

Bessel Functions

→ solutions of Bessel's differential equation:

$$x^2 \frac{d^2 y}{dx^2} + x \frac{dy}{dx} + (x^2 - \alpha^2)y = 0$$

arbitrary complex number α
(called the order of the solution Bessel equations/functions)

→ solutions do not have "closed form" solutions involving only elementary functions

α integer → cylindrical Bessel functions

appear in solution to Laplace's equation in cylindrical form

first kind J_α ← order α

→ finite at the origin $x=0$ for integer or positive α

→ diverge as $x \rightarrow 0$ for negative, non-integer α

may be defined by series expansion around $x=0$:

$$J_\alpha(x) = \sum_{m=0}^{\infty} \frac{(-1)^m}{m! \Gamma(m+\alpha+1)} \left(\frac{x}{2}\right)^{2m+\alpha}$$

gamma function

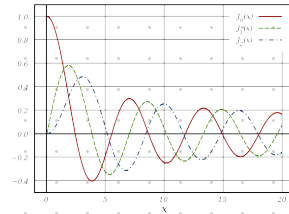
Bessel's integrals:

$$J_n(x) = \frac{1}{2\pi} \int_{-\pi}^{+\pi} e^{i(x \sin \tau - n\tau)} d\tau$$

real

$$J_n(x) = \frac{1}{\pi} \int_0^\pi \cos(n\tau - x \sin \tau) d\tau$$

Bessel plots look like decaying sine/cosine functions → proportionally to $x^{-0.5}$



(always well behaved)

plot for integer orders $\alpha = 0, 1, 2$

Second kind Y_α (singular solution)

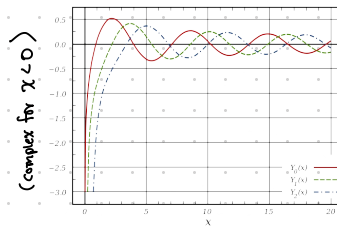
→ have a singularity at the origin $x=0$

for non-integer α : $Y_\alpha \rightarrow \infty$ as $x \rightarrow 0$

$$Y_\alpha(x) = \frac{J_\alpha(x) \cos(\alpha\pi) - J_{-\alpha}(x)}{\sin(\alpha\pi)}$$

for integer order n , function defined by taking limit as a non-integer $\alpha \rightarrow n$

$$Y_n(x) = \lim_{\alpha \rightarrow n} Y_\alpha(x)$$



plot of second kind for integer orders $\alpha = 0, 1, 2$

Fourier Expansion / Series (watch 3b1b video on Fourier Series)

we may write any periodic function as an infinite weighted sum of sinusoids

Consider a real-valued function $s(x)$, integrable on an interval of length P , which is also the period of the function. The n^{th} harmonic frequency is given by:

each term in the sum:

$$c_n e^{\frac{i \cdot n 2\pi x}{P}} = \underbrace{\left(\text{initial size + direction of each rotating vector} \right)}_{c_n} \exp \left[\underbrace{\left(\text{rotation frequency} \right)}_{\frac{n 2\pi}{P} \equiv k} i x \right]$$

$\nearrow \frac{n 2\pi}{P}$
 \searrow n^{th} rotation frequency

the Fourier series (in complex form) is given by:

$$S_N(x) = \sum_{n=-N}^{+N} c_n e^{i \cdot 2\pi n x / P}$$

and the coefficients are given by:

$$c_n = \begin{cases} A_0/2 & = a_0/2 & n=0 \\ \frac{A_n}{2} e^{-i\varphi_n} & = 1/2 (a_n - i b_n) & n > 0 \\ c_{n1}^* & & n < 0 \end{cases}$$

we know $s(x)$ is real so

$$c_n = c_{-n}^* \quad \leftarrow \text{complex conjugate}$$

$$c_n = \frac{1}{P} \int_P s(x) \cdot e^{-i 2\pi n x / P} dx$$

we also know that all coefficients will be real-valued, because the starting complex "vectors" lie in a one-dimensional line (real) in the complex (output) plane.

* need to figure out why the Fourier formulation of eg. 3.7 is missing a factor of 2 in the exponential

domain is of size $2L$ ($-L \leq x \leq L$)
so the 2 cancels w the 2π

DISCRETE / FAST FOURIER TRANSFORM (notes from §5.1 numerical methods book)

DISCRETE → see 3016 video

N data points $\vec{y} = [y_0, y_1, \dots, y_{N-1}] \rightarrow$ evenly spaced in time, so $t_j = \tau j$

Sampling interval τ
where $j = 0, \dots, N-1$
 N points
(spatial/time index)

DISCRETE TRANSFORM

$$Y_k = \sum_{j=0}^{N-1} y_j e^{-2\pi i j k / N}$$

where $k = 0, \dots, N-1$
(frequency index)
(see p. 120 for coefficients)

each point of the transform has an associated frequency:

$$f_k = \frac{k}{\tau N}$$

+1 (zero-frequency)
 $N/2$ frequencies
(Hz)
get a total of $N/2 + 1$ frequencies from transform

- measure long time series to extract low frequencies
- measure small τ for large frequencies

LOWEST $\rightarrow f_1 = \frac{1}{\tau N} = \frac{1}{\tau}$
time series length

HIGHEST $\rightarrow f_{N-1} \approx \frac{1}{\tau}$

$$\mathbb{R} \rightarrow \mathbb{C}$$

The Fourier transform, transforms a function



ALIASING and NYQUIST

ALIASING \rightarrow the effect when functions / signals of different frequencies become indistinguishable when sampled

due to the above, there is maximum frequency for which we may resolve for a sampling interval τ

NYQUIST frequency $\rightarrow f_{Ny} = \frac{1}{2\tau}$ ← the Fourier transform may be truncated at this upper bound for accurate results

* one-half of sampling rate *

SAMPLING RATE: $\frac{1}{\tau} \left[\frac{\text{samples}}{\text{sec}} \right] = [\text{sec}^{-1}]$ (for time series data)

everything past the Nyquist frequency will be mirrored

NOTE:

SERIES

represents periodic function by a discrete sum of complex exponentials

TRANSFORM

represents a general non-periodic function by continuous superposition or integral of complex exponentials

FAST FOURIER TRANSFORM (FFT)

→ the number of operations for the discrete transform is $O(N^2)$

$O(N)$ for one k

need to sum over all $k = 0, \dots, N-1$

FFT computes the transform in an efficient order such that the number of operations is reduced to $O(N \log_2 N)$

→ most efficient for $N = 2^n$

(when the number of sampled points is a power of 2)

FFT - Based Differentiation (notes from Johnson, MIT 2011, writeup)

Consider a periodic function $y(x)$ w/ period L and write as Fourier series:

$$y(x) = \sum_{k=-\infty}^{\infty} Y_k e^{\frac{2\pi i}{L} k x}$$

coefficients

$$Y_k = \frac{1}{L} \int_0^L e^{-\frac{2\pi i}{L} k x} y(x) dx$$

(continuous Fourier transform)

Differentiation is performed term by term in Fourier domain:

$$\frac{d}{dx} y(x) = y'(x) = \sum_{k=-\infty}^{\infty} \left(\frac{2\pi i}{L} k \cdot Y_k \right) e^{\frac{2\pi i}{L} k x}$$

(note that this is not always valid, but is valid for a general $y(x)$ in PDE applications)

simply multiplication of coefficients Y_k by a $\frac{2\pi i}{L} k$ term

* approximate the Fourier series for Y_k by a discrete Fourier transform (or a fast Fourier transform)

the function $y(x)$ is replaced by N discrete samples $y_n = y\left(\frac{nL}{N}\right)$, $n \in \mathbb{Z}^+$

sample number \uparrow # of samples

$$Y_k = \frac{1}{N} \sum_{n=0}^{N-1} y_n e^{-\frac{2\pi i}{N} n k}$$

now, all we need to do is sample $y(x)$ to obtain y_n for a given number of n , N and the derivative may be computed

ZERO-PADDING Technique (notes from <https://www.bitweenie.com/listings/fft-zero-padding/>)

great general resource



<https://www.youtube.com/watch?v=NCZG-jk3FCs>

(good overview of DFT and zero-padding)

2 examples

→ adding zeros to the end of an input prior to computing transform

FFT Resolution

* these two are identical w/o zero-padding *

WAVEFORM FREQUENCY RESOLUTION

minimum spacing between 2 frequencies that may be resolved

$$\Delta R = \frac{1}{T}$$

time length of data signal

do not include zero padding time here!
(only actual data signals)

the same effect is observed when input is sine interpolated

(see zero-padding theorem)

FFT RESOLUTION

number of points in the spectrum
→ directly proportional to # of points used in the FFT

$$\Delta R = \frac{f_s}{N_{fft}}$$

source and/or sample frequency

number of points in spectrum

increases w/ zero padding

how many Hz each DFT bin represents

decreases w/ zero-padding

FFT resolution increases when input fraction is zero-padded

NOTE: normalize with original N of the signal, not the number of points after zero padding

NOTE that when zero-padding an input, we are not adding any new information to the signal.

→ therefore, we can increase the resolution of the FT but not the precision

of frequencies resolved

be careful in interpreting the transform

* Essentially zero-padding is a computationally efficient method of interpolating a large number of points and mitigate against aliasing error and/or bring number of points to a power of 2 for FFT algorithm efficiency.

Trapezium rule (integration) * notes from numerical methods book § 10.2 *

Consider the integral:

$$I = \int_a^b f(x) dx$$

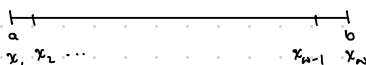
evaluate $f(x)$ at few points \rightarrow Fit simple curve through points (eg. piecewise linear) \rightarrow Estimate area

①

②

③

① Divide interval $[a, b]$ into $N-1$ intervals, define N points x_i :



$$f_i = f(x_i)$$

② Fit a simple linear piecewise function through the evaluated function points (see fig. 10.3, p. 253)

③ True integral is estimated as the sum of the trapezoid areas T_i :

$$I \approx I_T = T_1 + T_2 + \dots + T_{N-1}$$

$$T_i = \frac{1}{2} (x_{i+1} - x_i) (f_{i+1} + f_i)$$

single trapezoid area

note last area is indexed $N-1$, because there is one fewer panel than grid point

Equally spaced grid points \rightarrow general formula simplifies

Spacing:
$$h = \frac{b-a}{N-1}$$

So:
$$x_i = a + \frac{h}{1} (i-1)$$

$$T_i = \frac{1}{2} h (f_{i+1} + f_i)$$

single trap. area (simplified)

domain length
of panels

trapezoid rule for evenly spaced points:

$$I_T(h) = \frac{1}{2} h f_1 + h f_2 + h f_3 + \dots + h f_{N-1} + \frac{1}{2} h f_N$$

$$I_T(h) = \frac{1}{2} h (f_1 + f_N) + h \sum_{i=2}^{N-1} f_i$$

COEFFICIENTS

interior points $h \rightarrow$ each interior point appears in 2 trapezoids

exterior points $\frac{h}{2} \rightarrow$ only appear in one trapezoid each

Periodic Trapezoidal Rule

→ the trapezoidal rule converges quickly for smooth periodic integrands

NOTES on AFM* paper

* THE NON-LOCAL AFM WATER WAVE METHOD FOR CYLINDRICAL GEOMETRY

The change of variables $(x, t) \mapsto (z, t)$; $z = x - ct$ is introduced to compute travelling wave solutions
 constant wave speed, $c > 0$

this is substituted into the Bernoulli eq'n, and many previous relations

The final travelling wave form is given by eq'n (2.18):

$$(2.18) \quad \int_{-L}^L kS \left[(1 + S_z^2)(c^2 - 2\mathcal{F}) \right]^{1/2} \left(K_1(kb)I_1(kS) - I_1(kb)K_1(kS) \right) e^{ikz} dz = 0,$$

\swarrow wave speed \swarrow α or $n=1$ (Bessel order)

where

$$(2.19) \quad \mathcal{F} \equiv \frac{\gamma\kappa}{\rho} - V - \mathcal{E}, \quad \kappa = -\frac{S_{zz}}{(1 + S_z^2)^{3/2}} + \frac{1}{S(1 + S_z^2)^{1/2}}.$$

\swarrow potential field associated to body forces \swarrow Bernoulli constant

Bessel eq'n of first kind Bessel of second kind

§ 3.1 NUMERICAL METHOD

Periodic travelling wave solutions are represented by a Fourier expansion:

$$(3.7) \quad S(z) \simeq S_N = \sum_{n=-N}^N a_n e^{in\pi z/L}$$

$\boxed{k = \frac{n\pi}{L}}$
 \rightarrow may replace $\exp(ikz) \rightarrow \cos(kz)$

$S(z)$ real
 \Downarrow
 $a_n = -a_n^*$
 $(a_n \text{ is real})$

Substitute (3.7) into (1.18) \rightarrow also substitute (1.19) \mathcal{F} and κ } approximate integral using
 (take first and second $S(z)$ derivatives using FFT) } trapezoidal integration rule

