# Package 'cTMed'

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confint.ctmeddelta

Delta Method Confidence Intervals

# **Description**

Delta Method Confidence Intervals

# Usage

```
## S3 method for class 'ctmeddelta'
confint(object, parm = NULL, level = 0.95, ...)
```

# Arguments

object Object of class ctmeddelta.

parm a specification of which parameters are to be given confidence intervals, either

a vector of numbers or a vector of names. If missing, all parameters are consid-

ered.

level the confidence level required.

... additional arguments.

# Value

Returns a matrix of confidence intervals.

# Author(s)

Ivan Jacob Agaloos Pesigan

confint.ctmeddelta 3

```
phi <- matrix(</pre>
 data = c(
   -0.357, 0.771, -0.450,
   0.0, -0.511, 0.729,
   0, 0, -0.693
 nrow = 3
)
colnames(phi) <- rownames(phi) <- c("x", "m", "y")</pre>
vcov_phi_vec <- matrix(</pre>
 data = c(
   0.002704274, -0.001475275, 0.000949122,
    -0.001619422, 0.000885122, -0.000569404,
   0.00085493, -0.000465824, 0.000297815,
    -0.001475275, 0.004428442, -0.002642303,
   0.000980573, -0.00271817, 0.001618805,
    -0.000586921, 0.001478421, -0.000871547,
    0.000949122, -0.002642303, 0.006402668,
    -0.000697798, 0.001813471, -0.004043138,
    0.000463086, -0.001120949, 0.002271711,
    -0.001619422, 0.000980573, -0.000697798,
   0.002079286, -0.001152501, 0.000753,
   -0.001528701, 0.000820587, -0.000517524,
   0.000885122, -0.00271817, 0.001813471,
    -0.001152501, 0.00342605, -0.002075005,
   0.000899165, -0.002532849, 0.001475579,
    -0.000569404, 0.001618805, -0.004043138,
   0.000753, -0.002075005, 0.004984032,
    -0.000622255, 0.001634917, -0.003705661,
   0.00085493, -0.000586921, 0.000463086,
    -0.001528701, 0.000899165, -0.000622255,
    0.002060076, -0.001096684, 0.000686386,
    -0.000465824, 0.001478421, -0.001120949,
   0.000820587, -0.002532849, 0.001634917,
    -0.001096684, 0.003328692, -0.001926088,
   0.000297815, -0.000871547, 0.002271711,
   -0.000517524, 0.001475579, -0.003705661,
    0.000686386, \ -0.001926088, \ 0.004726235 
 ),
 nrow = 9
)
# Specific time-interval -------
delta <- DeltaMed(</pre>
 phi = phi,
 vcov_phi_vec = vcov_phi_vec,
 delta_t = 1,
 from = "x",
 to = "y",
 med = "m"
)
```

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```
confint(delta)

# Range of time-intervals ------
delta <- DeltaMed(
   phi = phi,
   vcov_phi_vec = vcov_phi_vec,
   delta_t = 1:30,
   from = "x",
   to = "y",
   med = "m"
)
confint(delta)</pre>
```

confint.ctmedmc

Monte Carlo Method Confidence Intervals

# **Description**

Monte Carlo Method Confidence Intervals

# Usage

```
## S3 method for class 'ctmedmc'
confint(object, parm = NULL, level = 0.95, ...)
```

# Arguments

object Object of class ctmedmc.

parm a specification of which parameters are to be given confidence intervals, either

a vector of numbers or a vector of names. If missing, all parameters are consid-

ered.

level the confidence level required.

... additional arguments.

# Value

Returns a matrix of confidence intervals.

#### Author(s)

Ivan Jacob Agaloos Pesigan

confint.ctmedmc 5

```
set.seed(42)
phi <- matrix(</pre>
  data = c(
   -0.357, 0.771, -0.450,
   0.0, -0.511, 0.729,
   0, 0, -0.693
  ),
  nrow = 3
)
colnames(phi) <- rownames(phi) <- c("x", "m", "y")</pre>
vcov_phi_vec <- matrix(</pre>
  data = c(
    0.002704274, -0.001475275, 0.000949122,
    -0.001619422, 0.000885122, -0.000569404,
    0.00085493, -0.000465824, 0.000297815,
    -0.001475275, 0.004428442, -0.002642303,
    0.000980573, -0.00271817, 0.001618805,
    -0.000586921, 0.001478421, -0.000871547,
    0.000949122, -0.002642303, 0.006402668,
    -0.000697798, 0.001813471, -0.004043138,
    0.000463086, -0.001120949, 0.002271711,
    -0.001619422, 0.000980573, -0.000697798,
    0.002079286, -0.001152501, 0.000753,
    \hbox{\tt -0.001528701, 0.000820587, -0.000517524,}
    0.000885122, -0.00271817, 0.001813471,
    -0.001152501, 0.00342605, -0.002075005,
    0.000899165, -0.002532849, 0.001475579,
    -0.000569404, 0.001618805, -0.004043138,
    0.000753, -0.002075005, 0.004984032,
    -0.000622255, 0.001634917, -0.003705661,
    0.00085493, -0.000586921, 0.000463086,
    -0.001528701, 0.000899165, -0.000622255,
    0.002060076, -0.001096684, 0.000686386,
    -0.000465824, 0.001478421, -0.001120949,
    0.000820587, -0.002532849, 0.001634917,
    -0.001096684, 0.003328692, -0.001926088,
    0.000297815, -0.000871547, 0.002271711,
    -0.000517524, 0.001475579, -0.003705661,
    0.000686386, -0.001926088, 0.004726235
  ),
  nrow = 9
)
# Specific time-interval ------
mc <- MCMed(</pre>
  phi = phi,
  vcov_phi_vec = vcov_phi_vec,
  delta_t = 1,
  from = "x",
  to = "y",
  med = "m",
```

```
R = 100L # use a large value for R in actual research
)
confint(mc)

# Range of time-intervals ------
mc <- MCMed(
   phi = phi,
   vcov_phi_vec = vcov_phi_vec,
   delta_t = 1:30,
   from = "x",
   to = "y",
   med = "m",
   R = 100L # use a large value for R in actual research
)
confint(mc)</pre>
```

DeltaMed

Delta Method Sampling Variance-Covariance Matrix for the Total, Direct, and Indirect Effects of X on Y Through M Over a Specific Time-Interval or a Range of Time-Intervals

# **Description**

This function computes the delta method sampling variance-covariance matrix for the total, direct, and indirect effects of the independent variable X on the dependent variable Y through mediator variables  $\mathbf{m}$  over a specific time-interval  $\Delta t$  or a range of time-intervals using the first-order stochastic differential equation model's drift matrix  $\Phi$ .

# Usage

```
DeltaMed(phi, vcov_phi_vec, delta_t, from, to, med, ncores = NULL)
```

## **Arguments**

phi	Numeric matrix. The drift matrix ( $\Phi$ ). phi should have row and column names pertaining to the variables in the system.
vcov_phi_vec	Numeric matrix. The sampling variance-covariance matrix of $\operatorname{vec}\left(\mathbf{\Phi}\right)$ .
delta_t	Vector of positive numbers. Time interval $(\Delta t)$ .
from	Character string. Name of the independent variable $X$ in phi.
to	Character string. Name of the dependent variable $Y$ in phi.
med	Character vector. Name/s of the mediator variable/s in phi.
ncores	Positive integer. Number of cores to use. If ncores = NULL, use a single core. Consider using multiple cores when the length of delta_t is long.

#### **Details**

See Total(), Direct(), and Indirect() for more details.

#### **Delta Method:**

Let  $\theta$  be  $\text{vec}(\Phi)$ , that is, the elements of the  $\Phi$  matrix in vector form sorted column-wise. Let  $\hat{\theta}$  be  $\text{vec}(\hat{\Phi})$ . By the multivariate central limit theory, the function  $\mathbf{g}$  using  $\hat{\theta}$  as input can be expressed as:

$$\sqrt{n}\left(\mathbf{g}\left(\hat{\boldsymbol{\theta}}\right) - \mathbf{g}\left(\boldsymbol{\theta}\right)\right) \xrightarrow{\mathrm{D}} \mathcal{N}\left(0, \mathbf{J}\boldsymbol{\Gamma}\mathbf{J}'\right)$$

where **J** is the matrix of first-order derivatives of the function **g** with respect to the elements of  $\theta$  and  $\Gamma$  is the asymptotic variance-covariance matrix of  $\hat{\theta}$ .

From the former, we can derive the distribution of  $g(\hat{\theta})$  as follows:

$$\mathbf{g}\left(\hat{\boldsymbol{\theta}}\right) \approx \mathcal{N}\left(\mathbf{g}\left(\boldsymbol{\theta}\right), n^{-1}\mathbf{J}\boldsymbol{\Gamma}\mathbf{J}'\right)$$

The uncertainty associated with the estimator  $\mathbf{g}\left(\hat{\boldsymbol{\theta}}\right)$  is, therefore, given by  $n^{-1}\mathbf{J}\Gamma\mathbf{J}'$ . When  $\Gamma$  is unknown, by substitution, we can use the estimated sampling variance-covariance matrix of  $\hat{\boldsymbol{\theta}}$ , that is,  $\hat{\mathbb{V}}\left(\hat{\boldsymbol{\theta}}\right)$  for  $n^{-1}\Gamma$ . Therefore, the sampling variance-covariance matrix of  $\mathbf{g}\left(\hat{\boldsymbol{\theta}}\right)$  is given by

$$\mathbf{g}\left(\hat{\boldsymbol{\theta}}\right) \approx \mathcal{N}\left(\mathbf{g}\left(\boldsymbol{\theta}\right), \mathbf{J}\hat{\mathbb{V}}\left(\hat{\boldsymbol{\theta}}\right) \mathbf{J}'\right).$$

# **Linear Stochastic Differential Equation Model:**

The measurement model is given by

$$\mathbf{y}_{i,t} = \boldsymbol{\nu} + \boldsymbol{\Lambda} \boldsymbol{\eta}_{i,t} + \boldsymbol{\varepsilon}_{i,t}, \quad ext{with} \quad \boldsymbol{\varepsilon}_{i,t} \sim \mathcal{N}\left(\mathbf{0}, \boldsymbol{\Theta}\right)$$

where  $\mathbf{y}_{i,t}$ ,  $\boldsymbol{\eta}_{i,t}$ , and  $\boldsymbol{\varepsilon}_{i,t}$  are random variables and  $\boldsymbol{\nu}$ ,  $\boldsymbol{\Lambda}$ , and  $\boldsymbol{\Theta}$  are model parameters.  $\mathbf{y}_{i,t}$  represents a vector of observed random variables,  $\boldsymbol{\eta}_{i,t}$  a vector of latent random variables, and  $\boldsymbol{\varepsilon}_{i,t}$  a vector of random measurement errors, at time t and individual i.  $\boldsymbol{\nu}$  denotes a vector of intercepts,  $\boldsymbol{\Lambda}$  a matrix of factor loadings, and  $\boldsymbol{\Theta}$  the covariance matrix of  $\boldsymbol{\varepsilon}$ .

An alternative representation of the measurement error is given by

$$oldsymbol{arepsilon}_{i,t} = oldsymbol{\Theta}^{rac{1}{2}} \mathbf{z}_{i,t}, \quad ext{with} \quad \mathbf{z}_{i,t} \sim \mathcal{N}\left(\mathbf{0}, \mathbf{I}\right)$$

where  $\mathbf{z}_{i,t}$  is a vector of independent standard normal random variables and  $\left(\Theta^{\frac{1}{2}}\right)\left(\Theta^{\frac{1}{2}}\right)' = \Theta$ . The dynamic structure is given by

$$\mathrm{d}oldsymbol{\eta}_{i,t} = \left(oldsymbol{\iota} + oldsymbol{\Phi}oldsymbol{\eta}_{i,t}
ight)\mathrm{d}t + oldsymbol{\Sigma}^{rac{1}{2}}\mathrm{d}\mathbf{W}_{i,t}$$

where  $\iota$  is a term which is unobserved and constant over time,  $\Phi$  is the drift matrix which represents the rate of change of the solution in the absence of any random fluctuations,  $\Sigma$  is the matrix of volatility or randomness in the process, and  $\mathrm{d}W$  is a Wiener process or Brownian motion, which represents random fluctuations.

#### Value

Returns an object of class ctmeddelta which is a list with the following elements:

```
call Function call.
```

args Function arguments.

fun Function used (DeltaMed).

output A list with length of length(delta\_t).

Each element in the output list has the following elements:

```
delta_t Time-interval.
```

jacobian Jacobian matrix.,

est Estimated total, direct, and indirect effects.,

vcov Sampling variance-covariance matrix of the estimated total, direct, and indirect effects.

#### Author(s)

Ivan Jacob Agaloos Pesigan

#### References

Bollen, K. A. (1987). Total, direct, and indirect effects in structural equation models. Sociological Methodology, 17, 37. doi:10.2307/271028

Deboeck, P. R., & Preacher, K. J. (2015). No need to be discrete: A method for continuous time mediation analysis. Structural Equation Modeling: A Multidisciplinary Journal, 23 (1), 61–75. doi:10.1080/10705511.2014.973960

Ryan, O., & Hamaker, E. L. (2021). Time to intervene: A continuous-time approach to network analysis and centrality. Psychometrika, 87 (1), 214–252. doi:10.1007/s11336021097670

#### See Also

```
Other Continuous Time Mediation Functions: Direct(), Indirect(), MCMed(), MCPhi(), Med(), PosteriorMed(), PosteriorPhi(), TestPhi(), TestStable(), Total()
```

```
phi <- matrix(
  data = c(
    -0.357, 0.771, -0.450,
    0.0, -0.511, 0.729,
    0, 0, -0.693
  ),
  nrow = 3
)
colnames(phi) <- rownames(phi) <- c("x", "m", "y")
vcov_phi_vec <- matrix(
  data = c(
    0.002704274, -0.001475275, 0.000949122,</pre>
```

```
-0.001619422, 0.000885122, -0.000569404,
   0.00085493, -0.000465824, 0.000297815,
   -0.001475275, 0.004428442, -0.002642303,
   0.000980573, -0.00271817, 0.001618805,
   -0.000586921, 0.001478421, -0.000871547,
   0.000949122, -0.002642303, 0.006402668,
   -0.000697798, 0.001813471, -0.004043138,
   0.000463086, -0.001120949, 0.002271711,
   -0.001619422, 0.000980573, -0.000697798,
   0.002079286, -0.001152501, 0.000753,
   -0.001528701, 0.000820587, -0.000517524,
   0.000885122, -0.00271817, 0.001813471,
   -0.001152501, 0.00342605, -0.002075005,
   0.000899165, -0.002532849, 0.001475579,
   -0.000569404, 0.001618805, -0.004043138,
   0.000753, -0.002075005, 0.004984032,
   -0.000622255, 0.001634917, -0.003705661,
   0.00085493, -0.000586921, 0.000463086,
   -0.001528701, 0.000899165, -0.000622255,
   0.002060076, -0.001096684, 0.000686386,
   -0.000465824, 0.001478421, -0.001120949,
   0.000820587, -0.002532849, 0.001634917,
   -0.001096684, 0.003328692, -0.001926088,
   0.000297815, -0.000871547, 0.002271711,
   -0.000517524, 0.001475579, -0.003705661,
   0.000686386, -0.001926088, 0.004726235
 ),
 nrow = 9
)
# Specific time-interval ------
DeltaMed(
 phi = phi,
 vcov_phi_vec = vcov_phi_vec,
 delta_t = 1,
 from = "x",
 to = "y",
 med = "m"
# Range of time-intervals ------
delta <- DeltaMed(</pre>
 phi = phi,
 vcov_phi_vec = vcov_phi_vec,
 delta_t = 1:30,
 from = "x",
 to = "y",
 med = "m"
)
plot(delta)
# Methods -----
# DeltaMed has a number of methods including
```

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```
# print, summary, confint, and plot
print(delta)
summary(delta)
confint(delta, level = 0.95)
plot(delta)
```

Direct

Direct Effect of X on Y Over a Specific Time-Interval

# Description

This function computes the direct effect of the independent variable X on the dependent variable Y through mediator variables  $\mathbf{m}$  over a specific time-interval  $\Delta t$  using the first-order stochastic differential equation model's drift matrix  $\mathbf{\Phi}$ .

# Usage

```
Direct(phi, delta_t, from, to, med)
```

# **Arguments**

phi	Numeric matrix. The drift matrix $(\Phi)$ , phi should have row and column names pertaining to the variables in the system.
delta_t	Numeric. Time interval $(\Delta t)$ .
from	Character string. Name of the independent variable $X$ in phi.
to	Character string. Name of the dependent variable $Y$ in phi.
med	Character vector. Name/s of the mediator variable/s in phi.

# **Details**

The direct effect of the independent variable X on the dependent variable Y relative to some mediator variables  $\mathbf{m}$  is given by

$$\operatorname{Direct}_{\Delta t_{i,j,\mathbf{m}}} = \exp\left(\Delta t \mathbf{D} \mathbf{\Phi} \mathbf{D}\right)_{i,j}$$

where  $\Phi$  denotes the drift matrix,  $\mathbf{D}$  a diagonal matrix where the diagonal elements corresponding to mediator variables  $\mathbf{m}$  are set to zero and the rest to one, i the row index of Y in  $\Phi$ , j the column index of X in  $\Phi$ , and  $\Delta t$  the time-interval.

#### **Linear Stochastic Differential Equation Model:**

The measurement model is given by

$$\mathbf{y}_{i,t} = oldsymbol{
u} + oldsymbol{\Lambda} oldsymbol{\eta}_{i,t} + oldsymbol{arepsilon}_{i,t}, \quad ext{with} \quad oldsymbol{arepsilon}_{i,t} \sim \mathcal{N}\left(\mathbf{0}, oldsymbol{\Theta}
ight)$$

where  $\mathbf{y}_{i,t}$ ,  $\boldsymbol{\eta}_{i,t}$ , and  $\boldsymbol{\varepsilon}_{i,t}$  are random variables and  $\boldsymbol{\nu}$ ,  $\boldsymbol{\Lambda}$ , and  $\boldsymbol{\Theta}$  are model parameters.  $\mathbf{y}_{i,t}$  represents a vector of observed random variables,  $\boldsymbol{\eta}_{i,t}$  a vector of latent random variables, and

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 $\varepsilon_{i,t}$  a vector of random measurement errors, at time t and individual i.  $\nu$  denotes a vector of intercepts,  $\Lambda$  a matrix of factor loadings, and  $\Theta$  the covariance matrix of  $\varepsilon$ .

An alternative representation of the measurement error is given by

$$oldsymbol{arepsilon}_{i,t} = oldsymbol{\Theta}^{rac{1}{2}} \mathbf{z}_{i,t}, \quad ext{with} \quad \mathbf{z}_{i,t} \sim \mathcal{N}\left(\mathbf{0}, \mathbf{I}
ight)$$

where  $\mathbf{z}_{i,t}$  is a vector of independent standard normal random variables and  $\left(\Theta^{\frac{1}{2}}\right)\left(\Theta^{\frac{1}{2}}\right)' = \Theta$ . The dynamic structure is given by

$$\mathrm{d}oldsymbol{\eta}_{i,t} = \left(oldsymbol{\iota} + oldsymbol{\Phi}oldsymbol{\eta}_{i,t}
ight)\mathrm{d}t + oldsymbol{\Sigma}^{rac{1}{2}}\mathrm{d}\mathbf{W}_{i,t}$$

where  $\iota$  is a term which is unobserved and constant over time,  $\Phi$  is the drift matrix which represents the rate of change of the solution in the absence of any random fluctuations,  $\Sigma$  is the matrix of volatility or randomness in the process, and  $\mathrm{d}W$  is a Wiener process or Brownian motion, which represents random fluctuations.

#### Value

Returns an object of class ctmedeffect which is a list with the following elements:

call Function call.

args Function arguments.

fun Function used ("Direct").

output The direct effect.

## Author(s)

Ivan Jacob Agaloos Pesigan

#### References

Bollen, K. A. (1987). Total, direct, and indirect effects in structural equation models. Sociological Methodology, 17, 37. doi:10.2307/271028

Deboeck, P. R., & Preacher, K. J. (2015). No need to be discrete: A method for continuous time mediation analysis. Structural Equation Modeling: A Multidisciplinary Journal, 23 (1), 61–75. doi:10.1080/10705511.2014.973960

Ryan, O., & Hamaker, E. L. (2021). Time to intervene: A continuous-time approach to network analysis and centrality. Psychometrika, 87 (1), 214–252. doi:10.1007/s11336021097670

#### See Also

Other Continuous Time Mediation Functions: DeltaMed(), Indirect(), MCMed(), MCPhi(), Med(), PosteriorPhi(), TestPhi(), TestStable(), Total()

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## **Examples**

```
phi <- matrix(</pre>
  data = c(
    -0.357, 0.771, -0.450,
    0.0, -0.511, 0.729,
    0, 0, -0.693
  ),
  nrow = 3
colnames(phi) <- rownames(phi) <- c("x", "m", "y")</pre>
delta_t <- 1
Direct(
  phi = phi,
  delta_t = delta_t,
  from = "x",
  to = "y",
  med = "m"
)
phi <- matrix(</pre>
  data = c(
    -6, 5.5, 0, 0,
    1.25, -2.5, 5.9, -7.3,
    0, 0, -6, 2.5,
    5, 0, 0, -6
  ),
  nrow = 4
)
colnames(phi) <- rownames(phi) <- paste0("y", 1:4)</pre>
Direct(
  phi = phi,
  delta_t = delta_t,
  from = "y2",
  to = "y4",
  med = c("y1", "y3")
```

Indirect

Indirect Effect of X on Y Through M Over a Specific Time-Interval

# Description

This function computes the indirect effect of the independent variable X on the dependent variable Y through mediator variables  $\mathbf{m}$  over a specific time-interval  $\Delta t$  using the first-order stochastic differential equation model's drift matrix  $\mathbf{\Phi}$ .

# Usage

```
Indirect(phi, delta_t, from, to, med)
```

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#### **Arguments**

phi	Numeric matrix. The drift matrix $(\Phi)$ , phi should have row and column names
	pertaining to the variables in the system.
delta_t	Numeric. Time interval $(\Delta t)$ .
from	Character string. Name of the independent variable $X$ in phi.
to	Character string. Name of the dependent variable $Y$ in phi.
med	Character vector. Name/s of the mediator variable/s in phi.

#### **Details**

The indirect effect of the independent variable X on the dependent variable Y relative to some mediator variables  $\mathbf{m}$  over a specific time-interval  $\Delta t$  is given by

where  $\Phi$  denotes the drift matrix,  $\mathbf{D_m}$  a matrix where the off diagonal elements are zeros and the diagonal elements are zero for the index/indices of mediator variables  $\mathbf{m}$  and one otherwise, i the row index of Y in  $\Phi$ , j the column index of X in  $\Phi$ , and  $\Delta t$  the time-interval.

#### **Linear Stochastic Differential Equation Model:**

The measurement model is given by

$$\mathbf{y}_{i,t} = \mathbf{\nu} + \mathbf{\Lambda} oldsymbol{\eta}_{i.t} + oldsymbol{arepsilon}_{i,t}, \quad ext{with} \quad oldsymbol{arepsilon}_{i,t} \sim \mathcal{N}\left(\mathbf{0}, oldsymbol{\Theta}
ight)$$

where  $\mathbf{y}_{i,t}$ ,  $\eta_{i,t}$ , and  $\varepsilon_{i,t}$  are random variables and  $\nu$ ,  $\Lambda$ , and  $\Theta$  are model parameters.  $\mathbf{y}_{i,t}$  represents a vector of observed random variables,  $\eta_{i,t}$  a vector of latent random variables, and  $\varepsilon_{i,t}$  a vector of random measurement errors, at time t and individual t.  $\nu$  denotes a vector of intercepts,  $\Lambda$  a matrix of factor loadings, and  $\Theta$  the covariance matrix of  $\varepsilon$ .

An alternative representation of the measurement error is given by

$$oldsymbol{arepsilon}_{i,t} = oldsymbol{\Theta}^{rac{1}{2}} \mathbf{z}_{i,t}, \quad ext{with} \quad \mathbf{z}_{i,t} \sim \mathcal{N}\left(\mathbf{0}, \mathbf{I}
ight)$$

where  $\mathbf{z}_{i,t}$  is a vector of independent standard normal random variables and  $\left(\mathbf{\Theta}^{\frac{1}{2}}\right)\left(\mathbf{\Theta}^{\frac{1}{2}}\right)' = \mathbf{\Theta}$ . The dynamic structure is given by

$$\mathrm{d} oldsymbol{\eta}_{i,t} = \left( oldsymbol{\iota} + oldsymbol{\Phi} oldsymbol{\eta}_{i,t} 
ight) \mathrm{d} t + oldsymbol{\Sigma}^{rac{1}{2}} \mathrm{d} \mathbf{W}_{i,t}$$

where  $\iota$  is a term which is unobserved and constant over time,  $\Phi$  is the drift matrix which represents the rate of change of the solution in the absence of any random fluctuations,  $\Sigma$  is the matrix of volatility or randomness in the process, and  $\mathrm{d}W$  is a Wiener process or Brownian motion, which represents random fluctuations.

#### Value

Returns an object of class ctmedeffect which is a list with the following elements:

call Function call.

args Function arguments.

**fun** Function used ("Indirect").

output The indirect effect.

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#### Author(s)

Ivan Jacob Agaloos Pesigan

#### References

Bollen, K. A. (1987). Total, direct, and indirect effects in structural equation models. Sociological Methodology, 17, 37. doi:10.2307/271028

Deboeck, P. R., & Preacher, K. J. (2015). No need to be discrete: A method for continuous time mediation analysis. Structural Equation Modeling: A Multidisciplinary Journal, 23 (1), 61–75. doi:10.1080/10705511.2014.973960

Ryan, O., & Hamaker, E. L. (2021). Time to intervene: A continuous-time approach to network analysis and centrality. Psychometrika, 87 (1), 214–252. doi:10.1007/s11336021097670

# See Also

Other Continuous Time Mediation Functions: DeltaMed(), Direct(), MCMed(), MCPhi(), Med(), PosteriorMed(), PosteriorPhi(), TestPhi(), TestStable(), Total()

```
phi <- matrix(</pre>
  data = c(
    -0.357, 0.771, -0.450,
    0.0, -0.511, 0.729,
    0, 0, -0.693
  ),
  nrow = 3
)
colnames(phi) <- rownames(phi) <- c("x", "m", "y")</pre>
delta_t <- 1
Indirect(
  phi = phi,
  delta_t = delta_t,
  from = "x",
  to = "y",
  med = "m"
)
phi <- matrix(</pre>
  data = c(
    -6, 5.5, 0, 0,
    1.25, -2.5, 5.9, -7.3,
    0, 0, -6, 2.5,
    5, 0, 0, -6
  ),
  nrow = 4
colnames(phi) <- rownames(phi) <- paste0("y", 1:4)</pre>
Indirect(
  phi = phi,
  delta_t = delta_t,
```

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```
from = "y2",
to = "y4",
med = c("y1", "y3")
)
```

**MCMed** 

Monte Carlo Sampling Distribution of Total, Direct, and Indirect Effects of X on Y Through M Over a Specific Time-Interval or a Range of Time-Intervals

# Description

This function generates a Monte Carlo method sampling distribution of the total, direct and indirect effects of the independent variable X on the dependent variable Y through mediator variables  $\mathbf{m}$  at a particular time-interval  $\Delta t$  using the first-order stochastic differential equation model drift matrix  $\mathbf{\Phi}$ .

# Usage

```
MCMed(
    phi,
    vcov_phi_vec,
    delta_t,
    from,
    to,
    med,
    R,
    test_phi = TRUE,
    ncores = NULL,
    seed = NULL
)
```

# **Arguments**

phi	Numeric matrix. The drift matrix $(\Phi)$ . phi should have row and column names pertaining to the variables in the system.
vcov_phi_vec	Numeric matrix. The sampling variance-covariance matrix of $\operatorname{vec}\left(\Phi\right)$ .
delta_t	Numeric. Time interval ( $\Delta t$ ).
from	Character string. Name of the independent variable $X$ in phi.
to	Character string. Name of the dependent variable $Y$ in phi.
med	Character vector. Name/s of the mediator variable/s in phi.
R	Positive integer. Number of replications.
test_phi	Logical. If $test\_phi = TRUE$ , the function runs $TestPhi()$ on the generated drift matrix $\Phi$ . If the $TestPhi()$ returns FALSE, the function generates a new drift matrix $\Phi$ and runs the test recursively until $TestPhi()$ returns TRUE.

ncores Positive integer. Number of cores to use. If ncores = NULL, use a single core. Consider using multiple cores when number of replications R is a large value.

seed Random seed.

#### **Details**

See Total(), Direct(), and Indirect() for more details.

#### **Monte Carlo Method:**

Let  $\theta$  be  $\operatorname{vec}(\Phi)$ , that is, the elements of the  $\Phi$  matrix in vector form sorted column-wise. Let  $\hat{\theta}$  be  $\operatorname{vec}(\hat{\Phi})$ . Based on the asymptotic properties of maximum likelihood estimators, we can assume that estimators are normally distributed around the population parameters.

$$\hat{oldsymbol{ heta}} \sim \mathcal{N}\left(oldsymbol{ heta}, \mathbb{V}\left(\hat{oldsymbol{ heta}}
ight)
ight)$$

Using this distributional assumption, a sampling distribution of  $\hat{\theta}$  which we refer to as  $\hat{\theta}^*$  can be generated by replacing the population parameters with sample estimates, that is,

$$\hat{oldsymbol{ heta}}^* \sim \mathcal{N}\left(\hat{oldsymbol{ heta}}, \hat{\mathbb{V}}\left(\hat{oldsymbol{ heta}}
ight)
ight).$$

Let  $\mathbf{g}\left(\hat{\boldsymbol{\theta}}\right)$  be a parameter that is a function of the estimated parameters. A sampling distribution of  $\mathbf{g}\left(\hat{\boldsymbol{\theta}}\right)$ , which we refer to as  $\mathbf{g}\left(\hat{\boldsymbol{\theta}}^*\right)$ , can be generated by using the simulated estimates to calculate  $\mathbf{g}$ . The standard deviations of the simulated estimates are the standard errors. Percentiles corresponding to  $100\left(1-\alpha\right)\%$  are the confidence intervals.

#### **Linear Stochastic Differential Equation Model:**

The measurement model is given by

$$\mathbf{y}_{i,t} = \boldsymbol{\nu} + \boldsymbol{\Lambda} \boldsymbol{\eta}_{i,t} + \boldsymbol{\varepsilon}_{i,t}, \quad ext{with} \quad \boldsymbol{\varepsilon}_{i,t} \sim \mathcal{N}\left(\mathbf{0}, \boldsymbol{\Theta}\right)$$

where  $\mathbf{y}_{i,t}$ ,  $\eta_{i,t}$ , and  $\varepsilon_{i,t}$  are random variables and  $\boldsymbol{\nu}$ ,  $\boldsymbol{\Lambda}$ , and  $\boldsymbol{\Theta}$  are model parameters.  $\mathbf{y}_{i,t}$  represents a vector of observed random variables,  $\eta_{i,t}$  a vector of latent random variables, and  $\varepsilon_{i,t}$  a vector of random measurement errors, at time t and individual i.  $\boldsymbol{\nu}$  denotes a vector of intercepts,  $\boldsymbol{\Lambda}$  a matrix of factor loadings, and  $\boldsymbol{\Theta}$  the covariance matrix of  $\varepsilon$ .

An alternative representation of the measurement error is given by

$$\boldsymbol{\varepsilon}_{i,t} = \boldsymbol{\Theta}^{\frac{1}{2}} \mathbf{z}_{i,t}, \quad \text{with} \quad \mathbf{z}_{i,t} \sim \mathcal{N}\left(\mathbf{0}, \mathbf{I}\right)$$

where  $\mathbf{z}_{i,t}$  is a vector of independent standard normal random variables and  $\left(\boldsymbol{\Theta}^{\frac{1}{2}}\right)\left(\boldsymbol{\Theta}^{\frac{1}{2}}\right)' = \boldsymbol{\Theta}$ . The dynamic structure is given by

$$\mathrm{d} oldsymbol{\eta}_{i,t} = \left( oldsymbol{\iota} + oldsymbol{\Phi} oldsymbol{\eta}_{i,t} 
ight) \mathrm{d} t + oldsymbol{\Sigma}^{rac{1}{2}} \mathrm{d} \mathbf{W}_{i,t}$$

where  $\iota$  is a term which is unobserved and constant over time,  $\Phi$  is the drift matrix which represents the rate of change of the solution in the absence of any random fluctuations,  $\Sigma$  is the matrix of volatility or randomness in the process, and  $\mathrm{d}W$  is a Wiener process or Brownian motion, which represents random fluctuations.

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#### Value

Returns an object of class ctmedmc which is a list with the following elements:

call Function call.

args Function arguments.

fun Function used (MCMed).

output A list with length of length(delta\_t).

Each element in the output list has the following elements:

est A vector of total, direct, and indirect effects.

thetahatstar A matrix of Monte Carlo total, direct, and indirect effects.

## Author(s)

Ivan Jacob Agaloos Pesigan

#### References

Bollen, K. A. (1987). Total, direct, and indirect effects in structural equation models. Sociological Methodology, 17, 37. doi:10.2307/271028

Deboeck, P. R., & Preacher, K. J. (2015). No need to be discrete: A method for continuous time mediation analysis. Structural Equation Modeling: A Multidisciplinary Journal, 23 (1), 61–75. doi:10.1080/10705511.2014.973960

Ryan, O., & Hamaker, E. L. (2021). Time to intervene: A continuous-time approach to network analysis and centrality. Psychometrika, 87 (1), 214–252. doi:10.1007/s11336021097670

## See Also

```
Other Continuous Time Mediation Functions: DeltaMed(), Direct(), Indirect(), MCPhi(), Med(), PosteriorMed(), PosteriorPhi(), TestPhi(), TestStable(), Total()
```

```
set.seed(42)
phi <- matrix(
    data = c(
        -0.357, 0.771, -0.450,
        0.0, -0.511, 0.729,
        0, 0, -0.693
    ),
    nrow = 3
)
colnames(phi) <- rownames(phi) <- c("x", "m", "y")
vcov_phi_vec <- matrix(
    data = c(
        0.002704274, -0.001475275, 0.000949122,
        -0.001619422, 0.000885122, -0.000569404,
        0.00085493, -0.000465824, 0.000297815,</pre>
```

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```
-0.001475275, 0.004428442, -0.002642303,
   0.000980573, -0.00271817, 0.001618805,
   -0.000586921, 0.001478421, -0.000871547,
   0.000949122, -0.002642303, 0.006402668,
   -0.000697798, 0.001813471, -0.004043138,
   0.000463086, -0.001120949, 0.002271711,
   -0.001619422, 0.000980573, -0.000697798,
   0.002079286, -0.001152501, 0.000753,
   -0.001528701, 0.000820587, -0.000517524,
   0.000885122, -0.00271817, 0.001813471,
   -0.001152501, 0.00342605, -0.002075005,
   0.000899165, -0.002532849, 0.001475579,
   -0.000569404, 0.001618805, -0.004043138,
   0.000753, -0.002075005, 0.004984032,
   -0.000622255, 0.001634917, -0.003705661,
   0.00085493, -0.000586921, 0.000463086,
   -0.001528701, 0.000899165, -0.000622255,
   0.002060076, -0.001096684, 0.000686386,
   -0.000465824, 0.001478421, -0.001120949,
   0.000820587, -0.002532849, 0.001634917,
   -0.001096684, 0.003328692, -0.001926088,
   0.000297815, -0.000871547, 0.002271711,
   -0.000517524, 0.001475579, -0.003705661,
   0.000686386, -0.001926088, 0.004726235
 ),
 nrow = 9
)
# Specific time-interval -------
MCMed(
 phi = phi,
 vcov_phi_vec = vcov_phi_vec,
 delta_t = 1,
 from = "x",
 to = "y",
 med = "m",
 R = 100L # use a large value for R in actual research
)
# Range of time-intervals ------
mc <- MCMed(</pre>
 phi = phi,
 vcov_phi_vec = vcov_phi_vec,
 delta_t = 1:30,
 from = "x",
 to = "y",
 med = "m",
 R = 100L # use a large value for R in actual research
)
plot(mc)
# Methods -----
# MCMed has a number of methods including
```

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```
# print, summary, confint, and plot
print(mc)
summary(mc)
confint(mc, level = 0.95)
```

MCPhi

Generate Random Drift Matrices Using the Monte Carlo Method

# Description

This function generates random drift matrices  $\Phi$  using the Monte Carlo method.

#### Usage

```
MCPhi(phi, vcov_phi_vec, R, test_phi = TRUE, ncores = NULL, seed = NULL)
```

# **Arguments**

phi	Numeric matrix. The drift matrix ( $\Phi$ ). phi should have row and column names pertaining to the variables in the system.
vcov_phi_vec	Numeric matrix. The sampling variance-covariance matrix of $\operatorname{vec}\left(\Phi\right)$ .
R	Positive integer. Number of replications.
test_phi	Logical. If test_phi = TRUE, the function runs TestPhi() on the generated drift matrix $\Phi$ . If the TestPhi() returns FALSE, the function generates a new

drift matrix  $\Phi$  and runs the test recursively until TestPhi() returns TRUE.

Positive integer. Number of cores to use. If ncores = NULL, use a single core. Consider using multiple cores when number of replications R is a large value.

seed Random seed.

## **Details**

ncores

#### **Monte Carlo Method:**

Let  $\theta$  be  $\operatorname{vec}(\Phi)$ , that is, the elements of the  $\Phi$  matrix in vector form sorted column-wise. Let  $\hat{\theta}$  be  $\operatorname{vec}(\hat{\Phi})$ . Based on the asymptotic properties of maximum likelihood estimators, we can assume that estimators are normally distributed around the population parameters.

$$\hat{oldsymbol{ heta}} \sim \mathcal{N}\left(oldsymbol{ heta}, \mathbb{V}\left(\hat{oldsymbol{ heta}}
ight)
ight)$$

Using this distributional assumption, a sampling distribution of  $\hat{\theta}$  which we refer to as  $\hat{\theta}^*$  can be generated by replacing the population parameters with sample estimates, that is,

$$\hat{oldsymbol{ heta}}^* \sim \mathcal{N}\left(\hat{oldsymbol{ heta}}, \hat{\mathbb{V}}\left(\hat{oldsymbol{ heta}}
ight)
ight).$$

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## **Linear Stochastic Differential Equation Model:**

The measurement model is given by

$$\mathbf{y}_{i,t} = \mathbf{\nu} + \mathbf{\Lambda} \boldsymbol{\eta}_{i|t} + \boldsymbol{\varepsilon}_{i,t}, \quad ext{with} \quad \boldsymbol{\varepsilon}_{i,t} \sim \mathcal{N}\left(\mathbf{0}, \mathbf{\Theta}\right)$$

where  $\mathbf{y}_{i,t}$ ,  $\boldsymbol{\eta}_{i,t}$ , and  $\boldsymbol{\varepsilon}_{i,t}$  are random variables and  $\boldsymbol{\nu}$ ,  $\boldsymbol{\Lambda}$ , and  $\boldsymbol{\Theta}$  are model parameters.  $\mathbf{y}_{i,t}$  represents a vector of observed random variables,  $\boldsymbol{\eta}_{i,t}$  a vector of latent random variables, and  $\boldsymbol{\varepsilon}_{i,t}$  a vector of random measurement errors, at time t and individual i.  $\boldsymbol{\nu}$  denotes a vector of intercepts,  $\boldsymbol{\Lambda}$  a matrix of factor loadings, and  $\boldsymbol{\Theta}$  the covariance matrix of  $\boldsymbol{\varepsilon}$ .

An alternative representation of the measurement error is given by

$$oldsymbol{arepsilon}_{i.t} = oldsymbol{\Theta}^{rac{1}{2}} \mathbf{z}_{i.t}, \quad ext{with} \quad \mathbf{z}_{i.t} \sim \mathcal{N}\left(\mathbf{0}, \mathbf{I}\right)$$

where  $\mathbf{z}_{i,t}$  is a vector of independent standard normal random variables and  $\left(\Theta^{\frac{1}{2}}\right)\left(\Theta^{\frac{1}{2}}\right)' = \Theta$ . The dynamic structure is given by

$$\mathrm{d}oldsymbol{\eta}_{i,t} = \left(oldsymbol{\iota} + oldsymbol{\Phi}oldsymbol{\eta}_{i,t}
ight)\mathrm{d}t + oldsymbol{\Sigma}^{rac{1}{2}}\mathrm{d}\mathbf{W}_{i,t}$$

where  $\iota$  is a term which is unobserved and constant over time,  $\Phi$  is the drift matrix which represents the rate of change of the solution in the absence of any random fluctuations,  $\Sigma$  is the matrix of volatility or randomness in the process, and  $\mathrm{d}W$  is a Wiener process or Brownian motion, which represents random fluctuations.

#### Value

Returns a list of simulated drift matrices.

#### Author(s)

Ivan Jacob Agaloos Pesigan

#### See Also

Other Continuous Time Mediation Functions: DeltaMed(), Direct(), Indirect(), MCMed(), Med(), PosteriorMed(), PosteriorPhi(), TestPhi(), TestStable(), Total()

```
set.seed(42)
phi <- matrix(
  data = c(
    -0.357, 0.771, -0.450,
    0.0, -0.511, 0.729,
    0, 0, -0.693
  ),
  nrow = 3
)
colnames(phi) <- rownames(phi) <- c("x", "m", "y")
MCPhi(
  phi = phi,</pre>
```

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```
vcov_phi_vec = 0.1 * diag(9),
  R = 100L # use a large value for R in actual research
)
phi <- matrix(</pre>
  data = c(
    -6, 5.5, 0, 0,
    1.25, -2.5, 5.9, -7.3,
    0, 0, -6, 2.5,
    5, 0, 0, -6
  ),
  nrow = 4
)
colnames(phi) <- rownames(phi) <- paste0("y", 1:4)</pre>
  phi = phi,
  vcov_phi_vec = 0.1 * diag(16),
  R = 100L, # use a large value for R in actual research
  test_phi = FALSE
)
```

Med

Total, Direct, and Indirect Effects of X on Y Through M Over a Specific Time-Interval or a Range of Time-Intervals

# Description

This function computes the total, direct, and indirect effects of the independent variable X on the dependent variable Y through mediator variables  $\mathbf{m}$  over a specific time-interval  $\Delta t$  or a range of time-intervals using the first-order stochastic differential equation model's drift matrix  $\mathbf{\Phi}$ .

## Usage

```
Med(phi, delta_t, from, to, med)
```

### **Arguments**

phi	Numeric matrix. The drift matrix $(\Phi)$ , phi should have row and column names pertaining to the variables in the system.
delta_t	Vector of positive numbers. Time interval $(\Delta t)$ .
from	Character string. Name of the independent variable $X$ in $\mathtt{phi}$ .
to	Character string. Name of the dependent variable $Y$ in phi.
med	Character vector. Name/s of the mediator variable/s in phi.

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#### **Details**

See Total(), Direct(), and Indirect() for more details.

# **Linear Stochastic Differential Equation Model:**

The measurement model is given by

$$\mathbf{y}_{i,t} = oldsymbol{
u} + oldsymbol{\Lambda} oldsymbol{\eta}_{i,t} + oldsymbol{arepsilon}_{i,t}, \quad ext{with} \quad oldsymbol{arepsilon}_{i,t} \sim \mathcal{N}\left(\mathbf{0}, oldsymbol{\Theta}
ight)$$

where  $\mathbf{y}_{i,t}$ ,  $\eta_{i,t}$ , and  $\varepsilon_{i,t}$  are random variables and  $\nu$ ,  $\Lambda$ , and  $\Theta$  are model parameters.  $\mathbf{y}_{i,t}$  represents a vector of observed random variables,  $\eta_{i,t}$  a vector of latent random variables, and  $\varepsilon_{i,t}$  a vector of random measurement errors, at time t and individual i.  $\nu$  denotes a vector of intercepts,  $\Lambda$  a matrix of factor loadings, and  $\Theta$  the covariance matrix of  $\varepsilon$ .

An alternative representation of the measurement error is given by

$$oldsymbol{arepsilon}_{i.t} = oldsymbol{\Theta}^{rac{1}{2}} \mathbf{z}_{i.t}, \quad ext{with} \quad \mathbf{z}_{i.t} \sim \mathcal{N}\left(\mathbf{0}, \mathbf{I}\right)$$

where  $\mathbf{z}_{i,t}$  is a vector of independent standard normal random variables and  $\left(\Theta^{\frac{1}{2}}\right)\left(\Theta^{\frac{1}{2}}\right)' = \Theta$ . The dynamic structure is given by

$$\mathrm{d}\boldsymbol{\eta}_{i,t} = \left(\boldsymbol{\iota} + \boldsymbol{\Phi}\boldsymbol{\eta}_{i,t}\right) \mathrm{d}t + \boldsymbol{\Sigma}^{\frac{1}{2}} \mathrm{d}\mathbf{W}_{i,t}$$

where  $\iota$  is a term which is unobserved and constant over time,  $\Phi$  is the drift matrix which represents the rate of change of the solution in the absence of any random fluctuations,  $\Sigma$  is the matrix of volatility or randomness in the process, and  $\mathrm{d}W$  is a Wiener process or Brownian motion, which represents random fluctuations.

#### Value

Returns an object of class ctmedmed which is a list with the following elements:

call Function call.

args Function arguments.

fun Function used (Med).

**output** A matrix of total, direct, and indirect effects.

#### Author(s)

Ivan Jacob Agaloos Pesigan

#### References

Bollen, K. A. (1987). Total, direct, and indirect effects in structural equation models. Sociological Methodology, 17, 37. doi:10.2307/271028

Deboeck, P. R., & Preacher, K. J. (2015). No need to be discrete: A method for continuous time mediation analysis. Structural Equation Modeling: A Multidisciplinary Journal, 23 (1), 61–75. doi:10.1080/10705511.2014.973960

Ryan, O., & Hamaker, E. L. (2021). Time to intervene: A continuous-time approach to network analysis and centrality. Psychometrika, 87 (1), 214–252. doi:10.1007/s11336021097670

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#### See Also

Other Continuous Time Mediation Functions: DeltaMed(), Direct(), Indirect(), MCMed(), MCPhi(), PosteriorMed(), PosteriorPhi(), TestPhi(), TestStable(), Total()

# **Examples**

```
phi <- matrix(</pre>
 data = c(
   -0.357, 0.771, -0.450,
   0.0, -0.511, 0.729,
   0, 0, -0.693
 ),
 nrow = 3
)
colnames(phi) \leftarrow rownames(phi) \leftarrow c("x", "m", "y")
# Specific time-interval ------
Med(
 phi = phi,
 delta_t = 1,
 from = "x",
 to = "y",
 med = "m"
)
# Range of time-intervals ------
med <- Med(
 phi = phi,
 delta_t = 1:30,
 from = "x",
 to = "y",
 med = "m"
)
plot(med)
# Methods ------
# Med has a number of methods including
# print, summary, and plot
print(med)
summary(med)
plot(med)
```

plot.ctmeddelta

Plot Method for an Object of Class ctmeddelta

# **Description**

Plot Method for an Object of Class ctmeddelta

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#### Usage

```
## S3 method for class 'ctmeddelta'
plot(
    x,
    alpha = 0.05,
    col_direct = "#2c7bb6",
    col_indirect = "#d7191c",
    col_total = "#5e3c99",
    ...
)
```

# **Arguments**

```
x Object of class ctmeddelta.

alpha Numeric. Significance level

col_direct Character string. Optional argument. Color for the direct effect.

col_indirect Character string. Optional argument. Color for the indirect effect.

col_total Character string. Optional argument. Color for the total effect.

Additional arguments.
```

#### Author(s)

Ivan Jacob Agaloos Pesigan

```
phi <- matrix(</pre>
  data = c(
    -0.357, 0.771, -0.450,
    0.0, -0.511, 0.729,
    0, 0, -0.693
  ),
  nrow = 3
)
colnames(phi) \leftarrow rownames(phi) \leftarrow c("x", "m", "y")
vcov_phi_vec <- matrix(</pre>
  data = c(
    0.002704274, -0.001475275, 0.000949122,
    -0.001619422, 0.000885122, -0.000569404,
    0.00085493, -0.000465824, 0.000297815,
    -0.001475275, 0.004428442, -0.002642303,
    0.000980573, -0.00271817, 0.001618805,
    -0.000586921, 0.001478421, -0.000871547,
    0.000949122, -0.002642303, 0.006402668,
    -0.000697798, 0.001813471, -0.004043138,
    0.000463086, -0.001120949, 0.002271711,
    -0.001619422, 0.000980573, -0.000697798,
    0.002079286, -0.001152501, 0.000753,
    -0.001528701, 0.000820587, -0.000517524,
```

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```
0.000885122, -0.00271817, 0.001813471,
   -0.001152501, 0.00342605, -0.002075005,
   0.000899165, -0.002532849, 0.001475579,
   -0.000569404, 0.001618805, -0.004043138,
   0.000753, -0.002075005, 0.004984032,
   -0.000622255, 0.001634917, -0.003705661,
   0.00085493, -0.000586921, 0.000463086,
   -0.001528701, 0.000899165, -0.000622255,
   0.002060076, -0.001096684, 0.000686386,
   -0.000465824, 0.001478421, -0.001120949,
   0.000820587, -0.002532849, 0.001634917,
   -0.001096684, 0.003328692, -0.001926088,
   0.000297815, -0.000871547, 0.002271711,
   -0.000517524, 0.001475579, -0.003705661,
   0.000686386, -0.001926088, 0.004726235
 ),
 nrow = 9
)
# Range of time-intervals ------
delta <- DeltaMed(</pre>
 phi = phi,
 vcov_phi_vec = vcov_phi_vec,
 delta_t = 1:30,
 from = "x",
 to = "y",
 med = "m"
plot(delta)
```

plot.ctmedmc

Plot Method for an Object of Class ctmedmc

# **Description**

Plot Method for an Object of Class ctmedmc

## Usage

```
## S3 method for class 'ctmedmc'
plot(
    x,
    alpha = 0.05,
    col_direct = "#2c7bb6",
    col_indirect = "#d7191c",
    col_total = "#5e3c99",
    ...
)
```

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# Arguments

х	Object of class ctmedmc.
alpha	Numeric. Significance level
col_direct	Character string. Optional argument. Color for the direct effect.
col_indirect	Character string. Optional argument. Color for the indirect effect.
col_total	Character string. Optional argument. Color for the total effect.
• • •	Additional arguments.

#### Author(s)

Ivan Jacob Agaloos Pesigan

```
set.seed(42)
phi <- matrix(</pre>
  data = c(
   -0.357, 0.771, -0.450,
   0.0, -0.511, 0.729,
   0, 0, -0.693
  ),
  nrow = 3
)
colnames(phi) <- rownames(phi) <- c("x", "m", "y")</pre>
vcov_phi_vec <- matrix(</pre>
  data = c(
    0.002704274, -0.001475275, 0.000949122,
    -0.001619422, 0.000885122, -0.000569404,
    0.00085493, -0.000465824, 0.000297815,
    -0.001475275, 0.004428442, -0.002642303,
    0.000980573, -0.00271817, 0.001618805,
    -0.000586921, 0.001478421, -0.000871547,
    0.000949122, -0.002642303, 0.006402668,
    -0.000697798, 0.001813471, -0.004043138,
    0.000463086, -0.001120949, 0.002271711,
    -0.001619422, 0.000980573, -0.000697798,
   0.002079286, -0.001152501, 0.000753,
    -0.001528701, 0.000820587, -0.000517524,
    0.000885122, -0.00271817, 0.001813471,
    -0.001152501, 0.00342605, -0.002075005,
    0.000899165, -0.002532849, 0.001475579,
    -0.000569404, 0.001618805, -0.004043138,
    0.000753, -0.002075005, 0.004984032,
    -0.000622255, 0.001634917, -0.003705661,
    0.00085493, -0.000586921, 0.000463086,
    -0.001528701, 0.000899165, -0.000622255,
    0.002060076, -0.001096684, 0.000686386,
    -0.000465824, 0.001478421, -0.001120949,
    0.000820587, -0.002532849, 0.001634917,
    -0.001096684, 0.003328692, -0.001926088,
```

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```
0.000297815, -0.000871547, 0.002271711,
   -0.000517524, 0.001475579, -0.003705661,
   0.000686386, -0.001926088, 0.004726235
 ),
 nrow = 9
)
# Range of time-intervals ------
mc <- MCMed(</pre>
 phi = phi,
 vcov_phi_vec = vcov_phi_vec,
 delta_t = 1:30,
 from = "x",
 to = "y",
 med = "m"
 R = 100L # use a large value for R in actual research
plot(mc)
```

plot.ctmedmed

Plot Method for an Object of Class ctmedmed

# Description

Plot Method for an Object of Class ctmedmed

# Usage

```
## S3 method for class 'ctmedmed'
plot(
    x,
    col_direct = "#2c7bb6",
    col_indirect = "#d7191c",
    col_total = "#5e3c99",
    ...
)
```

# Arguments

x Object of class ctmedmed.
 col\_direct Character string. Optional argument. Color for the direct effect.
 col\_indirect Character string. Optional argument. Color for the indirect effect.
 col\_total Character string. Optional argument. Color for the total effect.
 Additional arguments.

#### Author(s)

Ivan Jacob Agaloos Pesigan

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# **Examples**

```
phi <- matrix(</pre>
 data = c(
    -0.357, 0.771, -0.450,
   0.0, -0.511, 0.729,
   0, 0, -0.693
 ),
 nrow = 3
colnames(phi) \leftarrow rownames(phi) \leftarrow c("x", "m", "y")
# Range of time-intervals ------
med <- Med(</pre>
 phi = phi,
 delta_t = 1:30,
 from = "x",
 to = "y",
 med = "m"
plot(med)
```

PosteriorMed

Posterior Distribution of Total, Direct, and Indirect Effects of X on Y Through M Over a Specific Time-Interval

# Description

This function generates a posterior distribution of the total, direct and indirect effects of the independent variable X on the dependent variable Y through mediator variables  $\mathbf{m}$  at a particular time-interval  $\Delta t$  using the posterior distribution of the first-order stochastic differential equation model drift matrix  $\mathbf{\Phi}$ .

# Usage

```
PosteriorMed(phi, delta_t, from, to, med, ncores = NULL)
```

#### **Arguments**

phi	List of numeric matrices. Each element of the list is a sample from the posterior distribution of the drift matrix ( $\Phi$ ). Each matrix should have row and column names pertaining to the variables in the system.
delta_t	Numeric. Time interval ( $\Delta t$ ).
from	Character string. Name of the independent variable $X$ in phi.
to	Character string. Name of the dependent variable $Y$ in phi.
med	Character vector. Name/s of the mediator variable/s in phi.
ncores	Positive integer. Number of cores to use. If ncores = NULL, use a single core. Consider using multiple cores when number of replications R is a large value.

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#### **Details**

See Total(), Direct(), and Indirect() for more details.

#### Value

Returns an object of class ctmedmc which is a list with the following elements:

call Function call.

args Function arguments.

fun Function used (PosteriorMed).

output A list with length of length(delta\_t).

Each element in the output list has the following elements:

est Mean of the posterior distribution of the total, direct, and indirect effects.

thetahatstar Posterior distribution of the total, direct, and indirect effects.

#### Author(s)

Ivan Jacob Agaloos Pesigan

#### References

Bollen, K. A. (1987). Total, direct, and indirect effects in structural equation models. Sociological Methodology, 17, 37. doi:10.2307/271028

Deboeck, P. R., & Preacher, K. J. (2015). No need to be discrete: A method for continuous time mediation analysis. Structural Equation Modeling: A Multidisciplinary Journal, 23 (1), 61–75. doi:10.1080/10705511.2014.973960

Ryan, O., & Hamaker, E. L. (2021). Time to intervene: A continuous-time approach to network analysis and centrality. Psychometrika, 87 (1), 214–252. doi:10.1007/s11336021097670

#### See Also

```
Other Continuous Time Mediation Functions: DeltaMed(), Direct(), Indirect(), MCMed(), MCPhi(), Med(), PosteriorPhi(), TestPhi(), TestStable(), Total()
```

```
phi <- matrix(
   data = c(
     -0.357, 0.771, -0.450,
     0.0, -0.511, 0.729,
     0, 0, -0.693
   ),
   nrow = 3
)
colnames(phi) <- rownames(phi) <- c("x", "m", "y")
phi <- MCPhi(
   phi = phi,</pre>
```

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```
vcov_phi_vec = 0.1 * diag(9),
 R = 100L # use a large value for R in actual research
)$output
# Specific time-interval ------
PosteriorMed(
 phi = phi,
 delta_t = 1,
 from = "x",
 to = "y",
 med = "m"
# Range of time-intervals ------
posterior <- PosteriorMed(</pre>
 phi = phi,
 delta_t = 1:30,
 from = "x",
 to = "y",
 med = "m"
# Methods -----
# PosteriorMed has a number of methods including
# print, summary, confint, and plot
print(posterior)
summary(posterior)
confint(posterior, level = 0.95)
plot(posterior)
```

PosteriorPhi

Extract the Posterior Samples of the Drift Matrix

# Description

The function extracts the posterior samples of the drift matrix from a fitted model from the ctsem::ctStanFit() function.

## Usage

```
PosteriorPhi(object)
```

# **Arguments**

object

Object of class ctStanFit. Output of the ctsem::ctStanFit() function.

#### Author(s)

Ivan Jacob Agaloos Pesigan

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#### See Also

```
Other Continuous Time Mediation Functions: DeltaMed(), Direct(), Indirect(), MCMed(), MCPhi(), Med(), PosteriorMed(), TestPhi(), TestStable(), Total()
```

print.ctmeddelta

Print Method for Object of Class ctmeddelta

# **Description**

Print Method for Object of Class ctmeddelta

#### Usage

```
## S3 method for class 'ctmeddelta'
print(x, alpha = 0.05, digits = 4, ...)
```

# Arguments

```
x an object of class ctmeddelta. alpha Numeric vector. Significance level \alpha. digits Integer indicating the number of decimal places to display. . . . further arguments.
```

#### Value

Returns a matrix of time-interval, estimates, standard errors, test statistics, p-values, and confidence intervals.

#### Author(s)

Ivan Jacob Agaloos Pesigan

```
phi <- matrix(
  data = c(
    -0.357, 0.771, -0.450,
    0.0, -0.511, 0.729,
    0, 0, -0.693
  ),
  nrow = 3
)
colnames(phi) <- rownames(phi) <- c("x", "m", "y")
vcov_phi_vec <- matrix(
  data = c(
    0.002704274, -0.001475275, 0.000949122,
    -0.001619422, 0.000885122, -0.000569404,</pre>
```

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```
0.00085493, -0.000465824, 0.000297815,
   -0.001475275, 0.004428442, -0.002642303,
   0.000980573, -0.00271817, 0.001618805,
   -0.000586921, 0.001478421, -0.000871547,
    0.000949122, \ -0.002642303, \ 0.006402668, \\
   -0.000697798, 0.001813471, -0.004043138,
   0.000463086, -0.001120949, 0.002271711,
   -0.001619422, 0.000980573, -0.000697798,
   0.002079286, -0.001152501, 0.000753,
   -0.001528701, 0.000820587, -0.000517524,
   0.000885122, -0.00271817, 0.001813471,
   -0.001152501, 0.00342605, -0.002075005,
   0.000899165, -0.002532849, 0.001475579,
   -0.000569404, 0.001618805, -0.004043138,
   0.000753, -0.002075005, 0.004984032,
   -0.000622255, 0.001634917, -0.003705661,
   0.00085493, -0.000586921, 0.000463086,
   -0.001528701, 0.000899165, -0.000622255,
   0.002060076, -0.001096684, 0.000686386,
   -0.000465824, 0.001478421, -0.001120949,
   0.000820587, -0.002532849, 0.001634917,
   -0.001096684, 0.003328692, -0.001926088,
   0.000297815, -0.000871547, 0.002271711,
   -0.000517524, 0.001475579, -0.003705661,
   0.000686386, -0.001926088, 0.004726235
 ),
 nrow = 9
)
# Specific time-interval ------
delta <- DeltaMed(</pre>
 phi = phi,
 vcov_phi_vec = vcov_phi_vec,
 delta_t = 1,
 from = x^{*},
 to = "y",
 med = "m"
)
print(delta)
# Range of time-intervals ------
delta <- DeltaMed(</pre>
 phi = phi,
 vcov_phi_vec = vcov_phi_vec,
 delta_t = 1:30,
 from = "x",
 to = "y",
 med = "m"
)
print(delta)
```

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print.ctmedeffect

Print Method for Object of Class ctmedeffect

#### **Description**

Print Method for Object of Class ctmedeffect

## Usage

```
## S3 method for class 'ctmedeffect'
print(x, digits = 4, ...)
```

#### **Arguments**

```
x an object of class ctmedeffect.digits Integer indicating the number of decimal places to display.... further arguments.
```

#### Value

Returns the effects.

# Author(s)

Ivan Jacob Agaloos Pesigan

```
phi <- matrix(</pre>
 data = c(
  -0.357, 0.771, -0.450,
  0.0, -0.511, 0.729,
  0, 0, -0.693
 ),
 nrow = 3
)
colnames(phi) \leftarrow rownames(phi) \leftarrow c("x", "m", "y")
delta_t <- 1
# Time-Interval of One ------
## Total Effect ------
total_dt <- Total(</pre>
 phi = phi,
 delta_t = delta_t
print(total_dt)
## Direct Effect ------
```

print.ctmedmc

```
direct_dt <- Direct(</pre>
 phi = phi,
 delta_t = delta_t,
 from = "x",
 to = "y",
 med = "m"
print(direct_dt)
## Indirect Effect ------
indirect_dt <- Indirect(</pre>
 phi = phi,
 delta_t = delta_t,
 from = "x",
 to = "y",
 med = "m"
)
print(indirect_dt)
```

print.ctmedmc

Print Method for Object of Class ctmedmc

# **Description**

Print Method for Object of Class ctmedmc

# Usage

```
## S3 method for class 'ctmedmc'
print(x, alpha = 0.05, digits = 4, ...)
```

# Arguments

x an object of class ctmedmc. alpha Numeric vector. Significance level  $\alpha$ . digits Integer indicating the number of decimal places to display. . . . further arguments.

## Value

Returns a matrix of estimates, standard errors, number of Monte Carlo replications, and confidence intervals.

# Author(s)

Ivan Jacob Agaloos Pesigan

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```
set.seed(42)
phi <- matrix(</pre>
  data = c(
   -0.357, 0.771, -0.450,
   0.0, -0.511, 0.729,
   0, 0, -0.693
  ),
  nrow = 3
)
colnames(phi) <- rownames(phi) <- c("x", "m", "y")</pre>
vcov_phi_vec <- matrix(</pre>
  data = c(
    0.002704274, -0.001475275, 0.000949122,
    -0.001619422, 0.000885122, -0.000569404,
    0.00085493, -0.000465824, 0.000297815,
    -0.001475275, 0.004428442, -0.002642303,
    0.000980573, -0.00271817, 0.001618805,
    -0.000586921, 0.001478421, -0.000871547,
    0.000949122, -0.002642303, 0.006402668,
    -0.000697798, 0.001813471, -0.004043138,
    0.000463086, -0.001120949, 0.002271711,
    -0.001619422, 0.000980573, -0.000697798,
    0.002079286, -0.001152501, 0.000753,
    \hbox{\tt -0.001528701, 0.000820587, -0.000517524,}
    0.000885122, -0.00271817, 0.001813471,
    -0.001152501, 0.00342605, -0.002075005,
    0.000899165, -0.002532849, 0.001475579,
    -0.000569404, 0.001618805, -0.004043138,
    0.000753, -0.002075005, 0.004984032,
    -0.000622255, 0.001634917, -0.003705661,
    0.00085493, -0.000586921, 0.000463086,
    -0.001528701, 0.000899165, -0.000622255,
    0.002060076, -0.001096684, 0.000686386,
    -0.000465824, 0.001478421, -0.001120949,
    0.000820587, -0.002532849, 0.001634917,
    -0.001096684, 0.003328692, -0.001926088,
    0.000297815, -0.000871547, 0.002271711,
    -0.000517524, 0.001475579, -0.003705661,
    0.000686386, -0.001926088, 0.004726235
  ),
  nrow = 9
)
# Specific time-interval ------
mc <- MCMed(</pre>
  phi = phi,
  vcov_phi_vec = vcov_phi_vec,
  delta_t = 1,
  from = "x",
  to = "y",
  med = "m",
```

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```
R = 100L # use a large value for R in actual research
)
print(mc)

# Range of time-intervals ------
mc <- MCMed(
   phi = phi,
   vcov_phi_vec = vcov_phi_vec,
   delta_t = 1:30,
   from = "x",
   to = "y",
   med = "m",
   R = 100L # use a large value for R in actual research
)
print(mc)</pre>
```

print.ctmedmcphi

Print Method for Object of Class ctmedmcphi

# **Description**

Print Method for Object of Class ctmedmcphi

# Usage

```
## S3 method for class 'ctmedmcphi'
print(x, digits = 4, ...)
```

# Arguments

x an object of class ctmedmcphi.

digits Integer indicating the number of decimal places to display.

... further arguments.

#### Value

Returns the structure of the output.

# Author(s)

Ivan Jacob Agaloos Pesigan

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## **Examples**

```
set.seed(42)
phi <- matrix(</pre>
  data = c(
    -0.357, 0.771, -0.450,
    0.0, -0.511, 0.729,
    0, 0, -0.693
  ),
  nrow = 3
)
colnames(phi) \leftarrow rownames(phi) \leftarrow c("x", "m", "y")
mc <- MCPhi(</pre>
  phi = phi,
  vcov_phi_vec = 0.1 * diag(9),
  R = 100L # use a large value for R in actual research
)
print(mc)
```

print.ctmedmed

Print Method for Object of Class ctmedmed

# Description

Print Method for Object of Class ctmedmed

## Usage

```
## S3 method for class 'ctmedmed'
print(x, digits = 4, ...)
```

# Arguments

x an object of class ctmedmed.digits Integer indicating the number of decimal places to display.... further arguments.

# Value

Returns a matrix of effects.

#### Author(s)

Ivan Jacob Agaloos Pesigan

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#### **Examples**

```
phi <- matrix(</pre>
 data = c(
   -0.357, 0.771, -0.450,
   0.0, -0.511, 0.729,
   0, 0, -0.693
 ),
 nrow = 3
colnames(phi) \leftarrow rownames(phi) \leftarrow c("x", "m", "y")
# Specific time-interval ------
med <- Med(</pre>
 phi = phi,
 delta_t = 1,
 from = "x",
 to = "y",
 med = "m"
print(med)
# Range of time-intervals ------
med <- Med(
 phi = phi,
 delta_t = 1:30,
 from = "x",
 to = "y",
 med = "m"
)
print(med)
```

summary.ctmeddelta

Summary Method for an Object of Class ctmeddelta

#### **Description**

Summary Method for an Object of Class ctmeddelta

# Usage

```
## S3 method for class 'ctmeddelta'
summary(object, alpha = 0.05, ...)
```

## Arguments

```
object Object of class ctmeddelta. alpha Numeric vector. Significance level \alpha. . . . additional arguments.
```

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#### Value

Returns a matrix of effects, time-interval, estimates, standard errors, test statistics, p-values, and confidence intervals.

#### Author(s)

Ivan Jacob Agaloos Pesigan

## **Examples**

```
phi <- matrix(</pre>
 data = c(
   -0.357, 0.771, -0.450,
   0.0, -0.511, 0.729,
   0, 0, -0.693
 ),
 nrow = 3
)
colnames(phi) <- rownames(phi) <- c("x", "m", "y")</pre>
vcov_phi_vec <- matrix(</pre>
 data = c(
   0.002704274, -0.001475275, 0.000949122,
    -0.001619422, 0.000885122, -0.000569404,
   0.00085493, -0.000465824, 0.000297815,
   -0.001475275, 0.004428442, -0.002642303,
   0.000980573, -0.00271817, 0.001618805,
   -0.000586921, 0.001478421, -0.000871547,
   0.000949122, -0.002642303, 0.006402668,
    -0.000697798, 0.001813471, -0.004043138,
   0.000463086, -0.001120949, 0.002271711,
    -0.001619422, 0.000980573, -0.000697798,
   0.002079286, -0.001152501, 0.000753,
    -0.001528701, 0.000820587, -0.000517524,
   0.000885122, -0.00271817, 0.001813471,
    -0.001152501, 0.00342605, -0.002075005,
   0.000899165, -0.002532849, 0.001475579,
    -0.000569404, 0.001618805, -0.004043138,
   0.000753, -0.002075005, 0.004984032,
    -0.000622255, 0.001634917, -0.003705661,
   0.00085493, -0.000586921, 0.000463086,
    -0.001528701, 0.000899165, -0.000622255,
   0.002060076, -0.001096684, 0.000686386,
    -0.000465824, 0.001478421, -0.001120949,
   0.000820587, -0.002532849, 0.001634917,
    -0.001096684, 0.003328692, -0.001926088,
   0.000297815, -0.000871547, 0.002271711,
    -0.000517524, 0.001475579, -0.003705661,
   0.000686386, -0.001926088, 0.004726235
 ),
 nrow = 9
)
```

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```
# Specific time-interval -----
delta <- DeltaMed(</pre>
 phi = phi,
 vcov_phi_vec = vcov_phi_vec,
 delta_t = 1,
 from = "x",
 to = "y",
 med = "m"
)
summary(delta)
# Range of time-intervals ------
delta <- DeltaMed(</pre>
 phi = phi,
 vcov_phi_vec = vcov_phi_vec,
 delta_t = 1:30,
 from = "x",
 to = "y",
 med = "m"
)
summary(delta)
```

summary.ctmedmc

Summary Method for an Object of Class ctmedmc

# Description

Summary Method for an Object of Class ctmedmc

## Usage

```
## S3 method for class 'ctmedmc'
summary(object, alpha = 0.05, ...)
```

## **Arguments**

object Object of class ctmedmc.

alpha Numeric vector. Significance level  $\alpha$ .

... additional arguments.

## Value

Returns a matrix of effects, time-interval, estimates, standard errors, test statistics, p-values, and confidence intervals.

#### Author(s)

Ivan Jacob Agaloos Pesigan

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#### **Examples**

```
set.seed(42)
phi <- matrix(</pre>
  data = c(
   -0.357, 0.771, -0.450,
   0.0, -0.511, 0.729,
   0, 0, -0.693
  ),
  nrow = 3
)
colnames(phi) <- rownames(phi) <- c("x", "m", "y")</pre>
vcov_phi_vec <- matrix(</pre>
  data = c(
    0.002704274, -0.001475275, 0.000949122,
    -0.001619422, 0.000885122, -0.000569404,
    0.00085493, -0.000465824, 0.000297815,
    -0.001475275, 0.004428442, -0.002642303,
    0.000980573, -0.00271817, 0.001618805,
    -0.000586921, 0.001478421, -0.000871547,
    0.000949122, -0.002642303, 0.006402668,
    -0.000697798, 0.001813471, -0.004043138,
    0.000463086, -0.001120949, 0.002271711,
    -0.001619422, 0.000980573, -0.000697798,
    0.002079286, -0.001152501, 0.000753,
    \hbox{\tt -0.001528701, 0.000820587, -0.000517524,}
    0.000885122, -0.00271817, 0.001813471,
    -0.001152501, 0.00342605, -0.002075005,
    0.000899165, -0.002532849, 0.001475579,
    -0.000569404, 0.001618805, -0.004043138,
    0.000753, -0.002075005, 0.004984032,
    -0.000622255, 0.001634917, -0.003705661,
    0.00085493, -0.000586921, 0.000463086,
    -0.001528701, 0.000899165, -0.000622255,
    0.002060076, -0.001096684, 0.000686386,
    -0.000465824, 0.001478421, -0.001120949,
    0.000820587, -0.002532849, 0.001634917,
    -0.001096684, 0.003328692, -0.001926088,
    0.000297815, -0.000871547, 0.002271711,
    -0.000517524, 0.001475579, -0.003705661,
    0.000686386, -0.001926088, 0.004726235
  ),
  nrow = 9
)
# Specific time-interval ------
mc <- MCMed(</pre>
  phi = phi,
  vcov_phi_vec = vcov_phi_vec,
  delta_t = 1,
  from = "x",
  to = "y",
  med = "m",
```

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```
R = 100L # use a large value for R in actual research
)
summary(mc)

# Range of time-intervals ------
mc <- MCMed(
   phi = phi,
   vcov_phi_vec = vcov_phi_vec,
   delta_t = 1:30,
   from = "x",
   to = "y",
   med = "m",
   R = 100L # use a large value for R in actual research
)
summary(mc)</pre>
```

summary.ctmedmed

Summary Method for an Object of Class ctmedmed

## **Description**

Summary Method for an Object of Class ctmedmed

# Usage

```
## S3 method for class 'ctmedmed'
summary(object, digits = 4, ...)
```

# Arguments

object an object of class ctmedmed.

digits Integer indicating the number of decimal places to display.

... further arguments.

#### Value

Returns a matrix of effects.

## Author(s)

Ivan Jacob Agaloos Pesigan

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## **Examples**

```
phi <- matrix(</pre>
 data = c(
   -0.357, 0.771, -0.450,
   0.0, -0.511, 0.729,
   0, 0, -0.693
 ),
 nrow = 3
colnames(phi) \leftarrow rownames(phi) \leftarrow c("x", "m", "y")
# Specific time-interval ------
med <- Med(
 phi = phi,
 delta_t = 1,
 from = "x",
 to = v'',
 med = "m"
)
summary(med)
# Range of time-intervals ------
med <- Med(
 phi = phi,
 delta_t = 1:30,
 from = "x",
 to = "y",
 med = "m"
)
summary(med)
```

TestPhi

Test the Drift Matrix

## **Description**

Both have to be true for the function to return TRUE.

- Test that the real part of all eigenvalues of  $\Phi$  is less than zero.
- Test that the diagonal values of  $\Phi$  are between 0 to negative inifinity.

## Usage

```
TestPhi(phi)
```

## **Arguments**

phi

Numeric matrix. The drift matrix  $(\Phi)$ .

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#### Author(s)

Ivan Jacob Agaloos Pesigan

#### See Also

```
Other Continuous Time Mediation Functions: DeltaMed(), Direct(), Indirect(), MCMed(), MCPhi(), Med(), PosteriorMed(), PosteriorPhi(), TestStable(), Total()
```

#### **Examples**

```
phi <- matrix(</pre>
  data = c(
    -0.357, 0.771, -0.450,
    0.0, -0.511, 0.729,
    0, 0, -0.693
  ),
  nrow = 3
colnames(phi) <- rownames(phi) <- c("x", "m", "y")</pre>
TestPhi(phi = phi)
phi <- matrix(</pre>
  data = c(
    -6, 5.5, 0, 0,
    1.25, -2.5, 5.9, -7.3,
    0, 0, -6, 2.5,
    5, 0, 0, -6
  ),
  nrow = 4
)
colnames(phi) <- rownames(phi) <- paste0("y", 1:4)</pre>
TestPhi(phi = phi)
```

TestStable

Test Stability

# Description

The function computes the eigenvalues of the input matrix x. It checks if the real part of all eigenvalues is negative. If all eigenvalues have negative real parts, the system is considered stable.

# Usage

TestStable(x)

## **Arguments**

Χ

Numeric matrix.

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#### Author(s)

Ivan Jacob Agaloos Pesigan

#### See Also

```
Other Continuous Time Mediation Functions: DeltaMed(), Direct(), Indirect(), MCMed(), MCPhi(), Med(), PosteriorMed(), PosteriorPhi(), TestPhi(), Total()
```

# **Examples**

```
x <- matrix(</pre>
  data = c(
    -0.357, 0.771, -0.450,
    0.0, -0.511, 0.729,
    0, 0, -0.693
  ),
  nrow = 3
)
TestStable(x)
x <- matrix(
  data = c(
    -6, 5.5, 0, 0,
    1.25, -2.5, 5.9, -7.3,
    0, 0, -6, 2.5,
    5, 0, 0, -6
  ),
  nrow = 4
)
TestStable(x)
```

Total

Total Effect Matrix Over a Specific Time-Interval

## Description

This function computes the total effects matrix over a specific time-interval  $\Delta t$  using the first-order stochastic differential equation model's drift matrix  $\Phi$ .

## Usage

```
Total(phi, delta_t)
```

#### Arguments

phi Numeric matrix. The drift matrix ( $\Phi$ ). phi should have row and column names pertaining to the variables in the system.

delta\_t Numeric. Time interval ( $\Delta t$ ).

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#### **Details**

The total effect matrix over a specific time-interval  $\Delta t$  is given by

$$Total_{\Delta t} = \exp(\Delta t \mathbf{\Phi})$$

where  $\Phi$  denotes the drift matrix, and  $\Delta t$  the time-interval.

#### **Linear Stochastic Differential Equation Model:**

The measurement model is given by

$$\mathbf{y}_{i,t} = \boldsymbol{\nu} + \boldsymbol{\Lambda} \boldsymbol{\eta}_{i,t} + \boldsymbol{\varepsilon}_{i,t}, \quad \text{with} \quad \boldsymbol{\varepsilon}_{i,t} \sim \mathcal{N}\left(\mathbf{0}, \boldsymbol{\Theta}\right)$$

where  $\mathbf{y}_{i,t}$ ,  $\boldsymbol{\eta}_{i,t}$ , and  $\boldsymbol{\varepsilon}_{i,t}$  are random variables and  $\boldsymbol{\nu}$ ,  $\boldsymbol{\Lambda}$ , and  $\boldsymbol{\Theta}$  are model parameters.  $\mathbf{y}_{i,t}$  represents a vector of observed random variables,  $\boldsymbol{\eta}_{i,t}$  a vector of latent random variables, and  $\boldsymbol{\varepsilon}_{i,t}$  a vector of random measurement errors, at time t and individual i.  $\boldsymbol{\nu}$  denotes a vector of intercepts,  $\boldsymbol{\Lambda}$  a matrix of factor loadings, and  $\boldsymbol{\Theta}$  the covariance matrix of  $\boldsymbol{\varepsilon}$ .

An alternative representation of the measurement error is given by

$$\boldsymbol{\varepsilon}_{i,t} = \boldsymbol{\Theta}^{\frac{1}{2}} \mathbf{z}_{i,t}, \quad \text{with} \quad \mathbf{z}_{i,t} \sim \mathcal{N}\left(\mathbf{0}, \mathbf{I}\right)$$

where  $\mathbf{z}_{i,t}$  is a vector of independent standard normal random variables and  $\left(\Theta^{\frac{1}{2}}\right)\left(\Theta^{\frac{1}{2}}\right)' = \Theta$ . The dynamic structure is given by

$$\mathrm{d}\boldsymbol{\eta}_{i,t} = \left(\boldsymbol{\iota} + \boldsymbol{\Phi}\boldsymbol{\eta}_{i,t}\right) \mathrm{d}t + \boldsymbol{\Sigma}^{\frac{1}{2}} \mathrm{d}\mathbf{W}_{i,t}$$

where  $\iota$  is a term which is unobserved and constant over time,  $\Phi$  is the drift matrix which represents the rate of change of the solution in the absence of any random fluctuations,  $\Sigma$  is the matrix of volatility or randomness in the process, and  $\mathrm{d}W$  is a Wiener process or Brownian motion, which represents random fluctuations.

#### Value

Returns an object of class ctmedeffect which is a list with the following elements:

call Function call.

args Function arguments.

**fun** Function used ("Total").

output The matrix of total effects.

## Author(s)

Ivan Jacob Agaloos Pesigan

#### References

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## See Also

Other Continuous Time Mediation Functions: DeltaMed(), Direct(), Indirect(), MCMed(), MCPhi(), Med(), PosteriorMed(), PosteriorPhi(), TestPhi(), TestStable()

# **Examples**

```
phi <- matrix(</pre>
  data = c(
    -0.357, 0.771, -0.450,
    0.0, -0.511, 0.729,
    0, 0, -0.693
  ),
  nrow = 3
colnames(phi) \leftarrow rownames(phi) \leftarrow c("x", "m", "y")
delta_t <- 1
Total(
  phi = phi,
  delta_t = delta_t
phi <- matrix(</pre>
  data = c(
    -6, 5.5, 0, 0,
    1.25, -2.5, 5.9, -7.3,
    0, 0, -6, 2.5,
    5, 0, 0, -6
  ),
  nrow = 4
colnames(phi) <- rownames(phi) <- paste0("y", 1:4)</pre>
Total(
  phi = phi,
  delta_t = delta_t
)
```

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