

Edge Latents Guided Graph Attention Networks

STA-695 Final Project

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Outline

- 1 Introduction to graph and graph learning
- 2 Introduction to attention mechanism
- 3 Edge latents guided graph attention networks
- 4 Results
- 5 Future directions

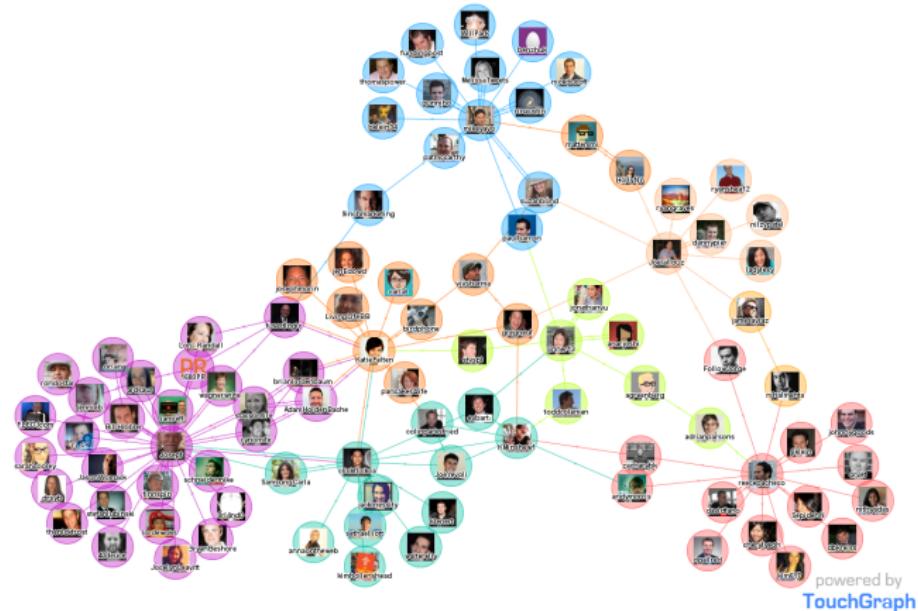
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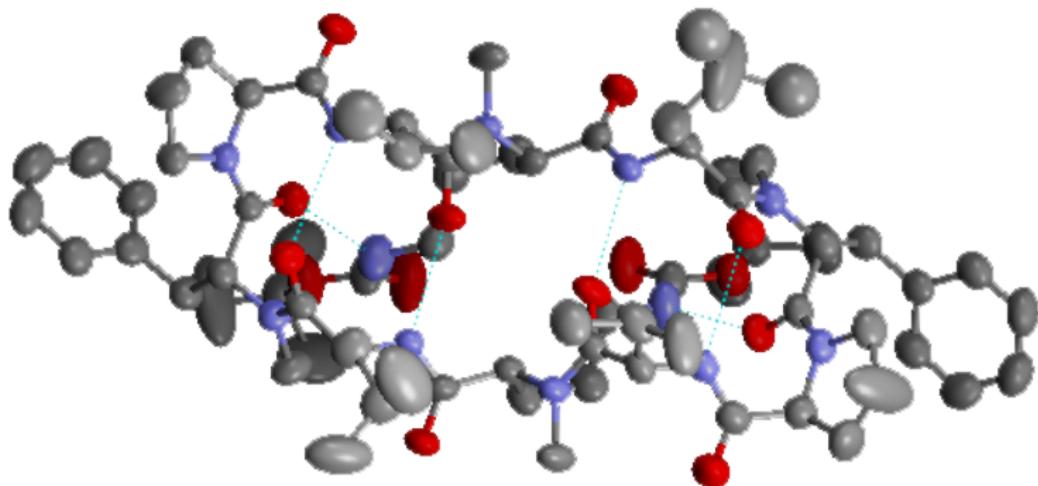
Graph

- ▶ A graph is a structure amounting to a set of objects in which some pairs of the objects are in some sense “related”.
- ▶ Components
 - ▶ Nodes (vertices, points)
 - ▶ Edges (arcs, lines)
- ▶ Graph learning
 - ▶ Node classification (regression)
 - ▶ Edge classification (regression)
 - ▶ Graph classification (regression)
 - ▶ Node clustering
 - ▶ ...

Social network



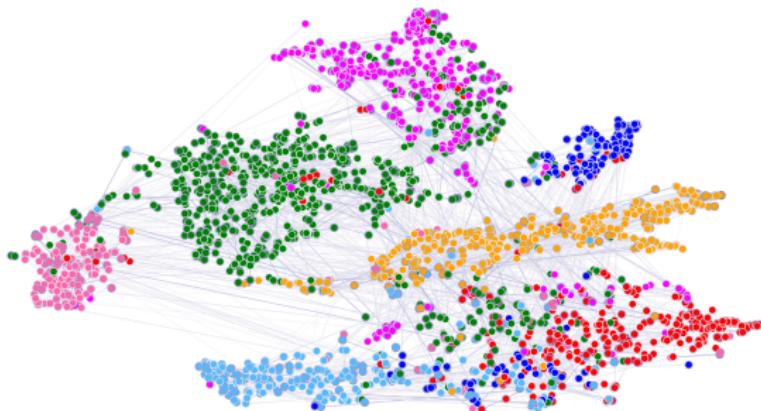
Protein-protein interaction



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Citation graph



- Node: Paper
- Edge: Citation

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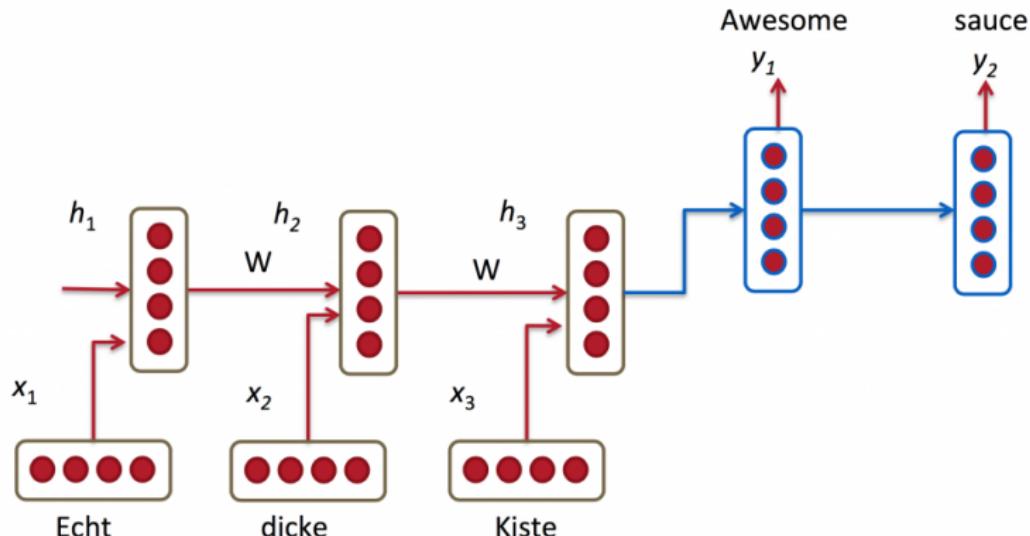
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Attention mechanism

- ▶ Hot and new topic in deep learning
- ▶ Successfully applied to machine translation problem
- ▶ A learnable mechanism to aggregate features
- ▶ Aggregate by weighted average
- ▶ The weights for aggregating is a function of features
- ▶ different content of features will have different weights
(attention)

RNN based machine translation

- ▶ Input sequence are encoded into a single vector by RNN
- ▶ Output sequence are generated from this vector by RNN



Why attention mechanism?

- ▶ The RNN (LSTM) based method surprisingly works well!
- ▶ But, obviously, there is space for improvement

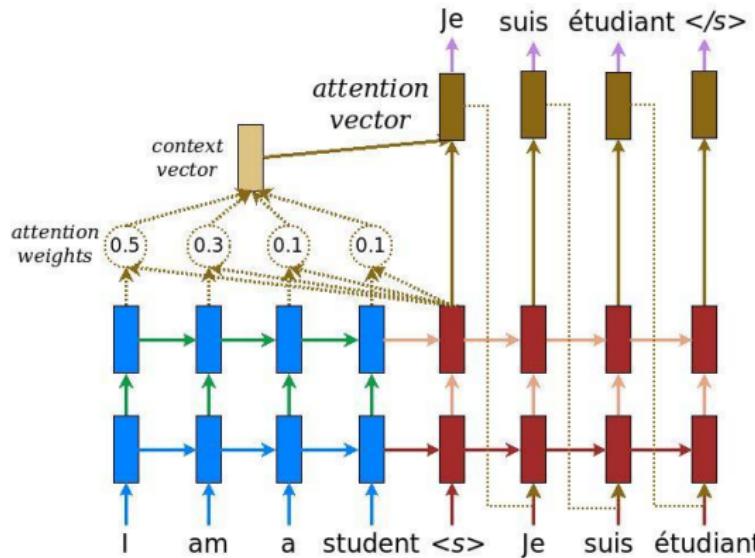
Problem

The dependency between output sequence and input sequence is complex which could not be captured by the encoding RNN

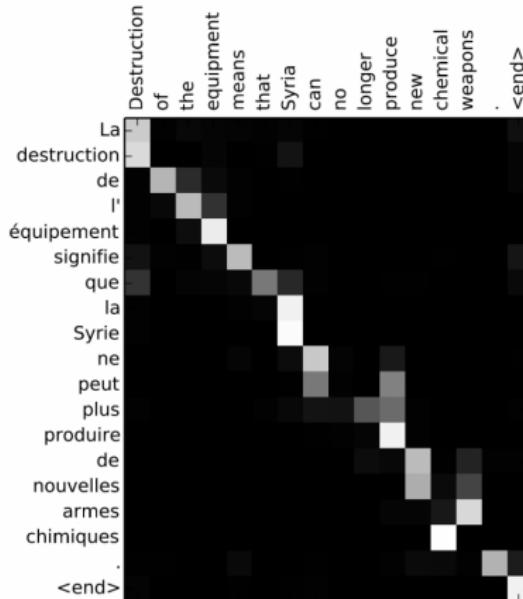
Attention mechanism

- ▶ Instead of using the last encoded vector, aggregate a feature vector from all the previous hidden states each time generating an output
- ▶ Aggregating could be a weighted average
- ▶ Weights are a trainable function of the contents

Machine translation with attention mechanism



Interpreting attention weights



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Graph node classification with attention mechanism

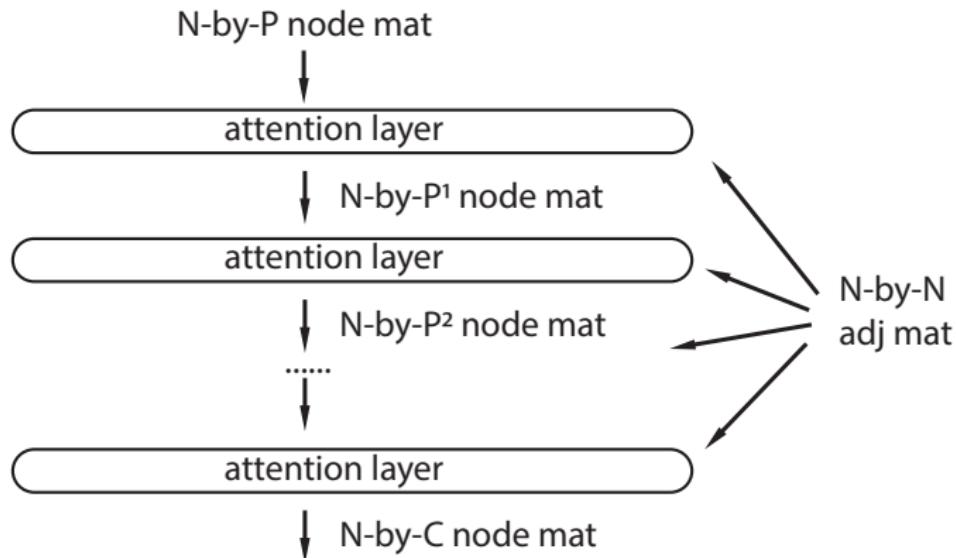
Useful information to classify a node

- ▶ features of the node
- ▶ features of its neighbor nodes
- ▶ label or prediction of its neighbor nodes

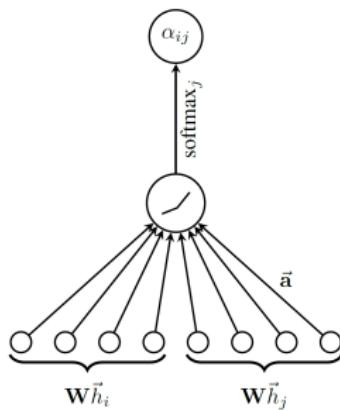
Graph attention network

- ▶ aggregate node features using multiple attention layers
- ▶ simultaneously classify all nodes of a graph
- ▶ neighbor label or prediction are aggregated through back-propagation

Graph attention network

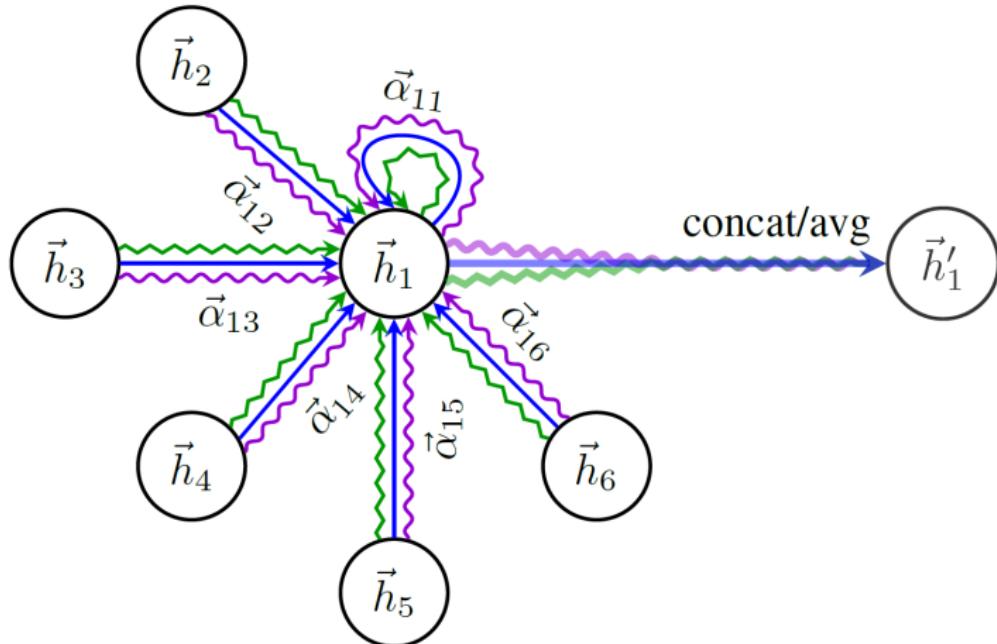


Graph attention mechanism

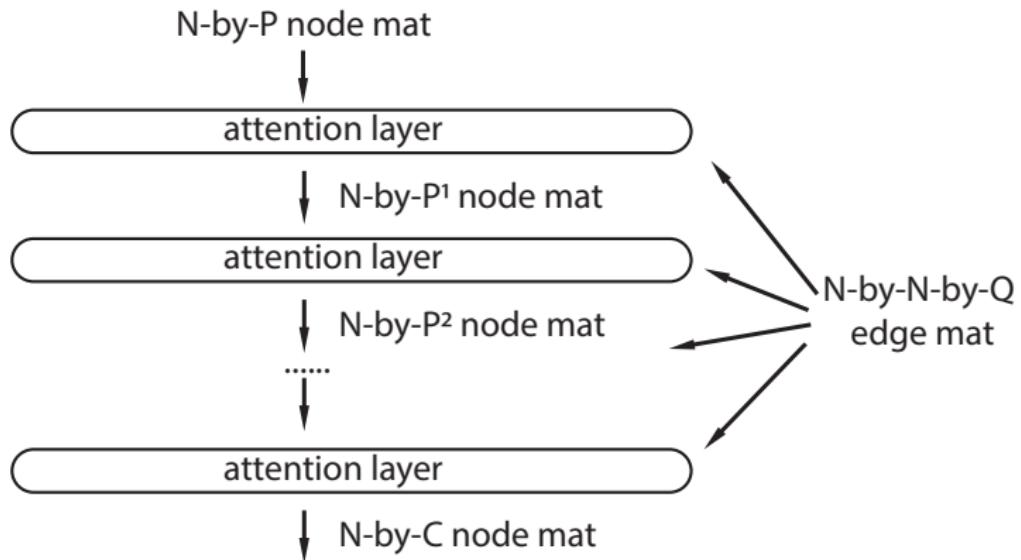


$$\alpha_{ij} = \frac{\exp \left(\text{LeakyReLU} \left(\mathbf{a}^T [\vec{W}\vec{h}_i \parallel \vec{W}\vec{h}_j] \right) \right)}{\sum_{j \in \mathcal{N}_i} \exp \left(\text{LeakyReLU} \left(\mathbf{a}^T [\vec{W}\vec{h}_i \parallel \vec{W}\vec{h}_j] \right) \right)}$$

Multi-head attention



Edge guided graph attention network



Edge latents guided attention

- ▶ For different type of edges, attention functions are different
- ▶ Edge types are represented by edge latent variables

$$\alpha_{ij} = \frac{\exp \left(\text{LeakyReLU} \left(\sum_l \left(\mathbf{a}_l^T [\mathbf{W}\mathbf{h}_i \| \mathbf{W}\mathbf{h}_j] + \mathbf{v}_l \mathbf{g}_{ij} \right) \right) \right)}{\sum_{j \in \mathcal{N}_i} \exp \left(\text{LeakyReLU} \left(\sum_l \left(\mathbf{a}_l^T [\mathbf{W}\mathbf{h}_i \| \mathbf{W}\mathbf{h}_j] + \mathbf{v}_l \mathbf{g}_{ij} \right) \right) \right)}$$

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Cora dataset

# Nodes	2708
# Edges	5429
# Features/Node	1433
# Features/Edge	2
# Classes	7
# Training Nodes	140
# Validation Nodes	500
# Test Nodes	1000

Table: Summary of cora dataset



Experimental Results

Method	Accuracy
MLP	55.1%
ManiReg [1]	59.5%
SemiEmb [2]	59.0%
LP [3]	68.0%
DeepWalk [4]	67.2%
ICA [5]	75.1%
Planetoid [6]	75.7%
Chebyshev [7]	81.2%
GCN [8]	81.5%
MoNet [9]	81.7 ± 0.5%
GAT	83.0 ± 0.7%
EGAT	83.4 ± 0.6%

Table: Summary of results



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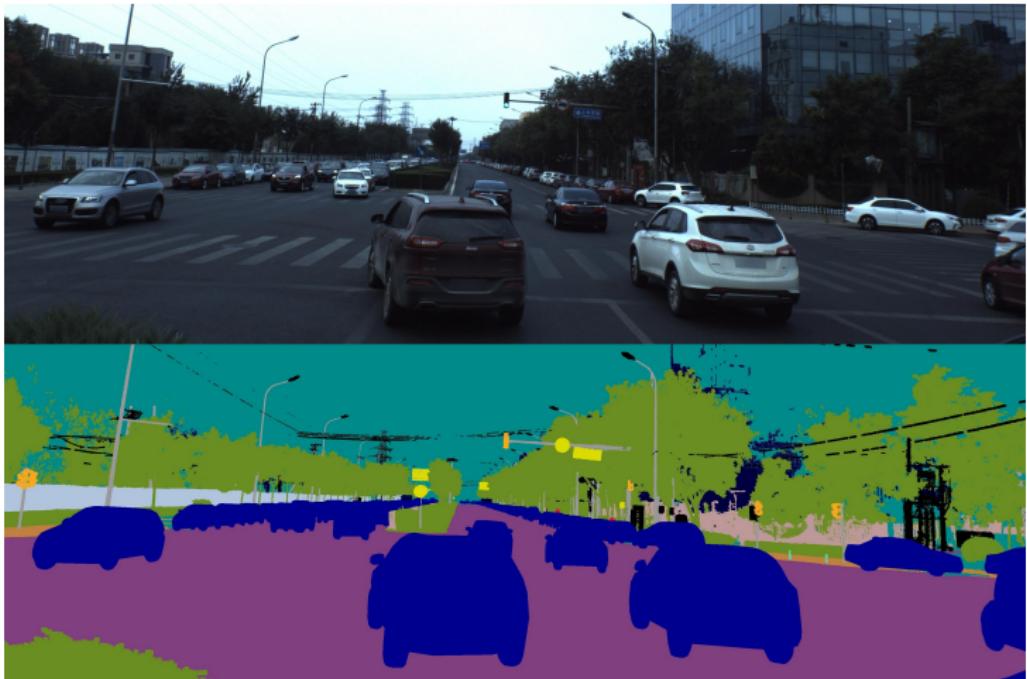
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Future directions

- ▶ Apply to problems with more edge information
- ▶ Address problems with large graphs
- ▶ Combine with GCN
- ▶ Apply to image semantic segmentation (FCN/MS-D + EGAT)

Semantic segmentation



Semantic segmentation as node classification

Current state-of-the-art method

- ▶ Convolution based
- ▶ Fully CNN or MS-D (Mixed scale dense CNN)
- ▶ Convolution weights are shared by all pixel position

Promising EGAT based method

- ▶ Model the problem as a graph node classification
- ▶ Fully CNN or MS-D for feature learning
- ▶ EGAT for feature aggregation and pixel classification

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