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Denoising Diffusion model variations

- DDPM → markov forward process
- DDIM → non-markov forward process

DDPM based diffusion model (dataset = CIFAR10)

- $T = 300$, epoch = 100
- 2min/1epoch → total = 2.5h (geforce RTX 4070) 오래 걸리는 건지 원래 이 정도 걸리는지 모르겠음
- loss : 0.58~0.6 (l1 loss) (한 50epoch 까지만 진행)
- 예시 코드에서는 loss 0.17~0.18수준 (dataset = Stanfordcars) / source가 삭제되어서 CIFAR10로 대체

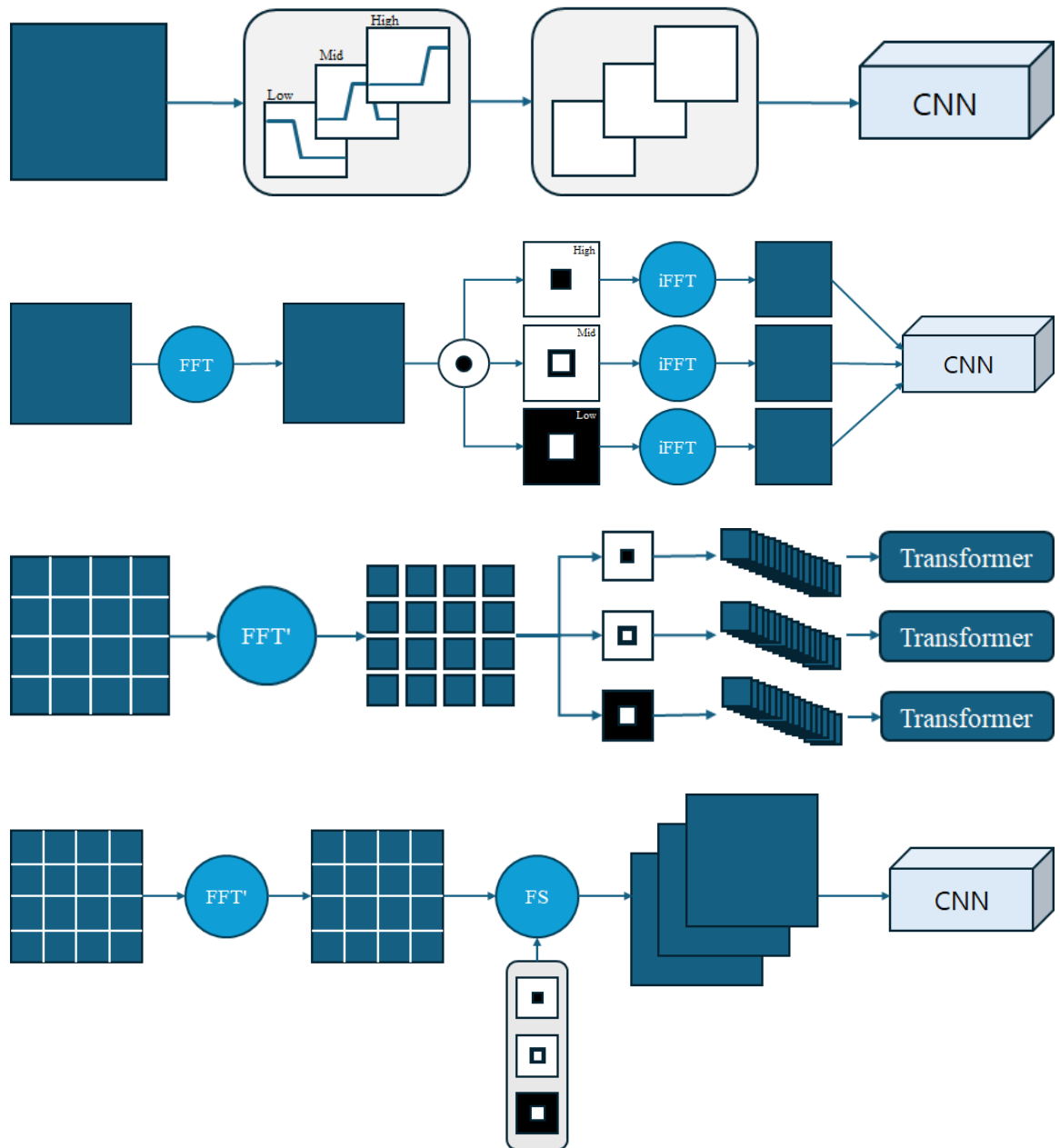
loss 계산할 때 noise/noised image vs model output

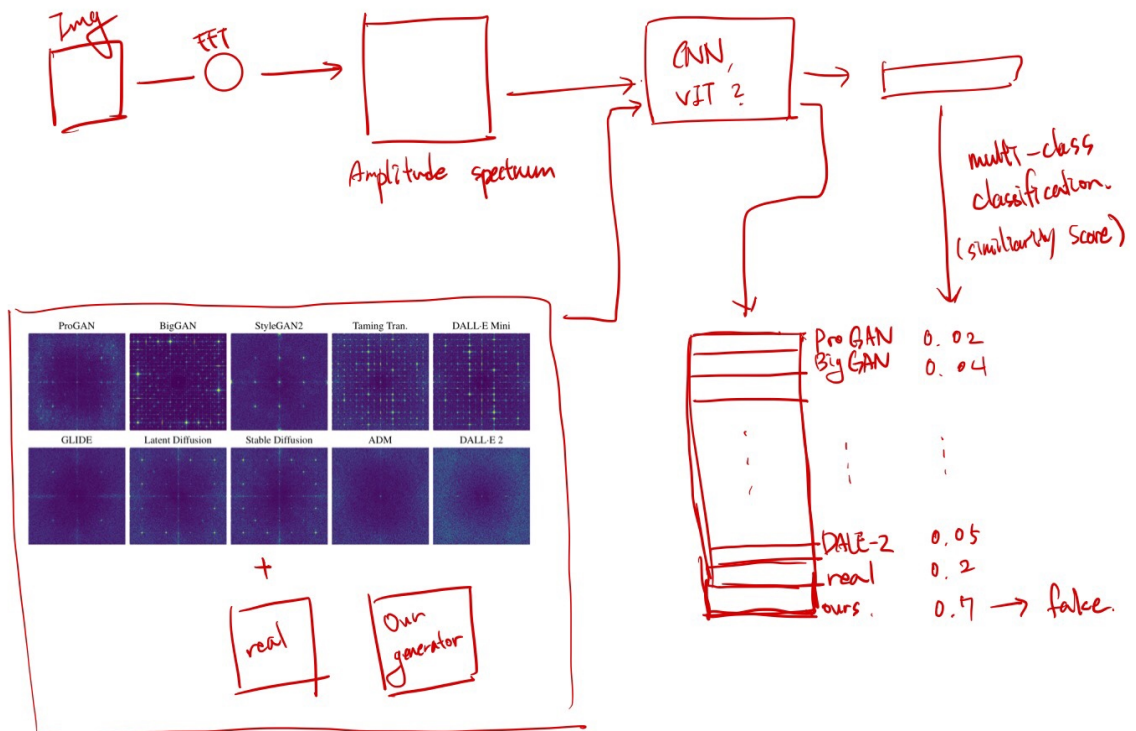
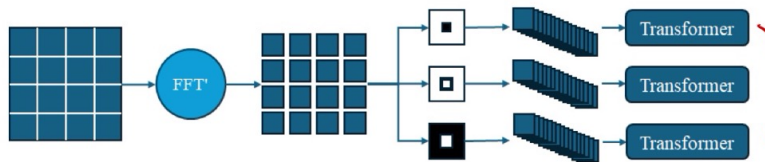
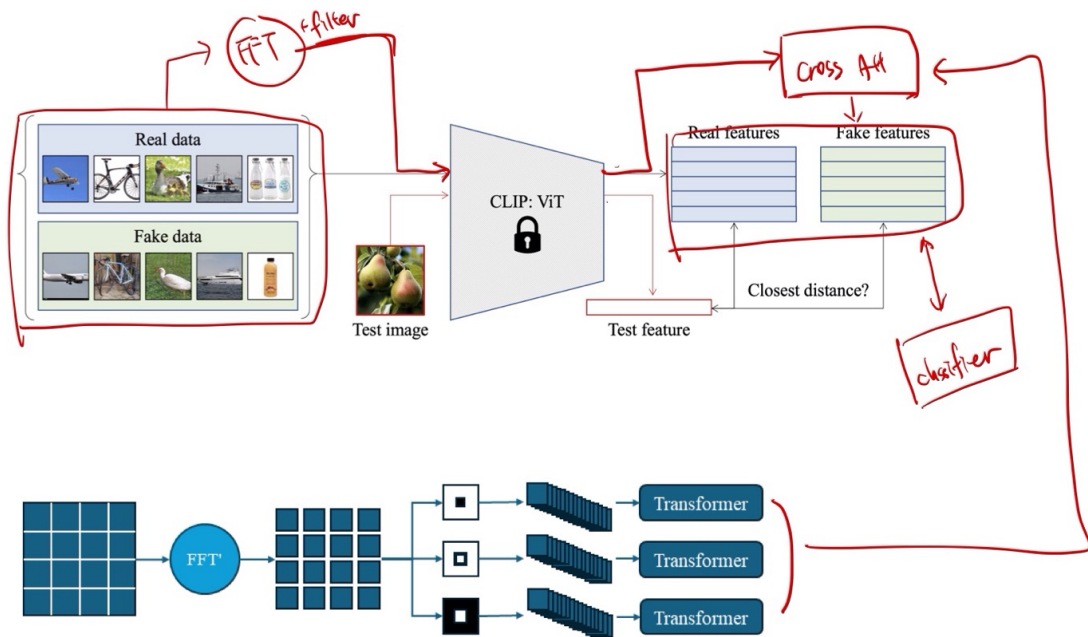
- noise랑 noised image 둘 중 뭐랑 비교하는 게 맞는지? → model output이 noised image를 prediction하는거니까 noised image랑 비교하는 게 맞는 것 같긴 한데..
- L1 loss는 noised image랑 비교할 때 더 낮음
- noise, noised image는 dim3(RGB), model output은 dim1 → 그대로 비교 or model output을 dim3으로 convolution하고 비교

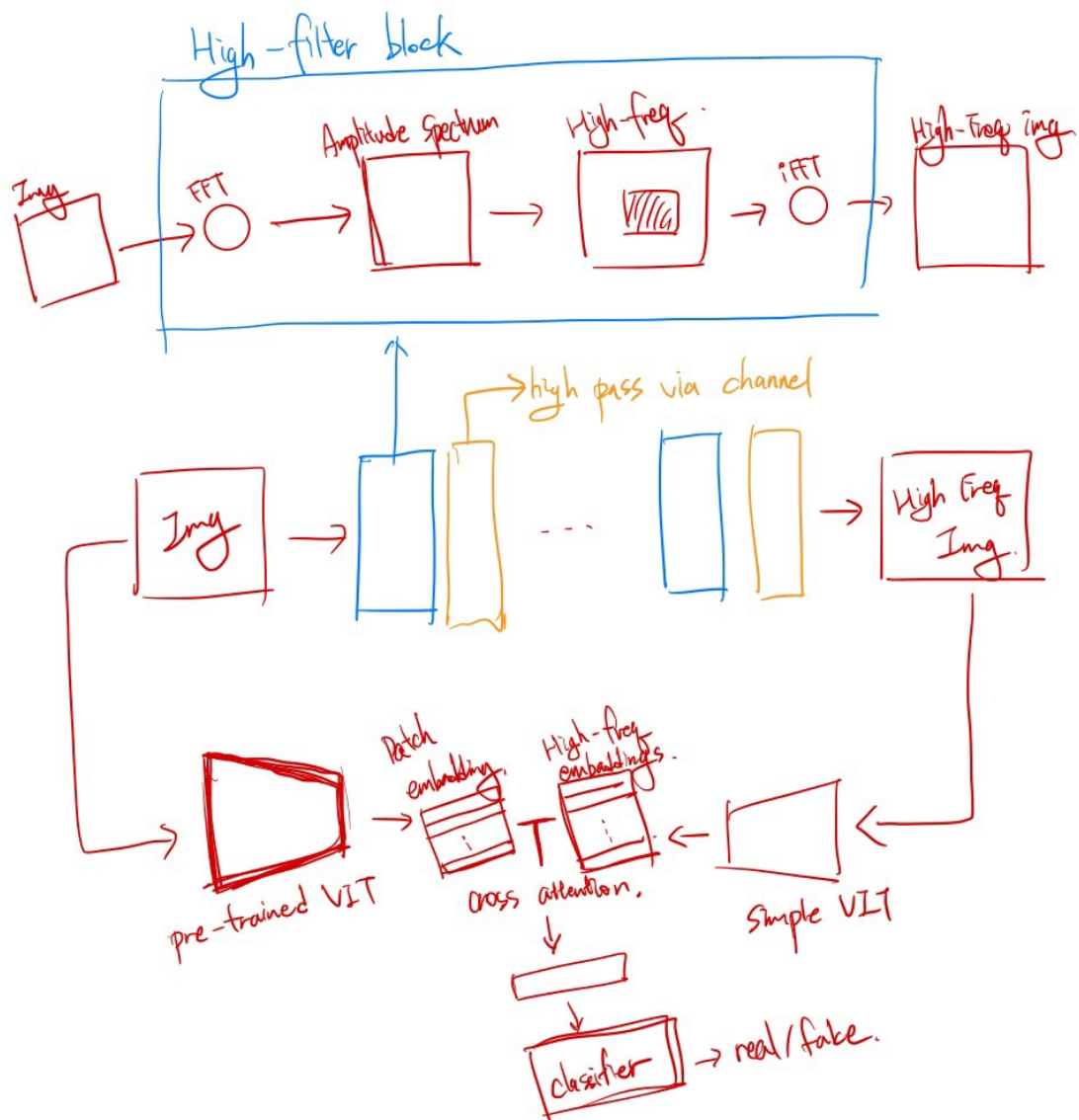
Generation은 follow-up / Detection을 main task로

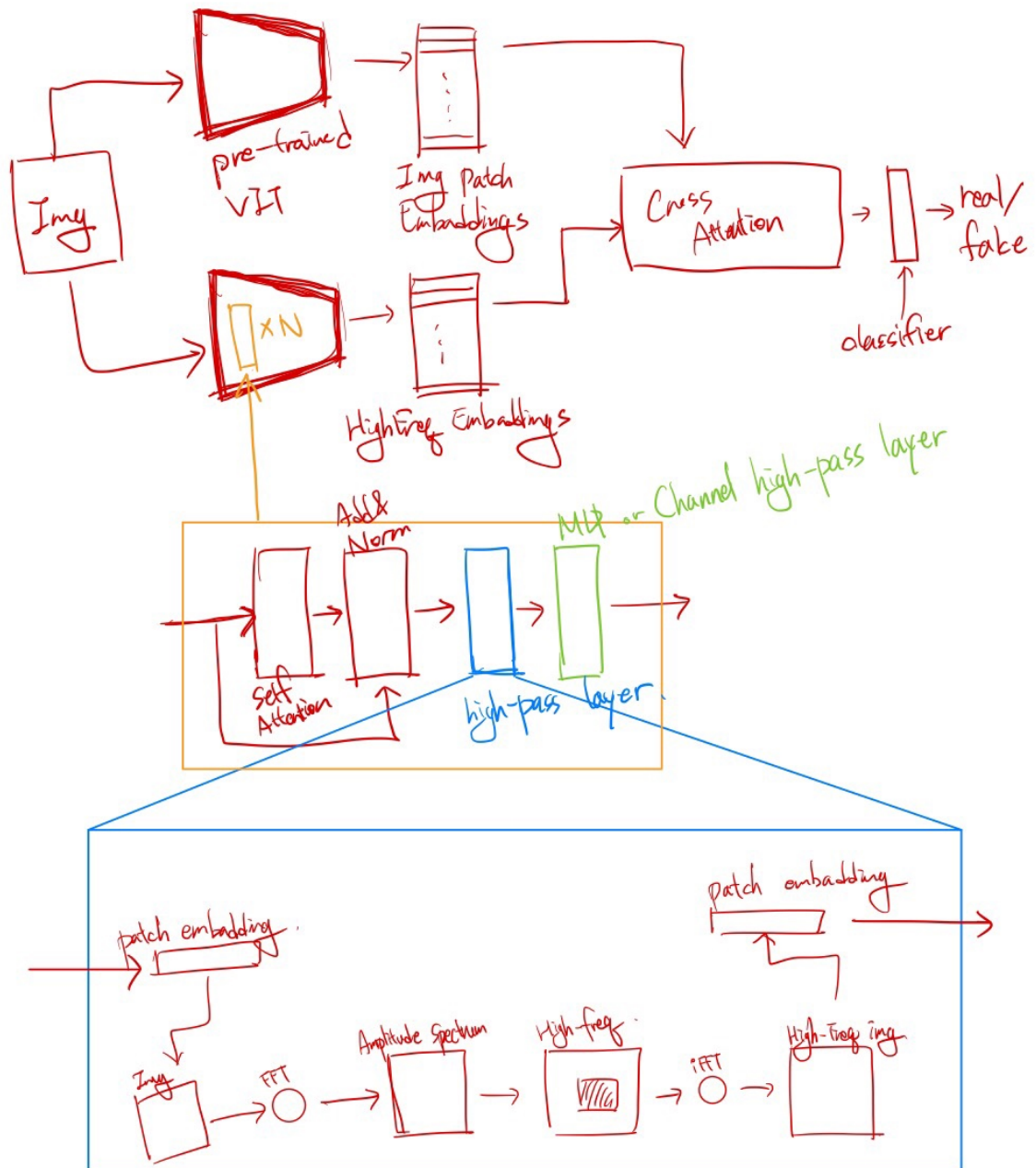
frequency-domain deepfake detections

- FreqNet
- F3Net









Frequency-based detection

- Frequency-level과 image-level analysis를 dual stream으로
- vit-base
- attention layer 처럼 frequency layer 만들어서 반복적인 학습이 가능하도록 하기