

Multiplicative Updates for Nonnegative Quadratic Programming

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Non-negative Quadratic Programming

$$\begin{aligned} \min_v F(v) &= \frac{1}{2} v^T A v + b^T v \\ \text{s.t. } v &\geq 0 \end{aligned} \tag{1}$$

The constraint indicates that the variable v is confined to the non-negative orthant. Assuming that the matrix A is symmetric and positive definite (may have negative elements off the diagonal), so that the objective function $F(v)$ is convex having one global minimum and no local minima in particular.

- ▶ Presenting the multiplicative updates for the basic problem of NQP in eq.(1)
- ▶ Extending the multiplicative updates with upper-bound constraints $v \leq I$

Splitting Matrix A

Expressing the multiplicative updates for NQP in terms of the positive and negative components of the matrix A .

- Positive components of A

$$A_{ij}^+ = \begin{cases} A_{ij} & \text{if } A_{ij} > 0 \\ 0 & \text{otherwise} \end{cases} \quad (2)$$

- Negative components of A

$$A_{ij}^- = \begin{cases} \|A_{ij}\| & \text{if } A_{ij} < 0 \\ 0 & \text{otherwise} \end{cases} \quad (3)$$

It follows that $A = A^+ - A^-$.

Decomposing the Objective Function

- Combination of three terms.

$$F(v) = F_a(v) + F_b(v) - F_c(v) \quad (4)$$

- The first and third terms split the quadratic pieces of $F(v)$ and the second term captures the linear piece:

$$\begin{aligned} F_a(v) &= \frac{1}{2} v^T A^+ v, \\ F_b(v) &= b^T v \\ F_c(v) &= \frac{1}{2} v^T A^- v. \end{aligned} \quad (5)$$

Corresponding Derivatives

- Derivative of $F_a(v)$

$$a_i = \frac{\partial F_a}{\partial v_i} = (A^+ v)_i \quad (6)$$

- Derivative of $F_b(v)$

$$b_i = \frac{\partial F_b}{\partial v_i} \quad (7)$$

- Derivative of $F_c(v)$

$$c_i = \frac{\partial F_c}{\partial v_i} = (A^- v)_i \quad (8)$$

Multiplicative Updates

Expressing the multiplicative updates in terms of partial derivatives

$$v_i \leftarrow \left[\frac{-b_i + \sqrt{b_i^2 + 4a_i c_i}}{2a_i} \right] \quad (9)$$

Note that the partial derivatives a_i and b_i are guaranteed to be non-negative when evaluated the vectors v in the non-negative orthant, so that the optimization remains confined to the feasible region for NQP.

Upper-Bound Constraints

Extending the multiplicative updates in Eq.(9) to incorporate upper-bound constraints of the form $v \leq l$. A sample way of enforcing such constraints is to clip the output of the updates in Eq.(10):

$$v_i \leftarrow \min \left\{ l_i, \left[\frac{-b_i + \sqrt{b_i^2 + 4a_i c_i}}{2a_i} \right] v_i \right\} \quad (10)$$

Analysis of Auxiliary Function

The auxiliary function $G(v, v_t)$ for the objective function in Eq.(1) has two critical properties:

1. $F(v) \leq G(v, v^t)$
2. $F(v) = G(v, v)$

We can derive the update rule $v^{t+1} = \arg \min_v G(v, v^t)$, which never increases the objective function $F(v)$:

$$F(v^{t+1}) \leq G(v^{t+1}, v^t) \leq G(v^t, v^t) \leq F(v^t) \quad (11)$$

Constructing Auxiliary Functions

- ▶ Auxiliary Function for $F_a(v)$

$$G_a(v, v^t) = \frac{1}{2} \sum_i \frac{(A^+ v^t)}{v_i^t} v_i^2 \quad (12)$$

$$F_a(v) \leq G_a(v, v^t) \quad (13)$$

- ▶ Auxiliary Function for $-F_c(v)$

$$G_c(v, v^t) = -\frac{1}{2} \sum_{ij} A_{ij}^- v_i v_j (1 + \log \frac{v_i v_j}{v_i^t v_j^t}) \quad (14)$$

$$-F_c(v) \leq G_c(v, v^t) \quad (15)$$

Combination of two Auxiliary Function

Combining the auxiliary functions $G_a(v, v^t)$ and $G_c(v, v^t)$ to generate the final auxiliary function:

$$\begin{aligned} G(v, v^t) &= G_a(v, v^t) + G_c(v, v^t) + F_b(v) \\ &= \frac{1}{2} \sum_i \frac{(A^+ v^t)_i}{v_i^t} v_i^2 - \frac{1}{2} \sum_{ij} A_{ij}^- v_i^t v_j^t (1 + \log \frac{v_i v_j}{v_i^t v_j^t}) + \sum_i b_i v_i \\ &= \frac{1}{2} \sum_i \frac{(A^+ v^t)_i}{v_i^t} v_i^2 - \sum_i (A^- v^t)_i v_i^t \log \frac{v_i}{v_i^t} \\ &\quad + \sum_i b_i v_i - \frac{1}{2} \sum_{ij} A_{ij}^- v_i^t v_j^t \end{aligned} \tag{16}$$

Then $G(v, v^t)$ is an auxiliary function for $F(v)$ satisfying $F(v) \leq G(v, v^t)$ and $F(v) = g(v, v)$.

Decomposing Auxiliary Function

1. We identify the auxiliary function with

$$G(v, v^t) = \sum_i G_i(v_i) - \frac{1}{2} v^T A^- v \quad (17)$$

$$G_i(v_i) = \frac{1}{2} \frac{(A^+ v)_i}{v_i^t} v_i^2 - (A^- v)_i v_i \log \frac{v_i}{v_i^t} + b_i v_i \quad (18)$$

where $G_i(v_i)$ is a single-variable function of v_i .

2. Note that the minimizer of $G(v, v^t)$ can be easily found by minimizing each $G_i(v_i)$ separately: $v_i = \arg \min_{v_i} G_i(v_i)$.
3. Besides, $G_i(v_i)$ is strictly convex in v_i :

$$G_i''(v_i) = \frac{(A^+ v^t)_i}{v_i^t} + \frac{(A^- v^t)_i}{v_i^2} v_i^t \geq 0. \quad (19)$$

Locality Sensitive Discriminant Analysis(LSDA)

We only consider the problem of mapping all the data points $X = (\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_m)^T$ to a line. Here, we get a set of points $\mathbf{y} = (y_1, y_2, \dots, y_m)^T$.

- ▶ Objective function of within-class graph:

$$\min \sum_{ij} (y_i - y_j)^2 W_{w,ij} \quad (20)$$

- ▶ Objective function of between-class graph:

$$\max \sum_{ij} (y_i - y_j)^2 W_{b,ij} \quad (21)$$

What do we want to do?

Adding sparseness and non-negativity to LSDA and applying them in hashing.

- ▶ Objective function of sparseness:

$$\min \|\mathbf{y}\|_1 \quad (22)$$

- ▶ Constraint C1: $\mathbf{y}^T D_b \mathbf{y} = 1$
- ▶ Constraint C2: $\forall i, y_i \geq 0$

Rewriting the First Objective Function

By simple algebra formulation, the objective function (20) can be reduced to

$$\begin{aligned} & \frac{1}{2} \sum_{ij} (y_i - y_j)^2 W_{w,ij} \\ &= \frac{1}{2} \sum_{ij} (y_i^2 + y_j^2 - 2y_i y_j) W_{w,ij} \\ &= \sum_i y_i^2 W_{w,ij} - \sum_{ij} y_i y_j W_{w,ij} \\ &= y^T D_w y - y^T W_w y \\ &= y^T L_w y \end{aligned} \tag{23}$$

Reorganizing the Expression of the Second Objective Function

Similarly, the objective function (21) can be reduced to

$$\begin{aligned} & \frac{1}{2} \sum_{ij} (y_i - y_j)^2 W_{b,ij} \\ &= \frac{1}{2} \sum_{ij} (y_i^2 + y_j^2 - 2y_i y_j) W_{b,ij} \\ &= \sum_i y_i^2 W_{b,ij} - \sum_{ij} y_i y_j W_{b,ij} \\ &= y^T D_b y - y^T W_b y \end{aligned} \tag{24}$$

Simplifying the Objective Functions above

- ▶ The objective function (20) is equivalent to:

$$\min_y y^T L_w y \quad (25)$$

- ▶ Under the constraint C1, the objective function (21) becomes the following:

$$\min_y y^T W_b y \quad (26)$$

- ▶ And the objective function (22) can be rewritten as follows under the constrain C2:

$$\min_y b y. \quad (27)$$

where b is a row vector with all ones.

Final Objective Function

Combining the objective functions (25),(26),(27) and the constraints together,we get the final objective function:

$$\begin{aligned}\min_y F(y) &= \frac{1}{2}y^T(\alpha L_w + (1 - \alpha)W_b)y + \frac{\eta}{2}(1 - y^T D_b y) + \lambda by \\ &= \frac{1}{2}y^T(\alpha L_w + (1 - \alpha)W_b - \eta D_b)y + \frac{\eta}{2} + \lambda by\end{aligned}\tag{28}$$

Constraint 1: $y \geq 0$

Constraint 2: $0 \leq \alpha \leq 1$

Constraint 3: $\eta \geq 0$

Constraint 4: $\lambda \geq 0$

Extracting and Splitting the Quadratic Parameter of $F(y)$

- ▶ Quadratic Parameter of $F(y)$:

$$A = \alpha L_w + (1 - \alpha)W_b - \eta D_b \quad (29)$$

- ▶ Positive Components of A :

$$A^+ = \alpha D_w + (1 - \alpha)W_b \quad (30)$$

- ▶ Negative Components of A :

$$A^- = \alpha W_w + \eta D_b \quad (31)$$

Decomposing the Objective Function $F(y)$

- ▶ Positive Quadratic Piece of $F(y)$:

$$F_a(y) = \frac{1}{2}y^T A^+ y \quad (32)$$

- ▶ Linear Piece of $F(y)$:

$$F_b(y) = \lambda b y + \frac{\eta}{2} \quad (33)$$

- ▶ Negative Quadratic Piece of $F(y)$:

$$F_c(y) = \frac{1}{2}y^T A^- y \quad (34)$$

Constructing Auxiliary Functions

- ▶ Auxiliary Function for $F_a(y)$:

$$G_a(y, y^t) = \frac{1}{2} \sum_i \frac{(A^+ y^t)_i}{y_i^t} y_i^2 \quad (35)$$

$$F_a(y) \leq G_a(y, y^t) \quad (36)$$

- ▶ Auxiliary Function for $-F_c(y)$:

$$G_c(y) = -\frac{1}{2} \sum_{ij} A_{ij}^- y_i^t y_j^t (1 + \log \frac{y_i y_j}{y_i^t y_j^t}) \quad (37)$$

$$-F_c(y) \leq G_c(y) \quad (38)$$

- Generating Global Auxiliary Function $G(y, y^t)$ for $F(y)$:

$$\begin{aligned}
 G(y, y^t) &= G_a(y, y^t) + G_c(y, y^t) + F_b(y) \\
 &= \frac{1}{2} \sum_i \frac{(A^+ y^t)_i}{y_i^t} y_i^2 - \frac{1}{2} \sum_{ij} A_{ij}^- y_i^t y_j^t (1 + \log \frac{y_i y_j}{y_i^t y_j^t}) \\
 &\quad + \lambda \sum_i y_i + \frac{\eta}{2} \\
 &= \frac{1}{2} \sum_i \frac{(A^+ y^t)_i}{y_i^t} y_i^2 - \sum_i (A^- y^t)_i y_i^t \log \frac{y_i}{y_i^t} - \frac{1}{2} \sum_{ij} A_{ij}^- y_i^t y_j^t \\
 &\quad + \lambda \sum_i y_i + \frac{\eta}{2}
 \end{aligned} \tag{39}$$

- Having the following properties:

$$F(y^{t+1}) \leq G(y^{t+1}, y^t) \leq G(y^t, y^t) = F(y^t) \tag{40}$$

Splitting Auxiliary Function

- ▶ The Auxiliary Function can be reduced to:

$$G(y, y^t) = \sum_i G_i(y_i) - \frac{1}{2} \sum_{ij} A_{ij}^- y_i^t y_j^t + \frac{\eta}{2} \quad (41)$$

- ▶ Picking Up the Single-Variable of y_i from $G(y, y^t)$

$$G_i(y_i) = \frac{1}{2} \frac{(A^+ y^t)_i}{y_i^t} y_i^2 - (A^- y^t)_i y_i^t \log \frac{y_i}{y_i^t} + \lambda y_i \quad (42)$$

First and Second Derivative of $G_i(y_i)$

- ▶ The First Derivative of $G_i(y_i)$:

$$G'_i(y_i) = \frac{(A^+ y^t)_i}{y_i^t} y_i - \frac{(A^- y^t)_i}{y_i^t} y_i + \lambda \quad (43)$$

- ▶ The Second Derivative of $G_i(y_i)$:

$$G''_i(y_i) = \frac{(A^+ y^t)_i}{y_i^t} + \frac{(A^- y^t)_i}{y_i^2} y_i^t \geq 0 \quad (44)$$

So that $G_i(y_i)$ is convex in y_i .

Deriving Update Rule

- ▶ Minimizing each $G_i(y_i)$ separately so as to find the minimizer of $G(y, y^t)$. Simply setting the first derivative of $G_i(y_i)$ to zero:

$$G'_i(y_i) = 0 \implies (A^+ y^t)_i y_i^2 + \lambda y_i^t y_i - (A^- y^t)_i y_i^{t^2} = 0 \quad (45)$$

- ▶ Solving the quadratic formula Eq.(45) to get the update rule:

$$y_i = \frac{-\lambda y_i^t + \sqrt{(\lambda y_i^t)^2 + 4(A^+ y^t)_i (A^- y^t)_i y_i^{t^2}}}{2(A^+ y^t)_i} \quad (46)$$