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...potencia\Proyecto de placa de potencia\Command_Handler..c
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1
 2 #include "Command Handler.h"
 3 #include "nrf24.h"
 4 #include <stdbool.h>
 5 #include <string.h>
 6 #include <stdlib.h>
 7 #include <stdint.h>
 8 #include <avr/io.h>
9 #include <util/delay.h>
10
11
12 const commandType availableCommand[AVAILABLE_COMMANDS] = {
13
        { .commandBase = "TURN_RELAY_ON", .nParameters = 1, .handlerFunction =
          &TURN RELAY ON HANDLE},
14
        { .commandBase = "TURN_RELAY_OFF", .nParameters = 1, .handlerFunction =
          &TURN_RELAY_OFF_HANDLE},
        { .commandBase = "BUILT_IN_LED_TEST", .nParameters = 0, .handlerFunction =
15
          &BUILT IN LED TEST HANDLER },
        { .commandBase = "TURN_EVERYTHING_ON", .nParameters = 0, .handlerFunction =
16
         &TURN_EVERYTHING_ON_HANDLER},
        { .commandBase = "TURN_EVERYTHING_OFF", .nParameters = 0, .handlerFunction = →
17
          &TURN_EVERYTHING_OFF_HANDLER},
        { .commandBase = "CALL NURSE", .nParameters = 0, .handlerFunction =
18
          &CALL NURSE HANDLE}
19 };
20
21
   bool initliazeMemory(){
22
        if(memoryInitialized) return false;
23
        parameter[0] = (void*)calloc(28,1);
24
       parameter[1] = (void*)calloc(28,1);
25
        parameter[2] = (void*)calloc(28,1);
26
        command_buffer = (uint8_t*)calloc(32,1);
       if(parameter[0]==nullptr||parameter[1]==nullptr||parameter[2]==nullptr||
27
          command_buffer==nullptr) return false;
28
       memoryInitialized = true;
29
       return true;
30 }
31
32
33 void composeCommand(void* output buffer, commandType* commandT, void**
     inputParameter){
        strcpy(output_buffer, commandT->commandBase);
34
35
        char* startParamPTR = (char*)(output_buffer+strlen(commandT->commandBase));
       char* endParamPTR = (char*)(startParamPTR+1+strlen(*inputParameter));
36
37
38
       for (uint8_t index = 0; index < commandT->nParameters; index++){
39
            *startParamPTR='[';
40
            strcpy(startParamPTR+1, *inputParameter);
41
            *endParamPTR=']';
42
            startParamPTR=(endParamPTR+1);
43
            if (index!=(commandT->nParameters-1)){
44
                inputParameter++;
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...potencia\Proyecto de placa de potencia\Command_Handler..c
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45
                uint8_t len = strlen(*inputParameter);
46
                endParamPTR = (char*)(startParamPTR+len+1);
47
            }
48
        }
49
        *startParamPTR='\0';
50 }
51
   bool decomposeCommand(void* input_buffer, commandType* commandT, void**
52
                                                                                        P
      outputParameter){
53
       for (uint8_t index = 0; index < AVAILABLE_COMMANDS; index++){</pre>
54
55
            if (memmem(input_buffer, COMMAND_BUFFER_SIZE, availableCommand
              [index].commandBase, strlen(availableCommand[index].commandBase))!
                                                                                        P
              =nullptr)
56
            {
57
                *commandT = availableCommand[index]; break;
58
59
            else if (index==(AVAILABLE COMMANDS-1)) { return false;}
60
       }
61
62
       for (uint8_t x = 0; x < commandT->nParameters; x++){
            uint8_t* startNumPTR = memchr(input_buffer, '[', COMMAND_BUFFER_SIZE);
63
            uint8_t* endNumPTR = memchr(input_buffer, ']', COMMAND_BUFFER_SIZE);
64
            if (startNumPTR==nullptr||endNumPTR==nullptr) { if(x==0) return false;
65
              break; }
66
            (*startNumPTR) = 0x20;
67
            (*endNumPTR) = 0x20;
68
            startNumPTR++;
69
            uint32 t bytes = ((endNumPTR)) - ((startNumPTR));
70
            if (bytes>PARAMETER_BUFFER_SIZE) return false;
           memcpy(outputParameter[x], startNumPTR, bytes);
71
72
       }
73
74
       return true;
75 }
76
77
   void TURN_RELAY_ON_HANDLE() {
78
       uint8_t relayIndex = atoi(parameter[0]);
79
        switch (relayIndex) {
80
            case 0:
81
            bit_set(PORTD, BIT(3));
82
            break:
83
            case 1:
            bit_set(PORTD, BIT(2));
84
85
            break;
86
            case 2:
            bit_set(PORTD, BIT(6));
87
88
            break;
89
            case 3:
90
            bit_set(PORTD, BIT(5));
91
            break;
92
       }
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3
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93
 94
 95
    void TURN RELAY OFF HANDLE() {
 96
         uint8_t relayIndex = atoi(parameter[0]);
 97
         switch (relayIndex) {
 98
             case 0:
 99
             bit_clear(PORTD, BIT(3));
100
             break;
101
             case 1:
             bit_clear(PORTD, BIT(2));
102
103
             break;
104
             case 2:
105
             bit_clear(PORTD, BIT(6));
106
             break;
107
             case 3:
108
             bit_clear(PORTD, BIT(5));
109
             break;
         }
110
111 }
112
113 void BUILT_IN_LED_TEST_HANDLER(){
         for (uint8_t x = 0; x < 8; x++) {
             bit flip(PORTD, BIT(7));
115
116
             bit_flip(PORTB, BIT(0));
117
             _delay_ms(250);
118
         }
         bit_clear(PORTD, BIT(7));
119
120
         bit_clear(PORTB, BIT(0));
121 }
122
123 void TURN_EVERYTHING_ON_HANDLER(){
         bit_set(PORTD, BIT(3));
124
         bit_set(PORTD, BIT(2));
125
126
         bit set(PORTD, BIT(6));
127
         bit_set(PORTD, BIT(5));
128 }
129
130 void TURN_EVERYTHING_OFF_HANDLER(){
131
         bit_clear(PORTD, BIT(3));
         bit clear(PORTD, BIT(2));
         bit_clear(PORTD, BIT(6));
133
134
         bit_clear(PORTD, BIT(5));
135 }
136
137 void CALL_NURSE_HANDLE(){
138
         bit_set(PORTD, BIT(5));
139
         delay ms(500);
140
         bit_clear(PORTD, BIT(5));
         _delay_ms(500);
141
142
         bit_set(PORTD, BIT(5));
143
         delay ms(500);
         bit_clear(PORTD, BIT(5));
144
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...potencia\Proyecto de placa de potencia\Command_Handler..c

145    __delay_ms(500);
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4
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145    _delay_ms(500);
146    bit_set(PORTD, BIT(5));
147    _delay_ms(500);
148    bit_clear(PORTD, BIT(5));
149 }
150
```