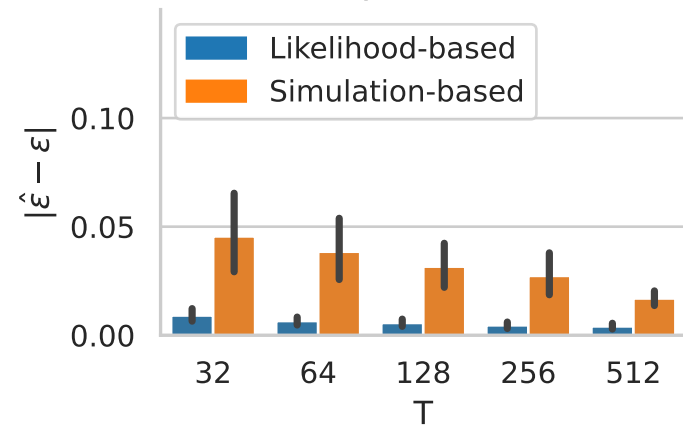
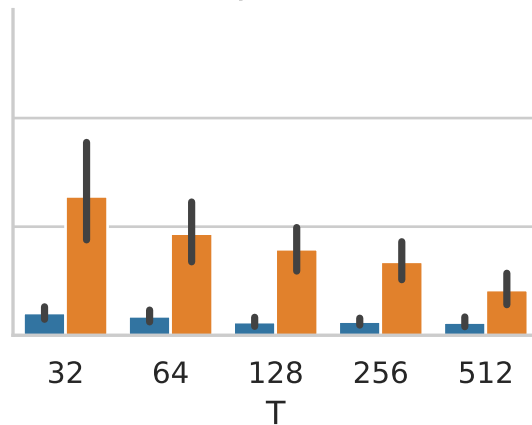


Fully observed



Partially observed



Noisy observations

