Package 'cTMed'

May 13, 2024			
Title Continuous Time Mediation			
Version 0.9.1			
Description Calculates standard errors and confidence intervals for effects in continuous time mediation models.			
<pre>URL https://github.com/jeksterslab/cTMed, https://jeksterslab.github.io/cTMed/</pre>			
BugReports https://github.com/jeksterslab/cTMed/issues License MIT + file LICENSE Encoding UTF-8 Roxygen list(markdown = TRUE) Depends R (>= 3.5.0) LinkingTo Rcpp, RcppArmadillo Imports Rcpp, numDeriv, parallel, ctsem Suggests knitr, rmarkdown, testthat, simStateSpace, expm RoxygenNote 7.3.1 NeedsCompilation yes Author Ivan Jacob Agaloos Pesigan [aut, cre, cph]			
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confint.ctmeddelta

Delta Method Confidence Intervals

Description

Delta Method Confidence Intervals

Usage

```
## S3 method for class 'ctmeddelta'
confint(object, parm = NULL, level = 0.95, ...)
```

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Arguments

Object of class ctmeddelta. object a specification of which parameters are to be given confidence intervals, either parm a vector of numbers or a vector of names. If missing, all parameters are considered. the confidence level required. level

additional arguments.

Value

Returns a matrix of confidence intervals.

Author(s)

Ivan Jacob Agaloos Pesigan

```
phi <- matrix(</pre>
 data = c(
   -0.357, 0.771, -0.450,
   0.0, -0.511, 0.729,
   0, 0, -0.693
 ),
 nrow = 3
)
colnames(phi) <- rownames(phi) <- c("x", "m", "y")</pre>
vcov_phi_vec <- matrix(</pre>
 data = c(
   0.002704274, -0.001475275, 0.000949122,
    -0.001619422, 0.000885122, -0.000569404,
   0.00085493, -0.000465824, 0.000297815,
    -0.001475275, 0.004428442, -0.002642303,
   0.000980573, -0.00271817, 0.001618805,
   -0.000586921, 0.001478421, -0.000871547,
   0.000949122, -0.002642303, 0.006402668,
    -0.000697798, 0.001813471, -0.004043138,
   0.000463086, -0.001120949, 0.002271711,
    -0.001619422, 0.000980573, -0.000697798,
   0.002079286, -0.001152501, 0.000753,
    -0.001528701, 0.000820587, -0.000517524,
   0.000885122, -0.00271817, 0.001813471,
    -0.001152501, 0.00342605, -0.002075005,
   0.000899165, -0.002532849, 0.001475579,
    -0.000569404, 0.001618805, -0.004043138,
   0.000753, -0.002075005, 0.004984032,
    -0.000622255, 0.001634917, -0.003705661,
   0.00085493, -0.000586921, 0.000463086,
   -0.001528701, 0.000899165, -0.000622255,
   0.002060076, -0.001096684, 0.000686386,
```

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```
-0.000465824, 0.001478421, -0.001120949,
   0.000820587, -0.002532849, 0.001634917,
   -0.001096684, 0.003328692, -0.001926088,
   0.000297815, -0.000871547, 0.002271711,
   -0.000517524, 0.001475579, -0.003705661,
   0.000686386, -0.001926088, 0.004726235
 ),
 nrow = 9
)
# Specific time interval ------
delta <- DeltaMed(
 phi = phi,
 vcov_phi_vec = vcov_phi_vec,
 delta_t = 1,
 from = "x",
 to = "y",
 med = "m"
)
confint(delta)
# Range of time intervals ------
delta <- DeltaMed(</pre>
 phi = phi,
 vcov_phi_vec = vcov_phi_vec,
 delta_t = 1:5,
 from = "x",
 to = "y",
 med = "m"
confint(delta)
```

confint.ctmedmc

Monte Carlo Method Confidence Intervals

Description

Monte Carlo Method Confidence Intervals

Usage

```
## S3 method for class 'ctmedmc'
confint(object, parm = NULL, level = 0.95, ...)
```

Arguments

object

Object of class ctmedmc.

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a specification of which parameters are to be given confidence intervals, either a vector of numbers or a vector of names. If missing, all parameters are considered.

1evel the confidence level required.
... additional arguments.

Value

Returns a matrix of confidence intervals.

Author(s)

Ivan Jacob Agaloos Pesigan

```
set.seed(42)
phi <- matrix(</pre>
  data = c(
    -0.357, 0.771, -0.450,
    0.0, -0.511, 0.729,
    0, 0, -0.693
  ),
  nrow = 3
)
colnames(phi) \leftarrow rownames(phi) \leftarrow c("x", "m", "y")
vcov_phi_vec <- matrix(</pre>
  data = c(
    0.002704274, -0.001475275, 0.000949122,
    -0.001619422, 0.000885122, -0.000569404,
    0.00085493, -0.000465824, 0.000297815,
    -0.001475275, 0.004428442, -0.002642303,
    0.000980573, -0.00271817, 0.001618805,
    -0.000586921, 0.001478421, -0.000871547,
    0.000949122, -0.002642303, 0.006402668,
    -0.000697798, 0.001813471, -0.004043138,
    0.000463086, -0.001120949, 0.002271711,
    -0.001619422, 0.000980573, -0.000697798,
    0.002079286, -0.001152501, 0.000753,
    -0.001528701, 0.000820587, -0.000517524,
    0.000885122, -0.00271817, 0.001813471,
    -0.001152501, 0.00342605, -0.002075005,
    0.000899165, -0.002532849, 0.001475579,
    -0.000569404, 0.001618805, -0.004043138,
    0.000753, -0.002075005, 0.004984032,
    -0.000622255, 0.001634917, -0.003705661,
    0.00085493, -0.000586921, 0.000463086,
    -0.001528701, 0.000899165, -0.000622255,
    0.002060076, -0.001096684, 0.000686386,
    -0.000465824, 0.001478421, -0.001120949,
    0.000820587, -0.002532849, 0.001634917,
    -0.001096684, 0.003328692, -0.001926088,
```

```
0.000297815, -0.000871547, 0.002271711,
   -0.000517524, 0.001475579, -0.003705661,
   0.000686386, -0.001926088, 0.004726235
 ),
 nrow = 9
)
# Specific time interval -------
mc <- MCMed(</pre>
 phi = phi,
 vcov_phi_vec = vcov_phi_vec,
 delta_t = 1,
 from = "x",
 to = "y",
 med = "m"
 R = 100L # use a large value for R in actual research
)
confint(mc)
# Range of time intervals ------
mc <- MCMed(</pre>
 phi = phi,
 vcov_phi_vec = vcov_phi_vec,
 delta_t = 1:5,
 from = "x",
 to = "y",
 med = "m",
 R = 100L # use a large value for R in actual research
confint(mc)
```

DeltaBeta

Delta Method Sampling Variance-Covariance Matrix for the Elements of the Matrix of Lagged Coefficients Over a Specific Time Interval or a Range of Time Intervals

Description

This function computes the delta method sampling variance-covariance matrix for the elements of the matrix of lagged coefficients β over a specific time interval Δt or a range of time intervals using the first-order stochastic differential equation model's drift matrix Φ .

Usage

```
DeltaBeta(phi, vcov_phi_vec, delta_t, ncores = NULL)
```

Arguments

phi Numeric matrix. The drift matrix (Φ), phi should have row and column names

pertaining to the variables in the system.

vcov_phi_vec Numeric matrix. The sampling variance-covariance matrix of $vec(\Phi)$.

delta_t Vector of positive numbers. Time interval (Δt).

ncores Positive integer. Number of cores to use. If ncores = NULL, use a single core.

Consider using multiple cores when the length of delta_t is long.

Details

See Total().

Delta Method:

Let θ be $\operatorname{vec}(\Phi)$, that is, the elements of the Φ matrix in vector form sorted column-wise. Let $\hat{\theta}$ be $\operatorname{vec}(\hat{\Phi})$. By the multivariate central limit theory, the function g using $\hat{\theta}$ as input can be expressed as:

$$\sqrt{n}\left(\mathbf{g}\left(\hat{\boldsymbol{\theta}}\right) - \mathbf{g}\left(\boldsymbol{\theta}\right)\right) \xrightarrow{\mathrm{D}} \mathcal{N}\left(0, \mathbf{J}\boldsymbol{\Gamma}\mathbf{J}'\right)$$

where **J** is the matrix of first-order derivatives of the function **g** with respect to the elements of θ and Γ is the asymptotic variance-covariance matrix of $\hat{\theta}$.

From the former, we can derive the distribution of $\mathbf{g}\left(\hat{\boldsymbol{\theta}}\right)$ as follows:

$$\mathbf{g}\left(\hat{\boldsymbol{\theta}}\right) \approx \mathcal{N}\left(\mathbf{g}\left(\boldsymbol{\theta}\right), n^{-1}\mathbf{J}\boldsymbol{\Gamma}\mathbf{J}'\right)$$

The uncertainty associated with the estimator $\mathbf{g}\left(\hat{\boldsymbol{\theta}}\right)$ is, therefore, given by $n^{-1}\mathbf{J}\Gamma\mathbf{J}'$. When Γ is unknown, by substitution, we can use the estimated sampling variance-covariance matrix of $\hat{\boldsymbol{\theta}}$, that is, $\hat{\mathbb{V}}\left(\hat{\boldsymbol{\theta}}\right)$ for $n^{-1}\Gamma$. Therefore, the sampling variance-covariance matrix of $\mathbf{g}\left(\hat{\boldsymbol{\theta}}\right)$ is given by

$$\mathbf{g}\left(\hat{\boldsymbol{\theta}}\right) \approx \mathcal{N}\left(\mathbf{g}\left(\boldsymbol{\theta}\right), \mathbf{J}\hat{\mathbb{V}}\left(\hat{\boldsymbol{\theta}}\right) \mathbf{J}'\right).$$

Linear Stochastic Differential Equation Model:

The measurement model is given by

$$\mathbf{y}_{i,t} = oldsymbol{
u} + oldsymbol{\Lambda} oldsymbol{\eta}_{i,t} + oldsymbol{arepsilon}_{i,t}, \quad ext{with} \quad oldsymbol{arepsilon}_{i,t} \sim \mathcal{N}\left(\mathbf{0}, oldsymbol{\Theta}
ight)$$

where $\mathbf{y}_{i,t}$, $\eta_{i,t}$, and $\varepsilon_{i,t}$ are random variables and ν , Λ , and Θ are model parameters. $\mathbf{y}_{i,t}$ represents a vector of observed random variables, $\eta_{i,t}$ a vector of latent random variables, and $\varepsilon_{i,t}$ a vector of random measurement errors, at time t and individual t. ν denotes a vector of intercepts, Λ a matrix of factor loadings, and Θ the covariance matrix of ε .

An alternative representation of the measurement error is given by

$$\boldsymbol{\varepsilon}_{i,t} = \boldsymbol{\Theta}^{\frac{1}{2}} \mathbf{z}_{i,t}, \quad \text{with} \quad \mathbf{z}_{i,t} \sim \mathcal{N}\left(\mathbf{0}, \mathbf{I}\right)$$

where $\mathbf{z}_{i,t}$ is a vector of independent standard normal random variables and $\left(\mathbf{\Theta}^{\frac{1}{2}}\right)\left(\mathbf{\Theta}^{\frac{1}{2}}\right)'=\mathbf{\Theta}.$

The dynamic structure is given by

$$\mathrm{d}\boldsymbol{\eta}_{i,t} = \left(\boldsymbol{\iota} + \boldsymbol{\Phi}\boldsymbol{\eta}_{i,t}\right) \mathrm{d}t + \boldsymbol{\Sigma}^{\frac{1}{2}} \mathrm{d}\mathbf{W}_{i,t}$$

where ι is a term which is unobserved and constant over time, Φ is the drift matrix which represents the rate of change of the solution in the absence of any random fluctuations, Σ is the matrix of volatility or randomness in the process, and $\mathrm{d}W$ is a Wiener process or Brownian motion, which represents random fluctuations.

Value

Returns an object of class ctmeddelta which is a list with the following elements:

call Function call.

args Function arguments.

fun Function used (DeltaBeta).

output A list with length of length(delta_t).

Each element in the output list has the following elements:

delta_t Time interval.

jacobian Jacobian matrix.

est Estimated total, direct, and indirect effects.

vcov Sampling variance-covariance matrix of the estimated total, direct, and indirect effects.

Author(s)

Ivan Jacob Agaloos Pesigan

References

Bollen, K. A. (1987). Total, direct, and indirect effects in structural equation models. Sociological Methodology, 17, 37. doi:10.2307/271028

Deboeck, P. R., & Preacher, K. J. (2015). No need to be discrete: A method for continuous time mediation analysis. Structural Equation Modeling: A Multidisciplinary Journal, 23 (1), 61–75. doi:10.1080/10705511.2014.973960

Ryan, O., & Hamaker, E. L. (2021). Time to intervene: A continuous-time approach to network analysis and centrality. Psychometrika, 87 (1), 214–252. doi:10.1007/s11336021097670

See Also

```
Other Continuous Time Mediation Functions: DeltaIndirectCentral(), DeltaMed(), DeltaTotalCentral(), Direct(), Indirect(), IndirectCentral(), MCBeta(), MCIndirectCentral(), MCMed(), MCPhi(), MCTotalCentral(), Med(), PosteriorBeta(), PosteriorIndirectCentral(), PosteriorMed(), PosteriorPhi(), PosteriorTotalCentral(), TestPhi(), TestStable(), Total(), TotalCentral()
```

```
phi <- matrix(</pre>
 data = c(
   -0.357, 0.771, -0.450,
   0.0, -0.511, 0.729,
   0, 0, -0.693
 nrow = 3
)
colnames(phi) <- rownames(phi) <- c("x", "m", "y")</pre>
vcov_phi_vec <- matrix(</pre>
 data = c(
   0.002704274, -0.001475275, 0.000949122,
   -0.001619422, 0.000885122, -0.000569404,
   0.00085493, -0.000465824, 0.000297815,
   -0.001475275, 0.004428442, -0.002642303,
   0.000980573, -0.00271817, 0.001618805,
   -0.000586921, 0.001478421, -0.000871547,
   0.000949122, -0.002642303, 0.006402668,
   -0.000697798, 0.001813471, -0.004043138,
   0.000463086, -0.001120949, 0.002271711,
   -0.001619422, 0.000980573, -0.000697798,
   0.002079286, -0.001152501, 0.000753,
   -0.001528701, 0.000820587, -0.000517524,
   0.000885122, -0.00271817, 0.001813471,
   -0.001152501, 0.00342605, -0.002075005,
   0.000899165, -0.002532849, 0.001475579,
   -0.000569404, 0.001618805, -0.004043138,
   0.000753, -0.002075005, 0.004984032,
   -0.000622255, 0.001634917, -0.003705661,
   0.00085493, -0.000586921, 0.000463086,
   -0.001528701, 0.000899165, -0.000622255,
   0.002060076, -0.001096684, 0.000686386,
   -0.000465824, 0.001478421, -0.001120949,
   0.000820587, -0.002532849, 0.001634917,
   -0.001096684, 0.003328692, -0.001926088,
   0.000297815, -0.000871547, 0.002271711,
   -0.000517524, 0.001475579, -0.003705661,
    0.000686386, \ -0.001926088, \ 0.004726235 
 ),
 nrow = 9
)
# Specific time interval ------
DeltaBeta(
 phi = phi,
 vcov_phi_vec = vcov_phi_vec,
 delta_t = 1
# Range of time intervals -------
delta <- DeltaBeta(
```

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```
phi = phi,
  vcov_phi_vec = vcov_phi_vec,
  delta_t = 1:5
)
plot(delta)

# Methods -------
# DeltaBeta has a number of methods including
# print, summary, confint, and plot
print(delta)
summary(delta)
confint(delta, level = 0.95)
plot(delta)
```

DeltaIndirectCentral

Delta Method Sampling Variance-Covariance Matrix for the Indirect Effect Centrality Over a Specific Time Interval or a Range of Time Intervals

Description

This function computes the delta method sampling variance-covariance matrix for the indirect effect centrality over a specific time interval Δt or a range of time intervals using the first-order stochastic differential equation model's drift matrix Φ .

Usage

```
DeltaIndirectCentral(phi, vcov_phi_vec, delta_t, ncores = NULL)
```

Arguments

phi Numeric matrix. The drift matrix (Φ) , phi should have row and column names

pertaining to the variables in the system.

vcov_phi_vec Numeric matrix. The sampling variance-covariance matrix of vec (Φ) .

delta_t Vector of positive numbers. Time interval (Δt).

ncores Positive integer. Number of cores to use. If ncores = NULL, use a single core.

Consider using multiple cores when the length of delta_t is long.

Details

See IndirectCentral() more details.

Delta Method:

Let θ be $\operatorname{vec}(\Phi)$, that is, the elements of the Φ matrix in vector form sorted column-wise. Let $\hat{\theta}$ be $\operatorname{vec}(\hat{\Phi})$. By the multivariate central limit theory, the function \mathbf{g} using $\hat{\theta}$ as input can be expressed as:

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$$\sqrt{n}\left(\mathbf{g}\left(\hat{\boldsymbol{\theta}}\right) - \mathbf{g}\left(\boldsymbol{\theta}\right)\right) \xrightarrow{\mathrm{D}} \mathcal{N}\left(0, \mathbf{J}\boldsymbol{\Gamma}\mathbf{J}'\right)$$

where **J** is the matrix of first-order derivatives of the function **g** with respect to the elements of θ and Γ is the asymptotic variance-covariance matrix of $\hat{\theta}$.

From the former, we can derive the distribution of $\mathbf{g}\left(\hat{\boldsymbol{\theta}}\right)$ as follows:

$$\mathbf{g}\left(\hat{\boldsymbol{\theta}}\right) \approx \mathcal{N}\left(\mathbf{g}\left(\boldsymbol{\theta}\right), n^{-1}\mathbf{J}\boldsymbol{\Gamma}\mathbf{J}'\right)$$

The uncertainty associated with the estimator $\mathbf{g}\left(\hat{\boldsymbol{\theta}}\right)$ is, therefore, given by $n^{-1}\mathbf{J}\Gamma\mathbf{J}'$. When Γ is unknown, by substitution, we can use the estimated sampling variance-covariance matrix of $\hat{\boldsymbol{\theta}}$, that is, $\hat{\mathbb{V}}\left(\hat{\boldsymbol{\theta}}\right)$ for $n^{-1}\Gamma$. Therefore, the sampling variance-covariance matrix of $\mathbf{g}\left(\hat{\boldsymbol{\theta}}\right)$ is given by

$$\mathbf{g}\left(\hat{\boldsymbol{\theta}}\right) \approx \mathcal{N}\left(\mathbf{g}\left(\boldsymbol{\theta}\right), \mathbf{J}\hat{\mathbb{V}}\left(\hat{\boldsymbol{\theta}}\right) \mathbf{J}'\right).$$

Linear Stochastic Differential Equation Model:

The measurement model is given by

$$\mathbf{y}_{i,t} = \mathbf{\nu} + \mathbf{\Lambda} \boldsymbol{\eta}_{i,t} + \boldsymbol{arepsilon}_{i,t}, \quad ext{with} \quad \boldsymbol{arepsilon}_{i,t} \sim \mathcal{N}\left(\mathbf{0}, \mathbf{\Theta}
ight)$$

where $\mathbf{y}_{i,t}$, $\boldsymbol{\eta}_{i,t}$, and $\boldsymbol{\varepsilon}_{i,t}$ are random variables and $\boldsymbol{\nu}$, $\boldsymbol{\Lambda}$, and $\boldsymbol{\Theta}$ are model parameters. $\mathbf{y}_{i,t}$ represents a vector of observed random variables, $\boldsymbol{\eta}_{i,t}$ a vector of latent random variables, and $\boldsymbol{\varepsilon}_{i,t}$ a vector of random measurement errors, at time t and individual i. $\boldsymbol{\nu}$ denotes a vector of intercepts, $\boldsymbol{\Lambda}$ a matrix of factor loadings, and $\boldsymbol{\Theta}$ the covariance matrix of $\boldsymbol{\varepsilon}$.

An alternative representation of the measurement error is given by

$$oldsymbol{arepsilon}_{i,t} = oldsymbol{\Theta}^{rac{1}{2}} \mathbf{z}_{i,t}, \quad ext{with} \quad \mathbf{z}_{i,t} \sim \mathcal{N}\left(\mathbf{0}, \mathbf{I}
ight)$$

where $\mathbf{z}_{i,t}$ is a vector of independent standard normal random variables and $\left(\mathbf{\Theta}^{\frac{1}{2}}\right)\left(\mathbf{\Theta}^{\frac{1}{2}}\right)' = \mathbf{\Theta}$. The dynamic structure is given by

$$\mathrm{d}oldsymbol{\eta}_{i,t} = \left(oldsymbol{\iota} + oldsymbol{\Phi}oldsymbol{\eta}_{i,t}
ight)\mathrm{d}t + oldsymbol{\Sigma}^{rac{1}{2}}\mathrm{d}\mathbf{W}_{i,t}$$

where ι is a term which is unobserved and constant over time, Φ is the drift matrix which represents the rate of change of the solution in the absence of any random fluctuations, Σ is the matrix of volatility or randomness in the process, and $\mathrm{d}W$ is a Wiener process or Brownian motion, which represents random fluctuations.

Value

Returns an object of class ctmeddelta which is a list with the following elements:

call Function call.

args Function arguments.

fun Function used (DeltaIndirectCentral).

output A list with length of length(delta_t).

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Each element in the output list has the following elements:

delta t Time interval.

jacobian Jacobian matrix.

est Estimated total, direct, and indirect effects.

vcov Sampling variance-covariance matrix of the estimated total, direct, and indirect effects.

Author(s)

Ivan Jacob Agaloos Pesigan

References

Bollen, K. A. (1987). Total, direct, and indirect effects in structural equation models. Sociological Methodology, 17, 37. doi:10.2307/271028

Deboeck, P. R., & Preacher, K. J. (2015). No need to be discrete: A method for continuous time mediation analysis. Structural Equation Modeling: A Multidisciplinary Journal, 23 (1), 61–75. doi:10.1080/10705511.2014.973960

Ryan, O., & Hamaker, E. L. (2021). Time to intervene: A continuous-time approach to network analysis and centrality. Psychometrika, 87 (1), 214–252. doi:10.1007/s11336021097670

See Also

```
Other Continuous Time Mediation Functions: DeltaBeta(), DeltaMed(), DeltaTotalCentral(), Direct(), Indirect(), IndirectCentral(), MCBeta(), MCIndirectCentral(), MCMed(), MCPhi(), MCTotalCentral(), Med(), PosteriorBeta(), PosteriorIndirectCentral(), PosteriorMed(), PosteriorPhi(), PosteriorTotalCentral(), TestPhi(), TestStable(), Total(), TotalCentral()
```

```
phi <- matrix(</pre>
 data = c(
   -0.357, 0.771, -0.450,
   0.0, -0.511, 0.729,
   0, 0, -0.693
 ),
 nrow = 3
colnames(phi) <- rownames(phi) <- c("x", "m", "y")</pre>
vcov_phi_vec <- matrix(</pre>
 data = c(
    0.002704274, -0.001475275, 0.000949122,
    -0.001619422, 0.000885122, -0.000569404,
    0.00085493, -0.000465824, 0.000297815,
    -0.001475275, 0.004428442, -0.002642303,
    0.000980573, -0.00271817, 0.001618805,
    -0.000586921, 0.001478421, -0.000871547,
    0.000949122, -0.002642303, 0.006402668,
    -0.000697798, 0.001813471, -0.004043138,
    0.000463086, -0.001120949, 0.002271711,
```

```
-0.001619422, 0.000980573, -0.000697798,
   0.002079286, -0.001152501, 0.000753,
   -0.001528701, 0.000820587, -0.000517524,
   0.000885122, -0.00271817, 0.001813471,
   -0.001152501, 0.00342605, -0.002075005,
   0.000899165, -0.002532849, 0.001475579,
   -0.000569404, 0.001618805, -0.004043138,
   0.000753, -0.002075005, 0.004984032,
   -0.000622255, 0.001634917, -0.003705661,
   0.00085493, -0.000586921, 0.000463086,
   -0.001528701, 0.000899165, -0.000622255,
   0.002060076, -0.001096684, 0.000686386,
   -0.000465824, 0.001478421, -0.001120949,
   0.000820587, -0.002532849, 0.001634917,
   -0.001096684, 0.003328692, -0.001926088,
   0.000297815, -0.000871547, 0.002271711,
   -0.000517524, 0.001475579, -0.003705661,
   0.000686386, -0.001926088, 0.004726235
 ),
 nrow = 9
)
# Specific time interval ------
DeltaIndirectCentral(
 phi = phi,
 vcov_phi_vec = vcov_phi_vec,
 delta_t = 1
)
# Range of time intervals ------
delta <- DeltaIndirectCentral(</pre>
 phi = phi,
 vcov_phi_vec = vcov_phi_vec,
 delta_t = 1:5
plot(delta)
# Methods ------
# DeltaIndirectCentral has a number of methods including
# print, summary, confint, and plot
print(delta)
summary(delta)
confint(delta, level = 0.95)
plot(delta)
```

DeltaMed

Delta Method Sampling Variance-Covariance Matrix for the Total, Direct, and Indirect Effects of X on Y Through M Over a Specific Time Interval or a Range of Time Intervals

Description

This function computes the delta method sampling variance-covariance matrix for the total, direct, and indirect effects of the independent variable X on the dependent variable Y through mediator variables \mathbf{m} over a specific time interval Δt or a range of time intervals using the first-order stochastic differential equation model's drift matrix $\mathbf{\Phi}$.

Usage

DeltaMed(phi, vcov_phi_vec, delta_t, from, to, med, ncores = NULL)

Arguments

phi Numeric matrix. The drift matrix (Φ) , phi should have row and column names

pertaining to the variables in the system.

vcov_phi_vec Numeric matrix. The sampling variance-covariance matrix of $vec(\Phi)$.

delta_t Vector of positive numbers. Time interval (Δt).

from Character string. Name of the independent variable X in phi.

to Character string. Name of the dependent variable Y in phi.

med Character vector. Name/s of the mediator variable/s in phi.

ncores Positive integer. Number of cores to use. If ncores = NULL, use a single core.

Consider using multiple cores when the length of delta_t is long.

Details

See Total(), Direct(), and Indirect() for more details.

Delta Method:

Let θ be $\operatorname{vec}(\Phi)$, that is, the elements of the Φ matrix in vector form sorted column-wise. Let $\hat{\theta}$ be $\operatorname{vec}(\hat{\Phi})$. By the multivariate central limit theory, the function \mathbf{g} using $\hat{\theta}$ as input can be expressed as:

$$\sqrt{n}\left(\mathbf{g}\left(\hat{\boldsymbol{\theta}}\right) - \mathbf{g}\left(\boldsymbol{\theta}\right)\right) \xrightarrow{\mathrm{D}} \mathcal{N}\left(0, \mathbf{J}\boldsymbol{\Gamma}\mathbf{J}'\right)$$

where **J** is the matrix of first-order derivatives of the function **g** with respect to the elements of θ and Γ is the asymptotic variance-covariance matrix of $\hat{\theta}$.

From the former, we can derive the distribution of $\mathbf{g}\left(\hat{\boldsymbol{\theta}}\right)$ as follows:

$$\mathbf{g}\left(\hat{\boldsymbol{\theta}}\right) \approx \mathcal{N}\left(\mathbf{g}\left(\boldsymbol{\theta}\right), n^{-1}\mathbf{J}\boldsymbol{\Gamma}\mathbf{J}'\right)$$

The uncertainty associated with the estimator $\mathbf{g}\left(\hat{\boldsymbol{\theta}}\right)$ is, therefore, given by $n^{-1}\mathbf{J}\Gamma\mathbf{J}'$. When Γ is unknown, by substitution, we can use the estimated sampling variance-covariance matrix of $\hat{\boldsymbol{\theta}}$, that is, $\hat{\mathbb{V}}\left(\hat{\boldsymbol{\theta}}\right)$ for $n^{-1}\Gamma$. Therefore, the sampling variance-covariance matrix of $\mathbf{g}\left(\hat{\boldsymbol{\theta}}\right)$ is given by

$$\mathbf{g}\left(\hat{oldsymbol{ heta}}
ight)pprox\mathcal{N}\left(\mathbf{g}\left(oldsymbol{ heta}
ight),\mathbf{J}\hat{\mathbb{V}}\left(\hat{oldsymbol{ heta}}
ight)\mathbf{J}'
ight).$$

Linear Stochastic Differential Equation Model:

The measurement model is given by

$$\mathbf{y}_{i,t} = oldsymbol{
u} + oldsymbol{\Lambda} oldsymbol{\eta}_{i,t} + oldsymbol{arepsilon}_{i,t}, \quad ext{with} \quad oldsymbol{arepsilon}_{i,t} \sim \mathcal{N}\left(\mathbf{0}, oldsymbol{\Theta}
ight)$$

where $\mathbf{y}_{i,t}$, $\eta_{i,t}$, and $\varepsilon_{i,t}$ are random variables and ν , Λ , and Θ are model parameters. $\mathbf{y}_{i,t}$ represents a vector of observed random variables, $\eta_{i,t}$ a vector of latent random variables, and $\varepsilon_{i,t}$ a vector of random measurement errors, at time t and individual t. ν denotes a vector of intercepts, Λ a matrix of factor loadings, and Θ the covariance matrix of ε .

An alternative representation of the measurement error is given by

$$oldsymbol{arepsilon}_{i,t} = oldsymbol{\Theta}^{rac{1}{2}} \mathbf{z}_{i,t}, \quad ext{with} \quad \mathbf{z}_{i,t} \sim \mathcal{N}\left(\mathbf{0}, \mathbf{I}\right)$$

where $\mathbf{z}_{i,t}$ is a vector of independent standard normal random variables and $\left(\Theta^{\frac{1}{2}}\right)\left(\Theta^{\frac{1}{2}}\right)' = \Theta$. The dynamic structure is given by

$$\mathrm{d}oldsymbol{\eta}_{i,t} = \left(oldsymbol{\iota} + oldsymbol{\Phi}oldsymbol{\eta}_{i,t}
ight)\mathrm{d}t + oldsymbol{\Sigma}^{rac{1}{2}}\mathrm{d}\mathbf{W}_{i,t}$$

where ι is a term which is unobserved and constant over time, Φ is the drift matrix which represents the rate of change of the solution in the absence of any random fluctuations, Σ is the matrix of volatility or randomness in the process, and $\mathrm{d}W$ is a Wiener process or Brownian motion, which represents random fluctuations.

Value

Returns an object of class ctmeddelta which is a list with the following elements:

call Function call.

args Function arguments.

fun Function used (DeltaMed).

output A list with length of length(delta_t).

Each element in the output list has the following elements:

delta t Time interval.

jacobian Jacobian matrix.

est Estimated total, direct, and indirect effects.

vcov Sampling variance-covariance matrix of the estimated total, direct, and indirect effects.

Author(s)

Ivan Jacob Agaloos Pesigan

References

Bollen, K. A. (1987). Total, direct, and indirect effects in structural equation models. Sociological Methodology, 17, 37. doi:10.2307/271028

Deboeck, P. R., & Preacher, K. J. (2015). No need to be discrete: A method for continuous time mediation analysis. Structural Equation Modeling: A Multidisciplinary Journal, 23 (1), 61–75. doi:10.1080/10705511.2014.973960

Ryan, O., & Hamaker, E. L. (2021). Time to intervene: A continuous-time approach to network analysis and centrality. Psychometrika, 87 (1), 214–252. doi:10.1007/s11336021097670

See Also

Other Continuous Time Mediation Functions: DeltaBeta(), DeltaIndirectCentral(), DeltaTotalCentral(), Direct(), Indirect(), IndirectCentral(), MCBeta(), MCIndirectCentral(), MCMed(), MCPhi(), MCTotalCentral(), Med(), PosteriorBeta(), PosteriorIndirectCentral(), PosteriorMed(), PosteriorPhi(), PosteriorTotalCentral(), TestPhi(), TestStable(), Total(), TotalCentral()

```
phi <- matrix(</pre>
 data = c(
   -0.357, 0.771, -0.450,
   0.0, -0.511, 0.729,
   0, 0, -0.693
 ),
 nrow = 3
)
colnames(phi) \leftarrow rownames(phi) \leftarrow c("x", "m", "y")
vcov_phi_vec <- matrix(</pre>
 data = c(
   0.002704274, -0.001475275, 0.000949122,
    -0.001619422, 0.000885122, -0.000569404,
   0.00085493, -0.000465824, 0.000297815,
   -0.001475275, 0.004428442, -0.002642303,
   0.000980573, -0.00271817, 0.001618805,
   -0.000586921, 0.001478421, -0.000871547,
   0.000949122, -0.002642303, 0.006402668,
    -0.000697798, 0.001813471, -0.004043138,
   0.000463086, -0.001120949, 0.002271711,
    -0.001619422, 0.000980573, -0.000697798,
   0.002079286, -0.001152501, 0.000753,
    -0.001528701, 0.000820587, -0.000517524,
   0.000885122, -0.00271817, 0.001813471,
    -0.001152501, 0.00342605, -0.002075005,
   0.000899165, -0.002532849, 0.001475579,
    -0.000569404, 0.001618805, -0.004043138,
   0.000753, -0.002075005, 0.004984032,
    -0.000622255, 0.001634917, -0.003705661,
   0.00085493, -0.000586921, 0.000463086,
    -0.001528701, 0.000899165, -0.000622255,
   0.002060076, -0.001096684, 0.000686386,
    -0.000465824, 0.001478421, -0.001120949,
   0.000820587, -0.002532849, 0.001634917,
    -0.001096684, 0.003328692, -0.001926088,
   0.000297815, -0.000871547, 0.002271711,
    -0.000517524, 0.001475579, -0.003705661,
   0.000686386, -0.001926088, 0.004726235
 ),
 nrow = 9
)
# Specific time interval -------
DeltaMed(
```

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```
phi = phi,
 vcov_phi_vec = vcov_phi_vec,
 delta_t = 1,
 from = "x",
 to = "y",
 med = "m"
# Range of time intervals -----
delta <- DeltaMed(</pre>
 phi = phi,
 vcov_phi_vec = vcov_phi_vec,
 delta_t = 1:5,
 from = "x",
 to = "y",
 med = "m"
plot(delta)
# Methods -----
# DeltaMed has a number of methods including
# print, summary, confint, and plot
print(delta)
summary(delta)
confint(delta, level = 0.95)
plot(delta)
```

DeltaTotalCentral

Delta Method Sampling Variance-Covariance Matrix for the Total Effect Centrality Over a Specific Time Interval or a Range of Time Intervals

Description

This function computes the delta method sampling variance-covariance matrix for the total effect centrality over a specific time interval Δt or a range of time intervals using the first-order stochastic differential equation model's drift matrix Φ .

Usage

```
DeltaTotalCentral(phi, vcov_phi_vec, delta_t, ncores = NULL)
```

Arguments

phi	Numeric matrix. The drift matrix (Φ) , phi should have row and column names pertaining to the variables in the system.
vcov_phi_vec	Numeric matrix. The sampling variance-covariance matrix of $\operatorname{vec}\left(\mathbf{\Phi}\right)$.
delta_t	Vector of positive numbers. Time interval (Δt).

ncores

Positive integer. Number of cores to use. If ncores = NULL, use a single core. Consider using multiple cores when the length of delta_t is long.

Details

See TotalCentral() more details.

Delta Method:

Let θ be $\text{vec}(\Phi)$, that is, the elements of the Φ matrix in vector form sorted column-wise. Let $\hat{\theta}$ be $\text{vec}(\hat{\Phi})$. By the multivariate central limit theory, the function \mathbf{g} using $\hat{\theta}$ as input can be expressed as:

$$\sqrt{n}\left(\mathbf{g}\left(\hat{\boldsymbol{\theta}}\right) - \mathbf{g}\left(\boldsymbol{\theta}\right)\right) \xrightarrow{\mathrm{D}} \mathcal{N}\left(0, \mathbf{J}\boldsymbol{\Gamma}\mathbf{J}'\right)$$

where **J** is the matrix of first-order derivatives of the function **g** with respect to the elements of θ and Γ is the asymptotic variance-covariance matrix of $\hat{\theta}$.

From the former, we can derive the distribution of $\mathbf{g}\left(\hat{\boldsymbol{\theta}}\right)$ as follows:

$$\mathbf{g}\left(\hat{\boldsymbol{\theta}}\right) \approx \mathcal{N}\left(\mathbf{g}\left(\boldsymbol{\theta}\right), n^{-1}\mathbf{J}\boldsymbol{\Gamma}\mathbf{J}'\right)$$

The uncertainty associated with the estimator $\mathbf{g}\left(\hat{\boldsymbol{\theta}}\right)$ is, therefore, given by $n^{-1}\mathbf{J}\Gamma\mathbf{J}'$. When Γ is unknown, by substitution, we can use the estimated sampling variance-covariance matrix of $\hat{\boldsymbol{\theta}}$, that is, $\hat{\mathbb{V}}\left(\hat{\boldsymbol{\theta}}\right)$ for $n^{-1}\Gamma$. Therefore, the sampling variance-covariance matrix of $\mathbf{g}\left(\hat{\boldsymbol{\theta}}\right)$ is given by

$$\mathbf{g}\left(\hat{\boldsymbol{ heta}}\right) pprox \mathcal{N}\left(\mathbf{g}\left(\boldsymbol{ heta}
ight), \mathbf{J}\hat{\mathbb{V}}\left(\hat{\boldsymbol{ heta}}\right) \mathbf{J}'\right).$$

Linear Stochastic Differential Equation Model:

The measurement model is given by

$$\mathbf{y}_{i,t} = \mathbf{\nu} + \mathbf{\Lambda} oldsymbol{\eta}_{i,t} + oldsymbol{arepsilon}_{i,t}, \quad ext{with} \quad oldsymbol{arepsilon}_{i,t} \sim \mathcal{N}\left(\mathbf{0}, oldsymbol{\Theta}
ight)$$

where $\mathbf{y}_{i,t}$, $\eta_{i,t}$, and $\varepsilon_{i,t}$ are random variables and ν , Λ , and Θ are model parameters. $\mathbf{y}_{i,t}$ represents a vector of observed random variables, $\eta_{i,t}$ a vector of latent random variables, and $\varepsilon_{i,t}$ a vector of random measurement errors, at time t and individual t. ν denotes a vector of intercepts, Λ a matrix of factor loadings, and Θ the covariance matrix of ε .

An alternative representation of the measurement error is given by

$$oldsymbol{arepsilon}_{i,t} = oldsymbol{\Theta}^{rac{1}{2}} \mathbf{z}_{i,t}, \quad ext{with} \quad \mathbf{z}_{i,t} \sim \mathcal{N}\left(\mathbf{0}, \mathbf{I}\right)$$

where $\mathbf{z}_{i,t}$ is a vector of independent standard normal random variables and $\left(\boldsymbol{\Theta}^{\frac{1}{2}}\right)\left(\boldsymbol{\Theta}^{\frac{1}{2}}\right)' = \boldsymbol{\Theta}$. The dynamic structure is given by

$$\mathrm{d}oldsymbol{\eta}_{i,t} = \left(oldsymbol{\iota} + oldsymbol{\Phi}oldsymbol{\eta}_{i,t}
ight)\mathrm{d}t + oldsymbol{\Sigma}^{rac{1}{2}}\mathrm{d}\mathbf{W}_{i,t}$$

where ι is a term which is unobserved and constant over time, Φ is the drift matrix which represents the rate of change of the solution in the absence of any random fluctuations, Σ is the matrix of volatility or randomness in the process, and $\mathrm{d}W$ is a Wiener process or Brownian motion, which represents random fluctuations.

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Value

Returns an object of class ctmeddelta which is a list with the following elements:

call Function call.

args Function arguments.

fun Function used (DeltaTotalCentral).

output A list with length of length(delta_t).

Each element in the output list has the following elements:

delta_t Time interval.

jacobian Jacobian matrix.

est Estimated total, direct, and indirect effects.

vcov Sampling variance-covariance matrix of the estimated total, direct, and indirect effects.

Author(s)

Ivan Jacob Agaloos Pesigan

References

Bollen, K. A. (1987). Total, direct, and indirect effects in structural equation models. Sociological Methodology, 17, 37. doi:10.2307/271028

Deboeck, P. R., & Preacher, K. J. (2015). No need to be discrete: A method for continuous time mediation analysis. Structural Equation Modeling: A Multidisciplinary Journal, 23 (1), 61–75. doi:10.1080/10705511.2014.973960

Ryan, O., & Hamaker, E. L. (2021). Time to intervene: A continuous-time approach to network analysis and centrality. Psychometrika, 87 (1), 214–252. doi:10.1007/s11336021097670

See Also

```
Other Continuous Time Mediation Functions: DeltaBeta(), DeltaIndirectCentral(), DeltaMed(), Direct(), Indirect(), IndirectCentral(), MCBeta(), MCIndirectCentral(), MCMed(), MCPhi(), MCTotalCentral(), Med(), PosteriorBeta(), PosteriorIndirectCentral(), PosteriorMed(), PosteriorPhi(), PosteriorTotalCentral(), TestPhi(), TestStable(), Total(), TotalCentral()
```

```
phi <- matrix(
  data = c(
    -0.357, 0.771, -0.450,
    0.0, -0.511, 0.729,
    0, 0, -0.693
  ),
  nrow = 3
)
colnames(phi) <- rownames(phi) <- c("x", "m", "y")
vcov_phi_vec <- matrix(</pre>
```

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```
data = c(
   0.002704274, -0.001475275, 0.000949122,
   -0.001619422, 0.000885122, -0.000569404,
   0.00085493, -0.000465824, 0.000297815,
   -0.001475275, 0.004428442, -0.002642303,
   0.000980573, -0.00271817, 0.001618805,
   -0.000586921, 0.001478421, -0.000871547,
   0.000949122, -0.002642303, 0.006402668,
   -0.000697798, 0.001813471, -0.004043138,
   0.000463086, -0.001120949, 0.002271711,
   -0.001619422, 0.000980573, -0.000697798,
   0.002079286, -0.001152501, 0.000753,
   -0.001528701, 0.000820587, -0.000517524,
   0.000885122, -0.00271817, 0.001813471,
   -0.001152501, 0.00342605, -0.002075005,
   0.000899165, -0.002532849, 0.001475579,
   -0.000569404, 0.001618805, -0.004043138,
   0.000753, -0.002075005, 0.004984032,
   -0.000622255, 0.001634917, -0.003705661,
   0.00085493, -0.000586921, 0.000463086,
   -0.001528701, 0.000899165, -0.000622255,
   0.002060076, -0.001096684, 0.000686386,
   -0.000465824, 0.001478421, -0.001120949,
   0.000820587, -0.002532849, 0.001634917,
   -0.001096684, 0.003328692, -0.001926088,
   0.000297815, -0.000871547, 0.002271711,
   -0.000517524, 0.001475579, -0.003705661,
   0.000686386, -0.001926088, 0.004726235
 ),
 nrow = 9
)
# Specific time interval -------
DeltaTotalCentral(
 phi = phi,
 vcov_phi_vec = vcov_phi_vec,
 delta_t = 1
)
# Range of time intervals -------
delta <- DeltaTotalCentral(</pre>
 phi = phi,
 vcov_phi_vec = vcov_phi_vec,
 delta_t = 1:5
)
plot(delta)
# Methods ------
# DeltaTotalCentral has a number of methods including
# print, summary, confint, and plot
print(delta)
summary(delta)
confint(delta, level = 0.95)
```

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plot(delta)

Direct

Direct Effect of X on Y Over a Specific Time Interval

Description

This function computes the direct effect of the independent variable X on the dependent variable Y through mediator variables \mathbf{m} over a specific time interval Δt using the first-order stochastic differential equation model's drift matrix $\mathbf{\Phi}$.

Usage

Direct(phi, delta_t, from, to, med)

Arguments

phi	Numeric matrix. The drift matrix (Φ) . phi should have row and column names pertaining to the variables in the system.
delta_t	Numeric. Time interval (Δt).
from	Character string. Name of the independent variable X in phi.
to	Character string. Name of the dependent variable Y in phi.
med	Character vector. Name/s of the mediator variable/s in phi.

Details

The direct effect of the independent variable X on the dependent variable Y relative to some mediator variables \mathbf{m} is given by

$$\operatorname{Direct}_{\Delta t_{i,j,\mathbf{m}}} = \exp\left(\Delta t \mathbf{D} \mathbf{\Phi} \mathbf{D}\right)_{i,j}$$

where Φ denotes the drift matrix, \mathbf{D} a diagonal matrix where the diagonal elements corresponding to mediator variables \mathbf{m} are set to zero and the rest to one, i the row index of Y in Φ , j the column index of X in Φ , and Δt the time interval.

Linear Stochastic Differential Equation Model:

The measurement model is given by

$$\mathbf{y}_{i,t} = \boldsymbol{\nu} + \boldsymbol{\Lambda} \boldsymbol{\eta}_{i,t} + \boldsymbol{\varepsilon}_{i,t}, \quad ext{with} \quad \boldsymbol{\varepsilon}_{i,t} \sim \mathcal{N}\left(\mathbf{0}, \boldsymbol{\Theta}\right)$$

where $\mathbf{y}_{i,t}$, $\boldsymbol{\eta}_{i,t}$, and $\boldsymbol{\varepsilon}_{i,t}$ are random variables and $\boldsymbol{\nu}$, $\boldsymbol{\Lambda}$, and $\boldsymbol{\Theta}$ are model parameters. $\mathbf{y}_{i,t}$ represents a vector of observed random variables, $\boldsymbol{\eta}_{i,t}$ a vector of latent random variables, and $\boldsymbol{\varepsilon}_{i,t}$ a vector of random measurement errors, at time t and individual i. $\boldsymbol{\nu}$ denotes a vector of intercepts, $\boldsymbol{\Lambda}$ a matrix of factor loadings, and $\boldsymbol{\Theta}$ the covariance matrix of $\boldsymbol{\varepsilon}$.

An alternative representation of the measurement error is given by

$$oldsymbol{arepsilon}_{i,t} = oldsymbol{\Theta}^{rac{1}{2}} \mathbf{z}_{i,t}, \quad ext{with} \quad \mathbf{z}_{i,t} \sim \mathcal{N}\left(\mathbf{0}, \mathbf{I}\right)$$

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where $\mathbf{z}_{i,t}$ is a vector of independent standard normal random variables and $\left(\Theta^{\frac{1}{2}}\right)\left(\Theta^{\frac{1}{2}}\right)' = \Theta$. The dynamic structure is given by

$$\mathrm{d}\boldsymbol{\eta}_{i,t} = \left(\boldsymbol{\iota} + \boldsymbol{\Phi}\boldsymbol{\eta}_{i,t}\right) \mathrm{d}t + \boldsymbol{\Sigma}^{\frac{1}{2}} \mathrm{d}\mathbf{W}_{i,t}$$

where ι is a term which is unobserved and constant over time, Φ is the drift matrix which represents the rate of change of the solution in the absence of any random fluctuations, Σ is the matrix of volatility or randomness in the process, and $\mathrm{d}W$ is a Wiener process or Brownian motion, which represents random fluctuations.

Value

Returns an object of class ctmedeffect which is a list with the following elements:

call Function call.

args Function arguments.

fun Function used ("Direct").

output The direct effect.

Author(s)

Ivan Jacob Agaloos Pesigan

References

Bollen, K. A. (1987). Total, direct, and indirect effects in structural equation models. Sociological Methodology, 17, 37. doi:10.2307/271028

Deboeck, P. R., & Preacher, K. J. (2015). No need to be discrete: A method for continuous time mediation analysis. Structural Equation Modeling: A Multidisciplinary Journal, 23 (1), 61–75. doi:10.1080/10705511.2014.973960

Ryan, O., & Hamaker, E. L. (2021). Time to intervene: A continuous-time approach to network analysis and centrality. Psychometrika, 87 (1), 214–252. doi:10.1007/s11336021097670

See Also

Other Continuous Time Mediation Functions: DeltaBeta(), DeltaIndirectCentral(), DeltaMed(), DeltaTotalCentral(), Indirect(), IndirectCentral(), MCBeta(), MCIndirectCentral(), MCMed(), MCPhi(), MCTotalCentral(), Med(), PosteriorBeta(), PosteriorIndirectCentral(), PosteriorMed(), PosteriorPhi(), PosteriorTotalCentral(), TestPhi(), TestStable(), Total(), TotalCentral()

```
phi <- matrix(
  data = c(
    -0.357, 0.771, -0.450,
    0.0, -0.511, 0.729,
    0, 0, -0.693
),</pre>
```

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```
nrow = 3
)
colnames(phi) \leftarrow rownames(phi) \leftarrow c("x", "m", "y")
delta_t <- 1
Direct(
  phi = phi,
  delta_t = delta_t,
  from = "x",
  to = "y",
  med = "m"
phi <- matrix(</pre>
  data = c(
    -6, 5.5, 0, 0,
    1.25, -2.5, 5.9, -7.3,
    0, 0, -6, 2.5,
    5, 0, 0, -6
  ),
  nrow = 4
)
colnames(phi) <- rownames(phi) <- paste0("y", 1:4)</pre>
Direct(
  phi = phi,
  delta_t = delta_t,
  from = "y2",
  to = "y4",
  med = c("y1", "y3")
)
```

Indirect

Indirect Effect of X on Y Through M Over a Specific Time Interval

Description

This function computes the indirect effect of the independent variable X on the dependent variable Y through mediator variables \mathbf{m} over a specific time interval Δt using the first-order stochastic differential equation model's drift matrix $\mathbf{\Phi}$.

Usage

```
Indirect(phi, delta_t, from, to, med)
```

Arguments

phi	Numeric matrix. The drift matrix (Φ) , phi should have row and column names pertaining to the variables in the system.
delta_t	Numeric. Time interval (Δt).
from	Character string. Name of the independent variable X in phi.

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to Character string. Name of the dependent variable *Y* in phi.

med Character vector. Name/s of the mediator variable/s in phi.

Details

The indirect effect of the independent variable X on the dependent variable Y relative to some mediator variables \mathbf{m} over a specific time interval Δt is given by

Indirect_{$$\Delta t$$} = exp $(\Delta t \mathbf{\Phi})_{i,j}$ - exp $(\Delta t \mathbf{D_m} \mathbf{\Phi} \mathbf{D_m})_{i,j}$

where Φ denotes the drift matrix, $\mathbf{D_m}$ a matrix where the off diagonal elements are zeros and the diagonal elements are zero for the index/indices of mediator variables \mathbf{m} and one otherwise, i the row index of Y in Φ , j the column index of X in Φ , and Δt the time interval.

Linear Stochastic Differential Equation Model:

The measurement model is given by

$$\mathbf{y}_{i,t} = \mathbf{\nu} + \mathbf{\Lambda} \boldsymbol{\eta}_{i,t} + \boldsymbol{arepsilon}_{i,t}, \quad ext{with} \quad \boldsymbol{arepsilon}_{i,t} \sim \mathcal{N}\left(\mathbf{0}, \mathbf{\Theta}
ight)$$

where $\mathbf{y}_{i,t}$, $\boldsymbol{\eta}_{i,t}$, and $\boldsymbol{\varepsilon}_{i,t}$ are random variables and $\boldsymbol{\nu}$, $\boldsymbol{\Lambda}$, and $\boldsymbol{\Theta}$ are model parameters. $\mathbf{y}_{i,t}$ represents a vector of observed random variables, $\boldsymbol{\eta}_{i,t}$ a vector of latent random variables, and $\boldsymbol{\varepsilon}_{i,t}$ a vector of random measurement errors, at time t and individual i. $\boldsymbol{\nu}$ denotes a vector of intercepts, $\boldsymbol{\Lambda}$ a matrix of factor loadings, and $\boldsymbol{\Theta}$ the covariance matrix of $\boldsymbol{\varepsilon}$.

An alternative representation of the measurement error is given by

$$\boldsymbol{\varepsilon}_{i,t} = \boldsymbol{\Theta}^{\frac{1}{2}} \mathbf{z}_{i,t}, \quad \text{with} \quad \mathbf{z}_{i,t} \sim \mathcal{N}\left(\mathbf{0}, \mathbf{I}\right)$$

where $\mathbf{z}_{i,t}$ is a vector of independent standard normal random variables and $\left(\Theta^{\frac{1}{2}}\right)\left(\Theta^{\frac{1}{2}}\right)' = \Theta$. The dynamic structure is given by

$$\mathrm{d} oldsymbol{\eta}_{i,t} = \left(oldsymbol{\iota} + oldsymbol{\Phi} oldsymbol{\eta}_{i,t}
ight) \mathrm{d} t + oldsymbol{\Sigma}^{rac{1}{2}} \mathrm{d} \mathbf{W}_{i,t}$$

where ι is a term which is unobserved and constant over time, Φ is the drift matrix which represents the rate of change of the solution in the absence of any random fluctuations, Σ is the matrix of volatility or randomness in the process, and $\mathrm{d}W$ is a Wiener process or Brownian motion, which represents random fluctuations.

Value

Returns an object of class ctmedeffect which is a list with the following elements:

call Function call.

args Function arguments.

fun Function used ("Indirect").

output The indirect effect.

Author(s)

Ivan Jacob Agaloos Pesigan

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References

Bollen, K. A. (1987). Total, direct, and indirect effects in structural equation models. Sociological Methodology, 17, 37. doi:10.2307/271028

Deboeck, P. R., & Preacher, K. J. (2015). No need to be discrete: A method for continuous time mediation analysis. Structural Equation Modeling: A Multidisciplinary Journal, 23 (1), 61–75. doi:10.1080/10705511.2014.973960

Ryan, O., & Hamaker, E. L. (2021). Time to intervene: A continuous-time approach to network analysis and centrality. Psychometrika, 87 (1), 214–252. doi:10.1007/s11336021097670

See Also

Other Continuous Time Mediation Functions: DeltaBeta(), DeltaIndirectCentral(), DeltaMed(), DeltaTotalCentral(), Direct(), IndirectCentral(), MCBeta(), MCIndirectCentral(), MCMed(), MCPhi(), MCTotalCentral(), Med(), PosteriorBeta(), PosteriorIndirectCentral(), PosteriorMed(), PosteriorPhi(), PosteriorTotalCentral(), TestPhi(), TestStable(), Total(), TotalCentral()

```
phi <- matrix(</pre>
  data = c(
    -0.357, 0.771, -0.450,
    0.0, -0.511, 0.729,
    0, 0, -0.693
  ),
  nrow = 3
)
colnames(phi) <- rownames(phi) <- c("x", "m", "y")</pre>
delta_t <- 1
Indirect(
  phi = phi,
  delta_t = delta_t,
  from = "x",
  to = "y",
  med = "m"
)
phi <- matrix(</pre>
  data = c(
    -6, 5.5, 0, 0,
    1.25, -2.5, 5.9, -7.3,
    0, 0, -6, 2.5,
    5, 0, 0, -6
  ),
  nrow = 4
colnames(phi) <- rownames(phi) <- paste0("y", 1:4)</pre>
Indirect(
  phi = phi,
  delta_t = delta_t,
  from = "y2",
  to = "y4",
```

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```
med = c("y1", "y3")
```

IndirectCentral

Indirect Effect Centrality

Description

Indirect Effect Centrality

Usage

```
IndirectCentral(phi, delta_t)
```

Arguments

phi Numeric matrix. The drift matrix (Φ) , phi should have row and column names

pertaining to the variables in the system.

delta_t Vector of positive numbers. Time interval (Δt).

Author(s)

Ivan Jacob Agaloos Pesigan

See Also

```
Other Continuous Time Mediation Functions: DeltaBeta(), DeltaIndirectCentral(), DeltaMed(), DeltaTotalCentral(), Direct(), Indirect(), MCBeta(), MCIndirectCentral(), MCMed(), MCPhi(), MCTotalCentral(), Med(), PosteriorBeta(), PosteriorIndirectCentral(), PosteriorMed(), PosteriorPhi(), PosteriorTotalCentral(), TestPhi(), TestStable(), Total(), TotalCentral()
```

MCBeta

Monte Carlo Sampling Distribution for the Elements of the Matrix of Lagged Coefficients Over a Specific Time Interval or a Range of Time Intervals

Description

This function generates a Monte Carlo method sampling distribution for the elements of the matrix of lagged coefficients β over a specific time interval Δt or a range of time intervals using the first-order stochastic differential equation model drift matrix Φ .

Usage

```
MCBeta(
   phi,
   vcov_phi_vec,
   delta_t,
   R,
   test_phi = TRUE,
   ncores = NULL,
   seed = NULL
)
```

Arguments

phi Numeric matrix. The drift matrix (Φ) , phi should have row and column names

pertaining to the variables in the system.

vcov_phi_vec Numeric matrix. The sampling variance-covariance matrix of $vec(\Phi)$.

delta_t Numeric. Time interval (Δt).

R Positive integer. Number of replications.

test_phi Logical. If test_phi = TRUE, the function runs TestPhi() on the generated drift matrix Φ . If the TestPhi() returns FALSE, the function generates a new drift matrix Φ and runs the test recursively until TestPhi() returns TRUE.

ncores Positive integer. Number of cores to use. If ncores = NULL, use a single core. Consider using multiple cores when number of replications R is a large value.

seed Random seed.

Details

See Total().

Monte Carlo Method:

Let θ be $\operatorname{vec}(\Phi)$, that is, the elements of the Φ matrix in vector form sorted column-wise. Let $\hat{\theta}$ be $\operatorname{vec}(\hat{\Phi})$. Based on the asymptotic properties of maximum likelihood estimators, we can assume that estimators are normally distributed around the population parameters.

$$\hat{oldsymbol{ heta}} \sim \mathcal{N}\left(oldsymbol{ heta}, \mathbb{V}\left(\hat{oldsymbol{ heta}}
ight)
ight)$$

Using this distributional assumption, a sampling distribution of $\hat{\theta}$ which we refer to as $\hat{\theta}^*$ can be generated by replacing the population parameters with sample estimates, that is,

$$\hat{oldsymbol{ heta}}^* \sim \mathcal{N}\left(\hat{oldsymbol{ heta}}, \hat{\mathbb{V}}\left(\hat{oldsymbol{ heta}}
ight)
ight).$$

Let $\mathbf{g}\left(\hat{\boldsymbol{\theta}}\right)$ be a parameter that is a function of the estimated parameters. A sampling distribution of $\mathbf{g}\left(\hat{\boldsymbol{\theta}}\right)$, which we refer to as $\mathbf{g}\left(\hat{\boldsymbol{\theta}}^*\right)$, can be generated by using the simulated estimates to calculate \mathbf{g} . The standard deviations of the simulated estimates are the standard errors. Percentiles corresponding to $100 \left(1-\alpha\right)\%$ are the confidence intervals.

Linear Stochastic Differential Equation Model:

The measurement model is given by

$$\mathbf{y}_{i,t} = \boldsymbol{\nu} + \boldsymbol{\Lambda} \boldsymbol{\eta}_{i,t} + \boldsymbol{arepsilon}_{i,t}, \quad ext{with} \quad \boldsymbol{arepsilon}_{i,t} \sim \mathcal{N}\left(\mathbf{0}, oldsymbol{\Theta}
ight)$$

where $\mathbf{y}_{i,t}$, $\boldsymbol{\eta}_{i,t}$, and $\boldsymbol{\varepsilon}_{i,t}$ are random variables and $\boldsymbol{\nu}$, $\boldsymbol{\Lambda}$, and $\boldsymbol{\Theta}$ are model parameters. $\mathbf{y}_{i,t}$ represents a vector of observed random variables, $\boldsymbol{\eta}_{i,t}$ a vector of latent random variables, and $\boldsymbol{\varepsilon}_{i,t}$ a vector of random measurement errors, at time t and individual i. $\boldsymbol{\nu}$ denotes a vector of intercepts, $\boldsymbol{\Lambda}$ a matrix of factor loadings, and $\boldsymbol{\Theta}$ the covariance matrix of $\boldsymbol{\varepsilon}$.

An alternative representation of the measurement error is given by

$$\boldsymbol{\varepsilon}_{i,t} = \boldsymbol{\Theta}^{\frac{1}{2}} \mathbf{z}_{i,t}, \quad \text{with} \quad \mathbf{z}_{i,t} \sim \mathcal{N}\left(\mathbf{0}, \mathbf{I}\right)$$

where $\mathbf{z}_{i,t}$ is a vector of independent standard normal random variables and $\left(\Theta^{\frac{1}{2}}\right)\left(\Theta^{\frac{1}{2}}\right)' = \Theta$. The dynamic structure is given by

$$\mathrm{d}oldsymbol{\eta}_{i,t} = \left(oldsymbol{\iota} + oldsymbol{\Phi}oldsymbol{\eta}_{i,t}
ight)\mathrm{d}t + oldsymbol{\Sigma}^{rac{1}{2}}\mathrm{d}\mathbf{W}_{i,t}$$

where ι is a term which is unobserved and constant over time, Φ is the drift matrix which represents the rate of change of the solution in the absence of any random fluctuations, Σ is the matrix of volatility or randomness in the process, and $\mathrm{d}W$ is a Wiener process or Brownian motion, which represents random fluctuations.

Value

Returns an object of class ctmedmc which is a list with the following elements:

```
call Function call.
```

args Function arguments.

fun Function used (MCBeta).

output A list with length of length(delta_t).

Each element in the output list has the following elements:

est A vector of total, direct, and indirect effects.

thetahatstar A matrix of Monte Carlo total, direct, and indirect effects.

Author(s)

Ivan Jacob Agaloos Pesigan

References

Bollen, K. A. (1987). Total, direct, and indirect effects in structural equation models. Sociological Methodology, 17, 37. doi:10.2307/271028

Deboeck, P. R., & Preacher, K. J. (2015). No need to be discrete: A method for continuous time mediation analysis. Structural Equation Modeling: A Multidisciplinary Journal, 23 (1), 61–75. doi:10.1080/10705511.2014.973960

Ryan, O., & Hamaker, E. L. (2021). Time to intervene: A continuous-time approach to network analysis and centrality. Psychometrika, 87 (1), 214–252. doi:10.1007/s11336021097670

See Also

Other Continuous Time Mediation Functions: DeltaBeta(), DeltaIndirectCentral(), DeltaMed(), DeltaTotalCentral(), Direct(), Indirect(), IndirectCentral(), McIndirectCentral(), McMed(), McPhi(), McTotalCentral(), Med(), PosteriorBeta(), PosteriorIndirectCentral(), PosteriorMed(), PosteriorPhi(), PosteriorTotalCentral(), TestPhi(), TestStable(), Total(), TotalCentral()

```
set.seed(42)
phi <- matrix(
  data = c(
    -0.357, 0.771, -0.450,
    0.0, -0.511, 0.729,
    0, 0, -0.693</pre>
```

```
),
 nrow = 3
)
colnames(phi) <- rownames(phi) <- c("x", "m", "y")</pre>
vcov_phi_vec <- matrix(</pre>
 data = c(
   0.002704274, -0.001475275, 0.000949122,
   -0.001619422, 0.000885122, -0.000569404,
   0.00085493, -0.000465824, 0.000297815,
   -0.001475275, 0.004428442, -0.002642303,
   0.000980573, -0.00271817, 0.001618805,
   -0.000586921, 0.001478421, -0.000871547,
   0.000949122, -0.002642303, 0.006402668,
   -0.000697798, 0.001813471, -0.004043138,
   0.000463086, -0.001120949, 0.002271711,
   -0.001619422, 0.000980573, -0.000697798,
   0.002079286, -0.001152501, 0.000753,
   -0.001528701, 0.000820587, -0.000517524,
   0.000885122, -0.00271817, 0.001813471,
   -0.001152501, 0.00342605, -0.002075005,
   0.000899165, -0.002532849, 0.001475579,
   -0.000569404, 0.001618805, -0.004043138,
   0.000753, -0.002075005, 0.004984032,
   -0.000622255, 0.001634917, -0.003705661,
   0.00085493, -0.000586921, 0.000463086,
   -0.001528701, 0.000899165, -0.000622255,
   0.002060076, -0.001096684, 0.000686386,
   -0.000465824, 0.001478421, -0.001120949,
   0.000820587, -0.002532849, 0.001634917,
   -0.001096684, 0.003328692, -0.001926088,
   0.000297815, -0.000871547, 0.002271711,
   -0.000517524, 0.001475579, -0.003705661,
   0.000686386, -0.001926088, 0.004726235
 ),
 nrow = 9
)
MCBeta(
 phi = phi,
 vcov_phi_vec = vcov_phi_vec,
 delta_t = 1,
 R = 100L \; \# \; use \; a \; large \; value \; for \; R \; in \; actual \; research
)
# Range of time intervals ------
mc <- MCBeta(</pre>
 phi = phi,
 vcov_phi_vec = vcov_phi_vec,
 delta_t = 1:5,
 R = 100L # use a large value for R in actual research
plot(mc)
```

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```
# Methods -----
# MCBeta has a number of methods including
# print, summary, confint, and plot
print(mc)
summary(mc)
confint(mc, level = 0.95)
plot(mc)
```

MCIndirectCentral

Monte Carlo Sampling Distribution of Indirect Effect Centrality Over a Specific Time Interval or a Range of Time Intervals

Description

This function generates a Monte Carlo method sampling distribution of the indirect effect centrality at a particular time interval Δt using the first-order stochastic differential equation model drift matrix Φ .

Usage

```
MCIndirectCentral(
  phi,
  vcov_phi_vec,
  delta_t,
  R,
  test_phi = TRUE,
  ncores = NULL,
  seed = NULL
)
```

Arguments

pl	11	Numeric matrix. The drift matrix (Φ) , phi should have row and column names pertaining to the variables in the system.
V	cov_phi_vec	Numeric matrix. The sampling variance-covariance matrix of $\operatorname{vec}\left(\Phi\right)$.
de	elta_t	Numeric. Time interval (Δt) .
R		Positive integer. Number of replications.
te	est_phi	Logical. If $test_phi = TRUE$, the function runs $TestPhi()$ on the generated drift matrix Φ . If the $TestPhi()$ returns FALSE, the function generates a new drift matrix Φ and runs the test recursively until $TestPhi()$ returns TRUE.
n	cores	Positive integer. Number of cores to use. If ncores = NULL, use a single core. Consider using multiple cores when number of replications R is a large value.
S	eed	Random seed.

Details

See IndirectCentral() for more details.

Monte Carlo Method:

Let θ be $\operatorname{vec}(\Phi)$, that is, the elements of the Φ matrix in vector form sorted column-wise. Let $\hat{\theta}$ be $\operatorname{vec}(\hat{\Phi})$. Based on the asymptotic properties of maximum likelihood estimators, we can assume that estimators are normally distributed around the population parameters.

$$\hat{oldsymbol{ heta}} \sim \mathcal{N}\left(oldsymbol{ heta}, \mathbb{V}\left(\hat{oldsymbol{ heta}}
ight)
ight)$$

Using this distributional assumption, a sampling distribution of $\hat{\theta}$ which we refer to as $\hat{\theta}^*$ can be generated by replacing the population parameters with sample estimates, that is,

$$\hat{oldsymbol{ heta}}^* \sim \mathcal{N}\left(\hat{oldsymbol{ heta}}, \hat{\mathbb{V}}\left(\hat{oldsymbol{ heta}}
ight)
ight).$$

Let $\mathbf{g}\left(\hat{\boldsymbol{\theta}}\right)$ be a parameter that is a function of the estimated parameters. A sampling distribution of $\mathbf{g}\left(\hat{\boldsymbol{\theta}}\right)$, which we refer to as $\mathbf{g}\left(\hat{\boldsymbol{\theta}}^*\right)$, can be generated by using the simulated estimates to calculate \mathbf{g} . The standard deviations of the simulated estimates are the standard errors. Percentiles corresponding to $100\left(1-\alpha\right)\%$ are the confidence intervals.

Linear Stochastic Differential Equation Model:

The measurement model is given by

$$\mathbf{y}_{i,t} = oldsymbol{
u} + oldsymbol{\Lambda} oldsymbol{\eta}_{i,t} + oldsymbol{arepsilon}_{i,t}, \quad ext{with} \quad oldsymbol{arepsilon}_{i,t} \sim \mathcal{N}\left(\mathbf{0}, oldsymbol{\Theta}
ight)$$

where $\mathbf{y}_{i,t}$, $\eta_{i,t}$, and $\varepsilon_{i,t}$ are random variables and $\boldsymbol{\nu}$, $\boldsymbol{\Lambda}$, and $\boldsymbol{\Theta}$ are model parameters. $\mathbf{y}_{i,t}$ represents a vector of observed random variables, $\eta_{i,t}$ a vector of latent random variables, and $\varepsilon_{i,t}$ a vector of random measurement errors, at time t and individual i. $\boldsymbol{\nu}$ denotes a vector of intercepts, $\boldsymbol{\Lambda}$ a matrix of factor loadings, and $\boldsymbol{\Theta}$ the covariance matrix of ε .

An alternative representation of the measurement error is given by

$$oldsymbol{arepsilon}_{i,t} = oldsymbol{\Theta}^{rac{1}{2}} \mathbf{z}_{i,t}, \quad ext{with} \quad \mathbf{z}_{i,t} \sim \mathcal{N}\left(\mathbf{0}, \mathbf{I}\right)$$

where $\mathbf{z}_{i,t}$ is a vector of independent standard normal random variables and $\left(\Theta^{\frac{1}{2}}\right)\left(\Theta^{\frac{1}{2}}\right)' = \Theta$. The dynamic structure is given by

$$\mathrm{d}\boldsymbol{\eta}_{i,t} = \left(\boldsymbol{\iota} + \boldsymbol{\Phi}\boldsymbol{\eta}_{i,t}\right) \mathrm{d}t + \boldsymbol{\Sigma}^{\frac{1}{2}} \mathrm{d}\mathbf{W}_{i,t}$$

where ι is a term which is unobserved and constant over time, Φ is the drift matrix which represents the rate of change of the solution in the absence of any random fluctuations, Σ is the matrix of volatility or randomness in the process, and $\mathrm{d}W$ is a Wiener process or Brownian motion, which represents random fluctuations.

Value

Returns an object of class ctmedmc which is a list with the following elements:

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```
call Function call.
```

args Function arguments.

fun Function used (MCIndirectCentral).

output A list with length of length(delta_t).

Each element in the output list has the following elements:

est A vector of total, direct, and indirect effects.

thetahatstar A matrix of Monte Carlo total, direct, and indirect effects.

Author(s)

Ivan Jacob Agaloos Pesigan

References

Bollen, K. A. (1987). Total, direct, and indirect effects in structural equation models. Sociological Methodology, 17, 37. doi:10.2307/271028

Deboeck, P. R., & Preacher, K. J. (2015). No need to be discrete: A method for continuous time mediation analysis. Structural Equation Modeling: A Multidisciplinary Journal, 23 (1), 61–75. doi:10.1080/10705511.2014.973960

Ryan, O., & Hamaker, E. L. (2021). Time to intervene: A continuous-time approach to network analysis and centrality. Psychometrika, 87 (1), 214–252. doi:10.1007/s11336021097670

See Also

```
Other Continuous Time Mediation Functions: DeltaBeta(), DeltaIndirectCentral(), DeltaMed(), DeltaTotalCentral(), Direct(), Indirect(), IndirectCentral(), MCBeta(), MCMed(), MCPhi(), MCTotalCentral(), Med(), PosteriorBeta(), PosteriorIndirectCentral(), PosteriorMed(), PosteriorPhi(), PosteriorTotalCentral(), TestPhi(), TestStable(), Total(), TotalCentral()
```

```
set.seed(42)
phi <- matrix(</pre>
 data = c(
    -0.357, 0.771, -0.450,
   0.0, -0.511, 0.729,
   0, 0, -0.693
 ),
 nrow = 3
colnames(phi) <- rownames(phi) <- c("x", "m", "y")</pre>
vcov_phi_vec <- matrix(</pre>
 data = c(
    0.002704274, -0.001475275, 0.000949122,
    -0.001619422, 0.000885122, -0.000569404,
    0.00085493, -0.000465824, 0.000297815,
    -0.001475275, 0.004428442, -0.002642303,
    0.000980573, -0.00271817, 0.001618805,
```

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```
-0.000586921, 0.001478421, -0.000871547,
   0.000949122, -0.002642303, 0.006402668,
   -0.000697798, 0.001813471, -0.004043138,
   0.000463086, -0.001120949, 0.002271711,
   -0.001619422, 0.000980573, -0.000697798,
   0.002079286, -0.001152501, 0.000753,
   -0.001528701, 0.000820587, -0.000517524,
   0.000885122, -0.00271817, 0.001813471,
   -0.001152501, 0.00342605, -0.002075005,
   0.000899165, -0.002532849, 0.001475579,
   -0.000569404, 0.001618805, -0.004043138,
   0.000753, -0.002075005, 0.004984032,
   -0.000622255, 0.001634917, -0.003705661,
   0.00085493, -0.000586921, 0.000463086,
   -0.001528701, 0.000899165, -0.000622255,
   0.002060076, -0.001096684, 0.000686386,
   -0.000465824, 0.001478421, -0.001120949,
   0.000820587, -0.002532849, 0.001634917,
   -0.001096684, 0.003328692, -0.001926088,
   0.000297815, -0.000871547, 0.002271711,
   -0.000517524, 0.001475579, -0.003705661,
   0.000686386, -0.001926088, 0.004726235
 ),
 nrow = 9
)
# Specific time interval -------
MCIndirectCentral(
 phi = phi,
 vcov_phi_vec = vcov_phi_vec,
 delta_t = 1,
 R = 100L # use a large value for R in actual research
# Range of time intervals ------
mc <- MCIndirectCentral(</pre>
 phi = phi,
 vcov_phi_vec = vcov_phi_vec,
 delta_t = 1:5,
 R = 100L # use a large value for R in actual research
plot(mc)
# Methods ------
# MCIndirectCentral has a number of methods including
# print, summary, confint, and plot
print(mc)
summary(mc)
confint(mc, level = 0.95)
plot(mc)
```

MCMed 35

fects of X on Y Through M Over a Specific Time Interval or a Range of Time Intervals
Time Intervals

Description

This function generates a Monte Carlo method sampling distribution of the total, direct and indirect effects of the independent variable X on the dependent variable Y through mediator variables \mathbf{m} over a specific time interval Δt or a range of time intervals using the first-order stochastic differential equation model drift matrix $\mathbf{\Phi}$.

Usage

```
MCMed(
   phi,
   vcov_phi_vec,
   delta_t,
   from,
   to,
   med,
   R,
   test_phi = TRUE,
   ncores = NULL,
   seed = NULL
)
```

Arguments

phi	Numeric matrix. The drift matrix (Φ) , phi should have row and column names pertaining to the variables in the system.
vcov_phi_vec	Numeric matrix. The sampling variance-covariance matrix of $\operatorname{vec}\left(\Phi\right)$.
delta_t	Numeric. Time interval (Δt).
from	Character string. Name of the independent variable X in phi.
to	Character string. Name of the dependent variable Y in phi.
med	Character vector. Name/s of the mediator variable/s in phi.
R	Positive integer. Number of replications.
test_phi	Logical. If test_phi = TRUE, the function runs TestPhi() on the generated drift matrix Φ . If the TestPhi() returns FALSE, the function generates a new drift matrix Φ and runs the test recursively until TestPhi() returns TRUE.
ncores	Positive integer. Number of cores to use. If ncores = NULL, use a single core. Consider using multiple cores when number of replications R is a large value.
seed	Random seed.

Details

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See Total(), Direct(), and Indirect() for more details.

Monte Carlo Method:

Let θ be $\operatorname{vec}(\Phi)$, that is, the elements of the Φ matrix in vector form sorted column-wise. Let $\hat{\theta}$ be $\operatorname{vec}(\hat{\Phi})$. Based on the asymptotic properties of maximum likelihood estimators, we can assume that estimators are normally distributed around the population parameters.

MCMed

$$\hat{oldsymbol{ heta}} \sim \mathcal{N}\left(oldsymbol{ heta}, \mathbb{V}\left(\hat{oldsymbol{ heta}}
ight)
ight)$$

Using this distributional assumption, a sampling distribution of $\hat{\theta}$ which we refer to as $\hat{\theta}^*$ can be generated by replacing the population parameters with sample estimates, that is,

$$\hat{oldsymbol{ heta}}^* \sim \mathcal{N}\left(\hat{oldsymbol{ heta}}, \hat{\mathbb{V}}\left(\hat{oldsymbol{ heta}}
ight)
ight).$$

Let $\mathbf{g}\left(\hat{\boldsymbol{\theta}}\right)$ be a parameter that is a function of the estimated parameters. A sampling distribution of $\mathbf{g}\left(\hat{\boldsymbol{\theta}}\right)$, which we refer to as $\mathbf{g}\left(\hat{\boldsymbol{\theta}}^*\right)$, can be generated by using the simulated estimates to calculate \mathbf{g} . The standard deviations of the simulated estimates are the standard errors. Percentiles corresponding to $100\left(1-\alpha\right)\%$ are the confidence intervals.

Linear Stochastic Differential Equation Model:

The measurement model is given by

$$\mathbf{y}_{i,t} = oldsymbol{
u} + oldsymbol{\Lambda} oldsymbol{\eta}_{i,t} + oldsymbol{arepsilon}_{i,t}, \quad ext{with} \quad oldsymbol{arepsilon}_{i,t} \sim \mathcal{N}\left(\mathbf{0}, oldsymbol{\Theta}
ight)$$

where $\mathbf{y}_{i,t}$, $\eta_{i,t}$, and $\varepsilon_{i,t}$ are random variables and $\boldsymbol{\nu}$, $\boldsymbol{\Lambda}$, and $\boldsymbol{\Theta}$ are model parameters. $\mathbf{y}_{i,t}$ represents a vector of observed random variables, $\eta_{i,t}$ a vector of latent random variables, and $\varepsilon_{i,t}$ a vector of random measurement errors, at time t and individual i. $\boldsymbol{\nu}$ denotes a vector of intercepts, $\boldsymbol{\Lambda}$ a matrix of factor loadings, and $\boldsymbol{\Theta}$ the covariance matrix of ε .

An alternative representation of the measurement error is given by

$$oldsymbol{arepsilon}_{i,t} = oldsymbol{\Theta}^{rac{1}{2}} \mathbf{z}_{i,t}, \quad ext{with} \quad \mathbf{z}_{i,t} \sim \mathcal{N}\left(\mathbf{0}, \mathbf{I}\right)$$

where $\mathbf{z}_{i,t}$ is a vector of independent standard normal random variables and $\left(\Theta^{\frac{1}{2}}\right)\left(\Theta^{\frac{1}{2}}\right)' = \Theta$. The dynamic structure is given by

$$\mathrm{d} \boldsymbol{\eta}_{i,t} = \left(\boldsymbol{\iota} + \boldsymbol{\Phi} \boldsymbol{\eta}_{i,t} \right) \mathrm{d} t + \boldsymbol{\Sigma}^{\frac{1}{2}} \mathrm{d} \mathbf{W}_{i,t}$$

where ι is a term which is unobserved and constant over time, Φ is the drift matrix which represents the rate of change of the solution in the absence of any random fluctuations, Σ is the matrix of volatility or randomness in the process, and $\mathrm{d}W$ is a Wiener process or Brownian motion, which represents random fluctuations.

Value

Returns an object of class ctmedmc which is a list with the following elements:

MCMed 37

```
call Function call.
```

args Function arguments.

fun Function used (MCMed).

output A list with length of length(delta_t).

Each element in the output list has the following elements:

est A vector of total, direct, and indirect effects.

thetahatstar A matrix of Monte Carlo total, direct, and indirect effects.

Author(s)

Ivan Jacob Agaloos Pesigan

References

Bollen, K. A. (1987). Total, direct, and indirect effects in structural equation models. Sociological Methodology, 17, 37. doi:10.2307/271028

Deboeck, P. R., & Preacher, K. J. (2015). No need to be discrete: A method for continuous time mediation analysis. Structural Equation Modeling: A Multidisciplinary Journal, 23 (1), 61–75. doi:10.1080/10705511.2014.973960

Ryan, O., & Hamaker, E. L. (2021). Time to intervene: A continuous-time approach to network analysis and centrality. Psychometrika, 87 (1), 214–252. doi:10.1007/s11336021097670

See Also

```
Other Continuous Time Mediation Functions: DeltaBeta(), DeltaIndirectCentral(), DeltaMed(), DeltaTotalCentral(), Direct(), Indirect(), IndirectCentral(), MCBeta(), MCIndirectCentral(), MCPhi(), MCTotalCentral(), Med(), PosteriorBeta(), PosteriorIndirectCentral(), PosteriorMed(), PosteriorPhi(), PosteriorTotalCentral(), TestPhi(), TestStable(), Total(), TotalCentral()
```

```
set.seed(42)
phi <- matrix(</pre>
 data = c(
    -0.357, 0.771, -0.450,
   0.0, -0.511, 0.729,
   0, 0, -0.693
 ),
 nrow = 3
colnames(phi) <- rownames(phi) <- c("x", "m", "y")</pre>
vcov_phi_vec <- matrix(</pre>
 data = c(
    0.002704274, -0.001475275, 0.000949122,
    -0.001619422, 0.000885122, -0.000569404,
    0.00085493, -0.000465824, 0.000297815,
    -0.001475275, 0.004428442, -0.002642303,
    0.000980573, -0.00271817, 0.001618805,
```

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```
-0.000586921, 0.001478421, -0.000871547,
   0.000949122, -0.002642303, 0.006402668,
   -0.000697798, 0.001813471, -0.004043138,
   0.000463086, -0.001120949, 0.002271711,
   -0.001619422, 0.000980573, -0.000697798,
   0.002079286, -0.001152501, 0.000753,
   -0.001528701, 0.000820587, -0.000517524,
   0.000885122, -0.00271817, 0.001813471,
   -0.001152501, 0.00342605, -0.002075005,
   0.000899165, -0.002532849, 0.001475579,
   -0.000569404, 0.001618805, -0.004043138,
   0.000753, -0.002075005, 0.004984032,
   -0.000622255, 0.001634917, -0.003705661,
   0.00085493, -0.000586921, 0.000463086,
   -0.001528701, 0.000899165, -0.000622255,
   0.002060076, -0.001096684, 0.000686386,
   -0.000465824, 0.001478421, -0.001120949,
   0.000820587, -0.002532849, 0.001634917,
   -0.001096684, 0.003328692, -0.001926088,
   0.000297815, -0.000871547, 0.002271711,
   -0.000517524, 0.001475579, -0.003705661,
   0.000686386, -0.001926088, 0.004726235
 ),
 nrow = 9
)
# Specific time interval -------
MCMed(
 phi = phi,
 vcov_phi_vec = vcov_phi_vec,
 delta_t = 1,
 from = "x",
 to = "y",
 med = "m",
 R = 100L # use a large value for R in actual research
)
# Range of time intervals ------
mc <- MCMed(</pre>
 phi = phi,
 vcov_phi_vec = vcov_phi_vec,
 delta_t = 1:5,
 from = "x",
 to = "y",
 med = "m",
 R = 100L # use a large value for R in actual research
)
plot(mc)
# Methods ------
# MCMed has a number of methods including
# print, summary, confint, and plot
print(mc)
```

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```
summary(mc)
confint(mc, level = 0.95)
```

MCPhi

Generate Random Drift Matrices Using the Monte Carlo Method

Description

This function generates random drift matrices Φ using the Monte Carlo method.

Usage

```
MCPhi(phi, vcov_phi_vec, R, test_phi = TRUE, ncores = NULL, seed = NULL)
```

Arguments

phi	Numeric matrix. The drift matrix (Φ) , phi should have row and column names pertaining to the variables in the system.
vcov_phi_vec	Numeric matrix. The sampling variance-covariance matrix of $\operatorname{vec}\left(\mathbf{\Phi}\right)$.
R	Positive integer. Number of replications.
test_phi	Logical. If test_phi = TRUE, the function runs TestPhi() on the generated drift matrix Φ . If the TestPhi() returns FALSE, the function generates a new drift matrix Φ and runs the test recursively until TestPhi() returns TRUE.
ncores	Positive integer. Number of cores to use. If ncores = NULL, use a single core. Consider using multiple cores when number of replications R is a large value.
seed	Random seed.

Details

Monte Carlo Method:

Let θ be $\operatorname{vec}(\Phi)$, that is, the elements of the Φ matrix in vector form sorted column-wise. Let $\hat{\theta}$ be $\operatorname{vec}(\hat{\Phi})$. Based on the asymptotic properties of maximum likelihood estimators, we can assume that estimators are normally distributed around the population parameters.

$$\hat{oldsymbol{ heta}} \sim \mathcal{N}\left(oldsymbol{ heta}, \mathbb{V}\left(\hat{oldsymbol{ heta}}
ight)
ight)$$

Using this distributional assumption, a sampling distribution of $\hat{\theta}$ which we refer to as $\hat{\theta}^*$ can be generated by replacing the population parameters with sample estimates, that is,

$$\hat{oldsymbol{ heta}}^* \sim \mathcal{N}\left(\hat{oldsymbol{ heta}}, \hat{\mathbb{V}}\left(\hat{oldsymbol{ heta}}
ight)
ight).$$

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Linear Stochastic Differential Equation Model:

The measurement model is given by

$$\mathbf{y}_{i,t} = \mathbf{\nu} + \mathbf{\Lambda} \boldsymbol{\eta}_{i,t} + \boldsymbol{\varepsilon}_{i,t}, \quad ext{with} \quad \boldsymbol{\varepsilon}_{i,t} \sim \mathcal{N}\left(\mathbf{0}, \mathbf{\Theta}\right)$$

where $\mathbf{y}_{i,t}$, $\boldsymbol{\eta}_{i,t}$, and $\boldsymbol{\varepsilon}_{i,t}$ are random variables and $\boldsymbol{\nu}$, $\boldsymbol{\Lambda}$, and $\boldsymbol{\Theta}$ are model parameters. $\mathbf{y}_{i,t}$ represents a vector of observed random variables, $\boldsymbol{\eta}_{i,t}$ a vector of latent random variables, and $\boldsymbol{\varepsilon}_{i,t}$ a vector of random measurement errors, at time t and individual i. $\boldsymbol{\nu}$ denotes a vector of intercepts, $\boldsymbol{\Lambda}$ a matrix of factor loadings, and $\boldsymbol{\Theta}$ the covariance matrix of $\boldsymbol{\varepsilon}$.

An alternative representation of the measurement error is given by

$$oldsymbol{arepsilon}_{i,t} = oldsymbol{\Theta}^{rac{1}{2}} \mathbf{z}_{i,t}, \quad ext{with} \quad \mathbf{z}_{i,t} \sim \mathcal{N}\left(\mathbf{0}, \mathbf{I}\right)$$

where $\mathbf{z}_{i,t}$ is a vector of independent standard normal random variables and $\left(\boldsymbol{\Theta}^{\frac{1}{2}}\right)' = \boldsymbol{\Theta}$. The dynamic structure is given by

$$\mathrm{d}\boldsymbol{\eta}_{i,t} = \left(\boldsymbol{\iota} + \boldsymbol{\Phi}\boldsymbol{\eta}_{i,t}\right) \mathrm{d}t + \boldsymbol{\Sigma}^{\frac{1}{2}} \mathrm{d}\mathbf{W}_{i,t}$$

where ι is a term which is unobserved and constant over time, Φ is the drift matrix which represents the rate of change of the solution in the absence of any random fluctuations, Σ is the matrix of volatility or randomness in the process, and $\mathrm{d}W$ is a Wiener process or Brownian motion, which represents random fluctuations.

Value

Returns a list of simulated drift matrices.

Author(s)

Ivan Jacob Agaloos Pesigan

See Also

Other Continuous Time Mediation Functions: DeltaBeta(), DeltaIndirectCentral(), DeltaMed(), DeltaTotalCentral(), Direct(), Indirect(), IndirectCentral(), MCBeta(), MCIndirectCentral(), MCMed(), MCTotalCentral(), Med(), PosteriorBeta(), PosteriorIndirectCentral(), PosteriorMed(), PosteriorPhi(), PosteriorTotalCentral(), TestPhi(), TestStable(), Total(), TotalCentral()

```
set.seed(42)
phi <- matrix(
   data = c(
     -0.357, 0.771, -0.450,
     0.0, -0.511, 0.729,
     0, 0, -0.693
   ),
   nrow = 3
)
colnames(phi) <- rownames(phi) <- c("x", "m", "y")</pre>
```

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```
MCPhi(
  phi = phi,
  vcov_phi_vec = 0.1 * diag(9),
  R = 100L # use a large value for R in actual research
)
phi <- matrix(</pre>
  data = c(
    -6, 5.5, 0, 0,
    1.25, -2.5, 5.9, -7.3,
    0, 0, -6, 2.5,
    5, 0, 0, -6
  ),
  nrow = 4
colnames(phi) <- rownames(phi) <- paste0("y", 1:4)</pre>
MCPhi(
  phi = phi,
  vcov_phi_vec = 0.1 * diag(16),
  R = 100L, # use a large value for R in actual research
  test_phi = FALSE
)
```

MCTotalCentral

Monte Carlo Sampling Distribution of Total Effect Centrality Over a Specific Time Interval or a Range of Time Intervals

Description

This function generates a Monte Carlo method sampling distribution of the total effect centrality at a particular time interval Δt using the first-order stochastic differential equation model drift matrix Φ .

Usage

```
MCTotalCentral(
   phi,
   vcov_phi_vec,
   delta_t,
   R,
   test_phi = TRUE,
   ncores = NULL,
   seed = NULL
)
```

Arguments

phi

Numeric matrix. The drift matrix (Φ) , phi should have row and column names pertaining to the variables in the system.

vcov_phi_vec Numeric matrix. The sampling variance-covariance matrix of vec (Φ) .

delta_t Numeric. Time interval (Δt).

R Positive integer. Number of replications.

test_phi Logical. If test_phi = TRUE, the function runs TestPhi() on the generated

drift matrix Φ . If the TestPhi() returns FALSE, the function generates a new

drift matrix Φ and runs the test recursively until TestPhi() returns TRUE.

ncores Positive integer. Number of cores to use. If ncores = NULL, use a single core.

Consider using multiple cores when number of replications R is a large value.

seed Random seed.

Details

See TotalCentral() for more details.

Monte Carlo Method:

Let θ be $\operatorname{vec}(\Phi)$, that is, the elements of the Φ matrix in vector form sorted column-wise. Let $\hat{\theta}$ be $\operatorname{vec}(\hat{\Phi})$. Based on the asymptotic properties of maximum likelihood estimators, we can assume that estimators are normally distributed around the population parameters.

$$\hat{oldsymbol{ heta}} \sim \mathcal{N}\left(oldsymbol{ heta}, \mathbb{V}\left(\hat{oldsymbol{ heta}}
ight)
ight)$$

Using this distributional assumption, a sampling distribution of $\hat{\theta}$ which we refer to as $\hat{\theta}^*$ can be generated by replacing the population parameters with sample estimates, that is,

$$\hat{oldsymbol{ heta}}^* \sim \mathcal{N}\left(\hat{oldsymbol{ heta}}, \hat{\mathbb{V}}\left(\hat{oldsymbol{ heta}}
ight)
ight).$$

Let $\mathbf{g}\left(\hat{\boldsymbol{\theta}}\right)$ be a parameter that is a function of the estimated parameters. A sampling distribution of $\mathbf{g}\left(\hat{\boldsymbol{\theta}}\right)$, which we refer to as $\mathbf{g}\left(\hat{\boldsymbol{\theta}}^*\right)$, can be generated by using the simulated estimates to calculate \mathbf{g} . The standard deviations of the simulated estimates are the standard errors. Percentiles corresponding to $100\left(1-\alpha\right)\%$ are the confidence intervals.

Linear Stochastic Differential Equation Model:

The measurement model is given by

$$\mathbf{y}_{i,t} = \boldsymbol{\nu} + \boldsymbol{\Lambda} \boldsymbol{\eta}_{i,t} + \boldsymbol{\varepsilon}_{i,t}, \quad ext{with} \quad \boldsymbol{\varepsilon}_{i,t} \sim \mathcal{N}\left(\mathbf{0}, \boldsymbol{\Theta}\right)$$

where $\mathbf{y}_{i,t}$, $\eta_{i,t}$, and $\varepsilon_{i,t}$ are random variables and $\boldsymbol{\nu}$, $\boldsymbol{\Lambda}$, and $\boldsymbol{\Theta}$ are model parameters. $\mathbf{y}_{i,t}$ represents a vector of observed random variables, $\eta_{i,t}$ a vector of latent random variables, and $\varepsilon_{i,t}$ a vector of random measurement errors, at time t and individual i. $\boldsymbol{\nu}$ denotes a vector of intercepts, $\boldsymbol{\Lambda}$ a matrix of factor loadings, and $\boldsymbol{\Theta}$ the covariance matrix of ε .

An alternative representation of the measurement error is given by

$$\boldsymbol{\varepsilon}_{i,t} = \boldsymbol{\Theta}^{\frac{1}{2}} \mathbf{z}_{i,t}, \quad \text{with} \quad \mathbf{z}_{i,t} \sim \mathcal{N}\left(\mathbf{0}, \mathbf{I}\right)$$

where $\mathbf{z}_{i,t}$ is a vector of independent standard normal random variables and $\left(\mathbf{\Theta}^{\frac{1}{2}}\right)\left(\mathbf{\Theta}^{\frac{1}{2}}\right)'=\mathbf{\Theta}.$

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The dynamic structure is given by

$$\mathrm{d}\boldsymbol{\eta}_{i:t} = (\boldsymbol{\iota} + \boldsymbol{\Phi}\boldsymbol{\eta}_{i:t}) \, \mathrm{d}t + \boldsymbol{\Sigma}^{\frac{1}{2}} \mathrm{d}\mathbf{W}_{i:t}$$

where ι is a term which is unobserved and constant over time, Φ is the drift matrix which represents the rate of change of the solution in the absence of any random fluctuations, Σ is the matrix of volatility or randomness in the process, and $\mathrm{d}W$ is a Wiener process or Brownian motion, which represents random fluctuations.

Value

Returns an object of class ctmedmc which is a list with the following elements:

call Function call.

args Function arguments.

fun Function used (MCTotalCentral).

output A list with length of length(delta_t).

Each element in the output list has the following elements:

est A vector of total, direct, and indirect effects.

thetahatstar A matrix of Monte Carlo total, direct, and indirect effects.

Author(s)

Ivan Jacob Agaloos Pesigan

References

Bollen, K. A. (1987). Total, direct, and indirect effects in structural equation models. Sociological Methodology, 17, 37. doi:10.2307/271028

Deboeck, P. R., & Preacher, K. J. (2015). No need to be discrete: A method for continuous time mediation analysis. Structural Equation Modeling: A Multidisciplinary Journal, 23 (1), 61–75. doi:10.1080/10705511.2014.973960

Ryan, O., & Hamaker, E. L. (2021). Time to intervene: A continuous-time approach to network analysis and centrality. Psychometrika, 87 (1), 214–252. doi:10.1007/s11336021097670

See Also

Other Continuous Time Mediation Functions: DeltaBeta(), DeltaIndirectCentral(), DeltaMed(), DeltaTotalCentral(), Direct(), Indirect(), IndirectCentral(), MCBeta(), MCIndirectCentral(), MCMed(), MCPhi(), Med(), PosteriorBeta(), PosteriorIndirectCentral(), PosteriorMed(), PosteriorPhi(), PosteriorTotalCentral(), TestPhi(), TestStable(), Total(), TotalCentral()

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```
set.seed(42)
phi <- matrix(</pre>
  data = c(
   -0.357, 0.771, -0.450,
   0.0, -0.511, 0.729,
   0, 0, -0.693
  ),
  nrow = 3
)
colnames(phi) <- rownames(phi) <- c("x", "m", "y")</pre>
vcov_phi_vec <- matrix(</pre>
  data = c(
    0.002704274, -0.001475275, 0.000949122,
    -0.001619422, 0.000885122, -0.000569404,
    0.00085493, -0.000465824, 0.000297815,
    -0.001475275, 0.004428442, -0.002642303,
    0.000980573, -0.00271817, 0.001618805,
    -0.000586921, 0.001478421, -0.000871547,
    0.000949122, -0.002642303, 0.006402668,
    -0.000697798, 0.001813471, -0.004043138,
    0.000463086, -0.001120949, 0.002271711,
    -0.001619422, 0.000980573, -0.000697798,
    0.002079286, -0.001152501, 0.000753,
    -0.001528701, 0.000820587, -0.000517524,
    0.000885122, -0.00271817, 0.001813471,
    -0.001152501, 0.00342605, -0.002075005,
    0.000899165, -0.002532849, 0.001475579,
    -0.000569404, 0.001618805, -0.004043138,
    0.000753, -0.002075005, 0.004984032,
    -0.000622255, 0.001634917, -0.003705661,
    0.00085493, -0.000586921, 0.000463086,
    -0.001528701, 0.000899165, -0.000622255,
    0.002060076, -0.001096684, 0.000686386,
    -0.000465824, 0.001478421, -0.001120949,
    0.000820587, -0.002532849, 0.001634917,
    -0.001096684, 0.003328692, -0.001926088,
    0.000297815, -0.000871547, 0.002271711,
    -0.000517524, 0.001475579, -0.003705661,
    0.000686386, -0.001926088, 0.004726235
  ),
 nrow = 9
)
# Specific time interval -------
MCTotalCentral(
  phi = phi,
  vcov_phi_vec = vcov_phi_vec,
  delta_t = 1,
  R = 100L # use a large value for R in actual research
)
```

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Med

Total, Direct, and Indirect Effects of X on Y Through M Over a Specific Time Interval or a Range of Time Intervals

Description

This function computes the total, direct, and indirect effects of the independent variable X on the dependent variable Y through mediator variables \mathbf{m} over a specific time interval Δt or a range of time intervals using the first-order stochastic differential equation model's drift matrix $\mathbf{\Phi}$.

Usage

```
Med(phi, delta_t, from, to, med)
```

Arguments

phi	Numeric matrix. The drift matrix (Φ) , phi should have row and column names pertaining to the variables in the system.
delta_t	Vector of positive numbers. Time interval (Δt) .
from	Character string. Name of the independent variable X in phi.
to	Character string. Name of the dependent variable Y in phi.
med	Character vector. Name/s of the mediator variable/s in phi.

Details

See Total(), Direct(), and Indirect() for more details.

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Linear Stochastic Differential Equation Model:

The measurement model is given by

$$\mathbf{y}_{i,t} = \mathbf{\nu} + \mathbf{\Lambda} \boldsymbol{\eta}_{i,t} + \boldsymbol{\varepsilon}_{i,t}, \quad ext{with} \quad \boldsymbol{\varepsilon}_{i,t} \sim \mathcal{N}\left(\mathbf{0}, \mathbf{\Theta}\right)$$

where $\mathbf{y}_{i,t}$, $\eta_{i,t}$, and $\varepsilon_{i,t}$ are random variables and ν , Λ , and Θ are model parameters. $\mathbf{y}_{i,t}$ represents a vector of observed random variables, $\eta_{i,t}$ a vector of latent random variables, and $\varepsilon_{i,t}$ a vector of random measurement errors, at time t and individual t. ν denotes a vector of intercepts, Λ a matrix of factor loadings, and Θ the covariance matrix of ε .

An alternative representation of the measurement error is given by

$$\boldsymbol{\varepsilon}_{i,t} = \boldsymbol{\Theta}^{\frac{1}{2}} \mathbf{z}_{i,t}, \quad \text{with} \quad \mathbf{z}_{i,t} \sim \mathcal{N}\left(\mathbf{0}, \mathbf{I}\right)$$

where $\mathbf{z}_{i,t}$ is a vector of independent standard normal random variables and $\left(\Theta^{\frac{1}{2}}\right)\left(\Theta^{\frac{1}{2}}\right)' = \Theta$. The dynamic structure is given by

$$\mathrm{d}\boldsymbol{\eta}_{i,t} = \left(\boldsymbol{\iota} + \boldsymbol{\Phi}\boldsymbol{\eta}_{i,t}\right) \mathrm{d}t + \boldsymbol{\Sigma}^{\frac{1}{2}} \mathrm{d}\mathbf{W}_{i,t}$$

where ι is a term which is unobserved and constant over time, Φ is the drift matrix which represents the rate of change of the solution in the absence of any random fluctuations, Σ is the matrix of volatility or randomness in the process, and $\mathrm{d}W$ is a Wiener process or Brownian motion, which represents random fluctuations.

Value

Returns an object of class ctmedmed which is a list with the following elements:

call Function call.

args Function arguments.

fun Function used (Med).

output A matrix of total, direct, and indirect effects.

Author(s)

Ivan Jacob Agaloos Pesigan

References

Bollen, K. A. (1987). Total, direct, and indirect effects in structural equation models. Sociological Methodology, 17, 37. doi:10.2307/271028

Deboeck, P. R., & Preacher, K. J. (2015). No need to be discrete: A method for continuous time mediation analysis. Structural Equation Modeling: A Multidisciplinary Journal, 23 (1), 61–75. doi:10.1080/10705511.2014.973960

Ryan, O., & Hamaker, E. L. (2021). Time to intervene: A continuous-time approach to network analysis and centrality. Psychometrika, 87 (1), 214–252. doi:10.1007/s11336021097670

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See Also

Other Continuous Time Mediation Functions: DeltaBeta(), DeltaIndirectCentral(), DeltaMed(), DeltaTotalCentral(), Direct(), Indirect(), IndirectCentral(), MCBeta(), MCIndirectCentral(), MCMed(), MCPhi(), MCTotalCentral(), PosteriorBeta(), PosteriorIndirectCentral(), PosteriorMed(), PosteriorPhi(), PosteriorTotalCentral(), TestPhi(), TestStable(), Total(), TotalCentral()

```
phi <- matrix(</pre>
 data = c(
   -0.357, 0.771, -0.450,
   0.0, -0.511, 0.729,
   0, 0, -0.693
 ),
 nrow = 3
)
colnames(phi) <- rownames(phi) <- c("x", "m", "y")</pre>
# Specific time interval ------
Med(
 phi = phi,
 delta_t = 1,
 from = "x",
 to = "y",
 med = "m"
)
# Range of time intervals ------
med <- Med(
 phi = phi,
 delta_t = 1:30,
 from = "x",
 to = "y",
 med = "m"
)
plot(med)
# Methods -----
# Med has a number of methods including
# print, summary, and plot
med <- Med(
 phi = phi,
 delta_t = 1:5,
 from = "x",
 to = "y",
 med = "m"
)
print(med)
summary(med)
plot(med)
```

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plot.ctmeddelta

Plot Method for an Object of Class ctmeddelta

Description

Plot Method for an Object of Class ctmeddelta

Usage

```
## S3 method for class 'ctmeddelta'
plot(x, alpha = 0.05, col = NULL, ...)
```

Arguments

X	Object of class ctmeddelta.
alpha	Numeric. Significance level
col	Character vector. Optional argument. Character vector of colors.
	Additional arguments.

Author(s)

Ivan Jacob Agaloos Pesigan

```
phi <- matrix(</pre>
  data = c(
    -0.357, 0.771, -0.450,
    0.0, -0.511, 0.729,
    0, 0, -0.693
  ),
  nrow = 3
)
colnames(phi) \leftarrow rownames(phi) \leftarrow c("x", "m", "y")
vcov_phi_vec <- matrix(</pre>
  data = c(
    0.002704274, -0.001475275, 0.000949122,
    -0.001619422, 0.000885122, -0.000569404,
    0.00085493, -0.000465824, 0.000297815,
    -0.001475275, 0.004428442, -0.002642303,
    0.000980573, -0.00271817, 0.001618805,
    -0.000586921, 0.001478421, -0.000871547,
    0.000949122, -0.002642303, 0.006402668,
    -0.000697798, 0.001813471, -0.004043138,
    0.000463086, -0.001120949, 0.002271711,
    -0.001619422, 0.000980573, -0.000697798,
    0.002079286, -0.001152501, 0.000753,
    -0.001528701, 0.000820587, -0.000517524,
```

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```
0.000885122, -0.00271817, 0.001813471,
   -0.001152501, 0.00342605, -0.002075005,
   0.000899165, -0.002532849, 0.001475579,
   -0.000569404, 0.001618805, -0.004043138,
   0.000753, -0.002075005, 0.004984032,
   -0.000622255, 0.001634917, -0.003705661,
   0.00085493, -0.000586921, 0.000463086,
   -0.001528701, 0.000899165, -0.000622255,
   0.002060076, -0.001096684, 0.000686386,
   -0.000465824, 0.001478421, -0.001120949,
   0.000820587, -0.002532849, 0.001634917,
   -0.001096684, 0.003328692, -0.001926088,
   0.000297815, -0.000871547, 0.002271711,
   -0.000517524, 0.001475579, -0.003705661,
   0.000686386, -0.001926088, 0.004726235
 ),
 nrow = 9
)
# Range of time intervals ------
delta <- DeltaMed(</pre>
 phi = phi,
 vcov_phi_vec = vcov_phi_vec,
 delta_t = 1:5,
 from = "x",
 to = "y",
 med = "m"
plot(delta)
```

plot.ctmedmc

Plot Method for an Object of Class ctmedmc

Description

Plot Method for an Object of Class ctmedmc

Usage

```
## S3 method for class 'ctmedmc'
plot(x, alpha = 0.05, col = NULL, ...)
```

Arguments

X	Object of class ctmedmc.
alpha	Numeric. Significance level
col	Character vector. Optional argument. Character vector of colors.
	Additional arguments.

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Author(s)

Ivan Jacob Agaloos Pesigan

```
set.seed(42)
phi <- matrix(</pre>
 data = c(
   -0.357, 0.771, -0.450,
   0.0, -0.511, 0.729,
   0, 0, -0.693
 ),
 nrow = 3
)
colnames(phi) <- rownames(phi) <- c("x", "m", "y")</pre>
vcov_phi_vec <- matrix(</pre>
 data = c(
   0.002704274, -0.001475275, 0.000949122,
    -0.001619422, 0.000885122, -0.000569404,
   0.00085493, -0.000465824, 0.000297815,
    -0.001475275, 0.004428442, -0.002642303,
   0.000980573, -0.00271817, 0.001618805,
   -0.000586921, 0.001478421, -0.000871547,
   0.000949122, -0.002642303, 0.006402668,
   -0.000697798, 0.001813471, -0.004043138,
   0.000463086, -0.001120949, 0.002271711,
   -0.001619422, 0.000980573, -0.000697798,
   0.002079286, -0.001152501, 0.000753,
    -0.001528701, 0.000820587, -0.000517524,
   0.000885122, -0.00271817, 0.001813471,
    -0.001152501, 0.00342605, -0.002075005,
   0.000899165, -0.002532849, 0.001475579,
    -0.000569404, 0.001618805, -0.004043138,
   0.000753, -0.002075005, 0.004984032,
    -0.000622255, 0.001634917, -0.003705661,
   0.00085493, -0.000586921, 0.000463086,
    -0.001528701, 0.000899165, -0.000622255,
   0.002060076, -0.001096684, 0.000686386,
    -0.000465824, 0.001478421, -0.001120949,
   0.000820587, -0.002532849, 0.001634917,
    -0.001096684, 0.003328692, -0.001926088,
   0.000297815, -0.000871547, 0.002271711,
    -0.000517524, 0.001475579, -0.003705661,
   0.000686386, -0.001926088, 0.004726235
 ),
 nrow = 9
# Range of time intervals -------
mc <- MCMed(</pre>
 phi = phi,
 vcov_phi_vec = vcov_phi_vec,
```

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```
delta_t = 1:5,
  from = "x",
  to = "y",
  med = "m",
  R = 100L # use a large value for R in actual research
)
plot(mc)
```

plot.ctmedmed

Plot Method for an Object of Class ctmedmed

Description

Plot Method for an Object of Class ctmedmed

Usage

```
## S3 method for class 'ctmedmed'
plot(x, col = NULL, legend_pos = "topright", ...)
```

Arguments

x Object of class ctmedmed.

col Character vector. Optional argument. Character vector of colors.

legend_pos Character vector. Optional argument. Legend position.

... Additional arguments.

Author(s)

Ivan Jacob Agaloos Pesigan

```
phi <- matrix(
  data = c(
    -0.357, 0.771, -0.450,
    0.0, -0.511, 0.729,
    0, 0, -0.693
),
  nrow = 3
)
colnames(phi) <- rownames(phi) <- c("x", "m", "y")

# Range of time intervals ------
med <- Med(
  phi = phi,
  delta_t = 1:5,</pre>
```

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```
from = "x",
to = "y",
med = "m"
)
plot(med)
```

PosteriorBeta

Posterior Sampling Distribution for the Elements of the Matrix of Lagged Coefficients Over a Specific Time Interval or a Range of Time Intervals

Description

This function generates a posterior sampling distribution for the elements of the matrix of lagged coefficients β over a specific time interval Δt or a range of time intervals using the first-order stochastic differential equation model drift matrix Φ .

Usage

```
PosteriorBeta(phi, delta_t, ncores = NULL)
```

Arguments

phi Numeric matrix. The drift matrix (Φ), phi should have row and column names

pertaining to the variables in the system.

delta_t Numeric. Time interval (Δt).

ncores Positive integer. Number of cores to use. If ncores = NULL, use a single core.

Consider using multiple cores when number of replications R is a large value.

Details

```
See Total().
```

Value

Returns an object of class ctmedmc which is a list with the following elements:

call Function call.

args Function arguments.

fun Function used (PosteriorBeta).

output A list with length of length(delta_t).

Each element in the output list has the following elements:

est A vector of total, direct, and indirect effects.

thetahatstar A matrix of Monte Carlo total, direct, and indirect effects.

PosteriorBeta 53

Author(s)

Ivan Jacob Agaloos Pesigan

References

Bollen, K. A. (1987). Total, direct, and indirect effects in structural equation models. Sociological Methodology, 17, 37. doi:10.2307/271028

Deboeck, P. R., & Preacher, K. J. (2015). No need to be discrete: A method for continuous time mediation analysis. Structural Equation Modeling: A Multidisciplinary Journal, 23 (1), 61–75. doi:10.1080/10705511.2014.973960

Ryan, O., & Hamaker, E. L. (2021). Time to intervene: A continuous-time approach to network analysis and centrality. Psychometrika, 87 (1), 214–252. doi:10.1007/s11336021097670

See Also

Other Continuous Time Mediation Functions: DeltaBeta(), DeltaIndirectCentral(), DeltaMed(), DeltaTotalCentral(), Direct(), Indirect(), IndirectCentral(), MCBeta(), MCIndirectCentral(), MCMed(), MCPhi(), MCTotalCentral(), Med(), PosteriorIndirectCentral(), PosteriorMed(), PosteriorPhi(), PosteriorTotalCentral(), TestPhi(), TestStable(), Total(), TotalCentral()

```
phi <- matrix(</pre>
 data = c(
    -0.357, 0.771, -0.450,
   0.0, -0.511, 0.729,
   0, 0, -0.693
 ),
 nrow = 3
colnames(phi) <- rownames(phi) <- c("x", "m", "y")</pre>
vcov_phi_vec <- matrix(</pre>
 data = c(
    0.002704274, -0.001475275, 0.000949122,
    -0.001619422, 0.000885122, -0.000569404,
    0.00085493, -0.000465824, 0.000297815,
    -0.001475275, 0.004428442, -0.002642303,
    0.000980573, -0.00271817, 0.001618805,
    -0.000586921, 0.001478421, -0.000871547,
    0.000949122, -0.002642303, 0.006402668,
    -0.000697798, 0.001813471, -0.004043138,
    0.000463086, -0.001120949, 0.002271711,
    -0.001619422, 0.000980573, -0.000697798,
    0.002079286, -0.001152501, 0.000753,
    -0.001528701, 0.000820587, -0.000517524,
    0.000885122, -0.00271817, 0.001813471,
    -0.001152501, 0.00342605, -0.002075005,
    0.000899165, -0.002532849, 0.001475579,
    -0.000569404, 0.001618805, -0.004043138,
    0.000753, -0.002075005, 0.004984032,
```

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```
-0.000622255, 0.001634917, -0.003705661,
   0.00085493, -0.000586921, 0.000463086,
   -0.001528701, 0.000899165, -0.000622255,
   0.002060076, -0.001096684, 0.000686386,
   -0.000465824, 0.001478421, -0.001120949,
   0.000820587, -0.002532849, 0.001634917,
   -0.001096684, 0.003328692, -0.001926088,
   0.000297815, -0.000871547, 0.002271711,
   -0.000517524, 0.001475579, -0.003705661,
   0.000686386, -0.001926088, 0.004726235
 ),
 nrow = 9
)
phi <- MCPhi(</pre>
 phi = phi,
 vcov_phi_vec = vcov_phi_vec,
 R = 1000L
)$output
# Specific time interval ------
PosteriorBeta(
 phi = phi,
 delta_t = 1
# Range of time intervals -------
posterior <- PosteriorBeta(</pre>
 phi = phi,
 delta_t = 1:5
)
plot(posterior)
# Methods ------
# PosteriorBeta has a number of methods including
# print, summary, confint, and plot
print(posterior)
summary(posterior)
confint(posterior, level = 0.95)
plot(posterior)
```

PosteriorIndirectCentral

Posterior Distribution of the Indirect Effect Centrality Over a Specific Time Interval or a Range of Time Intervals

Description

This function generates a posterior distribution of the indirect effect centrality over a specific time interval Δt or a range of time intervals using the posterior distribution of the first-order stochastic

PosteriorIndirectCentral 55

differential equation model drift matrix Φ .

Usage

PosteriorIndirectCentral(phi, delta_t, ncores = NULL)

Arguments

phi List of numeric matrices. Each element of the list is a sample from the posterior

distribution of the drift matrix (Φ). Each matrix should have row and column

names pertaining to the variables in the system.

delta_t Numeric. Time interval (Δt).

ncores Positive integer. Number of cores to use. If ncores = NULL, use a single core.

Consider using multiple cores when number of replications R is a large value.

Details

See TotalCentral() for more details.

Value

Returns an object of class ctmedmc which is a list with the following elements:

call Function call.

args Function arguments.

fun Function used (PosteriorIndirectCentral).

output A list with length of length(delta_t).

Each element in the output list has the following elements:

est Mean of the posterior distribution of the total, direct, and indirect effects.

thetahatstar Posterior distribution of the total, direct, and indirect effects.

Author(s)

Ivan Jacob Agaloos Pesigan

References

Bollen, K. A. (1987). Total, direct, and indirect effects in structural equation models. Sociological Methodology, 17, 37. doi:10.2307/271028

Deboeck, P. R., & Preacher, K. J. (2015). No need to be discrete: A method for continuous time mediation analysis. Structural Equation Modeling: A Multidisciplinary Journal, 23 (1), 61–75. doi:10.1080/10705511.2014.973960

Ryan, O., & Hamaker, E. L. (2021). Time to intervene: A continuous-time approach to network analysis and centrality. Psychometrika, 87 (1), 214–252. doi:10.1007/s11336021097670

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See Also

Other Continuous Time Mediation Functions: DeltaBeta(), DeltaIndirectCentral(), DeltaMed(), DeltaTotalCentral(), Direct(), Indirect(), IndirectCentral(), MCBeta(), MCIndirectCentral(), MCMed(), MCPhi(), MCTotalCentral(), Med(), PosteriorBeta(), PosteriorMed(), PosteriorPhi(), PosteriorTotalCentral(), TestPhi(), TestStable(), Total(), TotalCentral()

```
phi <- matrix(</pre>
 data = c(
   -0.357, 0.771, -0.450,
   0.0, -0.511, 0.729,
   0, 0, -0.693
 ),
 nrow = 3
)
colnames(phi) \leftarrow rownames(phi) \leftarrow c("x", "m", "y")
vcov_phi_vec <- matrix(</pre>
 data = c(
    0.002704274, -0.001475275, 0.000949122,
    -0.001619422, 0.000885122, -0.000569404,
    0.00085493, -0.000465824, 0.000297815,
    -0.001475275, 0.004428442, -0.002642303,
    0.000980573, -0.00271817, 0.001618805,
    -0.000586921, 0.001478421, -0.000871547,
    0.000949122, -0.002642303, 0.006402668,
    -0.000697798, 0.001813471, -0.004043138,
    0.000463086, -0.001120949, 0.002271711,
    -0.001619422, 0.000980573, -0.000697798,
    0.002079286, -0.001152501, 0.000753,
    -0.001528701, 0.000820587, -0.000517524,
    0.000885122, -0.00271817, 0.001813471,
    -0.001152501, 0.00342605, -0.002075005,
    0.000899165, -0.002532849, 0.001475579,
    -0.000569404, 0.001618805, -0.004043138,
    0.000753, -0.002075005, 0.004984032,
    -0.000622255, 0.001634917, -0.003705661,
    0.00085493, -0.000586921, 0.000463086,
    -0.001528701, 0.000899165, -0.000622255,
    0.002060076, -0.001096684, 0.000686386,
    -0.000465824, 0.001478421, -0.001120949,
    0.000820587, -0.002532849, 0.001634917,
    -0.001096684, 0.003328692, -0.001926088,
    0.000297815, -0.000871547, 0.002271711,
    -0.000517524, 0.001475579, -0.003705661,
    0.000686386, -0.001926088, 0.004726235
 ),
 nrow = 9
)
phi <- MCPhi(</pre>
 phi = phi,
```

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```
vcov_phi_vec = vcov_phi_vec,
 R = 1000L
)$output
# Specific time interval ------
PosteriorIndirectCentral(
 phi = phi,
 delta_t = 1
)
# Range of time intervals ------
posterior <- PosteriorIndirectCentral(</pre>
 phi = phi,
 delta_t = 1:5
# Methods -----
# PosteriorIndirectCentral has a number of methods including
# print, summary, confint, and plot
print(posterior)
summary(posterior)
confint(posterior, level = 0.95)
plot(posterior)
```

PosteriorMed

Posterior Distribution of Total, Direct, and Indirect Effects of X on Y Through M Over a Specific Time Interval or a Range of Time Intervals

Description

This function generates a posterior distribution of the total, direct and indirect effects of the independent variable X on the dependent variable Y through mediator variables \mathbf{m} over a specific time interval Δt or a range of time intervals using the posterior distribution of the first-order stochastic differential equation model drift matrix $\mathbf{\Phi}$.

Usage

```
PosteriorMed(phi, delta_t, from, to, med, ncores = NULL)
```

Arguments

phi	List of numeric matrices. Each element of the list is a sample from the posterior
	distribution of the drift matrix (Φ). Each matrix should have row and column
	names pertaining to the variables in the system.
delta_t	Numeric. Time interval (Δt).
from	Character string. Name of the independent variable X in phi.
to	Character string. Name of the dependent variable Y in phi.

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med Character vector. Name/s of the mediator variable/s in phi.

ncores Positive integer. Number of cores to use. If ncores = NULL, use a single core.

Consider using multiple cores when number of replications R is a large value.

Details

See Total(), Direct(), and Indirect() for more details.

Value

Returns an object of class ctmedmc which is a list with the following elements:

call Function call.

args Function arguments.

fun Function used (PosteriorMed).

output A list with length of length(delta_t).

Each element in the output list has the following elements:

est Mean of the posterior distribution of the total, direct, and indirect effects.

thetahatstar Posterior distribution of the total, direct, and indirect effects.

Author(s)

Ivan Jacob Agaloos Pesigan

References

Bollen, K. A. (1987). Total, direct, and indirect effects in structural equation models. Sociological Methodology, 17, 37. doi:10.2307/271028

Deboeck, P. R., & Preacher, K. J. (2015). No need to be discrete: A method for continuous time mediation analysis. Structural Equation Modeling: A Multidisciplinary Journal, 23 (1), 61–75. doi:10.1080/10705511.2014.973960

Ryan, O., & Hamaker, E. L. (2021). Time to intervene: A continuous-time approach to network analysis and centrality. Psychometrika, 87 (1), 214–252. doi:10.1007/s11336021097670

See Also

Other Continuous Time Mediation Functions: DeltaBeta(), DeltaIndirectCentral(), DeltaMed(), DeltaTotalCentral(), Direct(), Indirect(), IndirectCentral(), MCBeta(), MCIndirectCentral(), MCMed(), MCPhi(), MCTotalCentral(), Med(), PosteriorBeta(), PosteriorIndirectCentral(), PosteriorPhi(), PosteriorTotalCentral(), TestPhi(), TestStable(), Total(), TotalCentral()

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```
phi <- matrix(</pre>
  data = c(
   -0.357, 0.771, -0.450,
   0.0, -0.511, 0.729,
   0, 0, -0.693
  ),
  nrow = 3
)
colnames(phi) <- rownames(phi) <- c("x", "m", "y")</pre>
vcov_phi_vec <- matrix(</pre>
  data = c(
    0.002704274, -0.001475275, 0.000949122,
    -0.001619422, 0.000885122, -0.000569404,
    0.00085493, -0.000465824, 0.000297815,
    -0.001475275, 0.004428442, -0.002642303,
    0.000980573, -0.00271817, 0.001618805,
    -0.000586921, 0.001478421, -0.000871547,
    0.000949122, -0.002642303, 0.006402668,
    -0.000697798, 0.001813471, -0.004043138,
    0.000463086, -0.001120949, 0.002271711,
    -0.001619422, 0.000980573, -0.000697798,
    0.002079286, -0.001152501, 0.000753,
    -0.001528701, 0.000820587, -0.000517524,
    0.000885122, -0.00271817, 0.001813471,
    -0.001152501, 0.00342605, -0.002075005,
    0.000899165, -0.002532849, 0.001475579,
    -0.000569404, 0.001618805, -0.004043138,
    0.000753, -0.002075005, 0.004984032,
    -0.000622255, 0.001634917, -0.003705661,
    0.00085493, -0.000586921, 0.000463086,
    -0.001528701, 0.000899165, -0.000622255,
    0.002060076, -0.001096684, 0.000686386,
    -0.000465824, 0.001478421, -0.001120949,
    0.000820587, -0.002532849, 0.001634917,
    -0.001096684, 0.003328692, -0.001926088,
    0.000297815, -0.000871547, 0.002271711,
    -0.000517524, 0.001475579, -0.003705661,
     0.000686386, \ -0.001926088, \ 0.004726235 
  ),
  nrow = 9
)
phi <- MCPhi(</pre>
  phi = phi,
  vcov_phi_vec = vcov_phi_vec,
  R = 1000L
)$output
# Specific time interval -------
PosteriorMed(
  phi = phi,
```

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```
delta_t = 1,
 from = "x",
 to = "y",
 med = "m"
)
# Range of time intervals ------
posterior <- PosteriorMed(</pre>
 phi = phi,
 delta_t = 1:5,
 from = "x",
 to = "y",
 med = "m"
# Methods ------
# PosteriorMed has a number of methods including
# print, summary, confint, and plot
print(posterior)
summary(posterior)
confint(posterior, level = 0.95)
plot(posterior)
```

PosteriorPhi

Extract the Posterior Samples of the Drift Matrix

Description

The function extracts the posterior samples of the drift matrix from a fitted model from the ctsem::ctStanFit() function.

Usage

PosteriorPhi(object)

Arguments

object

Object of class ctStanFit. Output of the ctsem::ctStanFit() function.

Author(s)

Ivan Jacob Agaloos Pesigan

See Also

```
Other Continuous Time Mediation Functions: DeltaBeta(), DeltaIndirectCentral(), DeltaMed(), DeltaTotalCentral(), Direct(), Indirect(), IndirectCentral(), MCBeta(), MCIndirectCentral(), MCMed(), MCPhi(), MCTotalCentral(), Med(), PosteriorBeta(), PosteriorIndirectCentral(), PosteriorMed(), PosteriorTotalCentral(), TestPhi(), TestStable(), Total(), TotalCentral()
```

PosteriorTotalCentral 61

PosteriorTotalCentral Posterior Distribution of the Total Effect Centrality Over a Specific Time Interval or a Range of Time Intervals

Description

This function generates a posterior distribution of the total effect centrality over a specific time interval Δt or a range of time intervals using the posterior distribution of the first-order stochastic differential equation model drift matrix Φ .

Usage

PosteriorTotalCentral(phi, delta_t, ncores = NULL)

Arguments

phi	List of numeric matrices. Each element of the list is a sample from the posterior
	distribution of the drift matrix (Φ). Each matrix should have row and column
	names pertaining to the variables in the system.
delta t	Numeric Time interval (Λt)

delta_t Numeric. Time interval (Δt).

ncores Positive integer. Number of cores to use. If ncores = NULL, use a single core.

Consider using multiple cores when number of replications R is a large value.

Details

See TotalCentral() for more details.

Value

Returns an object of class ctmedmc which is a list with the following elements:

call Function call.

args Function arguments.

fun Function used (PosteriorTotalCentral).

output A list with length of length(delta_t).

Each element in the output list has the following elements:

est Mean of the posterior distribution of the total, direct, and indirect effects.

thetahatstar Posterior distribution of the total, direct, and indirect effects.

Author(s)

Ivan Jacob Agaloos Pesigan

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References

Bollen, K. A. (1987). Total, direct, and indirect effects in structural equation models. Sociological Methodology, 17, 37. doi:10.2307/271028

Deboeck, P. R., & Preacher, K. J. (2015). No need to be discrete: A method for continuous time mediation analysis. Structural Equation Modeling: A Multidisciplinary Journal, 23 (1), 61–75. doi:10.1080/10705511.2014.973960

Ryan, O., & Hamaker, E. L. (2021). Time to intervene: A continuous-time approach to network analysis and centrality. Psychometrika, 87 (1), 214–252. doi:10.1007/s11336021097670

See Also

Other Continuous Time Mediation Functions: DeltaBeta(), DeltaIndirectCentral(), DeltaMed(), DeltaTotalCentral(), Direct(), Indirect(), IndirectCentral(), MCBeta(), MCIndirectCentral(), MCMed(), MCPhi(), MCTotalCentral(), Med(), PosteriorBeta(), PosteriorIndirectCentral(), PosteriorMed(), PosteriorPhi(), TestPhi(), TestStable(), Total(), TotalCentral()

```
phi <- matrix(</pre>
  data = c(
    -0.357, 0.771, -0.450,
   0.0, -0.511, 0.729,
   0, 0, -0.693
  ),
  nrow = 3
colnames(phi) <- rownames(phi) <- c("x", "m", "y")</pre>
vcov_phi_vec <- matrix(</pre>
  data = c(
    0.002704274, -0.001475275, 0.000949122,
    -0.001619422, 0.000885122, -0.000569404,
    0.00085493, -0.000465824, 0.000297815,
    -0.001475275, 0.004428442, -0.002642303,
    0.000980573, -0.00271817, 0.001618805,
    -0.000586921, 0.001478421, -0.000871547,
    0.000949122, -0.002642303, 0.006402668,
    -0.000697798, 0.001813471, -0.004043138,
    0.000463086, -0.001120949, 0.002271711,
    -0.001619422, 0.000980573, -0.000697798,
    0.002079286, -0.001152501, 0.000753,
    -0.001528701, 0.000820587, -0.000517524,
    0.000885122, -0.00271817, 0.001813471,
    -0.001152501, 0.00342605, -0.002075005,
    0.000899165, -0.002532849, 0.001475579,
    -0.000569404, 0.001618805, -0.004043138,
    0.000753, -0.002075005, 0.004984032,
    -0.000622255, 0.001634917, -0.003705661,
    0.00085493, -0.000586921, 0.000463086,
    -0.001528701, 0.000899165, -0.000622255,
    0.002060076, -0.001096684, 0.000686386,
```

print.ctmeddelta 63

```
-0.000465824, 0.001478421, -0.001120949,
   0.000820587, -0.002532849, 0.001634917,
   -0.001096684, 0.003328692, -0.001926088,
    0.000297815, \ -0.000871547, \ 0.002271711, \\
   -0.000517524, 0.001475579, -0.003705661,
   0.000686386, -0.001926088, 0.004726235
 ),
 nrow = 9
)
phi <- MCPhi(</pre>
 phi = phi,
 vcov_phi_vec = vcov_phi_vec,
 R = 1000L
)$output
# Specific time interval ------
PosteriorTotalCentral(
 phi = phi,
 delta_t = 1
)
# Range of time intervals ------
posterior <- PosteriorTotalCentral(</pre>
 phi = phi,
 delta_t = 1:5
# Methods ------
# PosteriorTotalCentral has a number of methods including
# print, summary, confint, and plot
print(posterior)
summary(posterior)
confint(posterior, level = 0.95)
plot(posterior)
```

print.ctmeddelta

Print Method for Object of Class ctmeddelta

Description

Print Method for Object of Class ctmeddelta

Usage

```
## S3 method for class 'ctmeddelta'
print(x, alpha = 0.05, digits = 4, ...)
```

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Arguments

X	an object of class ctmeddelta.
alpha	Numeric vector. Significance level α .
digits	Integer indicating the number of decimal places to display.
	further arguments.

Value

Returns a matrix of time interval, estimates, standard errors, test statistics, p-values, and confidence intervals.

Author(s)

Ivan Jacob Agaloos Pesigan

```
phi <- matrix(</pre>
 data = c(
   -0.357, 0.771, -0.450,
   0.0, -0.511, 0.729,
   0, 0, -0.693
 ),
 nrow = 3
colnames(phi) <- rownames(phi) <- c("x", "m", "y")</pre>
vcov_phi_vec <- matrix(</pre>
 data = c(
    0.002704274, -0.001475275, 0.000949122,
    -0.001619422, 0.000885122, -0.000569404,
   0.00085493, -0.000465824, 0.000297815,
    -0.001475275, 0.004428442, -0.002642303,
   0.000980573, -0.00271817, 0.001618805,
    -0.000586921, 0.001478421, -0.000871547,
   0.000949122, -0.002642303, 0.006402668,
   -0.000697798, 0.001813471, -0.004043138,
   0.000463086, -0.001120949, 0.002271711,
    -0.001619422, 0.000980573, -0.000697798,
   0.002079286, -0.001152501, 0.000753,
    -0.001528701, 0.000820587, -0.000517524,
   0.000885122, -0.00271817, 0.001813471,
    -0.001152501, 0.00342605, -0.002075005,
    0.000899165, -0.002532849, 0.001475579,
    -0.000569404, 0.001618805, -0.004043138,
    0.000753, -0.002075005, 0.004984032,
    -0.000622255, 0.001634917, -0.003705661,
   0.00085493, -0.000586921, 0.000463086,
    -0.001528701, 0.000899165, -0.000622255,
   0.002060076, -0.001096684, 0.000686386,
    -0.000465824, 0.001478421, -0.001120949,
```

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```
0.000820587, -0.002532849, 0.001634917,
   -0.001096684, 0.003328692, -0.001926088,
   0.000297815, -0.000871547, 0.002271711,
   -0.000517524, 0.001475579, -0.003705661,
    0.000686386, \ -0.001926088, \ 0.004726235 
 ),
 nrow = 9
)
# Specific time interval ------
delta <- DeltaMed(</pre>
 phi = phi,
 vcov_phi_vec = vcov_phi_vec,
 delta_t = 1,
 from = "x",
 to = "y",
 med = "m"
)
print(delta)
# Range of time intervals ------
delta <- DeltaMed(</pre>
 phi = phi,
 vcov_phi_vec = vcov_phi_vec,
 delta_t = 1:5,
 from = "x",
 to = "y",
 med = "m"
print(delta)
```

print.ctmedeffect

Print Method for Object of Class ctmedeffect

Description

Print Method for Object of Class ctmedeffect

Usage

```
## S3 method for class 'ctmedeffect'
print(x, digits = 4, ...)
```

Arguments

```
x an object of class ctmedeffect.digits Integer indicating the number of decimal places to display.... further arguments.
```

print.ctmedeffect

Value

Returns the effects.

Author(s)

Ivan Jacob Agaloos Pesigan

```
phi <- matrix(</pre>
 data = c(
  -0.357, 0.771, -0.450,
  0.0, -0.511, 0.729,
  0, 0, -0.693
 ),
 nrow = 3
)
colnames(phi) <- rownames(phi) <- c("x", "m", "y")</pre>
delta_t <- 1
# Time Interval of One ------
## Total Effect ------
total_dt <- Total(</pre>
 phi = phi,
 delta_t = delta_t
print(total_dt)
## Direct Effect ------
direct_dt <- Direct(</pre>
 phi = phi,
 delta_t = delta_t,
 from = "x",
 to = "y",
 med = "m"
print(direct_dt)
## Indirect Effect ------
indirect_dt <- Indirect(</pre>
 phi = phi,
 delta_t = delta_t,
 from = "x",
 to = "y",
 med = "m"
)
print(indirect_dt)
```

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print.ctmedmc

Print Method for Object of Class ctmedmc

Description

Print Method for Object of Class ctmedmc

Usage

```
## S3 method for class 'ctmedmc'
print(x, alpha = 0.05, digits = 4, ...)
```

Arguments

```
x an object of class ctmedmc. alpha Numeric vector. Significance level \alpha. digits Integer indicating the number of decimal places to display. . . . further arguments.
```

Value

Returns a matrix of estimates, standard errors, number of Monte Carlo replications, and confidence intervals.

Author(s)

Ivan Jacob Agaloos Pesigan

```
set.seed(42)
phi <- matrix(</pre>
  data = c(
    -0.357, 0.771, -0.450,
    0.0, -0.511, 0.729,
    0, 0, -0.693
  ),
  nrow = 3
)
colnames(phi) <- rownames(phi) <- c("x", "m", "y")</pre>
vcov_phi_vec <- matrix(</pre>
  data = c(
    0.002704274, -0.001475275, 0.000949122,
    -0.001619422, 0.000885122, -0.000569404,
    0.00085493, -0.000465824, 0.000297815,
    -0.001475275, 0.004428442, -0.002642303,
    0.000980573, -0.00271817, 0.001618805,
    -0.000586921, 0.001478421, -0.000871547,
```

68 print.ctmedmcphi

```
0.000949122, -0.002642303, 0.006402668,
    -0.000697798, 0.001813471, -0.004043138,
   0.000463086, -0.001120949, 0.002271711,
    -0.001619422, 0.000980573, -0.000697798,
    0.002079286, \ -0.001152501, \ 0.000753, \\
    -0.001528701, 0.000820587, -0.000517524,
   0.000885122, -0.00271817, 0.001813471,
    -0.001152501, 0.00342605, -0.002075005,
   0.000899165, -0.002532849, 0.001475579,
    -0.000569404, 0.001618805, -0.004043138,
   0.000753, -0.002075005, 0.004984032,
    -0.000622255, 0.001634917, -0.003705661,
   0.00085493, -0.000586921, 0.000463086,
    -0.001528701, 0.000899165, -0.000622255,
   0.002060076, -0.001096684, 0.000686386,
    -0.000465824, 0.001478421, -0.001120949,
   0.000820587, -0.002532849, 0.001634917,
   -0.001096684, 0.003328692, -0.001926088,
   0.000297815, -0.000871547, 0.002271711,
   -0.000517524, 0.001475579, -0.003705661,
   0.000686386, -0.001926088, 0.004726235
 ),
 nrow = 9
)
# Specific time interval ------
mc <- MCMed(</pre>
 phi = phi,
 vcov_phi_vec = vcov_phi_vec,
 delta_t = 1,
 from = "x",
 to = "y",
 med = "m",
 R = 100L # use a large value for R in actual research
)
print(mc)
# Range of time intervals ------
mc <- MCMed(</pre>
 phi = phi,
 vcov_phi_vec = vcov_phi_vec,
 delta_t = 1:5,
 from = "x",
 to = "y",
 med = "m",
 R = 100L # use a large value for R in actual research
)
print(mc)
```

print.ctmedmcphi 69

Description

Print Method for Object of Class ctmedmcphi

Usage

```
## S3 method for class 'ctmedmcphi'
print(x, digits = 4, ...)
```

Arguments

```
x an object of class ctmedmcphi.digits Integer indicating the number of decimal places to display.further arguments.
```

Value

Returns the structure of the output.

Author(s)

Ivan Jacob Agaloos Pesigan

```
set.seed(42)
phi <- matrix(
    data = c(
        -0.357, 0.771, -0.450,
        0.0, -0.511, 0.729,
        0, 0, -0.693
    ),
    nrow = 3
)
colnames(phi) <- rownames(phi) <- c("x", "m", "y")
mc <- MCPhi(
    phi = phi,
    vcov_phi_vec = 0.1 * diag(9),
    R = 100L # use a large value for R in actual research
)
print(mc)</pre>
```

70 print.ctmedmed

print.ctmedmed

Print Method for Object of Class ctmedmed

Description

Print Method for Object of Class ctmedmed

Usage

```
## S3 method for class 'ctmedmed'
print(x, digits = 4, ...)
```

Arguments

```
x an object of class ctmedmed.digits Integer indicating the number of decimal places to display.... further arguments.
```

Value

Returns a matrix of effects.

Author(s)

Ivan Jacob Agaloos Pesigan

```
phi <- matrix(</pre>
 data = c(
   -0.357, 0.771, -0.450,
   0.0, -0.511, 0.729,
   0, 0, -0.693
 ),
 nrow = 3
)
colnames(phi) <- rownames(phi) <- c("x", "m", "y")</pre>
# Specific time interval ------
med <- Med(</pre>
 phi = phi,
 delta_t = 1,
 from = "x",
 to = "y",
 med = "m"
print(med)
# Range of time intervals ------
```

summary.ctmeddelta 71

```
med <- Med(
    phi = phi,
    delta_t = 1:5,
    from = "x",
    to = "y",
    med = "m"
)
print(med)</pre>
```

summary.ctmeddelta

Summary Method for an Object of Class ctmeddelta

Description

Summary Method for an Object of Class ctmeddelta

Usage

```
## S3 method for class 'ctmeddelta'
summary(object, alpha = 0.05, ...)
```

Arguments

object Object of class ctmeddelta.
alpha Numeric vector. Significance level α .
additional arguments.

Value

Returns a matrix of effects, time interval, estimates, standard errors, test statistics, p-values, and confidence intervals.

Author(s)

Ivan Jacob Agaloos Pesigan

```
phi <- matrix(
  data = c(
    -0.357, 0.771, -0.450,
    0.0, -0.511, 0.729,
    0, 0, -0.693
  ),
  nrow = 3
)
colnames(phi) <- rownames(phi) <- c("x", "m", "y")
vcov_phi_vec <- matrix(</pre>
```

72 summary.ctmeddelta

```
data = c(
   0.002704274, -0.001475275, 0.000949122,
   -0.001619422, 0.000885122, -0.000569404,
   0.00085493, -0.000465824, 0.000297815,
   -0.001475275, 0.004428442, -0.002642303,
   0.000980573, -0.00271817, 0.001618805,
   -0.000586921, 0.001478421, -0.000871547,
   0.000949122, -0.002642303, 0.006402668,
   -0.000697798, 0.001813471, -0.004043138,
   0.000463086, -0.001120949, 0.002271711,
   -0.001619422, 0.000980573, -0.000697798,
   0.002079286, -0.001152501, 0.000753,
   -0.001528701, 0.000820587, -0.000517524,
   0.000885122, -0.00271817, 0.001813471,
   -0.001152501, 0.00342605, -0.002075005,
   0.000899165, -0.002532849, 0.001475579,
   -0.000569404, 0.001618805, -0.004043138,
   0.000753, -0.002075005, 0.004984032,
   -0.000622255, 0.001634917, -0.003705661,
   0.00085493, -0.000586921, 0.000463086,
   -0.001528701, 0.000899165, -0.000622255,
   0.002060076, -0.001096684, 0.000686386,
   -0.000465824, 0.001478421, -0.001120949,
   0.000820587, -0.002532849, 0.001634917,
   -0.001096684, 0.003328692, -0.001926088,
   0.000297815, -0.000871547, 0.002271711,
   -0.000517524, 0.001475579, -0.003705661,
   0.000686386, -0.001926088, 0.004726235
 ),
 nrow = 9
)
# Specific time interval -------
delta <- DeltaMed(</pre>
 phi = phi,
 vcov_phi_vec = vcov_phi_vec,
 delta_t = 1,
 from = "x",
 to = "y",
 med = "m"
summary(delta)
# Range of time intervals ------
delta <- DeltaMed(</pre>
 phi = phi,
 vcov_phi_vec = vcov_phi_vec,
 delta_t = 1:5,
 from = "x".
 to = "y",
 med = "m"
summary(delta)
```

summary.ctmedmc 73

summary.ctmedmc

Summary Method for an Object of Class ctmedmc

Description

Summary Method for an Object of Class ctmedmc

Usage

```
## S3 method for class 'ctmedmc'
summary(object, alpha = 0.05, ...)
```

Arguments

object Object of class ctmedmc.
alpha Numeric vector. Significance level α .
additional arguments.

Value

Returns a matrix of effects, time interval, estimates, standard errors, test statistics, p-values, and confidence intervals.

Author(s)

Ivan Jacob Agaloos Pesigan

```
set.seed(42)
phi <- matrix(</pre>
  data = c(
    -0.357, 0.771, -0.450,
    0.0, -0.511, 0.729,
    0, 0, -0.693
  ),
  nrow = 3
)
colnames(phi) <- rownames(phi) <- c("x", "m", "y")</pre>
vcov_phi_vec <- matrix(</pre>
  data = c(
    0.002704274, -0.001475275, 0.000949122,
    -0.001619422, 0.000885122, -0.000569404,
    0.00085493, -0.000465824, 0.000297815,
    -0.001475275, 0.004428442, -0.002642303,
    0.000980573, -0.00271817, 0.001618805,
    -0.000586921, 0.001478421, -0.000871547,
```

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```
0.000949122, -0.002642303, 0.006402668,
   -0.000697798, 0.001813471, -0.004043138,
   0.000463086, -0.001120949, 0.002271711,
   -0.001619422, 0.000980573, -0.000697798,
    0.002079286, \ -0.001152501, \ 0.000753, \\
   -0.001528701, 0.000820587, -0.000517524,
   0.000885122, -0.00271817, 0.001813471,
   -0.001152501, 0.00342605, -0.002075005,
   0.000899165, -0.002532849, 0.001475579,
   -0.000569404, 0.001618805, -0.004043138,
   0.000753, -0.002075005, 0.004984032,
   -0.000622255, 0.001634917, -0.003705661,
   0.00085493, -0.000586921, 0.000463086,
   -0.001528701, 0.000899165, -0.000622255,
   0.002060076, -0.001096684, 0.000686386,
   -0.000465824, 0.001478421, -0.001120949,
   0.000820587, -0.002532849, 0.001634917,
   -0.001096684, 0.003328692, -0.001926088,
   0.000297815, -0.000871547, 0.002271711,
   -0.000517524, 0.001475579, -0.003705661,
   0.000686386, -0.001926088, 0.004726235
 ),
 nrow = 9
)
# Specific time interval ------
mc <- MCMed(</pre>
 phi = phi,
 vcov_phi_vec = vcov_phi_vec,
 delta_t = 1,
 from = "x",
 to = "y",
 med = "m",
 R = 100L # use a large value for R in actual research
)
summary(mc)
# Range of time intervals ------
mc <- MCMed(</pre>
 phi = phi,
 vcov_phi_vec = vcov_phi_vec,
 delta_t = 1:5,
 from = "x",
 to = "y",
 med = "m",
 R = 100L # use a large value for R in actual research
)
summary(mc)
```

summary.ctmedmed 75

Description

Summary Method for an Object of Class ctmedmed

Usage

```
## S3 method for class 'ctmedmed'
summary(object, digits = 4, ...)
```

Arguments

```
object an object of class ctmedmed.

digits Integer indicating the number of decimal places to display.

further arguments.
```

Value

Returns a matrix of effects.

Author(s)

Ivan Jacob Agaloos Pesigan

```
phi <- matrix(</pre>
 data = c(
   -0.357, 0.771, -0.450,
   0.0, -0.511, 0.729,
   0, 0, -0.693
 ),
 nrow = 3
colnames(phi) <- rownames(phi) <- c("x", "m", "y")</pre>
# Specific time interval ------
med <- Med(
 phi = phi,
 delta_t = 1,
 from = x^{*},
 to = "y",
 med = "m"
)
summary(med)
# Range of time intervals -----
med <- Med(
 phi = phi,
 delta_t = 1:5,
 from = "x",
 to = "y",
 med = "m"
```

```
)
summary(med)
```

```
summary.ctmedposteriorphi
```

Summary Method for Object of Class ctmedposteriorphi

Description

Summary Method for Object of Class ctmedposteriorphi

Usage

```
## S3 method for class 'ctmedposteriorphi'
summary(object, ...)
```

Arguments

```
object an object of class ctmedposteriorphi.
... further arguments.
```

Value

Returns a list of the posterior means (in matrix form) and covariance matrix.

Author(s)

Ivan Jacob Agaloos Pesigan

```
set.seed(42)
phi <- matrix(
   data = c(
        -0.357, 0.771, -0.450,
        0.0, -0.511, 0.729,
        0, 0, -0.693
   ),
   nrow = 3
)
colnames(phi) <- rownames(phi) <- c("x", "m", "y")
mc <- MCPhi(
   phi = phi,
   vcov_phi_vec = 0.1 * diag(9),
   R = 100L # use a large value for R in actual research
)$output
summary(mc)</pre>
```

TestPhi 77

TestPhi

Test the Drift Matrix

Description

Both have to be true for the function to return TRUE.

- Test that the real part of all eigenvalues of Φ are less than zero.
- Test that the diagonal values of Φ are between 0 to negative inifinity.

Usage

```
TestPhi(phi)
```

Arguments

phi

Numeric matrix. The drift matrix (Φ) .

Author(s)

Ivan Jacob Agaloos Pesigan

See Also

```
Other Continuous Time Mediation Functions: DeltaBeta(), DeltaIndirectCentral(), DeltaMed(), DeltaTotalCentral(), Direct(), Indirect(), IndirectCentral(), MCBeta(), MCIndirectCentral(), MCMed(), MCPhi(), MCTotalCentral(), Med(), PosteriorBeta(), PosteriorIndirectCentral(), PosteriorMed(), PosteriorPhi(), PosteriorTotalCentral(), TestStable(), Total(), TotalCentral()
```

```
phi <- matrix(</pre>
  data = c(
    -0.357, 0.771, -0.450,
    0.0, -0.511, 0.729,
    0, 0, -0.693
  ),
  nrow = 3
colnames(phi) <- rownames(phi) <- c("x", "m", "y")</pre>
TestPhi(phi = phi)
phi <- matrix(</pre>
  data = c(
    -6, 5.5, 0, 0,
    1.25, -2.5, 5.9, -7.3,
    0, 0, -6, 2.5,
    5, 0, 0, -6
  ),
  nrow = 4
```

78 TestStable

```
)
colnames(phi) <- rownames(phi) <- paste0("y", 1:4)
TestPhi(phi = phi)
```

TestStable

Test Stability

Description

The function computes the eigenvalues of the input matrix x. It checks if the real part of all eigenvalues is negative. If all eigenvalues have negative real parts, the system is considered stable.

Usage

TestStable(x)

Arguments

Х

Numeric matrix.

Author(s)

Ivan Jacob Agaloos Pesigan

See Also

```
Other Continuous Time Mediation Functions: DeltaBeta(), DeltaIndirectCentral(), DeltaMed(), DeltaTotalCentral(), Direct(), Indirect(), IndirectCentral(), MCBeta(), MCIndirectCentral(), MCMed(), MCPhi(), MCTotalCentral(), Med(), PosteriorBeta(), PosteriorIndirectCentral(), PosteriorMed(), PosteriorPhi(), PosteriorTotalCentral(), TestPhi(), Total(), TotalCentral()
```

```
x <- matrix(
  data = c(
    -0.357, 0.771, -0.450,
    0.0, -0.511, 0.729,
    0, 0, -0.693
  ),
  nrow = 3
)
TestStable(x)
x <- matrix(
  data = c(
    -6, 5.5, 0, 0,
    1.25, -2.5, 5.9, -7.3,
    0, 0, -6, 2.5,
    5, 0, 0, -6</pre>
```

Total 79

```
),
nrow = 4
)
TestStable(x)
```

Total

Total Effect Matrix Over a Specific Time Interval

Description

This function computes the total effects matrix over a specific time interval Δt using the first-order stochastic differential equation model's drift matrix Φ .

Usage

```
Total(phi, delta_t)
```

Arguments

phi

Numeric matrix. The drift matrix (Φ) . phi should have row and column names pertaining to the variables in the system.

delta_t

Numeric. Time interval (Δt).

Details

The total effect matrix over a specific time interval Δt is given by

$$Total_{\Delta t} = \exp\left(\Delta t \mathbf{\Phi}\right)$$

where Φ denotes the drift matrix, and Δt the time interval.

Linear Stochastic Differential Equation Model:

The measurement model is given by

$$\mathbf{y}_{i,t} = oldsymbol{
u} + oldsymbol{\Lambda} oldsymbol{\eta}_{i,t} + oldsymbol{arepsilon}_{i,t}, \quad ext{with} \quad oldsymbol{arepsilon}_{i,t} \sim \mathcal{N}\left(\mathbf{0}, oldsymbol{\Theta}
ight)$$

where $\mathbf{y}_{i,t}$, $\eta_{i,t}$, and $\varepsilon_{i,t}$ are random variables and ν , Λ , and Θ are model parameters. $\mathbf{y}_{i,t}$ represents a vector of observed random variables, $\eta_{i,t}$ a vector of latent random variables, and $\varepsilon_{i,t}$ a vector of random measurement errors, at time t and individual t. ν denotes a vector of intercepts, Λ a matrix of factor loadings, and Θ the covariance matrix of ε .

An alternative representation of the measurement error is given by

$$\boldsymbol{\varepsilon}_{i,t} = \boldsymbol{\Theta}^{\frac{1}{2}} \mathbf{z}_{i,t}, \quad \text{with} \quad \mathbf{z}_{i,t} \sim \mathcal{N}\left(\mathbf{0}, \mathbf{I}\right)$$

where $\mathbf{z}_{i,t}$ is a vector of independent standard normal random variables and $\left(\Theta^{\frac{1}{2}}\right)\left(\Theta^{\frac{1}{2}}\right)' = \Theta$. The dynamic structure is given by

$$\mathrm{d} oldsymbol{\eta}_{i,t} = \left(oldsymbol{\iota} + oldsymbol{\Phi} oldsymbol{\eta}_{i,t}
ight) \mathrm{d} t + oldsymbol{\Sigma}^{rac{1}{2}} \mathrm{d} \mathbf{W}_{i,t}$$

80 Total

where ι is a term which is unobserved and constant over time, Φ is the drift matrix which represents the rate of change of the solution in the absence of any random fluctuations, Σ is the matrix of volatility or randomness in the process, and $\mathrm{d}W$ is a Wiener process or Brownian motion, which represents random fluctuations.

Value

Returns an object of class ctmedeffect which is a list with the following elements:

```
call Function call.args Function arguments.fun Function used ("Total").output The matrix of total effects.
```

Author(s)

Ivan Jacob Agaloos Pesigan

References

Bollen, K. A. (1987). Total, direct, and indirect effects in structural equation models. Sociological Methodology, 17, 37. doi:10.2307/271028

Deboeck, P. R., & Preacher, K. J. (2015). No need to be discrete: A method for continuous time mediation analysis. Structural Equation Modeling: A Multidisciplinary Journal, 23 (1), 61–75. doi:10.1080/10705511.2014.973960

Ryan, O., & Hamaker, E. L. (2021). Time to intervene: A continuous-time approach to network analysis and centrality. Psychometrika, 87 (1), 214–252. doi:10.1007/s11336021097670

See Also

```
Other Continuous Time Mediation Functions: DeltaBeta(), DeltaIndirectCentral(), DeltaMed(), DeltaTotalCentral(), Direct(), Indirect(), IndirectCentral(), MCBeta(), MCIndirectCentral(), MCMed(), MCPhi(), MCTotalCentral(), Med(), PosteriorBeta(), PosteriorIndirectCentral(), PosteriorMed(), PosteriorPhi(), PosteriorTotalCentral(), TestPhi(), TestStable(), TotalCentral()
```

```
phi <- matrix(
  data = c(
    -0.357, 0.771, -0.450,
    0.0, -0.511, 0.729,
    0, 0, -0.693
  ),
  nrow = 3
)
colnames(phi) <- rownames(phi) <- c("x", "m", "y")
delta_t <- 1
Total(
  phi = phi,</pre>
```

TotalCentral 81

```
delta_t = delta_t
)
phi <- matrix(
  data = c(
    -6, 5.5, 0, 0,
    1.25, -2.5, 5.9, -7.3,
    0, 0, -6, 2.5,
    5, 0, 0, -6
  ),
  nrow = 4
)

Colnames(phi) <- rownames(phi) <- paste0("y", 1:4)

Total(
  phi = phi,
  delta_t = delta_t
)</pre>
```

TotalCentral

Total Effect Centrality

Description

Total Effect Centrality

Usage

```
TotalCentral(phi, delta_t)
```

Arguments

phi

Numeric matrix. The drift matrix (Φ). phi should have row and column names

pertaining to the variables in the system.

delta_t

Vector of positive numbers. Time interval (Δt).

Author(s)

Ivan Jacob Agaloos Pesigan

See Also

```
Other Continuous Time Mediation Functions: DeltaBeta(), DeltaIndirectCentral(), DeltaMed(), DeltaTotalCentral(), Direct(), Indirect(), IndirectCentral(), MCBeta(), MCIndirectCentral(), MCMed(), MCPhi(), MCTotalCentral(), Med(), PosteriorBeta(), PosteriorIndirectCentral(), PosteriorMed(), PosteriorPhi(), PosteriorTotalCentral(), TestPhi(), TestStable(), Total()
```

82 TotalCentral

```
phi <- matrix(</pre>
 data = c(
   -0.357, 0.771, -0.450,
  0.0, -0.511, 0.729,
   0, 0, -0.693
 ),
 nrow = 3
colnames(phi) <- rownames(phi) <- c("x", "m", "y")</pre>
# Specific time interval ------
TotalCentral(
 phi = phi,
 delta_t = 1
)
# Range of time intervals ------
total_central <- TotalCentral(</pre>
 phi = phi,
 delta_t = 1:30
plot(total_central)
# Methods ------
# IndirectCentral has a number of methods including
# print, summary, and plot
total_central <- TotalCentral(</pre>
 phi = phi,
 delta_t = 1:5
)
print(total_central)
summary(total_central)
plot(total_central)
```

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