

```
1 #ifndef NRF24
2 #define NRF24
3
4 #ifndef F_CPU
5 #define F_CPU 16000000UL
6 #endif
7
8 #include "nRF24L01_Definitions.h"
9 #include "Command_Handler.h"
10 #include <stdint.h>
11 #include <stdbool.h>
12 #include <avr/io.h>
13 #include <avr/delay.h>
14
15
16
17 #ifndef BIT_MANIPULATION_MACRO
18 #define BIT_MANIPULATION_MACRO 1
19 #define bit_get(p,m) ((p) & (m))
20 #define bit_set(p,m) ((p) |= (m))
21 #define bit_clear(p,m) ((p) &= ~(m))
22 #define bit_flip(p,m) ((p) ^= (m))
23 #define bit_write(c,p,m) (c ? bit_set(p,m) : bit_clear(p,m))
24 #define BIT(x) (0x01 << (x))
25 #define LONGBIT(x) ((unsigned long)0x00000001 << (x))
26 #endif
27
28 #define LOW 0
29 #define HIGH 1
30 #define nrf24_ADDR_LEN 5
31 #define nrf24_CONFIG ((1<<EN_CRC)|(0<<CRCO))
32 #define NRF24_TRANSMISSION_OK 0
33 #define NRF24_MESSAGE_LOST 1
34
35 #define CLEAR_FAULTY_RF_LED bit_clear(PORTD, BIT(7))
36 #define FLIP_FAULTY_RF_LED bit_flip(PORTD, BIT(7))
37
38
39 enum TransmissionMode {
40     RECEIVE,
41     TRANSMIT
42 };
43 typedef enum TransmissionMode TransmissionMode;
44
45 enum CommandsBoard {
46     MAIN_BOARD = 0,
47     POWER_BOARD = 1,
48     MOTORIZED_BOARD = 2
49 };
50 typedef enum CommandsBoard CommandsBoard;
51
52 extern void nrf24_initRF_SAFE(uint8_t boardIndex,TransmissionMode initMode);
```

```
53
54 void    nrf24_init();
55 void    nrf24_rx_address(uint8_t* adr);
56 void    nrf24_tx_address(uint8_t* adr);
57 void    nrf24_config(uint8_t channel, uint8_t pay_length);
58 bool    nrf24_checkRegister(uint8_t reg, uint8_t desiredValue, uint8_t len);
59 bool    nrf24_checkConfig();
60 bool    nrf24_checkAvailability();
61
62 void    faultyRF_Alarm();
63
64
65
66 uint8_t nrf24_dataReady();
67 uint8_t nrf24_isSending();
68 uint8_t nrf24_getStatus();
69 uint8_t nrf24_rxFifoEmpty();
70
71 void    nrf24_send(uint8_t* value);
72 void    nrf24_getData(uint8_t* data);
73
74 uint8_t nrf24_payloadLength();
75
76 uint8_t nrf24_lastMessageStatus();
77 uint8_t nrf24_retransmissionCount();
78
79 uint8_t nrf24_payload_length();
80
81 void    nrf24_powerUpRx();
82 void    nrf24_powerUpTx();
83 void    nrf24_powerDown();
84
85 uint8_t spi_transfer(uint8_t tx);
86 void    nrf24_transmitSync(uint8_t* dataout, uint8_t len);
87 void    nrf24_transferSync(uint8_t* dataout, uint8_t* datain, uint8_t len);
88 void    nrf24_configRegister(uint8_t reg, uint8_t value);
89 void    nrf24_readRegister(uint8_t reg, uint8_t* value, uint8_t len);
90 void    nrf24_writeRegister(uint8_t reg, uint8_t* value, uint8_t len);
91
92 extern void nrf24_setupPins();
93
94 extern void nrf24_ce_digitalWrite(uint8_t state);
95
96 extern void nrf24_csn_digitalWrite(uint8_t state);
97
98 extern void nrf24_sck_digitalWrite(uint8_t state);
99
100 extern void nrf24_mosi_digitalWrite(uint8_t state);
101
102 extern uint8_t nrf24_miso_digitalRead();
103
104 #endif
```