

view frames Result

Recorded at time: 1696958673.392

locobot/odom

Broadcaster: /locobot/mobile base nodelet manager Average rate: 50.384 Hz Most recent transform: 1696958673.391 (0.001 sec old) Buffer length: 4.962 sec

locobot/base_footprint

Broadcaster: /locobot/robot state publisher

Broadcaster: /locobot/robot state publisher Average rate: $1000\overline{0}.000 \overline{\text{Hz}}$ Most recent transform: 0.000 (1696958673.392 sec old) Buffer length: 0.000 sec

locobot/base_link

Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec

Broadcaster: /locobot/robot state publisher

locobot/cliff_sensor_right_link locobot/cliff_sensor_left_link

locobot/gyro_link

Broadcaster: /locobot/robot state publisher

locobot/wheel_left_link

Broadcaster: /locobot/robot state publisher

Average rate: $1000\overline{0}.000 \overline{\text{Hz}}$

Buffer length: 0.000 sec

locobot/wheel_right_link

Broadcaster: /locobot/robot state publisher

Average rate: 38.462 Hz

Buffer length: 4.940 sec

Broadcaster: /locobot/robot state publisher

recent transform: 1696958673.383 (0.009 sec old)

Average rate: $38.\overline{4}62~\mathrm{Hz}^{-1}$

Buffer length: 4.940 sec