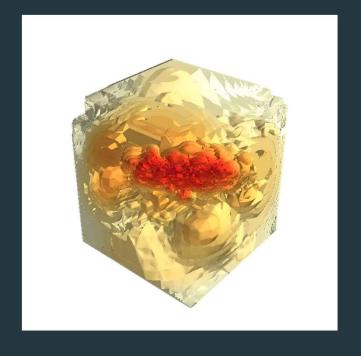
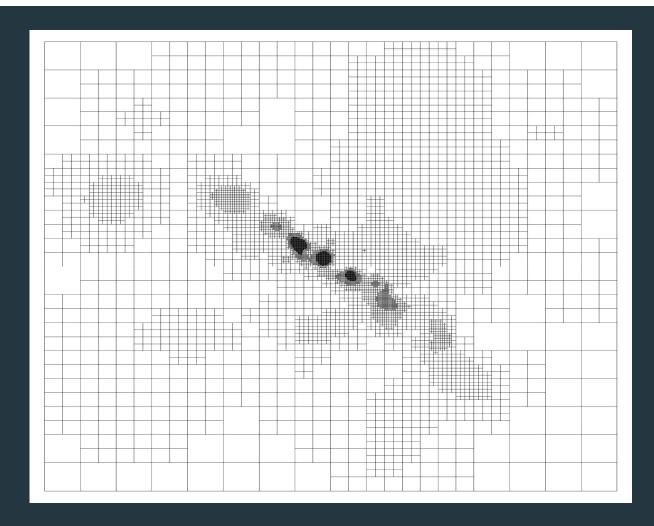


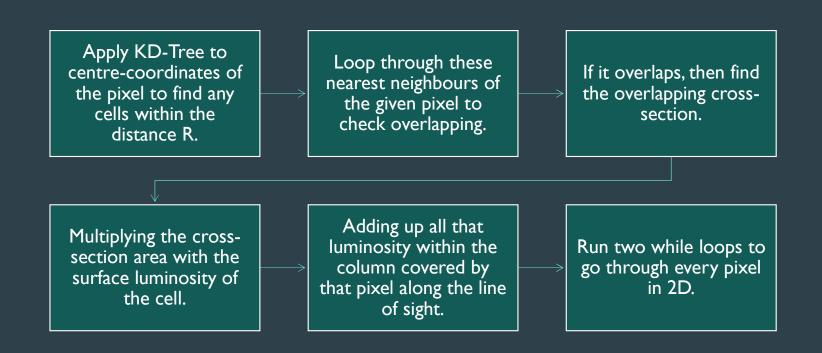
Data cube:





Credits: Karen Olsen

Algorithm:

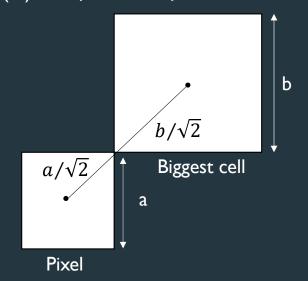


Scipy's spatial.KDTree class:

https://docs.scipy.org/doc/scipy/reference/generated/scipy.spatial.cKDTree.html

- query_ball_point() method
- Identifies all the points within a particular radius from the particular point
- Set the radius to be the maximum distance between centre of any touching cell and centre of the pixel

• Radius (R) = $a/\sqrt{2} + b/\sqrt{2}$

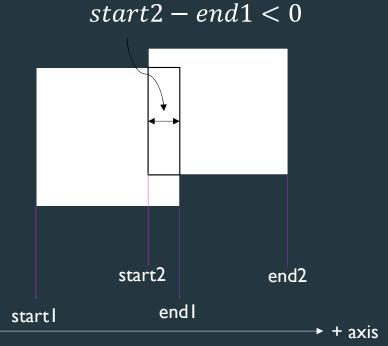


Overlapping:

 Loop through each nearest neighbour cell to check overlapping

• Cell and pixel overlaps if and only if:

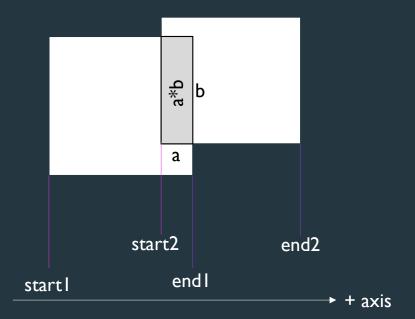
max(starting edges) - min(ending edges) < 0



Cross-section Area and Adding up Luminosity:

- Then, we find cross-section area of the overlapping cell and pixel.
- We multiply this cross-section area with the surface luminosity of the cell.
- We add up all the luminosity in that particular pixel.
- We find surface luminosity of every pixel using while loops.

a = end1 - start2 = min(ends) - max(starts)



Future Endeavors:

- Creating line ratio maps from the moment0 maps and analysing them.
- Correlating moment0 maps of line emissions to various properties of ISM.
- Creating radial maps.
- Implementation of higher order moment maps.

