CMSC 125: Operating Systems

- □ Instructor: **Joseph Anthony C. Hermocilla**
- □ Email: <u>jchermocilla@up.edu.ph</u>
- **Web:** https://jachermocilla.org



Resources

Book: https://pages.cs.wisc.edu/~remzi/OSTEP/

Slides Template:

https://pages.cs.wisc.edu/~remzi/OSTEP/Educators-Slides/Youjip/



Acknowledgement

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27. Interlude: Thread API

Operating System: Three Easy Pieces

Thread Creation

How to create and control threads?

- thread: Used to interact with this thread
- attr: Used to specify any attributes this thread might have
 - Stack size, Scheduling priority, ...
- start_routine: the function this thread start running in
- arg: the argument to be passed to the function (start routine)
 - o a void pointer allows us to pass in any type of argument

Thread Creation (Cont.)

- If start routine instead required another type argument, the declaration would look like this:
 - An integer argument:

• Return an integer:

Example: Creating a Thread

```
#include <pthread.h>
typedef struct myarg t {
        int a;
        int b;
} myarg t;
void *mythread(void *arg) {
        myarg_t *m = (myarg_t *) arg;
        printf("%d %d\n", m->a, m->b);
        return NULL;
int main(int argc, char *argv[]) {
        pthread t p;
        int rc;
        myarg t args;
        args.a = 10;
        args.b = 20;
        rc = pthread create(&p, NULL, mythread, &args);
```

Wait for a thread to complete

```
int pthread_join(pthread_t thread, void **value_ptr);
```

- thread: Specify which thread to wait for
- value ptr: A pointer to the <u>return value</u>
 - Because pthread join () routine changes the value, you need to pass in a pointer to that value

Example: Waiting for Thread Completion

```
#include <stdio.h>
   #include <pthread.h>
   #include <assert.h>
   #include <stdlib.h>
   typedef struct myarg t {
      int a;
     int b;
   } myarg t;
10
   typedef struct __myret_t {
12
     int x;
13
   int y;
14
   } myret t;
15
16
   void *mythread(void *arg) {
17
       myarg t *m = (myarg t *) arg;
18
       printf("%d %d\n", m->a, m->b);
19
    myret t *r = malloc(sizeof(myret t));
20
   r->x = 1;
21
   r->y = 2;
22
      return (void *) r;
23
24
```

Example: Waiting for Thread Completion (Cont.)

```
int main(int argc, char *argv[]) {
26
       int rc;
27
       pthread t p;
28
       myret t *m;
29
30
       myarg t args;
31
       args.a = 10;
32
    args.b = 20;
33
       pthread create(&p, NULL, mythread, &args);
34
       pthread join(p, (void **) &m); // this thread has been
                                        // waiting inside of the
                                        // pthread join() routine.
35
       printf("returned %d %d\n", m->x, m->y);
36
       return 0;
37 }
```

Example: Dangerous code

■ Be careful with <u>how values are returned</u> from a thread.

```
1  void *mythread(void *arg) {
2    myarg_t *m = (myarg_t *) arg;
3    printf("%d %d\n", m->a, m->b);
4    myret_t r; // ALLOCATED ON STACK: BAD!
5    r.x = 1;
6    r.y = 2;
7    return (void *) &r;
8  }
```

• When the variable r returns, it is automatically de-allocated

Example: Simpler Argument Passing to a Thread

Just passing in a single value

```
void *mythread(void *arg) {
       int m = (int) arg;
       printf("%d\n", m);
       return (void *) (arg + 1);
6
   int main(int argc, char *argv[]) {
       pthread t p;
       int rc, m;
10
       pthread create(&p, NULL, mythread, (void *) 100);
       pthread join(p, (void **) &m);
11
12
       printf("returned %d\n", m);
13
       return 0;
14 }
```

Locks

- Provide mutual exclusion to a critical section
 - Interface

```
int pthread_mutex_lock(pthread_mutex_t *mutex);
int pthread_mutex_unlock(pthread_mutex_t *mutex);
```

Usage (w/o lock initialization and error check)

```
pthread_mutex_t lock;
pthread_mutex_lock(&lock);
x = x + 1; // or whatever your critical section is
pthread_mutex_unlock(&lock);
```

- \circ No other thread holds the lock \rightarrow the thread will acquire the lock and enter the critical section
- \circ If another thread hold the lock \rightarrow the thread will not return from the call until it has acquired the lock.

Locks (Cont.)

- All locks must be properly initialized
 - One way: using PTHREAD MUTEX INITIALIZER

```
pthread_mutex_t lock = PTHREAD_MUTEX_INITIALIZER;
```

The dynamic way: using pthread_mutex_init()

```
int rc = pthread_mutex_init(&lock, NULL);
assert(rc == 0); // always check success!
```

Locks (Cont.)

- Check errors code when calling lock and unlock
 - An example wrapper

```
// Use this to keep your code clean but check for failures
// Only use if exiting program is OK upon failure
void Pthread_mutex_lock(pthread_mutex_t *mutex) {
   int rc = pthread_mutex_lock(mutex);
   assert(rc == 0);
}
```

These two calls are used in lock acquisition

- trylock: return failure if the lock is already held
- timelock: return after a timeout

Locks (Cont.)

These two calls are also used in lock acquisition

- trylock: return failure if the lock is already held
- timelock: return after a timeout or after acquiring the lock

Condition Variables

Condition variables are useful when some kind of signaling must take place between threads

- pthread_cond_wait:
 - Put the calling thread to sleep
 - Wait for some other thread to signal it
- pthread_cond_signal:
 - Unblock at least one of the threads that are blocked on the condition variable

Condition Variables (Cont.)

A thread calling wait routine:

```
pthread_mutex_t lock = PTHREAD_MUTEX_INITIALIZER;
pthread_cond_t init = PTHREAD_COND_INITIALIZER;

pthread_mutex_lock(&lock);
while (initialized == 0)
    pthread_cond_wait(&init, &lock);
pthread_mutex_unlock(&lock);
```

- The wait call releases the lock when putting said caller to sleep
- Before returning after being woken, the wait call re-acquire the lock

A thread calling signal routine:

```
pthread_mutex_lock(&lock);
initialized = 1;
pthread_cond_signal(&init);
pthread_mutex_unlock(&lock);
```

Condition Variables (Cont.)

□ The waiting thread **re-checks** the condition in a while loop, instead of a simple if statement

```
pthread_mutex_t lock = PTHREAD_MUTEX_INITIALIZER;
pthread_cond_t init = PTHREAD_COND_INITIALIZER;

pthread_mutex_lock(&lock);

while (initialized == 0)
    pthread_cond_wait(&init, &lock);

pthread_mutex_unlock(&lock);
```

Without rechecking, the waiting thread will continue thinking that the condition has changed even though it has not

Condition Variables (Cont.)

- Don't ever to this.
 - A thread calling wait routine:

```
while(initialized == 0)
    ; // spin
```

• A thread calling signal routine:

```
initialized = 1;
```

- It performs poorly in many cases. \rightarrow just wastes CPU cycles.
- It is error prone.

Compiling and Running

- □ To compile them, you must include the header pthread.h
 - Explicitly link with the pthreads library, by adding the -pthread flag.

```
prompt> gcc -o main main.c -Wall -pthread
```

• For more information,

man -k pthread