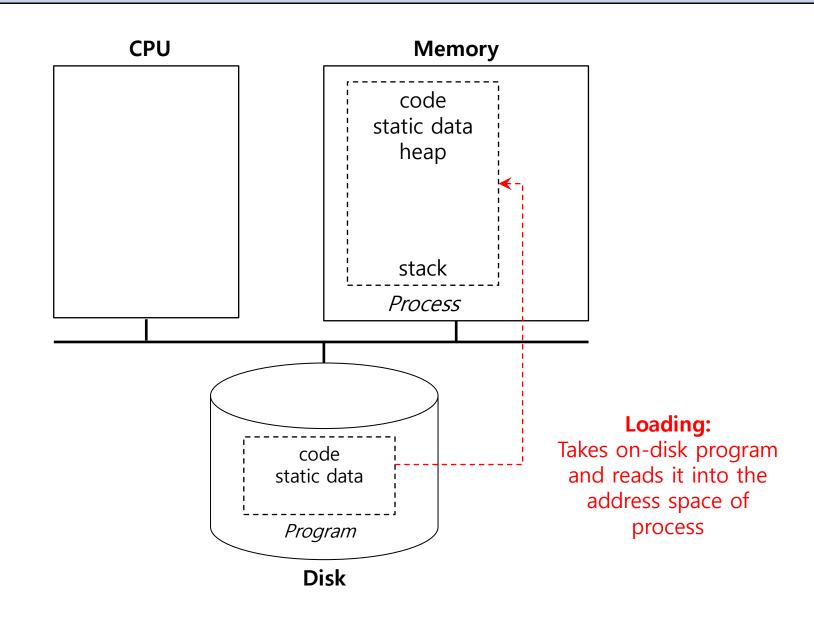
- 1. **Load** a program code(and state data) into <u>memory</u>, into the address space of the process.
 - Programs initially reside on disk in *executable format*. (ELF, PE)
 - OS perform the loading process lazily.
 - Loading pieces of code or data only as they are needed during program execution. (some programs a big)
- 2. The program's run-time **stack** is allocated.
 - Use the stack for local variables, function parameters, and return address.
 - Initialize the stack with arguments \rightarrow argc and the argv array of main () function

Process Creation (Cont.)

- 3. The program's **heap** is created.
 - Used for explicitly requested dynamically allocated data.
 - Program request such space by calling malloc() and free it by calling free().

- 4. The OS do some other initialization tasks.
 - input/output (I/O) setup
 - Each process by default has three open file descriptors.
 - Standard input (STDIN), standard output(STDOUT), and standard error(STDERR)
- 5. **Start the program** running at the entry point, namely main().
 - The OS *transfers control* of the CPU to the newly-created process.

Loading: From Program To Process



Process States

A process can be in one of three states.

Running

• A process is running on a processor. Instructions are being executed

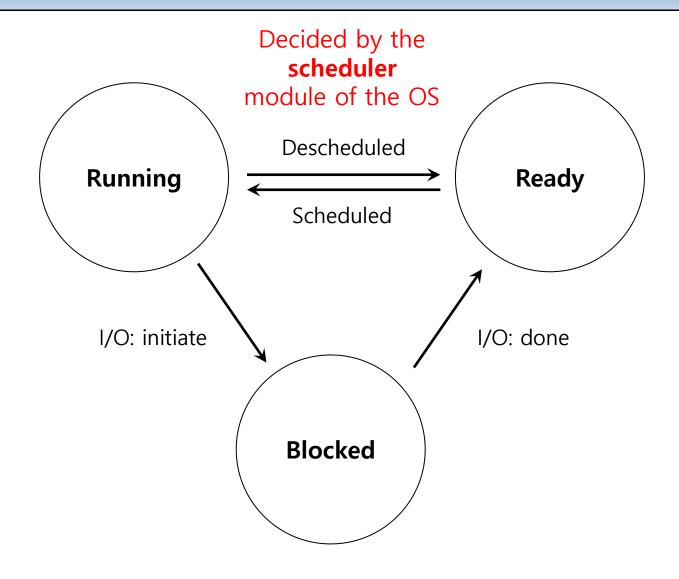
Ready

• A process is ready to run but for some reason the OS has chosen not to run it at this given moment

Blocked

- A process has performed some kind of operation and is waiting for the result
- Example: When a process initiates an I/O request to a disk, it becomes blocked and thus some other process can use the processor
- Additional states may be present depending on the OS
 - Initial
 - Final/Terminated

Process State Transition



Tracing Process States: CPU Only

□ Assumes a single processor is available

Time	$\mathbf{Process}_0$	$\mathbf{Process}_1$	Notes
1	Running	Ready	
2	Running	Ready	
3	Running	Ready	
4	Running	Ready	Process ₀ now done
5	_	Running	
6	_	Running	
7	_	Running	
8	_	Running	Process ₁ now done

Tracing Process States: CPU and I/0

□ Assumes a single processor is available

Time	$\mathbf{Process}_0$	$\mathbf{Process}_1$	Notes
1	Running	Ready	
2	Running	Ready	
3	Running	Ready	Process ₀ initiates I/O
4	Blocked	Running	Process ₀ is blocked,
5	Blocked	Running	so Process ₁ runs
6	Blocked	Running	
7	Ready	Running	I/O done
8	Ready	Running	Process ₁ now done
9	Running	-	
10	Running	_	Process ₀ now done

Data Structures

□ The OS has some key data structures that track various relevant pieces of information.

Process/Tasks lists

- Ready processes
- Blocked processes
- Current running process

Register context

- Will hold the values of the registers(in memory) when a process is stopped to be able to resume later
- This is done by copying these values back to the actual registers during a context-switch

PCB(Process Control Block)

A C-structure that contains information about a process.

Example: The xv6 kernel register context structure and process states definitions

```
// the registers xv6 will save and restore
  to stop and subsequently restart a process
struct context {
   int eip; // Index pointer register
   int esp; // Stack pointer register
   int ebx; // Called the base register
   int ecx; // Called the counter register
   int edx; // Called the data register
   int esi; // Source index register
   int edi; // Destination index register
   int ebp; // Stack base pointer register
};
// the different states a process can be in
enum proc state { UNUSED, EMBRYO, SLEEPING,
                 RUNNABLE, RUNNING, ZOMBIE };
```

Example: The xv6 kernel proc structure definition

```
// the information xv6 tracks about each process
// including its register context and state
struct proc {
   char *mem;
                          // Start of process memory
                          // Size of process memory
   uint sz;
                           // Bottom of kernel stack
   char *kstack;
                           // for this process
   enum proc state state;  // Process state
   int pid;
                           // Process ID
   struct proc *parent;
                          // Parent process
   void *chan;
                          // If non-zero, sleeping on chan
   int killed; // If non-zero, have been killed
   struct file *ofile[NOFILE]; // Open files
   struct inode *cwd; // Current directory
   struct context; // Switch here to run process
   struct trapframe *tf; // Trap frame for the
                           // current interrupt
};
```