



Optimization Techniques for Big Data Analysis

Chapter 6. Coordinate Descent Methods

Master of Science in Signal Theory and Communications

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2 Gradient Coordinate Descent

3 Block Coordinate Descent



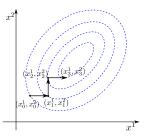
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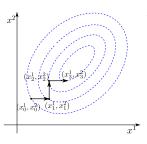
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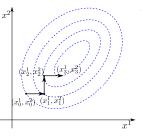


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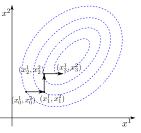


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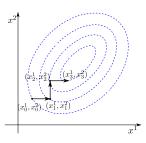


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We can also group the variables into block of dimension m_j , and optimise one block at a time; that's call **Block Coordinate Descent**.





Block Coordinate Descent

The BCD algorithm consists of solving our block-structured problem in an iterative manner. On iteration k we compute

$$\begin{array}{rcl} x_{k+1,j} & = & \displaystyle \mathop{\arg\min}_{x_j \in X_j} \, f\left(x_j, x_{k,-j}\right) \\ \\ x_{k+1,l} & = & x_{k,l}, \quad \forall l \neq j \end{array}$$

where $x_{k,-j} \triangleq (x_{k,1}, \dots, x_{k,j-1}, x_{k,j+1}, \dots, x_{k,d})$. In the next iteration, a different coordinate, for instance, j+1, is updated.



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The method is very intuitive and simple to implement and very popular in many applications. However, it does not have guaranteed convergence for an arbitrary function f.



Ridge regression:

$$\underset{\mathbf{w} \in \mathbb{R}^{d+1}}{\arg\min} f(\mathbf{w}) = \underset{\mathbf{w} \in \mathbb{R}^{d+1}}{\arg\min} \frac{1}{2} \|\mathbf{y} - \mathbf{X}\mathbf{w}\|_{2}^{2} + \lambda \|\mathbf{w}\|_{2}^{2}$$



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minimizing over w_j with all w_l , $l \neq j$ fixed,

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CD vs GD

Gradient Coordinate Descent.

$$x_{k+1,j} = x_{k,j} - \eta \nabla_{x_j} f(\mathbf{x}_k)$$

$$x_{k+1,j} = x_{k,j} \quad \forall j \neq i$$

where $\mathbf{x}_k = x_{k,1}, \dots, x_{k,j-1}, x_{k,j}, \dots, x_{k,d}$ is the pivoting point around whom we have evaluated the gradient over block variable x_j at instant k.



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- lacktriangledown If f is non-smooth, we could incorporate projected or proximal updates.
- **2** The SGD is also applicable, where an instantaneous estimate substitutes the gradient.
- **3** It could also be improved using Nesterov or Quasi-Newton principles.





BCD can be applied in different settings:

• Cyclic rule: the block coordinates are chosen cyclically, in a sequential manner. This scheme is frequently referred to as Gauss-Seidel scheme.



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- Randomized rule: In the randomized scheme, every block
 has a non-zero probability of being updated, and these
 probabilities are varied according to some information over

 \[
 \Lambda_t \text{ the estimated errors.}
 \]

Let us assume the general problem

$$\underset{\mathbf{w}}{\operatorname{arg\,min}} \frac{1}{n} \|\mathbf{X}\mathbf{w} - \mathbf{y}\|_{2}^{2} + \frac{\lambda}{2} \|\mathbf{w}\|_{2}^{2}$$

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$$\nabla_j f(\mathbf{w}) = \frac{2}{n} \mathbf{X}_{:,j}^T (\mathbf{X}_{:,j} \mathbf{w}_j + \mathbf{X}_{:,-j} \mathbf{w}_{-j} - \mathbf{y}) + \lambda \mathbf{w}_j = 0$$



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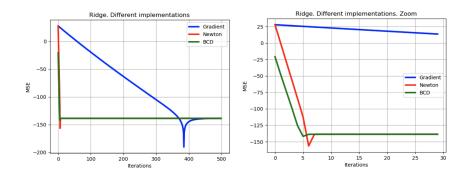
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So, the closed-form solution for the iteration k+1 results into



$$\mathbf{w}_{k+1,j} = \left(\mathbf{X}_{:,j}^T \mathbf{X}_{:,j} + \frac{n}{2} \lambda \mathbf{I}_{m_j}\right)^{-1} \mathbf{X}_{:,j}^T \left(\mathbf{y} - \mathbf{X}_{:,-j} \mathbf{w}_{k,-j}\right)$$

Follow the code provided in the notebook Case_study_6_1 to obtain results as those presented in the next Figure. Pay attention to how high-speed these algorithms are.





Let's now consider the LASSO case

$$\underset{\mathbf{w}}{\arg\min}\frac{1}{n}\left\|\mathbf{X}\mathbf{w}-\mathbf{y}\right\|_{2}^{2}+\lambda\left\|\mathbf{w}\right\|_{1}$$



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By differentiating it with respect to j-th weight, we get

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Solving for w_j

$$w_j = \frac{\mathbf{X}_{:,j}^T \left(\mathbf{y} - \mathbf{X}_{:,-j} \mathbf{w}_{-j} \right)}{\mathbf{X}_{:,j}^T \mathbf{X}_{:,j}} - \frac{n \lambda \operatorname{sgn}(w_j)}{2 \mathbf{X}_{:,j}^T \mathbf{X}_{:,j}}$$



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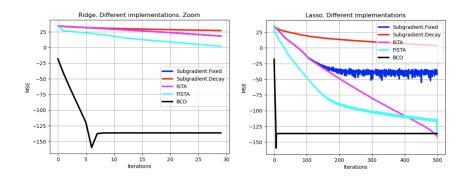
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$$w_{j} = \frac{\mathbf{X}_{:,j}^{T} (\mathbf{y} - \mathbf{X}_{:,-j} \mathbf{w}_{-j})}{\mathbf{X}_{:,j}^{T} \mathbf{X}_{:,j}} - \frac{n \lambda \operatorname{sgn}(w_{j})}{2 \mathbf{X}_{:,j}^{T} \mathbf{X}_{:,j}}$$
$$= \operatorname{Soft} \left(\frac{\mathbf{X}_{:,j}^{T} (\mathbf{y} - \mathbf{X}_{:,-j} \mathbf{w}_{-j})}{\mathbf{X}_{:,j}^{T} \mathbf{X}_{:,j}}, \frac{n \lambda}{2 \mathbf{X}_{:,j}^{T} \mathbf{X}_{:,j}} \right)$$



Follow the code provided in the notebook Case_study_6_2 to obtain the following results





Questions?



References

[1] Jorge Nocedal and J. Wright Stephen. *Numerical optimization*. Spinger, 2006.



Thank You

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