



## Optimization Techniques for Big Data Analysis

Chapter 6. Coordinate Descent Methods

Master of Science in Signal Theory and Communications

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2 Gradient Coordinate Descent

3 Block Coordinate Descent



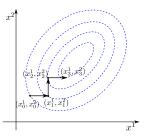
$$\min_{\mathbf{x}} f(\mathbf{x}); \ \mathbf{x} = [x_0, x_1, \cdots, x_j, \cdots, x_d]$$

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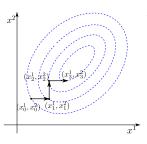
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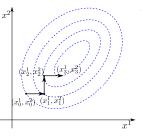


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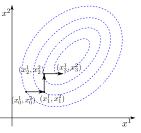


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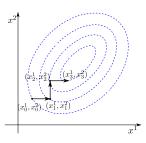


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We can also group the variables into block of dimension  $m_j$ , and optimise one block at a time; that's call **Block Coordinate Descent**.





#### Block Coordinate Descent

The BCD algorithm consists of solving our block-structured problem in an iterative manner. On iteration k we compute

$$\begin{array}{rcl} x_{k+1,j} & = & \displaystyle \mathop{\arg\min}_{x_j \in X_j} \, f\left(x_j, x_{k,-j}\right) \\ \\ x_{k+1,l} & = & x_{k,l}, \quad \forall l \neq j \end{array}$$

where  $x_{k,-j} \triangleq (x_{k,1}, \dots, x_{k,j-1}, x_{k,j+1}, \dots, x_{k,d})$ . In the next iteration, a different coordinate, for instance, j+1, is updated.



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The method is very intuitive and simple to implement and very popular in many applications. However, it does not have guaranteed convergence for an arbitrary function f.



#### Ridge regression:

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minimizing over  $w_j$  with all  $w_l$ ,  $l \neq j$  fixed,

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CD vs GD

#### Gradient Coordinate Descent.

$$x_{k+1,j} = x_{k,j} - \eta \nabla_{x_j} f(\mathbf{x}_k)$$
  
$$x_{k+1,j} = x_{k,j} \quad \forall j \neq i$$

where  $\mathbf{x}_k = x_{k,1}, \dots, x_{k,j-1}, x_{k,j}, \dots, x_{k,d}$  is the pivoting point around whom we have evaluated the gradient over block variable  $x_j$  at instant k.



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- lacktriangledown If f is non-smooth, we could incorporate projected or proximal updates.
- **2** The SGD is also applicable, where an instantaneous estimate substitutes the gradient.
- **3** It could also be improved using Nesterov or Quasi-Newton principles.





BCD can be applied in different settings:

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- 3 <u>Mixed scheme</u>: for big data, it is useful that some blocks are updated in parallel (in different processors) while the variables of each block are updated sequentially (within the same processor). This scheme is usually referred to as Gauss-Jacobi scheme.
- Randomized rule: In the randomized scheme, every block
  has a non-zero probability of being updated, and these
  probabilities are varied according to some information over

  \[
  \Lambda\_t \text{ the estimated errors.}
  \]

Let us assume the general problem

$$\underset{\mathbf{w}}{\operatorname{arg\,min}} \frac{1}{n} \|\mathbf{X}\mathbf{w} - \mathbf{y}\|_{2}^{2} + \frac{\lambda}{2} \|\mathbf{w}\|_{2}^{2}$$

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The gradient takes the same form as before, but the j represents a block of variables:

$$\nabla_j f(\mathbf{w}) = \frac{2}{n} \mathbf{X}_{:,j}^T (\mathbf{X}_{:,j} \mathbf{w}_j + \mathbf{X}_{:,-j} \mathbf{w}_{-j} - \mathbf{y}) + \lambda \mathbf{w}_j = 0$$



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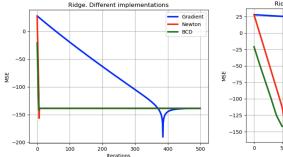
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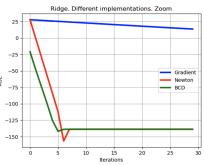
So, the closed-form solution for the iteration k+1 results into



$$\mathbf{w}_{k+1,j} = \left(\mathbf{X}_{:,j}^T \mathbf{X}_{:,j} + \frac{n}{2} \lambda \mathbf{I}_{m_j}\right)^{-1} \mathbf{X}_{:,j}^T \left(\mathbf{y} - \mathbf{X}_{:,-j} \mathbf{w}_{k,-j}\right)$$

Follow the code provided in the notebook Case\_study\_6\_1 to obtain results as those presented in the next Figure. Pay attention to how high-speed are these algorithms.







Let's now consider the LASSO case

$$\underset{\mathbf{w}}{\arg\min}\frac{1}{n}\left\|\mathbf{X}\mathbf{w}-\mathbf{y}\right\|_{2}^{2}+\lambda\left\|\mathbf{w}\right\|_{1}$$



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Solving for  $w_j$ 

$$w_j = \frac{\mathbf{X}_{:,j}^T \left( \mathbf{y} - \mathbf{X}_{:,-j} \mathbf{w}_{-j} \right)}{\mathbf{X}_{:,j}^T \mathbf{X}_{:,j}} - \frac{n \lambda \operatorname{sgn}(w_j)}{2 \mathbf{X}_{:,j}^T \mathbf{X}_{:,j}}$$



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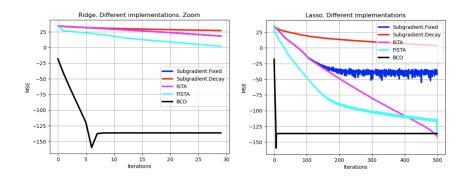
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$$= \operatorname{Soft} \left( \frac{\mathbf{X}_{:,j}^{T} (\mathbf{y} - \mathbf{X}_{:,-j} \mathbf{w}_{-j})}{\mathbf{X}_{:,j}^{T} \mathbf{X}_{:,j}}, \frac{n \lambda}{2 \mathbf{X}_{:,j}^{T} \mathbf{X}_{:,j}} \right)$$



Follow the code provided in the notebook Case\_study\_6\_2 to obtain the following results





# Questions?



#### References

[1] Jorge Nocedal and J. Wright Stephen. *Numerical optimization*. Spinger, 2006.



## Thank You

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