## Intel Compiler Options and Optimizations

#### SNUG TechTalk

SciNet www.scinet.utoronto.ca University of Toronto Toronto, Canada

December 14, 2011



# Outline

- Compiler
- Optimization
- Other Options
- 4 MKL



### Overview

## Intel® Composer XE 2011 aka (v12.1)

- C (icc)
- C++ (icpc)
- FORTRAN (ifort)
- Threaded Building Blocks (TBB)
- Integrated Performance Primitives (IPP)
- Math Kernel Libraries (MKL)



### **Optimization Levels**

- -O0 disable optimization
- -O1 optimizes for code size
- -O2 optimizes for speed (default)
- -O3 -O2 plus more aggressive optimizations



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#### From the Manual

"The  ${\bf -O3}$  option is particularly recommended for applications that have loops that do many floating-point calculations or process large data sets."



## -O2 Optimizations

- intrinsic inlining
- inlining
- constant propagation
- forward substitution
- routine attribute propagation
- variable address-taken analysis
- dead static function elimination
- removal of unreferenced variables
- constant propagation
- copy propagation
- dead-code elimination
- global register allocation
- global instruction scheduling and control speculation

- loop unrolling
- optimized code selection
- partial redundancy elimination
- strength reduction/induction variable simplification
- variable renaming
- exception handling optimizations
- tail recursions
- peephole optimizations
- structure assignment lowering and optimizations
- dead store elimination



# Optimization Terminology Inlining

## **Inlining**

Replaces the function call with the actual functions code.



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## Original

```
int func(int &x,int &y) { return 4*x+3*y; }
int main(){
  int x=4, y=3;
  int b=fun(x,y)
}
```



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int main(){
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}
```

### Inlined

```
int main(){
  int x=4,y=3;
  int b= 4*x+3*y;
}
```

# Original

```
if ( x < x1 ) {
    a = a0 + a1;
} else if ( x < x2 ) {
    a = a0 - a1;
} else if ( x < x3 ) {
    a = a0 * a1;
} else if ( x < x4 ) {
    a = a0 / a1;
} else {
    a = a0;
}</pre>
```

## Optimizer Approaches

- static branch elimination
- compute all cases and conditions, then pick the correct one
- replace with switch statements, jump tables
- branch re-alignment

### -O3 Additional Optimizations

- Loop Blocking for cache
- Loop Permutation or Interchange
- Loop Distribution
- Loop Fusion
- Loop Unrolling
- Unroll and Jam
- Loop Blocking or Tiling
- Loop Reversal
- Loop Peeling
- Loop Rerolling
- Profile-Guided Loop Unrolling

- Code Replication to eliminate branches
- Memory-access optimizations
- Data Prefetching
- Scalar Replacement
- Partial-Sum Optimization
- Predicate Optimization
- Data Transformation: Malloc Combining and Memset Combining
- Memset and Memcpy Recognition
- Statement Sinking for Creating Perfect Loopnests



# Optimization Terminology Loop Unrolling

```
Original
  for (int x=0; x < 100; x++)
    {
     func(x);
}</pre>
```



# Optimization Terminology Loop Unrolling

```
Original
   for (int x=0; x < 100; x++)
    {
      func(x);
   }</pre>
```

```
Optimized

for (int x = 0; x < 100; x+=5)
    {
     func(x);
     func(x+1);
     func(x+2);
     func(x+3);
     func(x+4);
    }</pre>
```



# Optimization Terminology Loop Collapsing

## Original

```
int a[100][300];
for (int i = 0; i < 300; i++)
  for (int j = 0; j < 100; j++)
    a[j][i] = 0;</pre>
```



# Optimization Terminology Loop Collapsing

## Original

```
int a[100][300];
for (int i = 0; i < 300; i++)
  for (int j = 0; j < 100; j++)
    a[j][i] = 0;</pre>
```

## Optimized

```
int a[100][300];
int *p = &a[0][0];

for (int i = 0; i < 30000; i++)
  *p++ = 0;</pre>
```



# Optimization Terminology Loop Fusion

# Original

```
int x[100], y[100];
for (int i = 0; i < 100; i++)
  x[i] = 1;
for (int i = 0; i < 100; i++)
  y[i] = 2;</pre>
```



# Optimization Terminology Loop Fusion

```
Original

int x[100], y[100];
for (int i = 0; i < 100; i++)
    x[i] = 1;
for (int i = 0; i < 100; i++)
    y[i] = 2;</pre>
```

```
Optimized
  int x[100], y[100];
  for (int i = 0; i < 100; i++)
  {
    x[i] = 1;
    y[i] = 2;
}</pre>
```



# Optimization Terminology Loop Peeling

```
Original
  int p = 10;
  for (int i=0; i<10; ++i)
  {
    y[i] = x[i] + x[p];
    p = i;
}</pre>
```



# Optimization Terminology Loop Peeling

```
Original
  int p = 10;
  for (int i=0; i<10; ++i)
  {
    y[i] = x[i] + x[p];
    p = i;
}</pre>
```

## Optimized

```
y[0] = x[0] + x[10];
for (int i=1; i<10; ++i)
{
   y[i] = x[i] + x[i-1];
}</pre>
```



## System Specific

- -march="cpu" optimize for a specific cpu
- -mtune="cpu" produce code only for a specific cpu
- -msse3,-msse4,-mavx, etc. level of SIMD and vector instructions



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-xHost optimize and tune for the compiling CPU



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#### **GPC** Recommendations

-xHost -O3



# Optimization Terminology Vector Extensions

#### Intel x86\_64 extensions

- Streaming SIMD Extensions (SEE1 SSE4.2)
- AVX

## Original x86

Add two single precision vectors requires four floating-point addition instructions.

```
vec_res.x = v1.x + v2.x;
vec_res.y = v1.y + v2.y;
vec_res.z = v1.z + v2.z;
vec_res.w = v1.w + v2.w;
```



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```

#### **SSE**

A single 128-bit 'packed-add' replaces four scalar addition instructions.

```
movaps xmm0, [v1]; xmm0 = v1.w | v1.z | v1.y | v1.x
addps xmm0, [v2]; xmm0 = v1.w+v2.w | v1.z+v2.z | v1.y+v2.y | v1.x+v2.x
movaps [vec_res], xmm0
```

## Inter Procedural Optimizations (IPO)

- inlining
- constant propagation
- mod/ref analysis
- alias analysis
- forward substitution
- routine key-attribute propagation
- address-taken analysis
- partial dead call elimination
- symbol table data promotion
- common block variable coalescing
- dead function elimination
- unreferenced variable removal

- whole program analysis
- array dimension padding
- common block splitting
- stack frame alignment
- structure splitting and field reordering
- formal parameter alignment analysis
- C++ class hierarchy analysis
- indirect call conversion
- specialization
- Passing arguments in registers to optimize calls and register usage



## Inter Procedural Optimizations

- -ip single file ip optimization
- -ipo multiple file or whole program optimization



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### Profile Guided Optimizations

- -prof-gen instrument code to generate profile
- -prof-use use profile to guide optimization



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## Flank Speed

-fast enables -xHost -O3 -ipo -no-prec-div -static



# Floating Point Math

### -fpmodel

- fast=1 default
- fast=2 most aggressive
- precise value-safe optimizations on intermediate operations
- except strict floating point semantics
- strict disables all "fast-math" options

## If Required

For floating point consistency and reproducibility use:

-fpmodel precise -fpmodel except



# Memory Model

### Seen this error?

relocation truncated to fit: R\_X86\_64\_PC32



# Memory Model

#### Seen this error?

relocation truncated to fit: R\_X86\_64\_PC32

#### -mcmodel=

- **small** code and data restricted to the first 2GB of address space
- medium code restricted to the first 2GB of address space
- large no restrictions



# Intel Math Kernel Library

## MKL Components

- BLAS
- LAPACK
- ScaLAPACK
- FFT
- PBLAS
- BLACS
- plus others



# Intel Math Kernel Library

#### Link Line - MKL 10.3 or less

-lmkl\_intel\_lp64 -lmkl\_sequential -lmkl\_core -lpthread -lm

### Link Line - Composer XE 2011

- -mkl=sequential no-threaded versions (serial)
- -mkl=parallel threaded (openmp)
- -mkl=cluster for ScaLAPACK, FFT, BLACS

#### Link Line Advisor

http://software.intel.com/en-us/articles/intel-mkl-link-line-advisor/



## Documentation

#### Intel Documentation

http://software.intel.com/en-us/articles/intel-parallel-studio-xe-for-linux-documentation/

## Compiler Optimization flags

 $http://software.intel.com/sites/products/collateral/hpc/compilers/compiler\_qrg12.pdf$ 

## White Paper on Floating Point

 $https://support.scinet.utoronto.ca/wiki/images/f/f2/FP\_Consistency.pdf$ 

