

Specializing Scala with Truffle

by

James You

A thesis
presented to the University of Waterloo
in fulfillment of the
thesis requirement for the degree of
Master of Mathematics
in
Computer Science

Waterloo, Ontario, Canada, 2022

© James You 2022

I hereby declare that I am the sole author of this thesis. This is a true copy of the thesis, including any required final revisions, as accepted by my examiners.

I understand that my thesis may be made electronically available to the public.

Abstract

Scala is a generic object-oriented programming language with higher-order abstractions. Programming abstractions in Scala exemplify reusability and extensibility in the context of type safety. In particular, generic programming allows user-defined data structures to behave identically irrespective of the types of their values while remaining free of type errors.

The implementation of reusability in Scala comes at a cost; The standard implementation of Scala compiles to Java bytecode, where type erasure significantly reduces Scala program type information to create compatible Java bytecode. Consequently, autoboxing, operations needed when using primitive values in a generic context, are unnecessarily introduced into the final program. The current state-of-the-art techniques for eliminating boxing and achieving optimal data representations at runtime, known as specialization, rely on static program analysis. Such techniques must mitigate the problem of code duplication as static optimizations cannot use runtime information to best select which data structures to specialize.

We propose a new approach to the specialization of Scala programs. Our approach integrates type information from a high-level source-like input language with the mechanisms of just-in-time compilation. We propose an ad-hoc specialization mechanism using a whole program approach; Specializations of data structures are created based on concrete type arguments. In our approach, specialized objects are compatible with non-specialized code. We use Truffle, a framework that simplifies the implementation of interpreters and just-in-time compilers, to implement an experimental research prototype.

We demonstrate that our approach is viable and produces improvements in throughput for simplified implementations of real-world Scala programs. While these programs are simple, it is still challenging for state-of-the-art approaches to specialize optimally. We show that our approach can improve performance by an order of magnitude in the context of polymorphic data structures and methods that use bulk storage. We compare the results of our approach to our interpreter without specialization and compiled Scala on GraalVM, a state-of-art Java Virtual Machine.

Acknowledgements

I would like to thank all the little people who made this thesis possible.

Dedication

This is dedicated to the one I love.

Table of Contents

List of Tables	ix
List of Figures	x
Abbreviations	xiv
1 Introduction	1
1.1 Thesis Organization	3
2 Background	4
2.1 Scala	4
2.2 Case Study: A List in Scala	5
2.3 Typed Abstract Syntax Trees	7
2.3.1 Definitions	8
2.3.2 Terms	11
2.3.3 Types and Type Trees	13
2.4 Java Bytecode	14
2.5 Type Erasure	15
2.6 GraalVM	17
2.6.1 Graal	18
2.6.2 Truffle	19

3	Implementation	24
3.1	The Monomorphic Interpreter	24
3.1.1	Converting the <code>DefDef</code> tree into a Truffle <code>RootNode</code>	25
3.1.2	Deriving a <code>Shape</code> from a <code>ClassDef</code>	29
3.1.3	Transforming <code>Terms</code> into <code>Nodes</code>	32
3.2	The Polymorphic Interpreter	45
3.2.1	Specializing Methods	46
3.2.2	Specializing Classes	56
4	Evaluation	64
4.1	Benchmarks	64
4.2	Methodology	66
4.3	Experimental Results	66
4.4	Discussion	70
4.4.1	Inspecting Graal Graphs	70
4.4.2	Mixing in Array Type Information	74
5	Related Work	77
5.1	Implementations of Parametric Polymorphism	77
5.2	Implementations of Reified Types	78
5.3	Generics and Java	79
5.4	Specialization in Scala	79
5.5	Truffle Interpreters	80
6	Future Work	81
7	Conclusions	83
	References	85

APPENDICES	93
A Scala Unified Type System	94
B Scala 3 Compiler Phases	95

List of Tables

List of Figures

2.1	Definition of <code>List</code> class	5
2.2	Implementation of <code>Cons</code> class	6
2.3	Implementation of <code>Nil</code> class	7
2.4	TASTy in the context of the Scala compilation pipeline.	8
2.5	Pseudocode class definitions for a subset of TASTy.	9
2.6	Simplified implementation of the <code>object Nil</code>	9
2.7	Class definition of <code>Cons</code> containing multiple <code>ValDef</code> nodes in a <code>ClassDef</code> .	10
2.8	Tree structure for the definition of <code>List</code> . For brevity, we use <code>_</code> to represent inferred[30] type trees by the compiler.	11
2.9	Pseudocode class definitions for a subset of TASTy trees.	12
2.10	Pseudocode class definitions for a subset of TASTy type trees.	13
2.11	Pseudocode class definitions for a subset of TASTy type trees.	14
2.12	Java bytecode of <code>Cons.contains</code>	15
2.13	<code>Cons</code> class after type erasure	16
2.14	Example of autoboxing introduced for a <code>List</code>	17
2.15	GraalVM overview[33].	18
2.16	Truffle’s approach to self-optimization[46].	19
2.17	Pseudocode for a Truffle node implementation of an equality which supports node rewriting.	20
2.18	Generated code by the Truffle DSL for the <code>AnyEqNode</code>	21
2.19	Implementation of <code>executeAndSpecialize</code> of <code>EqualsNodeGen</code>	22

2.20 Implementation of <code>execute_int_int0</code> of <code>EqualsNodeGen</code>	23
3.1 Pseudocode to evaluate every top level tree.	25
3.2 Pseudocode of a root node.	26
3.3 Defintion of a <code>DefDef</code> tree with names of less important members replaced with <code>_</code>	26
3.4 Simplified implementation of <code>FrameSlotKind</code>	27
3.5 Pseudocode for <code>DefDefNode</code> and <code>Parameter</code>	28
3.6 Pseudocode for parsing <code>DefDef</code> into <code>DefDefNode</code>	28
3.8 Pseudocode to convert a <code>ClassDef</code> into a <code>ClassShape</code>	30
3.9 Pseudocode of the field property.	31
3.10 Pseudocode of a method signature.	31
3.11 Pseudocode of a <code>TermNode</code>	32
3.12 Pseudocode of a <code>NewNode</code> and how it is parsed.	33
3.13 Pseudocode of parsing an <code>Apply</code> tree.	33
3.14 Simplified implementation of the call node with a polymorphic inline cache used in <code>TastyTruffle</code>	35
3.15 A possible polymorphic inline cache for a <code>List.contains</code> callsite.	36
3.16 Pseudocode of field read node with a polymorphic inline cache.	37
3.17 Pseudocode to parse an <code>Ident</code> tree.	38
3.18 Pseudocode of local and global value read nodes.	38
3.19 Pseudocode to parse an <code>Assign</code> tree.	39
3.20 Pseudocode for parsing an <code>If</code> into an <code>IfNode</code>	40
3.21 Pseudocode for a <code>WhileNode</code>	41
3.22 Pseudocode for parsing <code>Block</code> into <code>BlockNode</code>	42
3.23 Pseudocode of the <code>BlockNode</code>	42
3.24 Pseudocode of <code>ReturnException</code> and <code>ReturnNode</code>	43
3.25 TASTy of <code>Cons.contains</code>	44

3.26	<code>Cons.contains</code> as a Truffle AST	44
3.27	An abstract type node.	45
3.28	A <code>TypeNode</code> for handling type references.	45
3.29	Extension to the <code>NewNode</code> for the polymorphic interpreter.	46
3.30	Pseudocode for a <code>DefDefTemplate</code> .	46
3.31	Pseudocode for parsing <code>DefDef</code> into <code>DefDefNode</code>	47
3.32	Extension to parsing a polymorphic <code>Apply</code> tree.	48
3.33	Pseudocode for typed dispatch inside a <code>DefDefTemplate</code> .	49
3.34	The typed dispatch chain for a <code>List.contains</code> call site	51
3.35	Pseudocode for on-demand specialization inside a <code>DefDefTemplate</code> .	52
3.36	Extension to pseudocode that generates frame slots to include polymorphic definitions.	52
3.37		53
3.38	An alternate static constructor that converts an <code>Array[T]</code> to a <code>List[T]</code>	54
3.39	Implementation of <code>array_length</code>	55
3.40	Pseudocode for <code>DefDefNode</code> and <code>Parameter</code>	55
3.41	An example where type arguments are derived from type parameters.	56
3.42	The type node for dynamically resolving method type parameters.	56
3.43	Extensions to specialize a <code>ClassDef</code> .	57
3.44	The type node for dynamically class method type parameters.	58
3.45	The <code>AppliedTypeNode</code> and its derivation from an <code>AppliedType</code> .	58
3.46	Example of creating instance of an applied type.	59
3.47	TastyTruffle IR of creating an instance of an applied type.	59
3.48	Example invocation of <code>Cons.contains[Int]</code>	60
3.50	Extensions to generate a field from a polymorphic value definition.	61
3.51	Extension to parse a <code>DefDef</code> with class type arguments.	62
3.52	Shape of <code>Cons[Int]</code>	63

4.1	Code of the <code>ArrayBuffer</code> benchmark.	65
4.2	Benchmark results for <code>ArrayBuffer.append</code>	66
4.3	Benchmark results for <code>ArrayBuffer.contains</code>	67
4.4	Benchmark results for <code>ArrayBuffer.reverse</code>	68
4.5	Code to swap two elements in an array buffer	68
4.6	Benchmark results for <code>List.append</code>	68
4.7	Benchmark results for <code>List.contains</code>	69
4.8	Benchmark results for <code>List.hashCode</code>	69
4.9	Implementation of the <code>anyHash</code> function.	70
4.10	Graal IR with speculative unboxing of <code>elem</code> based on a type profile of its frame slot in <code>List.contains</code>	71
4.13	Graal IR of <code>array_length</code> in the context of <code>List.apply[T](array: Array[T])</code> augmented with a π node	75
4.14	Graal IR of <code>array_length</code> in the context of <code>List.apply[T](array: Array[T])</code>	76

Abbreviations

AST Abstract Syntax Tree [7](#)

DSL Domain Specific Language [20](#)

IR Intermediate Representation [7](#)

JIT Just-in-time [1](#), [4](#), [17](#), [35](#)

JVM Java Virtual Machine [4](#), [26](#)

TASTy Typed Abstract Syntax Tree [2](#), [4](#), [7](#), [24](#)

Chapter 1

Introduction

The best presents don't come in boxes.

Bill Watterson

[Just-in-time](#) (JIT) compilation has seen great success in implementing runtimes for objected-oriented programming languages. It has effectively generated efficient machine code in the presence of virtual dispatch arising from *subtype* polymorphism[31, 44]. While a call site may statically have many possible call targets, JIT compilation can incorporate dynamic runtime information to optimize the most frequently invoked call targets speculatively. These speculative optimizations often enable compiled code to be inlined, a critical transformation in the context of JIT compilation. Inlining compiled code generates opportunities for many further optimizations.

Many object-oriented languages have since incorporated the notion of generic programming, otherwise known as *parametric* polymorphism. Parametric polymorphism enables programs to be more modular and reusable as functions and data structures behave identically[63] regardless of the types of their inputs. Implementations of generic programming often come at the expense of program complexity and performance. Static compilers for object-oriented languages with parametric polymorphism must compromise when selecting an appropriate data representation for polymorphic data types and functions. This trade-off comes down to more optimal data layouts at the expense of space or uniform data layouts, which are not optimal for every type at the expense of performance.

The selection of an optimal data representation, or *specialization*, of a polymorphic

data structure relies on information typically found in the type-rich source representation of programming languages. Representations must be consistent throughout the whole program as code that manipulates such data structures assume their representations to be consistent. Consequently, the specialization problem is best suited to compilers with access to whole program information during compilation. However, this is not the case for object-oriented languages such as Java and Scala, which statically generate a uniform data representation for their polymorphic definitions to guarantee consistency throughout the whole program. Additionally, static compilers do not have sufficient runtime information, which is critical in making favourable optimization decisions compared to JIT compilers. On the other hand, JIT compilers are ill-suited to whole program optimizations as they are best at the dynamic optimization of small regions of a program[14]. Therefore, the problem of specialization falls between static compilation and JIT compilation.

This thesis introduces TASTYTRUFFLE, an interpreter and JIT compiler which incorporates rich source-level type information with speculative optimizations to specialize data representations for the Scala programming language. TASTYTRUFFLE is implemented in Truffle, a framework that simplifies the implementation of a JIT compiler for a source language by implementing an interpreter for that language. Our source language is the [Typed Abstract Syntax Tree \(TASTy\)](#) serialization format emitted by the Scala 3 compiler. TASTy is an abstract syntax tree format emitted after parsing and type checking Scala programs. By using TASTy, a suitable source language, we can access source-level type information without having to parse and type check a Scala source program.

The contributions of this thesis are as follows:

1. The implementation of an interpreter for the TASTy format using Truffle and the necessary transformations to make a TASTy program executable. TASTy is high-level uncanonical representation of Scala not suitable for execution; Non-trivial transformations must be applied to a TASTy program before execution. In contrast, Java bytecode of compiled Scala programs is readily available for execution on any Java virtual machine.
2. The extension of interpreter to support specialized data representations of generic types. These specialized data representations are created using concrete type arguments that generic types are instantiated with.
3. The evaluation of the interpreter on simple and realistic programs that present a challenge to existing state-of-the-art techniques that interpreter is able to optimize.

1.1 Thesis Organization

We describe the layout of the remainder of this thesis. Chapter 2 provides an overview of the many intermediate representations of Scala from compilation to execution. It explores the advantages and drawbacks of each intermediate representation concerning specialization. Chapter 3 details the implementation of TASTYTRUFFLE. It covers the translation of TASTy into a more suitable IR for execution in an interpreter where each polymorphic data structure has a uniform representation. The chapter then provides extensions to the interpreter to support the just-in-time specialization of polymorphic data structures. Chapter 4 evaluates the interpreter with and without extensions for dynamic specialization on simple but realistic data structures. The chapter provides the performance of these evaluated data structures in the context of the standard implementation of Scala with the underlying JIT compiler of our interpreter without any augmentation. Chapter 5 explores related work in various implementations of parametric polymorphism and other Truffle interpreters. Chapter 6 discusses possible extensions to TASTYTRUFFLE to better integrate source-level type semantics with JIT compilation. Chapter 7 concludes the thesis.

Chapter 2

Background

In this chapter, we will provide an introduction to the Scala programming language. We will showcase a running example that we will use for the remainder of this thesis which exhibits features commonly present in Scala programs. We will describe [Typed Abstract Syntax Tree \(TASTy\)](#), an intermediate storage format used for separate compilation of Scala programs. We will introduce a critical transformation, type erasure, which alters Scala programs so that they may be executable on their default platform, the [Java Virtual Machine \(JVM\)](#). Lastly, We will detail GraalVM [Just-in-time \(JIT\)](#) compiler infrastructure, an alternative JVM implementation that we use to implement a runtime for Scala.

2.1 Scala

Scala[58] is an objected-oriented, generic, and statically typed programming language. Scala uses a *pure* object-oriented programming model[40] and addresses many of the shortcomings[38] in other object-oriented programming languages. Scala can still be considered *Java-like* because of the interoperability between Java and Scala programs. Programs in Scala may contain generic definitions, allowing Scala programs to be composable and reusable[61]. While these features offer abstractions that facilitate the design of increasingly complex programs, their implementation has significant challenges. In the subsequent sections of this chapter, we will describe the challenges of implementing these paradigms when manifested in the various intermediate representations of Scala. We first begin with an explanation of the relevant programming paradigms present in Scala:

Object-oriented Every value in Scala is an object, and every operation is a method

invocation on an object. Every object in Scala is an instance of a *class*, and its class determines its type. Classes[28] are a mechanism for defining state and behaviour for a group of objects.

Generic Classes in Scala may contain *type parameters* and such classes can be considered *polymorphic*[71]. Polymorphic classes may define behaviour independent of their data, allowing them to be extensively reused for multiple data types. In this thesis, we will interchangeably use the term *parametric polymorphism* to refer to generics.

Statically typed Static typing is a discipline where the type information about a program is known *before* it is executed. For a Scala program to compile successfully, it must be *well-typed*. For our purposes, computation should always produce a value that has a type matching the type declared by the programmer to be considered well-typed. Classes are the primary syntactical mechanism for declaring types in Scala. The properties of classes, such as state, in the form of fields, and behaviour, in the form of methods, must be well-typed. Similarly, the uses of these properties in other classes must also be well-typed.

2.2 Case Study: A List in Scala

In this section, we will introduce the running example used for the remainder of this thesis and our motivations for its selection. Figures 2.1, 2.2 and 2.3 contain an abstract singly-linked list class and its two concrete subclass implementations. This set of `List` implementations represent probable real-world use cases as they are a scaled-down and simplified version of the list implementation present in the Scala collections library. The `List` definition from the collections library is available by default to all Scala programs.

```
1 abstract class List[+T] {  
2     def head: T  
3     def tail: List[T]  
4     def length: Int  
5     def isEmpty: Boolean = length == 0  
6     def contains[T1 >: T](elem: T1): Boolean  
7 }
```

Figure 2.1: Definition of `List` class

Figure 2.1 is an example that showcases the paradigms discussed in the previous section that are also commonly present in real-world Scala programs. Implementations which extend the abstract `List` class exhibit the object-oriented property of *inheritance*. The `List` class contains a mixture of polymorphic and non-polymorphic methods to showcase type specialization. The `head` method is class-polymorphic in that its type is derived from a class parameter and becomes specialized when the class is specialized. The `contains` method is method-polymorphic and must be specialized after the class is specialized.

```

1  case class Cons[+T](head: T, tail: List[T]) extends List[T] {
2      override def length: Int = 1 + tail.length
3
4      override def contains[T1 >: T](elem: T1): Boolean = {
5          var these: List[T] = this
6          while (!these.isEmpty)
7              if (these.head == elem) return true
8              else these = these.tail
9          false
10     }
11
12     override def hashCode(): Int = {
13         var these: List[T] = this
14         var hashCode: Int = 0
15         while (!these.isEmpty) {
16             val headHash = these.head.## // Compute hashcode
17             if (these.tail.isEmpty) hashCode = hashCode | headHash
18             else hashCode = hashCode | headHash >> 8
19             these = these.tail
20         }
21         hashCode
22     }
23 }

```

Figure 2.2: Implementation of `Cons` class

Figure 2.2 contains the implementation of a list node. The `Cons` implementation contains two polymorphic fields, `head` and `tail`. For specialization, how the `head` field fits into the storage layout of a `Cons` instance may differ between a `Cons[Int]` and a `Cons[String]`. On the other hand, the storage layout of the `tail` field does not have to change between instances of `Cons[Int]` and `Cons[String]` as they are both reference types.

Figure 2.3 contains the implementation of the empty list. We provide the implementation of this class for completeness.

```
1 case object Nil extends List[Nothing] {  
2   override def head: Nothing = throw new NoSuchElementException("head of empty list")  
3   override def tail: Nothing = throw new UnsupportedOperationException("tail of empty list")  
4   override def length: Int = 0  
5   override def contains[T1 >: Nothing](elem: T1): Boolean = false  
6   override def hashCode(): Int = 0  
7 }
```

Figure 2.3: Implementation of Nil class

2.3 Typed Abstract Syntax Trees

An [Intermediate Representation \(IR\)](#) is a structural abstraction representing a program during compilation or execution. Intermediate representations are more suitable for reasoning about a program than program source code. [IR](#) can be used for compilation[51], optimization[51, 27], or execution[52, 53].

[Typed Abstract Syntax Tree \(TASTy\)](#) is a high-level [Intermediate Representation \(IR\)](#) which is produced and emitted after the type checking phase (also called the typer) of the Scala compiler (see appendix B). Figure 2.4 gives an overview of TASTy generation in the context of the Scala compilation pipeline; note that TASTy is only generated for Scala program sources. TASTy is a well-typed variation of an [Abstract Syntax Tree \(AST\)](#). Abstract syntax trees are a commonly used intermediate representation that resembles the program source representation. TASTy can be considered a *complete* IR of a Scala program before compilation, unlike the other intermediate representations we will examine throughout this thesis. A complete IR is able to capture all information of the original Scala source program. We will expand on why complete intermediate representations are significant in section 2.5.

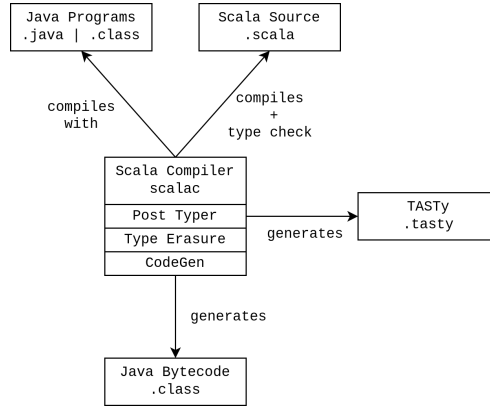


Figure 2.4: TASTy in the context of the Scala compilation pipeline.

The full TASTy IR can represent all Scala programs. The Truffle interpreter in this thesis supports the execution of a subset of TASTy trees sufficient to express the programs given in figures 2.1 and 2.2. The TASTy trees used in this thesis are divided into the following categories: definitions, terms, and types. We give the pseudo implementations of these tree nodes in figures: 2.5, 2.9, and 2.11.

2.3.1 Definitions

A Scala program consists of top-level class definitions, which themselves contain statements. Statements either represent a declaration inside a class, such as method definitions or executable code (or terms), which we discuss in section 2.3.2. Figure 2.5 provides the pseudo implementations of all definitions in our subset of TASTy. Every tree has a symbol, a unique reference to a definition. For the use cases in this thesis, most definitions are translated and represented by a corresponding implementation in Truffle. A **ClassDef** represents a top level class definition. A **DefDef** tree is the definition of a method inside a class definition.

A **ValDef** tree is a context-dependent definition representing different value definition semantics depending on its defined tree. A top level **ValDef**, that is a **ValDef** with no parent, represents the **object** abstraction in Scala. The **object** abstraction is commonly used to represent the *Singleton* pattern[38] or as a class-like interface to define static methods. Consider the **Nil** class given in figure 2.3, a simplified TASTy equivalent is given in figure 2.6

```

1 // Tree representing code written in the source
2 trait Tree {
3   def symbol: Symbol
4 }
5 trait Statement extends Tree // Tree representing a statement in the source code
6 trait Definition extends Statement // Tree representing a definition in the source code.
7
8 // Tree representing a class definition.
9 case class ClassDef(
10   name: String,
11   constructor: DefDef,
12   parents: List[Tree],
13   self: Option[ValDef],
14   body: List[Statement]
15 ) extends Definition
16 // Tree representing a method definition in the source code
17 case class DefDef(
18   name: String,
19   params: List[ParamClause],
20   returnTpt: TypeTree,
21   rhs: Option[Term]
22 ) extends Definition
23 // Tree representing a value definition in the source code.
24 case class ValDef(name: String, tpt: TypeTree, rhs: Option[Term]) extends Definition
25 // Tree representing a type (parameter or member) definition in the source code
26 case class TypeDef(name: String, rhs: Tree) extends Definition

```

Figure 2.5: Pseudocode class definitions for a subset of TASTy.

```

1 val Nil = new Nil$
2 class Nil$ extends List[Nothing] { ... }

```

Figure 2.6: Simplified implementation of the `object Nil`

A `ValDef` tree defined in the `body` of a `ClassDef` tree represent field definitions. A `ValDef` tree defined in the `TermParam` section of a `DefDef` tree represent parameter definitions of the method. A `ValDef` tree defined among the statements in a `Block` tree is a local variable definition limited to the block’s scope. Figure 2.7 shows a brief subset of the class definition tree for the `Cons` class to illustrate the many contexts in which `ValDef` tree nodes may appear.

Similarly, `TypeDef` trees refer to different kinds of definitions depending on their definition site. A `TypeDef` in the `body` of a `ClassDef` refers to a polymorphic class type parameter in our subset of TASTy. When a `TypeDef` is located in the `TypeParam` section

```

1 ClassDef(
2     // name
3     "Cons",
4     ...,
5     // body
6     List(
7         TypeDef("T", TypeBoundsTree(_, _)),
8         ValDef("head0", ...) // field definition
9         ...
10        DefDef(
11            "contains",
12            List(
13                ...,
14                TermParams(ValDef("elem", ...)) // method parameter of Cons.contains
15            ),
16            ...,
17            Block(
18                List(
19                    ValDef("these", ...), // local variable declaration
20                    ...
21                )
22            )
23        )
24    )
25 )

```

Figure 2.7: Class definition of `Cons` containing multiple `ValDef` nodes in a `ClassDef`

a `DefDef` tree, it refers to a polymorphic method type parameter. The trees defined here can be used to represent more complex object-oriented and functional abstractions such as nested classes or closures, but they are beyond the scope of this thesis.

Figure 2.8 is the TASTy structure of the `List` class given in figure 2.1. Recall that `ClassDef` trees have four structural components, the constructor, the list of parent class definitions, the self type, and the body of the definition. In this thesis, we will not discuss the self type as it is an abstraction for composition[19, 26] and is not relevant for execution. The list of parents in a class definition in our subset of TASTy is always a singleton. Note that while the abstract `List` class did not explicitly declare a constructor, the compiler autogenerates and inserts the appropriate constructor implementation before emitting TASTy. Since `List` is polymorphic, it contains an inner type definition of its sole type parameter. This distinction makes TASTy a complete IR compared to the other intermediate representations we will describe later in this chapter.

Similarly, `DefDef` trees also retain their polymorphic properties. The parameters section of a `DefDef` tree is split into two halves. The type parameter section preserves any

```

1 ClassDef(
2     // name
3     "List",
4     // constructor
5     DefDef("<init>", List(TypeParams(TypeDef("T", TypeBoundsTree(_, _)), TermParams(Nil)), _, None)),
6     // parents
7     List(Apply(Select(New(_, "<init>"), Nil))),
8     // self
9     None,
10    // body
11    List(
12        TypeDef("T", TypeBoundsTree(_, _)),
13        DefDef("head", Nil, TypeIdent("T"), None),
14        DefDef("tail", Nil, Applied(TypeIdent("List"), List(TypeIdent("T"))), None),
15        DefDef("length", Nil, TypeIdent("Int"), None),
16        DefDef("isEmpty", Nil, TypeIdent("Boolean"), None),
17        DefDef(
18            "contains",
19            List(
20                TypeParams(TypeDef("T1", TypeBoundsTree(TypeIdent("T"), _))),
21                TermParams(ValDef("elem", TypeIdent("T1"), None))
22            ),
23            TypeIdent("Boolean"),
24            None
25        )
26    )
27 )

```

Figure 2.8: Tree structure for the definition of `List`. For brevity, we use `_` to represent inferred^[30] type trees by the compiler.

polymorphic type parameters in the method definition. The term parameter section contains the normal value parameters found in a method. Term parameters may have types derived from the type parameter section.

2.3.2 Terms

Figure 2.9 gives the implementation for terms in our subset of TASTy. Terms represent executable atoms of code that return values. Terms can be considered analogous to expressions from the abstract syntax trees commonly used for other imperative programming languages. Our term tree subset of TASTy represents a basic language with support for simple imperative programming with control flow constructs such as branching and loops. A basic set of object-oriented features is also encapsulated in the tree definitions above. The set of object-oriented features includes object creation, instance method invocation,

```

1 // Tree representing an expression in the source code
2 trait Term extends Statement {
3   def tpe: Type
4 }
5 // Tree representing a reference to definition
6 trait Ref extends Term
7
8 // Tree representing an assignment lhs = rhs in the source code
9 case class Assign(lhs: Term, rhs: Term) extends Term
10 // Tree representing new in the source code
11 case class New(tpt: TypeTree) extends Term
12 // Tree representing a block `{ ... }` in the source code
13 case class Block(statements: List[Statement], expr: Term) extends Term
14 // Tree representing a while loop
15 case class While(cond: Term, body: Term) extends Term
16 // Tree representing an if/then/else if (...) ... else ... in the source code
17 case class If(cond: Term, thenp: Term, elsep: Term) extends Term
18 // Tree representing a return in the source code
19 case class Return(expr: Term, from: Symbol) extends Term
20 // Tree representing a selection of definition with a given name on a given prefix
21 case class Select(qualifier: Term, selector: String) extends Term
22 // Tree representing an application of arguments.
23 case class Apply(applicator: Term, arguments: List[Term]) extends Term
24 // Tree representing an application of type arguments
25 case class TypeApply(fun: Term, args: List[TypeTree]) extends Term
26 // Tree representing a reference to definition with a given name
27 case class Ident(name: String) extends Ref
28 // Tree representing constant value
29 case class Constant(value: Int | ... | String) extends Term

```

Figure 2.9: Pseudocode class definitions for a subset of TASTy trees.

and instance field access. This subset of TASTY is sufficient to represent the creation of polymorphic classes as well as the invocation of polymorphic methods to showcase the examples described in this thesis.

Terms in TASTy also retain their types after type checking by the Scala compiler. A type for a term describes the type of value produced by the term. Terms with no children, such as `Ident` trees, are *explicit* typed. Childrenless terms have their type information encoded in a TASTy file. For terms with children, their types are derived from those of their children’s trees. Type information for non-leaf term trees is regenerated from term leaves when a TASTy file is read. In essence, types ‘flow’ upwards from leaf nodes in TASTy to their parent terms until the root term. The interpreter described in this thesis interprets a tree where the types of all trees are regenerated. We will describe types in detail in the following section.

2.3.3 Types and Type Trees

TASTy encodes Scala programs with two kinds of type information, type trees and types. Type trees are a subset of trees which represent types as they are declared in Scala source code. On the other hand, types are the canonical representation of type trees after type checking in the Scala compiler. Multiple type trees may denote the same underlying type.

```
1 // Type tree representing a type written in the source
2 trait TypeTree extends Tree {
3   def tpe: Type
4 }
5
6 // Type tree representing a reference to definition with a given name
7 case class TypeIdent(name: String) extends TypeTree
8 // Type tree representing a type application
9 case class Applied(tpt: TypeTree, args: List[TypeTree | TypeBoundsTree]) extends TypeTree
10 // Type tree representing a type bound written in the source
11 case class TypeBoundsTree(lo: TypeTree, hi: TypeTree) extends TypeTree
```

Figure 2.10: Pseudocode class definitions for a subset of TASTy type trees.

Figure 2.10 gives the subset of type trees we will use in this thesis. For our purposes, there are only three ways to refer to types. A `TypeIdent` type tree is a reference to a type which is a `ClassDef`. An `Applied` type tree represents a type constructor, which accepts type arguments and produces a new type. For example, the type `Cons[T]` would be represented as an applied type tree, where `Cons` is the constructor and `T` is the type argument. A `TypeBounds` tree represents the type expression `Lo <: T <: Hi`, a constraint where `T` must be a subtype of type `Hi` and supertype of type `Lo`. Type bounds are typically used to represent declared type parameter constraints, otherwise known as *bounded quantification*[21], in polymorphic classes or polymorphic methods. However, the `Typer` also inserts type bounds because type parameters in TASTy are universally constrained. A type parameter `T` is expanded to `Nothing <: T <: Any`, that is the type parameter `T` must be a subtype of `Any` and a supertype of `Nothing`. In the context of this thesis, we can use subtype to mean *subclass of* and supertype to mean *superclass of*. Practically, this means the type parameter `T` has no constraints since `Any` is the supertype of all types and `Nothing` is the subtype of all types.

Figure 2.11 is set of types used in our subset of TASTy. In most cases in our subset of TASTy, the type trees have a corresponding type of the same name. However, the `NamedType` does not appear in type trees as they are predominantly used to type terms. The `TypeRef` type is a reference to a `ClassDef` tree or a type parameter `TypeDef`.

```

1 trait Type // A type, type constructors, type bounds
2 trait NamedType extends Type // Type of a reference to a type or term symbol
3 case class TypeRef extends NamedType // Type of a reference to a type symbol
4 case class AppliedType extends Type // A higher kinded type applied to some types T[U]
5 case class TypeBounds extends Type // Type bounds

```

Figure 2.11: Pseudocode class definitions for a subset of TASTy type trees.

In the Scala compilation pipeline, TASTy is eventually simplified and transformed by the Scala compiler to produce Java bytecode. In Chapter 3, We will review each tree before such transformations and their relevance for execution in our interpreter.

2.4 Java Bytecode

Java bytecode is a portable and compact, intermediate language and instruction set used by the Java Virtual Machine to execute programs. Java bytecode is similar to an assembly language, where programs are represented as sequences of atomic instructions that manipulate a stack or registers. The type system in Java bytecode can describe primitive values such as `int` and references to objects such as `String`. As bytecode is intended to be simple for execution, it is impossible to represent polymorphic programs entirely in Java bytecode.

Types in TASTy are not immediately compatible with types available in Java bytecode. Scala’s type semantics must be eliminated from programs by the compiler before emitting the Java bytecode of the program. The resulting Java bytecode is considered an *incomplete* IR of Scala source programs, as the type information found in the program source or inferred from the compilation is no longer present. This deficiency is a drawback for executing Scala programs on the JVM because speculative optimizations cannot incorporate source-level semantics.

Figure 2.12 contains the Java bytecode of the `contains` defined at line 4 in figure 2.2. Typical control flow elements of Scala programs, such as if terms and while terms have been converted into branch or jump instructions. Notice that there are no polymorphic type parameters in the description of classes nor the invocation of polymorphic methods present in the bytecode. In particular, notice the equality comparison in line 7 of figure 2.2 is actually a method invocation (instruction 14 in figure 2.12). As the Scala compiler is unable to determine the type of a polymorphic type parameter during compilation time, it is unable

```

1  aload_0
2  astore_2
3  aload_2
4  invokevirtual #44 // List.isEmpty():Z
5  ifne        30
6  aload_2
7  invokevirtual #46 // List.head():Ljava/lang/Object;
8  aload_1
9  invokestatic #52 // Method scala/runtime/BoxesRunTime.equals:(Ljava/lang/Object;Ljava/lang/Object;)Z
10 ifeq        22
11 iconst_1
12 ireturn
13 aload_2
14 invokevirtual #53 // List.tail():LList;
15 astore_2
16 goto       2
17 iconst_0
18 ireturn

```

Figure 2.12: Java bytecode of `Cons.contains`

to select a Java bytecode instruction that implements polymorphic comparison. Instead, a bridge method part of the Scala standard library is responsible for handling polymorphic operations which operate on both reference and primitive types during runtime. In the next section, we describe the process that transforms Scala programs to a representation amenable to Java bytecode generation and the additional runtime overhead associated with this transformation.

2.5 Type Erasure

Type erasure^[57] is a transformation that converts polymorphic classes and methods in Scala to monomorphic classes and methods. This conversion is necessary because the JVM does not support polymorphic classes during runtime. Erasure ensures that any given polymorphic class and method has a single representation in practice. Type erasure is a crucial part of Scala compilation that renders the JVM bytecode generated from TASTy incomplete. Figure 2.13 shows the `Cons` class after type erasure.

The polymorphic `Cons` class has all type parameters in its class definition *erased* and replaced by the `Any` type. The `Any` type is a Scala platform-independent^[58] abstract type representing the supertype of primitive and reference types. In Java bytecode, the `Any` type is compiled to the `Object` type, the supertype of all reference types on the JVM.

```

1 case class Cons(head: Any, tail: List) extends List {
2     override def length: Int = 1 + tail.length
3
4     override def contains(elem: Any): Boolean = {
5         var these: List = this
6         while (!these.isEmpty)
7             if (these.head == elem) return true
8         else these = these.tail
9         false
10    }
11
12    override def hashCode(): Int = {
13        var these: List = this
14        var hashCode: Int = 0
15        while (!these.isEmpty) {
16            val headHash = these.head.##
17            if (these.tail.isEmpty) hashCode |= headHash
18            else hashCode |= headHash >> 8
19            these = these.tail
20        }
21        hashCode
22    }
23 }

```

Figure 2.13: Cons class after type erasure

While type erasure simplifies classes for runtime, the Scala compiler must resolve the incompatibility of operations between primitive types and reference types on the JVM[52]. In order for primitive types to have a uniform representation compatible with reference types, primitive types are encapsulated into corresponding boxed classes whose objects are passed by reference. For example, `java.lang.Integer` is a class with an `Int` field. In a polymorphic context in which a type variable is replaced by the reference type `Object`, an `Int` value is not passed directly but by reference to an object of class `Integer` that contains the primitive value. *autoboxing*[1] is the set of operations introduced by the compiler whenever a primitive value is accessed under a polymorphic context. Autoboxing can be divided into two operations. *Boxing* occurs when a primitive value must be used where a polymorphic value is expected. *Unboxing* occurs when a polymorphic value must be used where a primitive value is expected. Figure 2.14 shows a simple example of inserted autoboxing operations using the polymorphic `Cons` class after type erasure.

The `head0` field inside the `Cons` class after erasure is no longer polymorphic and instead has the type `Any`. The integer value `1` is passed into the `Cons` class is boxed, and the primitive value is wrapped as an instance of its boxed class. Similarly, when the `head0` field of the instance is read and stored into a local variable, an unboxing operation ex-

```
1 // Before type erasure
2 val lst: List[Int] = Cons(1, Nil)
3 val head: Int = lst.head
4 // After type erasure
5 val lst: List = Cons(box(1), Nil)
6 val head: Int = unbox(lst.head)
```

Figure 2.14: Example of autoboxing introduced for a `List`

tracts the primitive value out of its wrapper instance. In the Scala collections library, a set of commonly used polymorphic data structures, autoboxing operations are frequent and necessary. The computational overheads of autoboxing operations on programs that make substantial use of polymorphic collections, especially the Scala standard library, are significant[64]. Eliminating this overhead through optimizing autoboxing operations is one of the central goals of this thesis. In addition to this direct overhead, autoboxing is a significant indirect overhead that makes analyzing programs using primitive values difficult. As a result, autoboxing inhibits many significant compiler optimizations.

2.6 GraalVM

GraalVM[79] is an implementation of a JVM. Traditionally, the JVM is responsible for most of the performance optimizations in Java programs[62] through **Just-in-time (JIT)** compilation. JIT compilation is an adaptive optimization that occurs during program execution. JIT compilation is concerned with optimizing and eliminating *hotspots* or portions of the program executed most frequently. JIT compilers[37, 6] employ a range of *speculative* techniques to transform the program under optimization. Speculative optimizations use information collected during program execution, otherwise known as *profiling*. Assumptions are made from collected profiling data in order to generate high-performance native machine code. A key aspect of speculative optimizations using assumptions is that optimizations may be undone when their underlying assumptions are violated; This enables the JIT compiler to optimize programs without the need to prove assumptions hold in every execution path from a static perspective.

While other implementations of Java virtual machines were designed specifically for Java, GraalVM was designed from the onset to be *language-independent*. GraalVM can be divided into two primary components of interest. The first is *Graal*, a language-agnostic JIT compilation infrastructure that handles speculative optimizations and the generation

of high-performance machine code. The second is *Truffle*, a framework for translating the semantics of a source language, also called a *guest language*, to take advantage of the Graal infrastructure.

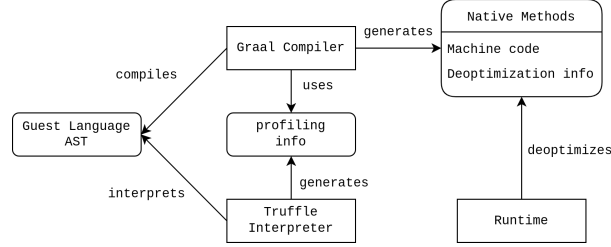


Figure 2.15: GraalVM overview[33].

This thesis makes substantial of both components of GraalVM to create a runtime for Scala programs using TASTy. The runtime is able to incorporate source level information for speculative optimizations.

2.6.1 Graal

GraalVM incorporates an existing implementation of a JVM[62] for the actual execution of programs. Graal is *only* the general-purpose just-in-time compilation infrastructure which optimizes the programs to be executed. Graal is general-purpose in that it conducts analysis and optimization on the same intermediate representation, *Graal IR*, regardless of the source language. Notably, most implementations of a source language utilizing GraalVM have an implementation in Truffle; Java is an exceptional case. In addition to a Truffle interpreter for Java bytecode[41], there is a direct translator for Java programs in GraalVM that parses Java bytecode into Graal IR.

Graal IR[33] is an IR suitable for speculative optimizations while still retaining information from the Truffle guest language AST. Graal IR is based on the *sea of nodes* concept[25] and satisfies the *static single-assignment*[27] property. A sea of nodes is an abstraction based on a directed graph structure that relates the control flow graph[11] of a program to its data flow graph[10]. An intermediate representation is in single-static assignment form when each variable is declared once, and every use of a variable occurs immediately after its declaration[47].

GraalIR enables Graal to speculatively compile only the *hot* branches[34], or branches that are most frequently taken in the control flow portion of the IR and their transitive data

dependencies. When a compiled program violates any underlying assumptions, execution is *deoptimized*[45] and the program resumes execution in the interpreter. Deoptimization occurs when the compiled program is no longer considered stable and valid. Graal automatically inserts *guard nodes* into the IR, which are conditional checks which validate that speculative assumptions used to compile the program still hold. Deoptimization is part of an execution loop between Graal and Truffle, which allows GraalVM to adapt aggressively and speculate to find the best optimization in a dynamic execution environment.

2.6.2 Truffle

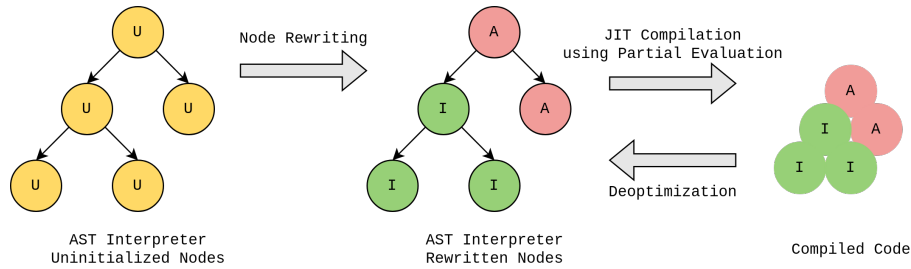


Figure 2.16: Truffle’s approach to self-optimization[46].

Truffle is a framework for implementing an interpreter embedded into GraalVM. Truffle differs significantly from other implementations of interpreters. Interpreters can usually be divided into two subsets: tree interpreters and bytecode interpreters. Tree interpreters transform the program source into an abstract syntax tree. Trees are executed in post-order; children nodes are executed before their parents. Abstract syntax tree interpretation has the added benefit of executing an intermediate representation close to the program source representation and is, therefore, more amenable to program optimization. In contrast, bytecode interpreters, such as the JVM, execute a vastly simplified representation of programs. While interpreters of bytecode programs tend to be faster than their tree counterparts, the absence of detailed source information, such as types, often makes program optimization difficult. The problem of efficiently executing bytecode while retaining the ability to optimize them effectively using source program information is difficult for Scala on the JVM.

Truffle is an atypical tree interpreter in that it combines the definition, execution, and optimization of an abstract syntax tree structure into a single abstraction. While the structure of input programs in other interpreters is independent of the implementation of the interpreter, a Truffle interpreter is integrated into the structure of its input. More

concretely, this means an implementation of a Truffle interpreter is a collection of subclasses that extend `Node` class and implement a `execute()` method. An interpreter is derived from implementing its input tree structure by defining execution semantics inside the abstract syntax tree to be executed.

```
1 abstract class EqualsNode extends BinaryOpNode {
2     @Specialization
3     def equalsInt(lhs: Int, rhs: Int): Boolean = lhs == rhs
4
5     @Specialization
6     def equals(lhs: Any, rhs: Any): Boolean = if (lhs == null) rhs == null else lhs.equals(rhs)
7 }
```

Figure 2.17: Pseudocode for a Truffle node implementation of an equality which supports node rewriting.

During the execution of the AST, profiling information collected from the interpreter is used to drive *node rewriting* and just-in-time compilation. While Graal is language-agnostic, Truffle is able to exploit guest language semantics for dynamic optimizations. This process of replacing nodes in the AST with better, specialized guest language counterparts in Truffle is called node rewriting. Node rewriting makes Truffle abstract syntax trees self-optimizing and serves two purposes. The first is to incorporate guest language semantics into the executing program dynamically. The second is to augment the AST for more efficient JIT compilation. The nature of compiler optimizations requires that programs are incrementally simplified in order to be optimized. While such types of optimizations are widely applicable to many languages using the JVM, node rewriting is a high-level language-specific optimization that occurs *before* such simplifications.

The self-optimizing execution semantics of the AST are implemented with the Truffle [Domain Specific Language \(DSL\)](#). The Truffle DSL is a mechanism to allow a *guest language* to integrate semantics into a Truffle AST for self-optimization. A guest language is a set of semantics, most commonly a programming language, encoded into a Truffle AST. In this thesis, the guest language that our Truffle AST encodes and executes is TASTy (which represents Scala).

Figure 2.17 demonstrates an example of the node that supports rewriting declared using the Truffle DSL. The node declares semantics of the equality operation between integers and values of type `Any`. This equality node has semantics for every type because the `Any` type is the supertype of all types in Scala. A Truffle node that supports node rewriting begins in an uninitialized state. When both the left and right-hand side operands are integers,

```

1  @GeneratedBy(EqualsNode.class)
2  public final class EqualsNodeGen extends EqualsNode {
3      @Child
4      private TermNode lhs_;
5      @Child
6      private TermNode rhs_;
7      @CompilationFinal
8      private int current_state;
9
10     private EqualsNodeGen(TermNode lhs, TermNode rhs) {
11         this.lhs_ = lhs;
12         this.rhs_ = rhs;
13     }
14
15     public Object execute(VirtualFrame frame) {
16         int state = this.current_state;
17         return (state & 2) == 0 && state != 0 ?
18             this.execute_int_int0(state, frame) :
19             this.execute_generic1(state, frame);
20     }
21
22     private Object execute_generic1(int state, VirtualFrame frame) {
23         Object lhs = this.lhs_.execute(frame);
24         Object rhs = this.rhs_.execute(frame);
25         if ((state & 1) != 0 && lhs instanceof Integer)
26             if (rhs instanceof Integer)
27                 return this.executeInt((Integer) lhs, (Integer) rhs);
28
29         if ((state & 2) != 0) {
30             return this.executeObject(lhs, rhs);
31         } else {
32             CompilerDirectives.transferToInterpreterAndInvalidate();
33             return this.executeAndSpecialize(lhs, rhs);
34         }
35     }
36 }

```

Figure 2.18: Generated code by the Truffle DSL for the `AnyEqNode`.

the node is rewritten to `equalsInt` state. When arguments of any other combination of types are detected, either in the uninitialized state or the `equalsInt` state, the node is rewritten to the `equals` state.

Figure 2.18 gives the auto-generated Java program that implements the semantics defined in 2.17. We will not discuss the semantics of every possible state in our generated node for brevity. Instead, we will discuss the possible state transitions when a node starts in the uninitialized state. State transitions are encoded as methods that execute the semantics for a given state, and update said state. States are encoded as bit fields. The uninitialized

state is the 0 value with no states encoded. The `equalsInt` state is encoded with 1 and the `equals` state is encoded with 2. `execute_generic1` is invoked when no states (specializations) are active in a `EqualsNode`. The first state transition checks whether the node is in one of two possible states (`equalsInt` or `equals`). The corresponding specialization is invoked if the node is in either state and its arguments satisfy the preconditions. This portion of the node may exist in either interpreted or compiled code. However, if the node is not initialized, i.e., it is in neither possible state, the code is deoptimized (if compiled), and execution resumes from the interpreter.

The `executeAndSpecialize` method (figure 2.19) initializes the node to a specialized state. If both arguments satisfy the `Int` type check invariant, the node is initialized to the `equalsInt` state. Otherwise, it is initialized to the `equals` state. Subsequent executions of the newly initialized node will invoke the appropriate specialization as long as their respective invariants are maintained. Node rewriting narrows down a node's best implementation(s) for a particular profile of values. If a Truffle AST cannot be rewritten further, it is considered *stable*. Stable nodes vastly simplify JIT compilation because of partial evaluation, a critical transformation applied to ASTs for JIT compilation that we will describe next.

```

1 private boolean executeAndSpecialize(Object lhs, Object rhs) {
2     int prev_state = this.state_0_;
3     if (lhs instanceof Integer)
4         if (rhs instanceof Integer) {
5             this.current_state = prev_state | 1;
6             return this.equalsInt((Integer) lhs, (Integer) rhs);
7         }
8
9     this.current_state = prev_state | 2;
10    return this.equals(lhs, rhs);
11 }

```

Figure 2.19: Implementation of `executeAndSpecialize` of `EqualsNodeGen`

When invocations of a root node exceed a limit, Graal JIT compiles its children trees into native machine code using *partial evaluation*. Partial evaluation is a program optimization technique for specializing a program (code) for a given input (data)[36]. In the context of Truffle, this means specializing an AST node (code) based on the values (or types of values) produced by their children nodes (data)[77]. We can say that the partial evaluation of an AST will produce an AST which is *specialized* for a particular set of values, or more commonly, in our case, a particular set of types.

For example, consider the partial evaluation of a `EqualsNodeGen` node in the `equalsInt` state. The `current_state` field of the node is annotated with the `CompilationFinal` directive. Truffle provides the `CompilationFinal` directive to indicate that a value that may not be a constant in the guest language implementation *will* be a constant when being partially evaluated. Because the state is a compilation constant, the condition on line 17 of figure 2.18 evaluates to `true` when the state is 1 (`equalsInt`). As a result, only the code for `execute_int_int0` (provided in 2.20) will be compiled. The generated implementation of `execute_int0_int0` contains checks for the specialization invariant. These checks act as points in the control flow of the compiled code to deoptimize if these invariants are violated. The resulting code supplied to JIT compilation is the specialization of the `EqualsNode` for the `equalsInt` state.

```

1 private Object execute_int_int0(int state, VirtualFrame frame) {
2     int lhs_int;
3     try {
4         lhs_int = this.lhs_.executeInt(frame);
5     } catch (UnexpectedResultException ex) {
6         Object rhs = this.rhs_.execute(frame);
7         return this.executeAndSpecialize(ex.getResult(), rhs);
8     }
9
10    int rhs_int;
11    try {
12        rhs_int = this.rhs_.executeInt(frame);
13    } catch (UnexpectedResultException ex) {
14        return this.executeAndSpecialize(lhs_int, ex.getResult());
15    }
16
17    assert (state & 1) != 0;
18    return this.executeInt(lhs_int, rhs_int);
19 }

```

Figure 2.20: Implementation of `execute_int_int0` of `EqualsNodeGen`

The sequence of optimizations given in figure 2.16, node rewriting, partial evaluation into machine code, and deoptimization is the advantage that a TASTy Truffle interpreter has over the traditional JVM bytecode interpreter for Scala. Truffle allows for the incorporation of source-level type information into the just-in-time compilation loop. This thesis will focus on using these features in executing TASTy with type information to augment JIT compilation.

Chapter 3

Implementation

This chapter is divided into two halves which detail the implementation of a Truffle interpreter and extensions for parametric polymorphism. The first half of this chapter will describe the methods used to transform TASTy to make it suitable for a Truffle interpreter, TASTyTRUFFLE, *without* polymorphism. In particular, the first section covers how to translate the organization of data and code in the `DefDef`, `ClassDef`, and `Term` tree nodes into a Truffle implementation which is amenable to execution and JIT optimization. The second half of this chapter will then discuss extensions to our implementation to support parametric polymorphism and cover the techniques we use to specialize nodes to eliminate autoboxing in the presence of polymorphism.

3.1 The Monomorphic Interpreter

Scala programs in TASTy format are unsuitable for execution in a Truffle interpreter. Programs in TASTy must be parsed and transformed into an executable representation in Truffle. These transformations translate the TASTy tree structure into a more straightforward but semantically equivalent Truffle AST. For the rest of this thesis, we refer to the Truffle AST of TASTy as *TastyTruffle IR*. As TASTy represents a Scala program close to its equivalent source representation, canonicalization compiler passes (see appendix B) that would otherwise normalize the IR are not present. Instead, we implement TastyTruffle IR to represent a canonicalized executable intermediate representation which can later be specialized on demand.

Figure 3.1 gives an evaluation loop typical in other interpreters in the context of this one. A top-level tree is any tree without a parent. In our subset of TASTy, a top level tree

```

1 def parseTopLevel(tree: Tree): Object = tree match {
2   case vdef: ValDef =>
3     lazy val obj = initializeObject(vdef)
4     registerObject(vdef.symbol, obj)
5   case cdef: ClassDef =>
6     registerShape(cdef.tpe, parseClassDef(cdef))
7   case _ => ()
8 }

```

Figure 3.1: Pseudocode to evaluate every top level tree.

may be a `ValDef` (a singleton object) or a `ClassDef`. Here we only present the pseudocode sufficient to traverse a program in TASTy. Each top-level definition is parsed and saved in a global interpreter context (`registerShape` and `registerObject`). Top-level objects are lazily initialized as their class definitions may not have been parsed. Registered objects and classes are then used in subsequent executions of the program.

We omit details on *how* to execute the program to be concise. Entry points in TASTy are defined by a special method `main`. As multiple entry points may exist in a given program, we consider the selection of entry points as an implementation-specific detail. In the following sections, we will describe the individual types of TASTy nodes, why some are directly unsuitable for execution, and how to simplify their semantics.

3.1.1 Converting the DefDef tree into a Truffle RootNode

In this section, we describe the conversion of `DefDef` trees to *root nodes*. `DefDef` trees are the primary structure that organizes code (terms) in TASTy. Root nodes represent the root of an executable Truffle AST, the primary abstraction which organizes code in Truffle. In our case, root nodes are the Truffle analog of a `DefDef`. Each root node has a corresponding *call target*, which is used for the invocation of the root node. Call targets are the primary compilation unit for Graal. A compilation unit is an organization of code that can be independently compiled. A root node is automatically instrumented[69] to profile its number of invocations. When a root node has been frequently invoked inside the interpreter, it is JIT compiled into machine code by Graal. Subsequent invocations of the call target will then use the more efficient compiled root node.

Figure 3.2 gives a simplified implementation of a root node. Each root node in Truffle has a *frame descriptor* and execution semantics. A guest language must subclass and implement its root node to enable function invocation semantics.

```

1 abstract class RootNode(desc: FrameDescriptor) {
2     def execute(frame: VirtualFrame): Object
3     def getCallTarget: CallTarget
4 }

```

Figure 3.2: Pseudocode of a root node.

A frame descriptor describes guest language variables that are in scope during execution. The abstract `execute` method describes the invocation behaviour of a root node. When a root node is executed, it is always supplied with a *frame*. A frame contains the arguments supplied during invocation and storage slots for local variable definitions in the body of the method.

```

1 class DefDef(_: String, params: List[ParamClause], _: TypeTree, rhs: Option[Term]) extends Definition

```

Figure 3.3: Defintion of a `DefDef` tree with names of less important members replaced with `_`

A further simplified definition of a `DefDef` tree is provided in figure 3.3. This section focuses on two members of a `DefDef` tree. The parameters of a `DefDef` tree are given by the `params` field. In practice, the type of a `ParamClause` is an alias for the union type `TypeParams | TermParams`, so we omit the `ParamClause` definition. A `DefDef` tree will have a parameter section for type parameters when they are polymorphic and will always have a term parameters section. `DefDef` trees may optionally have a body defined in the `rhs` field. When trees do not have a body defined, they are abstract method definitions and do not have a corresponding root node in Truffle. We will only consider non-abstract method definitions with a body (a term) defined to be executable. We will cover the parsing of terms into nodes for execution in detail after section ??

Each value definition in the parameters of a `DefDef` will have a corresponding frame slot in its parent frame descriptor. A frame slot references a unique frame value in the context of a root node. Truffle permits each frame slot in a frame descriptor to be described by a *frame slot kind*. In Truffle, there is a corresponding frame slot kind for reference types and each `JVM` primitive type. The pseudocode of a frame slot kind and a method to convert a type into a slot kind is given in 3.4.

Truffle profiles frame accesses to minimize the amount of autoboxing that occurs when

```

1 object FrameSlotKind extends Enumeration {
2     type FrameSlotKind = Value
3     val Object, Long, Int, Double, Float, Boolean, Byte = Value
4 }
5
6 def getFrameSlotKind(tpe: Type): FrameSlotKind =
7     if (tpe.isPrimitive)
8         getPrimitiveSlotKind(tpe) // Int => FrameSlotKind.Int, ..., Double => FrameSlotKind.Double
9     else
10         FrameSlotKind.Object

```

Figure 3.4: Simplified implementation of `FrameSlotKind`

reading from frame slot with an `Object` kind. To eliminate unnecessary specialization of frame accesses where types are monomorphic and statically refer to a primitive type, a parameter is assigned the matching primitive frame slot kind in the frame descriptor. In cases where the type is not a primitive type or a polymorphic applied type, e.g. `List[T]` but not `T`, we assign its frame slot the `Object` kind. Otherwise, the type is a polymorphic parameter which *could* resolve to a primitive type, and the frame slot kind cannot be resolved statically. We will defer discussion on handling parameters of such polymorphic types that cannot be resolved statically until section 3.2.

Figure 3.5 provides the implementation of the `DefDefNode` and its parameters, the root node equivalent of a `DefDef`. The execution of a `DefDefNode` is divided into two stages, argument preparation, and execution. First, the arguments of the frame constructed during invocation (see 3.1.3) are copied into their respective parameter frame slots. Frames contain separate regions for values of each frame slot kind. We copy each argument into the appropriate frame slot region based on the frame slot kind prescribed to a parameter. Storing parameters in this manner eliminates any unnecessary boxing that would otherwise occur when passing primitives as arguments.

By default, all frames start off *virtual*. Virtual frames are Truffle abstractions that provide guest languages an opportunity to exploit escape analysis. Escape analysis[48] reasons about the dynamic scope of object allocations. Truffle and Graal both exploit the observations of *Partial Escape Analysis*[70], a path-sensitive variant of escape analysis, to enable the following optimizations for guest languages:

Region Allocation[16, 74] The substitution of heap allocations with stack allocations to eliminate unnecessary garbage collection.

```

1 case class LocalFrameVal(slot: FrameSlot, kind: FrameSlotKind)
2
3 class DefDefNode(desc: FrameDescriptor, params: Array[LocalFrameVal], body: TermNode) extends RootNode(desc) {
4     override def execute(frame: VirtualFrame): Object = {
5         copyArgumentsToFrame(frame)
6         try {
7             body.execute()
8         } catch {
9             case ex: ReturnException => ex.getValue
10        }
11    }
12
13    def copyArgumentsToFrame(frame: VirtualFrame): Unit =
14        for ((param, arg) <- params zip frame.getArguments)
15            param.kind match {
16                case FrameSlotKind.Int =>
17                    frame.setInt(param.slot, arg.asInstanceOf[Int])
18                ...
19                case FrameSlotKind.Double =>
20                    frame.setDouble(param.slot, arg.asInstanceOf[Double])
21                case _ =>
22                    frame.setObject(param.slot, arg)
23            }
24 }

```

Figure 3.5: Pseudocode for DefDefNode and Parameter

```

1 def parseDefDef(ddef: DefDef): DefDefNode = {
2     val desc = new FrameDescriptor
3     val parameters = self :: ddef.params.map {
4         case vdef: ValDef => generateLocal(vdef, desc)
5     }
6
7     val body = parse(ddef.rhs)
8     new DefDefNode(desc, parameters, body)
9 }
10
11 def generateLocal(vdef: ValDef, desc: FrameDescriptor): LocalFrameVal = {
12     val kind = getFrameSlotKind(vdef.tpt.tpe)
13     val slot = desc.addSlot(kind)
14     Parameter(slot, kind)
15 }

```

Figure 3.6: Pseudocode for parsing DefDef into DefDefNode

Scalar Replacement[\[49\]](#) The complete elimination of an object allocation, where the fields of the replaced object are substituted by local variables.

The virtual frame abstraction allows guest languages to read and write to a frame without the requirement to optimize their object allocations. Instead, escape analysis and scalar replacement are responsible for optimizing guest language object allocations during partial evaluation. After arguments are copied into the frame, their values become available for access during the execution of the body. The body of a `DefDefNode` is then executed, and its computed value is returned.

Figure 3.6 provides a summary on parsing a `DefDef` tree into its Truffle equivalent `DefDefNode`. Frame slot and frame slot kinds provide an abstraction for parameters and arguments to be resolved before executing the main body in a `DefDefNode`. In addition to the parameters explicitly present in TASTy, the root node will have an additional parameter representing the method’s receiver. The receiver is an object instance whose class definition owns the method being invoked. In Scala, every method invocation has a receiver. In TASTy, this translates to every `DefDef` is owned by a `ClassDef`. In the next section, we detail how to organize call targets in Truffle by using `ClassDef` trees.

3.1.2 Deriving a Shape from a ClassDef

```

1 class ClassDef(
2     name:      String,
3     constructor: DefDef,
4     parents:    List[Tree],
5     _:         Option[ValDef],
6     body:       List[Statement]
7 ) extends Definition

```

(a) Pseudocode of a `ClassDef`.

```

1 class ClassShape(
2     symbol:      Symbol,
3     parents:     Array[Symbol],
4     fields:       Array[Field]
5     methods:     Map[MethodSignature, CallTarget]
6     vtable:      Map[MethodSignature, Symbol]
7 )

```

(b) Pseudocode of a shape for a `ClassDef`.

`ClassDef` tree defines the layout of an object in TASTy. The layout of an object dictates the values that an object instance stores and the methods that can be invoked on an object instance. The data layout of an object in a Truffle interpreter is described by a *shape* [24, 78]. Shapes are a language-agnostic model for defining the properties of an object instance in Truffle. A property in a shape describes one member of an object instance; it has an identifier and a value. A Truffle object instance consists of *object storage*, which contains instance-specific data and its shape. Shapes map property identifiers to object storage locations; guest languages interface with object storage indirectly through properties. In this thesis, we use a *static shape*, an immutable variant of a shape. Normally, shapes are mutable, and their list of properties may change throughout the lifetime of a program [29].

However, programs that dynamically change the layout of their objects[5] are out of the scope of this thesis.

```

1 def parseClassDef(cdef: ClassDef): ClassShape = {
2   val parents = cdef.parents.map(_.symbol)
3
4   val fields = cdef.body map {
5     case vdef: ValDef => generateField(vdef)
6   }
7
8   val methods = (cdef.constructor :: cdef.body) map {
9     case ddef: DefDef => ddef.symbol.signature -> parseDefDef(ddef)
10  }
11
12  val vtable = cdef.symbol.methodMembers map {
13    symbol => symbol.signature -> symbol
14  }
15
16  new ClassShape(cdef.symbol, parents, fields, init ++ methods, vtable)
17 }
18
19 def generateField(vdef: ValDef): Field = vdef match {
20   case ValDef(_: String, tpt: TypeTree, rhs: Option[Term]) => new Field(vdef.symbol, vdef.tpt.tpe)
21 }

```

Figure 3.8: Pseudocode to convert a `ClassDef` into a `ClassShape`.

Recall the definition of a `ClassDef` in figure 3.7a. Each `ClassDef` tree can be parsed into a corresponding `ClassShape`, given in figure 3.7b. Figure 3.8 provides a very simplified implementation of the parsing steps to transform a `ClassDef` into a `ClassShape`. The `name` parameter of `ClassDef` alone is insufficient to be used as an identifier for a `ClassShape`. Names do not disambiguate between classes of the same name declared in different packages. Instead, we used the symbol of the `ClassDef` tree as the identifier for the `ClassShape`. For the remainder of this thesis, we will use a `ClassInstance` to refer to an object instance with properties described by a `ClassShape`.

A `ValDef` tree in the body of a `ClassDef` translates to a field definition in the `ClassShape`. A `ClassShape` has a collection of fields that implement the static shape property. Figure 3.9 gives our implementation of a field. Fields define operations to read and write from the object storage on a `ClassInstance`. Like frames with frame slot kinds, object instances in Truffle have separate regions for storing values of each primitive type and one for reference types. Following the same rules with types and frame slot kinds described in section 3.1.1, the data access of a field depends on the type of the `ValDef` tree from which the field originates. The remaining members of a `ClassShape` do not describe data that has to be

```

1  class Field(symbol: Symbol, tpe: Type) extends StaticProperty {
2      override def getId: String = symbol.name
3
4      def get(instance: Object): Any =
5          if (tpe == Int) getInt(instance)
6          else if ...
7          else if (tpe == Double) getDouble(instance)
8          else getObject(instance)
9
10
11     def set(instance: Object, value: Any): Unit =
12         if (tpe == Int) setInt(instance, value.asInstanceOf[Int])
13         else if ...
14         else if (tpe == Double) setDouble(instance, value.asInstanceOf[Double])
15         else setObject(instance, value)
16 }

```

Figure 3.9: Pseudocode of the field property.

stored in the object storage of a `ClassInstance`.

After the constructor and the `DefDef` statements of a `ClassDef` are converted into root nodes, they are stored in the `ClassShape` mapped by a method signature. The pseudocode for a method signature is given in figure 3.10. Method signatures disambiguate method invocations in the presence of *ad hoc polymorphism*^[71], where methods share the same name but have different arguments. When combined with parametric polymorphism, method signatures must also be able to disambiguate between methods sharing the same name but having different type parameters. However, method signatures do not have to disambiguate between different type parameters by name, only the number of type parameters a method has. Because type erasure erases polymorphic type parameters from methods, methods that share the same number of parameters, as well as the same arguments, will conflict and therefore are invalid. As previously mentioned, methods are shared between all `ClassInstance` objects with the same shape; call targets are stored on their owning shape.

```

1  case class MethodSignature(symbol: Symbol, params: Int, types: Array[Type])

```

Figure 3.10: Pseudocode of a method signature.

Often a shape will not contain the call target referenced by a signature because the

dispatch is dynamic, and the original type inherits the method. A `ClassShape` contains a *virtual method table*, which maps a method signature to the symbol of a shape that contains the call target matching the signature. If a method signature does not have a call target in the current shape, the shape which holds the target is indirectly resolved using the virtual method table during execution. While this resolution carries significant performance overhead in Truffle and other programming language implementations, we will describe a technique that partially mitigates this overhead further in this half of the chapter.

3.1.3 Transforming Terms into Nodes

```
1 abstract class TermNode extends Node with InstrumentableNode {
2
3     def execute(frame: VirtualFrame): Object
4     def executeInt(frame: VirtualFrame): Int = execute(frame).asInstanceOf[Int]
5     ...
6     def executeDouble(frame: VirtualFrame): Double = execute(frame).asInstanceOf[Double]
7
8 }
```

Figure 3.11: Pseudocode of a `TermNode`.

In this section, we will cover the conversion of `Term` trees into Truffle nodes. The Truffle `Node` abstraction allows guest languages to implement executable fragments of an AST. Figure 3.11 is our subclass of a Truffle `Node`. Subclasses of the `TermNode` will define node-specific semantics encapsulating a particular functionality of the interpreter. The `TermNode` takes advantage of Truffle’s autoboxing elimination by defining companion `execute[TYPE]` methods to allow subclasses to declare when an expected result from a child node must conform to a specific primitive type. In the following subsections, we give the subclasses that individually implement the monomorphic interpreter’s functionality.

Creating Instances

The `New` tree represents the allocation of an instance of a `ClassDef`. The Truffle equivalent allocate node given in figure 3.12 is not so different, but it allocates an instance with properties described by the `ClassShape` instead of a `ClassDef`. Note that a `NewNode` only *creates* an object; the parameters and fields of an object remain uninitialized. An

```

1 def parseNew(new: New): NewNode = new NewNode(new.tpe.symbol)
2
3 class NewNode(symbol: Symbol) extends TermNode {
4     override def execute(frame: VirtualFrame): Object = shapeOf(symbol.tpe).newInstance
5 }

```

Figure 3.12: Pseudocode of a `NewNode` and how it is parsed.

object is *initialized* when the initializer, `<init>`, method is invoked on a newly created object. TASTy is emitted with this sequence of events in mind; object creation is always followed by object initialization. Structurally, this means that a `New` tree is always the child of an initializer `Apply` tree.

Function Application

```

1 def parseApply(apply: Apply): ApplyNode = {
2     val signature = apply.symbol.signature
3     apply match {
4         case Apply(Select(qualifier, _), arguments) =>
5             if (qualifier.tpe.isPrimitive)
6                 if (args.length == 0) unaryOp(signature, qualifier)
7                 else binaryOp(signature, qualifier, args(0))
8             else if (qualifier.tpe.isArray)
9                 arrayOp(signature, qualifier, arguments)
10            else
11                new ApplyNode(signature, parse(qualifier), arguments.map(parse))
12    }
13 }

```

Figure 3.13: Pseudocode of parsing an `Apply` tree.

The `Apply` tree is a context-dependent tree that represents multiple types of operations. The types of their receiver disambiguate these operations. Figure 3.13 provides an overview of the transformations discussed in this section as pseudocode for parsing an `Apply` into TastyTruffle IR. We omit the implementations of `unaryOp`, `binaryOp`, `arrayOp` to remain concise; These methods generate a Truffle intrinsic node, representing a similar JVM equivalent. In the following subsections, we enumerate all possible semantics in our subset of TASTy:

Arithmetic and Logical Operators In TASTy, there are no unary and binary operators, typically found in Java or other imperative languages. Unary and binary operators are an invocation of the 0-argument (unary operator) or 1-argument (binary operator) method. For example, the following addition operator in Scala `1 + 2` is desugared to `1.+(2)`. That is, the binary operator `+` is represented as the invocation of the instance function `Int.+` on the receiver with value `1` and type `Int` with a single argument `2`. Generally, in the Scala compilation pipeline, methods that operate on primitive types and have an equivalent bytecode instruction on the JVM[52] are replaced by those instructions in compiled program bytecode. This process of selecting efficient implementations for numerical or logical operations is called *intrinsicification*. Similarly, TastyTruffle avoids implementing methods of primitive types with actual call semantics as primitive operations are frequently used and simplify optimization for Graal.

Array Access The syntax for accessing array elements in Scala does not differ from the invocation method on an array. In other imperative languages, such as Java, the syntax for accessing arrays is commonly separate from the syntax of invoking a method. For example, the access `array(0)` is desugared to `array.apply(0)` once the program is emitted in TASTy. However, an array write `array(0) = 42` is desugared to `array.update(0, 42)`.

Similar to unary and binary operators, the underlying implementation of array operations is intrinsicified into JVM bytecode instructions where possible. However, using the bytecode provided in figure 2.12 as an analog, operations on polymorphic arrays **cannot** be intrinsicified. Instead, polymorphic array operations are handled by functions in the Scala runtime library. The overhead of such operations is substantial and commonly represents the most significant performance bottlenecks in array-bound programs. These costs are additionally abstracted from the user as they commonly arise when using array-backed collections from the Scala standard library.

To operate without specialization, the implementation of our interpreter also incorporates the same runtime code to handle polymorphic array operations. In the second half of this chapter, we will discuss the methods used to eliminate the runtime overhead of these polymorphic bridge methods.

Method Invocation Otherwise, the `Apply` tree encodes a ‘normal’ method invocation. Truffle provides two abstractions for call nodes, the *direct call node* is used when the call target can be statically resolved. In our subset of TASTy, this is the set of methods with private or final modifiers[42] and class constructors. Otherwise, the Truffle *indirect call node* is used for calls where call targets must be dynamically resolved. Using indirect calls

```

1 @NodeChild("receiver")
2 @NodeField("signature", MethodSignature.class)
3 class ApplyNode(@Children args: Array[TermNode]) extends TermNode {
4     final val INLINE_CACHE_SIZE: Int = 5;
5
6     @Specialization(guards = "instance.getShape == shape", limit = "INLINE_CACHE_SIZE")
7     def cached(
8         frame: VirtualFrame,
9         instance: ClassInstance,
10         @Cached("instance.getShape") shape: ClassShape,
11         @Cached("create(resolveCall(instance, signature)") callNode: DirectCallNode
12     ): Object = callNode.call(evalArgs(frame, instance));
13
14     @Specialization(replaces = "cached")
15     def virtual(
16         frame: VirtualFrame,
17         instance: ClassInstance,
18         @Cached callNode: IndirectCallNode
19     ): Object = {
20         val callTarget = resolveCall(instance.getShape, signature);
21         callNode.call(callTarget, evalArgs(frame, instance))
22     }
23 }

```

Figure 3.14: Simplified implementation of the call node with a polymorphic inline cache used in TastyTruffle.

instead of direct calls comes with performance overhead as indirect call nodes cannot be inlined and inhibit Graal’s dynamic intraprocedural analyses. In this thesis, we describe a call node implementation for both statically and dynamically dispatched calls. In order to minimize the use of indirect call nodes, we take advantage of a polymorphic inline cache^[44] to eliminate the overhead of resolving virtual calls for JIT compilation.

Figure 3.14 shows a simplified Truffle call node in TASTYTRUFFLE which implements a polymorphic inline cache. The `ApplyNode` is declared using the Truffle DSL. The `@NodeChild` and `@NodeField` annotations declare that the DSL should generate children and properties of those names and types, respectively. The `@Specialization` annotation declares the node writing semantics for method invocation. Because we have defined a limit on the number of specializations, the DSL will also generate additional code for a polymorphic inline cache. This cache saves call targets based on the type of receiver seen at the call site.

When the type of receiver has not been seen in the inline cache, an additional cache entry is generated and appended to the cache for the next call. Because a polymorphic inline cache dispatches direct calls based on the type of the receiver value seen, Graal

can speculatively optimize the call site with the assumption that the receiver is always the same type and, therefore, the call target does change between invocations. Furthermore, this allows the call site to be inlined, allowing a feedback loop of intraprocedural optimizations[76][13] to propagate through the inlined tree. One important aspect to note is that the size of a polymorphic inline cache must be kept reasonable such that the cost of searching the cache should not defeat the speedup afforded by using the cache. If the size of the cache exceeds the limit set, the caller node is rewritten to use an indirect call, as the cost of inline cache lookup will outweigh the penalty of an indirect call.

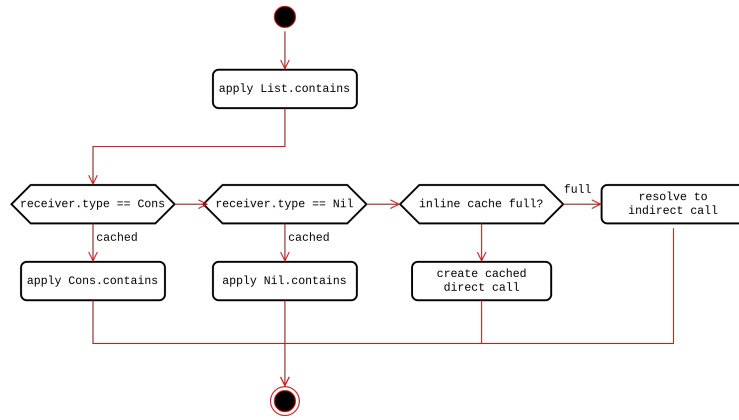


Figure 3.15: A possible polymorphic inline cache for a `List.contains` callsite.

Figure 3.15 shows a data flow diagram of the application of a polymorphic inline cache to a call site of `contains` when the receiver type is statically known to be `List`. The diagram shows that the call site was previously called with a receiver where the dynamic type has been both `Cons` and `Nil`. The `ApplyNode` will first check if the type of receiver at the call site has the type `Cons`; If the check passes, then the cached direct call node is invoked, and the call is complete. It will do the same for the type `Nil`. Otherwise, the type of receiver has not been seen before, and the call target is resolved virtually and then cached for the following invocation at this call site.

When the polymorphic inline cache is applied to a monomorphic call site (where the type of the receiver does not change), it simplifies to a single element inline cache[31]. Because the type of the receiver at the call site remains stable, the cache look-up of the call target based on the type always succeeds, and the call site never fallbacks to using an indirect call node.

Accessing Fields

In our subset of TASTy, the **Select** tree represents a read of a field of a **ClassInstance**. Notice in the resolution of the **Apply** tree that an **Apply** tree represents a method invocation when the applicator is a **Select**. Because functions are first-class objects in Scala, the TASTy tree for a method invocation is the access of a method as if it were a field, then the application of the subsequent function value read to a list of arguments. Since this case has been previously handled when parsing the **Apply** tree, a **Select** tree always selects a value definition.

```
1 @NodeChild("receiver")
2 @NodeField("symbol", Symbol.class)
3 abstract class ReadFieldNode extends TermNode {
4     final val INLINE_CACHE_SIZE: Int = 3;
5
6     @Specialization(guards = "instance.getShape == shape", limit = "INLINE_CACHE_SIZE")
7     def cached(
8         instance: ClassInstance,
9         @Cached("instance.getShape") shape: ClassShape,
10        @Cached("lookupField(shape)") field: Field
11    ): Object = field.getContents(instance)
12
13    @Specialization(replaces = "cached")
14    def virtual(instance: ClassInstance): Object = {
15        val field = lookupField(instance.getShape)
16        field.getContents(instance)
17    }
18
19    private def lookupField(shape: ClassShape): Field = shape.getField(symbol)
20 }
```

Figure 3.16: Pseudocode of field read node with a polymorphic inline cache.

However, fields may only be directly accessed in the immediate class scope. Field access from an outside context is achieved through an **accessor**. Accessors are special methods generated in the compilation pipeline solely to access a field. We apply the transformation to generate accessors in class definitions because accessors are normally generated after TASTy is emitted in the standard Scala compilation pipeline. Accessors also conveniently provide a mechanism to resolve indirect field access. Indirect field access occurs when an inherited field is accessed in a subclass. As we already have a mechanism for resolving method applications, we will combine this mechanism with a new direct field read node to implement field access.

Figure 3.16 gives a simplified implementation of a field read node. Like the virtual

dispatch of call targets, fields are resolved dynamically with the shape of a `ClassInstance`. We apply a polymorphic inline cache to the lookup of field properties to eliminate the performance overhead associated with this kind of virtual dispatch.

Accessing Locals and Globals

```
1 def parse(ident: Ident): TermNode = {
2   if (ident.symbol.isObjectDef)
3     new ReadGlobalNode(symbol)
4   else
5     new ReadLocalNode(localOf(symbol))
6 }
```

Figure 3.17: Pseudocode to parse an `Ident` tree.

The `Ident` tree is a name that refers to either a local or global value. Local values take the form of a local variable or a method parameter. Global values refer to a top level `object` definition. We differentiate between a local and a global based on whether the symbol of the `Ident` tree refers to an `object` definition (shown in figure 3.17).

```
1 object Globals {
2   val values: Map[Symbol, ClassInstance] = ???
3 }
4
5 class ReadGlobalNode(symbol: Symbol) extends TermNode {
6   override def execute(frame: VirtualFrame): Object = Globals.values.get(symbol)
7 }
8
9 class ReadLocalNode(local: Local) extends TermNode {
10   override def execute(frame: VirtualFrame): Object = frame.getObject(local.index)
11 }
```

Figure 3.18: Pseudocode of local and global value read nodes.

Figure 3.18 provides the implementations the `ReadGlobalNode` and `ReadLocalNode`. In our interpreter, local variables and method parameters are uniformly represented by the frame slot abstraction. During parsing, it is sufficient to maintain a mapping from symbols to a `Local` to resolve which local variable is read. Truffle does not provide an abstraction for storing global values. Instead, we retain a mapping of symbols to instances for all

global object value definitions. Recall from figure 3.1 that a top level value definition is registered. When the symbol of an `Ident` refers to a `ObjectDef`, or a top-level `ValDef`, it is resolved using the symbol to look up top-level global values previously registered in 3.1.

Mutating Values

```
1 def parseAssign(assign: Assign): TermNode = assign match {
2   case Assign(select: Select, rhs) =>
3     new WriteFieldNode(parse(select.qualified), select.symbol, parse(rhs))
4   case Assign(ident: Ident, rhs) =>
5     new WriteLocalNode(localOf(ident.symbol), parse(rhs))
6 }
```

Figure 3.19: Pseudocode to parse an `Assign` tree.

The `Assign` tree has context-dependent semantics based on the structure of its left-hand side term. Figure 3.19 contains the simplified logic to resolve `Assign` trees into the appropriate term nodes. If the left-hand side term is a `Select` tree, the current tree mutates the field of a `ClassInstance`. Otherwise, the left-hand side is an `Ident` which refers to the local variable in the frame. We differentiate between which node to generate based on the type of the tree seen on the left-hand side. The `WriteFieldNode` and `WriteLocalNode` mirror their read node counterparts, but instead of reading from their respective locations, they update the value at their locations. Like field reads, field writes in scopes outside of the class are dispatched through *mutators*. Mutators serve the same purpose as accessors but carry an argument to update the value of the field.

Conditionals

The implementation of conditional control flow in our interpreter is quite simple. Two execution paths exist for the two possible results from evaluating the condition term; The path taken depends on the boolean after evaluation. An `IfNode` is derived from an `If` tree (given in figure 3.20), which allows for divergence in program control flow. The implementation of the TastyTruffle IR mirrors the semantics given by its original TASTy tree. In order to take advantage of conditional speculative optimization, we add a `ConditionProfile` onto the result of the condition term. A condition profile records the likelihood that a branch is either true or false. Graal then speculatively optimizes the frequently true or false branches of an `IfNode` using its condition profile.

```

1 def parseIf(i: If): IfNode = new IfNode(parse(i.cond), parse(i.thenp), parse(i.elsep))
2
3 class IfNode(@Child cond: TermNode, @Child t: TermNode, @Child f: TermNode) extends TermNode {
4     val cp = ConditionProfile.create();
5
6     override def execute(frame: VirtualFrame): Object = {
7         if (cp.profile(cond.executeBoolean(frame)))
8             t.execute(frame)
9         else
10            f.execute(frame)
11     }
12 }

```

Figure 3.20: Pseudocode for parsing an If into an IfNode

Loops

In our subset of TASTy, the **While** tree is the only looping construct. The control flow of the **While** tree is quite simple; the body term is executed as long as the condition term holds at the beginning of every iteration. Truffle provides the **LoopNode** abstraction for implementations of guest language loop structures. The loop node abstraction allows guest languages to take advantage of *On-Stack Replacement*[\[35\]](#). On-stack replacement is a technique that switches control of part of a program running in the interpreter to compiled code while that part is executing.

So far in this thesis, the root node has been the primary compilation unit in Graal. Root nodes profile their invocation count and get JIT compiled when they have been invoked frequently. However, loop constructs that are executed for many iterations also justify JIT compilation. The loop node is an additional type of JIT compilation unit which Graal can compile. A key difference between loop nodes and root nodes is when their compiled equivalents are utilized. While compiled root nodes are used in subsequent invocations of their call targets after they are JIT compiled, compiled loop nodes are used in the next iteration after they are JIT compiled. As on-stack replacement is not a central focus of this thesis, we will only discuss it briefly because loop nodes are the recommended abstraction for guest languages to implement loop structures in Truffle.

Figure [3.21](#) contains the implementation of a **WhileNode** and its derivation from a **While** tree. Like our implementation of the **IfNode**, we add a condition profile onto the node which evaluates the termination condition inside **WhileRepeatingNode**. Truffle will automatically instrument the **WhileNode**. After sufficient iterations of the **WhileRepeatingNode**, the repeating node is compiled, and the next iteration of the **WhileNode** will use the compiled

```

1 def parseWhile(tree: While): WhileNode = new WhileNode(parse(tree.cond), parse(tree.body))
2
3 class WhileNode(@Child cond: TermNode, @Child body: TermNode) extends TermNode {
4
5     @Child val loopNode: LoopNode =
6         Truffle.getRuntime.createLoopNode(new WhileRepeatingNode(cond, body))
7
8     override def execute(frame: VirtualFrame): Object = {
9         loopNode.execute(frame)
10        ()
11    }
12
13    class WhileRepeatingNode(
14        @Child cond: TermNode,
15        @Child body: TermNode
16    ) extends Node with RepeatingNode {
17        val cp = ConditionProfile.create()
18
19        override def executeRepeating(frame: VirtualFrame): Boolean =
20            if (cp.profile(cond.executeBoolean(frame))) {
21                body.execute(frame)
22                true
23            } else false
24    }
25 }
26 }

```

Figure 3.21: Pseudocode for a WhileNode

repeating node.

Blocks

This section covers the translation of the **Block** tree to its TastyTruffle IR equivalent. The **Block** is unique among term trees as it describes data and code. In our subset of TASTy, this means that a block may contain declarations of local variables as well as executable terms. Figure 3.22 provides an overview on the transformations necessary to convert a **Block** tree into **BlockNode**. We divide the discussion of blocks into the resolution of local variables when encountering a **ValDef** tree and the execution of all other trees.

Local variables are bound to a *scope*. A scope represents the lifetime in which a variable can refer to a value. Similarly, uses of variables are only valid when used under the appropriate scope. Local variables and their use sites are represented in intermediate representations through various methods. In abstract syntax trees, local variables and their uses are represented as nodes *dominated* by their scopes (which are themselves nodes). In

```

1 def parseBlock(block: Block): BlockNode = {
2     val desc = getParentFrameDescriptor(block)
3
4     val terms = block.statements map {
5         case vdef: ValDef => generateBlockLocal(desc, vdef)
6         case term => term
7     }
8
9     new BlockNode(terms, parse(block.expr))
10 }
11
12 def generateBlockLocal(desc: FrameDescriptor, vdef: ValDef): TermNode = {
13     val local = generateLocal(vdef)
14     new WriteLocalNode(local, parse(vdef.rhs))
15 }

```

Figure 3.22: Pseudocode for parsing Block into BlockNode

our subset of TASTy, a ValDef dominated by a Block represents a local variable. When a ValDef tree is present in this context, the right-hand side of the value definition will be non-empty.

```

1 class BlockNode(stats: Array[TermNode], last: TermNode) extends TermNode {
2     @ExplodeLoop
3     override def execute(frame: VirtualFrame): Object = {
4         for (stat <- stats)
5             stat.execute(frame)
6
7         last.execute(frame)
8     }
9 }

```

Figure 3.23: Pseudocode of the BlockNode

Because terms always return a value, the Block tree must follow the same semantics. Figure 3.23 gives the pseudocode for our implementation of a BlockNode. The @ExplodeLoop is a Truffle DSL directive that guides Graal to unroll^[12] the loop for the execution of each child node. Unrolled loops simplify partial evaluation as each iteration of the loop is treated as an individual statement, and thus they reveal constant values, which are simpler for partial evaluation. As the number of children in a BlockNode is known before execution, it makes sense to unroll this loop to simplify optimization.

Returns

```
1 class ReturnException(result: Object) extends ControlFlowException
2
3 class ReturnNode(@Child term: TermNode) extends TermNode {
4     override def execute(frame: VirtualFrame): Object = {
5         val result = term.execute(frame)
6         throw new ReturnException(result)
7     }
8 }
```

Figure 3.24: Pseudocode of `ReturnException` and `ReturnNode`

A **Return** tree ends the execution of the current method and passes a value back to the caller. The semantics of returning control flow in Truffle is implemented as a program *exception*. An exception is an unexpected disruption of program control flow. Recall in figure 3.5 that a body of a `DefDefNode` is executed and a `ReturnException` is possibly caught. The implementation of the `ReturnException` and `ReturnNode` is given in figure 3.24. The `ReturnException` is a subclass of the `ControlFlowException`. Control flow exceptions are special exceptions that Truffle treats differently from other JVM exceptions for control flow analysis. A return exception is thrown with the return value evaluated from a return node. The exception is then caught by the executing `DefDefNode`, where the return value is passed back to the caller.

Putting it All Together

In this section, we summarize all the tree transformations introduced for the monomorphic variant of our interpreter. Figure 3.25 is the structure of the `Cons.contains` method in TASTy. We have omitted the type tree, which has been declared inside the local variable definition. We use the `Cons.contains` method as an example to summarize the transformations described in this section.

Figure 3.26 is the Truffle equivalent AST of `Cons.contains`. We use simple strings to represent symbols and method signatures to avoid unnecessary detail in the example. Notice that many TASTy nodes have an equivalent TastyTruffle IR, which closely mirrors their structure. However, other TASTy nodes must be simplified to a representation more suitable for runtime. In particular, `ValDef` trees are eliminated and replaced by an initializer node which assumes that the frame slot for the local variable definition was added

```

1 Block(
2   List(
3     ValDef("these", _, This),
4     While(
5       Apply(Select(Ident("these"), "empty"), "!", List.empty),
6       If(
7         Apply(Select(Select(Ident("these"), "head")), "==", List(Ident("elem")))
8         Return(Constant(true)),
9         Assign(Ident("these"), Select(Ident("these"), "tail"))
10      )
11    )
12  ),
13  Constant(false)
14 )

```

Figure 3.25: TASTy of `Cons.contains`

```

1 BlockNode(
2   Array(
3     WriteLocalNode("these", ReadLocalNode("this")),
4     WhileNode(
5       UnaryOpNode("!", ApplyNode("these", "List.isEmpty[0]()", Array.empty)),
6       IfNode(
7         ApplyNode(
8           FieldReadNode(ReadLocalNode("these"), "head"),
9           "Any.==[0]()",
10          ReadLocalNode("elem")
11        ),
12        ReturnNode(ConstantNode(true)),
13        WriteLocalNode("these", ReadFieldNode(ReadLocalNode("these"), "tail")),
14      )
15    )
16  ),
17  ConstantNode(false)
18 )

```

Figure 3.26: `Cons.contains` as a Truffle AST

during parsing. In the second half of this chapter, we will describe the challenges of using these trees in the presence of parametric polymorphism and their associated performance overhead.

3.2 The Polymorphic Interpreter

```
1 abstract class TypeNode extends Term {
2   override final def execute(frame: VirtualFrame): Object = resolveType(frame)
3   def resolveType(frame: VirtualFrame): Type
4 }
```

Figure 3.27: An abstract type node.

In this section, we extend our interpreter to support the execution of polymorphic trees. To that end, we introduce the notion of *reified* type nodes. In essence, to implement specialization of polymorphic classes and methods, we make types a *first-class* value. Like the `TermNode` represents the `Term` tree node from TASTy, the `TypeNode` represents the `Type` from TASTy but instead of producing a value from evaluation, it produces a *type*. To better illustrate this concept, figure 3.27 contains the implementation of the node superclass which evaluates to a type and not a value.

```
1 parseType(tpe: Type): TypeNode = tpe match {
2   case ref: TypeRef => TypeRefNode(ref)
3 }
4
5 class TypeRefNode(ref: TypeRef) extends TypeNode {
6   override def resolveType(frame: Frame): Type = ref
7 }
```

Figure 3.28: A `TypeNode` for handling type references.

Figure 3.28 gives the simplified implementation to reify type references in the polymorphic interpreter. For now, we will limit the scope of reified type to the simplest and introduce concepts which integrate reified types with Truffle abstractions further in the chapter. Figure 3.29 extends the `NewNode` to support the creation of object instances using reified type nodes. Because a type reference essentially reifies statically available type information, very little changes in the implementation of a `NewNode`.

Because the underlying type of a type parameter is only known during runtime, introducing types during execution will allow data layouts to be determined at runtime. The type node is the abstraction we use to encapsulate this concept. The principal idea behind

```

1 def parseNew(new: New): NewNode = new NewNode(parseType(new.tpe))
2
3 class NewNode(@Child typeNode: TypeNode) extends TermNode {
4   override def execute(frame: VirtualFrame): Object = {
5     val tpe = typeNode.resolveType(frame)
6     shapeOf(tpe).newInstance
7   }
8 }

```

Figure 3.29: Extension to the `NewNode` for the polymorphic interpreter.

the type node is to allow for the resolution of types during runtime. Introducing a mechanism to resolve types during runtime avoids the pitfalls of type erasure. In this half of the chapter, whenever we discuss the advantages of the polymorphic interpreter, we will use a monomorphic interpreter where the code has undergone type erasure as our frame of reference.

Using the newly available type information during runtime, data layout can be specialized based on the types seen. In the following subsections, we will focus on specific instances of boxing using Graal IR of compiled code executed using the monomorphic interpreter. Then we introduce subclasses of the `TypeNode` and show how reified types can be utilized to specialize the data layouts from the monomorphic interpreter.

3.2.1 Specializing Methods

```

1 class DefDefTemplate(
2   desc:   FrameDescriptor
3   tparams: Int,
4   vparams: List[ValDef | LocalFrameVal],
5   locals: List[ValDef | LocalFrameVal],
6   rhs:    Term
7 ) extends RootNode(desc) {
8   def execute(frame: VirtualFrame): Object = ???
9   def specialize(types: Array[Type]): DefDefNode = ???
10 }

```

Figure 3.30: Pseudocode for a `DefDefTemplate`.

Polymorphic methods in Scala can be polymorphic under class type parameters, method type parameters, or both. This section will focus only on the specialization of polymorphic

methods under their type parameters. We defer the discussion of the specialization of class-polymorphic methods until the next section. We will introduce the concept of a *template*; Templates retain sufficient information about the data layout of a definition in TASTy to generate their runtime representations dynamically. Instead of a `DefDefNode`, a `DefDefTemplate` (given in figure 3.30) is a root node that represents a polymorphic method. When a `DefDefTemplate` is specialized, the result is a monomorphic `DefDefNode` specialization. As Truffle does not have mechanisms that support root node rewriting at the current time, we describe how to use Truffle DSL constructs to make method specialization performant.

```

1 def parseDefDef(ddef: DefDef): DefDefNode | DefDefTemplate = {
2   val tparams = ddef.params.filter(_._isInstanceOf[TypeDef]).length
3   if (tparams == 0)
4     createDefDefNode(ddef)
5   else {
6     val vparams = ddef.filter(_._isInstanceOf[ValDef]) map {
7       case vdef @ ValDef(_, tpt, rhs) =>
8         if (tpt.tpe.isTypeParameter)
9           vdef
10        else
11          generateLocal(vdef)
12    }
13
14    val locals = liftLocals(ddef.rhs)
15    new DefDefTemplate(desc, tparams, vparams, locals, ddef.rhs)
16  }
17 }
18
19 def createDefDefNode(ddef: DefDef): DefDefNode // a monomorphic DefDef
20
21 ...

```

Figure 3.31: Pseudocode for parsing `DefDef` into `DefDefNode`

The specialization of a `DefDefTemplate` begins at invocation. Because type arguments are introduced at specific polymorphic call sites, method specializations must be created at or after invocation. When a method template is invoked with both type and value arguments, it forwards the value arguments to the appropriate specialization based on the type arguments.

The specialization of a method template is the ad-hoc creation of a root node with a specialized frame descriptor. A `DefDefTemplate` retains the number of type parameters it owns; this is sufficient to resolve type arguments for creation and dispatching to specializations, and type parameters never collide by name. Source information about value

parameters is stored on a template instead of abstracted local frame values. The type of value parameter can potentially be resolved from a method type parameter. Since the frame descriptor is unpopulated because value parameters are possibly polymorphic, it is not yet appropriate to create executable term nodes which may read from or write to the frame slots of polymorphic value parameters. Figure 3.31 extends the transformation of a `DefDef` to include method templates.

Invoking Polymorphic Methods

```

1 def parseApply(apply: Apply): ApplyNode = {
2   val signature = apply.symbol.signature
3   apply match {
4     case Apply(Select(qualifier, _), arguments) => ... // monomorphic trees
5     case Apply(TypeApply(Select(qualifier, _), targs), args) =>
6       new ApplyNode(signature, parse(qualifier), (targs ++ args).map(parse))
7   }
8 }

```

Figure 3.32: Extension to parsing a polymorphic `Apply` tree.

In this section, we demonstrate when and where polymorphic methods are invoked. For this demonstration, we will show one of the natural benefits of executing TASTy. A polymorphic method invocation in TASTy is always an `Apply` tree node where the qualifier is a `TypeApply`. The `TypeApply` tree node represents a *type application*. Without delving into great detail, a type application is the process of producing a monomorphic method from a polymorphic method by matching type parameters to type arguments. Analogous to normal applications, which accept values as arguments and produce values as results, type applications accept types as arguments and produce types as a result. With this in mind, `TypeApply` nodes are a naturally suitable site to invoke and create specializations for methods.

```

1 def apply(T: Type, array: Array[T]): List[T] = T match {
2   case Int => apply$Int(array.asInstanceOf[Array[Int]])
3   ...
4   case _ => apply$Any(array.asInstanceOf[Array[Any]])
5 }

```

Figure 3.32 extends the transformation of **Apply** tree nodes to include polymorphic applications. The application of a polymorphic method follows the same semantics as the application of a monomorphic method. The actual specialization of the frame layout occurs inside the template that a polymorphic **ApplyNode** invokes. This design decision allows the invocation of polymorphic methods even in the presence of dynamic dispatch. In the next section, we will describe the additional machinery that is added *after* a polymorphic inline cache has resolved virtual dispatch to handle type application and how to make such mechanisms amenable for partial evaluation.

Typed Dispatch Chains

```

1  class DefDefTemplate(...) extends RootNode(...) {
2
3      @CompilerDirectives.CompilationFinal
4      val specializations: Array[(Array[Type], DirectCallNode)] = Array.empty
5
6      def execute(frame: VirtualFrame): Object = {
7          val typeArguments = resolveArguments
8          dispatchCached(frame, types)
9      }
10
11      @ExplodeLoop
12      def dispatchCached(frame: VirtualFrame, typeArguments: Array[Type]): Object = {
13          for ((typeSignature, specialization) <- specializations)
14              if (typeSignature == typeArguments)
15                  return specialization.call(frame.getArguments)
16          CompilerDirectives.transferToInterpreterAndInvalidate()
17          dispatchNew(frame, typeArguments)
18      }
19
20      def dispatchNew(frame: VirtualFrame, typeArguments: Array[Type]): Object = {
21          val specialization = specialize(typeArguments)
22          val callNode = DirectCallNode.create(specialization)
23          specializations += (typeArguments -> callNode)
24          callNode.call(frame.getArguments)
25      }
26
27      ...
28  }

```

Figure 3.33: Pseudocode for typed dispatch inside a **DefDefTemplate**.

Dispatch chains^[67] are multi-layered inline caches. We introduce the notion of *typed dispatch chains*. Typed dispatch chains integrate the semantics of type applications via

a second inline cache after virtual call resolution. Figure 3.33 contains the simplified implementation of the execution semantics in a `DefDefTemplate`.

Specializations of polymorphic methods are created on demand and then cached based on their reified type signatures. One challenge of making caching mechanism fold away in partial evaluation is that the cache must be a *compilation constant*. Type arguments at type application sites are always stable, i.e., their respective type nodes evaluate to the same type; the look-up of the specialized call node should have no overhead when JIT compiled with the aid of partial evaluation. We exploit a simple array of type signatures and specialized call node pairs to make this possible. When the loop for looking up a cache entry in the array is unrolled during partial evaluation (directed by `ExplodeLoop`), the loop is transformed into a block of conditional expressions for each cache entry. This unrolled loop combined with the injected knowledge that type argument values are compilation constants results in the conditional elimination[18] of checks for non-matching cache entries. Once the appropriate specialization is found, the call is forwarded to the root node, which contains the specialized term nodes.

When a combination of type arguments has not yet been encountered and their corresponding specialization is unavailable, the specialization must be generated and invoked. To prevent this *slow* path of execution from being JIT compiled, we direct the compiler to *bail out* of JIT compilation with the `transferToInterpreterAndInvalidate` directive. The directive allows guest languages to insert their own deoptimization points into the control flow of a program; This ensures code of the slow branch when creating the specialization is never compiled. Note that in the first case where a type argument lookup succeeds (the fast path), the directive is unreachable because the control flow of the code returns and, therefore, will not be part of compiled code.

Figure 3.34 is an extension of the example given in figure 3.15 with typed dispatch. The example assumes the type arguments for `Int` and `Double` for `Cons.contains[T]` and `Nil.contains[T]` has previously been specialized and cached. After the polymorphic inline cache resolves the receiver to an exact type, the corresponding specialization is looked up. While this example may seem deceptively large, only the path taken in the control flow is compiled after partial evaluation. For example, consider the invocation `List.contains[Int]` when the receiver is an instance of `Cons`, the corresponding compiled code will not contain the check that type parameter is an `Int`. Because all other program logic is eliminated during partial evaluation, the inlining of calls is also straightforward. After the partial evaluation, the typed dispatch mechanism is also eliminated, and the specialized method is the only code remaining.

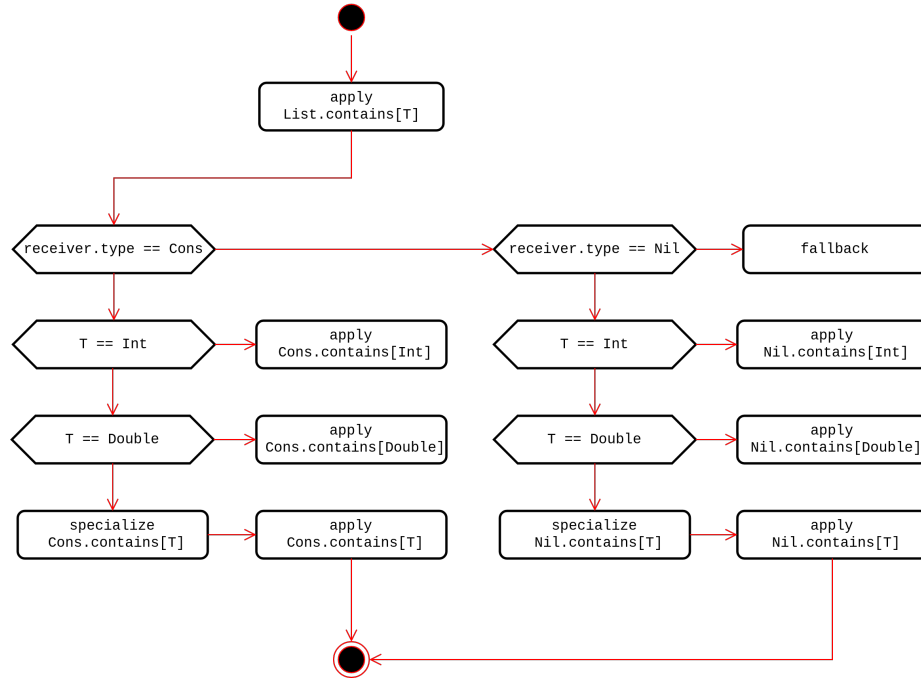


Figure 3.34: The typed dispatch chain for a `List.contains` call site

Specializing Polymorphic Parameters

The data layout of a method is given by the frame descriptor of its root node. A specialized method will have a specialized frame descriptor. Specialized frame descriptors will have the appropriate primitive frame slot kinds assigned to value definitions that have their polymorphic resolve to a primitive type. Therefore, the core principle behind method specialization is generating a **TermNode** tree from a **Term** tree using a specialized frame descriptor. Apart from extensions given earlier in this section, the parsing of **Term** nodes does not differ from their monomorphic counterparts.

Figure 3.36 gives an extension to generate frame slots from type parameters and polymorphic value definitions atop the method to generate frame slots from monomorphic value definitions. Like its counterpart in the monomorphic interpreter, the abstraction for a local frame value in the polymorphic interpreter has a slot. However, a local frame value in the polymorphic interpreter retains a type instead of a frame slot kind. If the type of a value parameter can be resolved with the type arguments supplied during specialization, the specialized frame slot is created and added to the descriptor.

```

1 class DefDefTemplate(...) extends RootNode(...) {
2     def execute(frame: VirtualFrame): Object = ...
3
4     def specialize(types: Array[Type]): DefDefNode = {
5         val desc = this.desc.copy()
6
7         val parameters = self :: vparams.map(specializeValDef(types, desc))
8         locals.foreach(specializeValDef(types, desc))
9
10        val body = parse(rhs)
11        new DefDefNode(desc, parameters, body)
12    }
13
14    def specializeValDef(
15        types: Array[Type],
16        desc: FrameDescriptor,
17        v: LocalFrameVal | ValDef
18    ): LocalFrameVal = v match {
19        case vdef: ValDef => generateLocal(types, vdef, desc)
20        case v => v
21    }
22 }

```

Figure 3.35: Pseudocode for on-demand specialization inside a DefDefTemplate.

```

1 def generateLocal(types: Array[Type], defn: ValDef | TypeDef, desc: FrameDescriptor): LocalFrameVal =
2     defn match {
3         case tdef: TypeDef =>
4             val kind = FrameSlotKind.Object
5             val slot = desc.addSlot(kind)
6             LocalFrameVal(slot, ReifiedType)
7         case vdef: ValDef =>
8             val idx = index(vdef.tpt.tpe)
9             val tpe = if (idx != -1) types(idx) else vdef.tpt.tpe
10            val kind = getFrameSlotKind(tpe)
11            val slot = desc.addSlot(kind)
12            LocalFrameVal(slot, tpe)
13    }

```

Figure 3.36: Extension to pseudocode that generates frame slots to include polymorphic definitions.

$$index(\tau) = \begin{cases} i & \text{def } f[t_0, \dots, t_i, \dots, t_n](\dots) \text{ if } t_i = \tau, owner(\tau) = f \\ -1 & \text{otherwise} \end{cases}$$

A mapping of types (via their symbols) to their respective index in the type argument array is sufficient to handle this resolution. Because we are only discussing methods polymorphic under their own type parameters, there are no polymorphic value parameters that are not resolvable in this context. The derivation of local frame values from monomorphic value definitions remains unchanged.

A type definition is treated in the same manner as a value definition; it is assigned a frame slot with a `Object` frame slot kind. This allows storing types in the method frame, allowing for the resolution of types after invoking a method template. So far, we have only discussed the resolution of type arguments in an intraprocedural context. Storing reified types in the frame during execution allows for the resolution in an interprocedural context. We will detail why this is important in the following subsection.

Truffle conveniently profiles the types of frame arguments to speculatively eliminate the unboxing of boxed values when reading frame values (including arguments). For example, the following invocation `list.contains((elem: Int))` will be profiled by Truffle even if we store `elem` in an `Object` frame slot. Truffle will then speculatively unbox `elem` in the body of `contains` if appropriate. We will discuss these optimizations and their limits in detail in Chapter 4.

```
1 def maximum[T <: Numeric](list: List[T]): Boolean = {
2   var max: T = zero
3   var curr: List[T] = a
4   while (!curr.isEmpty)
5     if (curr.head > max)
6       max = curr.head
7   max
8 }
```

Figure 3.37

In contrast, write operations of polymorphic frame values cannot be speculatively eliminated. Because Truffle does not specialize data layouts, i.e., frames are determined by their descriptors, which in turn are determined by the guest language implementation, frame writes of polymorphic values will always have to be boxed. The elimination of unnecessary boxed polymorphic writes from frame descriptor specialization is one of the major benefits when compared to the monomorphic interpreter. Code that has polymorphic code which reads and writes to a frame frequently will no longer have to unbox, compute primitive operations on unboxed values, then box those values back into their respective slots. Figure 3.37 contains an example program with polymorphic code that frequently writes to a

polymorphic local variable after some computation.

Case Study: A List Constructor

```
1 object List {
2   def apply[T](array: Array[T]): List[T] = {
3     var i = array.length - 1
4     var these: List[T] = Nil
5     while (i >= 0) {
6       these = new Cons[T](array(i), these)
7       i -= 1
8     }
9     these
10  }
11 }
```

Figure 3.38: An alternate static constructor that converts an `Array[T]` to a `List[T]`

In this subsection, we examine an example containing code Truffle cannot optimize well. Figure 3.38 gives an additional constructor that creates a polymorphic list from a polymorphic array. We focus on the term `array.length`, which computes the length for a polymorphic array on line 3. When the Typer detects an array operation on a polymorphic array value, it automatically inserts the array runtime bridge method responsible for handling the operation. For example, line 3 after the Typer would be transformed into `var i = array_length(array) - 1`. We give the implementation of `array_length` in figure 3.39.

In both Scala and the JVM, arrays of primitive types are invariant. That is to say, the type `Array[Int]` is neither a subtype or supertype of the type `Array[Any]`. On the other hand, the type `Array[T <: AnyRef]` is covariant. This contradiction in the presence of code that creates or operates on polymorphic arrays requires runtime bridge methods to appear seamless to a programmer. When combined with the nature of Scala’s type system, the Scala runtime obscures opportunities for speculative optimizations.

Notice the type of the argument in `array_length` is `AnyRef`; Because the types of arrays are invariant, the direct supertype is `AnyRef`, the type for any reference type. To compute the length for a polymorphic array, `array_length` switches over every similar but unrelated array type. In the body of every type check condition, the argument must be cast to the appropriate array type after the type check succeeds before the length is finally computed. We introduce a method to vastly simplify the Graal IR of such instances of

```

1 def array_length(array: AnyRef): Int = {
2     if (array.isInstanceOf[Array[AnyRef]]) array.asInstanceOf[Array[AnyRef]].length
3     else if (array.isInstanceOf[Array[Int]]) array.asInstanceOf[Array[Int]].length
4     else if (array.isInstanceOf[Array[Double]]) array.asInstanceOf[Array[Double]].length
5     else if (array.isInstanceOf[Array[Long]]) array.asInstanceOf[Array[Long]].length
6     else if (array.isInstanceOf[Array[Float]]) array.asInstanceOf[Array[Float]].length
7     else if (array.isInstanceOf[Array[Char]]) array.asInstanceOf[Array[Char]].length
8     else if (array.isInstanceOf[Array[Byte]]) array.asInstanceOf[Array[Byte]].length
9     else if (array.isInstanceOf[Array[Short]]) array.asInstanceOf[Array[Short]].length
10    else if (array.isInstanceOf[Array[Boolean]]) array.asInstanceOf[Array[Boolean]].length
11    else throw new NullPointerException
12 }

```

Figure 3.39: Implementation of `array_length`

array bridge methods when specialized methods would have type-specific information to augment JIT compilation.

```

1 import CompilerDirectives.castExact
2 def copyArgumentsToFrame(frame: VirtualFrame): Unit =
3     for ((param, arg) <- params zip frame.getArguments)
4         param.tpe match {
5             case Int =>
6                 frame.setInt(param.slot, arg.asInstanceOf[Int])
7                 ...
8             case Double =>
9                 frame.setDouble(param.slot, arg.asInstanceOf[Double])
10            case tpe: Array[AnyRef] | tpe: Array[Int] | ... | tpe: Array[Double] =>
11                frame.setObject(param.slot, castExact(arg, getClass(tpe)))
12            case _ =>
13                frame.setObject(param.slot, arg)
14        }

```

Figure 3.40: Pseudocode for `DefDefNode` and `Parameter`

As arrays are references, they are stored on frames via an `Object` slot. This alone is insufficient to optimize polymorphic frame slots for array types. Instead, we extend the way that frame arguments are copied into the frame from figure 3.5 in figure 3.40. Because a parameter now retains its type instead of a frame slot kind, we introduce a special operation when copying arguments that are arrays. The `castExact` directive is a type narrowing operation that hints to Graal that a value is an instance of a type. By injecting type information from TASTy into our executable IR, all subsequent checks that switch over the type of an array are simplified during partial evaluation.

Propagating Type Arguments

```
1 def subset[T](a: List[T], b: List[T]): Boolean = {
2     var curr: List[T] = a
3     while (!curr.isEmpty) {
4         if (!b.contains[T](curr.head)) return false
5         curr = curr.tail
6     }
7     true
8 }
```

Figure 3.41: An example where type arguments are derived from type parameters.

Polymorphic code has a habit of using other polymorphic codes. As a result, polymorphic invocations often occur inside the definition of a polymorphic class or a polymorphic method. That is to say that the type argument at a type application site could be a type parameter. Figure 3.41 is an example where a type application occurs inside the definition of a polymorphic method and derives its type argument from a type parameter.

```
1 class MethodParamTypeNode(@Child readLocal: ReadLocalNode) extends TypeNode {
2     override def resolveType(frame: VirtualFrame): Type =
3         readLocal.execute(frame).asInstanceOf[Type]
4 }
```

Figure 3.42: The type node for dynamically resolving method type parameters.

We introduce a subclass of a type node that retrieves method type arguments stored on the frame. Because type parameters are treated the same manner as value parameters, they are stored in the method's frame. The resolution of type arguments which are parameters from a method, follows the same mechanism as the resolution of local variables. This mechanism enjoys the same Truffle virtualization optimizations of value reads when propagating type arguments interprocedurally. In turn, subsequent invocations of polymorphic methods that have type parameters stored on the frame will partial evaluate their specializations.

3.2.2 Specializing Classes

```

1 def parseClassDef(cdef: ClassDef, types: Array[Type]): ClassShape = {
2   val parents = cdef.parents.map(_.symbol)
3
4   val fields = cdef.body map {
5     case vdef: ValDef => generateField(vdef, types)
6   }
7
8   val methods = (cdef.constructor :: cdef.body) map {
9     case ddef: DefDef => ddef.symbol.signature -> parseDefDef(ddef)
10  }
11
12  val vtable = cdef.symbol.methodMembers map {
13    symbol => symbol.signature -> symbol
14  }
15
16  new ClassShape(cdef.symbol, parents, fields, init ++ methods, vtable)
17 }

```

Figure 3.43: Extensions to specialize a `ClassDef`.

This section details the specialization of classes and class members with polymorphic semantics based on class type parameters. Previously we discussed the specialization of methods that are solely polymorphic under their parameters without the mention of methods that are class-polymorphic. The reasoning behind this decision can be explained thus: The invocation of a class-polymorphic method requires a look up into that class’s shape; by extension, that class must be specialized before such a polymorphic invocation may occur. For example, the method `List.contains` in figure 2.1 contains method-polymorphic semantics that are resolved *after* a polymorphic class instance is created.

As class specialization does not share the same demands regarding runtime mechanisms as method specialization, we will adopt a rewrite-driven approach to specializing class definitions at object creation sites. We will use techniques to monomorphize, at least partially, polymorphic TASTy trees instead of altering the transformation of a `ClassDef` to a `ClassShape`. With this rationale, we can adapt many elements of the monomorphic interpreter for polymorphism.

Figure 3.43 provides an overview of the steps that are required to create a specialized monomorphic `ClassDef` from a polymorphic origin. Similar to how type definitions become parameters when reified in the context of a `DefDef`, type definitions in the context of `ClassDef` become fields when reified. The rationale is that instances of specialized polymorphic classes store their specialized type fields to propagate types. Figure 3.44 gives the pseudocode for a type node that resolves a type parameter from an instance of a special-

```

1 class ClassParamTypeNode(@Child readField: ReadFieldNode) extends TypeNode {
2   override def resolveType(frame: VirtualFrame): Type =
3     readLocal.execute(frame).asInstanceOf[Type]
4 }

```

Figure 3.44: The type node for dynamically class method type parameters.

ized class. We rewrite both value and method definitions to transform polymorphic class definitions into monomorphic class definitions.

Creating Specialized Instances

```

1 parseType(tpe: Type): TypeNode = tpe match {
2   ...
3   case AppliedType(con, targs) => new AppliedTypeNode(parseType(con), targs map parseType)
4 }
5
6 class AppliedTypeNode(@Child con: TypeNode, @Children targs: Array[TypeNode]) extends TypeNode {
7   @ExplodeLoop
8   override def resolve(frame: VirtualFrame): Type {
9     val types = Array.empty[Type]
10    for (targ <- targs)
11      types += targ.resolve(frame)
12
13    AppliedType(con.resolve(frame), types)
14  }
15 }
16
17 def shapeOf(tpe: Type): ClassShape = tpe match {
18   ...
19   case AppliedType(con, targs) =>
20     val cdef = getClassDef(con)
21     parseClassDef(cdef, targs)
22 }

```

Figure 3.45: The `AppliedTypeNode` and its derivation from an `AppliedType`.

The `AppliedType` is the analogue of `TypeApply` for type applications when creating object instances. We can derive a specialization site for class definition by the reification of an applied type into an `AppliedTypeNode`. Figure 3.45 is an overview of the `AppliedTypeNode` and its derivation from its TASTY type counterpart. In our subset of TASTy, an applied type represents an instantiation of a polymorphic type.

```
1 new List[Int]
```

Figure 3.46: Example of creating instance of an applied type.

For example, consider the term, given in figure 3.46, that returns an instance of a polymorphic type. The type `List[Int]` is the result of the type application of `List[T]` to `Int`. We will refer to polymorphic applied types, such as `List[T]`, as *polymorphic* applied types. The data representation of a polymorphic applied type is undetermined; Depending on the type arguments supplied during type application, the data representation will vary.

```
1 NewNode(AppliedTypeNode(TypeRefNode("List"), Array(TypeRefNode("Int"))))
```

Figure 3.47: TastyTruffle IR of creating an instance of an applied type.

When executable nodes are derived from polymorphic applied types, given in figure 3.47, type arguments are resolved during runtime before application to their type constructor. We refer to the instantiations resulting from the application of type arguments to polymorphic applied types as *monomorphic* applied types (e.g., `List[Int]`). Having a monomorphic applied type provides the opportunity to generate a specialized shape. Therefore, each group of monomorphic applied types has a unique data representation. For example, a `List[Int]` and `List[Double]` will each have a unique data representation, and the underlying layout of their instances will be different. However, a `List[String]` and `List[List[Int]]` will share the same data representation as their type arguments are reference types and will not see any benefit from independent specialization. Therefore, creating an object instance with a polymorphic class definition will have its shape determined when its created.

This approach avoids the issue of *name mangling*. Name mangling is a technique to disambiguate distinct entities in a program that share the same name but do not inhabit the same namespace (e.g., a `package`). In the context of parametric polymorphism and specialization, many approaches to specialization require specialized classes and methods to have mangled names. The creation of polymorphic classes and call sites of polymorphic methods must be rewritten to refer to the correct specialization. In our approach, operations on object instances with a polymorphic type are unaffected by its underlying shape. In the next section, we give extensions on generating a static shape from a monomorphic

applied type after type application.

Case Study: `Cons.head`

```
1 val list: List[Int] = ???
2 list.contains(0)
```

Figure 3.48: Example invocation of `Cons.contains[Int]`

In this subsection, we introduce an example, given in figure 3.48, that motivates the specialization of shapes. The example is a source-like representation of `List.contains[Int]`, the specialized variant of the `List.contains` method. We compare the body of `List.contains` with and without a specialized storage layout for the implementation of `contains` in the `Cons` class.

```
1 def contains$Int(elem: Int): Boolean = {
2   var these: List = this
3   while (!these.isEmpty) {
4     val head = these.head.asInstanceOf[Int]
5     if (unbox(head) == elem)
6       return true
7     else
8       these = these.tail
9   }
10  false
11 }
```

(a) Implementation of `contains` in a erased `Cons` class.

```
1 def contains$Int(elem: Int): Boolean = {
2   var these: List = this
3   while (!these.isEmpty) {
4     // val head = ...
5     if (these.head == elem)
6       return true
7     else
8       these = these.tail
9   }
10  false
11 }
```

(b) Implementation of `contains` in a specialized `Cons` class.

Figure 3.49a contains a source-like representation of `contains` if the data layout of `Cons` follows the standard translation of type erasure but the method is still specialized. We draw attention to the example’s equality operation defined on line 4. Without the specialization of either classes or methods, both the left-hand-side and right-hand-side operands would be boxed integers, and the `==` operation dispatches to `these.head.equals(elem)`. However, because methods are specialized and classes are not specialized in our case, the `head` field must be unboxed before equality can be checked. Figure 3.49b contains the specialized equivalent code of 3.49a. Once the class layout is specialized, no unboxing is present in the program.

Specializing Class Members

```

1 def generateField(vdef: ValDef, types: Array[Type]): Field = vdef match {
2   case ValDef(_: String, tpt: TypeTree, rhs: Option[Term]) =>
3     val idx = index(tpt.tpe)
4     val tpe = if (idx > 0) types[idx] else tpt.tpe
5     new Field(vdef.symbol, tpe)
6 }

```

Figure 3.50: Extensions to generate a field from a polymorphic value definition.

This section extends the translation scheme for generating shapes from class definitions to include polymorphic class definitions. There are two elements of data layout that must be determined when generating the shape of a polymorphic class definition. Fields constitute the portion of data layout on an object instance that must be resolved with monomorphic types for value definitions. Local frame values whose frame slot kinds must be derived from polymorphic type parameters constitute the other portion of the data layout in a class definition that must be specialized.

The underlying type of a polymorphic field, and therefore its data representation as part of its static shape, cannot be determined statically. When the field translation scheme is supplied with type arguments, we can generate the specialized monomorphic field. Figure 3.50 extends the pseudocode that generates fields for shapes to include polymorphic value definitions. If it is beneficial to specialize a field, e.g. `val x: T` or `val x: Array[T]`, we resolve the type parameter from the type arguments to generate a specialized field property. Otherwise, we default to the monomorphic implementation for generating a field.

Polymorphic methods challenge specialization because they can be polymorphic under two sets of type parameters. As a result, dynamically resolved types are not available for specialization at the *same* time; Class type arguments are available at object creation, and method type arguments are available at invocation. To address this, we need to be able to **partially specialize** methods from the class perspective. Figure 3.51 extends the translation of `DefDef` nodes with class type arguments. If the method is polymorphic under class type parameters, the layout of a frame for the root node of a `DefDef` must be partially determined.

$$index(\tau) = \begin{cases} i & \text{def } f[t_0, \dots, t_i, \dots, t_n](\dots) \text{ if } t_i = \tau, owner(\tau) = f \\ j & \text{class } C[t_0, \dots, t_j, \dots, t_m](\dots) \text{ if } t_j = \tau, owner(\tau) = C \\ -1 & \text{otherwise} \end{cases}$$

```

1 def parseDefDef(ddef: DefDef, types: Array[Type]): DefDefNode | DefDefTemplate = {
2   val tparams = ddef.params.filter(_.isInstanceOf[TypeDef]).length
3
4   val vparams = ddef.filter(_.isInstanceOf[ValDef]) map {
5     case vdef @ ValDef(_, tpt, rhs) => specializeValDef(desc, vdef, types)
6   }
7
8   val locals = liftLocals(ddef.rhs) map {
9     case vdef @ ValDef(_, tpt, rhs) => specializeValDef(desc, vdef, types)
10  }
11
12  if (vparams.forall(_.isInstanceOf[LocalFrameVal]) && locals.forall(_.isInstanceOf[LocalFrameVal]))
13    new DefDefNode(desc, vparams, ddef.rhs)
14  else
15    new DefDefTemplate(desc, tparams, vparams, locals, ddef.rhs)
16 }

```

Figure 3.51: Extension to parse a `DefDef` with class type arguments.

We extend the definition of `index` to resolve the index of a type parameter to a corresponding type argument array in a context-sensitive manner (i.e., whether type arguments originate from a type application of a class or a method).

After the class specialization of a `DefDef`, it is still possible that a `DefDef` contains polymorphic semantics. However, all polymorphism that is derived from a class type parameter has been specialized, and such terms and parameters are now monomorphic. Therefore, a `DefDef` that is still polymorphic is only polymorphic under its own type parameters. The remaining polymorphic data layout will be specialized when the method template is invoked.

As an example, we give figure 3.52 to show the data layout of the specialized class `Cons[Int]`. We omit the runtime elements of a shape in our example as we only want to show how the data of a specialized shape is organized. The only object storage property that differs between class specializations is the `head` field. For the specialization `Cons[Int]`, the `head` field is stored with the `Int` type. The storage types of fields may differ between specializations; they are all referenced by the same symbol. This allows the access of fields between specializations to remain opaque from the perspective of client code.

The layout of the shape with respect call targets remains unchanged. Call targets are duplicated across each shape of a specialized class definition. Because method definitions potentially contain polymorphic code that relies on class type parameters, this duplication is necessary.

Each specialized shape contains fields that store the type argument of their specializa-

```
1 ClassShape(  
2     "Cons$Int",  
3     Array(  
4         Field("T", Object),  
5         Field("head", Int),  
6         Field("tail", Object)  
7     ),  
8     Map(  
9         "length()"          -> DefDefNode("length")  
10        "contains[1](scala.Any)" -> DefDefTemplate("contains")  
11        "hashCode()"         -> DefDefNode("hashCode")  
12    ),  
13    ...  
14 )  
15 )
```

Figure 3.52: Shape of `Cons[Int]`

tion. While these remain constant throughout all instances of the same specialized shape, allowing us to store the type arguments on shapes directly. Having type parameters as fields allow the reuse of the field access interface for class type definitions.

Chapter 4

Evaluation

In this chapter, we will evaluate and discuss the performance of our polymorphic interpreter on six microbenchmarks. We use an existing set of benchmarks from [75] as they exercise many features of the Scala runtime that require specialization to perform optimally. We will evaluate the performance of these benchmarks on the monomorphic interpreter and Scala bytecode on GraalVM as points of comparison for relative performance. Finally, we discuss the results of the benchmarks, examine the causes of performance deficiencies, and how our implementation resolves them.

4.1 Benchmarks

In this section, we will introduce an additional program on top of our running example for benchmarking. We will also summarize the motivations for selecting these benchmarks from [75].

Each microbenchmark exercises unique polymorphic operations which are typically performance bottlenecks[64][68] in Scala programs. The `ArrayBuffer` class implements a resizable buffer backed by an array. It contains three microbenchmarks that stress polymorphic operations in the context of contiguous memory access.

The `List` class is the implementation of a linked list that we have used as the running example in this thesis. We use the `List` class to evaluate polymorphic operations in the context of random heap access. Like the `ArrayBuffer` benchmarks, there is an `append` and `contains` microbenchmark. We will use lists to test the performance of polymorphic hash computations using `List.hashCode`.

```

1 class ArrayBuffer[T] {
2     protected def initialSize: Int = 16
3     var size0 = 0
4     var array: Array[T] = newArray[T](Math.max(initialSize, 1))
5
6     def length: Int = size0
7
8     private def get(i: Int): T = array(i)
9     private def set(i: Int, elem: T): Unit = array(i) = elem
10
11     def contains(elem: T): Boolean = {
12         var i = 0
13         while (i < size0) {
14             if (array(i) == elem) return true
15             i += 1
16         }
17         false
18     }
19
20     def reverse(): Unit = {
21         var pos = 0
22         while (pos * 2 < size0) {
23             swap(pos, size0 - pos - 1) // swaps two elements in the array
24             pos += 1
25         }
26     }
27
28     def append(elem: T): Unit = {
29         val newSize0 = size0 + 1
30         ensureSize(newSize0)
31         set(size0, elem)
32         size0 = newSize0
33     }
34
35     // Ensure that the internal array has at least `n` cells.
36     def ensureSize(n: Int): Unit = {
37         val arrayLength: Long = array.length // Use a Long to prevent overflows
38         if (n > arrayLength) {
39             var newSize: Long = arrayLength * 2
40             while (n > newSize)
41                 newSize = newSize * 2
42             // Clamp newSize to Int.MaxValue
43             if (newSize > lang.Int.MaxValue) newSize = lang.Int.MaxValue
44
45             val resized = newArray[T](newSize.toInt)
46             var i = 0
47             while (i < size0) {
48                 resized(i) = get(i)
49                 i += 1
50             }
51             array = resized
52         }
53     }

```

Figure 4.1: Code of the ArrayBuffer benchmark.

4.2 Methodology

Performance measurement of just-in-time compiled programs is an infamously difficult issue[43][39]. Many non-deterministic effects, such as speculative optimization, garbage collection, and thread scheduling, affect the performance of programs executing on the Java Virtual Machine. As a result, the JVM must be *warmed up* before measuring program performance. A benchmarking routine is warmed up with several iterations of invocations for profiling data to be collected and JIT compilation to be finished. Therefore the measured performance of a microbenchmark will record the program executing the stable JIT compiled code instead of code executing in the interpreter.

Each benchmark method in this chapter is warmed up with 10 iterations of warmup lasting 10 seconds each. Results of these are measured in throughput, the number of executions that were successfully completed in a second. The results are averaged from 10 measurement iterations for 10 seconds each. We evaluate our microbenchmarks on input sizes between one hundred thousand and one million elements to account for memory factors in our benchmarks. Each benchmark is run on three different implementations, Scala on GraalVM (Gaal), the monomorphic interpreter (Mono), and the polymorphic interpreter (Poly). While we provide the evaluation of our benchmarks on Scala and GraalVM, we do so to provide a baseline to show that the performance of our monomorphic interpreter is reasonable and that the performance improvement of our polymorphic extensions is fair.

4.3 Experimental Results

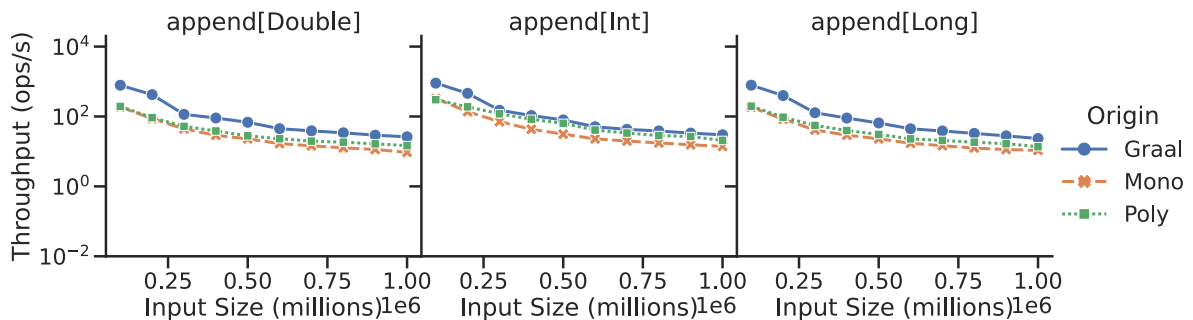


Figure 4.2: Benchmark results for `ArrayBuffer.append`.

The benchmark for `ArrayBuffer.append` inserts a sequence of elements into a newly initialized array buffer. This benchmark stresses array memory movement. Each time the backing array is too small for an additional element, the backing array is resized by creating a new larger array and copying over existing elements. This resizing operation (`ensureSize` in 4.1) dominates the time spent in execution. Because of this bottleneck, executing compiled Scala bytecode on GraalVM is up to 4 times faster than the monomorphic and polymorphic interpreter.

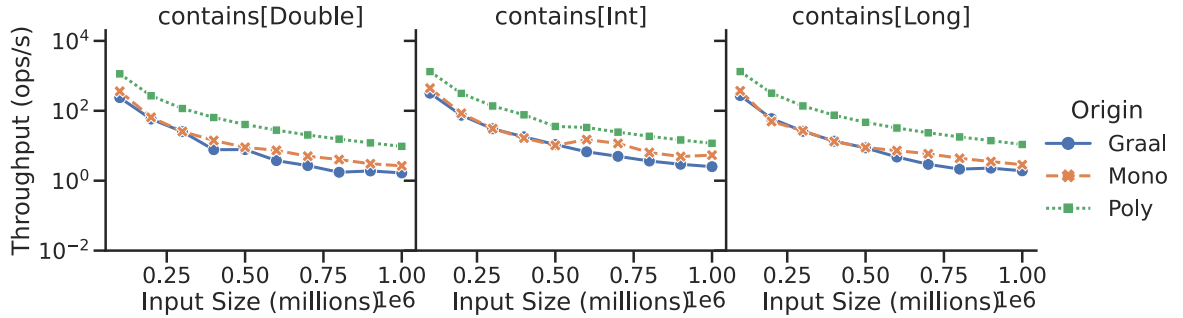


Figure 4.3: Benchmark results for `ArrayBuffer.contains`.

The `ArrayBuffer.contains` benchmark tests array operations in isolation. The benchmark checks an array buffer for the existence of an element. It exercises a polymorphic array access followed by a polymorphic equality operation (e.g. $(x: T) == (y: T)$). A polymorphic equality operator has dispatched the `equals` method of its left-hand side argument. This results in boxing one or both arguments in equality checks between polymorphic values.

`ArrayBuffer.reverse` reverses the order of the elements in the array buffer. Reversing an array is performance-bound by the loop of swap operations. A swap operation (given in 4.5) consists of two polymorphic value definitions (frame writes) initialized from polymorphic array accesses followed by the inverse of those two operations.

The performance of this microbenchmark proved to be the most challenging benchmark in terms of matching handwritten monomorphic code in [75]. The performance of each type variant of `reverse` is roughly equal in the monomorphic interpreter and Scala and GraalVM; Neither implementation can specialize the polymorphic reads and array accesses. The polymorphic interpreter has up to 25 times more throughput than the monomorphic interpreter and GraalVM.

The `List.append` benchmark constructs a list from an array. As the creation of poly-

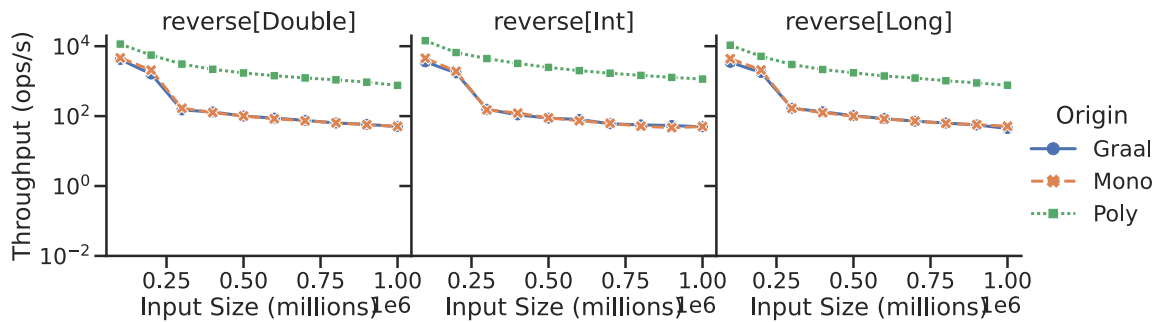


Figure 4.4: Benchmark results for `ArrayBuffer.reverse`.

```

1 def swap(i: Int, j: Int): Unit = {
2   val tmp1: T = get(i)
3   val tmp2: T = get(j)
4   set(i, tmp2)
5   set(j, tmp1)
6 }

```

Figure 4.5: Code to swap two elements in an array buffer

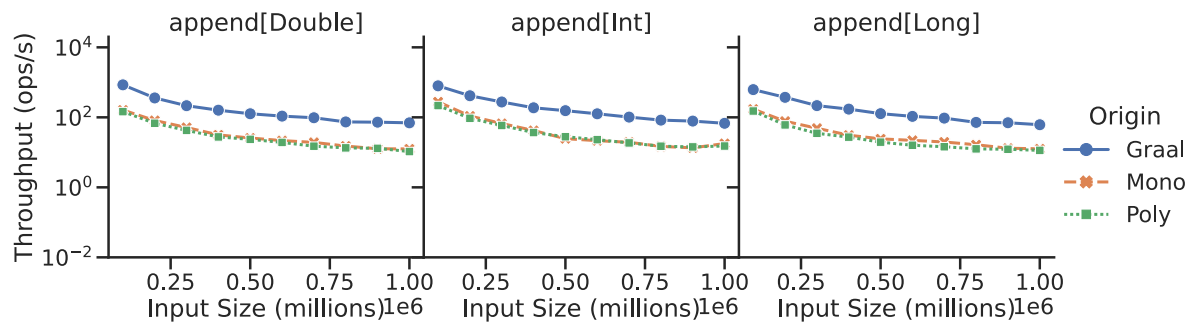


Figure 4.6: Benchmark results for `List.append`.

morphic instances is predominantly memory-bound and not compute-bound, there is no significant improvement in throughput from specialization. In fact, executing Scala via Java bytecode on the JVM results in substantially greater throughput.

`List.contains` exercises the same performance-bottlenecks as `ArrayBuffer.contains`,

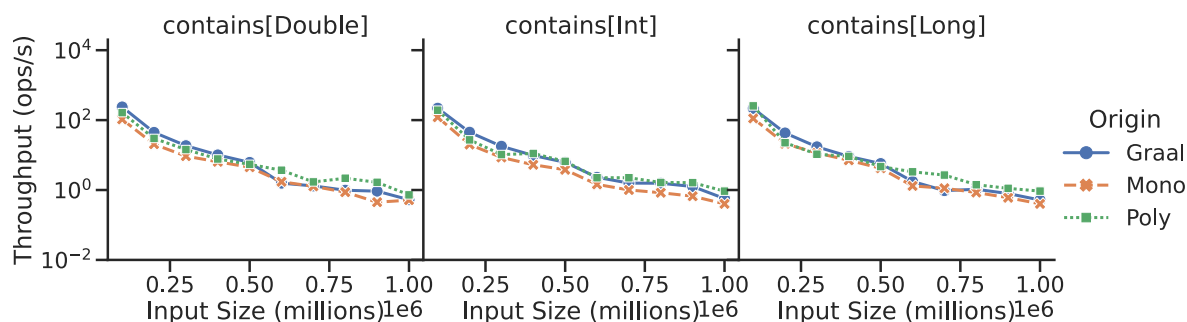


Figure 4.7: Benchmark results for `List.contains`.

except under the context of random heap access for a list. The execution of `List.contains` on the polymorphic interpreter is roughly 50% faster than on the monomorphic interpreter.

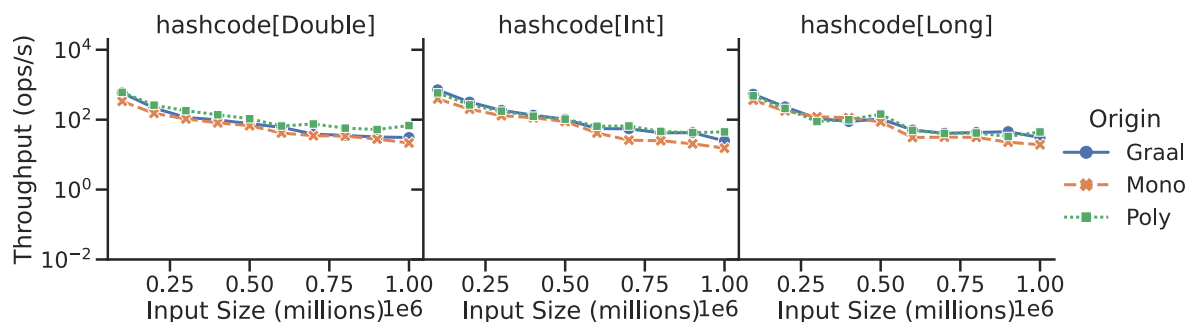


Figure 4.8: Benchmark results for `List.hashCode`.

`List.hashCode` tests the specialization of the hash code function. Every class in Scala inherits the `hashCode` function from the `T` type. When the `hashCode` method is invoked in a polymorphic context, the Scala compiler inserts the `anyHash` bridge. The semantics of computing hash codes between the same values with different types, such as `Int` and `Long`, necessitates the insertion of this bridge, which complicates JIT compilation.

Figure 4.9 gives the implementation of the `anyHash` function. In the `Int` and `Long` invocations of `List.hashCode`, the polymorphic interpreter keeps parity with the implementation of Scala on GraalVM. In the `Double` invocation of `List.hashCode`, the throughput on the polymorphic interpreter is 2.5 times greater than that of the implementation of the monomorphic interpreter.

```
1 public static int anyHash(Object x) {
2     if (x == null) return 0;
3     if (x instanceof Long) return longHash(((Long) x).longValue());
4     if (x instanceof Double) return doubleHash(((java.lang.Double) x).doubleValue());
5     if (x instanceof Float) return floatHash(((Float) x).floatValue());
6
7     return x.hashCode();
8 }
```

Figure 4.9: Implementation of the `anyHash` function.

4.4 Discussion

In this section, we discuss the results of our evaluation through the examination of Graal IR. We will specifically look at the performance overhead of autoboxing operations when combined with the Scala runtime. We divide the discussion into two segments. The first covers the performance benefits of specialization methods and classes for each value type in Scala. The second shows the impact of specializing methods and classes for array types.

4.4.1 Inspecting Graal Graphs

Many of our microbenchmarks, such as `List.contains` and `List.hashCode`, rely on optimal frame and field accesses (without boxing) for performance. This subsection examines the Graal IR of `List.head`. We show that the Graal IR of the microbenchmarks on the monomorphic interpreter contains autoboxing nodes that incur performance overheads compared to the Graal IR of the same programs seen in the polymorphic interpreter.

As previously mentioned, Truffle can speculatively optimize read operations on boxed frame values. Figure 4.10, contains the parameter of `elem` in `List.contains`, which is an example of such a speculative optimization. This speculative optimization relies on a `TrustedBoxedValue` to unbox the primitive. A `TrustedBoxedValue` represents injected information from an external source.

In this particular case, it is known by the compiler that the boxed instance comes from the invocation `List.contains((elem: Int))`. Unique `int` values may be mapped to a unique `Integer` instance in the Java runtime, eliminating unnecessary boxed object creation. The unbox operation in node 848 will be ‘floated’ up the graph such that all subsequent nodes dominated by the reading of a boxed frame value have no autoboxing.

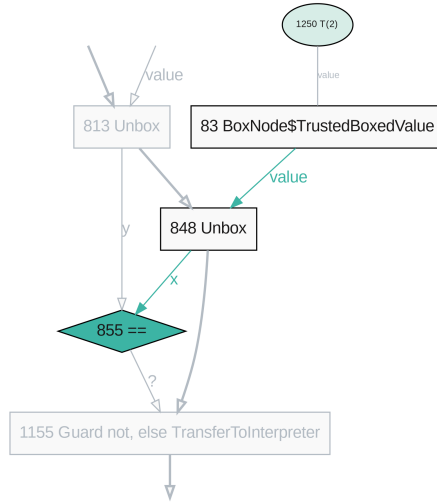
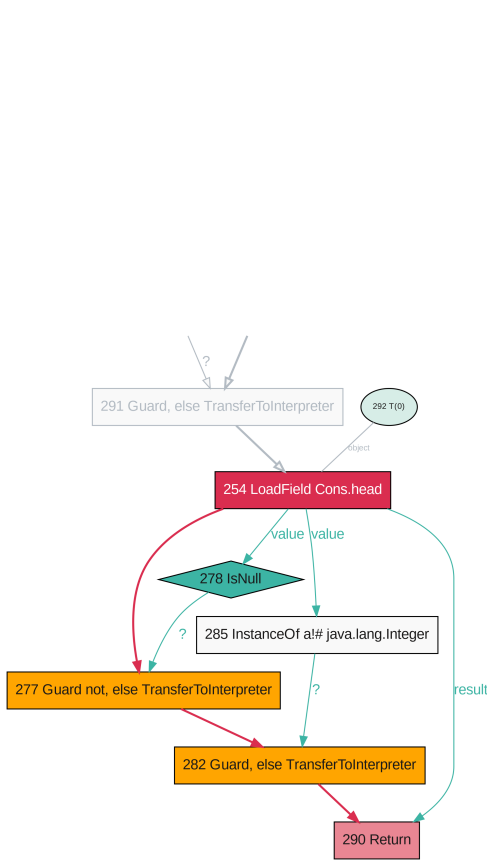


Figure 4.10: Graal IR with speculative unboxing of `elem` based on a type profile of its frame slot in `List.contains`

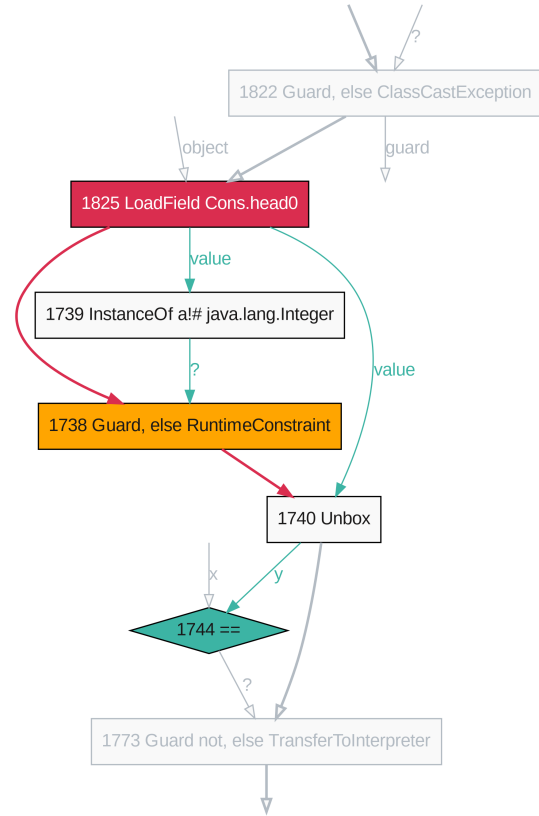
This optimization is also possible because the invocation of `contains` occurs in a single type context. That is, `contains` is only ever invoked with a single type argument in our microbenchmark; therefore, Truffle can insert speculative optimizations based on the type of the argument passed. As the number of types is limited, in our case, only a single type, the value can be speculatively unboxed. This optimization would *not* be possible in a multiple type context, where `contains` is invoked at many sites with distinct value type arguments. This type of invocation environment, more commonly found in real-world programs, pollutes the type profiles of the method and inhibits speculative unboxing operations. In theory, our approach to method specialization would not be hindered by this problem; we consider the evaluation of the interpreter in this environment out of the scope of this thesis.

We examine in detail the Graal IR focusing on the `List.head` accessor method in our `List` running example. The accessor is frequently used in our `List` microbenchmarks; Performance of `List.contains` and `List.hashCode` depends on the elimination of the unboxing in this method. We focus on unboxing when the `head` field is accessed by the `List.head` accessor. This unboxing can be seen in 4.11a.

We can see that *guard* nodes are inserted by Graal into the compiled graph during JIT compilation. A guard node ensures that a speculative assumption still holds during execution. Because the default storage type of a polymorphic field without specialization



(a) Graal IR of `Cons.head` focused on field access of `head0`



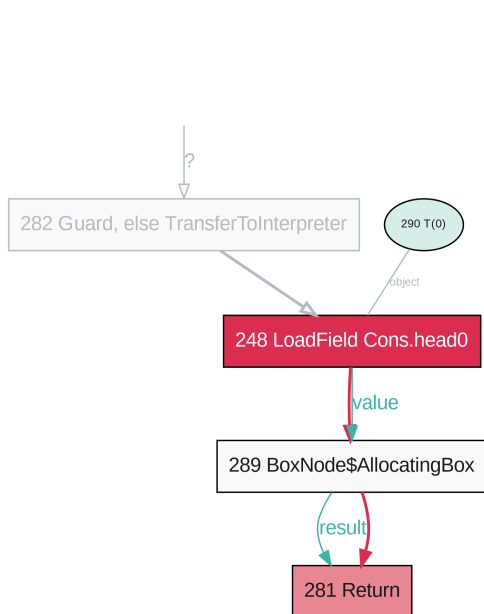
(b) Graal IR of `Cons.head` after being inlined into `Cons.contains`

is an `Object`, Graal makes two runtime assumptions about the field in the JIT compiled `contains` method to ensure the compiled method does not throw a runtime exception if the return value needs to be unboxed. The first guard, identifiable by node 278, checks that the value is not the `null` reference. As the `null` value is only compatible with reference types, attempting to unbox a `null` value produces a runtime exception. The second guard, with the identifier 282, is a type check that the value is an `Integer` object. Notice that the predecessor node is the type check `instanceof a!# java.lang.Integer` and not `instanceof java.lang.Integer`. `instanceof` nodes in Graal IR checks against *stamps* instead of normal JVM types identifiers. A stamp is much like a type identifier but has additional descriptors attached. For example, the stamp `a!# java.lang.Integer` has

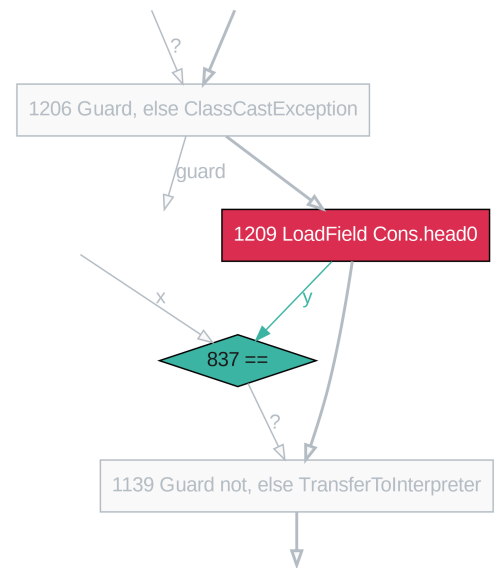
the following descriptors:

- (a) Asserts that the stamp marks a reference type identifier. In the case of this stamp, the stamp marks the boxed reference type `java.lang.Integer`.
- (!) Asserts that value is not the `null` reference value. The stamp contains this descriptor because it is preceded by a non-null guard.
- (#) Asserts that value marked by the stamp is *exactly* an instance of the type identifier described by the stamp and not an instance of a subclass of the type identifier

In more succinct terms, the `instanceof` node 285 checks that value is precisely the instance of a `java.lang.Integer` and is not the `null` value. If the assumptions are not violated in compiled code, the boxed integer value is then returned from the compiled code. Note that no unboxing happens because the value of `head` has not yet been used in a polymorphic context.



(a) Graal IR of `List.head` after field read of `head` is specialized.



(b) Graal IR of `Cons.head` after being inlined into `Cons.contains`

When the access or method `List.head` is inlined into its callsite in `Cons.contains` (see figure 4.11b), an unbox operation is introduced because the equality operation in node 1744 compares primitives and not references. Notice that the two guards nodes previously seen in figure 4.11a are folded into one node because the `instanceof` node is an extension of the null check node. Because polymorphic field values are stored as a reference on the object instance, these speculative assumptions are necessary to generate compiled code. To eliminate the overhead of the unbox operation and the accompanying guard nodes, The polymorphic fields of a class must be specialized.

Figure 4.12a contains the field access of `head` after the field has been specialized and has the appropriate storage type in the storage layout of `Cons[Int]`. Notice that a box node has been introduced prior to the value of `head` prior to the return node of `Cons.head`. Because the `execute` method of a `DefDefNode` returns an `Object`, the return value is preemptively boxed when inspecting the IR of the method. However, after inlining into the body of `Cons.contains`, the box operation is no longer necessary as the boxed value will be immediately unboxed. Graal will automatically eliminate this type of autoboxing. When a specialized class instance is used in place of a generic class instance, the field access subgraph of `List.head` is fully simplified.

4.4.2 Mixing in Array Type Information

While eliminating the autoboxing of frame and field accesses provided incremental improvements, incorporating array type information atop produced further throughput improvements for our array-backed microbenchmark. In this subsection, we examine the Graal IR that contain type switches for the Scala runtime to handle arrays.

Figure 4.14 contains the Graal IR of `array_length` inlined into `List.apply[T]`. Notice that the `instanceof` type checks nodes (white) that are succeeded by an `ArrayLength` node (red) for each of the branches in `array_length`. The numerous consecutive conditional expressions complicate the control flow analysis in JIT compilation. These conditional checks add unnecessary branching and burdens JIT compilation when the type of a specialized array could be known from specialization.

Figure 4.13 contains the simplified Graal IR of `array_length` inlined into `List.apply[T]`. Notice that there is a single `ArrayLength` node that is dominated by a π node. A π node^[17] enforces a bound on a value. In the case of Graal, a π node enforces bound on the type of a value. More specifically in our example, the π node narrows the type of the 2nd parameter of `List.apply[T]` to a monomorphic array type. When the type of the parameter is

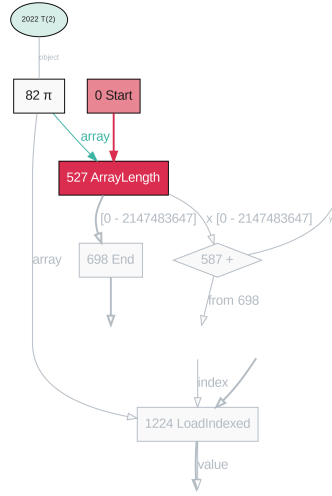


Figure 4.13: Graal IR of `array_length` in the context of `List.apply[T](array: Array[T])` augmented with a π node

narrowed, the type checks that enforce array types from figure 4.14 are eliminated because the type is now known.

This method does not consider polymorphic scenarios where an array of boxed primitives are used interchangeably with an array of primitives. Such scenarios would require the insertion of additional autoboxing nodes or an intraprocedural transformation where boxed arrays are converted to primitive arrays. While these solutions are possible in the context of Truffle, we consider these kinds of scenarios out of the scope of this thesis.

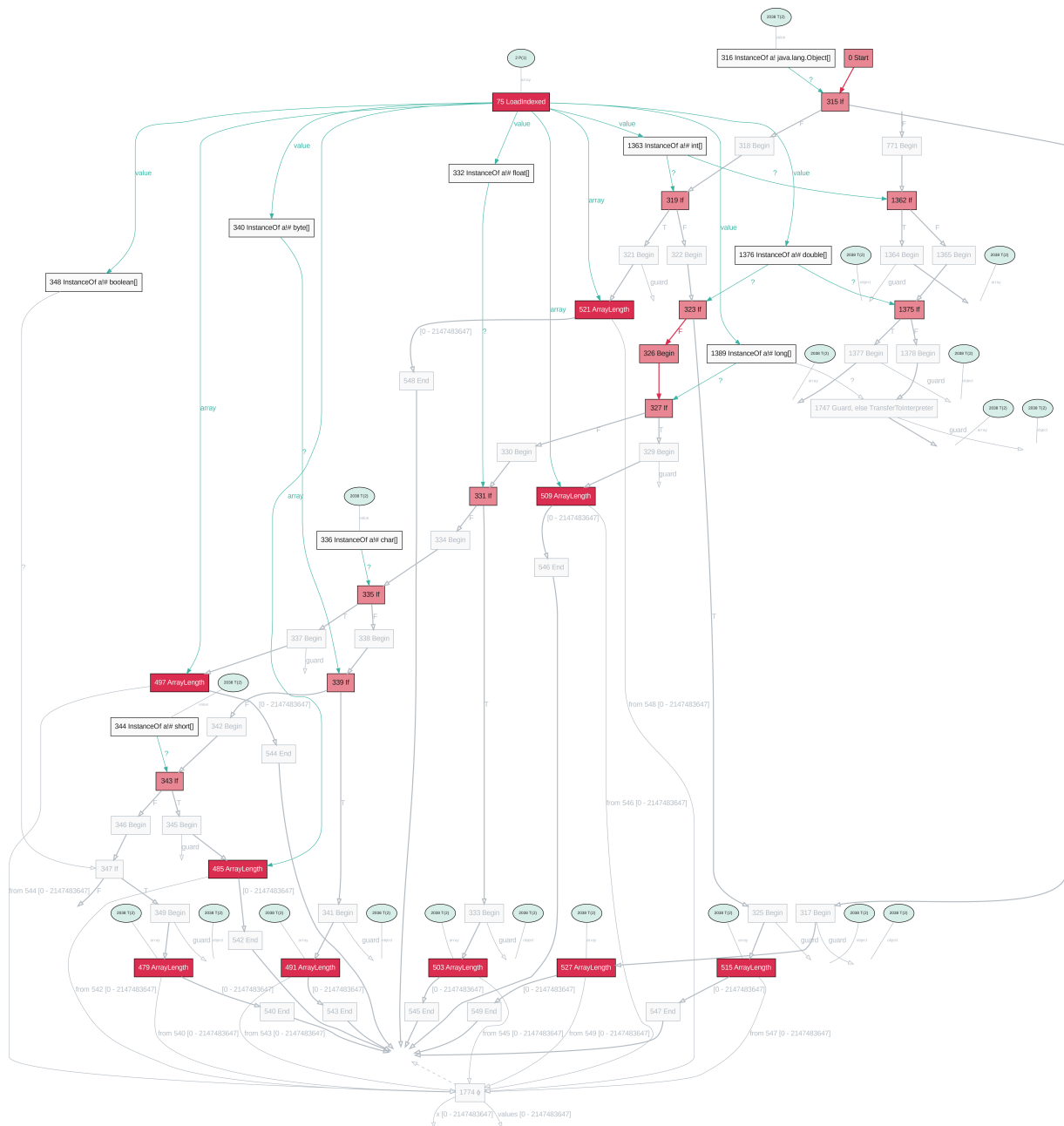


Figure 4.14: Graal IR of `array_length` in the context of `List.apply[T](array: Array[T])`

Chapter 5

Related Work

This chapter discusses previous academic and industrial work related to this thesis. The first section provides an introduction to the various implementations of parametric polymorphism. The second section is a brief overview of programming languages that support a notion of reified types. The third section covers related work on the implementation of polymorphism in Java. The fourth section of this chapter provides an overview of previous and state-of-the-art efforts to specialize Scala programs. The last section presents prior and ongoing efforts in the implementation of other Truffle interpreters.

5.1 Implementations of Parametric Polymorphism

Implementations of parametric polymorphism can be divided into two broad categories[20]:

Homogeneous Translation This approach provides a single data representation for each polymorphic type. An example of this implementation is the type erasure transformation applied in the Java and Scala compilation pipelines. Morrison et al. also refer to this form of polymorphism as the `uniform polymorphism`[?].

Heterogeneous Translation In contrast to homogeneous translation, the heterogeneous translation ensures a unique data representation for every polymorphic type instantiation. The heterogeneous translation can also be referred to as *textual polymorphism*.

This section will cover various approaches to implementing parametric polymorphism in the context of these two forms. As polymorphism in Java and Scala are more relevant

to the central themes of this thesis, we will first focus on implementations of parametric polymorphism for other languages.

Parametric polymorphism was first studied in functional programming languages[55, 30]. Leroy proposed an approach in which type coercion operations are inserted between polymorphic operations and monomorphic data. The coercion operations in this approach are quite similar to the notion of boxing and unboxing, which Leroy describes as *wrapping* and *unwrapping*.

The heterogeneous translation is the more prevalent implementation of parametric polymorphism in object-oriented programming languages. The `template` concept in the C++ programming language popularized parametric polymorphism in objected-oriented programming languages. Templates define a generic definition of some kind in C++. The C++ compiler will generate heterogeneous translations based on every set of concrete type arguments supplied during compilation. The implementation of polymorphism in the Common Language Runtime[54, 53] by Kennedy and Syme makes use of reified types in a polymorphic bytecode IR during execution. Polymorphic class definitions are loaded as templates; Templates generate specialized class layouts on an ad-hoc basis based on the reified type arguments seen during bytecode execution. Their approach relies on CLR extensions to support types not present in existing JVM implementations. Our approach shares many similarities with the approach described by Kennedy and Syme. One drawback of their approach is that the polymorphic bytecode IR does not support the complete set of operations on types. For example, reflection is necessary to differentiate between a `List[Int]` and a `List[String]`. Our implementation differs as such operations are possible because the IR could potentially incorporate the full type language of TASTy.

5.2 Implementations of Reified Types

Some programming languages have previously introduced similar notions of types-as-values. Zig[2] permits compilation-time types as first-class values. Compile-time evaluation in Zig exposes constant folding as a useful abstraction. Specific instantiations of generic data structures are then created based on reified type values during compilation-time. Hack[4] and Kotlin[3] both have the notion of *inline reified types*. More specifically, reified types in Hack and Zig allow type parameters of user-annotated inline-able methods to be available during run-time. Combined with inlining, this allows concrete type arguments from invocation sites to be used in the method body. For example, run-time type switches over types without needing reflection are possible in the context of inline reified types.

5.3 Generics and Java

Prior efforts to implement generics in Java have been based on static compilation techniques restricted by the *open world assumption*. The open world assumption assumes that the program under compilation is *incomplete*; extra parts of the program will be supplied in a future iteration of compilation. This form of compilation is commonly known as *separate compilation*. As such, the compilation results of the current parts of the program must be interoperable with the compilation results of the remaining yet-to-be-determined parts.

The Java language did not initially support parametric polymorphism in its initial release. As a result, many different approaches were proposed before a uniform polymorphism became the accepted implementation for Java. Pizza[60] was a superset of Java that supported heterogeneous and homogeneous translations of polymorphic definitions into Java. Agesen, Freund, and Mitchell proposed a heterogeneous translation for parametric polymorphism for Java during load-time instead of compile-time[7]. NextGen[22] separates the translation of polymorphic classes into monomorphic and polymorphic components. In NextGen, Only the polymorphic members of a class definition are specialized; These specialized classes inherit the implementation of their monomorphic members from a common parent class. Finally, GJ[20] proposed the foundations for what is now the accepted implementation of parametric polymorphism in Java. Polymorphic class definitions have a single uniform data representation after type erasure. These approaches determine the data representation of polymorphic definitions in a static context. Our approach is based on the *closed world assumption* as the entire program must be available in order for it to be executed.

5.4 Specialization in Scala

The standard implementation of parametric polymorphism follows that of Java; generic class definitions have their type parameters erased. All previous approaches attempt to avoid the problem of bytecode explosion, where the specialization of polymorphic data with every possible type creates an exponential number of unique data representations. Dragos describes the earliest efforts to specialize Scala programs with the aid of annotations[32]. Annotations avoid unnecessarily specializing polymorphic data through knowledge injected by a programmer. Ureche, Talau, and Odersky expand upon this approach by reducing unnecessary duplication among specializations through sharing[75]. Sharing exploits the insight that specializations of some value types may be reused for the specializations of other value types. For example, the representation of `ArrayBuffer[Long]` could be used,

with the addition of some glue code, for the specialization of `ArrayBuffer[Int]` instead of generating an additional specialized representation. Both approaches mix the implementation of uniform polymorphism with user-guided specialization directives. Our approach generates a heterogeneous translation of a generic class definition on an ad-hoc basis.

5.5 Truffle Interpreters

There are many Truffle interpreters in active development at the time of writing. This section will attempt to provide a brief survey of Truffle interpreters. TruffleRuby[67, 29], FastR, Graal.js, Graal.Python,[46] are some of the industrial implementations of dynamically typed languages implemented with Truffle. They all make substantial use of Truffle facilities, some discussed earlier in this thesis, to speculative optimize program execution. Espresso[41] is an implementation of a Java bytecode interpreter in Truffle. Espresso is a metacircular implementation of a Java Virtual Machine. Because Espresso executes the same Java bytecode format as other JVM implementations, it uses the same approaches to optimizing polymorphic data layout as the conventional implementation of Java on GraalVM.

Chapter 6

Future Work

TastyTruffle is intended to be a framework for dynamic whole-program approaches to optimizing Scala. In this section, we discuss some possible extensions to the interpreter that further take advantage of Truffle mechanisms. A substantial penalty of heterogeneous translations of polymorphic programs is *code explosion*. For large polymorphic programs, the penalty of heterogeneous translation is twofold; The first is the cost of increased memory usage. Having many specialized data representations incurs extra storage unless these data representations are regenerated every time a specialization is needed. The second is the hidden computational overhead of specialization. Like other computational overheads of managed runtimes such as garbage collection, time spent generating specialized variants of polymorphic classes or methods means time not spent executing the program. We propose several methods to augment *when* a specialization is created.

Many prior approaches to specialization have already attempted to minimize the number of specializations to mitigate performance degradation for complex polymorphic definitions, where there is often a $O(t^n)$ space complexity worse case¹, and very large programs. These approaches balance the tradeoff between performance and code size to optimistically generate *only* the specializations required to eliminate performance bottlenecks. Because of the work done in [32], many existing Scala programs are already user-annotated with a specialization directive. Similarly, our approach could be extended to include the semantics of this annotation, generating specializations with user-guide information only where needed. The translation of non-annotated definitions will use a shared type-erased data representation. However, mixing annotated and non-annotated programs will present

¹ t is the number of values types combined with the reference type, n is the number of type parameters in a generic definition.

missed optimization opportunities in the non-annotated portions of the program.

Truffle offers many existing mechanisms for profiling values and types. Some of this profiling instrumentation is automatically done by Truffle, such as the profiling of argument types for node rewrites. While other instrumentation, such as condition profiles, are added by the guest language implementer. These profiles augment partial evaluation and enable speculative assumptions to augment optimizations such as conditional elimination. We propose instrumenting specialization sites to profile type arguments. Type argument profiles could then be used to decide the specific instantiation to specialize. A *profile-guided* approach to specialization could limit specializations to only the most frequently used instantiations.

Often a polymorphic instantiation is not sufficiently frequent to warrant specialization; the default homogeneous data representation will be shared among unspecialized instantiation. A type-erased homogeneous data representation may still be tagged with the underlying applied type. We can further augment type-erased polymorphic fields, and frame slots to profile reads from and writes to their respective storage locations. These two pieces of dynamic information can be combined to allow the specialization of specific instantiations that are frequently manipulated but not frequently created.

We can apply the same optimization to sharing data layouts between specific specializations with inspiration from the work done by Ureche et al. in [75]. Because the additional operations that adapt shared specializations to their original type contexts are negligible in terms of performance[75], these operations make sense to intrinsify as Truffle nodes that will be further optimized by JIT compilation.

Chapter 7

Conclusions

This thesis introduced TASTYTRUFFLE, a Truffle interpreter that is a platform for experimenting with ad-hoc data representations. The thesis described methods to translate TASTy, a tree serialization format for Scala 3, into an executable IR suitable for execution in an optimizing interpreter. We show in this thesis how to exploit the type information present in an input source language such as TASTy to generate specialized data representations for polymorphic data structures. We demonstrate that these techniques can substantially improve the performance of simple Scala programs in an experimental interpreter when compared to a state-of-the-art Java virtual machine.

A particular challenge in the implementation of TASTYTRUFFLE was the translation of TASTy into TASTYTRUFFLE IR. Because TASTy is emitted after parsing and type checking, no other compiler transformations typical in other intermediate representations are present. Many features of the Scala programming language are built as abstractions of simpler constructs that the compiler must further simplify. Without the existing compiler transformations to simplify these abstractions, TASTy can be at times *extraneously* high-level for execution. While this did not significantly impact the evaluation of simple Scala programs for our experiments, it limits the *breadth* of programs that are executable by our interpreter. A possible solution to this hurdle is to read TASTy, perform a subset of Scala compiler transforms, then execute the program using our translation. While we will have to avoid the type erasure transformation and all subsequent transformations that depend on the type erasure results, a much more significant portion of existing Scala programs can be executed on our interpreter. This is particularly important in the context of the Scala collections library. As many Scala applications rely extensively on the Scala collections library, it would open the possibility for evaluating TASTYTRUFFLE on larger real-world workloads.

The specialization of classes with both class-polymorphic and method-polymorphic semantics proved to be a complex implementation detail. The gap between the specialization of classes (at object creation) and the specialization of methods (at method invocation) required the selection of appropriate intermediate representation to encapsulate the *partial* specialization. Partial specializations have been specialized but also still contain polymorphic semantics, which must be resolved at a future specialization site. In this thesis, we chose to use a high-level approach to aid the translation of TASTy definitions with TASTy type arguments. However, many prior approaches provide inspiration to tackle this problem. A possible solution might avoid multiple mechanisms for specialization, there avoiding partial specializations entirely. Alternatively, specialized call targets could be added onto a shape in an ad-hoc, profile-driven manner without the need to dispatch and select a specialization inside a call target. Truffle already has the tooling for dynamic object layouts in the form of the `DynamicShape`. As class specialization is a relatively experimental feature in the lifespan of TASTYTRUFFLE, we consider this a possibility for future optimization.

In this thesis, we have evaluated TASTYTRUFFLE on simple but challenging to specialize data structures exhibiting bulk memory access and random heap access. The elimination of autoboxing in the list data structure resulted in incremental performance improvements where autoboxing proved to be a performance bottleneck. The elimination of autoboxing in data structures backed by polymorphic arrays resulted in performance improvements by an order of magnitude. TASTYTRUFFLE validates that there are opportunities for data representation optimizations that bridge static compilation and just-in-time compilation.

References

- [1] Autoboxing and Unboxing (The Java™ Tutorials > Learning the Java Language > Numbers and Strings).
- [2] Documentation - The Zig Programming Language.
- [3] Inline functions | Kotlin.
- [4] Reified Generics.
- [5] Using Java Reflection.
- [6] IBM Research | Technical Paper Search | The Jikes RVM Project: Building an Open Source Research Community(Search Reports), September 2016.
- [7] Ole Agesen, Stephen N. Freund, and John C. Mitchell. Adding type parameterization to the Java language. *ACM SIGPLAN Notices*, 32(10):49–65, October 1997.
- [8] Alfred V Aho, Jeffrey D Ullman, et al. *Principles of compiler design*. Addison-Wesley Pub. Co., 1977.
- [9] Alexander Aiken, Manuel Fähndrich, and Raph Levien. Better static memory management: Improving region-based analysis of higher-order languages. In *Proceedings of the ACM SIGPLAN 1995 Conference on Programming Language Design and Implementation*, PLDI '95, page 174–185, New York, NY, USA, 1995. Association for Computing Machinery.
- [10] F. E. Allen and J. Cocke. A program data flow analysis procedure. *Commun. ACM*, 19(3):137, mar 1976.
- [11] Frances E. Allen. Control flow analysis. In *Proceedings of a Symposium on Compiler Optimization*, page 1–19, New York, NY, USA, 1970. Association for Computing Machinery.

- [12] John R. Allen and Ken Kennedy. Automatic loop interchange. *ACM SIGPLAN Notices*, 19(6):233–246, June 1984.
- [13] B. Alpern, M. Wegman, and F. K. Zadeck. Detecting equality of variables in programs. In *POPL '88*, 1988.
- [14] John Aycock. A brief history of just-in-time. *ACM Computing Surveys*, 35(2):97–113, June 2003.
- [15] Lars Birkedal, Mads Tofte, and Magnus Vejlstrup. From region inference to von neumann machines via region representation inference. In *Proceedings of the 23rd ACM SIGPLAN-SIGACT Symposium on Principles of Programming Languages*, POPL '96, page 171–183, New York, NY, USA, 1996. Association for Computing Machinery.
- [16] Bruno Blanchet. Escape analysis for javatm: Theory and practice. *ACM Trans. Program. Lang. Syst.*, 25(6):713–775, nov 2003.
- [17] Rastislav Bodík, Rajiv Gupta, and Vivek Sarkar. ABCD: eliminating array bounds checks on demand. *ACM SIGPLAN Notices*, 35(5):321–333, May 2000.
- [18] Rastislav Bodík, Rajiv Gupta, and Mary Lou Soffa. Interprocedural conditional branch elimination. In *Proceedings of the ACM SIGPLAN 1997 conference on Programming language design and implementation*, PLDI '97, pages 146–158, New York, NY, USA, May 1997. Association for Computing Machinery.
- [19] Gilad Bracha and William Cook. Mixin-based inheritance. In *Proceedings of the European Conference on Object-Oriented Programming on Object-Oriented Programming Systems, Languages, and Applications*, OOPSLA/ECOOP '90, page 303–311, New York, NY, USA, 1990. Association for Computing Machinery.
- [20] Gilad Bracha, Martin Odersky, David Stoutamire, and Philip Wadler. Making the future safe for the past: Adding genericity to the java programming language. *SIGPLAN Not.*, 33(10):183–200, oct 1998.
- [21] Luca Cardelli, Simone Martini, John C. Mitchell, and Andre Scedrov. An extension of system F with subtyping. In Takayasu Ito and Albert R. Meyer, editors, *Theoretical Aspects of Computer Software*, Lecture Notes in Computer Science, pages 750–770, Berlin, Heidelberg, 1991. Springer.
- [22] Robert Cartwright and Guy L. Steele. Compatible genericity with run-time types for the Java programming language. *ACM SIGPLAN Notices*, 33(10):201–215, October 1998.

- [23] Giuseppe Castagna. Covariance and contravariance: Conflict without a cause. *ACM Trans. Program. Lang. Syst.*, 17(3):431–447, may 1995.
- [24] C. Chambers, D. Ungar, and E. Lee. An efficient implementation of self a dynamically-typed object-oriented language based on prototypes. In *Conference Proceedings on Object-Oriented Programming Systems, Languages and Applications*, OOPSLA '89, page 49–70, New York, NY, USA, 1989. Association for Computing Machinery.
- [25] Cliff Click and Keith D. Cooper. Combining analyses, combining optimizations. *ACM Transactions on Programming Languages and Systems*, 17(2):181–196, March 1995.
- [26] Vincent Cremet, François Garillot, Sergueï Lenglet, and Martin Odersky. A core calculus for scala type checking. In *International Symposium on Mathematical Foundations of Computer Science*, pages 1–23. Springer, 2006.
- [27] Ron Cytron, Jeanne Ferrante, Barry K. Rosen, Mark N. Wegman, and F. Kenneth Zadeck. Efficiently computing static single assignment form and the control dependence graph. *ACM Transactions on Programming Languages and Systems*, 13(4):451–490, Oct 1991.
- [28] Ole-Johan Dahl and Kristen Nygaard. Simula: an algol-based simulation language. *Communications of the ACM*, 9(9):671–678, 1966.
- [29] Benoit Daloze, Stefan Marr, Daniele Bonetta, and Hanspeter Mössenböck. Efficient and thread-safe objects for dynamically-typed languages. 11 2016.
- [30] Luis Damas and Robin Milner. Principal type-schemes for functional programs. In *Proceedings of the 9th ACM SIGPLAN-SIGACT symposium on Principles of programming languages*, pages 207–212, 1982.
- [31] L. Peter Deutsch and Allan M. Schiffman. Efficient implementation of the smalltalk-80 system. In *Proceedings of the 11th ACM SIGACT-SIGPLAN Symposium on Principles of Programming Languages*, POPL '84, page 297–302, New York, NY, USA, 1984. Association for Computing Machinery.
- [32] Iulian Dragos, editor. *Compiling Scala for Performance*. EPFL, Lausanne, 2010.
- [33] Gilles Duboscq, Lukas Stadler, Thomas Wuerthinger, Doug Simon, Christian Wimmer, and Hanspeter Mössenböck. Graal IR: An Extensible Declarative Intermediate Representation. February 2013.

- [34] Gilles Duboscq, Thomas Würthinger, Lukas Stadler, Christian Wimmer, Doug Simon, and Hanspeter Mössenböck. An Intermediate Representation for Speculative Optimizations in a Dynamic Compiler. In *Proceedings of the 7th ACM workshop on Virtual Machines and Intermediate Languages - VMIL '13*, pages 1–10, Indianapolis, Indiana, USA, 2013. ACM Press.
- [35] S.J. Fink and Feng Qian. Design, implementation and evaluation of adaptive recompilation with on-stack replacement. In *International Symposium on Code Generation and Optimization, 2003. CGO 2003.*, pages 241–252, March 2003.
- [36] Yoshihiko Futamura. Partial evaluation of computation process—an approach to a compiler-compiler. *Higher-Order and Symbolic Computation*, 12(4):381–391, 1999.
- [37] Etienne M Gagnon and Laurie J Hendren. Sable vm: A research framework for the efficient execution of java bytecode. In *Java Virtual Machine Research and Technology Symposium*, pages 27–40, 2001.
- [38] Erich Gamma, Richard Helm, Ralph Johnson, and John Vlissides. Design patterns: Abstraction and reuse of object-oriented design. In *European Conference on Object-Oriented Programming*, pages 406–431. Springer, 1993.
- [39] Andy Georges, Dries Buytaert, and Lieven Eeckhout. Statistically rigorous java performance evaluation. *ACM SIGPLAN Notices*, 42(10):57–76, October 2007.
- [40] Adele Goldberg and David Robson. *Smalltalk-80: the language and its implementation*. Addison-Wesley Longman Publishing Co., Inc., 1983.
- [41] Ekaterina Goltsova, editor. *Optimizing Java on Truffle*. 2022.
- [42] James Gosling, Bill Joy, Guy Steele, and Gilad Bracha. *The Java language specification*. Addison-Wesley Professional, 2000.
- [43] Dayong Gu, Clark Verbrugge, and Etienne M. Gagnon. Relative factors in performance analysis of Java virtual machines. In *Proceedings of the 2nd international conference on Virtual execution environments*, VEE '06, pages 111–121, New York, NY, USA, June 2006. Association for Computing Machinery.
- [44] Urs Hölzle, Craig Chambers, and David Ungar. Optimizing dynamically-typed object-oriented languages with polymorphic inline caches. In Pierre America, editor, *ECOOP'91 European Conference on Object-Oriented Programming*, pages 21–38, Berlin, Heidelberg, 1991. Springer Berlin Heidelberg.

- [45] Urs Hölzle, Craig Chambers, and David Ungar. Debugging optimized code with dynamic deoptimization. In *Proceedings of the ACM SIGPLAN 1992 Conference on Programming Language Design and Implementation*, PLDI '92, page 32–43, New York, NY, USA, 1992. Association for Computing Machinery.
- [46] Christian Humer. *Truffle DSL: A DSL for Building Self-Optimizing AST Interpreters*. PhD thesis, Johannes Kepler University Linz, Linz, Austria, 2016. Publisher: Unpublished.
- [47] Richard Johnson and Keshav Pingali. Dependence-based program analysis. In *PLDI '93*, 1993.
- [48] Thomas Kotzmann and Hanspeter Mössenböck. Escape analysis in the context of dynamic compilation and deoptimization. In *Proceedings of the 1st ACM/USENIX International Conference on Virtual Execution Environments*, VEE '05, page 111–120, New York, NY, USA, 2005. Association for Computing Machinery.
- [49] Thomas Kotzmann and Hanspeter Mossenbock. Run-time support for optimizations based on escape analysis. In *Proceedings of the International Symposium on Code Generation and Optimization*, CGO '07, page 49–60, USA, 2007. IEEE Computer Society.
- [50] Peter J. Landin. The mechanical evaluation of expressions. *Comput. J.*, 6:308–320, 1964.
- [51] Chris Lattner and Vikram Adve. Llvm: A compilation framework for lifelong program analysis & transformation. In *International Symposium on Code Generation and Optimization, 2004. CGO 2004.*, pages 75–86. IEEE, 2004.
- [52] Tim Lindholm, Frank Yellin, Gilad Bracha, and Alex Buckley. *The Java Virtual Machine Specification, Java SE 7 Edition: Java Virt Mach Spec Java_3*. Addison-Wesley, 2013.
- [53] Erik Meijer and John Gough. Technical overview of the common language runtime. *language*, 29(7), 2001.
- [54] Erik Meijer and John Gough. Technical overview of the common language runtime. *language*, 29(7), 2001.
- [55] R. Milner, L. Morris, and M. Newey. A logic for computable functions with reflexive and polymorphic types. In *Proceedings of the Conference on Proving and Improving Programs*, pages 371–394. IRIA-Laboria, 1975.

- [56] R. Morrison, A. Dearle, R. C. H. Connor, and A. L. Brown. An ad hoc approach to the implementation of polymorphism. *ACM Trans. Program. Lang. Syst.*, 13(3):342–371, jul 1991.
- [57] Maurice Naftalin and Philip Wadler. *Java Generics and Collections: Speed Up the Java Development Process.* ” O’Reilly Media, Inc.”, 2006.
- [58] Martin Odersky, Philippe Altherr, Vincent Cremet, Burak Emir, Sebastian Maneth, Stéphane Micheloud, Nikolay Mihaylov, Michel Schinz, Erik Stenman, and Matthias Zenger. An overview of the scala programming language. 2004.
- [59] Martin Odersky, Philippe Altherr, Vincent Cremet, Burak Emir, Stphane Micheloud, Nikolay Mihaylov, Michel Schinz, Erik Stenman, and Matthias Zenger. The scala language specification, 2004.
- [60] Martin Odersky and Philip Wadler. Pizza into Java: translating theory into practice. In *Proceedings of the 24th ACM SIGPLAN-SIGACT symposium on Principles of programming languages*, POPL ’97, pages 146–159, New York, NY, USA, January 1997. Association for Computing Machinery.
- [61] Martin Odersky and Matthias Zenger. Scalable component abstractions. In *Proceedings of the 20th annual ACM SIGPLAN conference on Object-oriented programming, systems, languages, and applications*, pages 41–57, 2005.
- [62] Michael Paleczny, Christopher Vick, and Cliff Click. The java {HotSpot™} server compiler. In *Java (TM) Virtual Machine Research and Technology Symposium (JVM 01)*, 2001.
- [63] Benjamin C Pierce. *Types and programming languages*. MIT press, 2002.
- [64] Aleksandar Prokopec, David Leopoldseder, Gilles Duboscq, and Thomas Würthinger. Making collection operations optimal with aggressive jit compilation. In *Proceedings of the 8th ACM SIGPLAN International Symposium on Scala*, SCALA 2017, page 29–40, New York, NY, USA, 2017. Association for Computing Machinery.
- [65] Manuel Rigger, Roland Schatz, Jacob Kreindl, Christian Häubl, and Hanspeter Mössenböck. Sulong, and thanks for all the fish. In *Conference Companion of the 2nd International Conference on Art, Science, and Engineering of Programming*, Programming’18 Companion, pages 58–60, New York, NY, USA, April 2018. Association for Computing Machinery.

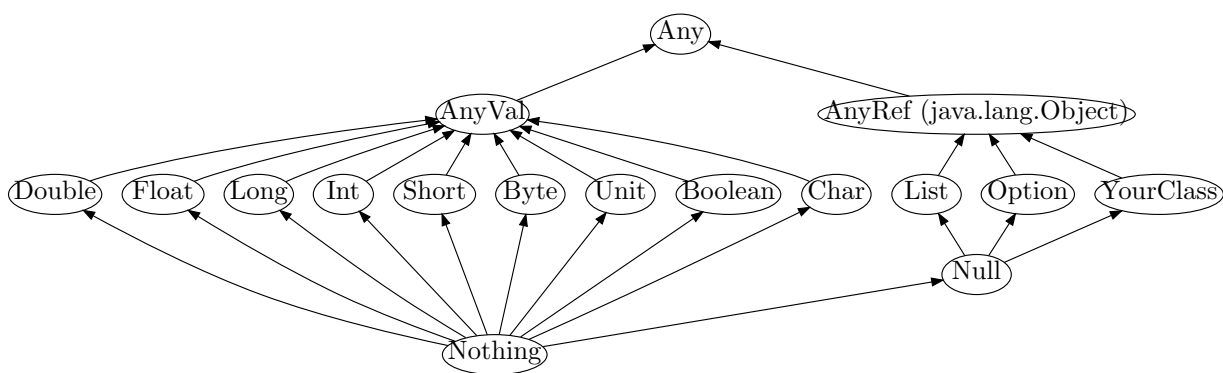
- [66] Ben Sander and AMD SENIOR FELLOW. Hsail: Portable compiler ir for hsa. In *Hot Chips Symposium*, volume 2013, pages 1–32, 2013.
- [67] Chris Seaton. *Specialising Dynamic Techniques for Implementing the Ruby Programming Language | Research Explorer | The University of Manchester*. PhD thesis.
- [68] Andreas Sewe, Mira Mezini, Aibek Sarimbekov, and Walter Binder. Da capo con scala: design and analysis of a scala benchmark suite for the java virtual machine. *ACM SIGPLAN Notices*, 46(10):657–676, October 2011.
- [69] Amitabh Srivastava and Alan Eustace. Atom: A system for building customized program analysis tools. In *Proceedings of the ACM SIGPLAN 1994 Conference on Programming Language Design and Implementation*, PLDI '94, page 196–205, New York, NY, USA, 1994. Association for Computing Machinery.
- [70] Lukas Stadler, Thomas Würthinger, and Hanspeter Mössenböck. Partial escape analysis and scalar replacement for java. In *Proceedings of Annual IEEE/ACM International Symposium on Code Generation and Optimization*, CGO '14, page 165–174, New York, NY, USA, 2014. Association for Computing Machinery.
- [71] Christopher Strachey. Fundamental concepts in programming languages. *Higher-order and symbolic computation*, 13(1):11–49, 2000.
- [72] Bjarne Stroustrup. *The C++ programming language*. Pearson Education, 2013.
- [73] Gerald Jay Sussman and Guy L Steele. Scheme: A interpreter for extended lambda calculus. *Higher-Order and Symbolic Computation*, 11(4):405–439, 1998.
- [74] Mads Tofte and Jean-Pierre Talpin. Region-based memory management. *Information and Computation*, 132(2):109–176, 1997.
- [75] Vlad Ureche, Cristian Talau, and Martin Odersky. Miniboxing: Improving the Speed to Code Size Tradeoff in Parametric Polymorphism Translations. In *Proceedings of the 2013 ACM SIGPLAN International Conference on Object Oriented Programming Systems Languages & Applications - OOPSLA '13*, pages 73–92, Indianapolis, Indiana, USA, 2013. ACM Press.
- [76] Mark N. Wegman and F. Kenneth Zadeck. Constant propagation with conditional branches. *ACM Transactions on Programming Languages and Systems*, 13(2):181–210, April 1991.

- [77] Thomas Würthinger, Christian Wimmer, Christian Humer, Andreas Wöß, Lukas Stadler, Chris Seaton, Gilles Duboscq, Doug Simon, and Matthias Grimmer. Practical partial evaluation for high-performance dynamic language runtimes. In *Proceedings of the 38th ACM SIGPLAN Conference on Programming Language Design and Implementation*, PLDI 2017, page 662–676, New York, NY, USA, 2017. Association for Computing Machinery.
- [78] Andreas Wöß, Christian Wirth, Daniele Bonetta, Chris Seaton, Christian Humer, and Hanspeter Mössenböck. An Object Storage Model for the Truffle Language Implementation Framework. In *Proceedings of the 2014 International Conference on Principles and Practices of Programming on the Java Platform Virtual machines, Languages, and Tools - PPPJ '14*, pages 133–144, Cracow, Poland, 2014. ACM Press.
- [79] Thomas Würthinger, Christian Wimmer, Andreas Wöß, Lukas Stadler, Gilles Duboscq, Christian Humer, Gregor Richards, Doug Simon, and Mario Wolczko. One VM to Rule Them All. In *Proceedings of the 2013 ACM International Symposium on New ideas, New Paradigms, and Reflections on Programming & Software - Onward! '13*, pages 187–204, Indianapolis, Indiana, USA, 2013. ACM Press.

APPENDICES

Appendix A

Scala Unified Type System



Appendix B

Scala 3 Compiler Phases

```
1  /** Phases dealing with the frontend up to trees ready for TASTY pickling */
2  protected def frontendPhases: List[List[Phase]] =
3      List(new Parser) ::                               // scanner, parser
4      List(new TyperPhase) ::                             // namer, typer
5      List(new YCheckPositions) ::                       // YCheck positions
6      List(new sbt.ExtractDependencies) ::               // Sends information on classes' dependencies to sbt via callbacks
7      List(new semanticdb.ExtractSemanticDB) ::          // Extract info into .semanticdb files
8      List(new PostTyper) ::                             // Additional checks and cleanups after type checking
9      List(new sjs.PreJSInterop) ::                     // Additional checks and transformations for Scala.js (Scala.js only)
10     List(new Staging) ::                               // Check PCP, heal quoted types and expand macros
11     List(new sbt.ExtractAPI) ::                         // Sends a representation of the API of classes to sbt via callbacks
12     List(new SetRootTree) ::                           // Set the `rootTreeOrProvider` on class symbols
13     Nil
```

```
1  /** Phases dealing with TASTY tree pickling and unpickling */
2  protected def picklerPhases: List[List[Phase]] =
3      List(new Pickler) ::                               // Generate TASTY info
4      List(new PickleQuotes) ::                         // Turn quoted trees into explicit run-time data structures
5      Nil
```

```
1  /** Phases dealing with the transformation from pickled trees to backend trees */
2  protected def transformPhases: List[List[Phase]] =
3      List(
4          new FirstTransform,                            // Some transformations to put trees into a canonical form
5          new CheckReentrant,                            // Internal use only: Check that compiled program has no data races involving global v
6          new ElimPackagePrefixes,                      // Eliminate references to package prefixes in Select nodes
7          new CookComments,                             // Cook the comments: expand variables, doc, etc.
8      )
```

```

8      new CheckStatic,           // Check restrictions that apply to @static members
9      new BetaReduce,           // Reduce closure applications
10     new init.Checker) ::       // Check initialization of objects
11   List(
12     new ElimRepeated,           // Rewrite vararg parameters and arguments
13     new ExpandSAMs,             // Expand single abstract method closures to anonymous classes
14     new ProtectedAccessors,     // Add accessors for protected members
15     new ExtensionMethods,       // Expand methods of value classes with extension methods
16     new UncacheGivenAliases,    // Avoid caching RHS of simple parameterless given aliases
17     new ByNameClosures,         // Expand arguments to by-name parameters to closures
18     new HoistSuperArgs,         // Hoist complex arguments of supercalls to enclosing scope
19     new SpecializeApplyMethods, // Adds specialized methods to FunctionN
20     new RefChecks) ::          // Various checks mostly related to abstract members and overriding
21   List(
22     // Turn opaque into normal aliases
23     new ElimOpaque,
24     // Compile cases in try/catch
25     new TryCatchPatterns,
26     // Compile pattern matches
27     new PatternMatcher,
28     // Make all JS classes explicit (Scala.js only)
29     new sjs.ExplicitJSClasses,
30     // Add accessors to outer classes from nested ones.
31     new ExplicitOuter,
32     // Make references to non-trivial self types explicit as casts
33     new ExplicitSelf,
34     // Expand by-name parameter references
35     new ElimByName,
36     // Optimizes raw and s string interpolators by rewriting them to string concatenations
37     new StringInterpolatorOpt) ::
38   List(
39     new PruneErasedDefs,         // Drop erased definitions from scopes and simplify erased expressions
40     new InlinePatterns,         // Remove placeholders of inlined patterns
41     new VCInlineMethods,        // Inlines calls to value class methods
42     new SeqLiterals,            // Express vararg arguments as arrays
43     new InterceptedMethods,     // Special handling of `==`, `!=`, `getClass` methods
44     new Getters,               // Replace non-private vals and vars with getter defs (fields are added later)
45     new SpecializeFunctions,    // Specialized Function{0,1,2} by replacing super with specialized super
46     new LiftTry,               // Put try expressions that might execute on non-empty stacks into their own methods
47     new CollectNullableFields,  // Collect fields that can be nulled out after use in lazy initialization
48     new ElimOuterSelect,       // Expand outer selections
49     new ResolveSuper,          // Implement super accessors
50     new FunctionXXLForwarders,  // Add forwarders for FunctionXXL apply method
51     new ParamForwarding,       // Add forwarders for aliases of superclass parameters
52     new TupleOptimizations,     // Optimize generic operations on tuples
53     new LetOverApply,          // Lift blocks from receivers of applications
54     new ArrayConstructors) ::  // Intercept creation of (non-generic) arrays and intrinsify.
55   List(new Erasure) ::        // Rewrite types to JVM model, erasing all type parameters, abstract types and refinements
56   List(
57     new ElimErasedValueType,    // Expand erased value types to their underlying implementation types
58     new PureStats,              // Remove pure stats from blocks
59     new VCElideAllocations,     // Peep-hole optimization to eliminate unnecessary value class allocations
60     new ArrayApply,             // Optimize `scala.Array.apply([...])` and `scala.Array.apply(..., [...])` into `[...]`
61     new sjs.AddLocalJSFakeNews, // Adds fake new invocations to local JS classes in calls to `createLocalJSClass`
62     new ElimPolyFunction,       // Rewrite PolyFunction subclasses to FunctionN subclasses
63     new TailRec,                // Rewrite tail recursion to loops
64     new CompleteJavaEnums,      // Fill in constructors for Java enums

```

```

65     new Mixin,                // Expand trait fields and trait initializers
66     // Expand lazy vals
67     new LazyVals,
68     // Add private fields to getters and setters
69     new Memoize,
70     // Expand non-local returns
71     new NonLocalReturns,
72     // Represent vars captured by closures as heap objects
73     new CapturedVars) ::
74 List(
75     new Constructors,        // Collect initialization code in primary constructors
76     // Note: constructors changes decls in transformTemplate, no InfoTransformers should be added after it
77     new Instrumentation) :: // Count calls and allocations under -Yinstrument
78 List(
79     // Lifts out nested functions to class scope, storing free variables in environments
80     new LambdaLift,
81     // Note: in this mini-phase block scopes are incorrect. No phases that rely on scopes should be here
82     // Replace `this` references to static objects by global identifiers
83     new ElimStaticThis,
84     // Identify outer accessors that can be dropped
85     new CountOuterAccesses) ::
86 List(
87     // Drop unused outer accessors
88     new DropOuterAccessors,
89     // Lift all inner classes to package scope
90     new Flatten,
91     // Renames lifted classes to local numbering scheme
92     new RenameLifted,
93     // Replace wildcards with default values
94     new TransformWildcards,
95     // Move static methods from companion to the class itself
96     new MoveStatics,
97     // Widen private definitions accessed from nested classes
98     new ExpandPrivate,
99     // Repair scopes rendered invalid by moving definitions in prior phases of the group
100    new RestoreScopes,
101    // get rid of selects that would be compiled into GetStatic
102    new SelectStatic,
103    // Generate JUnit-specific bootstrapper classes for Scala.js (not enabled by default)
104    new sjs.JUnitBootstrappers,
105    // Find classes that are called with super
106    new CollectSuperCalls) ::
107 Nil

```

```

1  /** Generate the output of the compilation */
2  protected def backendPhases: List[List[Phase]] =
3    List(new backend.sjs.GenSJSIR) :: // Generate .sjsir files for Scala.js (not enabled by default)
4    List(new GenBCode) ::             // Generate JVM bytecode
5    Nil

```
