

To any vector field v one can associate a flow ϕ_t which maps points p along the integral curves of v . Can we think of the pullback ϕ_t^* as an exponential?

Consider an arbitrary function f , evaluated at some point along the flow: $f(\phi_t(p))$. f is smooth, so we could hope that the Taylor series converges, and then

$$\begin{aligned} f(\phi_t(p)) &= \sum_{k=0}^{\infty} \left. \frac{d^k}{ds^k} f(\phi_s(p)) \right|_{s=0} \frac{1}{k!} t^k \\ &= f(p) + \left. \frac{d}{ds} f(\phi_s(p)) \right|_{s=0} t + \frac{1}{2} \left. \frac{d^2}{ds^2} f(\phi_s(p)) \right|_{s=0} t^2 + \dots \end{aligned}$$

The second term is just $t[vf](p)$ since ϕ_s is the flow of v .

We'd like to write the second term as $\frac{1}{2} t^2 [vvf](p)$. Is this true?

$$\begin{aligned} [vvf](p) &= \left. \frac{d}{ds} [vf](\phi_s(p)) \right|_{s=0} = \left. \frac{d^2}{ds ds'} f(\phi_{s'}(\phi_s(p))) \right|_{s=s'=0} \\ &= \left. \frac{d^2}{ds ds'} f(\phi_{s+s'}(p)) \right|_{s=s'=0} \end{aligned}$$

Letting $t=s+s'$, we have $\frac{d}{dt} = \frac{d}{ds} = \frac{d}{ds'}$, so

$$[vvf](p) = \left. \frac{d^2}{dt^2} f(\phi_t(p)) \right|_{t=0}$$

The same argument will work for $[v^k f](p)$, so we have

$$f(\phi_t(p)) = [\phi_t^* f](p) = \sum_{k=0}^{\infty} \frac{1}{k!} t^k [v^k f](p)$$

$$\text{Thus } \phi_t^* = \sum_{k=0}^{\infty} \frac{1}{k!} t^k v^k = \exp(tv)$$

Does this simplify the Lie derivative defⁿ? yes!

Return to the original definition of $\mathcal{L}_v(u)$:

$$\mathcal{L}_v(u) = \lim_{t \rightarrow 0} \frac{1}{t} (\phi_{-t*} u - u)$$

We can easily show that $\phi_{-t*} u = \phi_t^* u \phi_{-t}^*$ by applying both sides to a function and evaluating the result at point p :

$$[(\phi_{-t*} u)f](p) = [u \phi_{-t}^* f](\phi_t(p)) = [\phi_t^* (u \phi_{-t}^* f)](p)$$

Thus, in the Lie derivative we have

$$\begin{aligned} \mathcal{L}_v(u) &= \lim_{t \rightarrow 0} \frac{1}{t} (\phi_t^* u \phi_{-t}^* - u) \\ &= \lim_{t \rightarrow 0} \frac{1}{t} (e^{tv} u e^{-tv} - u) \\ &= \lim_{t \rightarrow 0} \frac{1}{t} (t[v, u] + o(t^2)) \\ &= [v, u] \end{aligned}$$

The simplest proof so far.