noisi inv

The noisi_inv code is an extension of noisi (https://github.com/lermert/noisi). Besides being able to simulate noise cross-correlations and source sensitivity kernels for any noise source distribution and includes an inversion code with other additions to allow for an efficient inversion of secondary microseismic sources. It is a combination of various different codes that were included to automate the entire workflow. Hence, an inversion can be run by only adapting the <code>inversion_config.yml</code> file. In the following, parts of the inversion code will be explained briefly to give a user a slightly better idea of the different aspects of the code.

/noisi_inv

This is the main directory. It contains a tutorial in Jupyter Notebook and script form and the main inversion script with a configuration file. To run the inversion script after changing the inversion_config.yml file on one core, run "python run_inversion.py inversion_config.yml" or multiple cores with "mpirun -np N_CORES python run_inversion.py inversion_config.yml" where N_CORES is the number of cores you want to run it on.

```
- LICENSE
        → Licensing details
 README.md
        → Readme file that gives details about the installation.
 Tutorial_inversion_setup.ipynb
        -> Jupyter notebook with a tutorial on how to setup the
        inversion_config file for the inversion.
 Tutorial_inversion_setup.py
        → Above notebook in script form.
 inversion_config.yml
        → Configuration file for the inversion with various
        different parameters.
 noisi
        → Directory with the code.
 noisi_inv.yml

    Environment file that could be used for installation.

 noisi_inv_doc.docx
        → This file.
 requirements.txt
        → Package requirements for this code.
 run_inversion.py
        → Main inversion script that calls various scripts
        and mostly deals with I/O, copying files, performing the
        inversion, plotting the output and things like that.
 setup.py
        → Script needed to install the package.
```

/noisi_inv/noisi/ants

The ants package is taken from https://github.com/lermert/ants 2 and is used to process and cross-correlate seismic ambient noise data. To avoid the introduction of numerical artefacts we stick to simple processing and stacking of the data. This code was written by Laura Ermert and slightly adapted for noisi_inv. More details about the configuration files and what the parameters do can be found in the documentation of the ants_2.

I	— classes	
I	- corrblock_noisi.py	
	ightarrow class used to correlate and stack data.	
I	- corrtrace_noisi.py	
•	\rightarrow class to deal with correlation I/O and metadata.	
I	L— prepstream_noisi.py	
•	→ class to process the raw data.	
I		
•	> script to make noisi_inv communicate with ants and creat	t.e
	config files that can be used to process and correlation	
	seismic noise data automatically.	•
I	— scripts	
I	- ant_correlation_noisi.py	
•	→ main script that calls classes and functions to creat	t.e
	cross-correlations.	•
I	L— ant_preprocess_noisi.py	
•	→ main script that calls classes and functions to	
	pre-process the raw data.	
I	— tools	
	├── bookkeep.py	
	→ file management for ants.	
	— correlations.py	
	→ functions needed to cross-correlate the data.	
	— data_splitter.py	
	→ not used in noisi_inv.	
	- download_staxml.py	
	→ not used in noisi_inv.	
	— geo.py	
	→ geographical functions.	
	- measurements.py	
	→ different measurements that could be taken on the	he
	correlations.	
	├── plot.py	
	→ Plotting functions.	
	- prepare.py	
	functions to prepare the raw data to be processed.	
	- treatment.py	
	functions to treat the processed data for the	he
	correlating.	
	- util.py	
	→ not used in noisi_inv.	
	- util_noisi.py	
	function to get geographic information from stationx	m 1
	files.	_
	L— windows.py	
	functions to calculate windows for correlations.	

/noisi inv/noisi/borrowed functions

These scripts are necessary to compute the Voronoi cells and surface area. The first script is part of the NSF DIBBS Project "An Infrastructure for Computer Aided Discovery in Geoscience" (PI: V. Pankratius) and NASA AIST Project "Computer-Aided Discovery of Earth Surface Deformation Phenomena" (PI: V. Pankratius). The second one is taken from https://github.com/tylerjereddy/spherical-SA-docker-demo/blob/master/docker-build/demonstration.py

/noisi inv/noisi/mfp

This package uses a Matched Field Processing method which can then be implemented as initial model in a noisi_inv inversion. The standalone package can be found here: https://github.com/jigel/mfp_surf_body. Several parts were adapted to allow for the automatic computation of an MFP model within noisi_inv.

```
mfp_code
       scripts
          create_sourcegrid.py
           > function that takes a config file and creates a source
          grid. Not needed for noisi_inv.
          - create_stat_phase_synthetics.py
           -> script to create synthetic correlations for a stationary
          phase analysis. Not needed for noisi_inv.
          - mfp_main.py
           → main MFP function that creates the noise source maps for
          different measurements.
      ·util
          - plot.py
          → script to plot the noise source maps.
        source_grid_svp.py
           \rightarrow function to create a spatially variable grid.
  mfp_config.yml
           → configuration file
run_mfp.py
           \rightarrow main script used to run the MFP. This is called by
          noisi_inv to create the initial model.
```

/noisi_inv /noisi/my_classes

Classes that are used within noisi inv to deal with the hdf5 files.

/noisi inv /noisi/scripts

This directory contains all the main scripts that are needed to create a new project and forward model cross-correlations and sensitivity kernels for different measurements.

```
├─ adjnt_functs.py
           \rightarrow functions to compute the adjoint sources for several
           different measurements.
- assemble_gradient.py
           \rightarrow function to assemble the gradient, i.e. sum of the
           sensitivity kernels.
  correlation.py
           \rightarrow functions to forward model cross-correlations.
├─ kernel.py
           → functions to compute the source sensitivity kernels.
- measurements.py
           → functions for the difference measurements.
rotate_kernel.py
           > functions to rotate the kernels if a horizontal component
           is involved.
  - run_measurement.py
           \rightarrow functions to take the different measurements on the
           correlations.
- run_sourcesetup.py
           → functions to setup the noise source distribution
- run_wavefieldprep.pv
           → class and functions to pre-compute the wavefield
L— source_grid.py
           → functions to create different source grids
```

/noisi inv /noisi/test

These script are used to test the code. These can be run with the "pytest" command in the terminal.

/noisi_inv /noisi/util

These script contain several functions that are needed to support the main code in the /scripts directory.

├── a	add_metadata.py
	ightarrow function to assign geographic metadata to correlations.
├─ a	ants_crosscorrelate.py
	functions to setup the configuration files for the ants processing and correlating. The parameters for these are
	set in this script.
├ a	auto_data_grid.py
•	function to automatically setup a spatially variable
	grid based on some input data.
├— c	compress_files.py
•	\rightarrow script to convert sac to asdf and npy to h5.
├— c	corr_add_noise.py
•	function to add random noise to synthetic correlations.
├— c	corr_obs_copy.py
	function to copy and select correlations based on a
	signal to noise ratio.
├— c	corr_pairs.py
•	function to define all possible correlation pairs and
	checks which ones already exist.
├ f	filter.py
•	→ different filter functions.
├— a	jeo.py
. 3	→ geographical functions.
├— i	nv_step_test.py
	> script to perform a step length test for the inversion.
├ •	bbspy_mass_download.py
	→ obspy mass downloader to automatically download data for
	certain time ranges and station lists.
├ •	output_copy.py
	copy the output of the inversion into one folder.
├ •	output_plot.py
	→ plot the most important output of the inversion.
⊢ — р	olot.py
1 6	→ plot functions for the source grid.
├— r	otate_horizontal_components.py
	functions to rotate the horizontal components.
├ ─ s	setup_new.py
, –	→ script to setup a new project.
├— s	smoothing.py
, –	functions to spatially smooth the distributions.
L c	source_grid_svp.py
s	→ main code to create a spatially variable grid.
L	syngine_download.py
s	→ script to download a pre-computed wavefield from syngine.
L	vindows.py
w	Tindows.py Tunctions to calculate windows for correlations.
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inversion_config.yml

To perform an inversion, the configuration file has to be adapted. An example of what the different parameters do can be found in the "Tutorial_inversion_setup.ipynb" Jupyter Notebook. Here we will go through all parameters and provide a little more detail.

main:

output_folder: ./noisi_output

→ Path to where project should be saved. Does not have to exist.

stationlist: ./noisi/examples_inv/stationlist_swiss_6.csv

→ Path to a stationlist. This should be a .csv file with columns: net, sta, lat, lon. If not stationlist is given and download_data is true, a stationlist will be created from the available data.

add_metadata: false

 \rightarrow Set this to true if only a forward simulation is being run and the metadata should be added to the cross-correlations files.

add_noise: 1.5

→ This adds random noise to the cross-correlation if not set to 0, 'False', or 'null'. It does this by creating a random time series the same length as the cross-correlation, multiplying it with maximum amplitude of the cross-correlation and the scaling term given here, filtering it with the bandpass filter given for the measurement, and finally adding it to the cross-correlation.

output_plot: true

 \rightarrow Set this to true if the output should be plotted automatically at the end of the inversion.

project_config:

project_name: noisi_inv_example

 \rightarrow Give the project a name.

synt_data: DIS

ightarrow What type of data should the synthetics be? Can be either 'DIS', 'VEL', or 'ACC'.

verbose: false

→ Set this to 'true' if you want print a lot of information.

load_to_memory: true

 \rightarrow This loads the wavefields to memory which can speed up the modelling signficiantly if the memory is large enough to store the wavefield.

compress_output_files: false

→ If set to 'true' this will combine the .sac files into one .asdf file and the .npy files into one .h5 file. If set to 'delete' it will delete the .sac and .npy files after each iteration to save space.

data_download:

→ Parameters to download data within noisi_inv

download_data: true

ightarrow Set this to true if you want to use the implemented obspy mass downloader to download data.

download_data_date: yesterday

 \rightarrow Pick the date for which you want to download data. This can either be 'yesterday' or a date in the format '2022-11-08'.

download_data_days: 1

 \rightarrow Number of days that the data should be downloaded for after the date chosen in download_data_date.

download_data_channels: ['BHZ']

 \rightarrow Channels that should be downloaded. Can include wildcards, i.e. ['*Z','*E','*N'].

process_data_win_len: 7200

 \rightarrow Window length in seconds that the data will be split into for the stacking and correlating.

process_data_overlap: 100

→ Overlap of the above set windows in seconds.

gcmt_exclude: False

 \rightarrow If set to True all windows that include an earthquake in the GCMT catalogue above a magnitude of 5.6 will be excluded.

<u>NOTE</u>: The parameters below will be used if station list is None and download_data is True to create a station list from all the available data within the given domain.

min_station_dist: 0

→ Minimum interstation distance in degrees for

domain_type: circular

 \rightarrow Domain to be used to look for stations and data. One of the following: circular, rectangular, global.

circ_lat_center: 46
circ_lon_center: 8
circ_radius_min: 0
circ_radius_max: 2

 \rightarrow Parameters for a circular domain with the latitude/longitude of the centre, and minimum/maximum radius from the centre.

rect_lat_min: 30
rect_lat_max: 50
rect_lon_min: -10
rect_lon_max: 30

→ Parameters for a rectangular domain with the minimum/maximum latitude and longitude.

inversion_config:

→ Parameters for the inversion

observed_corr: null

 \rightarrow Path to the observed correlations. Set to null if the data is being downloaded here.

opt_statpair: null

> Path to a csv file that contains the optimal station pairs.

snr_thresh: 0

ightarrow Signal-to-noise ratio threshold above which correlations will be used for the inversion. Set to 0 or null to include all correlations.

corr_max_dist: null

ightarrow Maximum distance between station pairs in degrees. Set to null if this should be ignored.

nr_iterations: 1

 \rightarrow Number of iterations for the inversion. Set to 0 if only a forward model should be run.

nr_step_tests: 5

> Number of step tests for each iteration.

step_test_smoothing: false

 \rightarrow Tests if the misfit of the updated model is below the previous misfit. If not, smoothing is reduced in steps of 0.5 degrees.

frac_corr_slt: 1

 \rightarrow Fraction of correlations that is used for the step length test, e.g. 2 means 1/2 of the correlations are used Set to 1 to use all correlations.

step_length_min: 0.05

→ Minimum step length that will be tested.

step_length_max: 3.0

→ Maximum step length that will be tested.

step_smooth: [[2,3],[4,2],[6,1.5],[8,1]]

ightharpoonup list of iterations and smoothing in degrees. [[iteration1,smoothing1],[iteration2,smoothing2],..]. Up to iteration1 (could be iteration number 2 or 3), smoothing1 will be used. Afterwards smoothing2 will be used up to iteration2 etc.

smoothing_cap: 95

 \rightarrow Percentage at which the distribution will be capped when it is being smoothed.

grid_config:

→ Parameters to setup a rectangular grid

grid_dx_in_m: 35000
grid_lat_max: 65
grid_lat_min: 30
grid_lon_max: 25
grid_lon_min: -15

→ Grid point distance in metres and minimum/maximum latitude/longitude. These parameters will be used if the svp_grid parameter below is set to False.

svp_grid_config:

→ Parameters to setup a spatially variable grid.

svp_grid: true

→ Set to true if a spatially variable grid should be used.

svp_dense_antipole: false

 \rightarrow This creates a variable grid which is mirrored at the equator before being rotated to its centre, i.e. the antipole will also have a denser grid.

svp_only_ocean: true

 \rightarrow Set to true if all grid points on land should be removed.

svp_voronoi_area: true

 \rightarrow Set to true if the Voronoi cell surface areas should be calculated. This is necessary to forward model correlations and kernels properly.

svp_station_remove: 1

 \rightarrow Radius in degrees around stations where any grid points will be removed.

svp_plot: false

→ Set to true if the grid should be plotted.

<u>NOTE</u>: The following parameters are lists because multiple values can be given for multiple grids. If this is the case, the

svp_gamma parameters sets the radius around the centre where the new grid will be included.

svp_beta: [7]

 \rightarrow Steepness of the drop from dense to sparse grid. The higher the number, the steeper the grid point distance increase.

svp_gamma: [0]

 \rightarrow Radius in degrees where a new grid will replace the old one. Only necessary if multiple grids are given.

svp_lat_0: [47]

→ Latitude of the spatially variable grid centre.

svp_lon_0: [8]

→ Longitude of the spatially variable grid centre.

svp_phi_min: [2]

→ Minimum grid point distance in degrees.

svp_phi_max: [5]

→ Maximum grid point distance in degrees.

svp_sigma: [10]

ightarrow Radius in degrees around centre where grid point distance is svp_phi_min .

 ${\it NOTE}$: The automatic grid is only recommended for forward modelling of cross-correlations for a given data set, not for inversions. It is best to play around with this in the Jupyter Notebook to see how many grid points there would be.

auto_data_grid_config:

→ These parameters can be set to automatically create a spatially variable grid based on input data.

auto_data_grid: false

→ Set to true if you want an automatic spatially variable grid. auto_data_path: null

 \rightarrow Path to the data the grid should be based on. The data should be a .npy file with latitude, longitude, data.

auto_data_thresh: 0.5

ightarrow Dense grids will be added for data point above this threshold for normalised data.

auto_station_remove: 1

 \rightarrow Radius around stations in degrees where grid is removed.

auto_back_grid_centre: stations

→ Can be either 'data', 'stations', or [longitude, latitude]. Sets the centre of the background grid.

auto_back_grid_phi_min: 2

→ Minimum grid point distance in degrees for the background grid.

auto_back_grid_phi_max: 4

ightarrow Maximum grid point distance in degrees for the background grid.

auto_data_grid_phi: 1

 \rightarrow Grid point distance in degrees of the additional grids that are added to the background grid.

auto_extent: [-90,0,0,90]

→ Area where denser grids will be added.

auto_gamma_thresh: 5

 \rightarrow Radius in degrees of the new denser grids that are added.

wavefield_config:

→ Parameters for the wavefield computation.

wavefield_channel: Z

 \rightarrow Channels that should be modelled. Can be one of 'Z','N', 'E' or a list like ['Z','N'] or 'all'.

wavefield_domain: time

 \rightarrow Domain for the wavefield computation, either time or frequency.

wavefield_duration: 5000.0

→ Duration of the simulation in seconds.

wavefield_filter: null

 \rightarrow Bandpass filter for the wavefield as a list,e.g. [0.01,0.2].

wavefield_path: null

→ Path to the wavefield. If wavefield_type is 'instaseis' this should be a path to an AxiSEM wavefield. If wavefield_type is 'greens' this should be a path to a folder with already precomputed Green's functions.

wavefield_point_force: 1.0e9

 \rightarrow Force of the vertical point source used for the AxiSEM simulations.

wavefield_sampling_rate: 1.0

→ Sampling rate of the wavefield in Hz.

wavefield_type: analytic

ightarrow Wavefield type can either be 'analytic', 'instaseis', or 'greens'.

v: 3000.0 q: 100.0

rho: 3000.0

 \rightarrow If the wavefield_type is 'analytic', set the velocity, attenuation, and density here.

source_config:

 \rightarrow Configuration for the source.

get_auto_corr: false

→ Set to true if autocorrelation should be computed.

model_observed_only: true

→ Set to true if only observed correlations should be modelled.

max_lag: 1500

 \rightarrow Maximum lag of the cross-correlation in seconds. Needs to be less than half of wavefield duration.

diagonals: false

→ NOT IMPLEMENTED.

rotate_horizontal_components: false

 \rightarrow Set to true to rotate horizontal components to Z, R, T.

source_setup_config:

→ Parameters for the source distribution. In theory, multiple distributions can be given.

- distribution: homogeneous

 \rightarrow Distribution type can be one of the following: homogeneous, zero or homogeneous_0, random, ocean, gaussian_blob, mfp or matchedfieldprocessing.

mfp_smooth: 4

 \rightarrow Smoothing parameter in degrees if mfp is chosen as distribution.

center_latlon: [[-50,-20],[0,0]

 \rightarrow Latitude/Longitude of the centres of the gaussian blobs if distribution is gaussian_blob.

sigma_m: [1000000, 1000000]

 \rightarrow Size of the gaussian blobs in metres.

mean_frequency_Hz: 0.15

→ Mean frequency of the distribution.

standard_deviation_Hz: 0.05

 \rightarrow Standard deviation of the frequency spectrum of the distribution.

weight: 1.0

→ Weight of the distribution.

taper_percent: 1.0

→ Taper for the frequency spectrum.

normalize_spectrum_to_unity: true

 \rightarrow Set to true if the frequency spectrum should be normalised.

measr_config:

→ Parameters for the inversion measurement.

mtype: "ln_energy_ratio"

→ Measurement type can be one of the following: ln_energy_ratio, energy_diff, square_envelope, envelope, full_waveform.

taper_perc: 0.01

→ Taper for the bandpass filter.

bandpass: [[0.01,0.2,5]]

 \rightarrow Bandpass filter given is a list with [[freq_min,freq_max,corners]].

weights: [1.0]

→ Weights of the bandpass filter if multiple are given.

g_speed: 2700

 \rightarrow Surface wave speed for the windowed measurements in m/s.

waterlevel_perc: 0

→ NOT IMPLEMENTED ANYMORE.

window_params_wtype: "hann"

 \rightarrow Window type for the measurement can be either 'hann' or 'boxcar'.

window_params_hw: 30

→ Width of the window in seconds.

window_params_hw_variable: 100

→ Parameter for a variable window size in m/s. Creates a window with g_speed - this value - window_params_hw, g_speed + this value + window_params_hw.

window_params_win_overlap: false

 \rightarrow Set to true if the windows are allowed to overlap.

window_params_sep_noise: 0.0

 \rightarrow Seperation between noise and data window to calculate a signal-to-noise ratio.

window_plot_measurements: false

 \rightarrow Set to true if you want to plot the measurement.

ignore_network: false

→ Set to true if the network of the stations should be ignored.