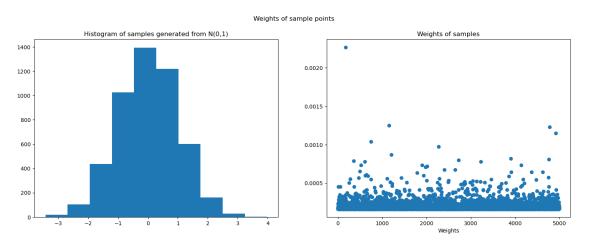
# Fall 2022: Monte Carlo Methods Homework 3

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#### Exercise 28

We are given a target distribution  $N(0,\sigma^2)$  and we are using the Standard Gaussian N(0,1) to generate samples. I implemented the mentioned re-sampling methods: 'Multinomial, Bernoulli and Systematic. Below is the sample image showing the weights of the points sampled from N(0,1).



We can also see that these re-sampling methods are still producing the unbiased estimators. Below is the mean computed using

$$E[x] = \sum_{i=1}^{k} x^{(i)} w^{(i)}$$

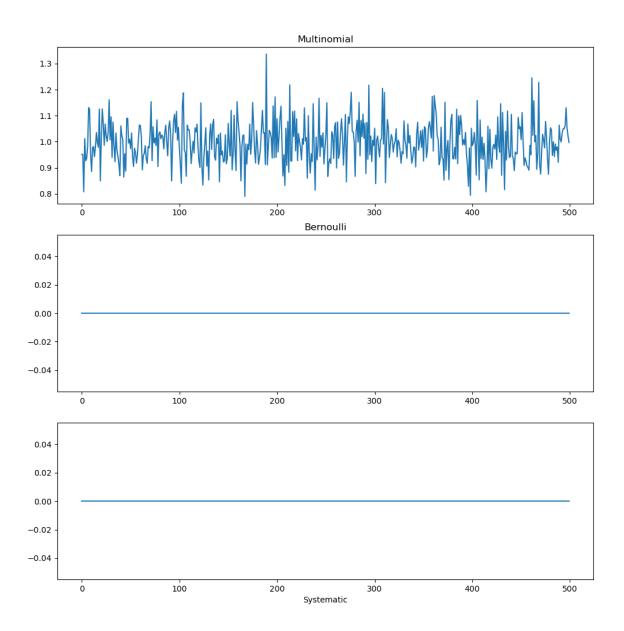
### /Users/utkarsh/.conda/envs/PyTorchTesting/bin/

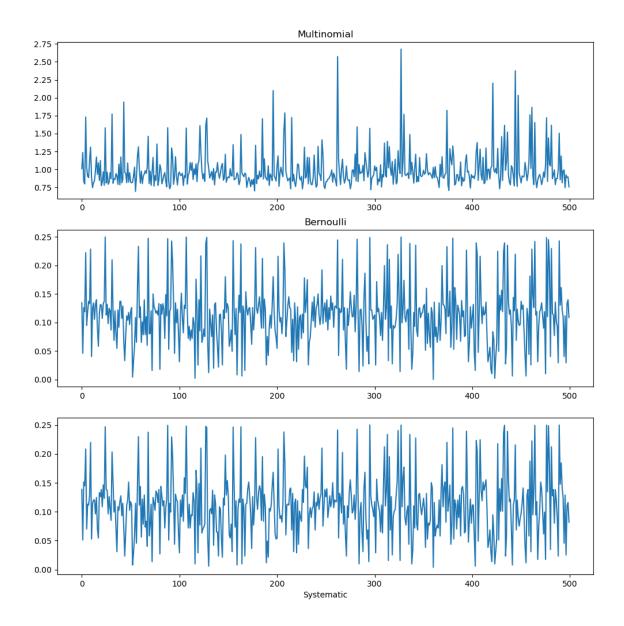
Multinomial, mean: 0.007095422624287677 Bernaulli, mean: -0.03118538840362053 Systematic, mean: -0.02605670696395046

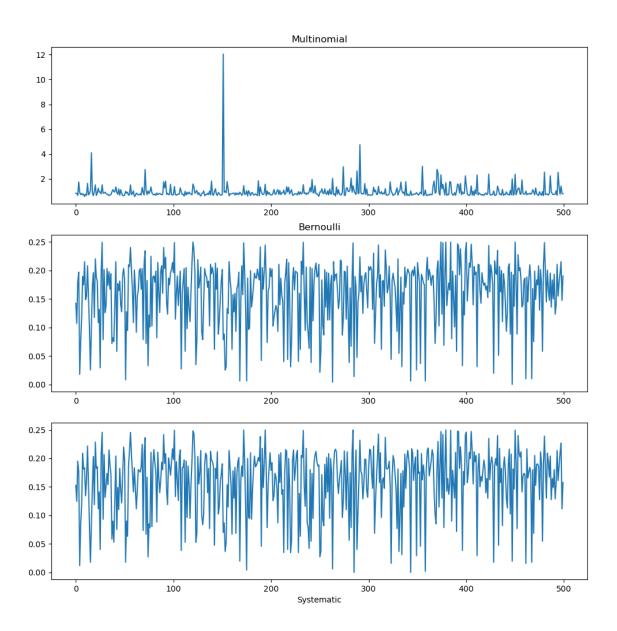
For the next part of the question, I generated five hundred sample points and computed weights for each sample respectively. So we have

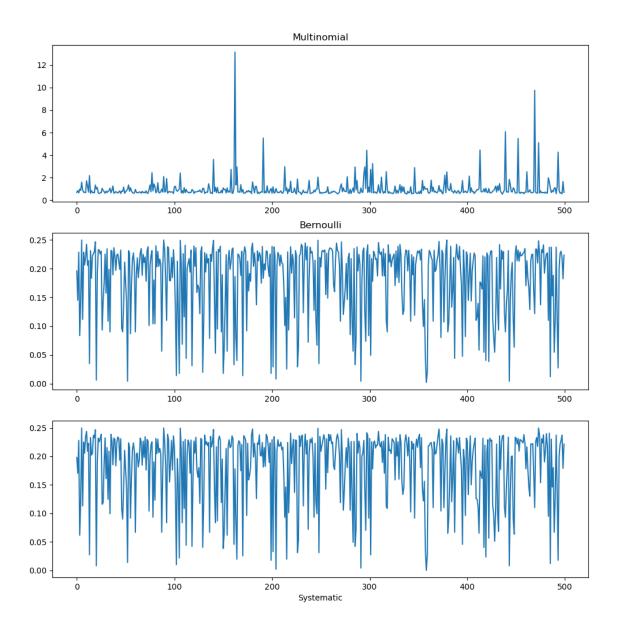
$$X^{(i)}, w^{(i)}$$
 for  $0 \le i < N$ 

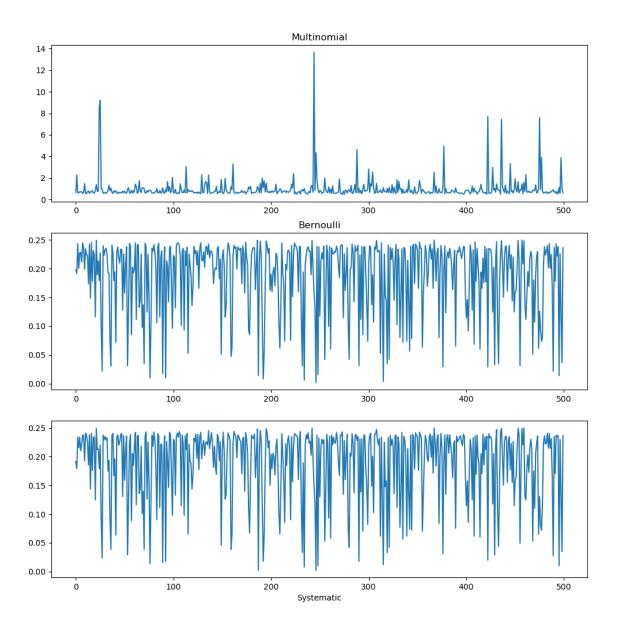
where N=500 Next step was to re-sample the points with all the three methods and for re-sampling we will generate  $N^{(k)}$  copies of the sample with weight  $w^{(k)}$ . Below are the figures showing variances that were computed normally for different values of  $\sigma^2$ .

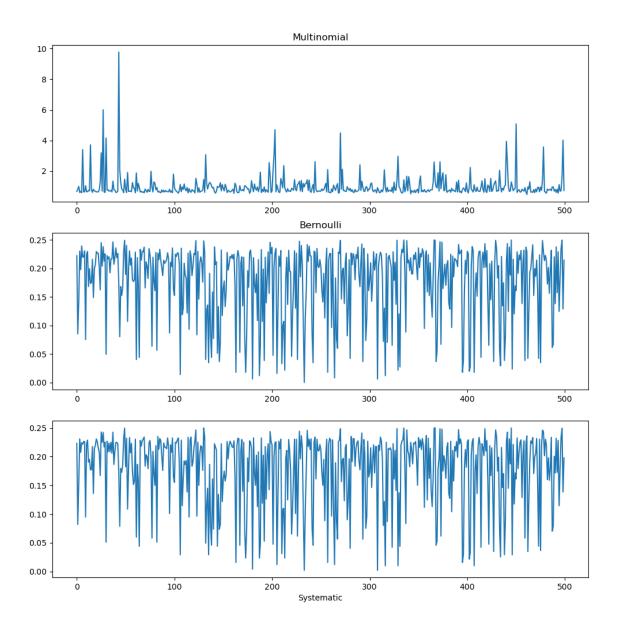


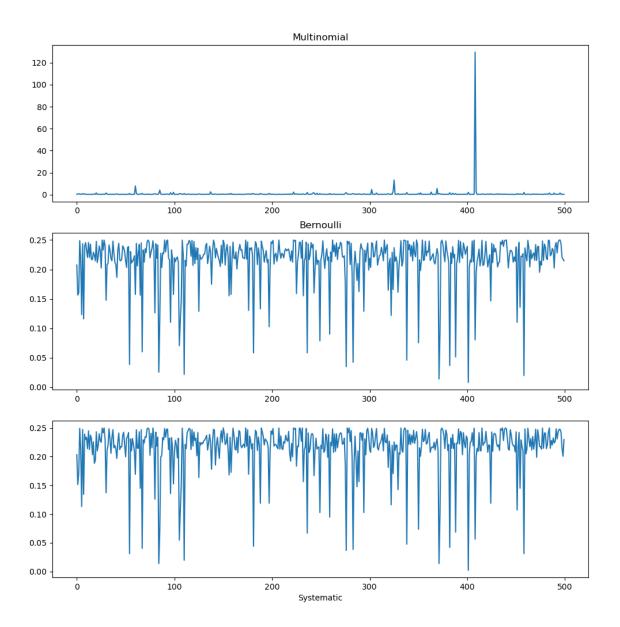


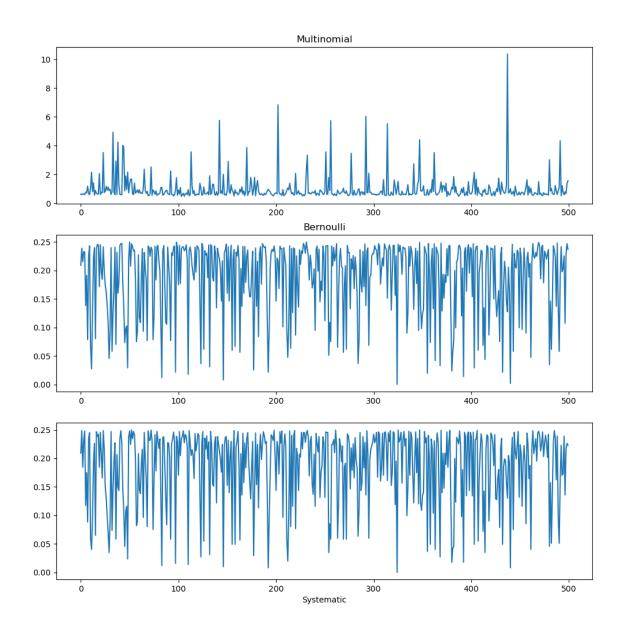












We can clearly observe that the variance for the Bernoulli and Systematic Re-sampling methods the variance is bounded between 0 and 0.25 while when using Multinomial for re-sampling the variance is sensitive with respect to the value of  $\sigma^2$ .

Below is the code snippet for the Multinomial Re-sampling method

Below is the code snippet for the Bernoulli Re-sampling method

```
1: def DoBernaulliResampling(x, w):
       m = len(w)
3:
       w_bar = np.sum(w) / m
4:
       x_resampled = np.zeros(0)
       copyCounts = np.zeros(m)
6:
7:
       for k in range(m):
8.
           curr_copy_count = np.floor(m * w[k])
g.
           u = np.random.uniform(0, 1)
10:
           if (u < m * w[k] - curr_copy_count):</pre>
11:
                curr_copy_count = curr_copy_count + 1
12:
           else:
13:
                curr_copy_count = curr_copy_count
           copyCounts[k] = (curr_copy_count.astype(np.int64))
14:
15:
       # print(copyCounts)
16:
       copyCounts = copyCounts.astype(np.int64)
17:
       # print(copyCounts)
18:
19:
       for i in range(m):
           cc = copyCounts[i]
20:
21:
           for j in range(cc):
22:
                x_resampled = np.append(x_resampled, x[i])
23:
24:
       return (copyCounts, x_resampled)
```

And, below is the code snippet for Systematic Re-sampling method

```
1: def DoSystematicSampling(x, w):
       m = len(w)
3:
       cumW = np.cumsum(w)
4.
5:
       u_s = []
6:
       u = np.random.uniform(0, 1 / m)
7:
       for i in range(1, m + 1):
8:
           u_s = np.append(u_s, i / m - u)
9:
10:
       copyCounts = np.zeros(m)
11:
       for k in range(1, m + 1):
           if (k == 1):
12:
13:
                sw = 0 # Starting weight
14:
                fw = cumW[k - 1] # Final weight
15:
                \# Count the num of us between sw and fw
16:
                satisfies = [u for u in u_s if u >= sw and u < fw]
17:
                copyCounts[k - 1] = len(satisfies)
18:
           else:
19:
               sw = cumW[k - 2]
20:
               fw = cumW[k - 1]
                \# Count the num of us between sw and fw
21:
22:
                satisfies = [u for u in u_s if u >= sw and u < fw]
```

```
23:
                copyCounts[k - 1] = len(satisfies)
24:
25:
       x_resampled = np.zeros(0)
26:
       w_bar = np.sum(w) / m
27:
28:
       copyCounts = copyCounts.astype(np.int64)
29:
30:
       for i in range(m):
31:
           cc = copyCounts[i]
32:
           # print(cc)
33:
           for j in range(cc):
                x_resampled = np.append(x_resampled, x[i])
34:
35:
       return (copyCounts, x_resampled)
```

#### Exercise 29

In this exercise, I wrote routines to generate points from Self Avoiding Walks of length (n) for both with and without multinomial resampling.

Below is the snippet of the code. It takes are Boolean to switch on or off the re-sampling code.

```
1: def GetAvailableDirections(curr_x, curr_y, curr_points_in_saw):
    free_neighbors_count = 0;
     directions = [(1,0), (0,1), (-1, 0), (0,-1)]
    availableDirections = []
    for dir in range(4):
       del_x, del_y = directions[dir]
6:
7:
      n_x = curr_x + del_x
      n_y = curr_y + del_y
8:
      if(not((n_x,n_y) in curr_points_in_saw)):
9:
10:
         free_neighbors_count +=1
11:
         availableDirections.append((del_x, del_y))
12:
     return free_neighbors_count, availableDirections
14: def GetNextPointInSAW(curr_x, curr_y, availableDirections):
     dirIndex = random.randint(0, len(availableDirections))
     del_x, del_y = availableDirections[dirIndex]
16:
     new_x = curr_x + del_x #New point x coordinate for this sample
17:
18:
     new_y = curr_y + del_y #New point y coordinate for this sample
19:
     return new_x, new_y
20:
21: def GetCopyCounts(m, weights):
     mean = weights.mean()
                            #This is w bar, weight to be used after resampling
23:
     probabVector = ((weights/(m * mean)).to_numpy()).astype(np.float64)
24:
     #print(probabVector)
25:
     copyCounts = np.random.multinomial(m, probabVector)
26:
     return copyCounts
27:
28: def GetSelfAvoidingWalk(m, d, resamplingOn = True):
     x_frame = pd.DataFrame(index=np.arange(m), columns=np.arange(d + 1))
30:
     y_frame = pd.DataFrame(index=np.arange(m), columns=np.arange(d + 1))
31:
     w_frame = pd.DataFrame(index=np.arange(m), columns=np.arange(d + 1))
32:
33:
     #Dimensions will run from 0 to d. Setting col 0 value to 0 for coords and 1
                                               for weights
34:
    x_frame[0] = 0
35:
   v_frame[0] = 0
36:
    w frame [0] = 1
37:
    #List of dictionaries for each sample. Dict will contain tuple of all the
                                               points in SAW.
38:
    coords_set_main = []
```

```
39:
     for i in range(m):
40:
       coords_set_main.append({(0,0)})
41:
42:
     for dim_iter in range(d):
                                                 #All dimension
43:
       for sample_iter in range(m):
                                                   #All samples
44:
45:
         curr_x = x_frame.at[sample_iter,dim_iter]
         curr_y = y_frame.at[sample_iter,dim_iter]
46:
47:
         free_neighbors_count, availableDirections = GetAvailableDirections(curr_x
                                                     , curr_y, coords_set_main[
                                                     sample_iter])
48:
         if(free_neighbors_count == 0):
49:
           #print('Returning false')
50:
           return False, [], [], []
                                         #Return Status as of now. Not processing
                                                       this any further
51:
52:
         new_x, new_y = GetNextPointInSAW(curr_x, curr_y, availableDirections)
53:
         (coords_set_main[sample_iter]).add((new_x, new_y)) #Adding in the
                                                     dictionary
54:
55:
         #Add it into the dataframes
56.
         x_frame.at[sample_iter,dim_iter + 1] = new_x
57:
         y_frame.at[sample_iter,dim_iter + 1] = new_y
58:
         w_frame.at[sample_iter,dim_iter + 1] = w_frame.at[sample_iter,dim_iter] *
                                                      free_neighbors_count
59:
60:
       #All samples computed for curr dim_iter and are stored in dim_iter + 1
61:
62:
       #Resampling code below
63:
       if (dim_iter < d - 1 and resamplingOn):</pre>
64:
         if (dim_iter == 1):
65:
           print('Resampling On')
66:
         copyCounts = GetCopyCounts(m, w_frame[dim_iter + 1])
67:
         x_resampled = []
68:
         y_resampled = []
69:
70:
         for i in range(m):
71:
           cc = copyCounts[i]
72:
           for j in range(cc):
73:
              x_resampled.append(x_frame.loc[i])
74:
              y_resampled.append(y_frame.loc[i])
75:
76:
         if(len(x_resampled) != m or len(y_resampled) != m):
77:
           print('Size not equal')
78.
79:
         for i in range(m):
80:
           x_frame.loc[i] = x_resampled[i]
81:
           y_frame.loc[i] = y_resampled[i]
82:
     #print('Code ran successfully')
     return True, x_frame, y_frame, w_frame
```

Nowe, for validating the code, I wrote sum wrapper and helper functions to find the expectation of the times, each Lattice point was visited for N SAWs of length d. Following is the output for few SAWs.

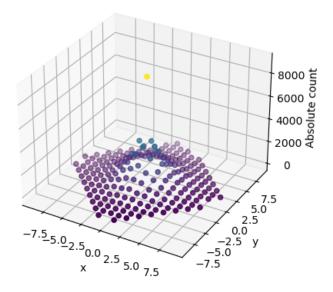
```
Expectation for d = 1
(x,y) Count
-----
(1, 0) 0.241676
(0, 1) 0.255604
(-1, 0) 0.245811
(0, -1) 0.25691
```

Expectati	on for d =	2
(x,y)	Count	
(1, -1)	0.165941	
(0, 2)	0.0834603	
(-1, 1)	0.174102	
(0, -2)	0.089445	
(-1, -1)	0.166812	
(-2, 0)	0.0787813	
(1, 1)	0.160936	
(2, 0)	0.0805223	

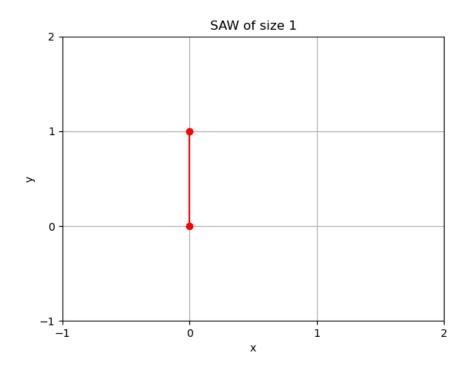
Expectati	on for d =	3
(x,y)	Count	
(0, -1)	0.0562568	
(1, 2)	0.0808487	
(-1, 0)	0.0568009	
(-2, 1)	0.0831338	
(2, -1)	0.0840044	
(1, -2)	0.0858542	
(-2, -1)	0.0828074	
(0, 1)	0.0564744	
(-1, 2)	0.0840044	
(1, 0)	0.0535365	
(2, 1)	0.0815016	
(0, 3)	0.0275299	
(3, 0)	0.0253536	
(-3, 0)	0.0278564	
(-1, -2)	0.0833515	
(0, -3)	0.0306855	

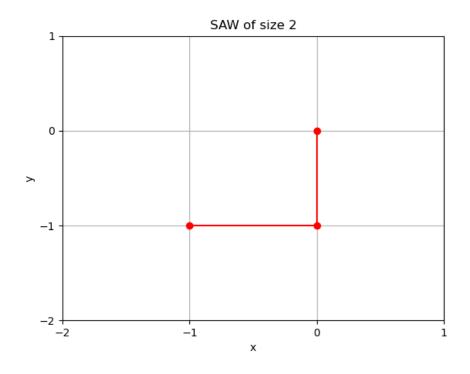
Also, plotted the variation of counts of visit of each Lattice point with the  $\boldsymbol{x}$  and  $\boldsymbol{y}$  coordinates. Following is the output obtained.

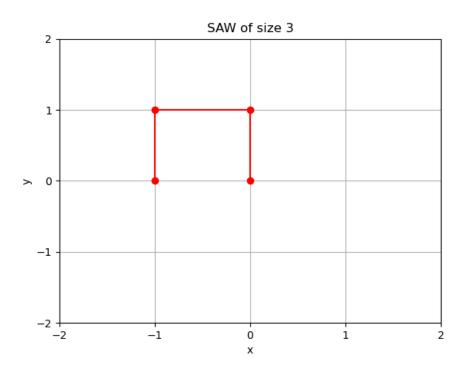
## Counts of Visits to Latice site

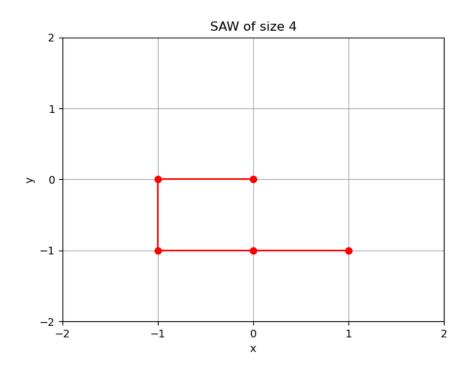


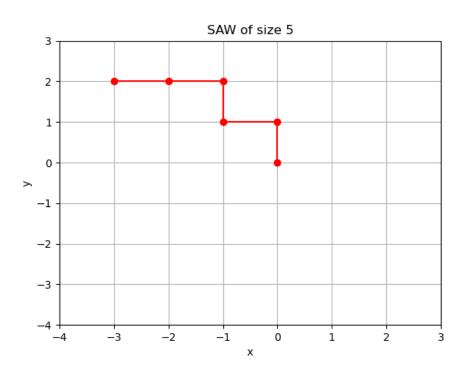
After checking that the method is valid, I produced SAW for each value  $\emph{d}.$  Below are the generated paths.

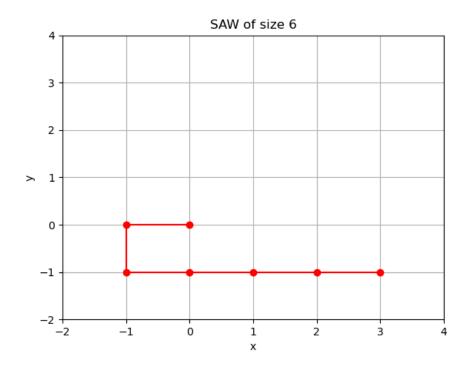


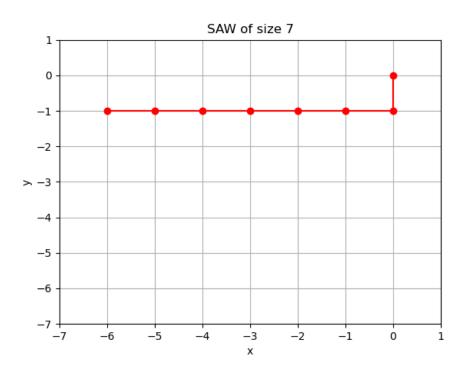


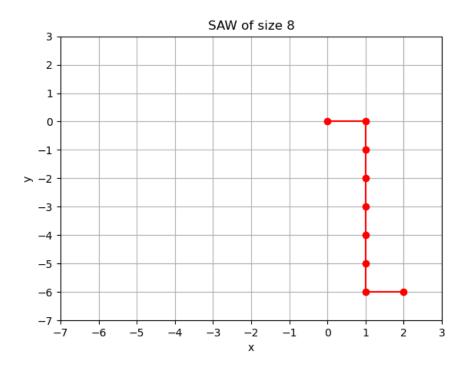


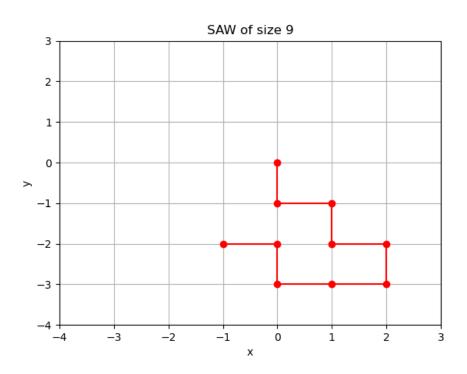


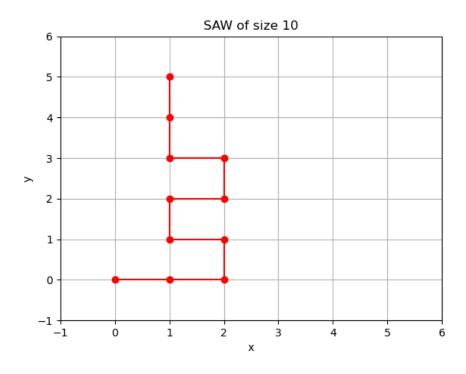


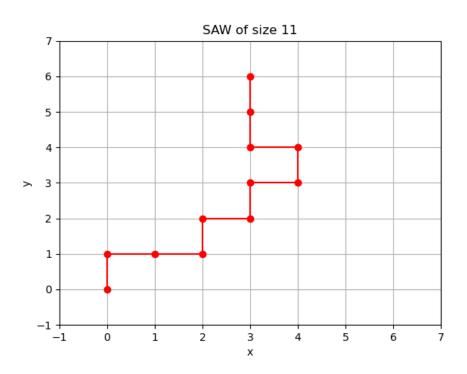


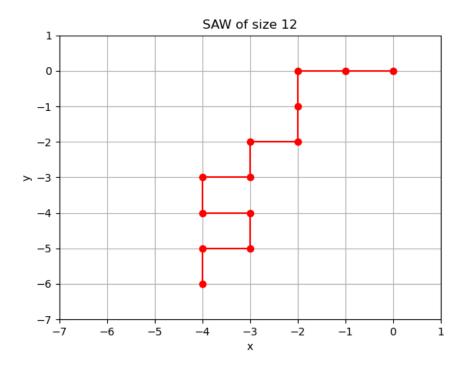


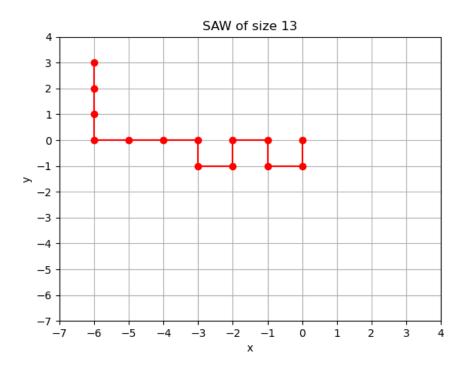


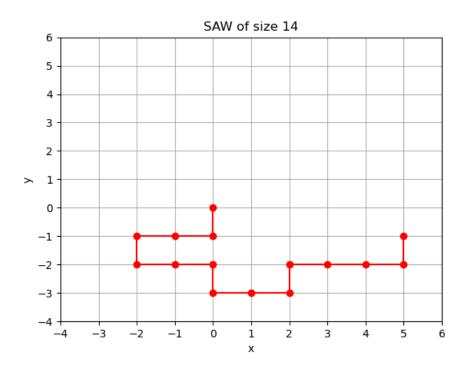


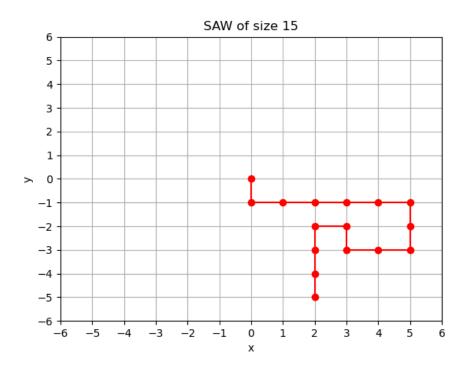


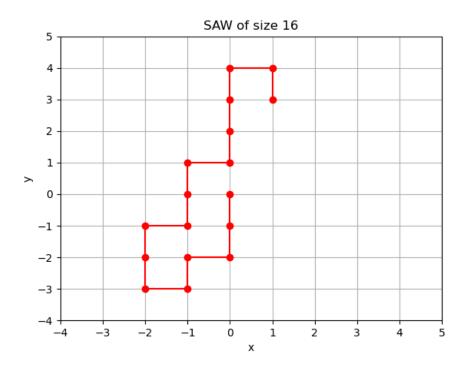


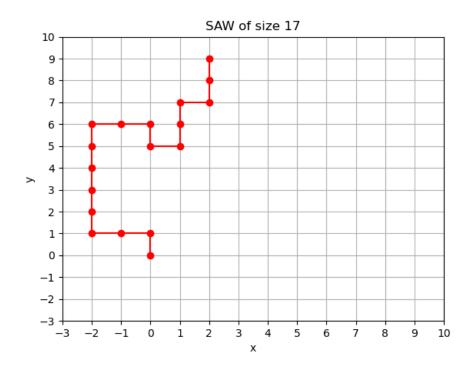


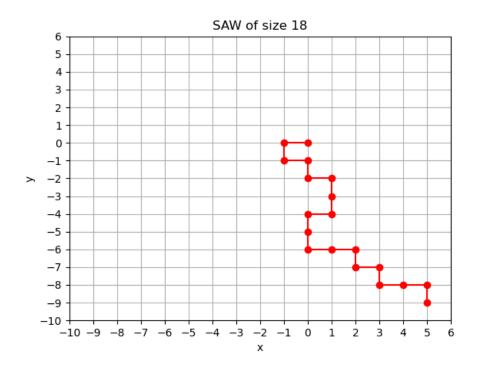


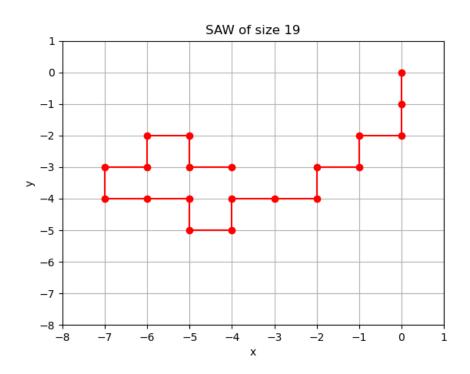


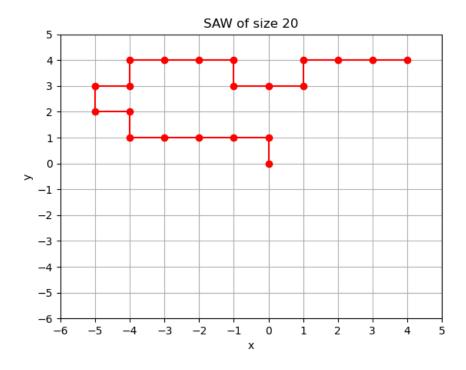












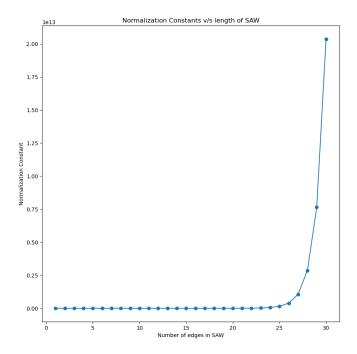
We can use this method to even compute the total count of the random walks  $Z_d$  for a given value of d. The following code snippet is doing the same:

```
1: def GetNormalizationConstantWithoutResampling():
       wFrames = []
2:
3:
       n = 1000
4:
5:
       m = 5
       d = 30
7:
       for i in range(n):
           status, x_frame, y_frame, w_frame = GetSelfAvoidingWalk(m, d, False)
8:
9:
           if (status == True):
10:
               wFrames.append(w_frame)
11:
12:
       Ws = pd.concat(wFrames, ignore_index=True)
13:
14:
       dims = np.arange(1, d + 1)
15:
       constants = Ws.mean()
16:
       constants = (constants[1:]).astype(np.int64)
17:
18:
       print(constants)
19:
20:
       fig, ax = plt.subplots(nrows=1, ncols=1, figsize=(10, 10))
21:
       ax.plot(dims, constants, marker='o')
22:
       ax.set_title('Normalization Constants v/s length of SAW')
23:
       ax.set_xlabel('Number of edges in SAW')
       ax.set_ylabel('Normalization Constant')
24:
25:
26:
       grpahName = '/Users/utkarsh/NYU/Monte Carlo Methods/Homeworks/homework3/' +
                                                    'question2_normalization' + '.
                                                   png,
```

### 27: plt.savefig(grpahName)

Below is the image and graph with the count

```
/Users/utkarsh/.conda/envs/PyTorchTesting
1
2
                 12
                 36
4
                99
5
                284
                775
               2152
8
               5867
              16058
10
              43685
             119391
11
             327722
13
             890853
            2428813
14
            6679559
16
           18261258
17
           49982024
18
          136528692
19
          374555010
20
         1035118208
         2819807559
         7637996876
22
23
        20804498970
        56909020984
25
       156015204801
       422159311514
26
      1126806729002
      3031335494199
28
29
      8159539941917
30 21612966197151
dtype: int64
Process finished with exit code 0
```



We can clearly see that there is exponential relationship between length and count of SAW.