FrenetSerretSystem

```
In[@]:= f[t_] := {Cos[t], Sin[t]} (3 + Cos[3t])
                                                   余弦
                                                                          正弦
                     With [\{p = ParametricPlot[f[t], \{t, 0, 2\pi\}]\},
                    With循环
                                              绘制参数图
                        Manipulate[Show[p, Graphics[{PointSize[Large], Magenta, Point[f[t0]], Arrow[
                                                                                                                 点的大小
                                                      显示
                                                                                  图形
                                                                                                                                                                          品红色
                                          {f[t0], f[t0] + Normalize[f'[t0]]}], Arrow[{f[t0], f[t0] + Normalize[f''[t0]]}],
                                      Orange, Arrow[{f[t0], f[t0] + f'[t0]}], Arrow[{f[t0], f[t0] + f''[t0]}],
                                     |橙色
                                                                                                                                                               上箭头
                                      Black,
                                     黑色
                                      Arrow[{f[t0],
                                     箭头
                                             f[t0] + ((Append[f'[t0], 0] × Append[f''[t0], 0]) × Append[f'[t0], 0]) [ ;; 2]]}],
                                      Green, Arrow[{f[t0], f[t0] + Normalize[
                                                     ((Append[f'[t0], 0] \times Append[f''[t0], 0]) \times Append[f'[t0], 0]) \cite{Months} \cite{M
                                   ]]], \{t0, 0, 2\pi\}, SaveDefinitions \rightarrow True]]
                                                                                        保存定义
                                                                                                                                               真
Out[ • ]=
                      ({1, 0, 0} \times {1, 2, 0}) \times {1, 0, 0}
Out[ • ]=
                     {0, 2, 0}
                     tf = KnotData[{3, 1}, "SpaceCurve"]
                                  细结数据
Out[ • ]=
                     \{\sin[\pm 1] + 2\sin[2\pm 1], \cos[\pm 1] - 2\cos[2\pm 1], -\sin[3\pm 1]\} \&
    In[ • ]:= tf[t]
                     tf'[t]
                     tf''[t]
Outf o l=
                     {Sin[t] + 2Sin[2t], Cos[t] - 2Cos[2t], -Sin[3t]}
Out[ • ]=
                     \{\cos[t] + 4\cos[2t], -\sin[t] + 4\sin[2t], -3\cos[3t]\}
Out[ - ]=
                     \{-Sin[t] - 8Sin[2t], -Cos[t] + 8Cos[2t], 9Sin[3t]\}
```

```
      In[*]:=
      tan = FullSimplify@Normalize[tf'[t]];

      完全简化
      L正规化

      bio = FullSimplify@Normalize[tf'[t] x tf''[t]];
      完全简化

      Incomplete
      L正规化

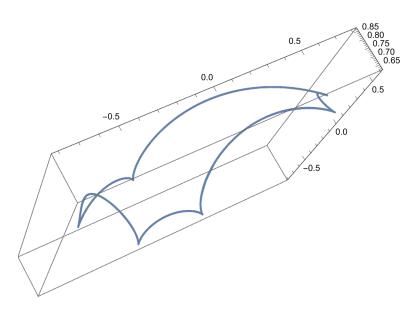
      nor = FullSimplify@Normalize[tan x bio];
      完全简化

      L正规化
      L正规化
```

ln[*]:= ParametricPlot3D[bio, {t, -10 π , 10 π }]

绘制三维参数图

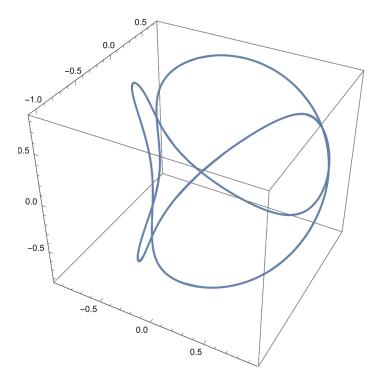
Out[•]=



$ln[\bullet] :=$ ParametricPlot3D[nor, {t, -10 π , 10 π }]

绘制三维参数图

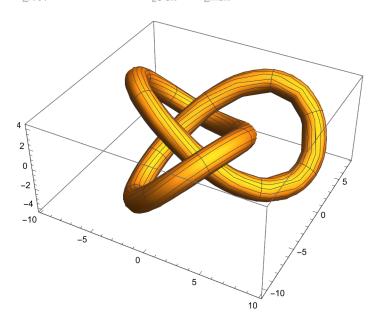
Out[•]=



In[@]:= ParametricPlot3D[

绘制三维参数图

Out[•]=



使用Frenet Frame

 $lo[\cdot]:=$ nb = FrenetSerretSystem[tf[t], t] [2, 2;;];

弗莱纳系统

ParametricPlot3D[Evaluate[tf[t] $3 + \{Cos[v], Sin[v]\}.nb], \{t, 0, 2\pi\}, \{v, 0, 2\pi\}]$

Out[•]=

