When All We Need is a Piece of the Pie:

A Generic Framework for Optimizing Two-way Partial AUC



Zhiyong Yang^{1,2}, Qianqian Xu³, Shilong Bao^{1,2}, Yuan He⁶, Xiaochun Cao^{1,2}, Qingming Huang^{2,3,4,5}*

¹Institute of Information Engineering, CAS ²University of Chinese Academy of Sciences

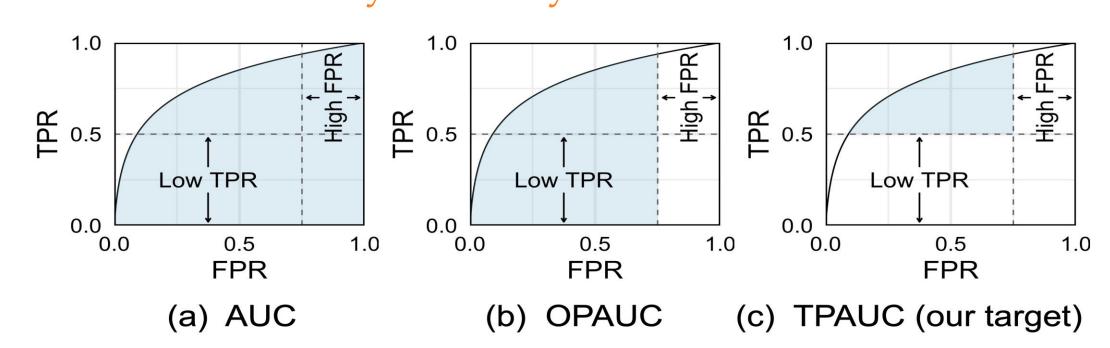
³Institute of Computing Technology, CAS ⁴BDKM, CAS ⁵Peng Cheng Laboratory ⁶Alibaba Group



Motivation

In most applications, a skillful classifier should simultaneously embrace a high TPR and a low FPR. However,

- Traditional AUC summarizes the average performance over all possible TPRs and FPRs, showing a biased estimation of the performance by involving some unrelated regions, Fig-(a).
- The One-way Partial AUC (OPAUC) only calculates the AUC within a pre-defined FPR range $[\alpha, \beta]$, Fig-(b).
- The Two-way Partial AUC (TPAUC) can serve this purpose shown in Fig-(c), which measures the area of a partial region of the ROC curve with $TPR \ge 1 - \alpha, FPR \le \beta$. But how to optimize the TPAUC metric directly has not yet been studied.



Two-Way Partial AUC Metrics

• Define TPAUC as follows:

$$\mathsf{TPR} \leq \beta$$

$$\mathsf{TPR} \geq 1 - \alpha$$

$$\mathsf{TPAUC} = \int_{\xi}^{\beta} \mathsf{TPR} \left(\mathsf{FPR}^{-1}(\theta) \right) d\theta - (1 - \alpha) \cdot (\beta - \xi)$$

$$\xi = \mathsf{FPR} \left(\mathsf{TPR}^{-1}(1 - \alpha) \right)$$
 a function of the scoring function f

• Reformulation of TPAUC:

$$AUC_{\beta}^{\alpha}(f_{\theta}, \mathcal{S}) = \mathbb{E}\left[\mathbf{1}\left[f(\boldsymbol{x}) > f(\boldsymbol{x'}), f(\boldsymbol{x}) \leq t_{1-\alpha}, f(\boldsymbol{x'}) \geq t_{\beta}|y = 1, y' = -1\right]\right]$$

$$t_{1-\alpha} = \operatorname*{argmin}_{\delta \in \mathbb{R}}\left[\delta \in \mathbb{R} : \mathbb{E}\left[\mathbf{1}\left[f(\boldsymbol{x}^{+}) \leq \delta\right]\right] = \alpha\right]$$

$$t_{\beta} = \operatorname*{argmin}_{\delta \in \mathbb{R}}\left[\delta \in \mathbb{R} : \mathbb{E}\left[\mathbf{1}\left[f(\boldsymbol{x}^{-}) \geq \delta\right]\right] = \beta\right]$$

• Surrogate loss minimization:

Construct Surrogate Optimization Problems

Bi-level optimization

$$(OP_1) \min_{\boldsymbol{\theta}} \frac{1}{n_+^{\alpha} n_-^{\beta}} \sum_{i=1}^{n_+} \sum_{j=1}^{n_-} v_i^+ \cdot v_j^- \cdot \ell\left(f_{\boldsymbol{\theta}}, \boldsymbol{x}_i^+, \boldsymbol{x}_j^-\right)$$
s.t $v_+ = \operatorname*{argmax}_{v_i^+ \in [0,1]} \sum_{i=1}^{n_+} \left(\boldsymbol{v}_i^+ \cdot \left(1 - f_{\boldsymbol{\theta}}\left(\boldsymbol{x}_i^+\right)\right) - \varphi_{\boldsymbol{\gamma}}\left(\boldsymbol{v}_i^+\right) \right)$

$$v_- = \operatorname*{argmax}_{v_j^- \in [0,1]} \sum_{j=1}^{n_-} \left(\boldsymbol{v}_j^- \cdot f_{\boldsymbol{\theta}}\left(\boldsymbol{x}_j^-\right) - \varphi_{\boldsymbol{\gamma}}\left(\boldsymbol{v}_j^-\right) \right)$$

$$v_- = \operatorname*{argmax}_{v_j^- \in [0,1]} \sum_{j=1}^{n_-} \left(\boldsymbol{v}_j^- \cdot f_{\boldsymbol{\theta}}\left(\boldsymbol{x}_j^-\right) - \varphi_{\boldsymbol{\gamma}}\left(\boldsymbol{v}_j^-\right) \right)$$

The connection between weight and the penalty is the key!

Dual correspondence

Definition 1 Calibrated Smooth Penalty Function regularities

A penalty function $\varphi_{\gamma}(x): \mathbb{R}_+ \to \mathbb{R}$ satisfies the following

(A) φ_{γ} has continuous third-order derivatives.

(B) φ_{γ} is strictly increasing in the sense that $\varphi'_{\gamma}(x) > 0$.

(C) φ_{γ} is strictly convex in the sense that $\varphi_{\gamma}''(x) > 0$.

(D) φ_{γ} has positive third-order derivatives in the sense that $\varphi_{\gamma}'''(x) > 0$.

Definition 2 Calibrated Weighting Function

A weighting function $\psi_{\gamma}(x):[0,1]\to\operatorname{Rng}$, where $\operatorname{Rng}\subseteq[0,1]$, satisfies the following regularities:

(A) ψ_{γ} has continuous second-order derivatives.

(B) ψ_{γ} is strictly increasing in the sense that $\psi'_{\gamma}(x) > 0$.

(C) ψ_{γ} is strictly concave in the sense that $\psi_{\gamma}''(x) < 0$.

Proposition 1

Given a strictly convex function φ_{γ} and define $\psi_{\gamma}(t)$ s

 $\psi_{\gamma}(t) = \operatorname{argmax} \ v \cdot t - \varphi_{\gamma}(v)$

Then we can draw the following conclusions:

(a) If φ_{γ} is a calibrated smooth penalty function, we have $\psi_{\gamma}(t) = \varphi_{\gamma}^{\prime - 1}(t)$. (b) If ψ_{γ} is a calibrated weighting function such that $v=\psi_{\gamma}(t)$ we have

 $\varphi_{\gamma}(v) = \int \psi_{\gamma}^{-1}(v) dv + \text{const.}$

weight to penalty

penalty to weight

Theoretical analysis

Theorem 1 (Informal).

The following inequality holds with high probability:

$$\mathcal{R}_{AUC}^{\alpha,\beta}\left(f_{\boldsymbol{\theta}},\mathcal{S}\right) \leq \hat{\mathcal{R}}_{\psi}^{\ell}\left(f_{\boldsymbol{\theta}},\mathcal{S}\right) + \tilde{\mathcal{O}}\left(\left(\frac{\text{VC}}{n_{+}}\right)^{1/2} + \left(\frac{\text{VC}}{n_{-}}\right)^{1/2}\right)$$

where $\tilde{\mathcal{O}}$ is the big-O complexity notation hiding the logarithm factors,

$$\mathcal{R}_{AUC}^{\alpha,\beta}\left(f_{\theta},\mathcal{S}\right) = 1 - \mathrm{AUC}_{\alpha}^{\beta}\left(f_{\theta},\mathcal{S}\right),$$

and VC is the VC dimension of the hypothesis class:

$$\mathcal{T}(\mathcal{F}) \triangleq \{ \operatorname{sign} (f_{\theta}(\cdot) - \delta) : f_{\theta} \in \mathcal{F}, \delta \in \mathbb{R} \}$$

$v_i^+ = \psi_{\gamma} \left(1 - f_{\theta} \left(\boldsymbol{x}_i^+\right)\right), v_j^- = \psi_{\gamma} \left(f_{\theta} \left(\boldsymbol{x}_j^-\right)\right), v_i^+, v_j^- \in [0, 1]$

If ψ_{γ} has a closed-form expression

Cancel the inner

$$\hat{\mathcal{R}}_{\psi}^{\ell}\left(\mathcal{S}, f_{\boldsymbol{\theta}}\right) = \frac{1}{n_{+}n_{-}} \sum_{i=1}^{n_{+}} \sum_{j=1}^{n_{-}} \psi_{\gamma} \left(1 - f_{\boldsymbol{\theta}}\left(\boldsymbol{x}_{i}^{+}\right)\right) \psi_{\gamma} \left(f_{\boldsymbol{\theta}}\left(\boldsymbol{x}_{j}^{-}\right)\right) \cdot \ell\left(f_{\boldsymbol{\theta}}, \boldsymbol{x}_{i}^{+}, \boldsymbol{x}_{j}^{-}\right)$$

Two instantiations

Example 1 (Polynomial Surrogate Model).

$$\varphi_{\gamma}^{\text{poly}}\left(t\right) = \frac{1}{\gamma} \cdot t^{\gamma}, \psi_{\gamma}^{\text{poly}}\left(t\right) = t^{\frac{1}{\gamma - 1}}, \gamma > 2$$

Example 2 (Exponential Surrogate Model).

$$\varphi_{\gamma}^{\exp}(t) = \frac{(1-t)(\log(1-t)-1)+1}{\gamma}$$
$$\psi_{\gamma}^{\exp}(t) = 1 - e^{-\gamma t}$$

Experiments

Table 1. Performance Comparisons over different metrics and datasets, where (x, y) stands for TPAUC(x, y) in short.

			Subset1			Subset2			Subset3		
dataset	type	methods	(0.3,0.3)	(0.4,0.4)	(0.5,0.5)	(0.3,0.3)	(0.4,0.4)	(0.5,0.5)	(0.3,0.3)	(0.4,0.4)	(0.5,0.5)
CIFAR-10-LT	Competitors	CE-RW	9.09	30.86	47.99	72.83	83.33	88.71	23.47	44.44	59.69
		Focal	9.84	30.89	50.83	75.72	85.10	90.06	21.47	45.88	59.09
		CBCE	3.29	27.30	43.95	69.48	80.80	86.87	12.94	34.06	51.09
		CBFocal	9.04	31.73	48.13	77.99	86.75	91.13	21.32	43.03	59.11
		SqAUC	18.05	40.74	57.94	80.09	87.78	91.87	31.52	50.00	64.42
	Ours	Poly	21.43	44.41	59.10	80.66	88.07	92.15	36.54	54.48	67.19
		Exp	20.86	41.78	<u>58.38</u>	81.22	<u>87.88</u>	91.93	<u>32.47</u>	53.86	67.32
CIFAR-100-LT	Competitors	CE-RW	31.43	52.60	66.21	79.70	88.06	92.64	3.09	21.32	40.75
		Focal	36.51	61.71	73.25	83.08	90.35	93.76	8.09	28.88	49.89
		CBCE	17.53	38.79	55.19	67.91	79.32	85.82	1.84	18.46	37.04
		CBFocal	41.85	62.41	73.13	82.75	89.57	92.89	7.10	29.12	44.84
		SqAUC	63.24	76.62	84.68	<u>91.02</u>	93.69	94.73	41.60	60.36	70.86
	Ours-TPAUC	Poly	68.02	79.11	85.17	91.13	93.78	95.69	47.07	65.89	75.08
		Exp	63.24	<u>77.94</u>	84.62	90.69	<u>93.74</u>	<u>95.41</u>	<u>44.54</u>	<u>64.58</u>	73.02
Tiny-ImageNet-200-LT	Competitors	CE-RW	80.90	87.76	91.54	93.30	96.15	97.53	90.37	94.34	96.75
		Focal	81.18	88.06	91.72	93.23	96.08	97.59	91.35	94.87	96.63
		CBCE	80.64	87.58	91.17	93.77	96.52	97.77	91.66	95.19	96.79
		CBFocal	80.44	87.95	91.91	93.46	96.43	<u>97.64</u>	91.06	94.82	96.62
		SqAUC	80.16	87.99	91.67	93.10	96.07	97.32	92.15	<u>95.16</u>	<u>96.75</u>
	Ours-TPAUC	Poly	80.44	88.21	91.98	93.00	95.61	97.47	92.02	95.25	96.84
		Exp	82.61	89.13	92.62	93.82	96.12	97.38	91.25	94.78	96.57