Object dragging in scenegraph-based systems

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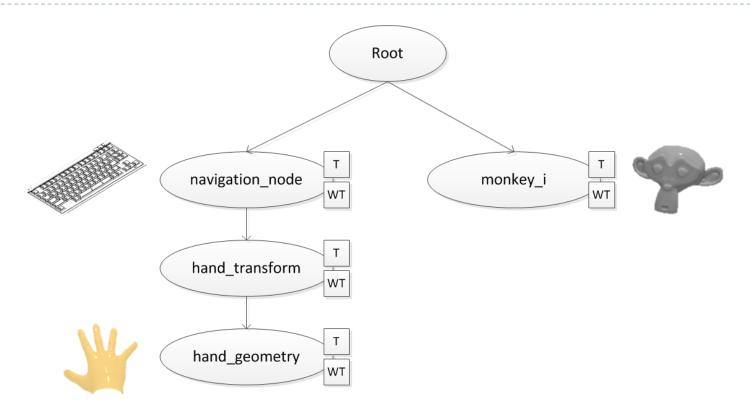




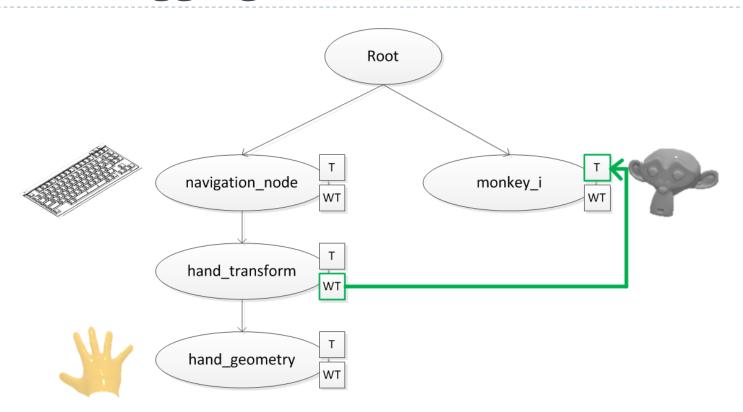


Scenegraph structure

Scenegraph structure



Naïve dragging



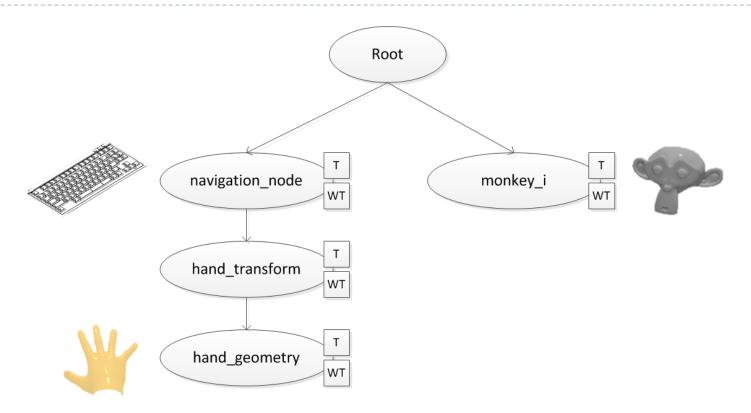


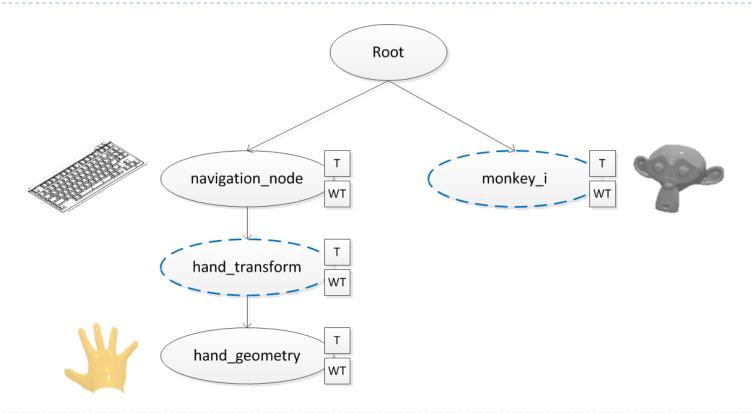
Preserving the contact point

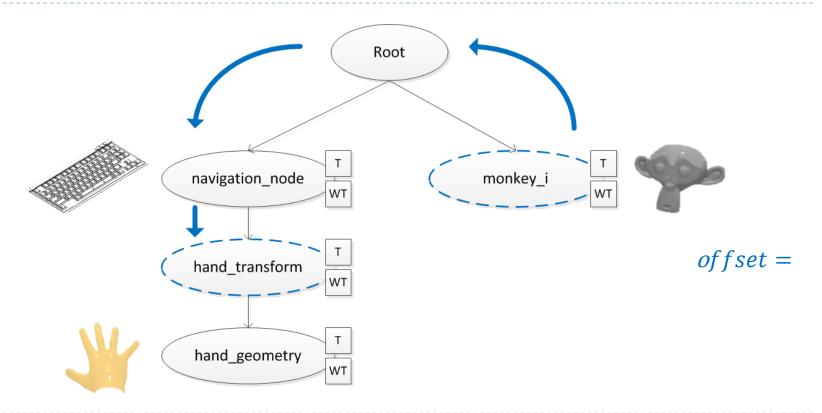


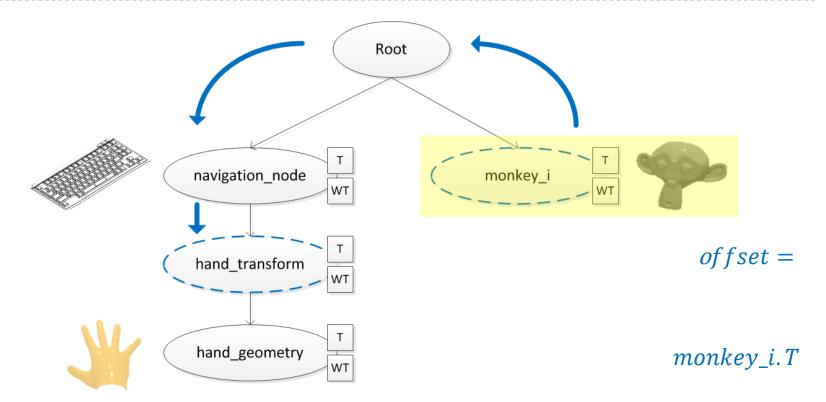
We want to keep the offset between the hand and the monkey during dragging!

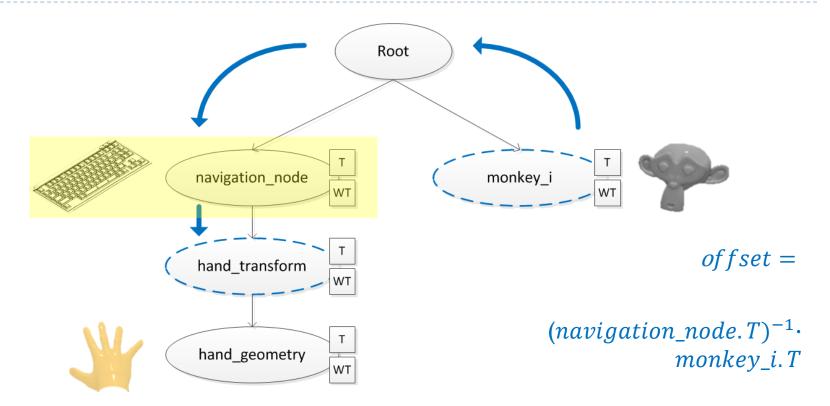
How do we compute it?

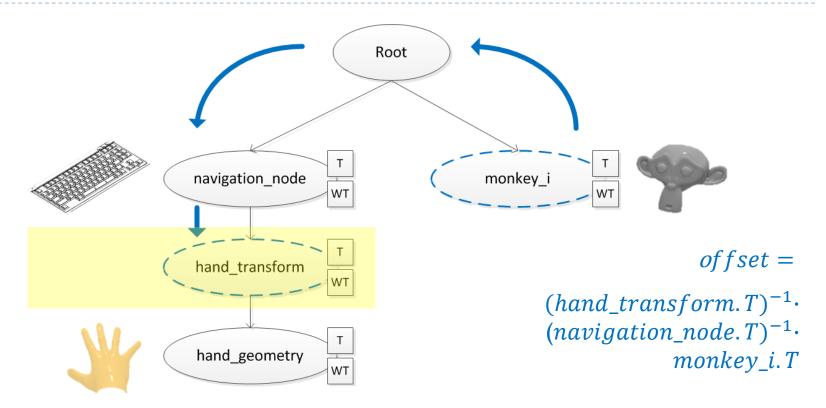


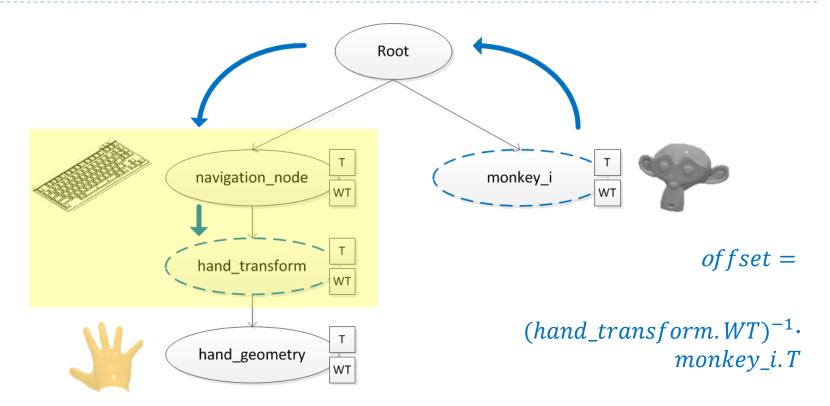


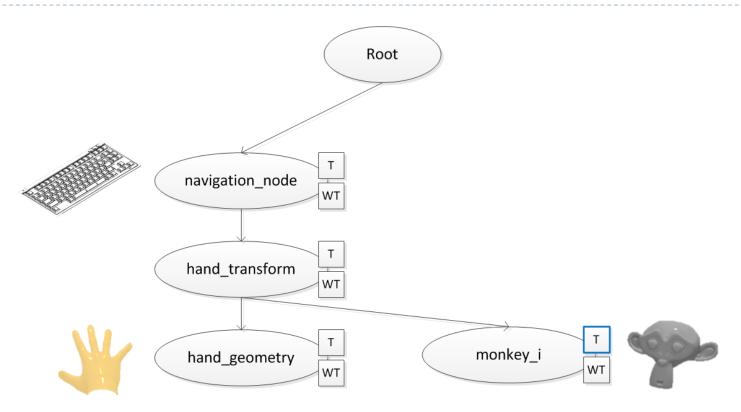


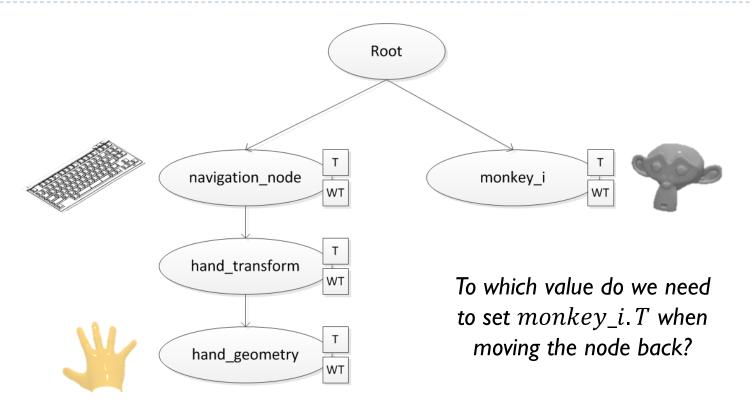


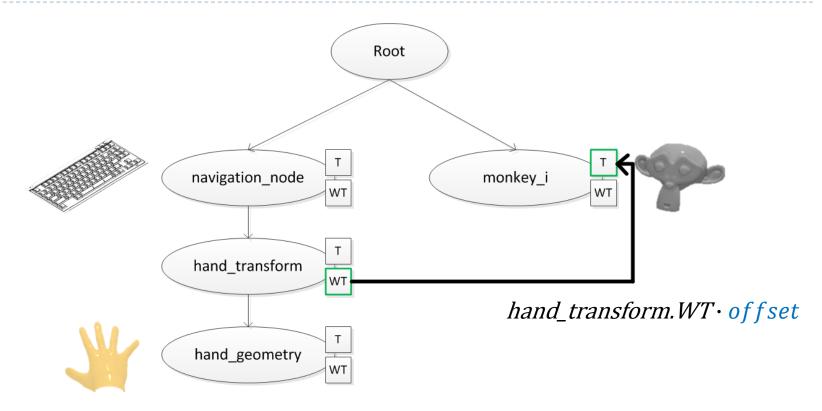




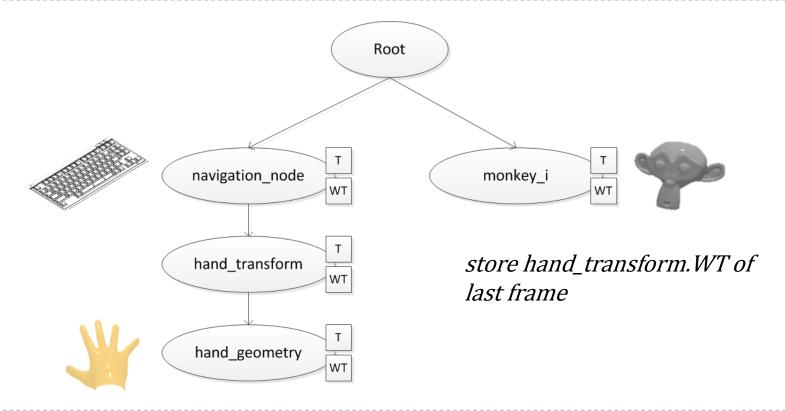


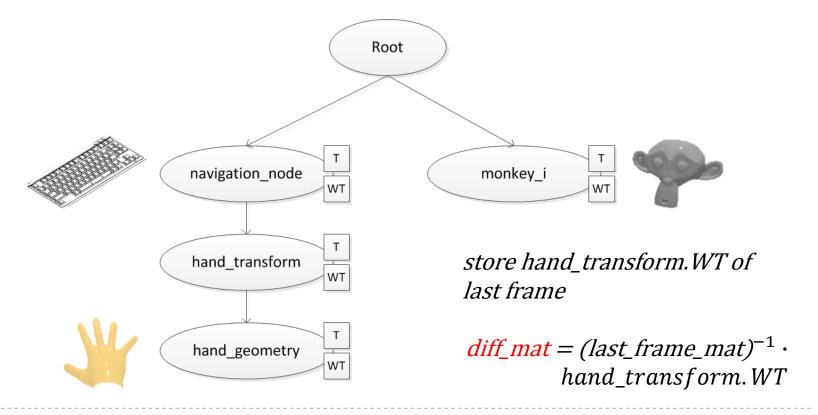


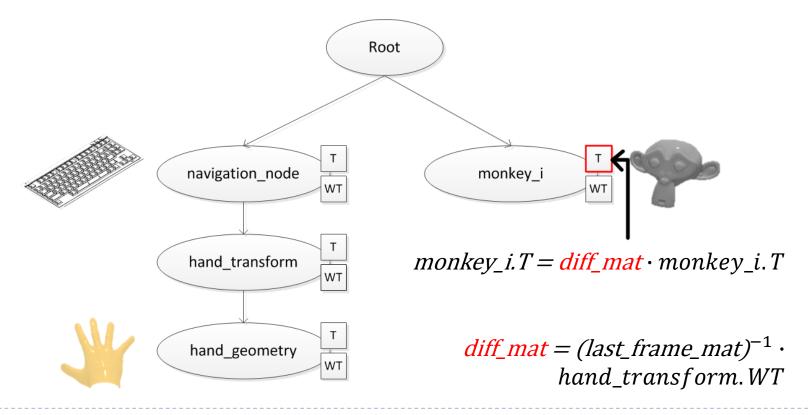




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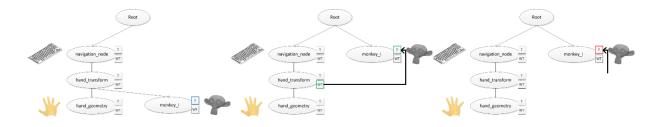
Implementation hints

Dragging methods

```
class ManipulationManager (avango.script.Script):
def start dragging(self):
  # . . .
def object dragging(self):
  # . . .
def stop dragging(self):
  # . . .
```

Comparison

Questions?



	Strategy I	Strategy 2	Strategy 3
start_dragging()	change node order in scenegraphset node transformation	compute offset	store tool matrix
object_dragging()		compute and set transformation	compute and apply diff matrixstore tool matrix
stop_dragging()	change node order in scenegraphset node transformation		