



# Optimization Techniques for Big Data Analysis

#### Chapter 1. Introduction

#### Master of Science in Signal Theory and Communications

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1 Introduction

Why take this course? Basic concepts

2 Optimization problems in Machine Learning ML setup Most common optimization problems in ML



#### Motivation

Optimization is a supporting technology in many numerical computation-related research fields, such as machine learning, signal processing, industrial design, and operation research.

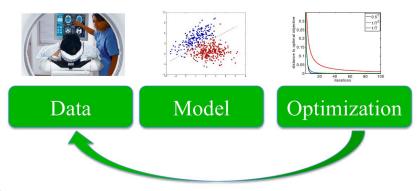
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- Continuous optimization: It often appears as a relaxation of risk/error minimisation problems. The *learning* problem in many parametrized models involves Continuous Optimization.
- Discrete optimization:
  It occurs in inference problems in structured spaces, such as Feature selection, Data subset selection, Data summarization, Architecture search etc.



## Continuous optimization in ML

- Supervised Learning: Logistic Regression, Least Square, Support Vector Machines, Deep Models.
- Unsupervised Learning: k-Means Clustering, Principal Component Analysis.
- Contextual bandits and Reinforcement learning: Soft-Max estimators and Policy Exponential Models.
- Recommender systems: Matrix Completion, Non-Negative Matrix Factorization, Collaborative Filtering.



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Countless ML libraries available implement all kinds of optimization algorithms (Tensorflow, PyTorch, Scipy, Sklearn, Vowpal Wabbit, ...)



Different setups and contexts can lead to different algorithm requirements:

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- Federated learning: Run the algorithm in different nodes without sharing any data among nodes.

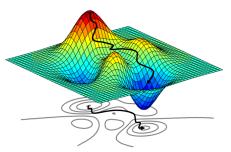


#### Nomenclature

- For the most part through this course, we will use n as the number of training instances and d as the number of dimensions (features).
- Function:  $f(\cdot)$
- Scalar: x; single-input function f(x)
- d-dimensional vector:  $\mathbf{x} \in \mathbb{R}^{\mathbf{d}}$ ;  $\mathbf{x}_i = [x_{1i}, x_{2i}, \cdots, x_{di}]$
- $\blacksquare$  multi-input function  $f(\mathbf{x})$ ; vector-valued function  $\mathbf{f}(\mathbf{x})$
- Vector Space:  $\mathcal{X}$
- Vector Norm:  $||\mathbf{x}||_L$
- Inner product: Given two vectors  $\mathbf{w}, \mathbf{x} \in \mathbb{R}^d$ , define the inner product  $\langle \mathbf{w}, \mathbf{x} \rangle = \sum_{j=1}^d \mathbf{w}_j \mathbf{x}_j = \mathbf{w}^T \mathbf{x}$
- $\blacksquare$  Random variable X; Matrix:  $\mathbf{X}$



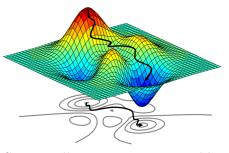
## Mathematical optimization



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# Mathematical optimization



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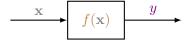
So typically we are given a problem like the following:

$$\hat{x} = \arg\max_{x} f(x) \text{ s.t. } g(x) < a$$
 (1)

- $\blacksquare$   $f(\cdot)$  function subject to optimization.
- $x \in \mathcal{X}$  variables/parameters that need to be adjusted.
- $\blacksquare$   $\mathcal{X}$  is the search space.  $\hat{x}$  is the optimum.
- $g(\cdot)$  restrictions.  $f|_{\mathcal{G}}$ , where  $\mathcal{G} \subseteq \mathcal{X}$ ;  $\mathcal{G}$  is the feasible set.



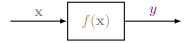
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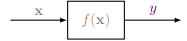


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$$y = f_{\theta}(\mathbf{x}) + \varepsilon; \ \varepsilon \sim \mathcal{N}(0, \sigma^2)$$
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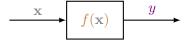
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Training  $f_{\theta}(\cdot)$  corresponds to the optimization of  $J(\theta)$ !



# Supervised Learning: Modelling

- Data: Given training examples  $\{(\mathbf{x}_1, y_1), \dots, (\mathbf{x}_n, y_n)\}$  where  $\mathbf{x}_i \in \mathbb{R}^d$  is the feature vector and  $y_i$  is the label.
- Model: Denote the Model by  $f_{\theta}(\mathbf{x})$  with  $\theta$  being the parameters of the model. e.g.  $f_{\theta}(\mathbf{x}) = \theta^T \mathbf{x}$
- Loss Functions: The loss function  $\ell$  tries to measure the distance between  $f_{\theta}(\mathbf{x}_i)$  and  $y_i$ .



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The generic problem denoted as the *expected loss function* can be expressed as:

$$\arg\min_{\theta} \mathcal{L}(\theta) = \mathbb{E}[\ell_{\theta}(\mathbf{x}, y)] + \lambda R(\theta)$$
 (3)

where  $\ell$  is the *instantaneous loss*,  $R(\cdot)$  is the *regularizer* and  $\lambda$  a regularization factor.



#### Empirical loss functions

In most of this course' cases, we are dealing with a supervised learning problem, so given a dataset  $\mathcal{D} = \{(\mathbf{x}_i, y_i)_{i=1}^n\}$  the loss function takes the form:

$$\mathcal{L}(\theta) = \frac{1}{n} \sum_{i=1}^{n} \ell_{\theta}(\mathbf{x}_{i}, y_{i}) + \lambda R(\theta)$$
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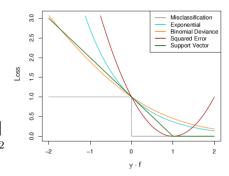
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#### Examples of $\ell$ :

- Logistic loss:  $\log(1 + \exp(-y_i f_{\theta}(\mathbf{x}_i)))$
- Hinge Loss:  $\max\{0, 1 y_i f_{\theta}(\mathbf{x}_i)\}$
- Absolute Error:  $|f_{\theta}(\mathbf{x}_i) y_i|$
- Least Squares:  $(f_{\theta}(\mathbf{x}_i) y_i)^2$





#### Instantaneous loss function

A common simplification approximates the original function by its instantaneous value:

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■ The minimization is performed by using an instantaneous version of the original gradient.



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- When minimizing it, we will have to consider the gradient noise that will affect convergence properties.
- This simplification makes the algorithm very attractive in big data applications, both because of hardware requirements and for distributed settings.



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- High dimensional data: Because of the dimensionality of the parameter spaces, we can't afford second-order optimization methods. First-order or simplified second-order methods are requested.
- Distributed processing is highly desirable.



## Acknowledgments

I would like to acknowledge several sources I have used to create slides

- Rishabh Iyer's course at University of Texas, DA https://github.com/rishabhk108/OptimizationML
- Martin Jaggi & Nicolas Flammarion's course at EPFL https://github.com/epfml/OptML\_course



# Questions?



[1] Melvyn W Jeter. Mathematical programming: an introduction to optimization. Routledge, 2018.



# Thank You

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