

(Not so) Intuitive Results from two Real-World Low-Power Wireless Mesh Deployments

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Abstract

Two wireless network sensors are deployed. One in a peach orchard and one in an office building. The two networks are collecting sensor values and network statistics. This paper presents an in-depth analysis of the statistics, in order to precisely understand the performance of the networks. Nodes in the networks exhibit an expected lifetime between 4 and 8 years, with an end-to-end reliability of 100%. We show how – contrary to popular belief – wireless links are symmetric. Thanks to the use of Time Slotted Channel Hopping (TSCH), the network topology is very stable, with ≤ 15 link changes on average per day in the entire network.

Keywords: WSN, SmartAgriculture, SmartBuilding

1. Introduction

Peaches do not like frost. If during the blooming season (September in Argentina), temperature gets below -3 C for only a couple of hours, the flowers freeze, and no peaches are produced. In 2013, 85% of the peach production in the Mendoza region (western Argentina) was lost because of frost events. Farmers can lose everything in only a couple of hours. Yet, if they are warned of a frost event a couple of hours ahead, they can install heaters throughout the orchards, and use big fans to move the hot air around. Fighting the frost events is not the issue, what is hard is predicting it.

The goal of the PEACH project [7] is to predict frost events. We install sensors around the orchard that measure air temperature, air relative humidity, soil moisture and soil temperature. We feed the collected data into a database, and by analyzing the data in real-time using machine learning, we identify patterns in the data and predict frost events.

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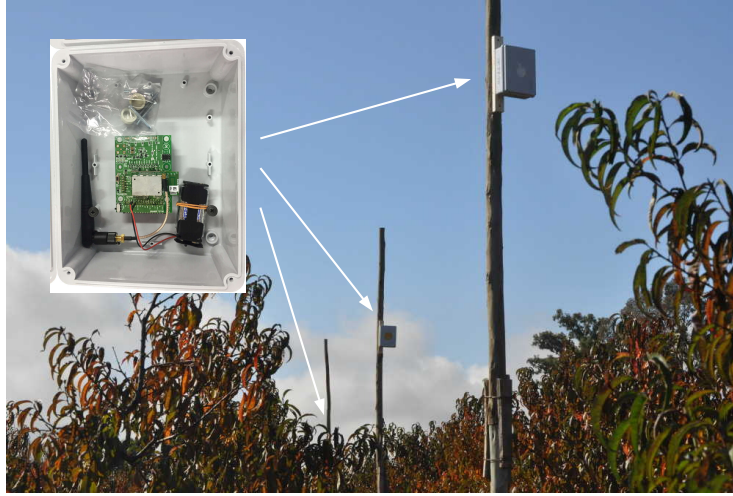


Figure 1: Areal view of the sensor network deployed in the orchard near Mendoza, Argentina.

Because of the heavy machinery that moves inside the orchard, using cables to interconnect the sensors is not an option. The main challenge is to deploy a system that provides both a high end-to-end reliability and a long lifetime without using cables. We use SmartMesh IP, an off-the-shelf low-power wireless mesh solution from Linear Technology. The sensor devices are battery-powered and equipped with a radio. They form a multi-hop topology, and collaborate to route the data generated by the devices (called “motes”) to a gateway. This gateway is connected to the Internet, and forwards the gathered data to the servers in Paris, France. Data appears on the web interface of the servers seconds after it was gathered by the sensor network.

The network is deployed in a peach orchard of 204 trees, planted in a 50 m \times 100 m area (shown in Fig. 2). The low-power wireless network is composed of 18 sensor motes¹ uniformly distributed between the peach trees, and 3 relay motes to connect the orchard to the gateway some 300 m away. Each mote is placed in a water-tight box that is fixed on a 4 m high pole (see Fig. 1).

To better understand and compare the network statistics gathered from the PEACH deployment, we deployed a second wireless network inside an office building. 14 motes are placed on the ceiling of one floor of the building and 3 nodes are placed outside on street lamps poles (shown in Fig. 3). The 14 inside motes are fixed to the ceiling with magnets and the 3 outside ones are placed in a water-tight box.

In the peach orchard we use four types of SmartMesh IP devices. The 2 DC9018 boards feature an external antenna; the 16 DC9003 boards a chip

¹2 motes malfunctioned and are not present on the map.

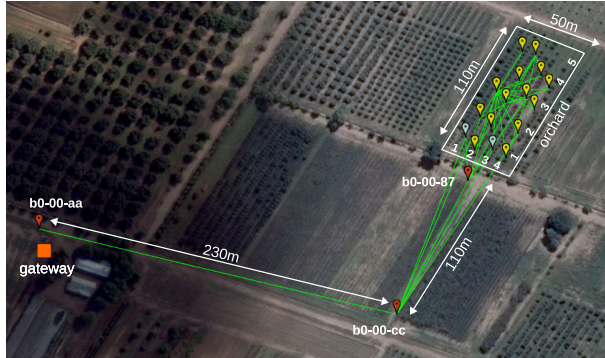


Figure 2: The wireless motes deployed in the peach orchard in Mendoza, Argentina.



Figure 3: The wireless motes deployed in the Inria office building, France.

antenna. These are deployed inside the orchard. We deploy 3 repeaters outside the orchards to connect the orchard to the gateway. In the office building we use 2 types of SmartMesh IP devices. The 11 DC9003 boards are the same as the ones used in the PEACH deployment. We use 1 DC9018 board with an external antenna. For the two deployments, the gateway is composed of a Raspberry Pi single-board computer, and a DC2274 SmartMesh IP manager.

The SmartMesh IP network implements the IEEE802.15.4e standard [2], which includes a channel hopping mechanism to reduce the impact of multipath fading and external interference. This allows the network to be highly reliable, stable, and extremely low power [8, 9].

Each mote produces a temperature value every 30 s, and network statistics every 5 min. We extracted 3 months of data for each deployment. We gathered over 4 million temperature values, and more than 350,000 network statistics for each deployment.

The goal of this paper is to analyze the network statistics over the two 3-month periods, and precisely assess the performance of the networks.

This paper makes the following contributions:

- We confirm that the SmartMesh IP network exhibits years of battery lifetime and wire-like reliability;
- We show that channel hopping causes the network topology to be very stable, with ≤ 15 link changes on average per day;
- Contrary to popular belief, we show that links in the network are symmetric, i.e. they exhibit the same signal strength in both directions of the same link.

type	PEACH	EVALab
<code>mote_create</code>	133	85
<code>path_create</code>	4,098	1,403
<code>path_delete</code>	3,653	1,325
HR_DEVICE	132,758	154,698
HR_DISCOVERED	87,737	152,641
HR_NEIGHBORS	140,897	128,072

Table 1: The number of statistics collected over the 3 month period.

The remainder of this paper is organized as follows. Section 2 describes what statistics we are collecting, and the amount of statistics collected over two periods of 3 months. Section 3 presents results that confirm assumptions about what we can expect for real-world SmartMesh IP deployment. Section 4 presents not so intuitive results about link symmetry and network stability. Finally, Section 5 concludes this paper and discusses further improvements.

2. Statistics Collected

PEACH: The PEACH wireless network is deployed in a peach orchard in Junin, 45 km South-East of Mendoza in Western Argentina. No other electronic devices are present in the field. Farmers work inside the field with heavy machinery for 1-2 h every 20 days approximately. In the region, air temperature ranges between -9 C in winter (May-October) to $+38$ C in summer (November-April). Because of the sunny weather, day/night temperature swings of $10+$ C are not uncommon in winter.

EVALab: The EVALab network is deployed in the French National Institute of Research in Computation and Automation (Inria) in Paris. On the same location there are multiple other wireless devices such as Wi-Fi, Bluetooth and Zigbee. There are also people moving around, mainly during office hours.

Each device in the network produces both sensor data and network statistics. Network statistics can be separated in Events and Health Reports messages. *Event* messages are non-periodic notifications the network sends when a network event happens (e.g. a node joins/leaves the network, a link is created/deleted). *Health Report* (HR) messages are sent periodically by each mote; they contain counters and statistics about that mote. HRs are used to assess the overall health of the network.

Table 1 summarizes the number of events and HRs gathered during the two periods of 3 month. In the remainder of this section, we detail the meaning of each of the statistics.

`mote_create`. Each node in a SmartMesh IP network can periodically send beacons to announce the presence of the network. When a mote wants to join a network, it listens for those beacons. Once it has heard a number of those, it starts a security handshake with the network. During that handshake, the SmartMesh IP manager sends a `mote_create` event notification over its serial

port. This is the event we log². It contains, among other information, the association between the newly-joined device’s 8-byte MAC address and its 2-byte `moteId`.

path_create and path_delete. In SmartMesh IP terminology, a “path” is the link-layer resource that allows two neighbor nodes to communicate³. Each time a mote starts communicating with a new neighbor (e.g. its routing parent), a `path_create` event is produced. Similarly, each time a mote *stops* communicating with a neighbor (e.g. it changes routing parent), a `path_delete` event is produced. We log both messages.

HR_DEVICE. Each network device produces a `HR_DEVICE` every 15 min. This health report contains counters/statistics internal to the mote, such as its current battery voltage, temperature, or total number of messages sent.

HR_DISCOVERED. SmartMesh IP nodes continuously monitor their surroundings to discover neighbor nodes. Every 15 min, each node produces an `HR_DISCOVERED` health report that contains the list of “discovered” neighbors, and the associate signal strength it heard them at. These discovered neighbors can potentially be used in the future as neighbors the node communicates with.

HR_NEIGHBORS. Two nodes are neighbors when link-layer resources are installed for them to communicate. The neighbors of a node are a subset of the discovered neighbors. Every 15 min, each node generates an `HR_NEIGHBORS` health report that contains its list of neighbors. These messages also specifies per-neighbor counters, such as the number of link-layer retransmissions.

After 3 months of operation, we have collected 369,276 and 386,929 network statistics in the PEACH and EVALab deployment respectively (see Table 1). The goal of the next section is to present the main results from analyzing this information. We group these results in two categories. “Intuitive” results (Section 3) are results that confirm the performance expected from a SmartMesh IP network. “Not so intuitive” results (Section 4) are results that we believe go against popular belief. This classification is necessarily subjective.

Possibly due to power line failure at the network manager side, the network experienced some restarting. For this reason, some analysis presented in the next sections are done in shorter period. As a side effect, this allows us to verify the network formation and joining process.

3. Intuitive Results

Previous publications [7, 8, 9, 10] underline the performance of TSCH networks in general, and SmartMesh IP in particular. Standardization work in the IETF 6TiSCH working group⁴ around TSCH networks further illustrates the move of the industry towards this type of networking technology. So while

²Normally, each mote generates a single `mote_create` event. Due to power issues at the manager side, the network restarted a couple of times and new events were created.

³ In more classical networking terminology, this is often referred to as a “link”. We use the terms “path” and “link” interchangeably in this paper.

⁴ <https://tools.ietf.org/wg/6tisch/charters>

we expect good performance from the network, this section verifies that this is indeed the case. We start by looking at two physical-layer metrics: RSSI vs Distance (Section 3.1) and PDR vs. RSSI (Section 3.2). While these have no dependency on TSCH (the type of medium access), they allow us to verify the overall connectivity in the network. We then look at key performance indicators of SmartMesh IP networks: end-to-end reliability (Section 3.3) and network lifetime (Section 3.4).

3.1. RSSI vs. Distance

The Friis transmission model [5] gives the relationship between the Received Signal Strength (RSSI)⁵ in free space. While it does *not* apply directly to our real-world deployment, we note in Fig. 4 that the individual RSSI values are located between the Friis model, and the Friis model offset by -40 dB. This corroborates the results from [11].

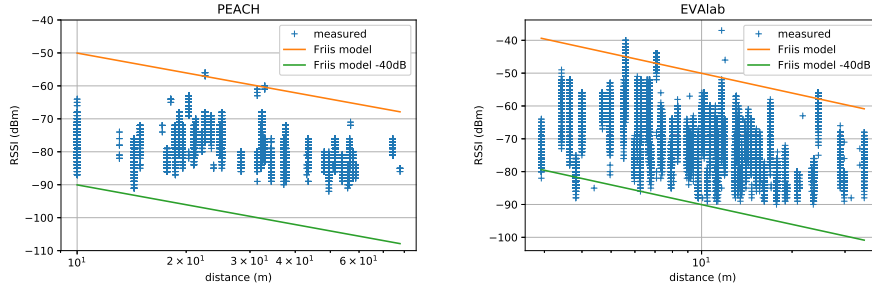


Figure 4: RSSI measurements are roughly located between the Friis model and the Friis model shifted by -40 dB.

3.2. Wireless Waterfall

Due to the inherent physical unreliability of the radio medium, it is impossible to know if a future transmission will be successful or not. The Packet Delivery Ratio (PDR) is the portion of successful link-layer transmissions over the total number of link-layer transmission attempts. A failed attempt means that the link-layer frame needs to be re-transmitted; it does *not* mean the packet is lost. Over a period of 3 months, 140,897 `HR_NEIGHBORS` messages are collected in the PEACH deployment and 128,072 in the EVALab deployment. These contain, for a given node, the number of link-layer transmission attempts and successes to each of its neighbors. We remove the portion of neighbors with no transmission and keep only the DC9003 motes, resulting in a total of 69,643 messages (approx. 49% from the total number of `HR_NEIGHBORS`) for

⁵ Strictly speaking, the RSSI is the Received Signal Strength *Indicator*, a value returned by radio chip. Because of its prevalence in low-power wireless literature, we use it RSS and RSSI interchangeably.

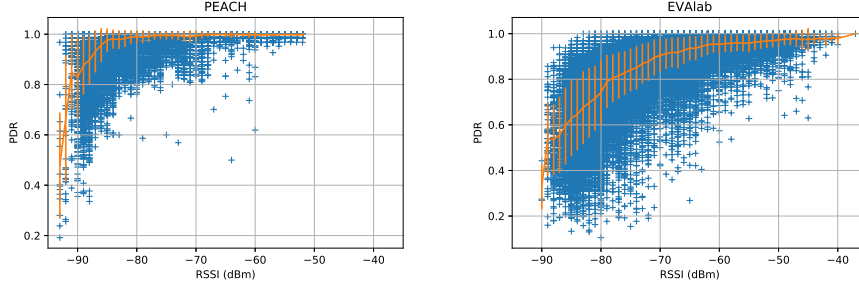


Figure 5: The PDR/RSSI “waterfall” plot. The EVALab curve is shifted right indicating an interference-prone environment.

the PEACH deployment and a total of 93,135 messages (approx. 73%) for the EVALab deployment.

Fig. 5 plots the PDR and the RSSI of these 69,643 and 93,135 messages. For readability, we also plot the average/deviation of the data for a given RSSI value. Because of its shape, this is known as the “waterfall plot”.

For the PEACH deployment, above -85 dBm , the PDR of the link is very good ($> 95\%$). Below that value, the PDR rapidly degrades, indicating that, on these links, frequent retransmissions happen. For the EVALab deployment, the PDR starts to degrade at -60 dBm . The device manufacturer documentation [4] indicates that a path is considered as “bad” when:

- $\text{RSSI} > -80\text{ dBm}$ and $\text{PDR} < 50\%$
- $\text{RSSI} > -70\text{ dBm}$ and $\text{PDR} < 70\%$

This is not the case in any of the two deployments.

A *waterfall plot* either shifted right with very few paths below -70 dBm , or with a non-constantly decreasing curve would be an example of interference-prone environment. This is not the case for the PEACH deployment, meaning that the SmartMesh IP network is not experiencing high levels of interferences from co-located wireless devices. This is the case for the EVALab deployment, meaning that the SmartMesh IP network is experiencing external interferences. Those results correspond to the environment described in Section 1 as other concurrent technologies are present in the building.

3.3. End-to-End Reliability

We expect the SmartMesh IP network to offer wire-like reliability. Table 2 confirms that this is the case. It presents statistics gathered over July 15-25 2016 period in the PEACH orchard and from the 12th of November 2016 to the 12th of February 2017 in the EVALab.

It shows that, as none of the 693,844 and 431,193 packets generated in the networks was lost, the end-to-end reliability is 100%. The average PDR over all

	PEACH	EVALab
reliability (Arrived/Lost)	100% (693,844/0)	100% (431,193/0)
average PDR (Transmit/Fails)	95% (4,405,569/258778)	87% (19,807,535/2,488,149)
latency	700 msec	Not measured

Table 2: The overall network performance in the 15-25 July 2016 period (PEACH) and the 12/11/16 and the 12/02/17 (EVALab).

the links is very high (95% and 87%), indicating that the nodes are deployed close enough to one another. Finally, the average latency over all nodes is 700 ms for the PEACH deployment. These results are very similar to the very initial results presented in [7], indicating no degradation in performance of the SmartMesh IP network over the 3 month operation.

3.4. Network Lifetime

Each device is powered by a pair of Energizer L-91 AA batteries. These contain a nominal 3134 mAh of charge, or 2821 mAh when accounting for a 10% decrease due to manufacturing differences. A SmartMesh IP node contains a “charge accounting” feature in which it tracks the amount of charge it has been drawing from the battery. Each mote reports this number every 15 min as a field in its `HR_DEVICE` health report. This number allows us to predict the lifetime of the device.

Table 3 shows charge consumed by the motes over the two 3 month periods, as well as the portion of the battery this represents. Assuming the same energy consumption rate, we can extrapolate the lifetime. The nodes with the longest lifetime (8 years) are all leaf nodes as we can see from Fig. 2. Since it does not have to relay data from any children, it is normal that this node consumes very little. The node with the shortest lifetime is `30-60-ef` and has 4 years of lifetime, it is normal as this node has an external antenna and relays a lot of data. This shows the ultra-low power consumption of the SmartMesh IP network.

4. Not so Intuitive Results

Results from Section 3 are “intuitive” is that they corroborate previous measurements [7] or confirm theoretical/lab results [8, 9, 10]. This section presents results which we believe go against popular belief. This classification is necessarily subjective.

In Section 4.1, we show that links are, in fact, symmetric. In Section 4.2, we show that, through the use of TSCH, the low-power wireless topology is, in fact, extremely stable.

MAC	charge consumed	lifetime	MAC	charge consumed	lifetime
30-60-ef	695 KC (6.8%)	4 years	38-03-dd	459 KC (5.8%)	4 years
38-0f-66	461 KC (4.5%)	6 years	58-e9-ca	411 KC (5.2%)	5 years
3f-f8-20	380 KC (3.7%)	8 years	58-e9-cb	407 KC (5.1%)	5 years
3f-fe-87	549 KC (5.4%)	5 years	58-eb-5b	423 KC (5.3%)	5 years
3f-fe-88	718 KC (7.1%)	4 years	58-eb-64	322 KC (4.1%)	6 years
58-32-36	311 KC (3.1%)	7 years	58-eb-67	468 KC (5.9%)	4 years
60-01-f8	387 KC (3.8%)	8 years	58-eb-69	243 KC (3.1%)	6 years
60-02-1b	371 KC (3.7%)	8 years	58-f3-17	357 KC (4.5%)	5 years
60-02-4b	406 KC (4.0%)	7 years	58-f4-f8	402 KC (5.1%)	5 years
60-03-82	395 KC (3.9%)	8 years	58-f5-23	416 KC (5.3%)	5 years
60-05-5f	386 KC (3.8%)	8 years	58-f5-3c	412 KC (5.2%)	5 years
60-05-69	509 KC (5.0%)	6 years	58-f5-58	387 KC (4.9%)	5 years
60-05-78	364 KC (3.6%)	8 years	58-f8-63	198 KC (2.5%)	7 years
60-05-ab	381 KC (3.8%)	8 years	58-f8-78	233 KC (2.9%)	6 years
60-06-27	422 KC (4.2%)	7 years	58-f8-8f	439 KC (5.5%)	4 years
60-08-d5	432 KC (4.3%)	7 years	58-f9-c4	325 KC (4.1%)	6 years

(a) PEACH
(b) EVALab

Table 3: Per-node power consumption and associated expected lifetime when powered by a pair of AA batteries.

4.1. Link (*A*)Symmetry

Motes report the average RSSI value of the packets received from each neighbor in their `HR_NEIGHBORS` health reports. Because the network uses channel hopping, these reported RSSI values are also averaged over 15 IEEE802.15.4 frequencies [1]. In this section, we use the term “RSSI” to denote the average RSSI over 15 frequencies.

A common assumption is that links between neighbor low-power wireless devices are hugely asymmetric. That is, on a link between nodes *A* and *B*, *A* receives *B*’s link-layer frames with an RSSI very different from the frames *B* receives from *A*. Numerous routing protocols (often standardized [3]) reuse that assumption and start with a costly step of filtering out asymmetric links.

We look at the link statistics between the 18th of June 2016 and the 4th of July 2016 (16 days) in the PEACH deployment and between the 12th of N. The sample contains 411,132 `HR_NEIGHBORS` messages received from 14 DC9003 nodes (same hardware). During that period, 21 links are active with at least 250 transmissions for each link. For each of those links, we compute the difference between average RSSI in each directions. Results are presented in Fig. 6.

Fig. 6 shows that the RSSI difference never exceeds a couple of dB. Looking at Fig. 5, this translates into a handful of percentage points difference in PDR only. This means the links can be considered symmetric. This result is in-line with the physical phenomenon that the signal traveling from *A* to *B* undergoes the same attenuation as that from *B* to *A*. This result would *not* hold if the

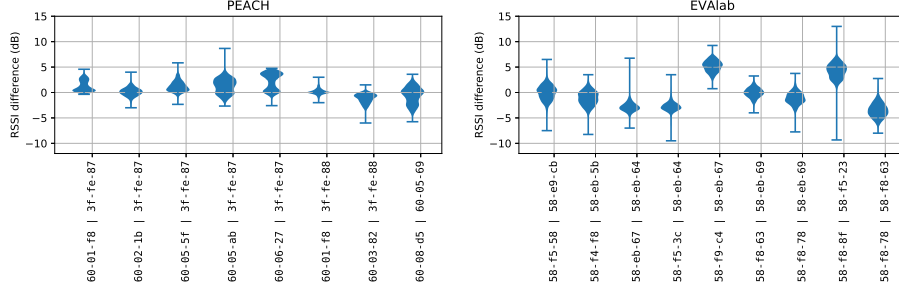


Figure 6: The difference in RSSI between the two directions of 7/12 wireless links in the PEACH/EVALab deployment. The violin plots show the distribution of the value and the standard deviation.

neighbor radios had a different transmit power or sensitivity. That being said, discussions on link symmetry at the routing layer is largely artificial, as any “good” medium access control (MAC) protocol uses link-layer acknowledgments.

4.2. Network Stability

Wireless is unreliable in nature. It is normal that some wireless links inter-connecting nodes “come and go”. That is, links that have been performing well (e.g. $PDR_{i,90\%}$) can suddenly disappear (e.g. $PDR < 10\%$). Similarly, nodes that were not able to communicate can suddenly hear one another perfectly.

The question, however, is what time scale is considered. Early academic work on low-power wireless [6] has looked at the “burstiness” of the wireless links, i.e. changes over the course of 10-1000’s ms. Some follow-up work has taken the assumption that wireless links are so unstable that only a reactive routing approach works. In this section, we in firm this statement by looking at the stability of the network.

In particular, we look at the `path_delete` and `path_create` events. These are generated each time a node adds/deletes a neighbor to communicate with, which happens for example when the routing topology changes (see Section 2). The number of `path_delete` and `path_create` events is a direct measurement of the network stability. Note that we removed the nodes that does not respect the Dust requirement of having at least two parents to associate with (one node in the PEACH deployment and three in the EVALab one). Due to the lack of second parent, the nodes were producing over 20 times the amount of messages than all the other nodes assembled.

Fig. 7 shows the number of `path_delete` and `path_create` events per day, over a 16 days (PEACH) and 2 months (EVALab). For reference, the total number of links in the network is also depicted. There are less than 5 `path_delete` or `path_create` events *per day* in the entire PEACH network and less than 15 `path_delete` or `path_create` events *per day* in the EVALab. This means that links, once established, remain useful for days/weeks at a time, and that the

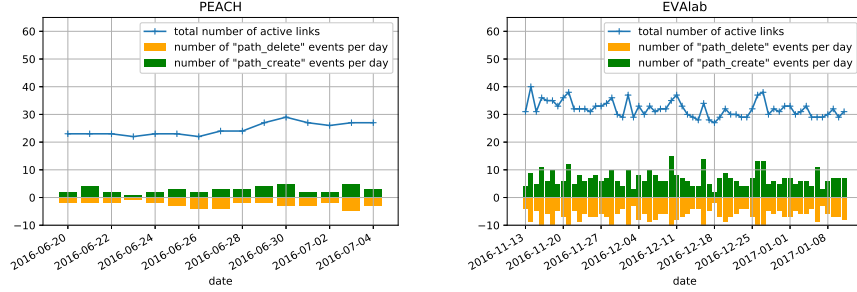


Figure 7: Network stability: the number of `path_create` and `path_delete` events generated per day over a 16 days (PEACH) and two months (EVALab). The top line shows the total number of active links.

network is extremely stable. The reason why there are more events per day in the EVALab deployment is not studied here.

This stability can largely be attributed to the use of channel hopping. Changing frequency for each packet is known to efficiently combat multi-path fading and external interference [9], the major causes of instability. It does not contradict the findings of [6], it just means that link-layer retransmissions can efficiently cope with link burstiness, and that the multi-hop topology can remain very stable.

5. Conclusion

This paper analyzes the network statistics generated by two low-power wireless mesh networks deployed in real-world conditions. The first deployment in peach orchard in Argentina of 21 nodes produced 369,276 statistics over the course of 3 months. The second deployment in an office building in Paris of 17 nodes produced 386,929 statistics over the course of 3 months

We use a “waterfall” plot to show that the two networks are subject to different amount of interferences from other wireless devices deployed in the same area. The SmartMesh IP network delivers its exceptional performance, with 0 packets lost out of 693,844 (PEACH) and 431,193 (EVALab) received (100% reliable) and 4-16 years of battery lifetime on a pair of commercial AA batteries.

While it is often assumed that wireless links are asymmetric, we show to the contrary that the difference in RSSI averaged over 15 IEEE802.15.4 channels does not exceed a handful of dB. We show that the network is extremely stable, with less than 5 links being added or deleted per day in an outdoor environment and 15 links being added or deleted per day in an indoor environment.

We attribute this performance to the use of Time Synchronized Channel Hopping (TSCH) technology at the heart of the SmartMesh IP products.

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