

MST part of Lecture 10 : Thu 25th Aug 2016, EE-677-2016

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1 Python script for Prim's algorithm for finding

Caution : This is a "first-cut" and "inefficient" implementation of Prim's algorithm for finding MST (minimum spanning tree).

For simplicity we also assume that the input graph is a connected graph.

Let us prepare the script. Let's name this function after Prim who invented this algorithm for computing MST (minimum spanning tree).

Within this function **PrimMST**, we will work with the list of nodes V . For simplicity we will assume it to be $V = [0,1,2,\dots,N-1]$.

This greedy algorithm would maintain the set of nodes of the partial MST, using an indicator list, namely, **isNodeInPartialMst**.

Let $V(\text{partialMST})$ denote the set of nodes of this partial MST, and let $E(\text{partialMST})$ denote set of its edges.

Then $v \in V(\text{partialMST})$ if and only if **isNodeInPartialMst[v] == True**.

Furthermore to represent $E(\text{partialMST})$, we will use the idea that in each iteration, we add an edge to the *partialMST*, and this edge is between the newly added node, say **nextNode** and another node that was already in the *partialMST*. This already existing node in *partialMST* is regarded as the **parent[nextNode]**.

In this manner, we represent $E(\text{partialMST})$ with the help of the list **parent**, such that $(u,v) \in E(\text{partialMST})$ if and only if **u == parent[v]** or **v == parent[u]**.

PrimMST_lec10_Thu25Aug16_ee677_2016.py

```
MAX=99999999
```

```
def PrimMST ( neighbors , costOfEdges ) :

    V = range ( len ( neighbors ) )

    numV = len( V )
    isNodeInPartialMst = [ False for v in V ]
    parent = [ None for v in V ]

    isNodeInPartialMst[0] = True

    for i in range( numV - 1 ) :

        nextNode, parentOfNextNode = \
            findNodeNotInPartialMstThatIsNearestToPartialMst ( \
                neighbors, costOfEdges, isNodeInPartialMst )
        if ( nextNode == None ) :
            raise Exception( "Graph is disconnected " )

        isNodeInPartialMst [ nextNode ] = True
        parent [ nextNode ] = parentOfNextNode

    return parent

def findNodeNotInPartialMstThatIsNearestToPartialMst \
    ( nbrs , cost, partialMstIndicator ) :
    V = range ( len ( nbrs ) )
    numV = len ( V )

    tmp = MAX
    bestNode = None
    parentOfBestNode = None
    for v in V :
        if ( partialMstIndicator [ v ] == False ) :
            for u in nbrs[ v ] :
                if (partialMstIndicator[u]==True) and (cost[v][u] <= tmp) :
                    tmp = cost[v][u]
                    bestNode = v
```

```

        parentOfBestNode = u
    return bestNode, parentOfBestNode

```

```

G_neighbors = [[1, 2, 3, 4, 5, 6, 7, 8, 9], \
    [0, 2, 3, 4, 5, 6, 7, 8, 9], \
    [0, 1, 3, 4, 5, 6, 7, 8, 9], \
    [0, 1, 2, 4, 5, 6, 7, 8, 9], \
    [0, 1, 2, 3, 5, 6, 7, 8, 9], \
    [0, 1, 2, 3, 4, 6, 7, 8, 9], \
    [0, 1, 2, 3, 4, 5, 7, 8, 9], \
    [0, 1, 2, 3, 4, 5, 6, 8, 9], \
    [0, 1, 2, 3, 4, 5, 6, 7, 9], \
    [0, 1, 2, 3, 4, 5, 6, 7, 8]]

```

```

cost_edges = [[0, 25, 65, 49, 55, 4, 59, 21, 98, 8], \
    [25, 0, 39, 27, 35, 3, 5, 21, 45, 89], \
    [65, 39, 0, 22, 77, 91, 93, 15, 8, 7], \
    [49, 27, 22, 0, 36, 89, 45, 13, 3, 2], \
    [55, 35, 77, 36, 0, 79, 78, 77, 15, 62], \
    [4, 3, 91, 89, 79, 0, 70, 64, 11, 99], \
    [59, 5, 93, 45, 78, 70, 0, 73, 41, 57], \
    [21, 21, 15, 13, 77, 64, 73, 0, 35, 20], \
    [98, 45, 8, 3, 15, 11, 41, 35, 0, 40], \
    [8, 89, 7, 2, 62, 99, 57, 20, 40, 0]]

```

```

print "parents of nodes in mst obtained by Prim's algo are \n", \
    PrimMST( G_neighbors, cost_edges )
#output : parents of nodes in mst obtained by Prim's algo are
#output : [None, 5, 9, 9, 8, 0, 1, 3, 3, 0]

```