

What does it take to create with domain-appropriate tools?

A case study on the “OROM” system

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Abstract There is a One-Size-Fits-All quality to languages, APIs and even programming itself. Whether you're making a mobile game or a scientific simulation, you will be using a text-based language with similar devices for structuring your code. This is a source of artificial difficulty in creating, understanding, and modifying software systems. No matter the domain, the author's design needs encoding into a form that does not resemble it.

This paper describes a vision where software can be built in a programming environment that is closer to the domain of the software itself. By doing so, users of the system can use familiar abstractions and tools for adapting it. A step towards this vision is presented: a Web version of a minimal OOP system, developed as an executable version of the diagrams of its design, in a substrate meant to facilitate this. The experience of creating such a substrate is analysed, and I suggest deficiencies in programming environments that stand in the way of making this practice commonplace, as well as ways to fill in these gaps.

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1 Introduction

As someone who can code, I have already passed the first and most important hurdle for making full use of the potential of my computer. However, even in this supposedly empowered state, I am still far away from feeling the relationship between myself and software as between artisan and material, free to shape it into any form with effort proportional to complexity.

One would have thought that software-creation acts like hypothetical super-intelligent Artificial Intelligence (AI). That is: even though we start from a primitive base in the 50s (or even today), there would surely be a recursive process of self-improvement, building better software-creation tools with the existing ones, until an “expressivity singularity” where software becomes a workable material as described.

However, this didn’t happen. Or at least, it is happening glacially slowly. The brute fact is that whenever you want to create software, you go to a text editor and figure out how to translate your design into that. The text editors, being software, were written with the help of previous text editors, and so on. It’s undeniable that text editors have improved, even if you think it peaked with Emacs. We just don’t seem able to go beyond them where it matters, such as visual domains ill-fitted to monospaced ASCII.

Amdahl’s Law generalises the following idea: even when you spend hours of effort doubling the performance of a component used 1% of the time, your reward is a system overall improved by a mere 0.5%. Now, text coding is certainly ubiquitous, the 99% case in programming, so you might wonder where I’m going with this. Well, a small improvement to text editing, if adopted by everyone, certainly does have a massive *intermediate* effect — but this only *matters* to the extent that text was helping the programmers in the first place. If my goal is to draw or animate pictures, or create a digital synth from a frequency spectrogram, then giving me the ability to auto-indent my SVG markup is rather underwhelming as a productivity increase, as it doesn’t target the core of the enterprise that makes it so hard.

My experience of coding, most of the projects requiring shapes (such as GUIs), leads me to conclude that no matter how much I improve my skill at a particular language, knowledge of libraries or even general coding ability, my predicament stays the same. Our basic method of creating software is optimised for an ever-diminishing proportion of the software we actually want to make; ill-optimised for the graphics, layout, interactivity and and basic physics — more on this later — that we usually require.

Whenever I work on these I feel stuck in a box I know I can never escape from: that box is the text editor, a fixed conduit through which all *fundamental* changes to my program must pass. It’s not a part of the system I am building, so I can’t even make use of features of the thing I’m developing, to make its own development easier.

Surely the trick is to *use* coding to build something *better than it*. And then use that, to build something even better. But there is an enormous breadth and depth of philosophies here, along with many failed historical attempts to do better — or at least, ones that failed to catch on. And even worse than this is that in my very *language* here I am making the same mistake as the text editor — speaking in unqualified terms

of “better” and “worse” as if there really is a One-Size-Fits-All solution to software creation!

Of course what we *really* want is the ability for people to create *in the way that they think is best* in their particular context — to equip them to feasibly create the tools that suit them for the thing they want to make. And second-order tools that suit them for making the first-order tools, and so on. It would do no good to replace text-imperialism with anything-else-imperialism, which is one interpretation of calls for alternatives.

This dream goes beyond the familiar sense of what constitutes a “craft”, as far as a strong melding of tool and material. Parallels can be drawn with industrialisation and a strong division of labour: the community as a whole produces its higher-order tools, but currently no single person can have the same autonomy. A (future) software craft could be expected to give this power to *individuals*, instead of the community alone. Whenever there are many small specialities (e.g. languages, tools, or subject areas) each serving many clients, the One-Size-Fits-All style is the best one can hope for. Adaptation to individual preferences and idiosyncrasies is only feasible when those individuals can do it themselves.

What we need is some system that not only lets us create software in a way that is “close to the problem domain” as decided by the user-developer, but also can augment or change itself to adapt to a different “way of creating”. Existing systems seem to only have one of these properties without the other: Smalltalk and LISP try to minimise arbitrary commitments of language *semantics* to this end, but their being textual languages is a fairly tough commitment to break out of. And it is not so hard to make a specific, *hard-baked* visual or alternative programming tool — but it is hard to make it re-programmable *without* having to go back to *its* textual source code.

If someone wants to type out pictures in ASCII, let them — whether they do it for a challenge, or even if they find that more natural for themselves. But equally, if I want to do it another way, then please give me that affordance. This is how I segue into the software artefact for which I have been attempting to build a natural representation. True, it is a programmer’s artefact, but it is still representative of what any normal person has to do, insofar as:

- a) Wanting to create a piece of software (for whatever reason)
- b) Having in mind a natural way to represent it as it’s being built.

2 The OROM system

When I first read the paper “Open, Reusable Object Models” [PW06], I was hooked on its idea of a small but expressive starting system that could be self-improved into anything. It describes a late-bound,¹ Smalltalk-style² objects and messaging environ-

¹ Fewer commitments; more things determined by runtime conditions

² OOP with more emphasis on object instances and messaging (methods) as in a distributed system; less emphasis on class hierarchies implementing traditional data structures

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ment that the authors call “Id” — but I shall refer to it as OROM, for pronunciation and Googleability.

Essentially, an OROM object is a block of state which can change as a result of messages received by it. A message is sent by first *bind*-ing its name to its *implementation*: specific code, which is then run in the context of the receiver. “Bind” is accomplished via another message send, this time to the receiver’s *vtable*, or “behaviour”. This is another object whose state defines a particular way of associating “message name” to “implementation code”. This continues up the *vtable*-chain, and terminates at a base case. The system as a whole is “bootstrapped” into existence by its initialisation code. Each step of this code makes use of any parts of the system set up by the previous steps.

The paper itself consists of mostly prose, several code listings, and full C sources for a sample implementation at the end. It also provides several diagrams. But to understand it, I repeatedly found myself drawing *extra* diagrams. For example, the first acts of the running system boil down to initialising the three or so objects. This consists of allocating memory, interpreting it as a C struct and then filling in fields in a mundane manner. I had great difficulty following the specifics in my head, but when I drew tables in the style of their diagrams I readily saw what was going on. I personally would have preferred these to have been in the paper in the first place, but I am not necessarily representative of those who read it. The One-Size-Fits-All approach is perhaps unavoidable for static media like print.

Other areas like messaging semantics could still be quite confusing. After all, should we expect to be able to predict the entire future evolution of a dynamical system from a static description of its initial state, such as source code? Is this not why debuggers exist? Having “de-compiled” English text and C source code into object diagrams, it is a shame to have to compile it all back to struct member assignments.

Worst of all, the reference system does not even have text I/O when it is run, let alone some sort of GUI. That is, the (un)intended user interface for this project is a C debugger! Faced with the necessity of adding *some* UI, it seemed a waste of effort to end up with a system that must be continually polled for its current state at a terminal prompt. If I naturally think of this system as 2D tables, why can’t that be how the running system looks? I do not have to keep polling my eyes for what state my diagrams are in.

But further than that — why can’t the system be *built* out of tables in the first place? Shouldn’t this be the main takeaway from the amount of time we spend prototyping, explaining and designing software as diagrams on paper? Why must the “natural representation” be restricted to the finished product?

Thus was my natural representation decided. My first attempt to make it a reality was a partial success: a webpage made of HTML tables, evolved via JavaScript (JS).

2.1 OROM as HTML tables

To emphasise the tendency of OROM objects to be visualised as key-value mappings, I will refer to them as *obj-dicts*. Figure 1 shows the OROM/HTML implementation [Jak18], in which they take the form of HTML tables.

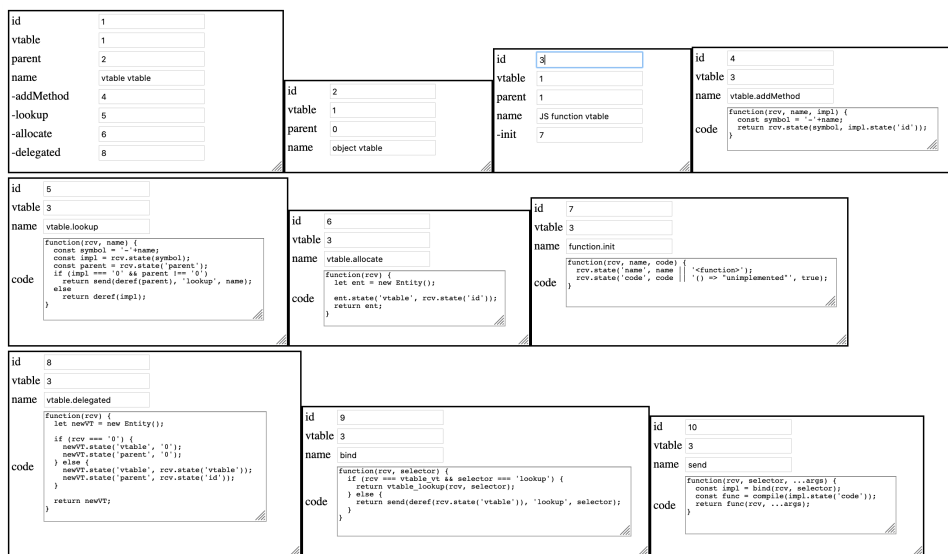


Figure 1 OROM/HTML: Obj-dicts are rendered as resizable tables, which reference each other through numerical IDs.

Here, I was grateful for the browser's management of graphical layout, resizable text fields, and keeping the DOM tree synchronised with what one sees. This last property enabled me to make the decision to *directly* encode much of the system state in the DOM, achieving basic liveness³ for the keys and values of obj-dicts.

I used a two-column <table> within a <div> for each obj-dict (matching the diagrams) and gave the rows CSS class names matching the keys (for easy lookup). Sending messages relied on the JS console, but existing values in text boxes (such as method implementations) could be edited directly.

This choice of ordinary HTML as a substrate, however, proved rather two-edged. The browser requires many features to do its job of rendering complex web pages. And sadly, as its client, I could only make use of those capabilities which the W3C had decided, at the time of authorship, were worth the effort exposing in JavaScript. For anything else, the browser is a black box, and this was very frustrating in the following case.

2.1.1 The Radical Concept of Arrows That Stay On The Shapes

A key aspect of the OROM system is that there is an object *graph*. That is, obj-dicts can have entries pointing to other obj-dicts, without restriction to a tree structure. Drawing arrows to denote this is a no-brainer (and easy on paper), so I wanted it in my substrate for OROM.

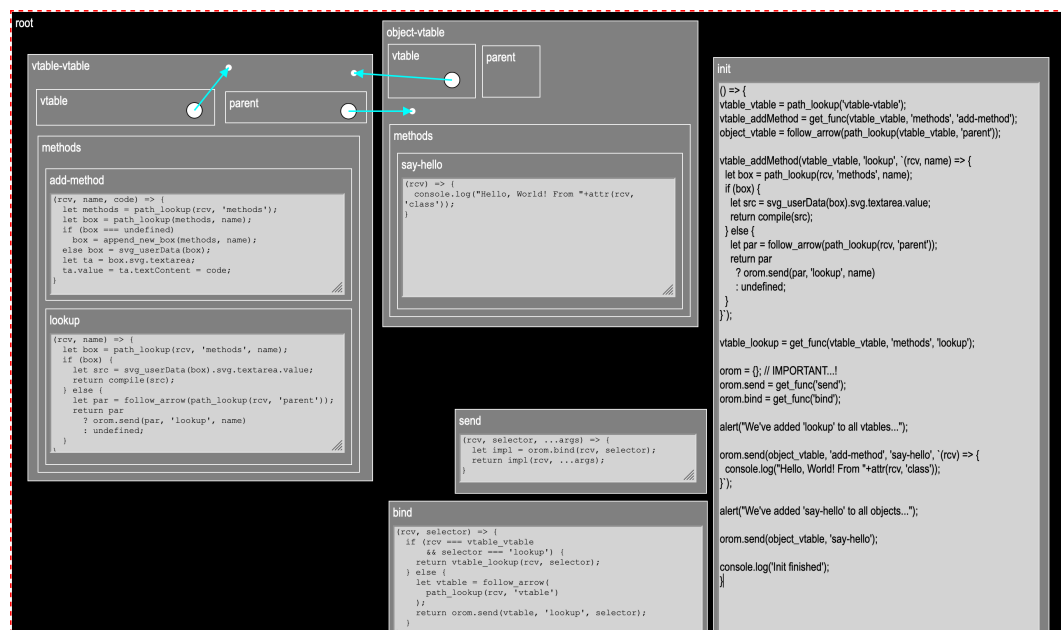
A small problem to surmount first: even though I could hijack the <table> for its display properties, what element could I hijack to make arrows between arbitrary points? Luckily, there were Scalable Vector Graphics (SVG) at my disposal, which

³ "The thing on the screen is the actual thing"

could be persuaded to display <line>s over the <div>s. But another key feature of my intended substrate was to be able to rearrange and resize the boxes. So I would also need to detect changes to the position and size of an element.

Reluctantly, I stuck with my plan B: each object has a numerical ID and pointers are just fields containing a number, followed using a deref() function.

2.2 OROM as SVG trees



In OROM/SVG, shown in Figure 2, obj-dicts are encoded as nested SVG `<rect>`s and other elements, reminiscent of diSessa’s Boxer[da86]. This was a significant departure from the table representation, and even though SVG supports (some) nested HTML via `<foreignObject>`, I actually preferred the possibility of multiple levels of nesting.

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patterns or themes that stand out to me from my development experience, hammered home by these OROM projects.

3 Typical Requirements Of Common Software (and the work we must do to meet them)

The “common case” of software present in our daily lives shares certain properties, such as being graphical and interactive. Such are expectations that “end-users” hold, consigned as they are to merely *consume* what programmers give them. But if we want to make “programming” more like “using”, such expectations on *use* at least need to be acknowledged.

In this section, I will present these and other seemingly *inevitable* demands of normal software, exemplified by OROM/SVG. I will comment on how our programming platforms measure up to the task, including my chosen platform of JavaScript and Web technologies.

3.1 Retained-Mode Vector Graphics

Most software is designed for the subset of people who have a colour display they can perceive. So right away it is going to require ways to draw coloured shapes. There are usually libraries for this (though note: not part of the language), but some only provide *immediate mode*: commands to instantaneously rasterise pixels to a buffer. This is not enough for modern software, as we often expect animation, or at least to see things change as we interact. Most often we wish to see *small changes* to the *same* shapes, rather than completely different shapes altogether; the reification that this requires to persist between frames, is known as *retained mode*.

On this requirement, SVG fits the bill very well. Although it is not part of the JavaScript language *per se*, it is a standard and widely supported technology of the Web *platform*. We can observe that anyone with a browser *in principle* has access to a powerful vector graphics editor — just one with no GUI.

The SVG tree has the nice properties of the DOM, such as updating the display when shape parameters are changed. This is well-adapted to “I/O-bound” software like mine, where things change only in response to user input. If I wanted animation, this would boil down to a regular “advance simulation” signal, and would require setting up some rendering loop. Alternatively, there is the W3C’s chosen ontology of CSS animations, but see Section 4.4.

3.2 Basic Assumptions About Physical Objects

In any software making use of vector graphics, there is usually some level of “physics” expected by users. This need not be nearly as exhaustive as the word “physics” might imply, as in e.g. physics engines for games; I feel it is important to recognise it for what it is instead of conceiving physics as an inherently complex thing to be found

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only in specialised simulations. For example, pretty much all mobile apps have what could be called “phone touch physics” where menus and screens slide in and out.

All humans learn a basic set of expectations about the things they see around them. Some of these, such as “things fall down”, are not generally appropriate to software UIs — perhaps because the screen has a role in our lives a more of a table work surface rather than a vertical wall, even if it is vertical in real life. The level of physics in software tends to not involve force, or mass, or very much at all, merely position and space; we could call it “geometric physics”.

One thing that all usable software must do, for example, is avoid crushing many visually complex shapes, such as lines of text, into the same (unreadable) region. Such concepts of “solid objects do not intersect” or “only things at different layers may overlap” are basic rules inherited from the real world of graphical presentation.

I feel the need to point this out, because by default the computer does not know even the most obvious things about how space works, so we must laboriously algorithmise this intuitive concept. This is not only true in the case of 2-dimensional visual domains, but even in the 1-dimensional case of memory allocation. The physics of 1D memory are something like this:

- This number range 0000–FFFF is like a space, addresses = points
- Every point has at most one owner block
- These blocks are contiguous, finite ranges (i.e. 1D boxes)

Hence the boilerplate involved to realise this in any domain with something resembling space. Far from being a niche topic in games and graphics, spatial partitioning algorithms and data structures have surprising relevance to more ordinary software. Both memory allocation and graphical layout are essential to today’s; shame that only one of those has been recognised as such — and entered the runtime of modern languages.

3.2.1 Translationally Rigid Bodies

When you have both a screen and a pointing device (e.g. touch or mouse), immediately it becomes worth having ways to move things around in at least a minimally realistic way. We can debate the appropriateness of Direct Manipulation for various situations. But it does make a lot of sense in simple cases, such moving around subdivisions of space (e.g. windows) or elements of a graphical design.

In OROM, the obvious candidate for this is the obj-dicts, plus all nested boxes in OROM/SVG. If I move the top-level rect, then I expect its children to move with it. This is simply the translational physics of **rigid bodies**: “this set of points all move together”. Of course, proper rigid bodies might also rotate and have mass, but this is usually undesirable for UI elements.

Translational rigidity can be expressed as the points X and Y always having the same displacement from each other. Or, when one point is moved, the rest also move by the same delta. This is a problem of **preserving the relationship over time**, which was a significant area of OROM/SVG.

3.3 Maintaining Relationships Over Time

The model of state-mutation present in most imperative languages is what I call “dumb” state. The language provides an affordance to change any part of the state to a new value, but nothing else.

What more could there be? Well, in *every* software system there are certain rules, or “invariants” of **internal consistency**, such as “translational rigidity” above. Often, changes to any part of the system are permissible, but only if connected or dependent parts of the state change in response.

The job of keeping track of who depends on whom can fall either on the programmer, or the computer. If the programmer has to do this, they can only go so far managing and simulating in their head. As systems grow more complex, it is only natural to try and make the computer more intelligent to do this work. What I am building up to is that whenever we (or I) consider constraints, “reactive” programming, or the “Observer” pattern as things you only wheel out *on special occasions*, we only deceive ourselves into doing the *same work* less explicitly. It seems that such “live state” should be the expected common case for software development.

If a platform does not provide a means to causally link and unlink bits of live state, then this must form part of the standard boilerplate. Such was the case in OROM/SVG. I implemented the system in an OOP fashion, and the Observable class is the most widely used. It wraps a current value and a list of subscribers, notifying them when it changes.

Getting an object to follow the mouse pointer (e.g. when dragging) is *conceptually* very simple: an “always equal” relation. In OROM/SVG founded on live-state, this can be expressed in much the same way:

```
subscribe(object.position, pointer.position);
```

By default, an Observable A responds to a change from Observable B by adopting B’s new value. So by subscribing the object’s position to the pointer’s, pointer movements copy the new position to the object.

3.4 Nut-Cracking With Sledgehammers

Speaking about vector graphics, physics, layout and constraint maintenance might give the impression of high *conceptual* complexity at the heart of even simple software. This is not quite true, which makes it all the worse that there is yet still immense *implementation* complexity.

We are conditioned to only think of these in their most general forms. But the “vector graphics” I use in OROM/SVG are just rects, lines, circles and text; a fraction of the full capability of SVG. The “geometric physics” I use is dwarfed by fully general 2D or 3D physics engines. The only layout algorithm I had the patience to implement was a simple way to expand a list of boxes to fit in a new child at the bottom. The affordance to place and size boxes *manually* is a convenient substitute, when required infrequently. Yet search for material on layout algorithms, and it can seem like Fully General Linear Inequality Solvers like Cassowary [Bor+97] are all there is.

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The inevitable requirements I suggest here, do *not* necessitate Fully General anything. In fact, such generality might make it *more* cumbersome to express what I wanted in OROM. As the old wisdom goes, there’s no point expressing a simple regex search as an arbitrary Turing machine; my boxes don’t *have* a moment of inertia or a mass and I don’t *need* a linear optimisation solver for my space management — for the time being. Under the theme of domain-appropriate tools, I think it is worth designing interfaces for *smaller-scale* instances of these areas and exploring what they can express.

4 Patterns and Polyfilling

The message of the previous section is that existing platforms are often at the wrong level of abstraction for the requirements of common software. I recognise that they are reasonably well-adapted to batch mode file I/O tasks, but that they fail for the *common case* is a problem. There is largely the same setup per project just to get basic functionality:

- Here is how I shall describe shapes
- Here is how I make these shapes move together
- Here is how I maintain internal consistency as the user unpredictably changes things

This burden either falls on the author, or on the wider community to build and maintain higher-level frameworks, syntax extensions, etc. In this paper, I refer to this process as “polyfilling”, with an emphasis on the DIY, individual level.

It is true, we already have a term for bringing into existence some software feature that isn’t already there: programming. The difference is that polyfilling is about filling in *boilerplate*, i.e. functionality *that should have been there in the first place, but isn’t*. This injects some subjectivity and value judgement into the term. But ultimately, all platforms are designed with certain features “out of the box” and leave other features for us to implement “if needed”.

When the *normal* problem domain “requires batteries”, yet the tools available say “batteries not included”, it is quite reasonable to want the batteries to be part of the platform. This section details the “batteries not included” I found myself polyfilling in OROM/SVG.

4.1 Wrapping and “user data”

The classic example of polyfilling is finding that JavaScript arrays do not support some familiar operation. For example, this used to be the case with the `map` function. Yet JavaScript lets you *directly augment* the `Array` class with the new operation, even though `Array` is “part of the language”:

```
Array.prototype.map = function() { ... }
```

One can do this to all objects, even those of Web APIs. For example, I use it to connect SVG nodes to the OROM system: when a `<rect>` is created, it is “annotated” with a `userData` pointer to the box that it is part of. Then, when clicked, the box can be found immediately.

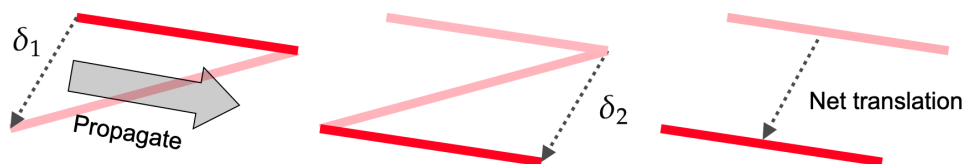
This could be described as the box “wrapping” the `<rect>`, but risks implying that the `<rect>` merely needs to *live inside*, or *be referenced by*, the box. In this case, the *reverse* association is also needed, because clicks can only enter the system *through* SVG in the first place. What is significant here is that JavaScript lets us add such a link to an entity that *we did not design*.

This term, “user data”, often crops up in libraries with the same idea: to associate arbitrary data with an API object. But in languages that do not permit such “annotation”, this has to be explicitly *designed in* ahead of time. If it wasn’t, then it has to be done in a roundabout way — for example, a separate `userData` lookup table, indexed by the memory address of the API object.

4.2 Positioning and Sizing

The simple desire to move and resize boxes with the mouse motivated a lot of the concepts in Sections 3.2 and 3.3. This problem could be considered a microcosm of OROM/SVG: what’s a natural way I *conceive* of this behaviour, and could I implement it that way?

It starts with a consideration of translational rigidity. In its most primitive form, this is a relation between two points. Thus it is natural to draw a line or “rod” between them. It seems that this rod transmits changes in one of its endpoints directly to the other endpoint. Since they both feel the same deltas, the displacement vector between them is preserved (Figure 3).

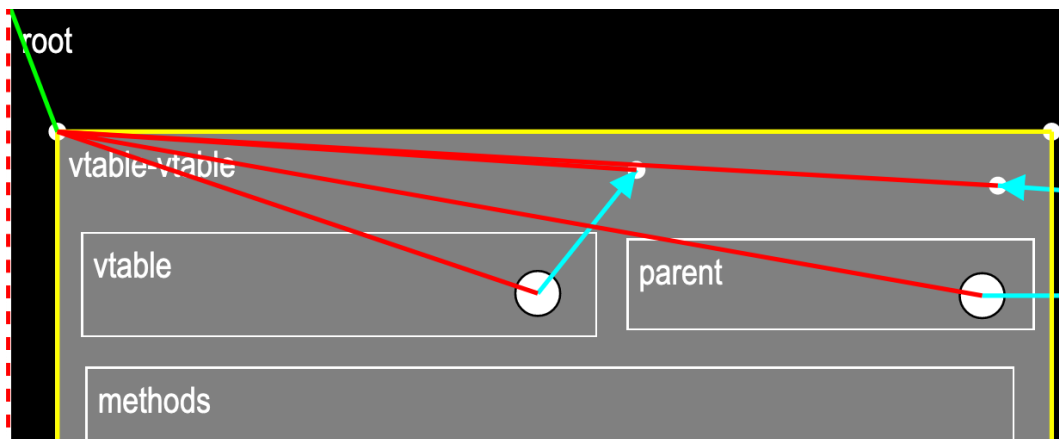


■ **Figure 3** Fully rigid rods transmit changes in one end to the other end.

I like to see what I’m doing, so I wanted these rods to be visible and thus somehow *present in the SVG*. This was not hard; in SVG I draw a `<line>`, though the background machinery of the Rod class does all the work. There is also a Point class that is used wherever manipulable points (SVG circles) are intended.

Resizing of boxes could be achieved through rods that stay horizontal or vertical. In the language of “small differences” spoken by the live-state infrastructure, this is expressed as a rod “transmitting deltas” in the vertical and horizontal, “absorbing” the other component into itself (Figure 4). Mirroring a DOM `rect` to these rods is as simple as subscribing its width and height to horizontal and vertical rods’ length Observables. This way, boxes can be resized from whatever corner is convenient.

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■ **Figure 4** The yellow rods on the box border are “half-rigid”: they transmit horizontal or vertical changes, but not both. The green rod in the top-left absorbs all changes from an endpoint into itself, visualising the displacement vector of the child box from its parent. The remaining red rods are fully rigid. A line of CSS can show this “scaffolding” which is normally hidden for users.

Unfortunately, with these rods came possibly the most frustrating technical challenges of the entire system. Initially I hoped to move boxes as rigid bodies by temporarily making their border rods rigid. However, the four border rods form a cyclic graph, as rods are not directed. This, coupled with the unintended depth-first semantics of Observable notification (a result of JavaScript function calls in a loop), led to duplicate deltas applied twice and other nightmares. This is the tip of an entire research iceberg stretching from Functional Reactive Programming to internet routing and distributed algorithms.

I had to shelve this investigation in the interest of continuing with the rest of the system, but I did manage to surmount this through kludging and compromise. So I do not know whether these problems are merely a consequence of some design decision I could change to escape it, or if they are intrinsic to my (modest) UI goal.

4.3 Visible Coordinate Systems

Rigidity in a flat world of sibling shapes is somewhat straightforward. However, rigidity in the SVG world is more involved.

First of all, SVG shapes (e.g. `<rect>`) are strictly *leaf* nodes of the DOM. So if I wish to nest boxes within boxes, the visible box `<rect>` must be a mere *accessory* to the nestable element, in my case a `<g>` (group). This means that instead of resizing the `x`, `y`, `width`, `height` attributes of the `<rect>`, only its `width` and `height` change, along with the `transform` attribute of its *parent* `<g>`. This was not too bad; just subscribe this attribute, instead of the `<rect>` position, to the top-left Point handle.

All child elements of a node transform with it, so already SVG has baked in a basic facility for translational rigidity. This is only available as a tree hierarchy,⁴ but it is still useful. However, it conflicts with my early decision to have Point objects all share the global co-ordinate system (this was to ensure that simple relations, such as a point following the mouse pointer, are not infuriating to express.) Still, it was necessary in the case of certain elements — especially those which must transcend the tree structure altogether, like arrows between boxes — to bite this bullet, one way or another.

Again, I return to how we tend to work things out in the freedom of paper. Co-ordinate systems, here merely positionally displaced, have their origins here and there and have vectors between them. The rods thus far let me visually express relations between global Points; now was a question of expressing one global Point as a displacement from another (the `<g>` transform). New rod Observables `p2_from_p1` and `p1_from_p2` do the vector subtraction, which can then be propagated as local co-ordinates to children. It is nice to express the relation (as well as see it!) this way (Figure 4).

4.4 Context-appropriate ontologies

Each API has its own conventions, including a way of naming and structuring expressions — an ontology [Bas18]. The One-Size-Fits-All approach is exemplified in such interfaces. For example, in SVG we express a rectangle by `<rect x="10" y="10" width="600" height="400">`. The SVG specification *defines* to the user that a `rect` simply is a top-left corner, a width, and a height — and that's it. However, this SVG-approved parametrisation of a rectangle is far from the only one, and thus is, unsurprisingly, ill-fitted to some contexts.

For example, I find it natural to resize boxes by dragging any of their four corners, so I wanted this in OROM/SVG. In this context, a “rectangle” is *seen as* four points: top-left, top-right, bottom-left, bottom-right. Obviously this is not a *minimal* description, since given e.g. the top-left and bottom-right, the other two points can be inferred. But one way or another, to be able to drag any of them, all four points must be present at *some* level. This alternative ontology was polyfilled in the form of a “rect controls” class that can be attached manually to any SVG `<rect>`. The `x` and `y` are subscribed to the top-left Point⁵; width and height are subscribed to Rod lengths.

Another example is to be found in the DOM's event listener model. Conceptually, many “events” are in fact changes to the state of some physical device. And both keyboard keys and mouse buttons, for example, have two states — pressed, not pressed — which ought to make them *interchangeable* to some extent. Indeed, this is

⁴ This highlights the mismatch between the tree-based DOM and any system that is graph-structured.

⁵ In the usual case where the `<rect>` is part of a box, the top-left instead controls the parent `<g>`'s transform — but the idea is the same.

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why there is such a thing as “key mapping”⁶ in PC games. But the official ontology of the Web makes it nontrivial to do this.

To start with, the situation is modelled not as the *changing* of some time-varying property, but instead as a sort of Cartesian product of event listeners. Rather than, say, a piece of live-state for the left mouse button (LMB), we get `onmousedown` and `onmouseup`. Thankfully we do not have `onAdown/onAup`, `onBdown/onBup`, ... all the way to `onZdown/onZup`, but only `onkeydown/onkeyup`. Yet this is just one of the many possible ways to slice this 3-dimensional⁷ space.

In OROM/SVG I did not quite want to re-map keys, but I did often want to have things follow the mouse when dragged. In order to do this, I reified the mouse pointer and its position, letting me write `subscribe(pointer.position, pointer.position)`. The Point has an `is-considering-me?` Observable wrapping `onmouseover/onmouseout`, and the LMB is reified into `left_mouse_button_is_down` to be explicit. The aforementioned subscription is set up whenever `is-considering-me?` and `left_mouse_button_is_down` become true, and torn down otherwise. I tended to think of this in the form “subscribe to pointer *only when* pointer is-considering-me *and* LMB is down”, but I could live with this notation as a future polyfill in JavaScript.

The way these things are connected to the browser’s event listeners could be called “device drivers” — an approach described in [Hagio]. It amounts to translating information from the Web’s ontology into that of my substrate, as early as possible:

```
svg.onmousedown = e =>
  if (e.button === 0) change(left_mouse_button_is_down, true);

svg.onmouseup = e =>
  if (e.button === 0) change(left_mouse_button_is_down, false);

svg.onmousemove = e => {
  let r = svg.getBoundingClientRect();
  let pos = vsub([e.clientX, e.clientY], [r.left, r.top]);
  change(pointer.position, pos);
};
```

It takes some frustration and experience to get used to the idea that you have a right to polyfill in alternative representations. Before I came to this conclusion, I used to twist my head around translating my intention into the `x,y,width,height` parameters, and un-translating when reading back the code I had produced. Once you get used to having to adapt your mental imagery to a single way of doing things (i.e. learning to code), it makes sense to simply expect to see more of it — especially when you know you are new, surrounded by veterans who see no problem, and so on. Nowadays, I take the position that these are simply *widespread* failings of our way of doing things, instead of *our* failure to adapt to the way software is.

⁶ For example, the player can re-assign the action “shoot” from its default mouse button to a keyboard key, or another action from keyboard to mouse, as it suits them.

⁷ Device (mouse, keyboard), sub-device (button, key), state (up, down)

What would it look like to support multiple ontologies? There are perhaps two answers: anticipate the possibilities ahead of time, or support users adding their own. It is unclear if we can do better on the latter than simply “support polyfilling”. As for the former: in general, anticipating the diversity of ways someone might look at the world is doomed to fail. But in the case of fairly *formalised* concepts such as geometrical shapes or mathematics, I could suggest that simple *under-specification* is the root of the problem in SVG. Instead of the specification explaining in English that “x and y are the co-ordinates of the top left-hand corner...”, it might be better to make these relations machine-readable or *embodied* in the API. For the rect this might look like:

A rect is...

- a polygon (to be defined elsewhere)
- defined by 4 *degrees of freedom* x y width height (internal representation)
- where there are 4 *vertices*, all points
 - [x,y] called top-left
 - [x+width,y] called top-right
 - [x,y+height] called bot-left
 - [x+width,y+height] called bot-right

The hope is that if we then specify enough information — say, the bot-left and top-right — then the runtime has all it needs to derive its internal 4 degrees of freedom.

In a crude sense, I have successfully anticipated the most obvious ontologies of a rectangle here. However, I missed out the “centre plus half-width and half-height” formulation, among others. Is this a futile effort even for precise mathematical knowledge structures, or could enough formalisation⁸ of Euclidean geometry in the Web platform put an end to this sort of polyfilling?

4.5 Extensional Functions

Time and time again we come across the same pattern of partitioning system state: trees or graphs of dictionaries, a.k.a. Maps, a.k.a. associative arrays. I am talking about filesystem paths `/path/to/some/file`, Python / Java modules `com.example.pkg.subpkg`, JavaScript objects `window.my_obj.component`. The common case is an association of a textual name to an arbitrary value. I find it useful to see this as a mathematical “function” defined *extensionally* by listing its input/output mappings — this opposed to an *intensional* definition such as $x \mapsto 2x + 3$, or a computer program.

Extensional functions are perhaps the most basic form of Knowledge Representation, and match natural language very well. “The bicycle’s wheels’ spokes are silver” straightforwardly translates to a function equation

```
root (bicycle) (wheels) (spokes) (colour) = root (silver)
```

⁸ A related question is whether type systems and other auto-reasoning formalisms are trapped in a doomed quest for “closed-form” AI, representable as a λ -calculus formula.

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That is, whatever object is the output of *silver* in the top-level root function, the output of *colour* (in the function on the left) points to the same object. The ability to partition a system in this way enables what [Bas+16] calls a “natural co-ordinate system” for a piece of software, crucial for understanding and adaptability by others.

It seems that this way of expressing the “parts” of a system is an inevitable requirement of any programming substrate. Some languages, such as C, do have static, *compile-time* associative arrays (structs). In my experience this is usually not enough, and it’s necessary to bring in a library or clutter the code with a home-grown approximation to dynamic ones. Some parts of the OROM authors’ C code were confusing until I realised they were just the guts of a basic associative-array implementation; when I switched to JavaScript, these lines vanished.

Perhaps another strength of JavaScript is its low *concrete syntax cost* for *instances* or *literals* of associative arrays. Writing or reading

```
a = {  
  b1: { c1: z, c2: y },  
  b2: { c3: x, c4: w }  
};
```

is more WYSIWYG⁹ than the imperative-style

```
a = new Map();  
a.set('b1', new Map());  
a.get('b1').set('c1', z);  
a.get('b1').set('c2', y);  
a.set('b2', new Map());  
a.get('b2').set('c3', x);  
a.get('b2').set('c4', w);
```

The latter style is unfortunately still required in JavaScript for extensional functions with *non-string* inputs.

The decision to switch from the flat tabular representation in OROM/HTML to the nestable, Boxer-like structure in OROM/SVG permitted extensional (tree) functions in its substrate. True, I could always encode these in flat tables by having them reference each other. But this is like the second listing above: hard to follow. In the case of distinguishing between ordinary state mappings and the “method dictionary” of *vtables*, I actually stored method mappings with a “-” character to avoid doing this (Figure 5). In OROM/SVG, I can directly express the model I was thinking of (Figure 6). So we can see this as polyfilling a mistake in the design of my substrate, rather than the Web platform underneath it.

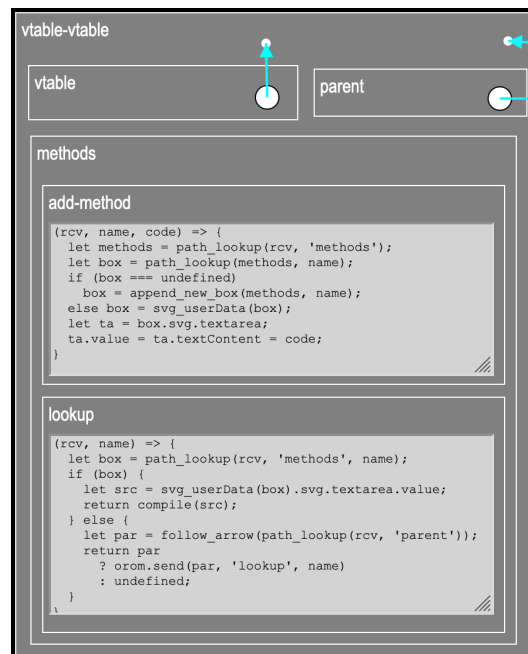
4.6 Persistence

This refers to exposing structured program state to the user. This data can then be saved and used to restore the system at a later date, but it can also be tweaked with corresponding changes reflected in the system.

⁹ What You See Is What You Get

id	1
vtable	1
parent	2
name	vtable vtable
-addMethod	4
-lookup	5
-allocate	6
-delegated	8

■ **Figure 5** OROM/HTML: use of hyphenated -lookup to signify a *method* called lookup instead of a property like vtable.



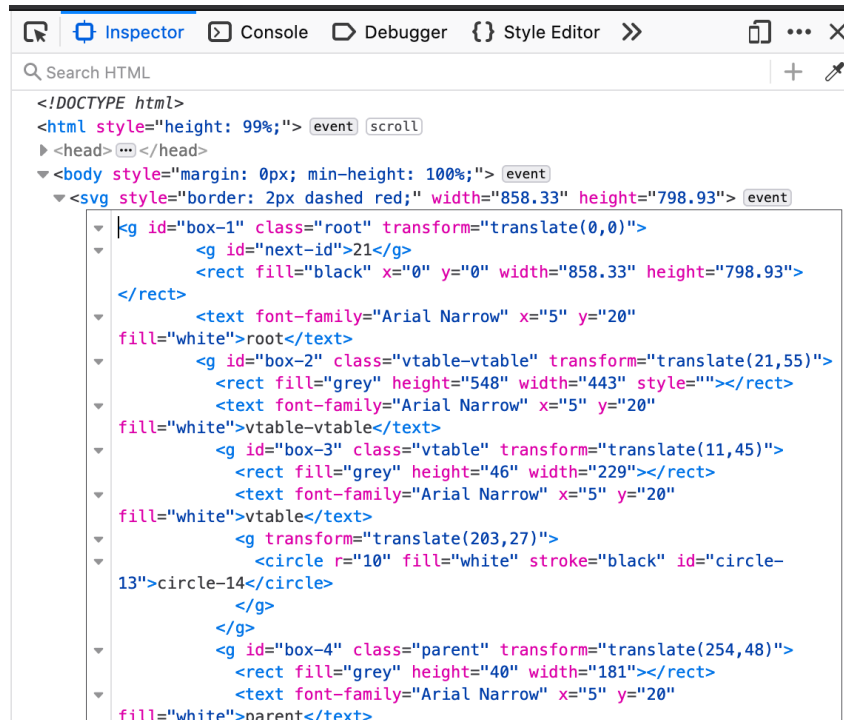
■ **Figure 6** OROM/SVG: the vtable box has a methods box, and that's where the method boxes go.

Persistence was absolutely necessary to continue OROM/SVG development, past a certain point. This is because, upon discovering a bug and fixing it in the source code, the web page must be refreshed and started anew. In the beginning, when verifying that box drawing with the mouse is working correctly, this is not much of a problem: upon refresh, the blank initial state is restored and I could draw again. But as the substrate matured, and I began to implement parts of the target system (OROM) — the cycle of finding a bug, tearing down the system, refreshing and losing work, and manually building it up again, proved frustrating. Because the system could only be

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patched externally and restarted, there needed to be some way to persist changes which live in the DOM, rather than the source files.

Normally, this can be as simple as autosave to the filesystem. But the Web platform is very wary of this;¹⁰ so the solution I turned to was manually copying the markup in the browser's inspector (Figure 7).



■ **Figure 7** To save the state of the system, the SVG group corresponding to the root box is copied and pasted inside the HTML file's `<svg>` element.

This required a slight change towards an architecture where the all the data required to reconstruct the system's current state is contained in the inspector HTML (as well as the OROM/SVG JavaScript source code, of course.) Where previously “boxes” were created first as invisible JS objects responsible for some SVG, now it was the other way round. When a rect is clicked, the system must look at some SVG and interpret it “on demand” as a box (lazily initialising its helper object if so).

Persistence seems to be a weaker cousin of **externalisability**, defined in [Bas+16]. As it stands, the system does not quite qualify as externalisable. When making changes to the HTML in the element inspector, the system's behaviour *ought* to adjust to match, but this is not currently guaranteed. Depending on the ability to listen for changes in node attributes or children, this may remain the case.

¹⁰ As anyone who learns WebGL can attest to, when they discover they must run a local Web server to provide image files for textures since any filesystem requests will be rejected for security.

5 The OROM system as a part of the solution

The OROM system was designed with a goal of eliminating the “artificial” distinction between implementation language and end-user language, by means of a mostly self-defining, or “meta-circular” object model. This general way of working on a piece of software “by means of itself” is easy to agree with, even if OOP is not to everyone’s taste. It is an open question whether OROM’s approach could be applied to other programming styles.

The allure of meta-circularity here is not merely in being “cool”, but that it paves the way to end-user empowerment. This is somewhat misleading because in OROM, these “end-users” are actually programmers. However, its purpose is to free a programmer’s dependence on some distant and busy¹¹ language designer. It seems plausible that this is a step on the way to enabling *creation* of a piece of software which non-programmers do not depend on us for.

I emphasise that this is the *allure* of OROM. However, there are some significant practical issues that must be overcome or clarified first.

5.1 Minimal descriptions

The OROM paper was part of the STEPS project of Alan Kay’s VPRI.¹² This project argued that the immense level of “accidental complexity” present in software implementation could be reduced, and Kay himself dreams of an end result analogous to a “Maxwell’s Equations” of software. That is: the behaviour of electromagnetic fields can be represented in four short equations that fit “on a T-shirt”.

A self-hosted LISP interpreter fits on a page. Could we aim at a similar “fundamental description of software” that fits on something less than millions of lines of code?

This argument as stated suffers by glossing over an important fact. Maxwell’s equations certainly do fit onto a T-shirt, but most people will not be able to explain what they mean. What typically amounts to years of study is compressed into those mathematical symbols, and the learning material involved most certainly does *not* fit on a T-shirt. The obvious *reductio ad absurdum* is where we encapsulate these equations under a single symbol, *M*. *M* is defined as “Maxwell’s Equations are true”. Ta-da — this fits on a coin, but good luck doing anything with it.¹³

I say this not to dismiss the argument, but to highlight the actually hard part of getting a “concise description” of some system; defining complexity away into a symbol helps us no more than naming the solution to an equation “*x*”. There is a connection with data compression: even if the data successfully compressed into a smaller file, the size of the compression *program* should be added as well. What matters is to reduce the *combined* size of notation and platform.

¹¹ Not to mention unelected? “Take Back Control!” (jokes aside, in this context it makes a lot of sense.)

¹² Viewpoints Research Institute

¹³ In fact, this is almost achieved by the formalism of Geometric Calculus, which reduces them to only one equation.

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Further, there is perhaps a risk of optimising for *formal* rather than *practical* minimality (e.g. the Turing machine). OROM’s “minimality” does not necessarily translate into “simplicity”. It suffers from the same *cognitive* complexity, or need for study, as Maxwell’s Equations; I cannot stress enough the amount of effort I have put in to wrap my head around the self-referential “vtable vtable” and the task of self-implementation. An overall better system might be one which is easier to pick up or understand, even if the number of formal objects is not as minimal.

Much to their credit, in the conclusion of [PW06], the authors note that “it is not necessarily a friendly model for hand-written code”, suggesting its use as a compilation target. In a similar vein, it could function as the kernel of a much more familiar system (on the surface) — it is, after all, supposed to be a vehicle that other things sit on, rather than the final user interface itself.

5.2 Self-implementation

The related paper [Piu06] expands on OROM, giving it a “structural” role complemented by a LISP-like programming language. Section 6.1 sketches out the intended “bootstrapping” process, ending with a self-sufficient, self-hosting version of the system.

However, this task again suffers from the same cognitive complexity as any other self-referential circle. This is even more so, having made the complexity of graphics and interaction somehow still “part of the system”. Figuring out exactly how the authors’ bootstrapping process of their wholly *language-based* system maps on to my task is full of unknowns at this point.

Finally, in [Bas18], there is a warning against “obsession with completely homogeneous systems” written in themselves. If this approach is doomed then obviously I want to take a different one, but the argument against it seems to hinge on what constitutes “failure”. It considers Smalltalk and LISP as “unsuitable”, yet the authors of OROM clearly think the opposite. The disagreement probably hinges on “unsuitable for *what?*” and it would be clearer if the following two questions were answered:

1. Is there a difference in (final, intermediate) goals between the two views?
2. Could systems like OROM and COLAs plausibly succeed at their own stated goals?

6 Conclusion and future work

It takes a lot of work to create in a substrate that feels suited to the domain. Much of this work involves filling in the machinery necessary to an awful lot of software, rather than the ways one’s domain *differs from* this common case. I have explicitly highlighted the obstacles one is likely to meet when starting from an ordinary programming platform. I also showed how I overcame them with solutions intended to be domain-appropriate to their use, within the limits of the implementation language.

OROM/SVG more or less realises my desired substrate for implementing OROM. However, there is one major area I failed to make domain-appropriate. Despite representing the “data” parts of the system as I wanted, the *computational* parts of OROM

were just transplanted into the text boxes as source code. I will reiterate that this is *sometimes* suitable, but not always, and it would be worth exploring alternative ways to express some of it in the substrate I have. Having JavaScript code that the user can modify also seems to mess up the browser’s debugger when stepping through it.

Still, in this mostly-suitable substrate for OROM, I can continue with my project of seeing whether the *allure* of [Piuo6] can be saved from the text-based “hidden world” limitation that pervades it. The obvious next step is attempting “self-implementation”. This is desirable because I still have not escaped my text editor. Any changes to my OROM/SVG substrate (of nested box drawing) require going back to the script files; I still cannot take advantage of the system I have developed, to ease its own development. In the words of [Piuo6], I wish to make it so that the original JavaScript files can be “jettisoned without remorse”.

In Section 3.1, I touched on how everyone with a browser has access to a powerful vector graphics editor (SVG) locked behind a completely inappropriate UI (the JS Console). It is similar for 3D graphics (WebGL), and sound and music (Web Audio). Similar observations are made about “native” OS apps in [Hagi3]. But even the interactive JS Console is a step above batch-mode compilation, which is the interface that unlocks your operating system’s range of functionalities. So I single out the far more ubiquitous Web platform as having more “wasted potential”.

I hope to use OROM/SVG to “tame” SVG and other JavaScript APIs, with some minimal on-demand visualisation in the large portion of the screen adjacent to the JS console. This is an attempt to generalise the “rect controls”, which allow the obvious geometric properties of a `<rect>` to be directly manipulated (Section 4.4). Giving OROM access to Web technologies in this way is essential for evolving it into a *fully-featured* self-changeable software environment, which could allow as much domain-specific representation as its user wishes.

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