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1
2 #include "Command_Handler.h"
3 #include "nrf24.h"
4 #include "crc.h"
5
6
7
8 const CommandType commandList[] = {
9     { .handlerFunction = &UPDATE_ALL_DEVICES_VALUE_H},
10    { .handlerFunction = &UPDATE_DEVICE_VALUE_H},
11    { .handlerFunction = &GET_ALL_DEVICES_VALUE_H},
12    { .handlerFunction = &GET_DEVICE_VALUE_H},
13    { .handlerFunction = &MESSAGE_STATUS_H}
14 };
15 #define commandListLength (uint8_t)(sizeof commandList/sizeof commandList[0])
16
17 bool initliazeMemory(){
18     if(memoryInitialized) return false;
19     parameter[0].startingPointer = (void*)calloc(23,1);
20     parameter[1].startingPointer = (void*)calloc(2,1);
21     parameter[2].startingPointer = (void*)calloc(2,1);
22     for (uint8_t x = 3; x<12; x++) parameter[x].startingPointer = (void*)calloc  ➤
        (1,1);
23     command_buffer = (uint8_t*)calloc(32,1);
24     if(command_buffer==NULL) return false;
25     for (uint8_t x = 0; x<12; x++) { if(parameter[x].startingPointer==NULL)  ➤
        return false; }
26     memoryInitialized = true;
27     return true;
28 }
29
30 CommandStatus DecomposeMessageFromBuffer(){
31     // Search for header
32     uint8_t* headerStart = command_buffer;
33     uint8_t* footerEnd = command_buffer+31;
34
35     for(;headerStart!=(command_buffer+22);headerStart++){
36         if (*headerStart==SOH&&*(headerStart+4)==STX){
37             for(;footerEnd!=(command_buffer+6);footerEnd--){
38                 if (*footerEnd==ETB&&*(footerEnd-2)==ETX){
39                     uint8_t netMessageLength = ((footerEnd-2)-headerStart);
40                     crc_t crc;
41                     crc = crc_init();
42                     crc = crc_update(crc, headerStart, netMessageLength);
43                     crc = crc_finalize(crc);
44                     if (*(footerEnd-1)!=crc) return WRONG_CHECKSUM_CONSISTENCY;
45                     if (*(headerStart+2)!=currentModuleID&&*(headerStart+2)!  ➤
                        =0xFF&&currentModuleID!=0x01) return WRONG_MODULE_ID;
46                     lastTargetModuleID = *(headerStart+2);
47                     lastTransmitterModuleID = *(headerStart+3);
48                     if (*(headerStart+5)>commandListLength-1) return  ➤
                        UNDEFINED_COMMAND_CODE;

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49         lastMessageCommandType = commandList[*(headerStart+5)];
50         lastMessagePID = *(headerStart+1);
51
52         uint8_t* parameterStart = headerStart+6;
53
54         for (uint8_t x = 0; x < 12; x++) {
55             realloc(parameter[x].startingPointer, *parameterStart);
56             parameter[x].byteLength = *parameterStart;
57             memcpy(parameter[x].startingPointer, parameterStart+1,  ↗
58                 *parameterStart);
59             parameterStart+=((*parameterStart)+1);
60             if (parameterStart>=(footerEnd-2)) break;
61         }
62         return SUCCESFUL_DECOMPOSITION;
63     }
64 }
65 }
66 }
67 return WRONG_HEADER_SEGMENTATION;
68 }
69
70 CommandStatus ComposeMessageToBuffer(CommandTypeID targetTypeID, uint8_t  ↗
71     parameterCount, uint8_t targetBoardID){
72     memset(command_buffer, 0, 32);
73     command_buffer[0] = SOH;
74     if (lastMessagePID==0xFF) { lastMessagePID++; } else { lastMessagePID = 0; }
75     command_buffer[1] = lastMessagePID;
76     command_buffer[2] = targetBoardID;
77     command_buffer[3] = currentModuleID;
78     command_buffer[4] = STX;
79     command_buffer[5] = targetTypeID;
80
81     if (parameterCount>12) return PARAMETER_COUNT_OVERSIZE;
82
83     uint8_t* parameterStart = &command_buffer[6];
84
85     for (uint8_t x = 0; x < parameterCount; x++){
86         *parameterStart = parameter[x].byteLength;
87         memcpy(parameterStart+1, parameter[x].startingPointer, parameter  ↗
88             [x].byteLength);
89         parameterStart+=(parameter[x].byteLength)+1;
90     }
91
92     crc_t crc;
93     crc = crc_init();
94     uint8_t crc_length = ((parameterStart)-(&command_buffer[0]));
95     crc = crc_update(crc, &command_buffer[0], crc_length);
96     crc = crc_finalize(crc);
97
98     *parameterStart = ETX;
99     *(parameterStart+1) = crc;
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98     *(parameterStart+2) = ETB;
99
100     return SUCCESFUL_COMPOSITION;
101 }
102
103 void HandleAvailableCommand(){
104     lastMessageCommandType.handlerFunction();
105 }
106
107 RF_TransmissionStatus RetransmissionToModule(){
108     nrf24_initRF_SAFE(lastTargetModuleID, TRANSMIT);    // CONNECTION TO MODULE: ↗
109     GENERAL RF CHANNEL 112
110     nrf24_send(command_buffer);
111     while(nrf24_isSending());
112
113     uint8_t messageStatus = nrf24_lastMessageStatus();
114     if(messageStatus == NRF24_TRANSMISSION_OK) { return RF_SUCCESFUL_TRANSMISSION; }
115     else if(messageStatus == NRF24_MESSAGE_LOST) { return RF_UNREACHEABLE_MODULE; }
116     return RF_UNREACHEABLE_MODULE;
117 }
118
119 void writeParameterValue(uint8_t parameterIndex, void* parameterData, uint8_t
parameterByteLength){
120     parameter[parameterIndex].startingPointer = (uint8_t*) realloc(parameter
[parameterIndex].startingPointer, parameterByteLength);
121     memcpy(parameter[parameterIndex].startingPointer, parameterData,
parameterByteLength);
122     parameter[parameterIndex].byteLength = parameterByteLength;
123 }
124
125 void UPDATE_ALL_DEVICES_VALUE_H() {
126     for (uint8_t x = 0; x < AVAILABLE_DEVICES;x++)
127     {
128         deviceStoredValue[x] = *((uint8_t*)parameter[x].startingPointer);
129         switch (x) {
130             case 0x00:
131                 bit_write(deviceStoredValue[x], PORTD, BIT(3));
132                 break;
133             case 0x01:
134                 bit_write(deviceStoredValue[x], PORTD, BIT(2));
135                 break;
136             case 0x02:
137                 bit_write(deviceStoredValue[x], PORTD, BIT(6));
138                 break;
139             case 0x03:
140                 bit_write(deviceStoredValue[x], PORTD, BIT(5));
141                 break;
142         }
143     }
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144
145
146 }
147
148 void UPDATE_DEVICE_VALUE_H() {
149     uint8_t deviceIndex = *((uint8_t*)parameter[0].startingPointer);
150     uint8_t deviceValue = *((uint8_t*)parameter[1].startingPointer);
151
152     switch (deviceIndex) {
153         case 0:
154             bit_write(deviceValue, PORTD, BIT(3));
155             break;
156         case 1:
157             bit_write(deviceValue, PORTD, BIT(2));
158             break;
159         case 2:
160             bit_write(deviceValue, PORTD, BIT(6));
161             break;
162         case 3:
163             bit_write(deviceValue, PORTD, BIT(5));
164             break;
165     }
166
167     deviceStoredValue[deviceIndex] = deviceValue;
168
169 }
170 void GET_ALL_DEVICES_VALUE_H() {
171     _delay_ms(50);
172
173     for (uint8_t x = 0; x < AVAILABLE_DEVICES; x++)
174     {
175         writeParameterValue(x, &deviceStoredValue[x], 2);
176     }
177
178     ComposeMessageToBuffer(UPDATE_ALL_DEVICES_VALUE_ID, AVAILABLE_DEVICES,
179                             PHONE_MODULE); // PHONE_MODULE deberia ser lastTransmitterModuleID
180
181     nrf24_initRF_SAFE(MAIN_BOARD, TRANSMIT);
182     nrf24_send(command_buffer);
183     while(nrf24_isSending());
184     uint8_t messageStatus = nrf24_lastMessageStatus();
185 }
186 void GET_DEVICE_VALUE_H() {
187     _delay_ms(50);
188     uint8_t deviceIndex = *((uint8_t*)parameter[0].startingPointer);
189     writeParameterValue(0, &deviceIndex, 1);
190     writeParameterValue(1, &deviceStoredValue[deviceIndex], 2);
191     ComposeMessageToBuffer(UPDATE_DEVICE_VALUE_ID, 2, PHONE_MODULE); //
192     PHONE_MODULE deberia ser lastTransmitterModuleID
193
194     nrf24_initRF_SAFE(MAIN_BOARD, TRANSMIT);
195     nrf24_send(command_buffer);
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```
194     while(nrf24_isSending());
195     uint8_t messageStatus = nrf24_lastMessageStatus();
196 }
197
198
199 void MESSAGE_STATUS_H() {}
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