

Doodleverse Lab  
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Warmup:

**For a simple image, say a triangle with a black 1 pixel wide edge on a white background, suggest a reasonable edge detector to find the contour of the image. Why might a simple edge detector be "good enough" for this application?**

- We can use the sobel operator to detect the change in x and y coordinates of the triangle. A simple edge detector is good enough because there is no other edges in the image that could interfere with the triangle

**Given an arbitrary two-dimensional shape, determine some candidate feature points that will always exist.**

- Where the edge changes directions, i.e when the magnitude of the change in x or y changes

**With the star dataset being used in this application taken into consideration, why is it so important to represent the shape in as few feature points as possible?**

- In regards to the stars, the stars are not always forming the proper shape nor is there enough stars to be able to find a certain shape. It also makes the shapes easier to find.

**Use this script to convert the 79 stars found in `stars.mat` to (x,y) coordinates centered at (c; c) = (293 ; -2.8). (we have converted hours to degrees for you, but be sure to convert degrees to radians for the function defined above)**

```
function [x,y] = project(ra, dec, c_ra, c_dec)

    theta_0 = dec - c_dec;
    epsilon = 10^(-6);
    error = 1+epsilon;
    while error > epsilon
        m = (2*theta_0+sin(2*theta_0)-pi*sin(dec - c_dec))/(2+2*cos(2*theta_0));
        theta_1 = theta_0 - m;
        error = abs(theta_1 - theta_0);
        theta_0 = theta_1;
    end

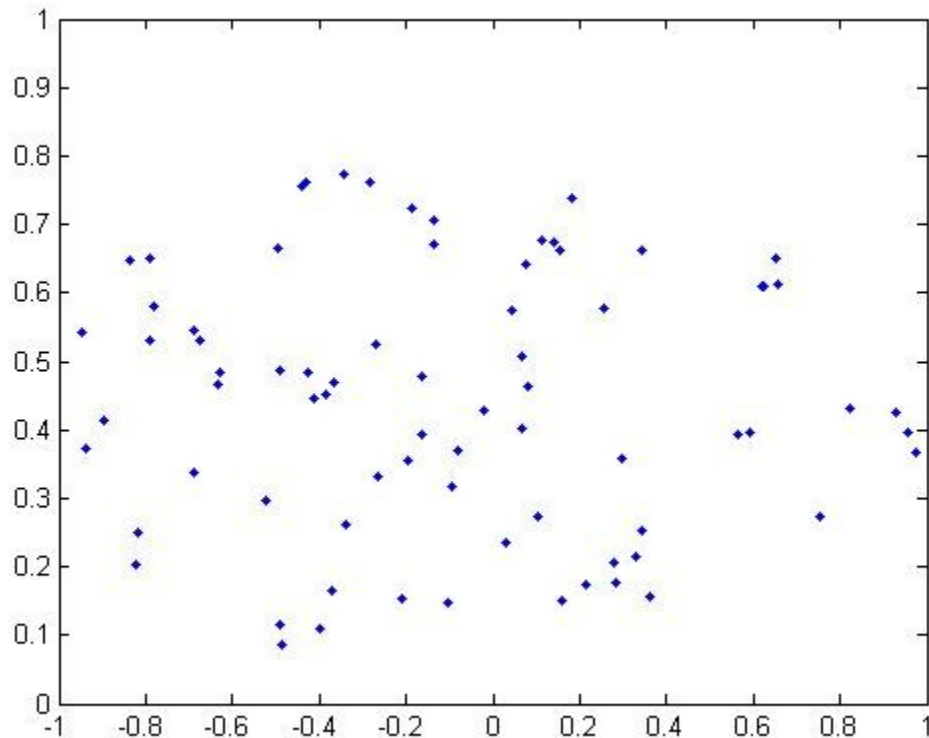
    x = 2*sqrt(2)*(ra-c_ra)*cos(theta_0)/pi;
    y = sqrt(2)*sin(theta_0);
end

mat = zeros(2,79);
for n = 1:79
    a=RA(n);
    b=Dec(n)*0.0174533;
    [x,y]= project(a,b,293,-2.8);
    mat(1,n) = x/15;
    mat(2,n) = y;
end

plot(79); hold on;
axis([-1 1 0 1])
for i=1:79
    a = mat(1,i);
    b = mat(2,i);
```

```
plot(a,b,'b.');
```

```
end
```



**Form this as a clustering problem  $X = DW$ . What do  $X, D, W$  look like? Our search set contains 79 stars. If  $D$  is  $n \times k$ , what is  $n$ ? What would be the effect of choosing smaller or larger values of  $k$ ?**

- $X$  will be an  $n \times 1$  matrix containing the result of the data,  $D$  will be an  $n \times k$  matrix containing the star data, and  $W$  will be a  $k \times 1$  matrix containing the weights to be put on each of the features.  $n$  is the number of stars, so in this case it is 79. A larger  $k$  would allow more features, and therefore would allow for a larger set of weights to be applied.

**This brute-force method only finds  $k$  possible tests, where we choose  $k$  ahead of time. Why might the clustering approach be more preferable?**

- it will allow us to find more tests that would work that may not be found when a limit is imposed on the testing process

**Let  $UV^T$  be the SVD of the matrix  $SF^T$ . Show that the orthogonal  $T$  that minimizes  $\|TF - S\|_F^2$  is equal to  $UV^T$ .**

**Use the Procrustes algorithm to find the transformation that best maps the  $A$  to  $B$  matrix found in the `procrustes.mat` file.**

```
0.5000  0.8660
-0.8660  0.5000
```

**Suppose we had  $k$  such possible matches  $\{S_i, M_i\}$ , and we want to determine the best one. Set up a cost/penalizer function that we are trying to minimize.**

Lab:

```
1.
im = imread('diamond.png');
image(im);
B = (0.2989 * double(im(:,:,1)) + 0.5870 * double(im(:,:,2)) + 0.1140 *
double(im(:,:,3)))/255;
C=double(B);
for i=1:size(C,1)-2
    for j=1:size(C,2)-2
        Gx=((2*C(i+2,j+1)+C(i+2,j)+C(i+2,j+2))-(2*C(i,j+1)+C(i,j)+C(i,j+2)));
        Gy=((2*C(i+1,j+2)+C(i,j+2)+C(i+2,j+2))-(2*C(i+1,j)+C(i,j)+C(i+2,j)));
        B(i,j)=sqrt(Gx.^2+Gy.^2);

    end
end
```

```
2. (289,115) , (290,115)
    (180,202)
    (289,289) , (289,290)
    (399,202)
    the points give a very close match
```

```
3. (289,115), (180,202), (289,289)-> 77.1913 degrees
```

(RA, Dec, Mag)

```
-0.3431, 0.7738, 3.760,
-0.4849, 0.0873, 4.0200,
0.7533, 0.2747, 5.3000    → 77.1941 degrees
```

```
0.0308, 0.2356, 4.4500
0.0684, 0.508, 4.9300
-0.6276, 0.4838, 5.38    → 77.1953 degrees
```

```
0.3299, 0.2148, 4.71
-0.6350, 0.4660, 4.22
0.3439, 0.6632, 5.01    → 77.1958 degrees
```

```
4.
5.
```

Feedback:

- I ran out of time, so I wasn't able to finish 4&5.
- Interesting lab concept
- I had no python experience, so I had to figure out what some of the operations were to convert to matlab. Not really a problem with the lab, just explaining my process during the lab
- warm up was a good step by step process that also takes you through the lab
- not 100% sure what numbers in brackets meant(Contour of shape determined by [1]). A reference to earlier problem, or equation? Could number them to clear that up.
- Maybe put some more comments in the code to tell reader what is being calculated at some steps
- could possibly explain how hours was converted to degrees for the mollyweid. Also how to convert degrees to radians