



Fig. 1: 2 Balls

Two particles with mass $m/2$ are attached by a linear spring with a spring constant k as shown in Fig. 1. Consider arbitrary the initial position and velocity of each mass on the plane. For simplicity, however, assume that the initial separation $2r_0$ is the unstretched length of the spring, and that the mass center has zero inertial velocity initially. Determine the differential equations of motion whose solution would give $r(t)$ and $\theta(t)$ as functions of time and initial conditions; it is not necessary to solve these differential equations.

- Use polar coord. (along \hat{e}_r & \hat{e}_θ)

- Assume there exists some motion along \hat{e}_r & \hat{e}_θ

- Solving using Newtonian mechanics;

• Force on masses due to spring,

$$\begin{aligned} F_{\text{spring}} &= -k \Delta r \\ &= -k (2r - 2r_0) \\ &= -2k (r - r_0) \end{aligned} \quad \left. \vphantom{\begin{aligned} F_{\text{spring}} &= -k \Delta r \\ &= -k (2r - 2r_0) \\ &= -2k (r - r_0) \end{aligned}} \right\} \begin{array}{l} \text{This force term will be along} \\ \hat{e}_r \end{array}$$

- Since the mass moves along \hat{e}_r & \hat{e}_θ only, there exists a forcing term radially.

So, for planar motion, the position vector can be written as,

$$\vec{r} = r \hat{e}_r$$

Then, the velocity vector,

$$\begin{aligned} \vec{v} &= \frac{d}{dt} (r \hat{e}_r) \\ &= \frac{dr}{dt} \hat{e}_r + r \frac{d}{dt} (\hat{e}_r) \\ &= \dot{r} \hat{e}_r + r \dot{\theta} \hat{e}_\theta \end{aligned}$$

Then, the accel. vector,

$$\begin{aligned} \vec{a} &= \frac{d}{dt} (\dot{r} \hat{e}_r + r \dot{\theta} \hat{e}_\theta) \\ &= \frac{d}{dt} (\dot{r}) \hat{e}_r + \dot{r} \frac{d}{dt} (\hat{e}_r) \\ &\quad + \frac{d}{dt} (r \dot{\theta}) \hat{e}_\theta + r \dot{\theta} \frac{d}{dt} (\hat{e}_\theta) \\ &= \ddot{r} \hat{e}_r + \dot{r} \dot{\theta} \hat{e}_\theta + (r \ddot{\theta} + \dot{r} \dot{\theta}) \hat{e}_\theta - r \dot{\theta}^2 \hat{e}_r \\ &= (\ddot{r} - r \dot{\theta}^2) \hat{e}_r + (r \ddot{\theta} + 2\dot{r} \dot{\theta}) \hat{e}_\theta \end{aligned}$$

• Since the frame is body-attached and rotating (changing w.r.t. time), the unit vectors must be differentiated.
• Recall the kinematic transport theorem,

$$N \frac{d}{dt} (\vec{r}) = \frac{B}{dt} (\vec{r}) + \omega \times \vec{r}$$

• So; $\frac{d}{dt} (\hat{e}_r) = 0 + \omega \times \hat{e}_r$, $\omega = \dot{\theta} \hat{e}_z$

$$\boxed{\frac{d}{dt} (\hat{e}_r) = \dot{\theta} \hat{e}_\theta}$$

• and, $\frac{d}{dt} (\hat{e}_\theta) = 0 + \omega \times \hat{e}_\theta$

$$\boxed{\frac{d}{dt} (\hat{e}_\theta) = -\dot{\theta} \hat{e}_r}$$

- So from the accel. vector, we have the acceleration terms along \hat{e}_r & \hat{e}_θ

- Radially (along \hat{e}_r),

$$F_{\text{spring}} = ma, \quad \text{1 ball is } m/2$$

$$-2k(r-r_0) = \frac{m}{2}(\ddot{r} - r\dot{\theta}^2)$$

$$-4k(r-r_0) = m(\ddot{r} - r\dot{\theta}^2)$$

$$m\ddot{r} - mr\dot{\theta}^2 + 4k(r-r_0) = 0 \quad \cancel{\times}$$

- Tangentially (along \hat{e}_θ),

$$F_{\text{tangential}} = ma$$

$$r\ddot{\theta} + 2\dot{r}\dot{\theta} = 0 \quad \cancel{\times}$$

Using the setup of the prior problem, determine an expression that relates the radial velocity \dot{r} and the angular velocity $\dot{\theta}$ as functions of r, θ and initial conditions.
(Hint: use conservation of energy)

- IN a Conserved system,

$$E = T + V, \quad \begin{array}{l} T - \text{kinetic energy} \\ V - \text{Potential energy} \end{array}$$

- IN the context of the question,

- There will be K.E. due to motion of the system
- There will be P.E. due to spring

- Kinetic energy,

$$\begin{aligned} T &= \frac{1}{2} m (\vec{v} \cdot \vec{v}) \\ &= \frac{1}{2} m (\dot{r}^2 + r^2 \dot{\theta}^2) \quad \Rightarrow \text{K.E. of both masses} \end{aligned}$$

- Potential Energy,

$$\begin{aligned} V &= \frac{1}{2} k (\Delta r)^2 \\ &= \frac{1}{2} k (2r - 2r_0)^2 \\ &= \frac{1}{2} k (2^2) (r - r_0)^2 \\ &= 2k (r - r_0)^2 \end{aligned}$$

- Then,

$$E = T + V = \frac{1}{2} m (\dot{r}^2 + r^2 \dot{\theta}^2) + 2k (r - r_0)^2$$

- So at time $t = t_0$, and some $t > t_0$, $E = \text{const.}$

$$E_{\text{final}} = E_{\text{initial}}$$

$$\frac{1}{2} m (\dot{r}^2 + r^2 \dot{\theta}^2) + 2k (r - r_0)^2 = \frac{1}{2} m (r_0^2 + r_0^2 \dot{\theta}_0^2) + 2k (r_0 - r_0)^2$$

Thus,

$$\frac{m}{2} (r_0^2 + r_0^2 \dot{\theta}_0^2) = 2k (r - r_0)^2 + \frac{m}{2} (\dot{r}^2 + r^2 \dot{\theta}^2)$$

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