```
1
2
 3 #ifndef COMMAND_HANDLER_H_
4 #define COMMAND_HANDLER_H_
 6 #ifndef nullptr
7 #define nullptr ((void *)0)
8 #endif
10 #ifndef F_CPU
11 #define F_CPU 16000000UL
12 #endif
13
14 #include <stdbool.h>
15 #include <stdint.h>
16 #include <stdio.h>
17 #include <string.h>
18 #include <stdlib.h>
19 #include <avr/io.h>
20 #include <util/delay.h>
21 #include "nrf24.h"
22
23 #ifndef BIT_MANIPULATION_MACRO
24 #define BIT_MANIPULATION_MACRO 1
25 #define bit_get(p,m) ((p) & (m))
26 #define bit_set(p,m) ((p) |= (m))
27 #define bit_clear(p,m) ((p) &= \sim(m))
28 #define bit_flip(p,m) ((p) ^= (m))
29 #define bit_write(c,p,m) (c ? bit_set(p,m) : bit_clear(p,m))
30 #define BIT(x) (0x01 << (x))</pre>
31 #define LONGBIT(x) ((unsigned long)0x00000001 << (x))</pre>
32 #endif
33
34 #define currentModuleID 0x03
35 #define SOH 0x01
36 #define STX 0x02
37 #define ETX 0x03
38 #define ETB 0x17
39 #define ON_STATE
                        0xFF
40 #define OFF_STATE
41
42 typedef struct CommandType {
43
       void (*handlerFunction)();
44 } CommandType;
45
46 typedef enum {
       SUCCESFUL DECOMPOSITION,
47
48
       WRONG_HEADER_SEGMENTATION,
49
       WRONG_FOOTER_SEGMENTATION,
50
       WRONG_CHECKSUM_CONSISTENCY,
51
       WRONG MODULE ID,
52
       UNDEFINED_COMMAND_CODE,
```

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2
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```
53
        PARAMETER DATA OVERFLOW,
54
        PARAMETER COUNT OVERSIZE,
55
        RETRANSMISSION FAILED,
56
        SUCCESFUL_RETRANSMISSION,
57
        SUCCESFUL COMPOSITION
58 } CommandStatus;
59
60
61 typedef enum {
62
        RF_SUCCESFUL_TRANSMISSION,
63
        RF_UNREACHEABLE_MODULE,
        RF ACKNOWLEDGE FAILED
64
67 typedef enum
68
                    UPDATE_ALL_DEVICES_VALUE_ID,
69
                    UPDATE_DEVICE_VALUE_ID,
70
                    GET ALL DEVICES VALUE ID,
71
                    GET DEVICE VALUE ID,
72
                    MESSAGE_STATUS_ID
73 } CommandTypeID;
74
75 typedef struct {
76
        void *startingPointer;
77
        uint8 t byteLength;
78 } Parameter;
79
80 Parameter parameter[12];
81 uint8 t *command buffer;
82 bool memoryInitialized;
83 uint8 t lastMessagePID;
84 CommandType lastMessageCommandType;
85 uint8_t lastTargetModuleID;
86 uint8 t lastTransmitterModuleID;
87
88
89 #define AVAILABLE_DEVICES 3
   uint8_t deviceStoredValue[AVAILABLE_DEVICES];
                                                        //Uint8, las posiciones no se ₹
       guardan en grados
91
92
93
94 void STRETCHER_POS_CHANGE_HANDLE(uint8_t positionToMove);
95 void CURTAIN_POS_CHANGE_HANDLE(uint8_t positionToMove);
   extern void UPDATE_ALL_DEVICES_VALUE_H(), UPDATE_DEVICE_VALUE_H(),
                                                                                      P
      GET ALL DEVICES_VALUE_H(), GET_DEVICE_VALUE_H(), MESSAGE_STATUS_H();
98 extern CommandStatus ComposeMessageToBuffer(CommandTypeID targetTypeID, uint8_t
      parameterCount, uint8_t targetBoardID);
99 extern CommandStatus DecomposeMessageFromBuffer();
100 extern void writeParameterValue(uint8 t parameterIndex, void* parameterData,
      uint8_t parameterByteLength);
```

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```

```
3
101 extern void HandleAvailableCommand();
102 extern bool initliazeMemory();
103
104 #endif /* COMMAND_HANDLER_H_ */
```