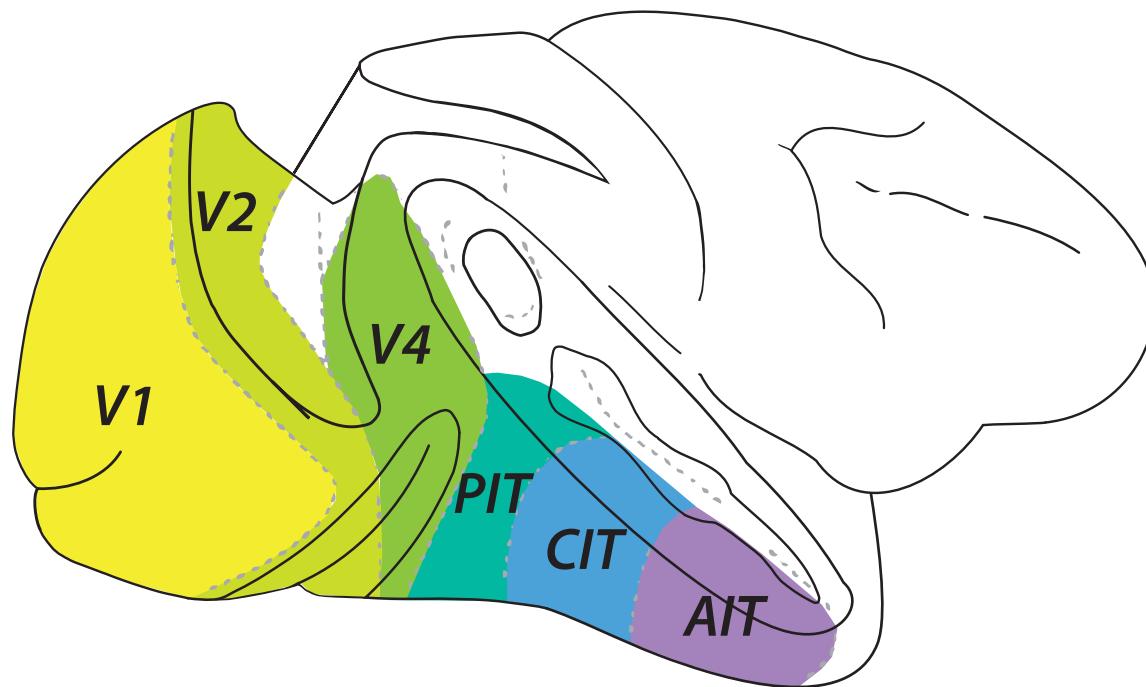


How do CNN units achieve translation invariance?

Dean Pospisil

6/29/17

Region of Interest: V4



Network of Interest: AlexNet

fc 8 identification

fc 7

fc 6 fully connected
Max Pooling

conv 5

conv 4

conv 3

Normalization

Max Pooling

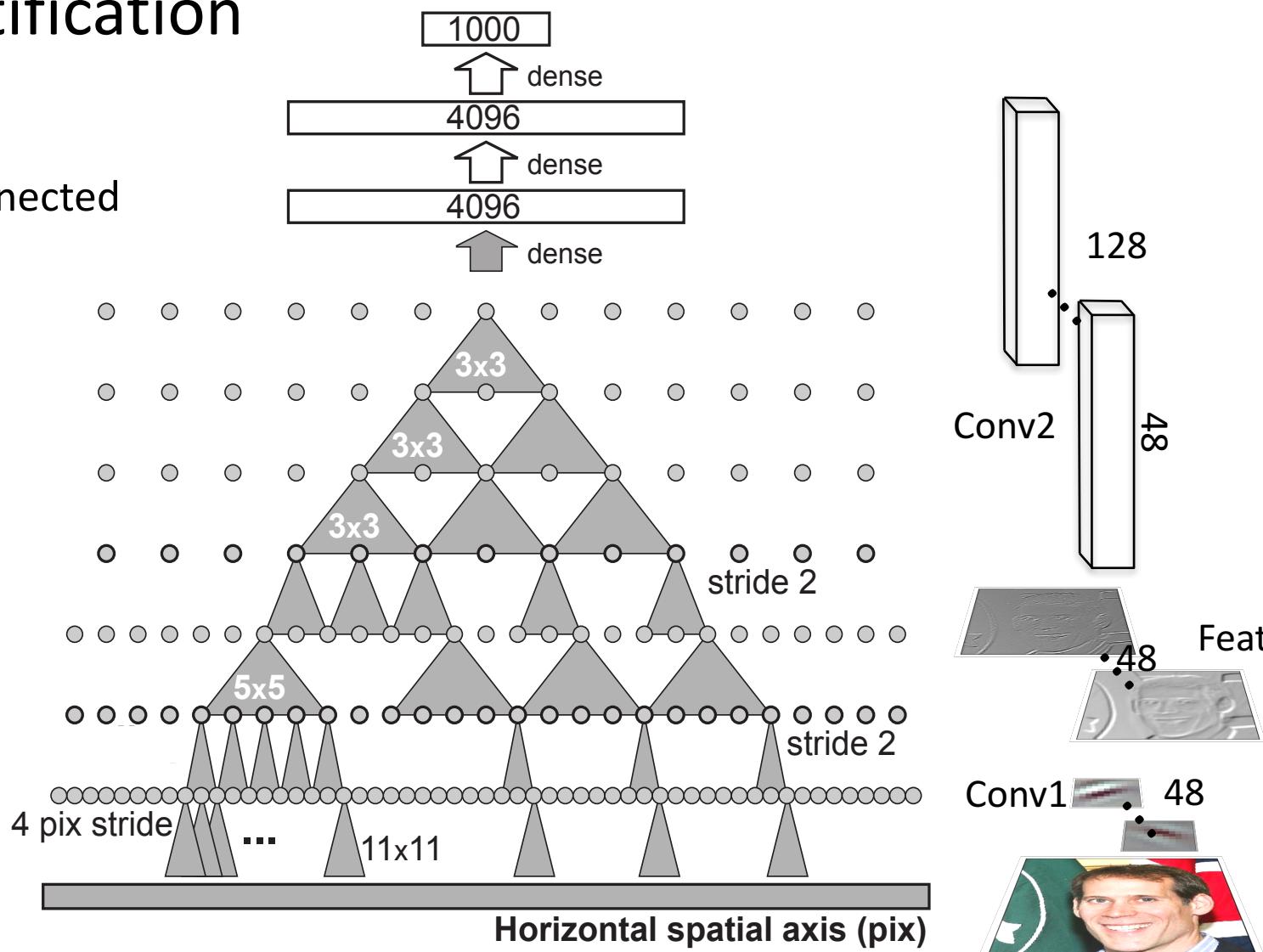
conv 2

Normalization

Max Pooling

conv 1

convolutional



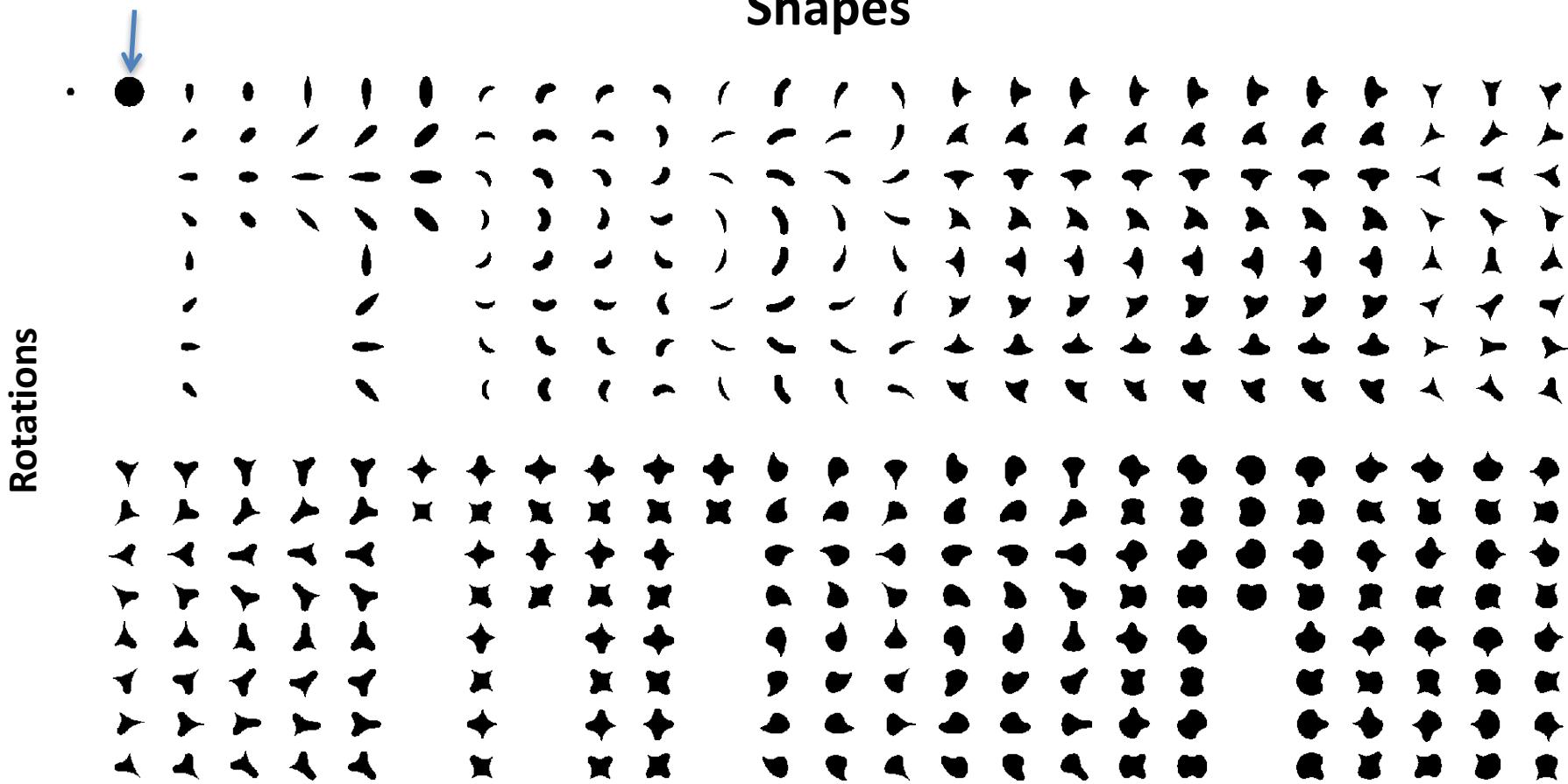
Krizhevsky, Alex, Ilya Sutskever, and Geoffrey E. Hinton.

"ImageNet Classification with Deep Convolutional Neural Networks."

Jia, Yangqing and Shelhamer, Evan and Donahue, Jeff and Karayev, Sergey and Long, Jonathan and Girshick, Ross and Guadarrama, Sergio and Darrell, Trevor
'Caffe: Convolutional Architecture for Fast Feature Embedding'

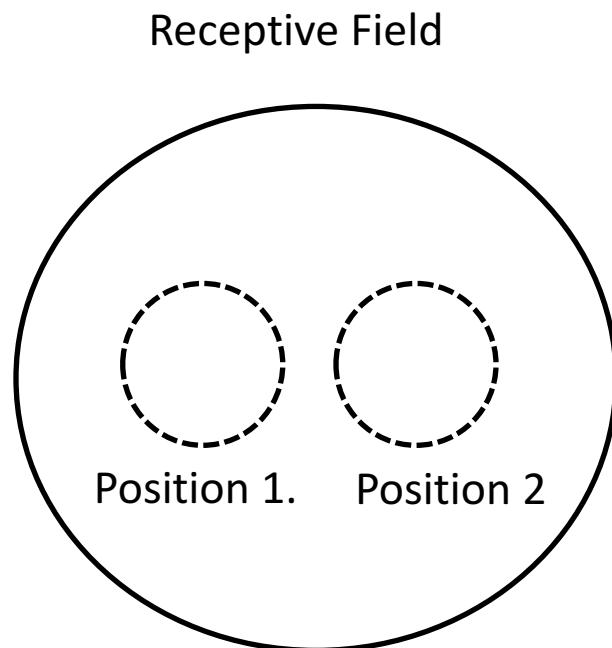
Experimental Stimuli

32 pixel diameter

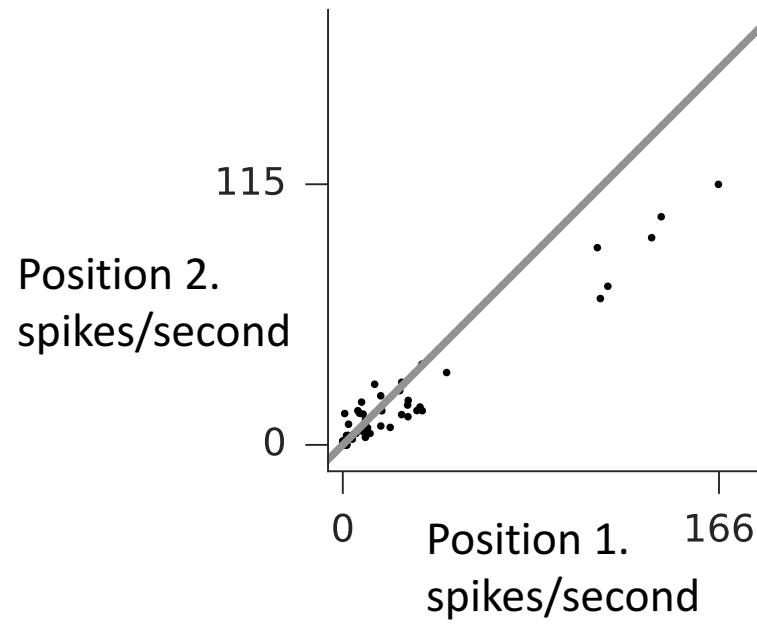
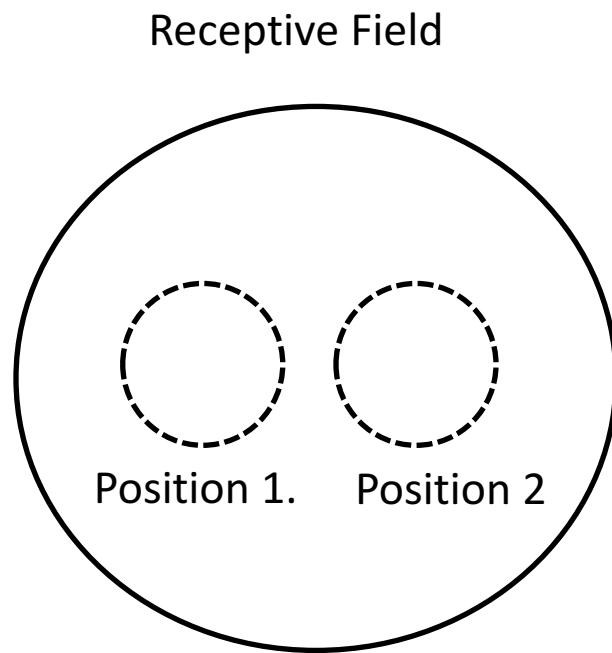


Pasupathy A, Connor CE. Shape representation in area V4: position-specific tuning for boundary conformation. *J Neurophysiol*. 2001

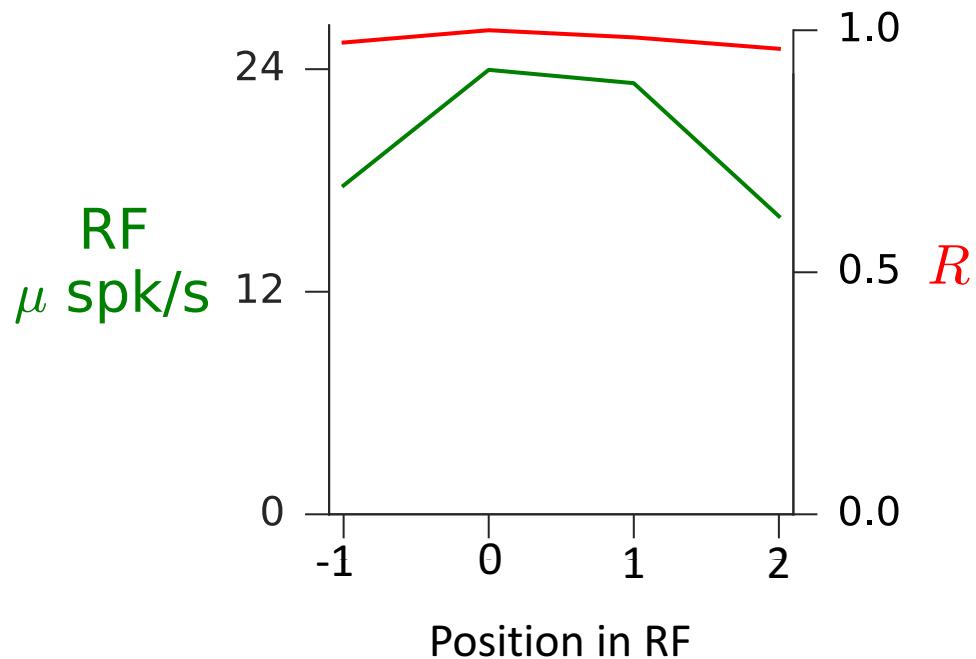
Translation Invariance



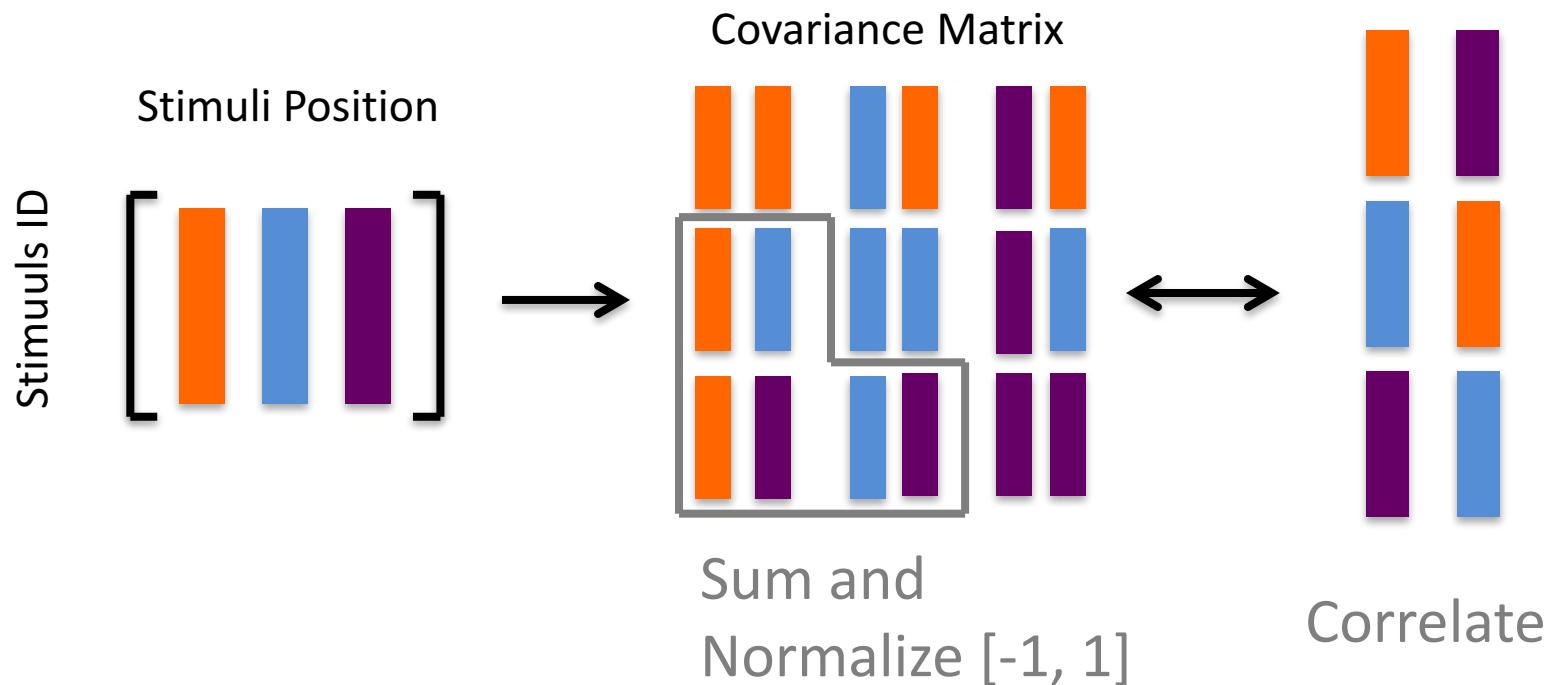
Translation Invariance



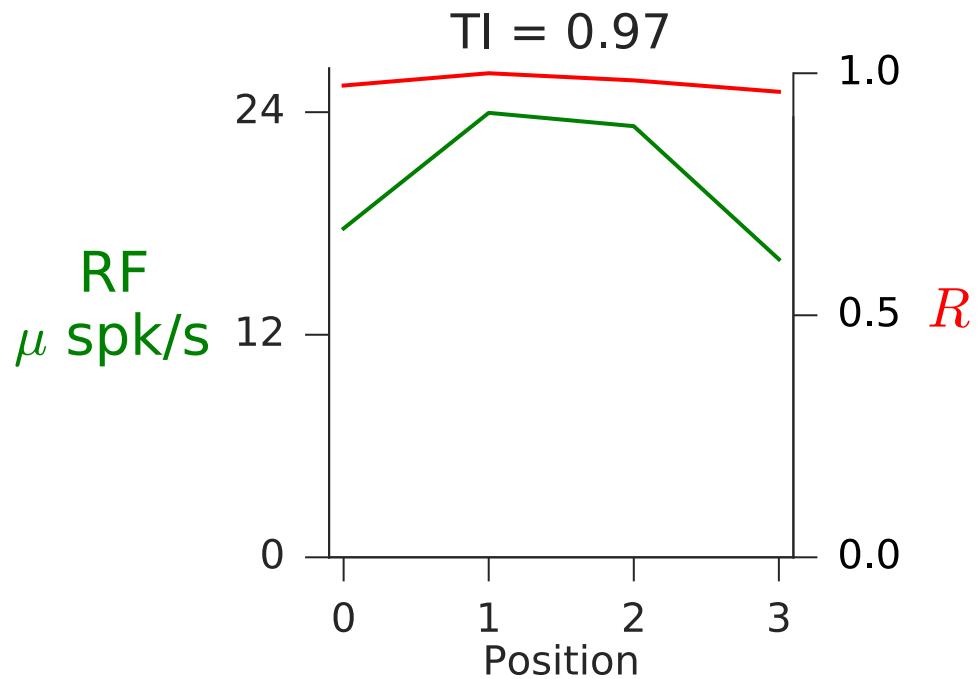
V4 Translation Invariance



$$\text{Normalized sum of covariances} = \frac{\sum_{i,j \in i \neq j} \vec{p}_i \cdot \vec{p}_j}{\sum_{i,j \in i \neq j} ||\vec{p}_i|| \ ||\vec{p}_j||}$$

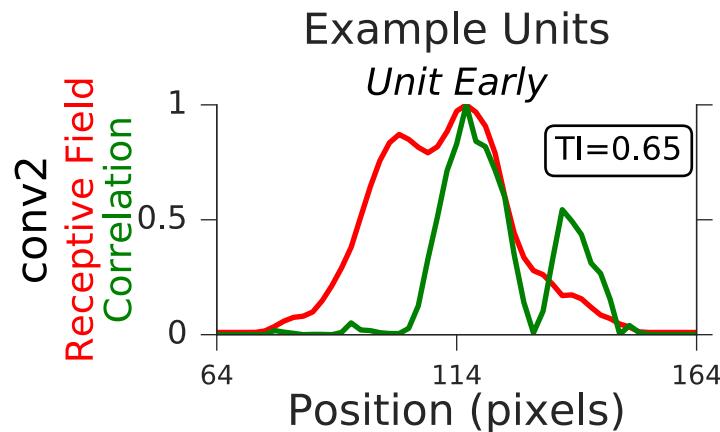


V4 Translation Invariance



$$TI = \frac{\sum_{i,j \in i \neq j} \vec{p}_i \cdot \vec{p}_j}{\sum_{i,j \in i \neq j} ||\vec{p}_i|| \ ||\vec{p}_j||}$$

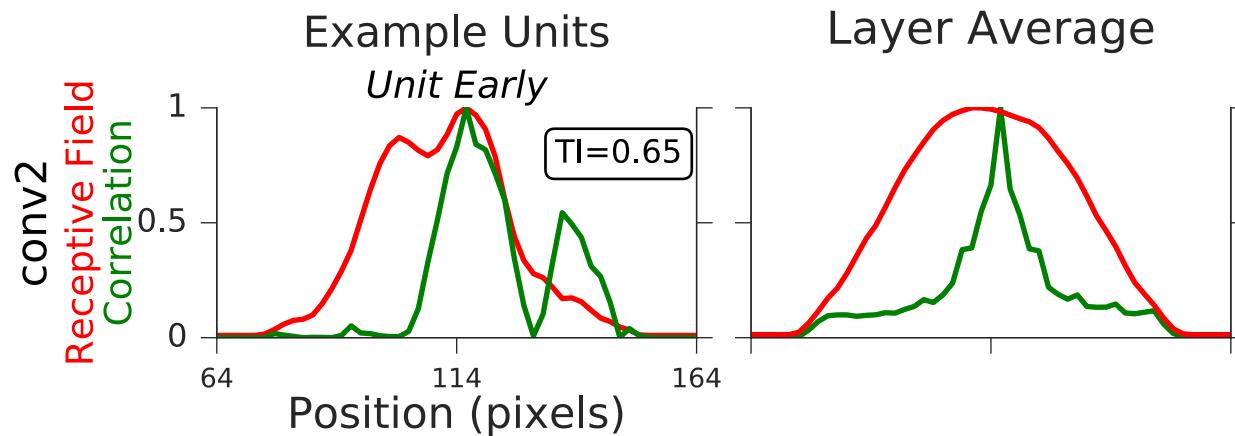
AlexNet Translation Invariance



conv5

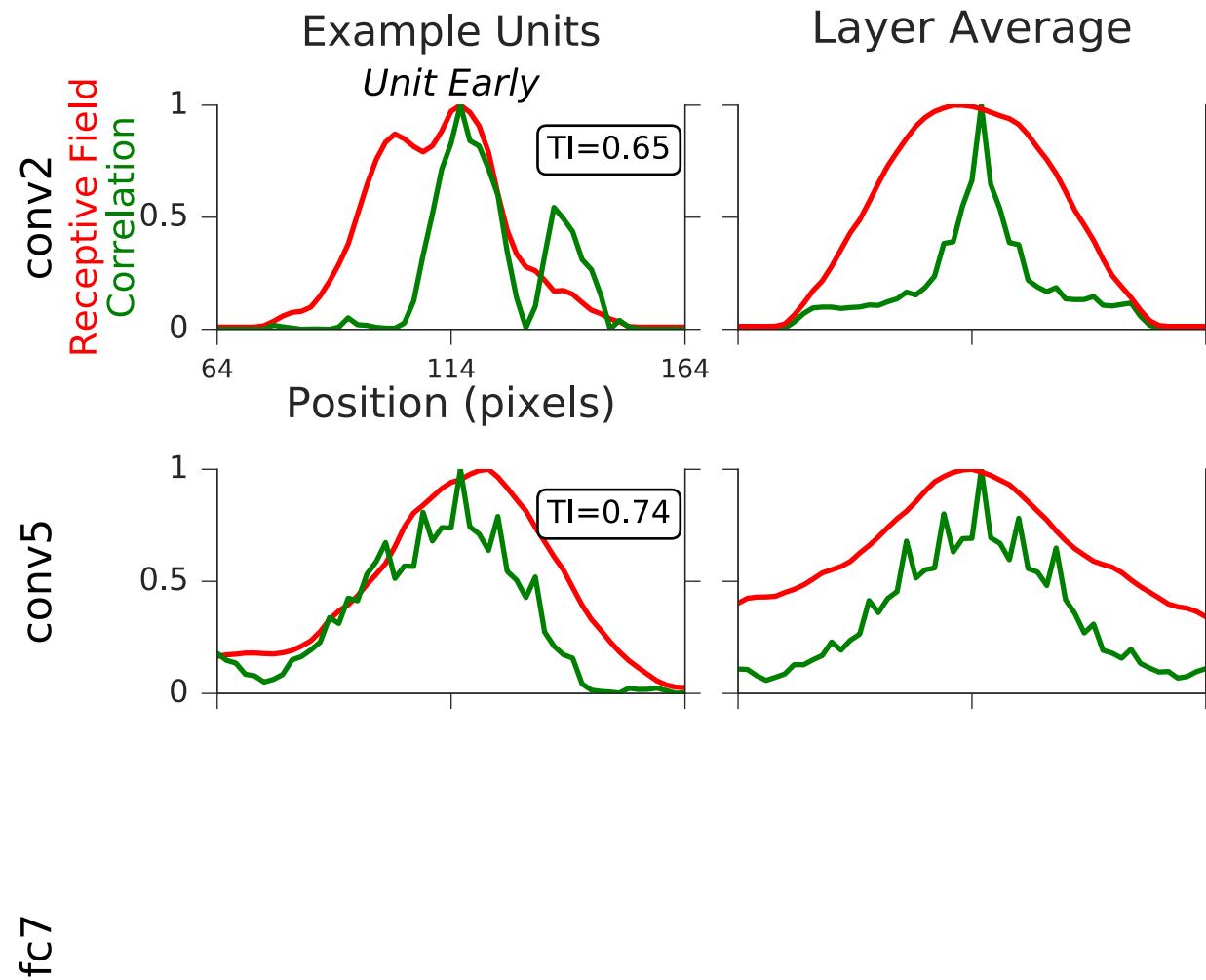
fc7

AlexNet Translation Invariance

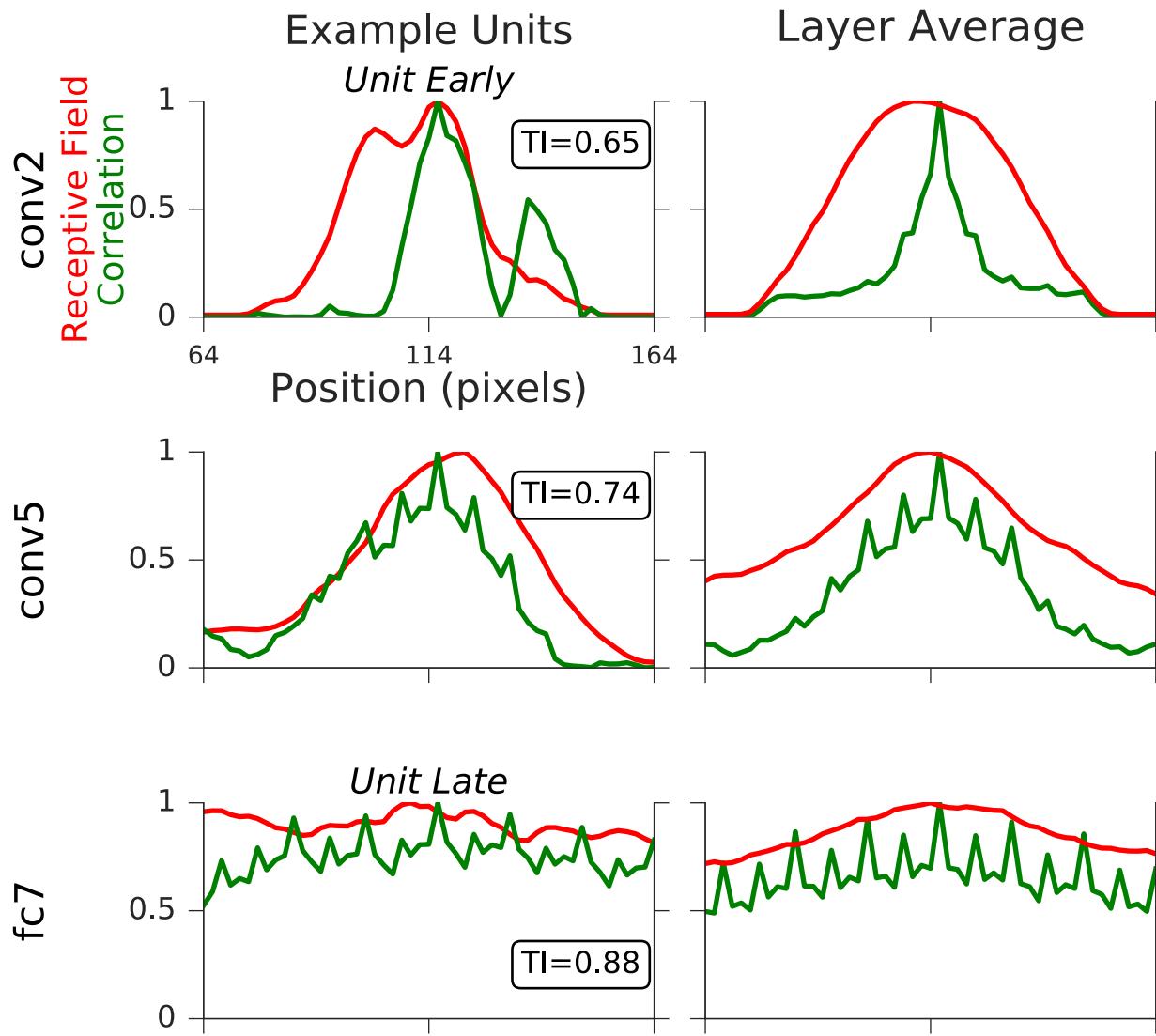


fc7

AlexNet Translation Invariance

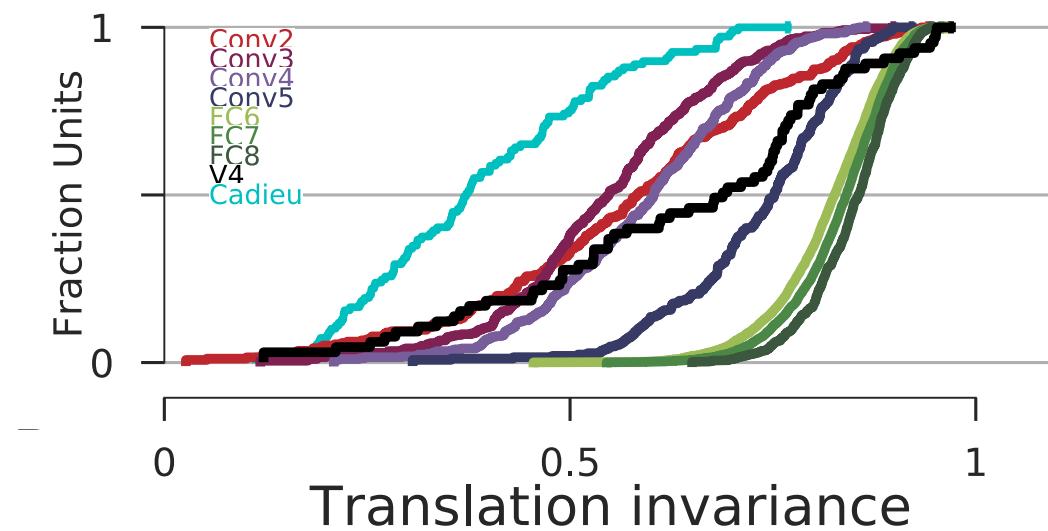


AlexNet Translation Invariance



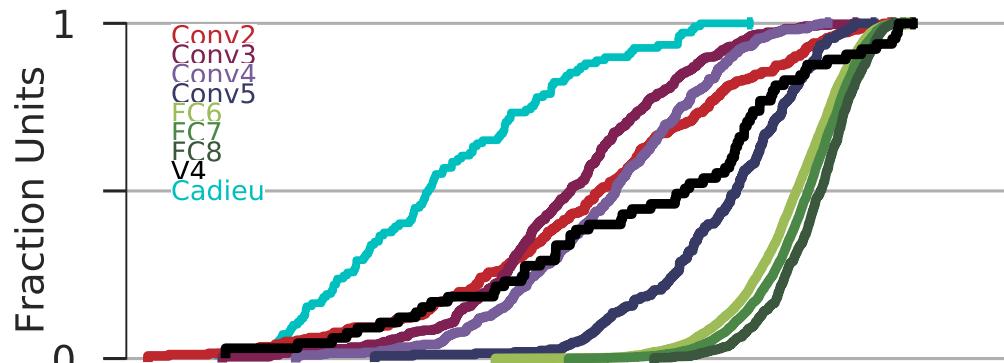
TI increases with Layer

A.

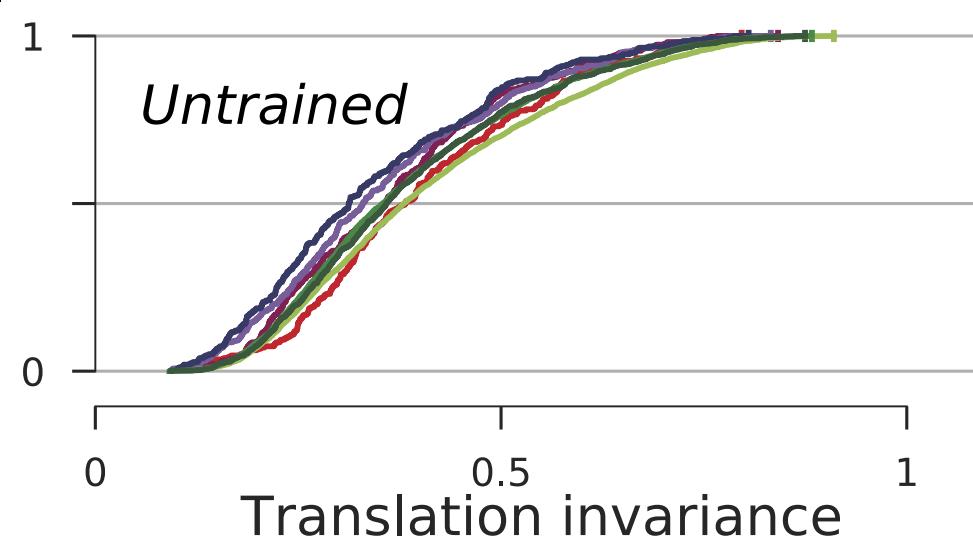


Convolution and Max-pooling don't give you translation invariance.

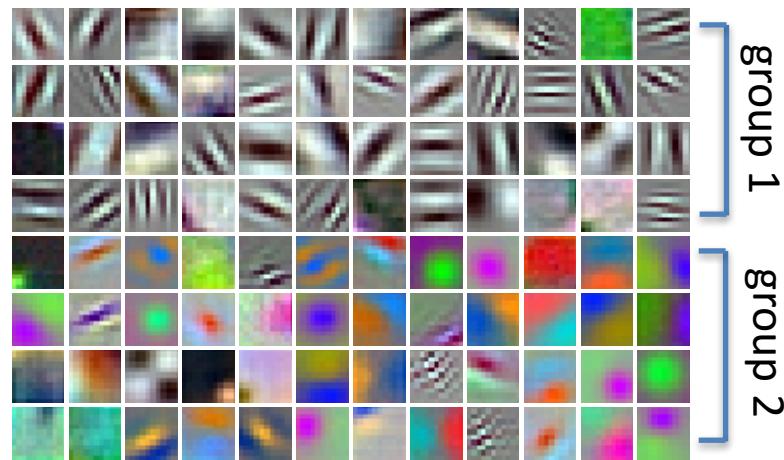
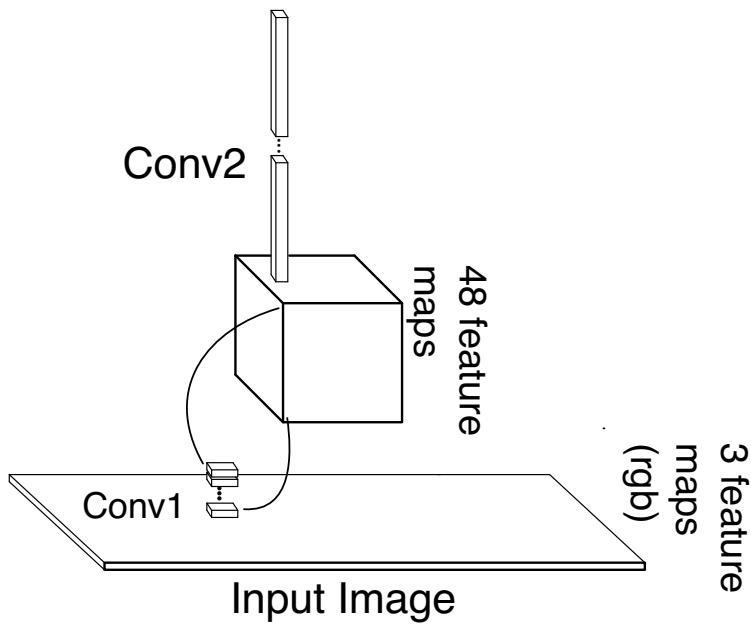
A.

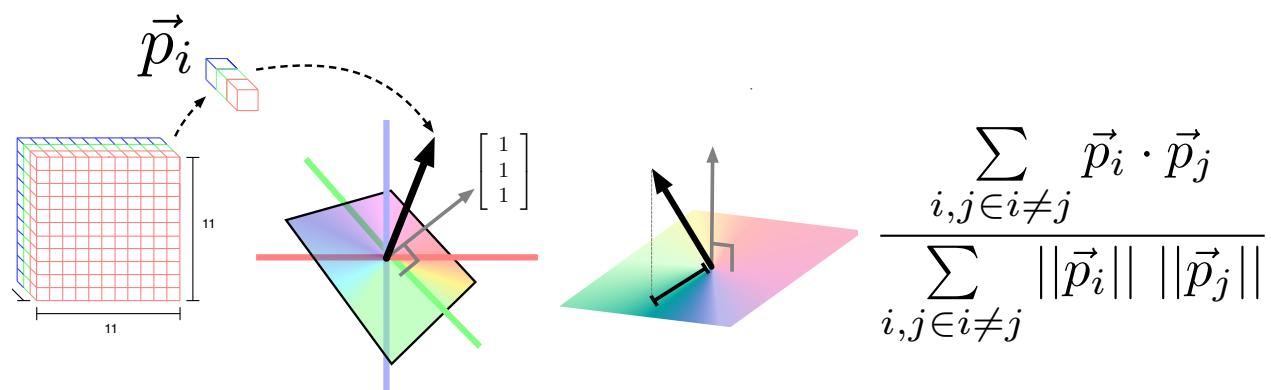
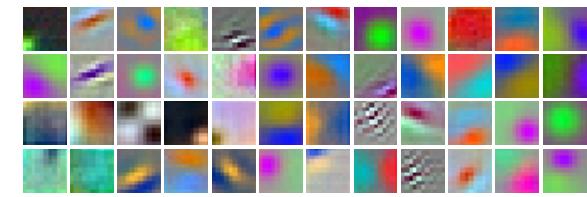


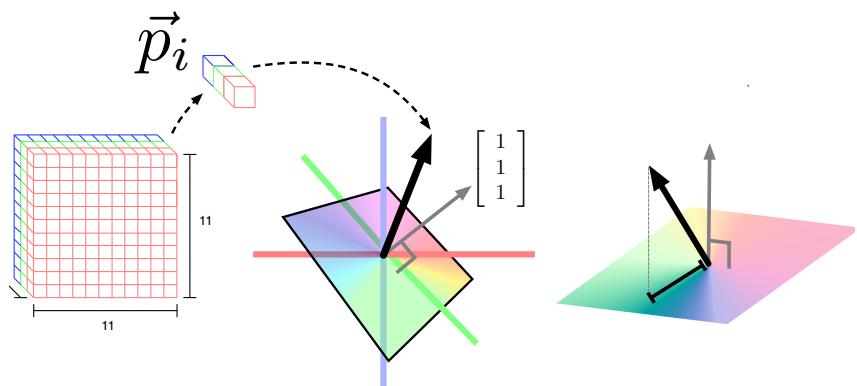
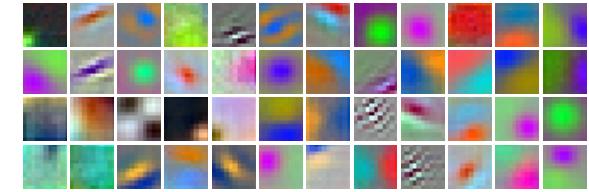
B.



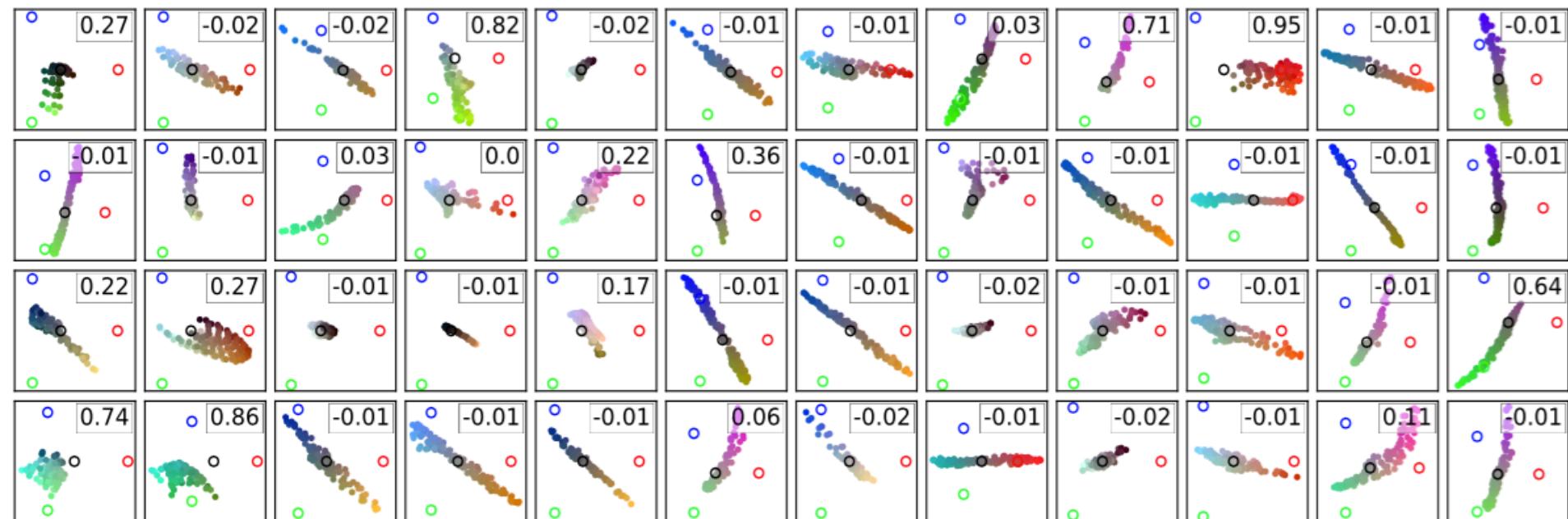
Hypothesis:
Cells with uniform spatial selectivity are translation invariant.



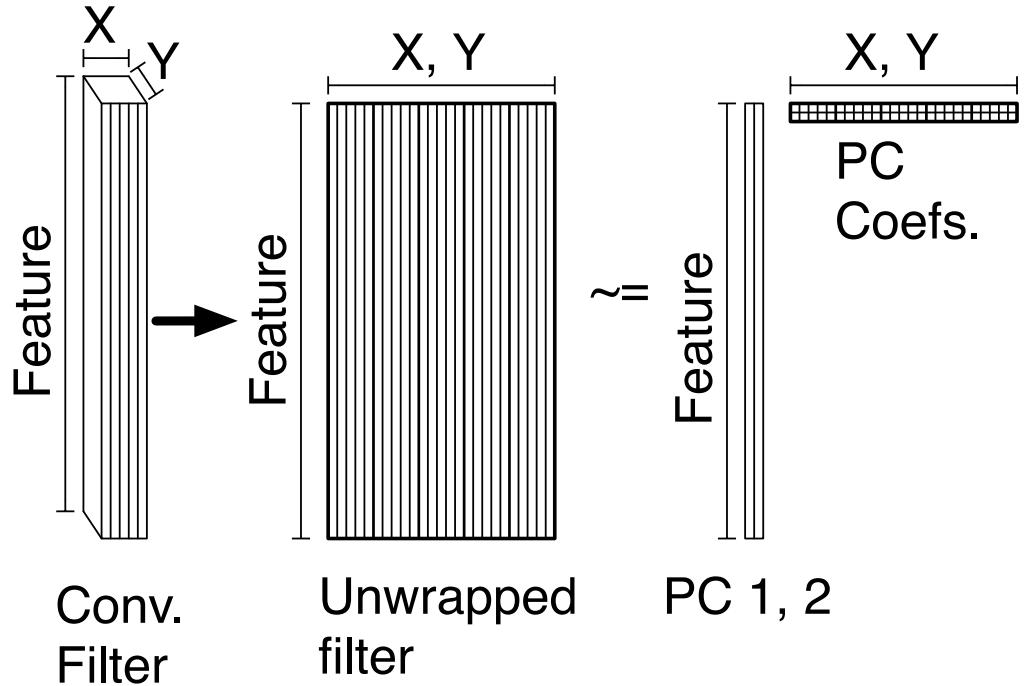




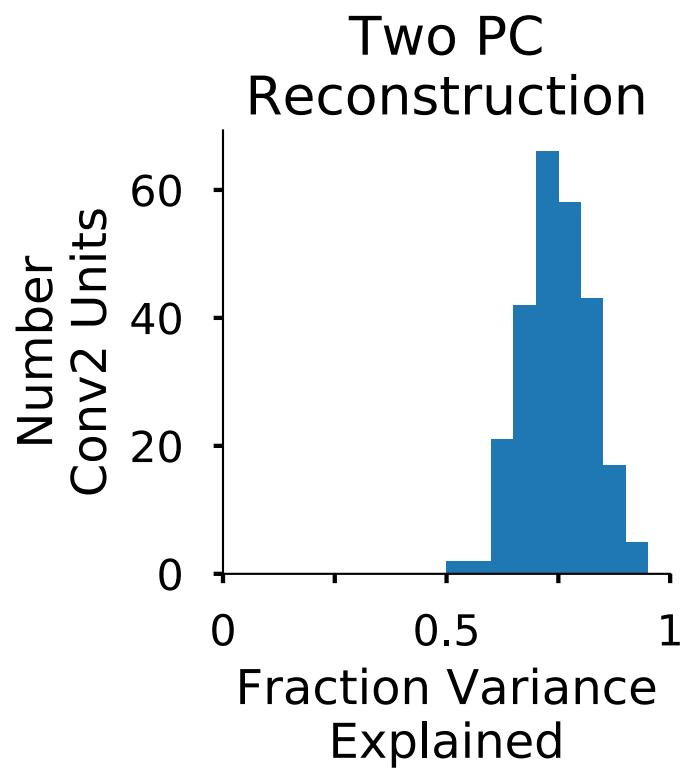
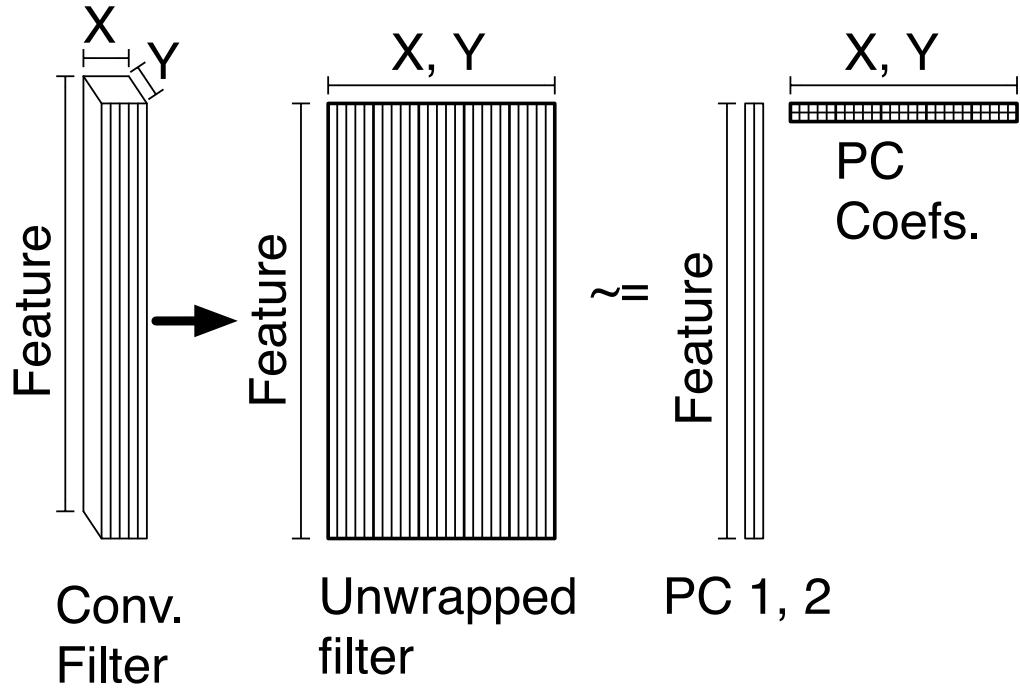
Filters plotted in the chromatic plane and their measured weight covariance.



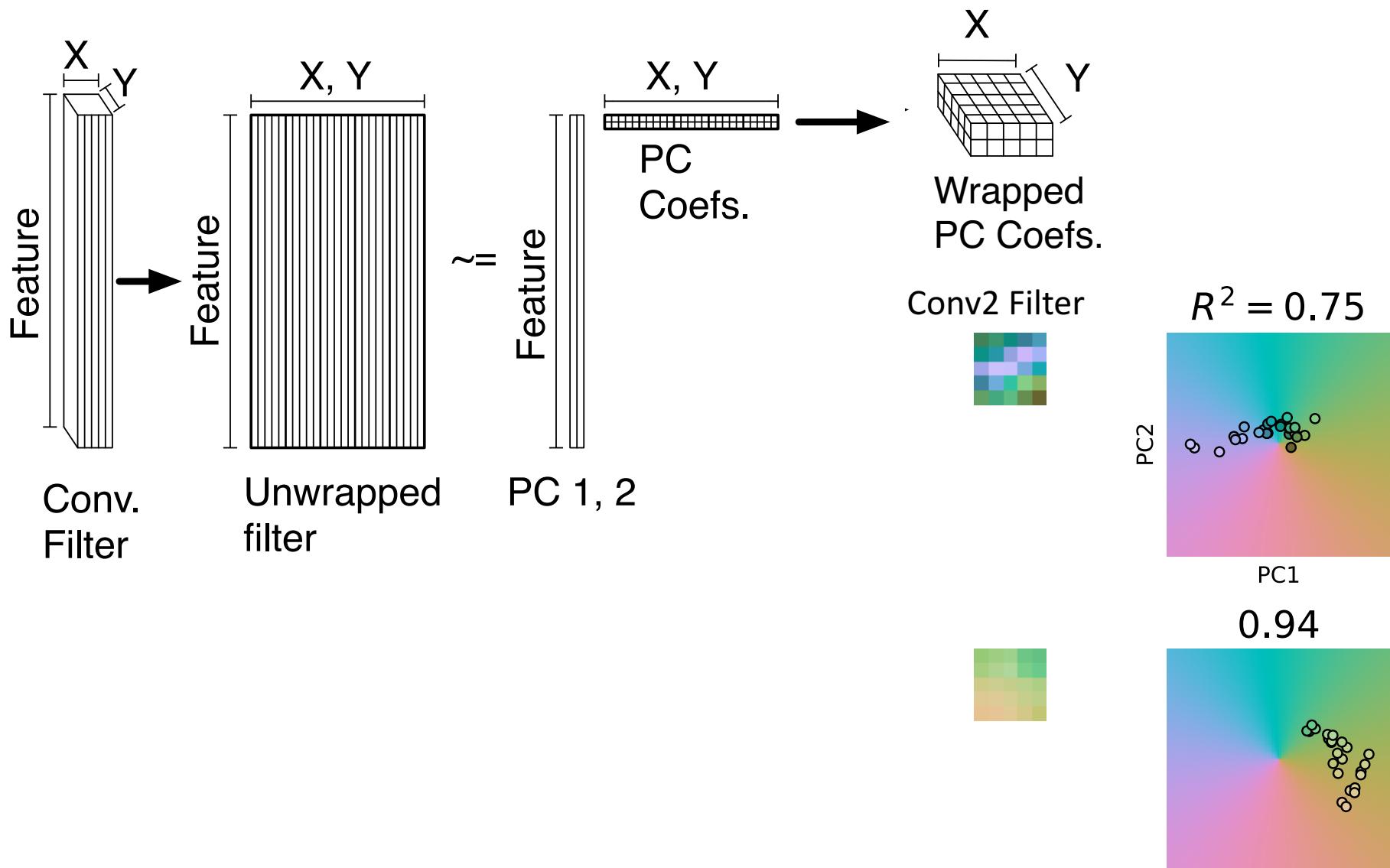
Selectivity is low-dimensional in conv2.



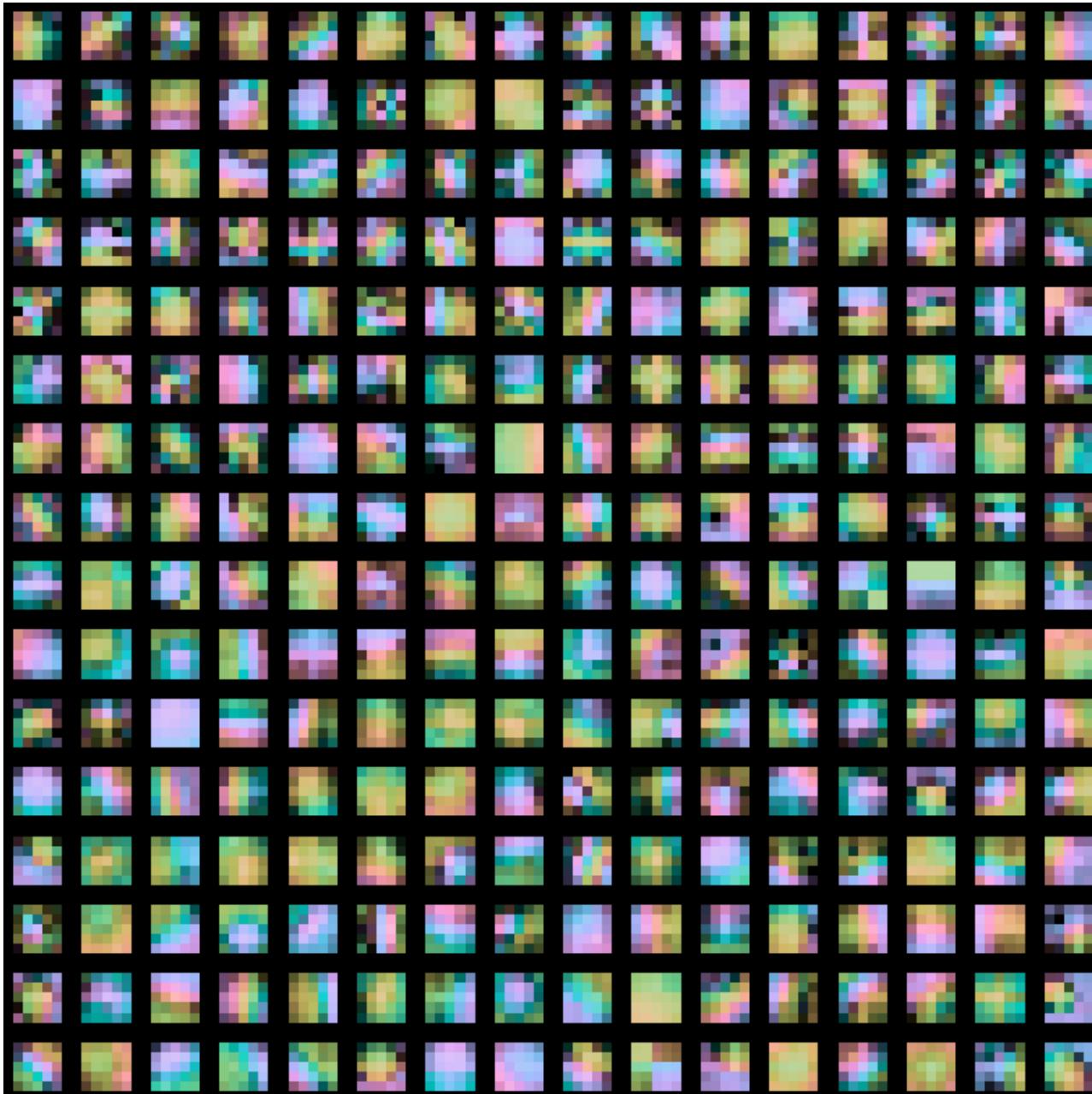
CNN selectivity is low dimensional



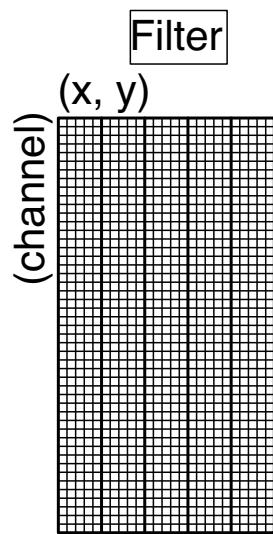
CNN selectivity is low dimensional



Hue=Angle(PC1 Coef., PC2 Coef.)
Luminance=Correlation(Reconstruction, Original)



Weight Covariance



$$\frac{\sum_{i,j \in i \neq j} \vec{p}_i \cdot \vec{p}_j}{\sum_{i,j \in i \neq j} ||\vec{p}_i|| \ ||\vec{p}_j||}$$

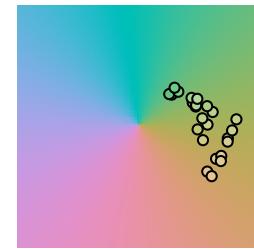
Conv2 Filter Wt. Cov.=0.17



PC2

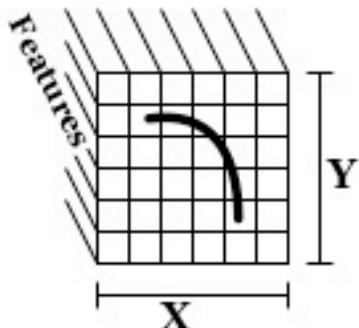


0.78



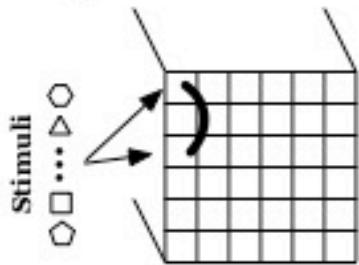
Linear models work in hidden layer.

Weight correlation



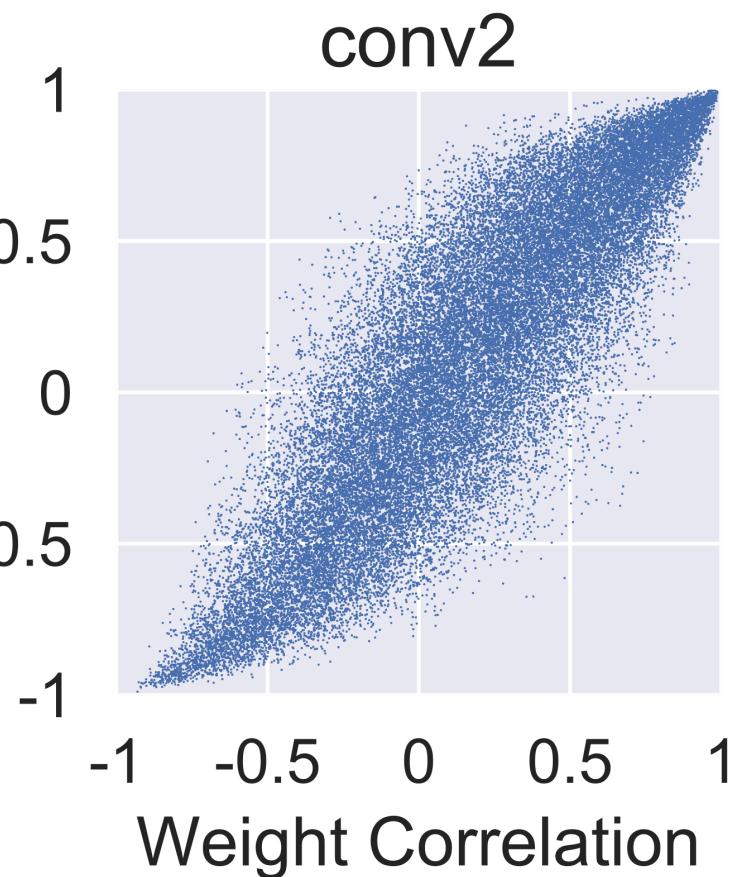
Get correlation between
spatial channel's feature weights.

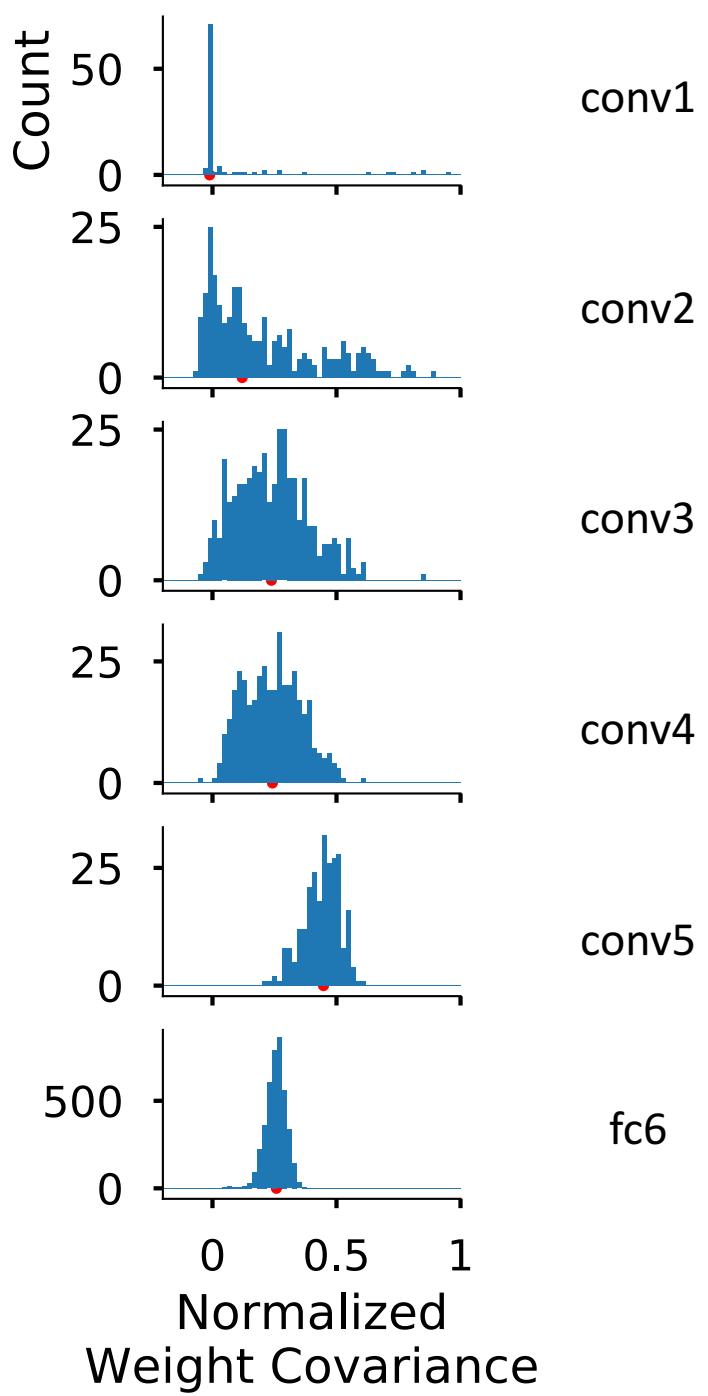
Response Correlation



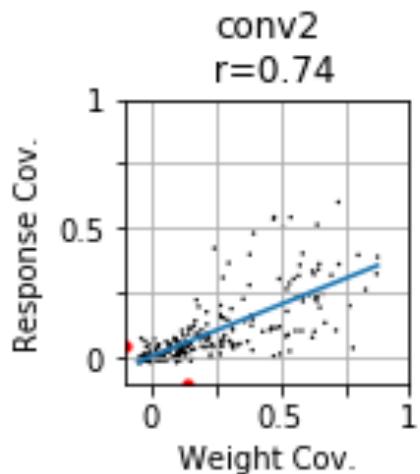
Stimulate all spatial channels
get correlations between responses.

Response Correlation

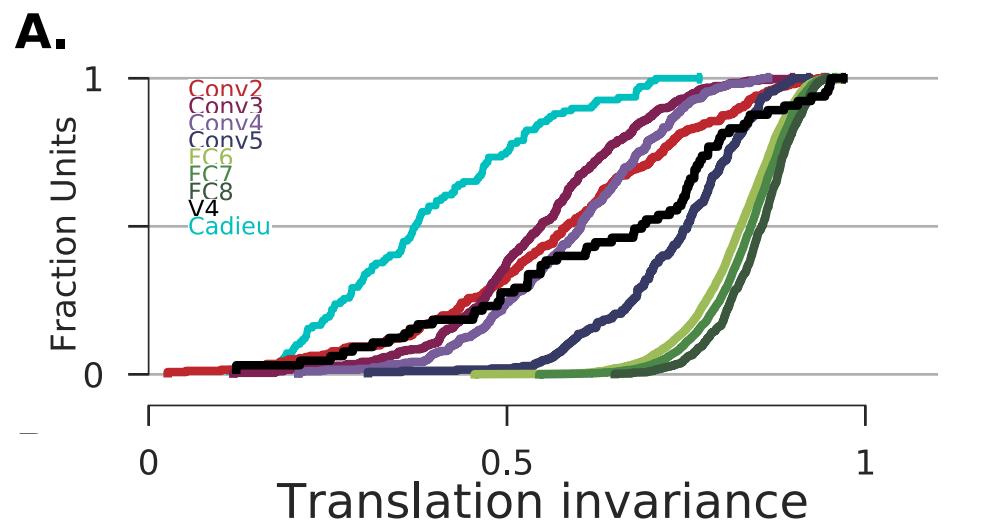
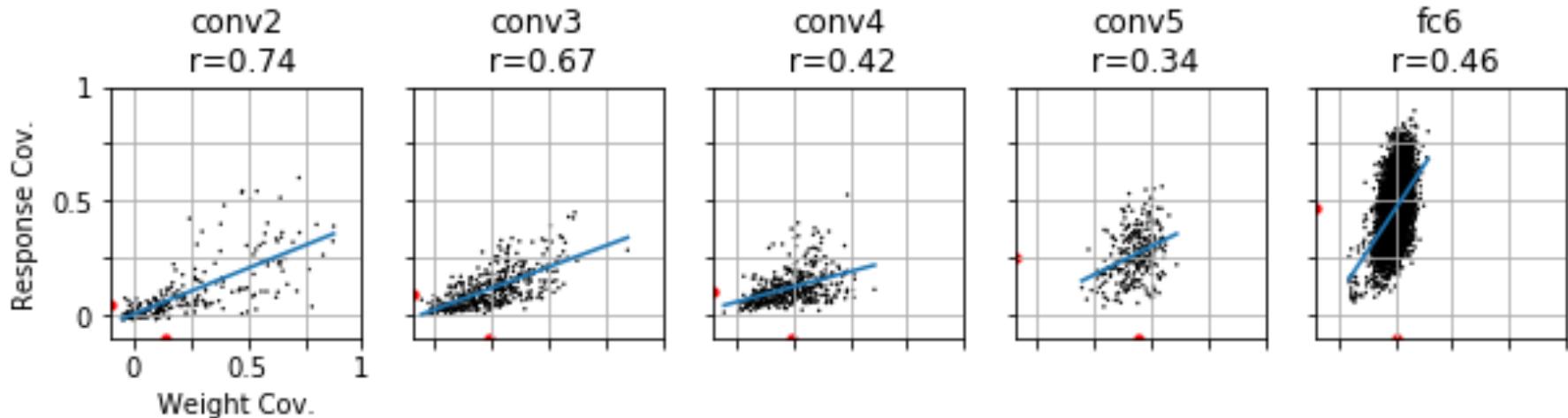




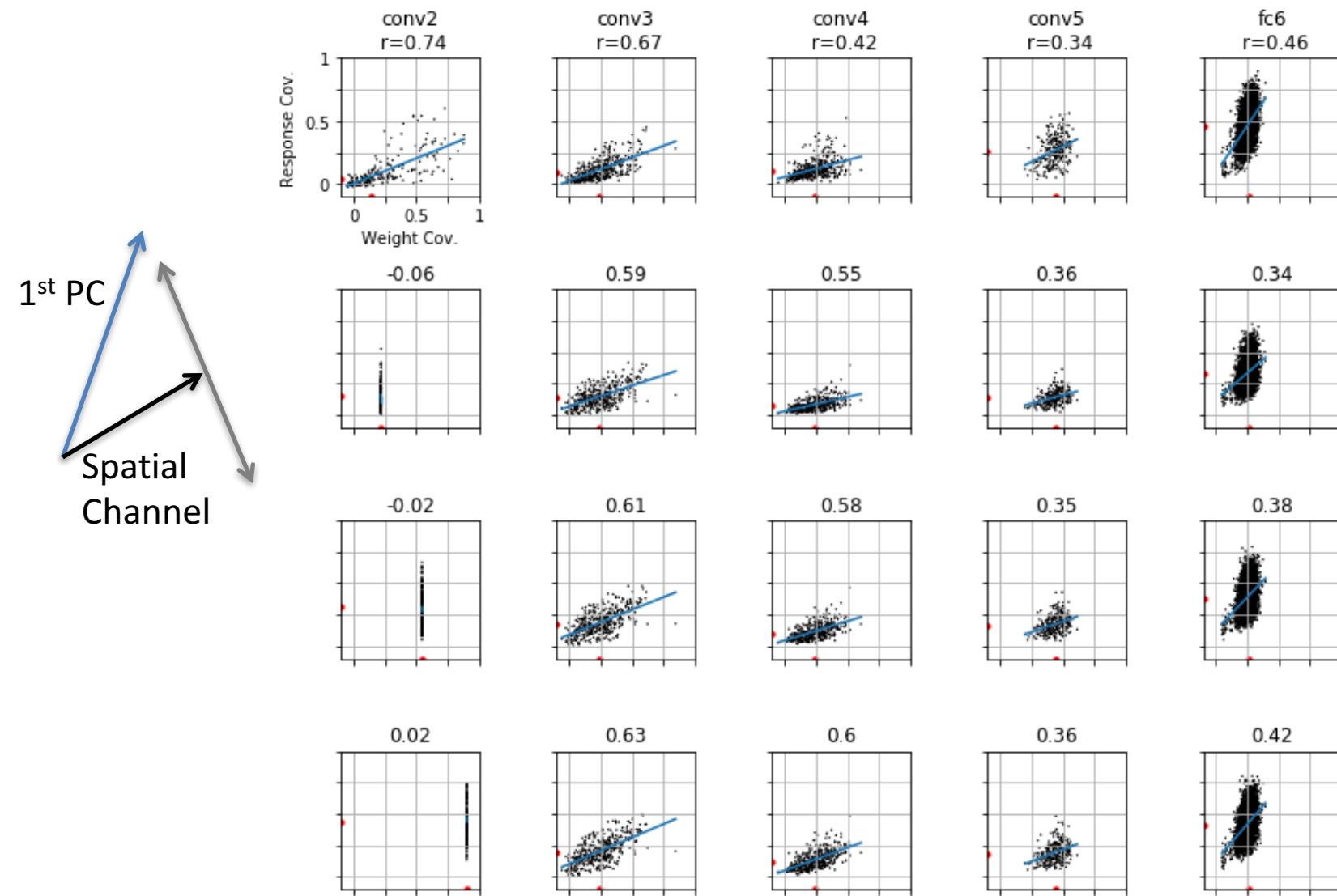
Weight Covariance Predicts TI



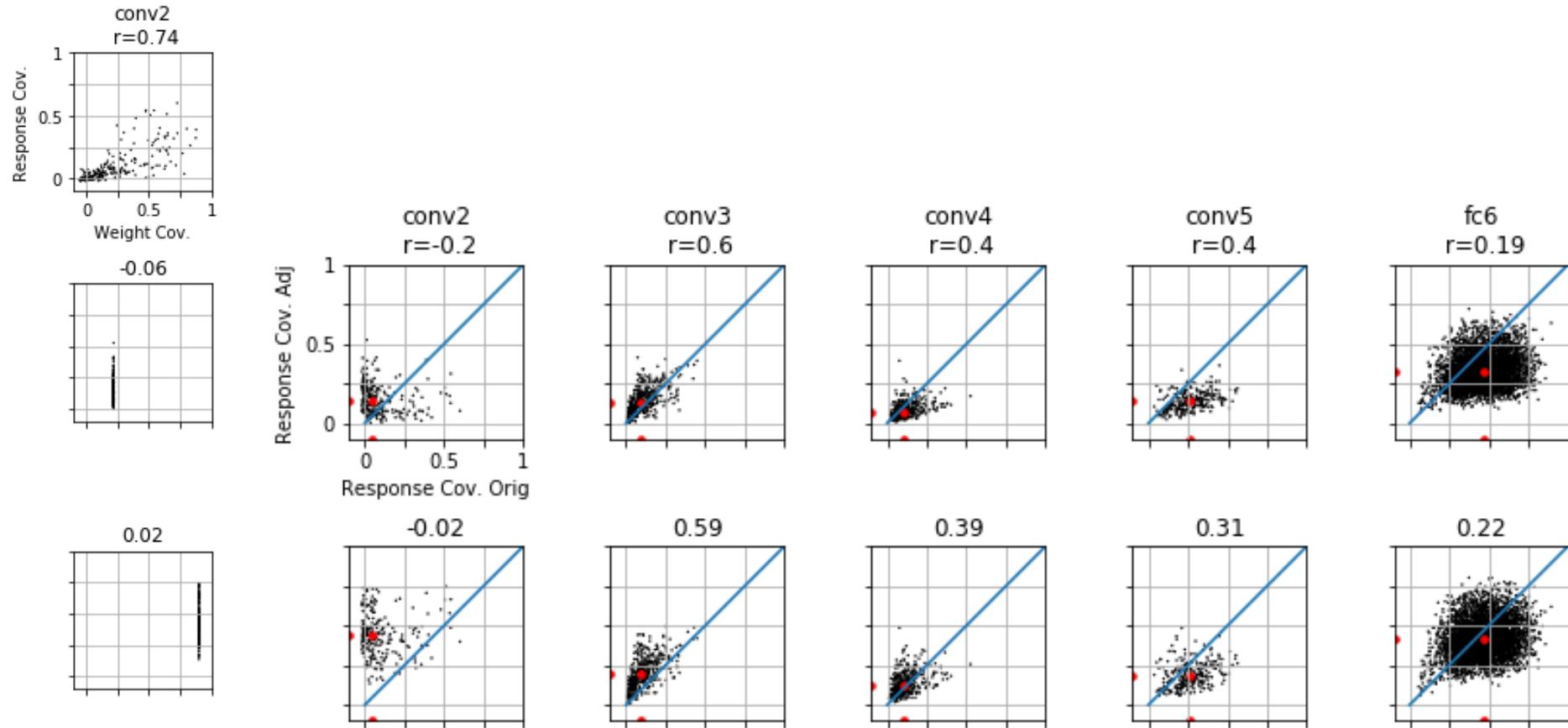
Weight Covariance Predicts Translation Invariance



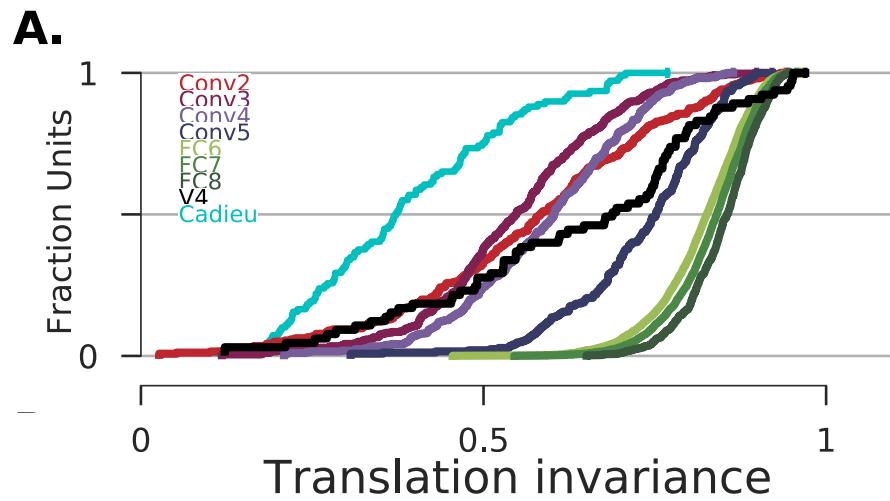
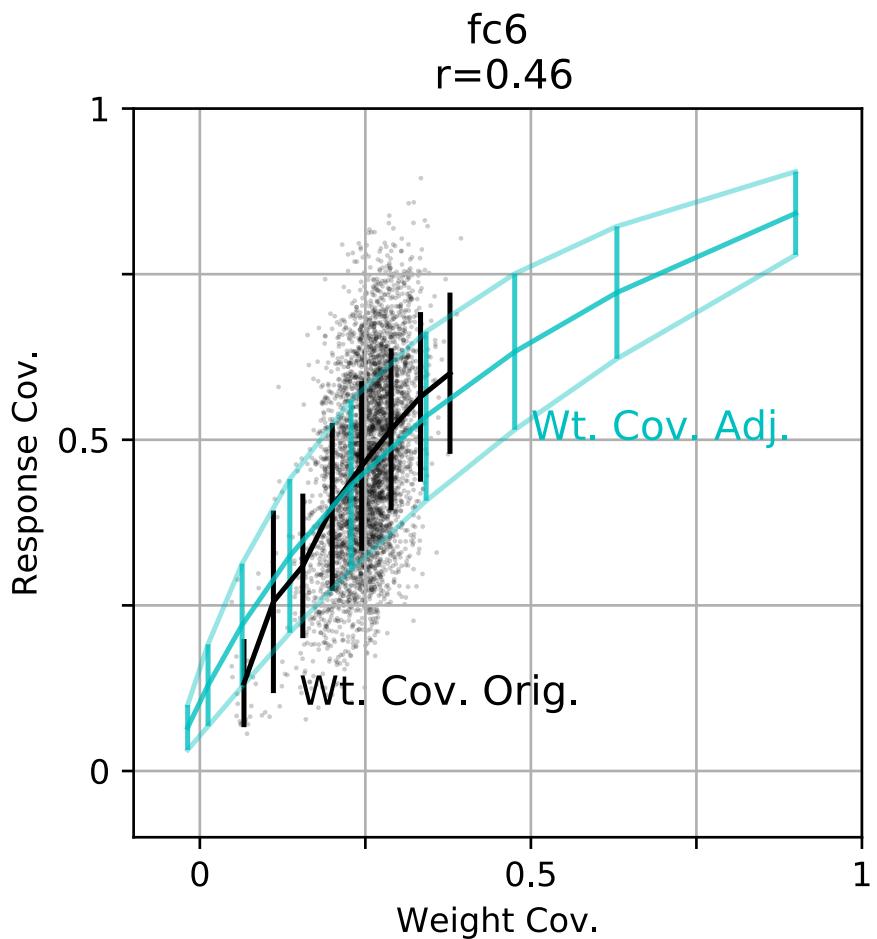
Weight Covariance Increases Translation Invariance



Weight Covariance Increases Translation Invariance



TI Could Have Been Higher



Thanks! Questions?

Weight Covariance Predicts Translation Invariance

