

The dynamics and the merging scenario of the galaxy cluster ACT-CL J0102-4915, El Gordo

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(temporary order)

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ABSTRACT

Merging galaxy clusters with radio relics provide rare insights to the merger dynamics as the relics are created by the violent merger process. We demonstrate one of the first uses of the properties of the radio relic to reduce the uncertainties of the dynamical variables and 3D configurations of a cluster merger, ACT-CL J0102-4915, El Gordo. At a redshift of 0.87, El Gordo ($M_{200c} = 2.75 \times 10^{15} \pm_{1.5}^{7.4} M_{\odot}$) is one of the most massive clusters discovered in the early universe. The two subclusters of El Gordo has a mass ratio of around 2:1. The X-ray and weak-lensing data of El Gordo show an offset of X kpc between the intercluster gas and the dark matter (DM) at $\sim 4 \sigma$ level. All these features of El Gordo make it part of a valuable class of dissociative mergers that can probe the self-interaction of dark matter. We employ a Monte Carlo simulation to investigate the three-dimensional (3D) configuration and dynamics of El Gordo. We give a summary of the inferred dynamical variables. By making use the polarization, velocity and position of the radio relic, we are able to confirm at X σ that the subclusters of El Gordo are moving away from each other. We find that the 3D merger speed of El Gordo to be $\sim 3000 \text{ km s}^{-1}$, which is still consistent with the low line-of-sight velocity of $\sim 600 \text{ km s}^{-1}$ based on the inferred time-since-collision ($TSC = \text{Gyrs}$) and the projection angle ($\alpha = 41^{\circ} \pm$). We put our estimates of TSC and α into context by relating them to existing observations of El Gordo. Finally, we compare our simulation result of El Gordo to the simulation result of the Bullet Cluster, and show that El Gordo is a very promising candidate for giving tighter constraint than the Bullet Cluster on the self-interaction of dark matter. (200 words) (check against astro-ph word limit)

Key words: gravitational lensing – dark matter – cosmology: observations – X-rays: galaxies: clusters – galaxies: clusters: individual (ACT-CL J0102-4915) – galaxies: high redshift

1 INTRODUCTION

Mergers of dark-matter-dominated galaxy clusters probes properties of the cluster components like no other systems. Clusters of galaxies are made up of 80% of dark matter in mass content, with a smaller portion of intercluster gas ($\sim 15\%$ in mass content), and sparsely spaced galaxies ($\sim 2\%$ in mass content) (REF). During a merger of clusters, the subclusters are accelerated to high speeds of several thousand km s^{-1} . The offsets of different components of the subclusters dissociate show how various interactions of the different components are at work. Observables such as

offset between dark matter and the other components may suggest dark matter self-interaction (REF). The difference of the galaxy colors in a merging cluster from relaxed cluster can also verify effects of environment on galaxy evolution.

van Weeren 2011a suggests that the double radio relic can provide clue to collisional parameters ??? **Ever since the discovery of El Gordo in the Atacama Camera Telescope (ACT) survey (REF), there is an ongoing effort for collecting comprehensive data for El Gordo.** From the spectroscopy and Dressler-Schechter test for the member galaxies in Sifón et al. (2013), El Gordo is confirmed to be a binary merger without significant sub-

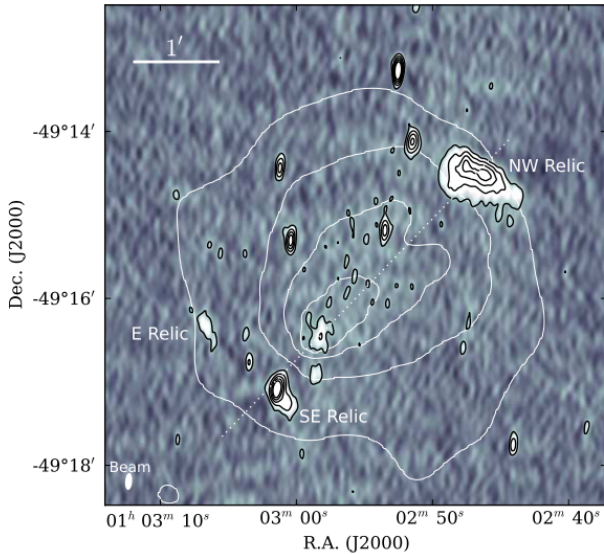


Figure 1. Configuration of El Gordo (to decide which figure to use, this one is from Lindner et al.)

structures. This picture is further supported by the weak lensing analysis by Jee et al. (2013). The weak lensing analysis shows a mass ratio of 2:1 between the two main subclusters, named according to their location as the northeast (NW) and southeast (SE) subclusters respectively. (See Figure 1). El Gordo has interesting intracluster medium morphology as shown in the X-ray. In the northwest, it shows a wake feature, i.e., depression in the X-ray emissivity, while in the southeast, it shows highest X-ray emissivity indicative of a cold gas core southeast of the wake. The cold gas core may have passed from the northwest to the southwest to have caused this morphology (Menanteau et al. 2011, hereafter M11). The extended mass distribution of El Gordo also makes it a good gravitational lens. Zitrin et al. (2013) have found multiple strong gravitationally lensed images around the center region of El Gordo. On the outer skirt of El Gordo, strong radio emission is detected in the NW and the SE respectively. These radio emission has steep spectral index gradient and are identified as radio relic created from a merger.

El Gordo is one of small sample of galaxy clusters (~ 50) that have been associated with a radio relic. (This paragraph needs a lot more organization) Even fewer of them have been studied in great details, making El Gordo a valuable candidate for further analysis. Furthermore, El Gordo satisfies the four criteria for being a dissociative merger which are proposed to be excellent probes of self-interacting dark matter (Dawson et al. 2012). (1) The subclusters of El Gordo has a small ratio of mass, i.e. $\sim 2 : 1$ (Jee et al. 2013, hereafter J13). (2) The merger axis, the line joining the two subclusters, coincides with the alignment of the double radio relic propagating outward at the periphery of the cluster (Menanteau et al. 2012, hereafter M12). This suggests a simple merger configuration with small impact variables. (3) The X-ray luminosity peak is shown to be offset from the weak-lensing peak by X kpc at X σ level (J13). (4) The observation of the double radio relic suggests that the angle between the merger axis and the plane of the sky has to be reasonably small (M11, Lindner et al. 2013), or

else the relic may appear as a halo instead. (Skillman et al. 2013)

In this paper, we perform results of simulations for modeling the time evolution of the mergers. Determining the time-since-collision of mergers of similar clusters helps us reconstruct different stages of a cluster merger. Mergers of clusters proceed on the time-scale of millions of year, observations of each cluster only provides a snapshot of a particular type of merger. In order to understand the merger process observationally, we need to capture and identify different stages of similar dissociative mergers.

Another crucial piece of missing information is the 3D configuration, i.e. the projection angle α , which contributes the largest amount of uncertainties to the dynamical variables (Dawson 2013). With a large projection angle α , the radio emission may appear as a radio halo instead. (Skillman et al. 2013)

This work is particularly important since it is forbiddingly expensive to simulate clusters similar to El Gordo in high resolution. The probability for finding an analog of El Gordo in a cosmological simulation is as low as % (REF). A realistic cosmological simulation of El Gordo is thus computationally expensive. Under the hierarchical picture of structure formation in the Λ CDM model, there is a rare chance for massive clusters like El Gordo to have formed at a redshift of $z = 0.87$. Staged simulation would not be able to probe the angular dependence. Both weak lensing analysis and BLAH DATA of El Gordo ((Jee et al. 2013)) has revealed a relatively simple bimodal mass distribution. The lack of complex substructures makes modeling of El Gordo with only two subclusters possible.

In this paper, we adopt the following conventions: (1) we assume the standard Λ CDM cosmology with $\Omega_m = 0.3$, $\Omega_\Lambda = 0.7$. (2) All confidence intervals are quoted at the 68% level unless otherwise stated. (3) All credible intervals (a.k.a. Bayesian confidence intervals) are also quoted at the 68% level unless otherwise stated and are central credible intervals. (4) All quoted masses (M_{200c}) are based on mass contained within r_{200} where the mass density is 200 times the critical density of the universe (ρ_{crit}) at the redshift of $z = 0.87$.

2 METHOD – MONTE CARLO SIMULATION

For this analysis, we made use of the collisionless dark-matter-only Monte Carlo modeling code written by Dawson (2013), hereafter (D13). In the code, the time evolution of the head-on merger was computed analytically, assuming that the only dominant force is the gravitational attraction from the masses of two truncated Navarro-Frenk-White (hereafter NFW) DM halos. Other major assumptions for modeling systems with this code include negligible impact parameter and no self-interaction of dark matter.

In the Monte Carlo simulation, many realizations of the collision is computed from the inputs of each realization, including the data (\vec{D}) and the model variable (α). In particular, the standard required data, which were in the form of samples of the probability density functions (PDFs), included the masses (M_{200NW}, M_{200SE}) the redshifts (z_{NW}, z_{SE}) and the projected separation of the two

Table 1. Properties of the sampling PDFs of the Monte Carlo simulation

| Data | Units | μ | σ | Ref |
|--------------|---------------------|---------|-------------|-----------------|
| M_{200cNW} | $10^{14} M_{\odot}$ | | | J13 |
| c_{NW} | / | | | J13 |
| M_{200cSE} | $10^{14} M_{\odot}$ | | | J13 |
| c_{SE} | / | | | J13 |
| z_{NW} | / | 0.86901 | 0.00017^b | M11, Sifón 2013 |
| z_{SE} | / | 0.87175 | 0.00019^b | M11, Sifón 2013 |
| d_{proj} | Mpc | | | J13 |

^aThis σ corresponds to the 68% central Bayesian credible interval computed from the posterior probability of our MCMC analysis.

^bThis σ corresponds to the biweight scale.

^cWe use the full PDFs as the inputs of our simulation so different ways of denoting the uncertainties do not affect the simulation.

subclusters (d_{proj}). In each realization, we randomly drew the samples of the PDFs. These inputs are then used for computing the output variables ($\vec{\theta}'$) by making use of conservation of energy to describe their collision due to the mutual gravitational attraction. (See Table 1 for quantitative descriptions of the sample PDFs and we outline how those PDFs are obtained in the following subsections.) To ensure convergence of the output PDFs, in total, 2 million (to be confirmed) realizations were computed. The results, however, are consistent up to a fraction of a percent just from 20 000 runs (D13).

We note that the Monte Carlo simulation is written under a Bayesian framework but differs from conventional Bayesian inference. The Bayes chain rule underlies the simulation is:

$$P(\vec{\theta}|\vec{D}) \propto P(\vec{D}|\vec{\theta})P(\vec{\theta}) \quad (1)$$

where the likelihood is defined to be the PDF of \vec{D} given $\vec{\theta}$, i.e. the input variables, not statistical parameters, and the priors are defined to be the probabilities due to prior knowledge of the estimated values of $\vec{\theta}$. The output variables $\vec{\theta}'$, on the other hand, were computed according to the conservation of energy, which is represented by a suitable function form f below. For example, the calculation of the j -th realization:

$$(\vec{\theta}')^{(j)} = f(\vec{\theta}^{(j)}, \vec{D}) \quad (2)$$

The estimated values of $(\vec{\theta}')^{(j)}$ were then computed over all j realizations. Finally, we took physical constraints on $\vec{\theta}$ and $\vec{\theta}'$ into account by excluding the unphysical realizations, and we refer to this process as “applying prior probability”.

2.1 Inputs of the Monte Carlo simulation

2.1.1 Membership selection and redshift estimation of subclusters

We used a 2D spatial cut to determine members of the two subclusters, then bootstrapped the biweight locations of the redshifts of the respective members in order to obtain the PDFs of the redshifts of each subcluster. We made use of the spectroscopic data obtained from the Very Large Telescope (VLT) and Gemini

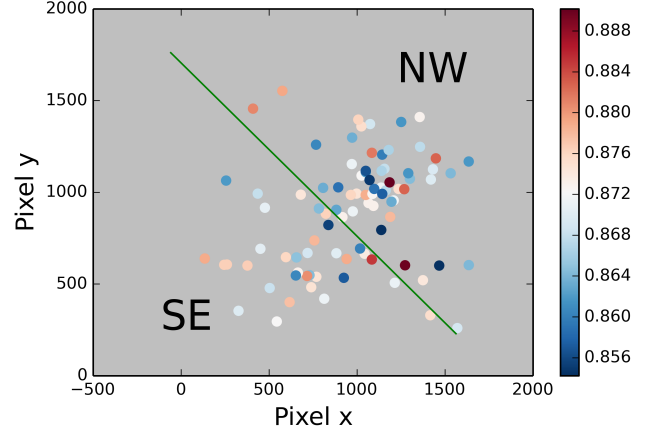


Figure 2. The division of the member galaxies among the two subclusters of El Gordo by a spatial cut (green line) that is approximately perpendicular to the 2D merger axis. The color bar shows the color mapping of the spectroscopic redshift of the member galaxies. The spatial cut is done after mapping the world coordinates to pixel coordinates to avoid anamorphic distortion.

South as described in M11 and Sifón et al. (2013). The overall membership of the galaxies of El Gordo was determined using a shifting gapper method after applying a rest frame cut of 4000 km s^{-1} . This method gives a total count of 89 galaxy members of El Gordo. From the 2D spatial cut of the confirmed members, we determined that there are 54 members in the NW subclusters and 35 members in the SE subclusters. (See Figure 2) The spectroscopic redshift of the clusters were determined to be $z_{NW} = 0.86901 \pm 0.00017$ and $z_{SE} = 0.87175 \pm 0.00019$, where the quoted numbers represent the biweight location and biweight scale respectively (Beers et al. 1990). The biweight location estimators are less susceptible to outliers than the mean and standard deviations.

2.1.2 Weak lensing mass estimation

We obtained the PDFs of the masses of the subclusters by doing a Monte Carlo Markov Chain (MCMC) analysis of the reduced shear from the weakly lensed background galaxies. We computed the reduced shear signal generated by two NFW halos according to Umetsu (2010) (See Appendix B for details of implementation and output diagnostics). At each step we followed the procedure of a Metropolis algorithm. The transition kernel was set to be the log likelihood of fit of the model shear to the reduced shear of the data (B1). In total, eight MCMC chains were used. After every 5000 MCMC steps for all the chains, we computed the R coefficient (Gelman & Rubin 1992) to check for convergence. We performed more MCMC steps as long as convergence was not achieved. After convergence was achieved, we removed the burn-in portions of the MCMC chains and used the resulting MCMC chains as samples of the PDFs of the masses.

We used an identical catalog of reduced and bias-corrected background galaxy shapes as in Hubble Space Telescope PROP 12755 from J13. (! Jee et al. 2013 actually used additional data) On the other hand, we fixed

the position of the centers of the NFW halos to be the luminosity peaks of the respective galaxy populations of the two subclusters, which are at R.A. = 01:02:51.68, Decl. = -49:15:04.40 and R.A. = 01:02:38.38, Decl. = -49:16:37.64 for the NW and SE subclusters respectively (J13). The agreement between our analysis and (J13) to within the 68% credible interval serves as a sanity check on the estimated masses.

2.1.3 Estimation of projected separation (d_{proj})

To be consistent with our MCMC mass inference, our Monte Carlo simulation takes the projected separation of the NFW halos to be those of the two aforementioned luminosity peaks.

2.2 Outputs of the Monte Carlo simulation

We summarize the output of the simulation here and leave detailed plots and descriptions in Appendix C. The simulation provides PDF estimates for many of the output variables. Variables of the most interest include the time dependence and α , which is defined to be the projection angle between the plane of the sky and the merger axis. Other output variables are dependent on α and the time dependence. Specifically, the simulation denotes the time dependence by providing several characteristic time-scales, including the time elapsed between the collision and when the subclusters first reach apoapsis (T) and the time-since-collision.

The two version of the time-since-collision variables TSC_0 and TSC_1 denotes different possible merger scenarios. 1) We call the scenario for which the subclusters are moving apart after collision to be “outgoing” and it corresponds to the smaller TSC_0 value, and 2) we call the alternative scenario “incoming” for which the subclusters are approaching each other after turning around from the apoapsis for the first time and it corresponds to TSC_1 . We describe how we use to break the degeneracies of the two scenarios in section 2.4.

The simulation also output estimates of variables that characterize the dynamics of the merger. The 3D velocities, both at the time of the collision ($v_{3D}(t_{col})$) and at the time of observation ($v_{3D}(t_{obs})$) are provided. The maximum 3D separation (d_{max}) which is defined to be the distance between the position of collision to the apoapsis is also part of the outputs. (See the lower half of Table 2 for all the outputs).

2.3 Design and application of priors

The strength of the Monte Carlo simulation by D13 is its ability to detect and rule out extreme input values that would result in unphysical realizations. Our default Monte Carlo filters are described in D13 and they are applied to ensure unphysical realizations in the simulation are ruled out. In addition to the default filters, we also examine the effects of applying two filters derived based on the position and the integrated polarization fraction of the radio relic of El Gordo respectively.

El Gordo shows remarkable double radio relics on the periphery (M11). The radio relic of El Gordo

was first mentioned in the Sydney University Molonglo Sky Survey (SUMSS) data in low resolution at 843 MHz (Mauch et al. 2003) as shown in M11. The higher resolution radio observation conducted by Lindner et al. (2013) at 610 MHz and 2.1 GHz confirms that those radio emission correspond to radio relic after removing effects of radio point sources.

Radio relics have been suggested to be able to constrain the mass ratios, the projection and the merger configuration. (van Weeren et al. 2010) Ever since the first detection of radio relic, cosmological hydrodynamical simulations of merging clusters have been used to model their emission spectrum and geometry. (Vazza et al. 2012, van Weeren et al. 2011, Bonafede et al. 2013, Ensslin et al. 1998, Brüggén et al., Skillman et al. 2013) While such cosmological simulations have provided valuable insights to verifying the physical models, they are expensive in terms of computational power and novel techniques have to be invented in order to analyze the large amount of simulated data so progress has been slow. Our Monte Carlo simulation can make use of known physics combined with the preliminary results from such cosmological simulations to use properties of the radio relic to constrain merger dynamics. Compared to hydrodynamical simulations or cosmological simulations, this Monte Carlo simulation is not demanding in terms of CPU time, therefore, we can run many realizations in order to probe how the input variables affect the output variables.

2.3.1 Monte Carlo filters based on the integrated polarization fraction of the radio relic

In particular, Lindner et al. (2013) reports an integrated polarization fraction of $\sim 33\%$ for the two identified relics. The high integrated polarization fraction can be explained by uniformly aligned magnetic field. (Synchrotron emission from unorganized magnetic field are randomly polarized) We refer to a model from Ensslin et al. (1998) with the following physical picture: during a merger, the intracluster medium is compressed, this aligns the unordered magnetic field perpendicular to the line joining the cluster center to the radio relic. (Ensslin et al. 1998, van Weeren et al. 2010, Feretti et al. 2012) Thus, the synchrotron emission emitted from the electrons near this aligned magnetic field is strongly polarized perpendicular to this magnetic field.

The major assumption behind the design of our filter is that the integrated polarization fraction is a monotonically decreasing function of α . This assumption is inspired by the class of models given by Ensslin et al. (1998), which, despite various inputs for spectral indices and magnetic field strength, each predicts a monotonically decreasing integrated polarization fraction as a function of α . In particular, we refer to a model from Ensslin et al. (1998) that would give the most conservative estimate on the upper bound of α . This model predicts a maximum integrated polarization fraction of $\sim 75\%$ when $\alpha = 0$. From this model, the observed integrated polarization fraction of 33% corresponds to $\mu_\alpha = 39^\circ$. This polarization fraction of $\sim 75\%$ predicted by (Ensslin et al. 1998) is consistent with the upper bound of relic polarization fraction in cosmological simulations (Skillman et al. 2013). No other model of the magnetic field should predict a higher polarization fraction, thus it is highly unlikely that we see 33% integrated polarization at $\alpha > 39^\circ$.

Table 2. Table of the output PDF properties of the model variables and output variables from Monte Carlo simulation

| Variables | Units | Location | Default priors | | Location | Default + position priors | |
|-------------------|--------------------|----------|---------------------|--------|----------|---------------------------|--------|
| | | | 68% CI [†] | 95% CI | | 68% CI | 95% CI |
| α | (degree) | | | | | | |
| TSC_0 | Gyr | | | | | | |
| TSC_1 | Gyr | | | | | | |
| T | Gyr | | | | | | |
| d_{max} | Mpc | | | | | | |
| $v_{3D}(t_{obs})$ | km s ⁻¹ | | | | | | |
| $v_{3D}(t_{col})$ | km s ⁻¹ | | | | | | |
| d_{max} | Mpc | | | | | | |
| d_{3D} | Mpc | | | | | | |

[†] CI stands for credible interval

We cannot rule out $\alpha \leq 39^\circ$ as a result of possible variations in the magnetic field. Ensslin et al. (1998) assumes an isotropic distribution of electrons in an isotropic magnetic field. Cosmological simulations of radio relics from Skillman et al. (2013) show varying polarization fraction across and along the relic assuming $\alpha = 0$, resulting in a lower integrated polarization fraction. For example, it is possible to see a edge-on radio relic ($\alpha = 0$) with integrated polarization fraction of 33%.

Observation also introduces uncertainties that we have to take into account. Skillman et al. (2013) shows that after convolving the simulated polarization signal with a Gaussian kernel of 4' to match observable resolution, the polarization fraction drops to between 30% to 65% even when $\alpha = 0$. Other uncertainties come from the fact that the inferred spectral indices differ between the two observed frequencies and vary between the three identified relic sources (Lindner et al. 2013). Following previous discussion, we pick a value of $\mu_\alpha = 39^\circ + 2^\circ$ to filter realizations, i.e. we do not draw values of $\alpha > 41^\circ$. The extra 2° in the prior is included to account for the uncertainty of the integrated polarization fraction reported by Lindner et al. (2013).

2.4 Extension to the Monte Carlo simulation - Determining merger scenario with radio relic position

We demonstrate that despite significant uncertainty in the time evolution of the shock, we can still break the degeneracy of the outgoing and incoming merger scenarios by comparing the observed and the simulated position of the radio relic. The key to the success of this method lies our ability in estimating the upper and lower bounds on the possible position of the relic. The uncertainty of the time evolution of the velocity of the shock stem from how the velocity depends on a number of physical quantities, including the local gravitational potential, matter density, temperature, pressure among others (Ensslin et al. 1998, Shu .F., more citations?). The exact time evolution of the shock velocity requires detailed numerical simulation similar to Springel & Farrar (2007), Vazza et al. (2012), Kang et al. (2007), etc. We draw physical insight from the simulations of the merger shock of the Bullet cluster from Springel & Farrar (2007) and Paul et al. (2011), which both show that, right after the collision of the subclusters, the shock speed is compara-

ble to the merger speed of the two subclusters in the center of mass frame. While Paul et al. (2011) reports the shock speed decreases only slightly as it propagates away from the center of mass, the Bullet shock speed mildly drops by only $\sim 14\%$ in the 300 Myr period after the formation of the Bullet shock versus a $\sim 65\%$ drop for the main subcluster, which was slowed down by gravity.

We approximated the upper and lower bounds of the NW relic speed with the simulated speeds of the NW subcluster. We simplified the calculation by working in the center of mass frame where the shock speed is expected to drop only slightly with time. We estimated the upper and lower bounds of the time-averaged velocity ($\langle v_{relic} \rangle$) of the shock between the collision of the subclusters and the observed time as:

$$\frac{(v_{3D}(t_{obs}) + v_{3D}(t_{col}))}{2} < \langle v_{relic} \rangle \lesssim v_{3D}(t_{col}) \quad (3)$$

where $v_{3D}(t_{col}) < 0$ for the incoming scenario. For the outgoing situation, the lower bound is set to be the average speed of the NW subcluster since the relic is observed to have traveled further away than the NW subcluster from the center of mass. The upper bound can be approximated as the collisional speed of the NW subclusters due to how the shock is powered by the collision. We base this physical picture on the fact that shock is a pressure wave and does not experience gravitational deceleration while some dissipative processes may have slowed down the shock wave slightly. It is unlikely that there would be significant energy injected into the shock to speed up the shock such that the shock travels much faster than the collision speed of the subcluster.

$$s_{proj} = \langle v_{relic} \rangle (\hat{t}_{obs} - \hat{t}_{col}) \cos(\hat{\alpha}) \quad (4)$$

where s_{proj} is the bound projected separation. We compare the bounds with the observed position of the NW relic from Lindner et al. (2013) at RA = 01:02:46, DEC = -49:14:43 (Lindner et al. 2013). Three sources of radio relic were identified - including the NW, SE and the E relic. The NW radio relic possesses the most extended geometry among all the identified relic source. We do not refer to the SE nor the E radio relic in this calculation since we do not have an estimation of the shock speed of the SE relic nor the E relic from Lindner et al. 2013 as a comparison case. From Lindner et al. (2013), the estimated speed of the NW relic

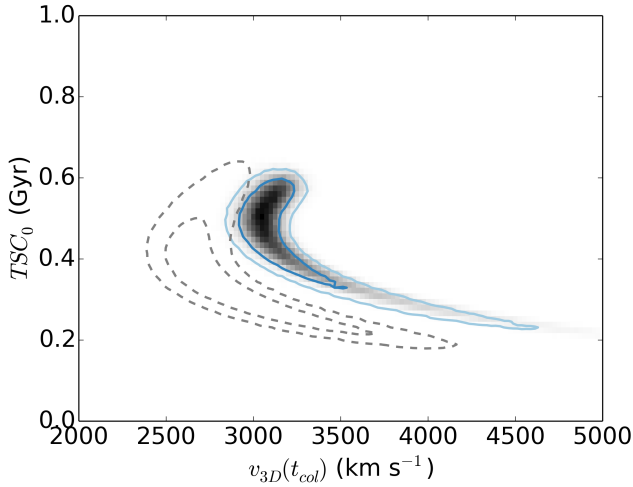


Figure 3. The marginalized time-since-collision (TSC) vs 3D velocities (v_{3D}) of El Gordo and the Bullet Cluster. (to add descriptions of the different filters used)

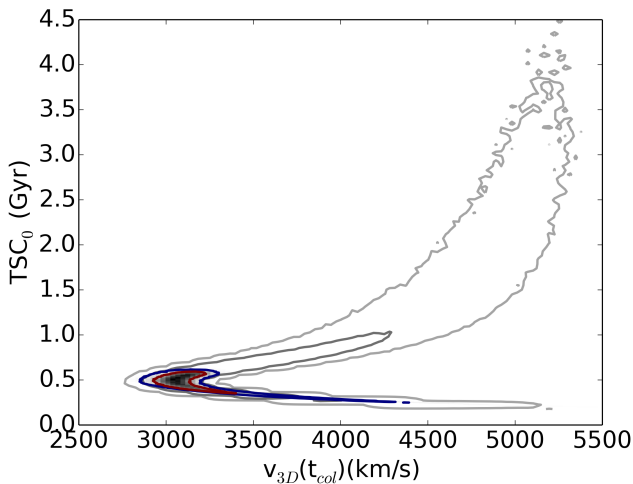


Figure 4. The marginalized output PDF of the time-since-collision (TSC_0) vs. the 3D velocity at the time of collision for El Gordo. (to add more description about contours)

is $4300 \pm_{500}^{800} \text{ km s}^{-1}$. This speed is compatible with our simulated collisional speed but the conversion of frame of reference is non-trivial since the speed is measured with respect to on the turbulent intercluster gas.

3 RESULTS

3.1 Relative merger speed

The relative merger speed of the two subclusters is estimated to be 3400 km s^{-1} at the time of collision. The two subclusters are estimated to slow down to a 3D relative velocity of only $\sim 800 \text{ km s}^{-1}$ at the time of observation. Based on this time evolution of the v_{3D} , it is unlikely that El Gordo is a slow merger as mentioned in Menanteau et al. (2011).

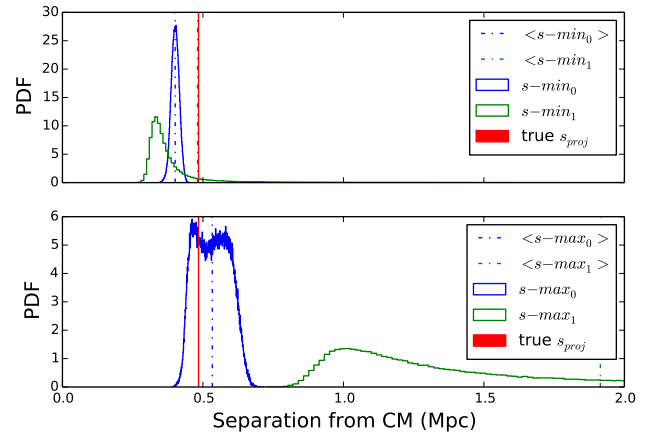


Figure 5. Position of the radio relic based on the estimated minimum velocities (upper figure) and the estimated maximum velocities (lower figure)

3.2 Time-since-collision

The simulation gives two plausible estimates for the time-since-collision, with $TSC_0 = \text{Gyr}$ and $TSC_1 = \text{Gyr}$. The presence of the radio relic, in conjunction with a depression in the X-ray surface brightness shown in M11, strongly suggest that El Gordo is a post-collision system. Based on section 2.4, we have come up with an estimate for the likely position based on the two inferred TSC. We summarize the realizations for the two possible scenarios with the polarization prior applied in Figure 5, while we leave the results from the default prior in Appendix C1.

After taking into this uncertainty, the possible locations of the relic still favors the outgoing scenario. (See figure 5) Other uncertainties arise from how we define the reference frame for the calculation. The uncertainty associated with the two centroids are of the order of $\sim 0.1 \text{ Mpc}$ (Jee et al. 2013) and are relatively unimportant???

3.3 Effects of applied prior on parameters

We perform tests of how sensitive our parameters are to the design of our prior filters.

4 DISCUSSION

4.1 Three-dimensional (3D) configuration of El Gordo

The Monte Carlo simulation estimates that the projection angle to be 41.7° , with the CI = $22.7^\circ, 61.14^\circ$.

- explains that there hasn't been quantitative constraints on the angle for which double radio relic can be observed, even though that many studies have suggested that the detection of radio relic should imply that α should be small. From this simulation we have shown that it is possible to detect the double radio relics with α being as big as 61.14° .

- Lindner et al. provided constraint of $\alpha > 7.8^\circ$ based on the dynamics.

- James' paper did mention how the mass estimation depends on α , with the estimated mass being a lot smaller if

$\alpha \geq 65^\circ$. However, since we did use the larger mass estimate as the input of this simulation, we can only say that the inferred α is consistent with the mass estimation.

- discussion of the different scenarios mention in M11:
 - 1) we are viewing after core passage, but before first turn around, and the merger speed is low”
 - 2) the merger speed is high, but we are viewing after the first turn around as the two components come together for a second core passage
- discuss the inclination angle estimate from M11
- Dave: explain where the limits of the projection angle comes from. what observational evidence contradicts the low velocity scenario the most

With this new piece of evidence, we find that the absence of an X-ray shock feature from El Gordo, may not be due to the merger speed being low, as suggested by J13. In particular, taking into account that the estimated projection angle of $\sim 41.7^\circ$, we estimate the projected relative velocity to be 597 km s^{-1} , which is consistent with the estimated line-of-sight velocity differences of $586 \pm 96 \text{ km s}^{-1}$ in M11.

Furthermore, the study from Lindner et al. (2013) Lindner et al. has come up with an estimation of the shock velocity of the radio relic of El Gordo as $\sim 4000 \text{ km s}^{-1}$. While this shock velocity is not the same as the merger velocity, they should be of similar magnitude. Indeed our simulation found that a merger velocity of 4000 km s^{-1} is within the 95% credible interval.

4.2 Our finding in the context of other studies of El Gordo

Compare to Lindner et al. Compare to Donnert et al. for their best fit scenario.

4.3 Comparison to other merger clusters of galaxies

Talks about how El Gordo is more massive and collided at higher speed than both the Bullet and the Musketball, so El Gordo is probably a better probe of SIDM properties.

With this new piece of evidence, we find that the absence of an X-ray shock feature from El Gordo, may not be due to the merger speed being low, as suggested by J13. In particular, taking into account that the estimated projection angle of $\sim 41.7^\circ$, we estimate the projected relative velocity to be 597 km s^{-1} , which is consistent with the estimated line-of-sight velocity differences of $586 \pm 96 \text{ km s}^{-1}$ in M11.

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4.4 Uncertainties of the radio relic prior

needs better simulation to understand the physical properties of radio relic.

4.5 Limitations of our model and future work

Impact parameter of El Gordo may not be negligible. Simulations from Ricker & Sarazin (2001) showed that cool-core is not disrupted when the impact parameters of mergers are of the order of $\sim 500 \text{ kpc}$.

5 SUMMARY & CONCLUSION

This paper presents one of the first examples of using the observed radio relic emission to constrain cluster merger properties. While we have demonstrated how to use the physical properties of the radio relic emission to constrain merger dynamics and configurations, many improvements can still be made as more studies of radio relic are being done from both cosmological simulations and observations.

Currently, there are only a few studies of radio relic available for a range of viewing angles (Skillman et al. 2013, one of Bruggen’s paper). As more cosmological simulations inform us if the relic is observable at certain viewing angles will help us come up with better Monte Carlo filters.

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APPENDIX A: BAYESIAN FORMALISM OF DAWSON’S MONTE CARLO SIMULATION

We make a distinction between common Bayesian inference and the formalism of the Bayesian framework of the Monte Carlo simulation. Common Bayesian parameter estimations involve:

APPENDIX B: DETAILS AND TESTS FOR THE MCMC MASS INFERENCE

The reduced shear generated by each NFW halo is determined by its mass (m_{200c}) and the position of its center (\vec{s}).

We consider the joint posterior as the fit to the ellipticity data:

$$\log(P(m_1, \vec{s}_1, m_2, \vec{s}_2 | \vec{e})) \propto - \left[\frac{(\hat{e}_1(m_1, \vec{s}_1, m_2, \vec{s}_2) - e_1)^2}{\sigma_{e_1}^2 + \sigma_{SN}^2} + \frac{(\hat{e}_2(m_1, \vec{s}_1, m_2, \vec{s}_2) - e_2)^2}{\sigma_{e_2}^2 + \sigma_{SN}^2} \right] \quad (\text{B1})$$

where $\sigma_{SN} = 0.25$ (to be checked) represents Gaussian shape noise of the background galaxies; The reduced shear due to the NFW halos can be decomposed into two components, \hat{e}_1 and \hat{e}_2

We only drew starting mass values between $10^{13} M_\odot$ and $10^{15} M_\odot$ for our MCMC chains, as informed by previous published mass estimates. (M11, J13, Zitrin et al. 2013). Each of the subsequent MCMC step then draws a random pairs of mass value with the values of previous step as the means of the distributions. The ellipticities generated by a NFW halo can be summarized as:

$$\hat{e}_1(m, \vec{s}_1) = \quad (\text{B2})$$

$$\hat{e}_2(m, \vec{s}_2) = \quad (\text{B3})$$

APPENDIX C: RESULT PLOTS OF MONTE CARLO SIMULATION

C1 Plots for distinguishing the two merger scenarios

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