

The dynamics and merging scenario of the galaxy cluster ACT-CL J0102-4915, El Gordo

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(temporary order)

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ABSTRACT

Merging galaxy clusters with radio relics provide rare insights to the merger dynamics as the relics are created by the violent merger process. We demonstrate one of the first uses of the properties of the radio relic to reduce the uncertainties of the dynamical variables and 3D configurations of a cluster merger, ACT-CL J0102-4915, El Gordo. From the double radio relic observation and X-ray wake morphology, it is believed that El Gordo is observed shortly after the first core-passage of the subclusters. At a redshift of 0.87, El Gordo ($M_{200c} = 2.75 \times 10^{15} \pm 7.4 M_\odot$) is one of the most massive clusters discovered in the early universe. The two subclusters of El Gordo has a mass ratio of around 2:1. The X-ray and weak-lensing data of El Gordo show an offset of X kpc between the intercluster gas and the dark matter (DM) at $\sim 4\sigma$ level. All these features of El Gordo make it part of a valuable class of dissociative mergers that can probe the self-interaction of dark matter. We employ a Monte Carlo simulation to investigate the three-dimensional (3D) configuration and dynamics of El Gordo and provide a summary of the probability density functions of the inferred variables. By making use the polarization fraction of the radio relic, we are able to constrain the estimate of the angle between the sky and the merger axis to be $\alpha = 21^\circ \pm$. The 3D merger speed of El Gordo was found to be $\sim 2400 \text{ km s}^{-1}$. We put our estimates of the time-since-collision into context and showed that if the time-averaged shock velocities $\gtrsim 2800 \text{ km s}^{-1}$ in the center of mass frame, the two subclusters are more likely to be moving away from each other than moving towards each other. Finally, we compare our simulation results with other merging clusters and show that El Gordo has very similar dynamical properties as the Bullet Cluster

Key words: gravitational lensing – dark matter – cosmology: observations – X-rays: galaxies: clusters – galaxies: clusters: individual (ACT-CL J0102-4915) – galaxies: high redshift

1 INTRODUCTION

Mergers of dark-matter-dominated galaxy clusters probes properties of the cluster components like no other systems. Clusters of galaxies are made up of 80% of dark matter in mass content, with a smaller portion of intercluster gas ($\sim 15\%$ in mass content), and sparsely spaced galaxies ($\sim 2\%$ in mass content) (REF). During a merger of clusters, the subclusters are accelerated to high speeds of several thousand km s^{-1} . The offsets of different components of the subclusters dissociate show how various interactions of the different components are at work. Observables such as offset between dark matter and the other components may

suggest dark matter self-interaction (REF). (The following sentence does not actually fit in this paragraph and I have to put it somewhere else) difference of the galaxy colors in a merging cluster from relaxed cluster can also verify effects of environment on galaxy evolution.

El Gordo possesses a range of special features that allows us to constrain the merger dynamics in multiple ways. Ever since the discovery of El Gordo in the Atacama Camera Telescope (ACT) survey (REF), there is an ongoing effort for collecting comprehensive data for El Gordo. From the spectroscopy and Dressler-Schecter test for the member galaxies in Sifón et al. (2013), El Gordo is confirmed to be a binary merger without significant substructures. This pic-

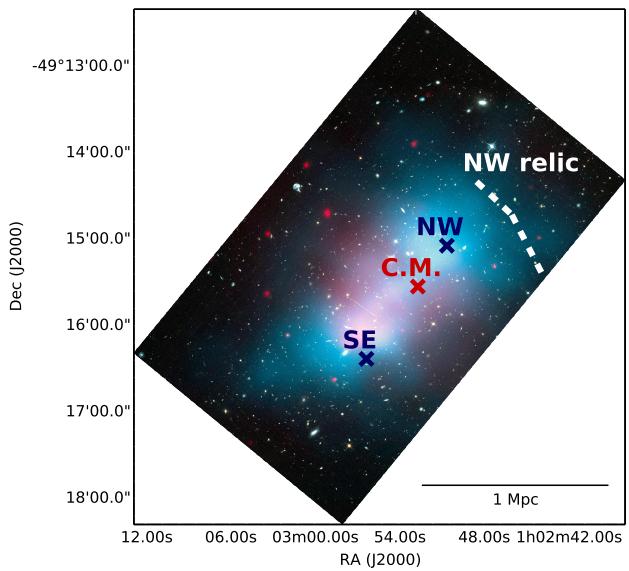


Figure 1. Configuration of El Gordo showing approximate overlaid of dark matter distribution in blue, and X-ray emissivity in red. The cross markers show the position of the northwest (NW) and southeast (SE) dark matter density peaks, and the center of mass (CM) location respectively. The dashed white line indicates the approximate location of the northwest radio relic (NW relic). (Image Credit: NASA, ESA and Jee et al. 2014 - not sure if I am citing the agencies in the appropriate format).

ture is further supported by the weak lensing analysis by Jee et al. (2013). The weak lensing analysis shows a mass ratio of $\sim 2:1$ between the two main subclusters, named according to their location as the northeast (NW) and southeast (SE) subclusters respectively. (See Figure 1). El Gordo has interesting intracluster medium morphology as shown in the X-ray. In the northwest, it shows a wake feature, i.e., depression in the X-ray emissivity, while in the southeast, it shows highest X-ray emissivity indicative of a cold gas core southeast of the wake. The cold gas core may have passed from the northwest to the southwest to have caused this morphology (Menanteau et al. 2011, hereafter M12). The extended mass distribution of El Gordo also makes it a good gravitational lens. Zitrin et al. (2013) have found multiple strong gravitationally lensed images around the center region of El Gordo. On the outer skirt of El Gordo, strong radio emission is detected in the NW and the SE respectively. These radio emission has steep spectral index gradient and are identified as radio relic created from a merger. El Gordo is one of small sample of galaxy clusters (~ 50) that have been associated with a radio relic and show dissociation between the X-ray gas and the DM subclusters. Even fewer of them have been studied in great details, making El Gordo a valuable candidate for further analysis.

In this paper, we combine available information of El Gordo with the main 1) inferring missing variables of the merger such as the time-evolution and the 3D configuration, 2) giving estimates of the associated dynamical parameters after taking into account all available constraints and reflecting uncertainties due to the observed data. Determining the time-since-collision of mergers of similar clusters helps us reconstruct different stages of a cluster merger. Mergers of

clusters proceed on the time-scale of millions of year, observations of each cluster only provides a snapshot of a particular type of merger. In order to understand the merger process observationally, we need to identify different stages of similar dissociative mergers and gather statistics to understand the physics of the mergers. Another crucial piece of missing information is the 3D configuration, i.e. the angle between the plane of the sky and the merger axis called the projection angle α . Since most of the dynamical observables are projected quantities while our physics require 3D variables, the deprojection based on α contributes the largest amount of uncertainties to the dynamical variables (D13). From the morphology of the double relic of El Gordo, it is believed that α should be small. However, there has not been any quantitative constraints on the upper bound of α .

We employ a data-driven approach that thoroughly probes parameter space by directly drawing samples from the observables. This work based on Monte Carlo simulation is particularly important since it is forbiddingly expensive to simulate and analyze clusters similar to El Gordo in high resolution. Previous attempts at modeling El Gordo with hydrodynamical simulations such as Donnert (2014) and Molnar & Broadhurst (2014) provided only in total a dozen possible configurations of El Gordo, which could hardly be representative of the input uncertainties. Their sophisticated but specialized setup are more suitable for understanding the gas dynamics rather than for estimating overall parameters. Another approach for estimating dynamical parameters would be to look for multiple analogs of El Gordo in cosmological simulations. However, under the hierarchical picture of structure formation in the Λ CDM model, there is a rare chance for massive clusters like El Gordo to have formed at a redshift of $z = 0.87$. The probability for finding an analog of El Gordo in a cosmological simulation is as low as % (M12).

In the following sections, we adopt the following conventions: (1) we assume the standard Λ CDM cosmology with $\Omega_m = 0.3$, $\Omega_\Lambda = 0.7$. (2) All confidence intervals are quoted at the 68% level unless otherwise stated. (3) All credible intervals (a.k.a. Bayesian confidence intervals that also takes into account prior probability) are also quoted at the 68% level unless otherwise stated and are central credible intervals. (4) All quoted masses (M_{200c}) are based on mass contained within r_{200} where the mass density is 200 times the critical density of the universe (ρ_{crit}) at the redshift of $z = 0.87$.

2 DATA

We gathered and analyzed data from multiple sources for different purposes. For assigning membership of galaxies to the two identified subclusters, we examined the spectroscopic data obtained from the Very Large Telescope (VLT) and Gemini South as described in M12 and Sifón et al. (2013). For the weak-lensing mass estimation, we used the published Monte Carlo Markov Chains (MCMC) mass estimates from J13. See Table 1 for descriptions of the probability density functions (PDFs) of the input variables.

In order to further constrain our parameter space, we referred to the properties of the radio relic from Lindner et al. (2014). El Gordo shows radio relics on the periphery

of both subclusters (M12). Two radio relics, the northwest (NW) relic and the southeast (SE) relic, of El Gordo were first discovered in the Sydney University Molonglo Sky Survey (SUMSS) data in low resolution at 843 MHz (Mauch et al. 2003) as shown in M12. The higher resolution radio observation conducted by Lindner et al. (2014) at 610 MHz and 2.1 GHz confirms that the identity of the NW radio relic after removing effects of radio point sources. The NW radio relic, which possesses the most extended geometry (0.56 Mpc in length) among all radio source, was identified to be associated with the merger. We do not refer to the SUMSS SE nor the E radio relic in this paper since the upstream velocity of those radio relics are not reported in Lindner et al. (2014).

3 METHOD – MONTE CARLO SIMULATION

We used the collisionless dark-matter-only Monte Carlo modeling code written by Dawson (2013), hereafter (D13), to compute the physics of between the first and second core-passage of the DM subclusters. In the D13 code, the time evolution of the head-on merger was computed based on an analytical, dissipationless model assuming that the only dominant force is the gravitational attraction from the masses of two truncated Navarro-Frenk-White (hereafter NFW) DM halos. In the simulation, many realizations of the collision is computed by drawing random realizations of the probability density functions (PDFs) of the inputs, including the data (\vec{D}) and one model variable, the projection angle between the plane of the sky and the merger axis, α . In particular, the required data, included the masses ($M_{200\text{NW}}, M_{200\text{SE}}$) the redshifts ($z_{\text{NW}}, z_{\text{SE}}$) and the projected separation of the two subclusters (d_{proj}). (See Table 1 for quantitative descriptions of the sample PDFs) Each set of inputs is then used for computing the output variables ($\vec{\theta}'$) by making use of conservation of energy to describe their collision due to the mutual gravitational attraction. To ensure convergence of the output PDFs, in total, 2 million realizations were computed. The results, however, are consistent up to a fraction of a percent just from 20 000 runs (D13). The random sampling allows us to thoroughly explore the multidimensional input parameter space and account for the uncertainties of the inputs at the same time.

We adapt a Bayesian interpretation of the PDFs of the Monte Carlo simulation. The Bayes chain rule underlies the simulation can be written as:

$$P(M|\vec{D}) \propto P(\vec{D}|M)P(M) \quad (1)$$

where the likelihood is defined to be the PDF of \vec{D} given our physical model M which we parametrize using variables in Table 1 ($\vec{\theta}$). For example, the calculation of the output variables of the j -th realization can be denoted as:

$$(\vec{\theta}')^{(j)} = f(\vec{\theta}^{(j)}, \vec{D}) \quad (2)$$

and computed over all j realizations. Finally, we took the physical constraints on the dynamical variables into account by examining the resulting physical variables against the physical limits and excluding realizations that would produce impossible values. We refer to this process of excluding unphysical realizations as applying priors. Even though

Table 1. Properties of the sampling PDFs of the Monte Carlo simulation

Data	Units	Location	Scale	Ref
$M_{200\text{NW}}$	$10^{14} h_{70}^{-1} M_\odot$	13.0	1.6	J13
c_{NW}		2.50	0.02	J13
$M_{200\text{SE}}$	$10^{14} h_{70}^{-1} M_\odot$	7.6	1.2	J13
c_{SE}		2.70	0.04	J13
z_{NW}		0.86842	0.00109	M12, Sifón 2013
z_{SE}		0.87110	0.00117	M12, Sifón 2013
d_{proj}	Mpc	0.74	0.007	J13

we denote the priors for one dimension at a time (See Appendix A), the correlations between different variables are properly taken into account due to how we throw away all the variables of problematic realizations.

The system of El Gordo satisfies several major assumptions in the Monte Carlo simulation. One of the strongest assumption is that all realizations correspond to gravitationally bound systems. The simulation excludes all realizations that would result in relative collisional velocities of the subclusters higher than the free-fall velocity. The relative escape velocity of the subclusters for El Gordo is 4500 km s^{-1} given the mass estimates of Jee et al. (2014). Studies from cosmological simulations giving the PDFs of the pairwise velocities of massive merging clusters ($> 10^{15} M_\odot$) indicate that it is highly unlikely that the pairwise velocities would $> 3000 \text{ km s}^{-1}$ under ΛCDM . (Thompson & Nagamine 2012, Lee & Komatsu 2010). Other major assumptions for modeling systems with this code include negligible impact parameter. Even though there are studies indicating that the impact parameter of El Gordo may be as large as 300 kpc $\approx 40\% r_s$ (Molnar & Broadhurst 2014), where r_s is the characteristic core radius of the NFW halo with the mass of El Gordo. According to Ricker (1998), the resulting remnant of bimodal cluster mergers would only be different when the impact parameter $> 10 r_{\text{core}}$. ? also reported that an impact parameter of $0.1r_{200}$ affected merger dynamics only at the $\sim 10\%$ level. Other assumptions in this simulation include negligible dynamical friction during the merger, negligible mass accretion and negligible self-interaction of dark matter. Discussion of the effects of each of these assumptions are included in D13.

3.1 Inputs of the Monte Carlo simulation

3.1.1 Membership selection and redshift estimation of subclusters

We adopt the identification of galaxy membership of El Gordo given by M12 with a total count of 89 galaxies. To further distinguish member galaxies of each subcluster, we adopt a redshift cut of $z < 0.886$, and a spatial cut along (01:03:22.0, -49:12:32.9) and (01:02:35.1, -49:18:09.8). The spatial cut is approximately perpendicular to the 2D merger axis and are consistent with the bimodal number density contours (See Figure 2). We determined that there are 51 members in the NW subclusters and 35 members in the SE subclusters. The spatial cut indicated by the black line was done after mapping the world coordinates to pixel coordinates to avoid anamorphic distortion.

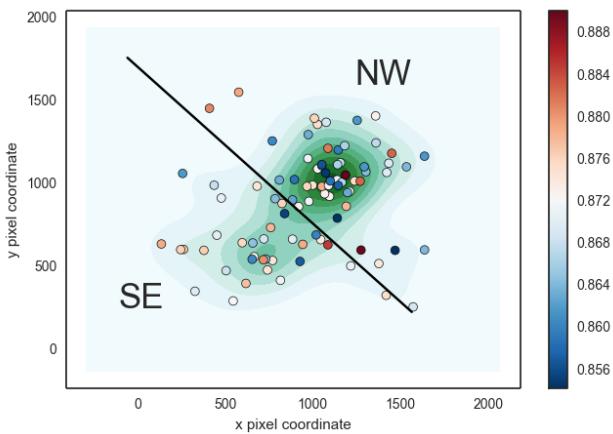


Figure 2. Points showing the locations of the member galaxies and the division of the member galaxies among the two subclusters of El Gordo by a spatial cut (black line). The color of the points shows the corresponding spectroscopic redshift of the member galaxies (see color bar for matching of spectroscopic values), with the redder end indicating higher redshift. The background number density contours in green indicate a bimodal distribution.

After identifying members of each subcluster, we performed 10, 000 bootstrap realizations to estimate the biweight locations of the spectroscopic redshifts of the respective members in order to obtain the samples of the PDFs of the redshifts of each subcluster. The spectroscopic redshift of the subclusters were determined to be $z_{\text{NW}} = 0.86842 \pm 0.0011$ and $z_{\text{SE}} = 0.87131 \pm 0.0012$, where the quoted numbers represent the biweight location and 1σ bias-corrected confidence level respectively (Beers et al. 1990). Both the estimated redshifts of the subclusters and the uncertainties are consistent with estimates of $z = 0.8701 \pm 0.0009$ for El Gordo given by Sifón et al. 2013, and the fact that the member galaxies of El Gordo shows large velocity dispersion and has the largest velocity dispersion among all the ACT galaxy clusters as reported by M12.

We estimated the radial velocity differences of the subclusters by first calculating the velocity of each subcluster with respect to us, using

$$v_i = \left[\frac{(1+z_i)^2 - 1}{(1+z_i)^2 + 1} \right] c \quad (3)$$

where $i = 1, 2$ represents the two subclusters, and c is the speed of light. The radial velocity was calculated by:

$$\Delta v_{\text{rad}}(t_{\text{obs}}) = \frac{|v_2 - v_1|}{1 - \frac{v_1 v_2}{c^2}} \quad (4)$$

Due to the estimates of the subcluster redshifts are close to one another with overlapping confidence intervals, we obtained a low radial velocity difference of the two subclusters to be $476 \pm 242 \text{ km s}^{-1}$. The quoted radial velocity differences of 586 km s^{-1} reported by M12 is higher than our estimates but within the 68% bias-corrected confidence interval. Limitations and possible improvements of this method are provided in the discussion.

3.1.2 Weak lensing mass estimation

We obtained 40, 000 samples of the joint PDFs of the masses of the two dark matter halos as the outputs of the Monte

Carlo Markov Chain (MCMC) procedure from Jee et al. 2014. Discussion of the handling of the weak lensing source galaxies and the details the MCMC procedure for mass estimation can be found in Jee et al. 2014.

3.1.3 Estimation of projected separation (d_{proj})

To be consistent with our MCMC mass inference, our Monte Carlo simulation takes the projected separation of the NFW halos to be those of the inferred DM centroid locations in Jee et al. 2014. We draw random samples of the location of centroids from two 2D Gaussians centered at RA=01:02:50.601, Decl.=−49:15:04.48 for the NW subcluster and RA = 01:02:56.312, Decl. = −49:16:23.15 for the SE subcluster, with a 1" standard deviation each. Or equivalently, the samples of the inferred centroid locations correspond to a projected separation of $0.74 \pm 0.007 \text{ Mpc}$.

3.2 Outputs of the Monte Carlo simulation

We outline the outputs of the simulation here to facilitate the discussion of the design of the priors used in the simulation. The simulation provides PDF estimates for 8 output variables. Variables of the most interest include the time dependence and the angle α , which is defined to be the projection angle between the plane of the sky and the merger axis. Other output variables are dependent on α and the time dependence. Specifically, the simulation denotes the time dependence by providing several characteristic timescales, including the time elapsed between consecutive collisions (T) and the time-since-collision of the observed state (TSC).

We provide two versions of the time-since-collision variables TSC_0 and TSC_1 to denote different possible merger scenarios. 1) We call the scenario for which the subclusters are moving apart after collision to be “outgoing” and it corresponds to the smaller TSC_0 value, and 2) we call the alternative scenario “returning” for which the subclusters are approaching each other after turning around from the apoapsis for the first time and it corresponds to TSC_1 . We describe how we make use of properties of the radio relic to evaluate which scenario is more likely in section ???. Evolution of the merger after the second passage is not considered.

The simulation also output estimates of variables that describe the dynamics and the characteristic distances of the merger. The relative 3D velocities of the subclusters, both at the time of the collision ($v_{3D}(t_{\text{col}})$) and at the time of observation ($v_{3D}(t_{\text{obs}})$) are provided. The characteristic distances included in the outputs are the maximum 3D separation (d_{max}), which is the distance between the position of collision to the apoapsis and the 3D separation of the subclusters at observation (d_{3D}).

3.3 Design and application of priors

One of the biggest strengths of the Monte Carlo simulation by D13 is its ability to detect and rule out extreme input values that would result in unphysical realizations via the application of prior probability. Our default priors are described in D13 and we include them in Appendix B for the convenience of the readers. In addition, we have come up

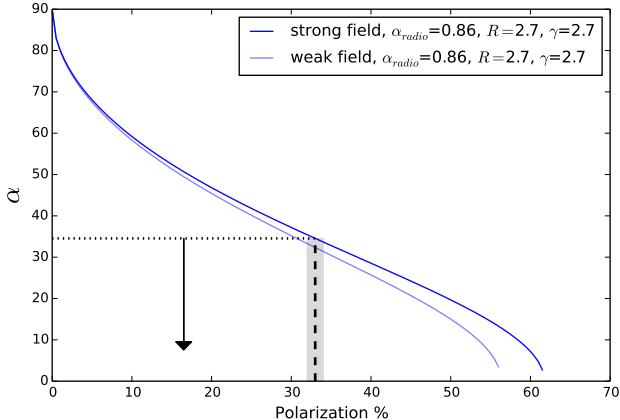


Figure 3. Predictions of polarization percentage of the radio relic at a given projection angle from different models, reproduced from Ensslin et al. 1998. Each model assumes electrons producing the radio emission to be accelerated inside uniform magnetic field of various strengths (*strong* or *weak*). The curves are plotted with spectral index of the radio emission (α_{radio}), spectral index of the electrons (γ) and compression ratio of the magnetic field (R) corresponding to the estimated values from Lindner et al. (2014). We highlight the observed polarization percentage of the main NW radio relic of El Gordo by the dotted vertical line with the greyed out region indicating the uncertainty (Lindner et al. 2014).

with a prior on the projection angle α based on the polarization fraction of the radio relic.

3.3.1 Monte Carlo prior based on the polarization fraction of the radio relic

We can relate the polarization fraction of the radio relic to the projection angle by examining the generating mechanism of the radio relic. The observed radio relic is due to synchrotron emission of free electrons in a magnetic field. If the magnetic field is uniform, the observed polarization fraction of the synchrotron emission of the electrons depends on the viewing angle (or equivalently the projection angle) with respect to the alignment of the magnetic field. Synchrotron emission from electrons inside unorganized magnetic field are randomly polarized. The high reported integrated polarization fraction from Lindner et al. (2014) can be explained by a highly aligned magnetic field, created by the compressed intracluster medium during a merger (Ensslin et al. 1998, van Weeren et al. 2010, Feretti et al. 2012). This picture is consistent with a high polarization fraction perpendicular to this magnetic field along the relic.

We designed our prior to reflect how α decreases monotonically as the maximum observable integrated polarization fraction. This assumption is based on the class of models given by Ensslin et al. (1998) (See Figure 3). In particular, we refer to a model from Ensslin et al. (1998) that would give the most conservative estimate on the upper bound of α :

$$\alpha = 90^\circ - \arcsin \left(\sqrt{\frac{\frac{2}{15} \frac{13R-7}{R-1} \frac{\gamma+7/3}{\gamma+1} \langle P_{strong} \rangle}{1 + \frac{\gamma+7/3}{\gamma+1} \langle P_{strong} \rangle}} \right) \quad (5)$$

This model corresponds to the strong field case with the relic being supported by magnetic pressure only, with

$\alpha_{radio} = 0.86$, compression ratio $R = 2.7$ and $\gamma = 2.7$. This model predicts a maximum integrated polarization fraction of $\sim 60\%$ when $\alpha \rightarrow 0$. From this model, the observed integrated polarization fraction of $33\% \pm 1\%$ corresponds to an estimated value of $\hat{\alpha} = 35^\circ$. This polarization fraction of $\sim 60\%$ predicted by (Ensslin et al. 1998) is consistent with the upper bound of relic polarization fraction in cosmological simulations (Skillman et al. 2013). No other model of the magnetic field should predict a higher polarization fraction, thus it is highly unlikely that we see 33% integrated polarization at $\alpha > 35^\circ$.

We cannot rule out $\alpha \leq 35^\circ$ as a result of possible variations in the magnetic field. Ensslin et al. (1998) assumes an isotropic distribution of electrons in an isotropic magnetic field. Cosmological simulations of radio relics from Skillman et al. (2013) show varying polarization fraction across and along the relic assuming $\alpha = 0$, resulting in a lower integrated polarization fraction. For example, it is possible to see a edge-on radio relic ($\alpha = 0$) with integrated polarization fraction of 33% . Furthermore, Skillman et al. (2013) shows that after convolving the simulated polarization signal with a Gaussian kernel of $4'$ to illustrate effects of non-zero beam size, the polarization fraction drops to between 30% to 65% even when $\alpha = 0$. Other uncertainties come from the fact that the inferred spectral indices differ between the two observed frequencies and vary between the three identified relic sources (Lindner et al. 2014). We examine the effects of changing the cutoff value of this prior to ensure the uncertainties do not introduce significant bias in the estimated output variables and we present the results in Appendix B. To summarize, we adopt a conservative uniform prior to encapsulate the information from the polarization fraction of the radio relic as:

$$P(\alpha) = \begin{cases} \text{const.} > 0 \text{ for } \alpha < 35^\circ \\ 0 \text{ otherwise} \end{cases} \quad (6)$$

We refer to 6 as the polarization prior. Unless otherwise stated, the main results of the paper are obtained after applying this polarization prior in addition to the default priors.

3.4 Extension to the Monte Carlo simulation - Determining merger scenario with radio relic position by model comparison

One of the biggest question involving the merger is if El Gordo was observed to be in a returning or outgoing phase. We performed a Bayesian model comparison of the observed and the simulated position of the NW radio relic in each scenario. We considered different possibilities of the time evolution of the merger shock. We drew physical insight from the simulations of the merger shock of the cosmological simulation from Paul et al. (2011) and a similar cluster merger of CIZA J2242.8+5301 (van Weeren et al. 2011). Right after the collision of the subclusters, both Paul et al. (2011) and van Weeren et al. (2011) showed that merger shock fronts that corresponds to the radio relics 1) are generated close to the center of the substructure, 2) propagated outwards with the shock speed decreases only slightly (between 10% to 30% via private communication with Paul S.) as the shock propagates away from the center of mass.

We make use of the reported shock speed and uncertainties from Lindner et al. (2014) to calculate how far the shock would have propagated for our inferred TSC_0 and TSC_1 values. We worked in the center of mass frame where the shock speed is expected to drop slightly with TSC. The projected separation of the shock is approximated as:

$$s_{proj} = \langle v_{relic} \rangle (\hat{t}_{obs} - \hat{t}_{col}) \quad (7)$$

where the quantities with hats on the right hand side of the equations were inferred from the simulation, and s_{proj} is the estimated projected separation and we estimated the upper and lower bounds of the time-averaged velocity $\langle v_{relic} \rangle$ of the shock between the collision of the subclusters and the observed time as:

$$\langle v_{relic} \rangle = \beta v_{3D,1}(t_{col}) \quad (8)$$

where $0.5 \leq \beta \leq 1.5$ is a factor that we introduce to represent the uncertainty of the velocity of the relic shockwave and $v_{3D,1}(t_{col})$ refers to the collisional velocity of the NW relic in the center-of-mass frame as a comparison.

4 RESULTS

We found that the two subclusters collided at with a relative velocity of 2400 ± 400 km s $^{-1}$, at an estimated projection angle of $\alpha = 21^\circ \pm 11^\circ$. From our analysis of the two scenarios, we found that El Gordo is more likely to be observed at a returning phase with a estimate of $TSC_1 = 0.91 \pm 0.39$ Gyr. We present an overview of all the estimated variables in table 2, with results only applying the default priors on the left hand side of the table and those applied with the polarization prior on the right hand side. Furthermore, we include the plots of all the marginalized PDFs with the polarization prior in Appendix B.

Our estimates of $v_{3D}(t_{col}) = 2400 \pm 400$ km s $^{-1}$ at the time of collision is compatible with independent estimates from Lindner et al. 2014. By making use of the upstream velocity of the shockwave, Lindner et al. (2014) inferred the upper bound of the relative collisional velocity from the Mach number of the NW radio relic, giving an estimate of 2500 ± 400 km s $^{-1}$. Since the radio relic leads the NW subcluster, the shock velocity can be viewed as an upper bound the relative velocities of the subcluster at collision. Magnitude of the relative v_{3D} of the subclusters drops as the subclusters climb out of the gravitational potential of each other, and reduced to $v_{3D}(t_{obs}) = 940$ km s $^{-1}$ at the time of observation.

4.1 Time-since-collision (TSC) and the merger scenario

(PLEASE SKIP THIS SECTION, I need to amend the figure by replacing the shock speed with the actual estimates from Lindner et al. instead of using our simulated speed) Comparison of the estimate of the location of the radio relic in the outgoing and returning scenario favors the returning scenario. The simulation gives two estimates for the time-since-collision, with $TSC_0 = 0.61$ Gyr and $TSC_1 = 1.0$ Gyr. Based on section ??/(cite cite cite), we present estimates for the position of the NW radio relic based on the two PDFs of inferred TSC as shown in Fig. 4. We plotted the

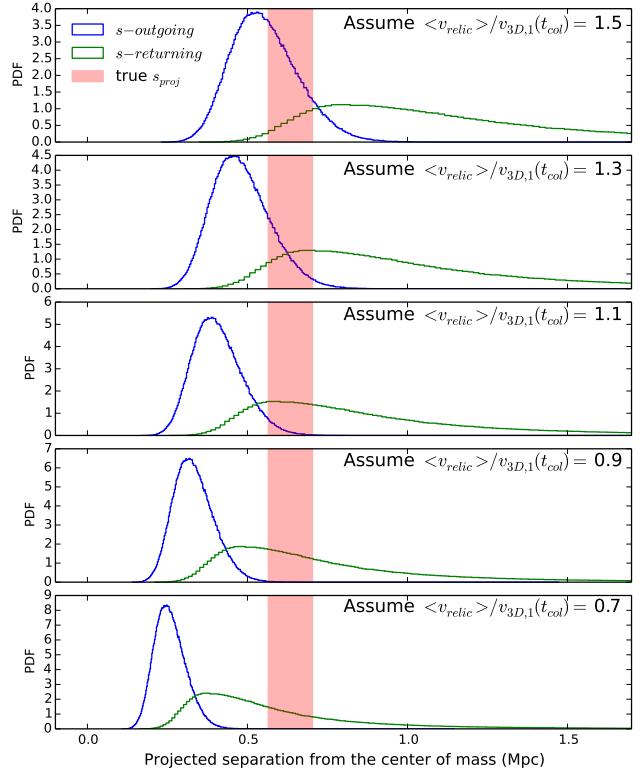


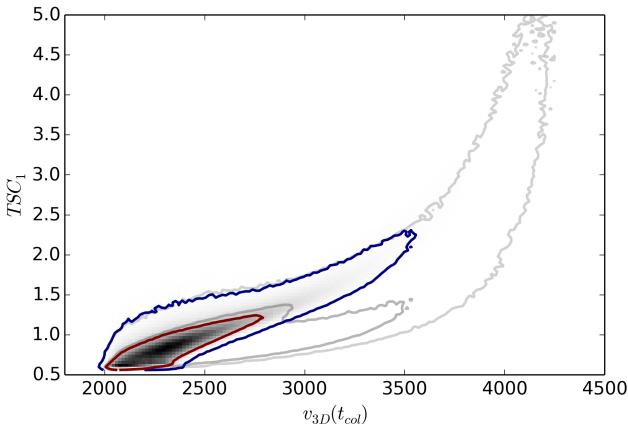
Figure 4. Comparison of the PDFs of the observed position of the relic (red bar includes 95% confidence interval of location of relic in the center of mass frame) with the predicted position from the two simulated merger scenarios (blue for outgoing and green for the returning scenario). The outgoing scenario is more favored than the returning scenario since the shock speed is unlikely to travel at much less than $1.1 v_{3D,1}(t_{col})$ for a significant period of time. We made use of the polarization prior for this figure.

PDF of the simulated positions of the relic for the outgoing scenario (blue) and the returning scenario (green) against the observed position of the relic (light red), with the width of the relic representing the 95% confidence interval, this uncertainty is greater than the width of the relic (~ 23 kpc) along merger axis (Lindner et al. 2014). When we assume $\langle v_{relic} \rangle / v_{3D,1}(t_{col}) = 1.5$ (uppermost panel of Figure 4), $\langle v_{relic} \rangle$ corresponds to an time-averaged relative velocity of ~ 3800 km s $^{-1}$ or, in the center of mass frame ~ 1400 km s $^{-1}$, the outgoing scenario is more favored. As we examine a decreased ratio of $\langle v_{relic} \rangle / v_{3D,1}(t_{col})$, we probe how much the shock could have slowed down and still be consistent with the outgoing scenario. The second (relative velocity of 2800 km s $^{-1}$) and third row of Fig. 4 show that if $\langle v_{relic} \rangle \lesssim 1.1$, the returning scenario would be favored instead. Estimates of Lindner et al. (2014) of the shock velocity corresponds to 2500 ± 400 km s $^{-1}$.

Both the estimates of TSC_0 and TSC_1 are compatible physical time-scales of observable features of El Gordo. Both estimates are lower than the sound crossing time of ~ 2 Gyr, which can be considered for which the wake feature can be observed. The observable time scale of the radio relics are also on the scale of ~ 1 Gyr. A definite conclusion about the best fit scenario would require better knowledge of the time evolution of the shock velocities.

Table 2. Table of the output PDF properties of the model variables and output variables from Monte Carlo simulation

Variables	Units	Default priors			Default + polarization priors		
		Location	68% CI [†]	95% CI	Location	68% CI	95% CI
α	(degree)	43	19-69	6-80	21	10-30	3-34
d_{max}	Mpc	1.2	0.9-2.2	0.77-4.6	0.93	0.81-1.2	0.75-1.9
d_{3D}	Mpc	1	0.79-2.1	0.75-4.3	0.8	0.76-0.88	0.74-0.91
TSC_0	Gyr	0.61	0.4-0.95	0.26-2.4	0.46	0.3-0.55	0.21-0.64
TSC_1	Gyr	1	0.77-1.7	0.63-4.4	0.91	0.69-1.3	0.59-2.3
T	Gyr	1.6	1.3-2.6	1.2-7.1	1.4	1.2-1.6	1.2-2.4
$v_{3D}(t_{obs})$	km s ⁻¹	580	260-1200	59-2400	940	360-1800	62-2900
$v_{rad}(t_{obs})$	km s ⁻¹	360	140-630	27-880	310	110-590	8-840
$v_{3D}(t_{col})$	km s ⁻¹	2800	2400-3700	2100-4200	2400	2200-2800	2100-3500

[†] CI stands for credible interval

Figure 5. The marginalized output PDF of the returning time-since-collision (TSC_1) vs. the 3D velocity at the time of collision for El Gordo. The grey set of contours show the credible regions before applying the polarization prior and the colored contours correspond to the credible regions after applying the priors. The contours represents the 95% and 68% credible regions respectively.

4.2 Sensitivity analysis of the polarization prior

We performed tests of how each of the output variables vary according to the choice of the cutoff of the polarization prior between $\alpha_{\text{cutoff}} = 29^\circ$ to 49° instead of 35° . We found that in the most extreme case, choosing the cutoff values as 29° (-6°), the location of the $v_{3D}(t_{obs})$, is increased by 16%. While the 95% CI of d_{max} is the most sensitive to the prior and it changes by $\sim 20\%$ when $\alpha_{\text{cutoff}} = 49^\circ$. This shows that the exact choice of the cut off value for α for the polarization prior does not change our estimates drastically.

5 DISCUSSION

5.1 Our finding in the context of other studies of El Gordo

We outline the qualitative agreement and disagreement between our simulations and other hydrodynamical simulations of El Gordo such as Donnert (2014) and Molnar & Broadhurst (2014). Our simulation focuses on giving PDF estimates of particular dynamical and kinematic variables,

whereas the hydrodynamical simulations focused on understanding the detailed gas dynamics and the corresponding X-ray observables of El Gordo. The goals, assumptions, and initial conditions of Donnert (2014) and Molnar & Broadhurst (2014) are different from our simulations such that detailed comparisons may not be meaningful. For example, both hydrodynamical simulations were based on a few sets of initial conditions, instead of a thorough sampling of the inputs. The outputs of the hydrodynamical simulations are unable to convey uncertainties due to the inputs. Both hydrodynamical simulations made use of a higher $m_{NW} = 1.9 \times 10^{15} M_\odot$ which is larger than the upper 95% CI of m_{NW} that we used. Furthermore, Molnar & Broadhurst (2014) initialized the relative infall velocity (velocity when separation of subclusters equal the sum of the two virial radii) to be > 2250 km s⁻¹. This corresponds to $v_{3D}(t_{col}) \gtrsim 4700$ km s⁻¹, which is close to the velocity required for the system not to be gravitationally bound. The range of projection angles suggested by Molnar & Broadhurst (2014) of $\alpha \gtrsim 45^\circ$ are also excluded by our polarization prior. On the other hand, our simulations show qualitative agreement with Donnert (2014) on the duration between consecutive core-passages. With the time resolution of 25 Myr, the simulation from Donnert (2014) gave an qualitative estimate of $T \approx 2$ Gyr between the first and second core-passage in Fig. 6, while our estimate gives $T = 1.6$ Gyr. A better comparison to the hydrodynamical simulations may be achieved by performing Gaussian process emulation to obtain outputs with more similar inputs as our simulations, but the work of fair, detailed comparison is out of the scope of this paper.

5.2 Comparison to other merging clusters of galaxies

Dynamical properties of El Gordo are more similar to the Bullet Cluster (cite cite) than the Musketball Cluster (Dawson et al. (2012), D13). Both the Bullet Cluster and the Musketball were studied by D13 using the Monte Carlo simulation. In addition to the default prior, D13 applied a temporal prior based on the observed X-ray luminosity boost for the Bullet Cluster, while only the default priors were suitable to be applied for the Musketball. Therefore, with the additional priors, both the Bullet Cluster and El Gordo show a more constrained parameter space. The three output variables that we compare among the listed clusters include

TSC, v_{3D} and the masses. These variables can affect how strongly the self-interaction of dark matter would manifest itself in case the DM self-interaction cross section is not zero. A higher *TSC* might allow more time for DM to interact with itself; a higher v_{3D} might and a higher mass would correspond to higher central density for a higher self-interaction rate. Although El Gordo is the most massive among the listed clusters, the higher mass did not result in a higher $v_{3D}(t_{col})$. The estimate of $v_{3D}(t_{col}) = 2400 \text{ km s}^{-1}$ is comparable to the inferred $v_{3D}(t_{col}) = 2800 \text{ km s}^{-1}$ of the Bullet Cluster. Both the phase $TSC_0 \approx 40\% T$ and the $TSC_0 = 0.6Gyr$ are similar between El Gordo and the Bullet Cluster. It is remained to be investigated if our hypothesis about the relationship between how these variables would affect our chance of seeing effects from self-interaction of dark matter.

5.3 Limitations of our data analysis and future work

We note that our method of inferring the 3D velocities by deprojecting the radial velocities might not be optimal but is commonly used (M12, Dawson et al. 2012). The relative radial velocities are dependent on the identification subcluster members. However, it is unclear that a spatial cut according to number density peaks would be optimal for selecting galaxies that represent the underlying velocities of the sub-clusters. Traditionally, grouping members may be treated as a (statistical) clustering problem with well known methods such as normal mixture model. However, our setting is complicated by the fact that each of the observed redshifts of galaxies is an unknown combination of cosmological redshift and redshift due to peculiar motion along the line-of-sight. Our study only make use of a limited galaxies with spectroscopic members. This could cause selection bias and incompleteness due to limitations of the of spectroscopic targets. Existing literature and tests mostly focus on detecting substructures in galaxy clusters through non-Gaussianity of the velocity dispersion (Dressler, Einasto). Few extensive studies have focused on finding out the uncertainties associated with this clustering procedure for inferring the dynamics of merging clusters. This problem presents an interesting direction for investigation in the future.

Despite the limitations and simplifying assumptions, this work provides insight to the merger dynamics and configuration of El Gordo as a basis for further studies. Tests for signs of self-interaction of DM in El Gordo can be done by comparing the offset between the member galaxies and the DM distribution of the subclusters. By understanding the merging scenario, we can infer if the observed galaxy-DM offset are in the expected direction such that the collisionless galaxies lead the DM subhalos along the direction of motion. In addition, our work has allowed us to examine what information would be needed to better understanding of the merger dynamics. Important pending questions concerning the radio relic and the merger include: What are the typical propagation velocities of the shockwave that corresponds to the radio relic in the center of mass frame of the cluster? What physical properties of the DM sub-clusters would correlate the best with the time-evolution of the propagation velocity of the shockwave? What are the duration after merger for which radio relics are observable

in terms of the merger oscillation time-scales? Answers to these questions may become available as more analysis tools get developed to extract observables from cosmological and hydrodynamical after overcoming resolution issues.

This paper presents one of the first examples of using the observed radio relic emission to constrain cluster merger properties. As a summary, our simulation of El Gordo:

- (i) favors the estimate of a small projection angle
- (ii) shows a low observed radial velocity and collisional velocity of El Gordo given its high mass
- (iii) predicts an outgoing scenario if the time-averaged merger shock velocity in the center of mass frame is $> 2800 \text{ km s}^{-1}$ between the collision and the observation.

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APPENDIX A: BAYESIAN PRIORS USED FOR DAWSON'S MONTE CARLO SIMULATION

The default prior probabilities that we employed can be summarized as follows for most of the output variables:

$$P(v_{3D}(t_{col})|\alpha, v_{proj}(t_{col})) = 0 \text{ if } v_{3D}(t_{col}) > v_{\text{free fall}} \quad (\text{A1})$$

$$P(TSC_0) = \begin{cases} \text{const if } TSC_0 < \text{age of universe at } z = 0.87 \\ 0 \text{ otherwise} \end{cases} \quad (\text{A2})$$

In addition, we apply the following prior on TSC_1 only when evaluating the statistics of TSC_1 , thus allowing realizations with a valid outgoing TSC but an invalid returning TSC_1 .

$$P(TSC_1) = \begin{cases} \text{const if } TSC_1 < \text{age of universe at } z = 0.87 \\ 0 \text{ otherwise} \end{cases} \quad (\text{A3})$$

To correct for observational limitations, we further convolve the posterior probabilities of the different realizations with

$$P(TSC_0|T) = 2 \frac{TSC_0}{T} \quad (\text{A4})$$

to account for how the subclusters move faster at lower TSC and thus it is more probable to observe the subclusters at a stage with a larger TSC .

APPENDIX B: PLOTS OF OUTPUTS OF THE MONTE CARLO SIMULATION

We present the PDFs of the inputs of the dynamical simulation and the marginalized PDFs of the outputs after applying the polarization prior in addition to the default priors. The 5-dimensional input parameter space and the 9-dimensional output parameter space are presented according to the different categories. (FIGURE TO BE ADDED SHOWING THE SPATIAL LOCATIONS OF THOSE PLOTS)

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by the author.

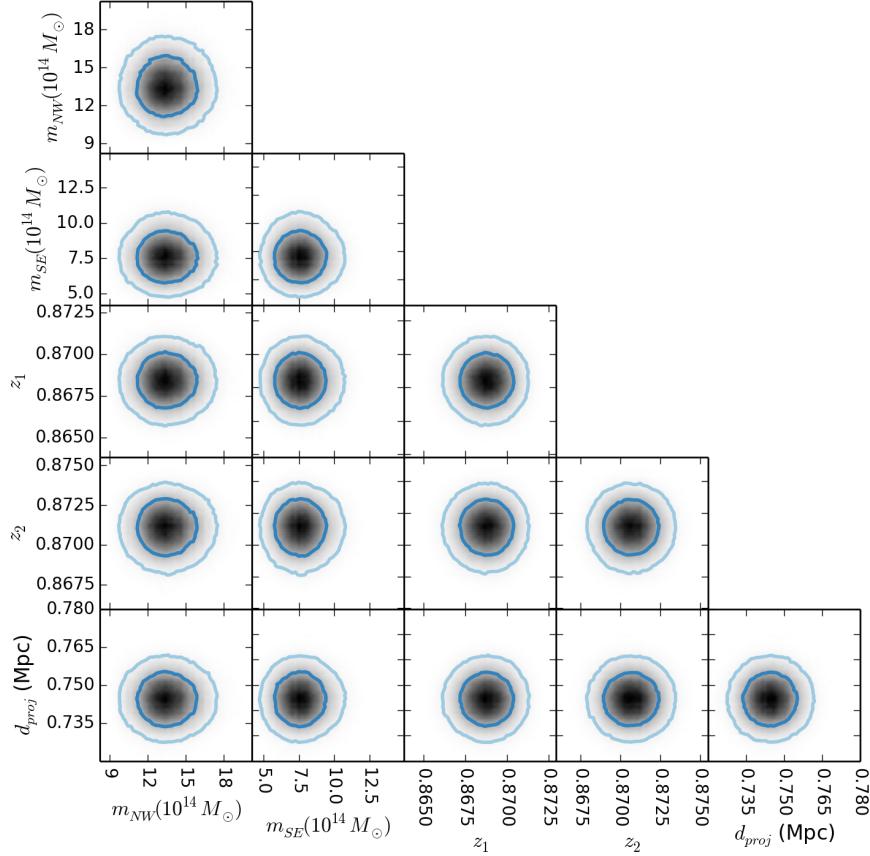


Figure B1. Marginalized PDFs of original inputs (vertical axis) and the inputs after applying polarization prior and default priors (horizontal axis). The inner and outer contour denote the central 68% and 95% credible regions respectively. The circular contours show that the application of priors did not introduce uneven sampling of inputs.

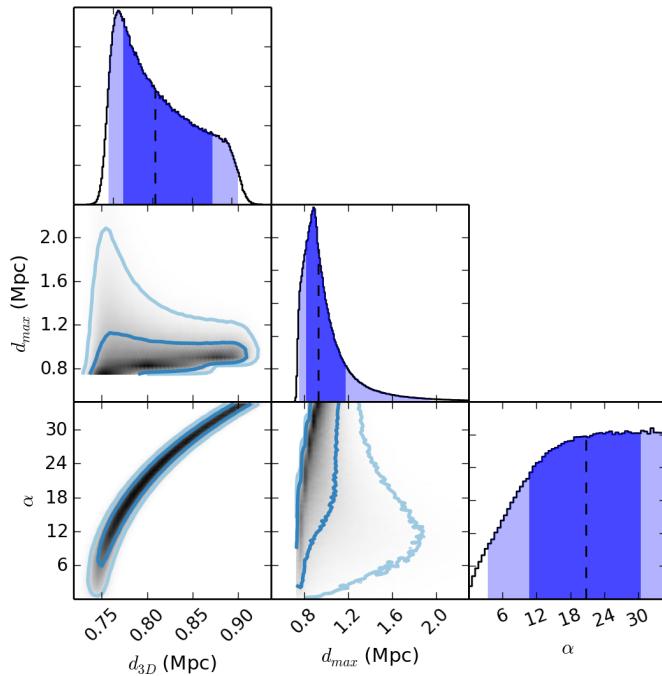


Figure B2. One-dimensional marginalized PDFs (panels on the diagonal) and two-dimensional marginalized PDFs of variables denoting characteristic distances and projection angle of the mergers.

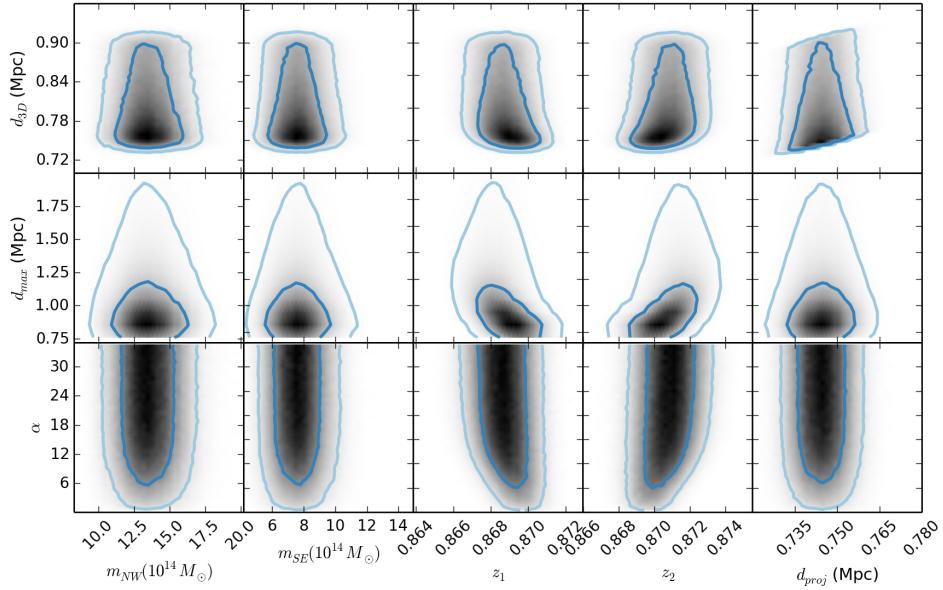


Figure B3. Marginalized PDFs of characteristic distances and projection angle of the merger and the inputs of the simulation.

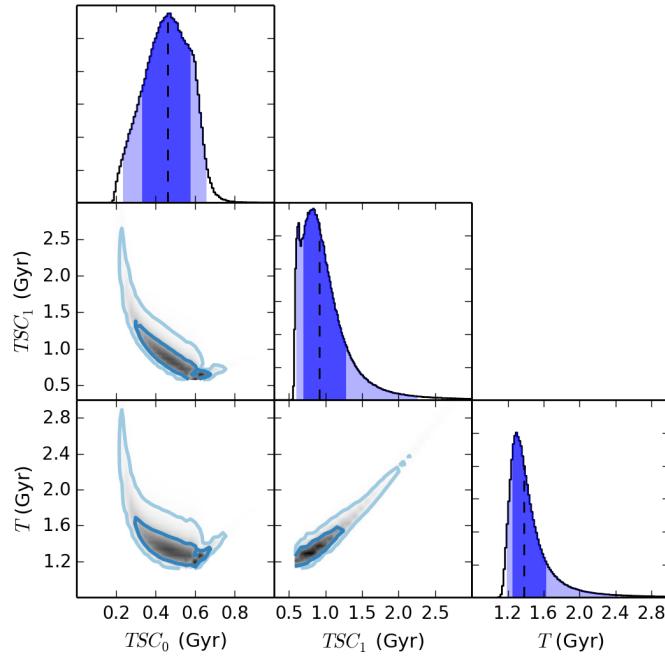


Figure B4. One-dimensional PDFs of characteristic timescales of the simulation (panels on the diagonal) and the marginalized PDFs of different timescales.

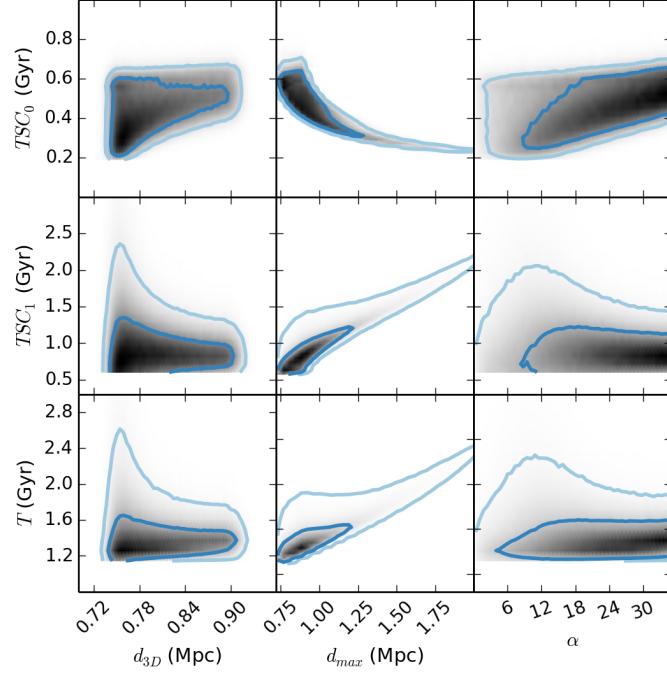


Figure B5. Marginalized PDFs of characteristic timescales of the simulation and the characteristic distances and the projection angle of the merger.

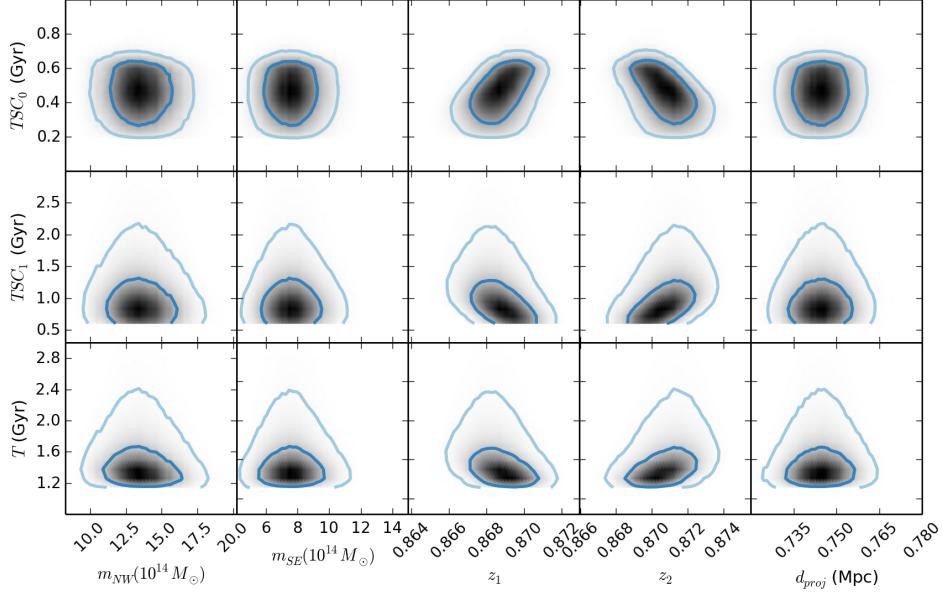


Figure B6. Marginalized PDFs of characteristic timescales of the simulation and the inputs.

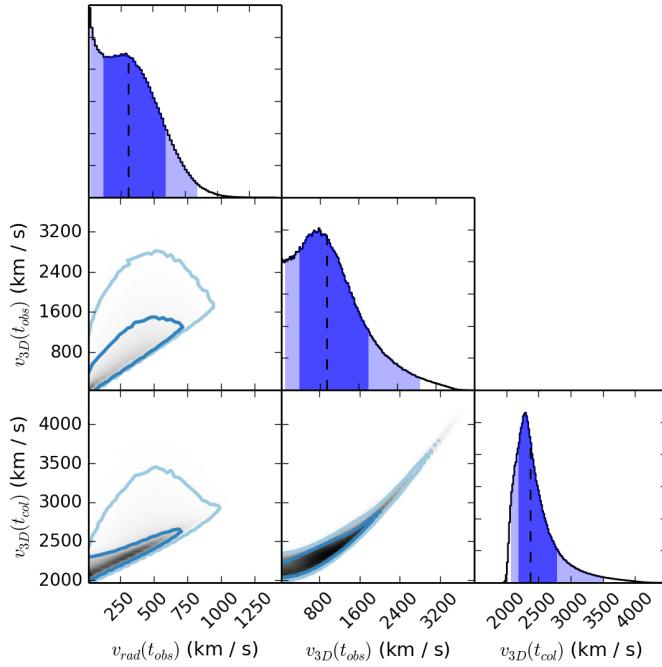


Figure B7. One-dimensional marginalized PDFs of velocities at characteristic times (panels on the diagonal) and marginalized PDFs of different velocities.

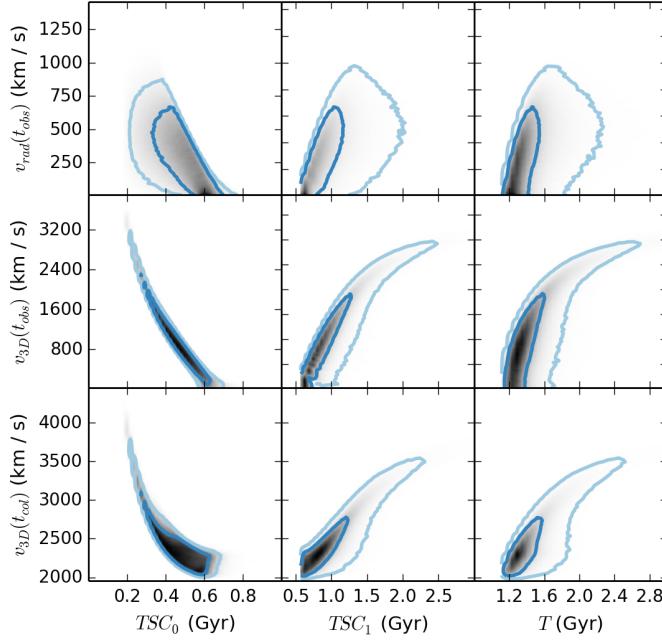


Figure B8. Marginalized PDFs velocities and the characteristic timescales of the simulation against the inputs.

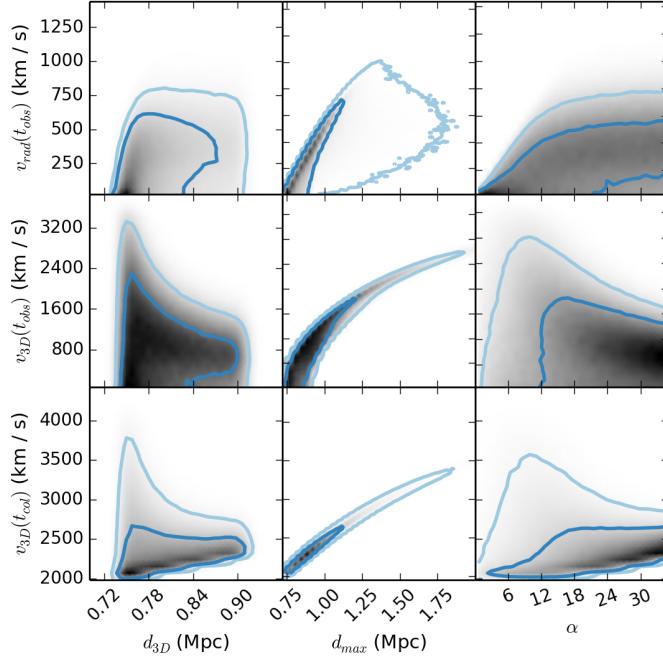


Figure B9. Marginalized PDFs of the velocities at characteristic timescales and the characteristic distances and the projection angle of the merger.

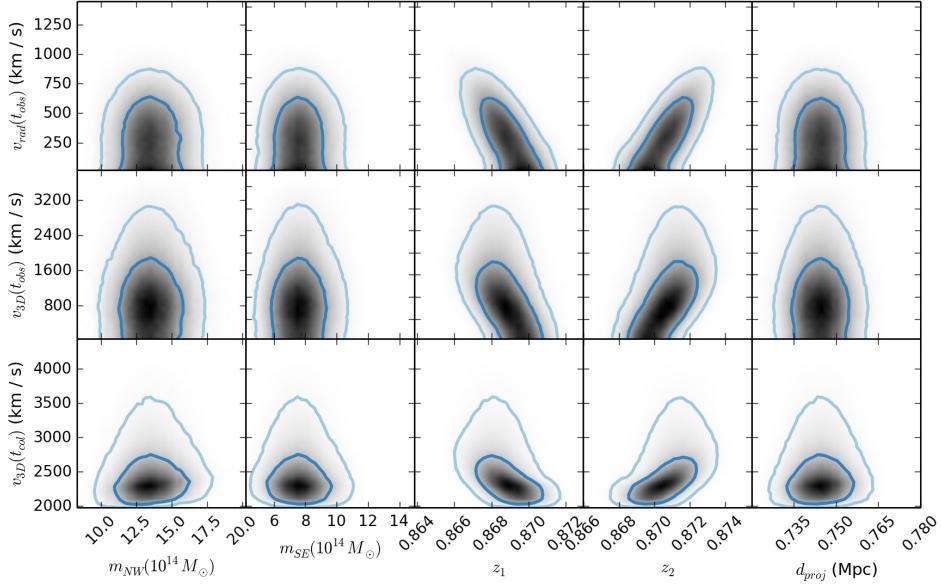


Figure B10. Marginalized PDFs of relative velocities characteristic timescales of the simulation and the inputs.