

## 物联网和机器人导论 VIPLE工作流程编程

Introduction to IoT and Robotics,  
based on Visual Programming  
Experiments

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## Lectures of the Course

<http://neptune.fulton.ad.asu.edu/VIPLE/>

- ASU VIPLE can be used as the lab environment in Introduction to Engineering's first semester. They can be used together with the VIPLE tutorial, which is a lab manual for writing experiments.
- L01 - About the Course and Syllabus
- L02 - CS Related Disciplines
- L03 - VIPLE - Visual IoT/Robotics Programming Language Environment
- L04 - AI-U Simulation in VIPLE
- L05 - Number systems
- L06 - Finite State Machine and Programming
- L07 - Algorithms
- L08 - Event Driven Programming
- L09 - Programming Languages
- L10 - Operating System
- L11 - Unix and Edison
- L12 - IoT and RaaS
- L13 - IoT and Augmented Reality
- L14 - from OOC to SOC
- L15 - SOC and Web Software
- L16 - Presentation Techniques
- L17 - Big Data
- L18 - Cloud Computing
- L19 - Amdahl's Law
- L20 - Ethics Theories

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## Lecture Outline

- 1 Introduction to VIPLE
- 2 General-Purpose Programming
- 3 Service-Oriented Programming
- 4 Parallel Programming
- 5 Event-Driven Programming

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## Workflow and Visual Programming

- Workflow defines a system through
  - Architecture: Service oriented using orchestration or choreography style
  - Interface: Partners and roles between the components
  - Behaviors: Activities and execution orders of activities
- Workflow is not necessarily visual
- BPEL is a workflow language, and it is text-based (XML)
- Workflow can be easily visualized and is often defined visually
- Oracle SOA Suite and JDeveloper visualize BPEL

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## Application of Visual Programming Languages

- Most workflow languages today are visualized;
- Simplified workflow languages are used in education:
  - MIT: Scratch - Visual Game Programming
  - University of Virginia and Carnegie Mellon: Alice Visual Game Programming
  - MIT App Inventor: Phone App Visual Programming
  - Lego NXT & EV3 – Visual Robotics Application Development
  - Microsoft Robotics Developer Studio Visual Programming Language (MRDS VPL)

VIPLE ASU VIPLE: Visual IoT/Robotics Programming Language Environment

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## VIPLE Programming Paradigms

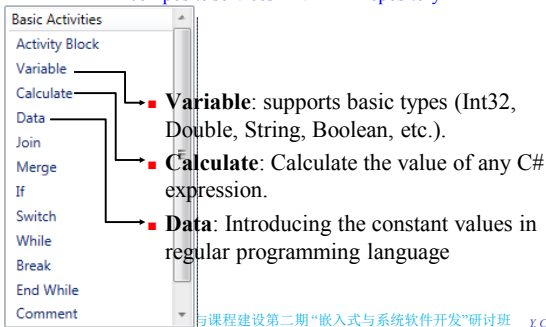
### VIPLE Features

- General-purpose control flow programming
- Service-oriented computing, supporting RESTful and WSDL
- Parallel / multithreading programming, with underlying threads safety
- Event-driven programming, with built-in and custom events
- Workflow and visual programming
- IoT and Robotics programming

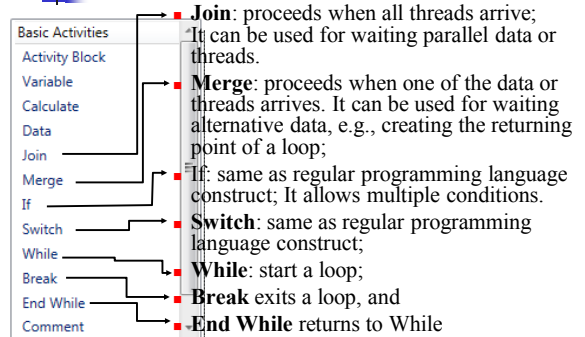
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## 7 Basic Activities of VIPLE

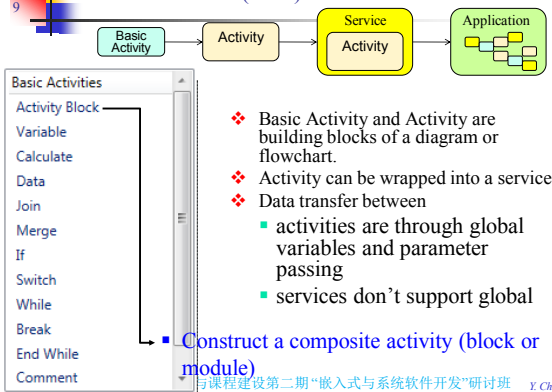
There are dozen of basic activities, and many composite services in VIPLE Repository



## 8 Basic Activities (cont.)



## 9 Basic Activities (cont.)



## 10 VIPLE Services

### General-purpose and event services

Services

- Code Activity
- Custom Event
- Key Press Event
- Key Release Event
- Print Line
- Random
- RESTful Service
- Simple Dialog
- Text to Speech
- Timer

### Generic robotic services

Robot

- Robot Color Sensor
- Robot Distance Sensor
- Robot Drive
- Robot Holonomic Drive
- Robot Light Sensor
- Robot Motor
- Robot Motor Encoder
- Robot Sound Sensor
- Robot Touch Sensor
- Robot+ Move at Power
- Robot+ Turn by Degrees

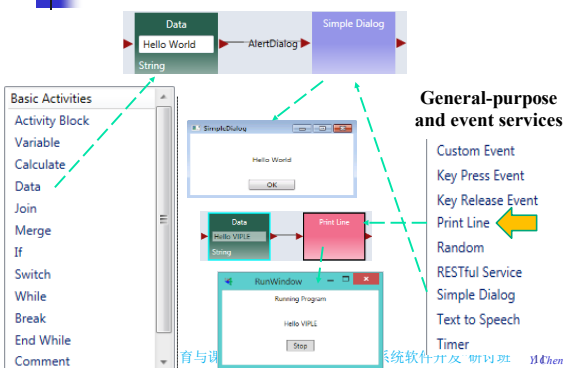
### Vendor-specific robotic services

Lego EV3 Brick

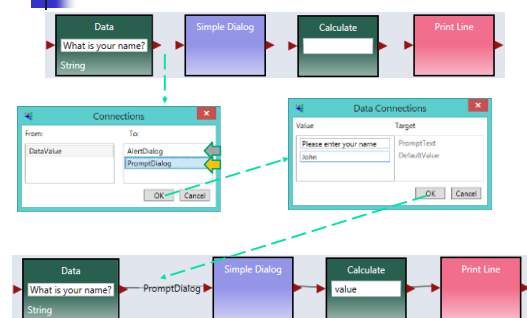
- Lego EV3 Color
- Lego EV3 Drive
- Lego EV3 Drive for Time
- Lego EV3 Gyro
- Lego EV3 Motor
- Lego EV3 Motor by Degrees
- Lego EV3 Motor for Time
- Lego EV3 Touch Pressed
- Lego EV3 Touch Released
- Lego EV3 Ultrasonic

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## VIPLE Programming: Output

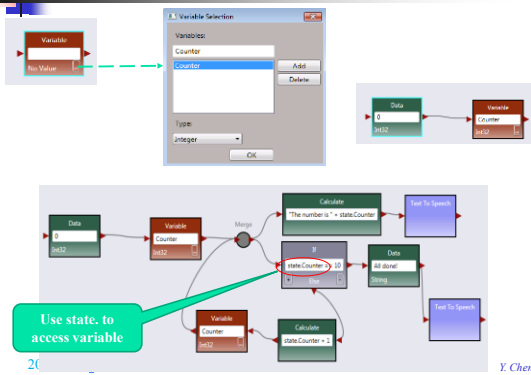


## 12 VIPLE Programming: Input

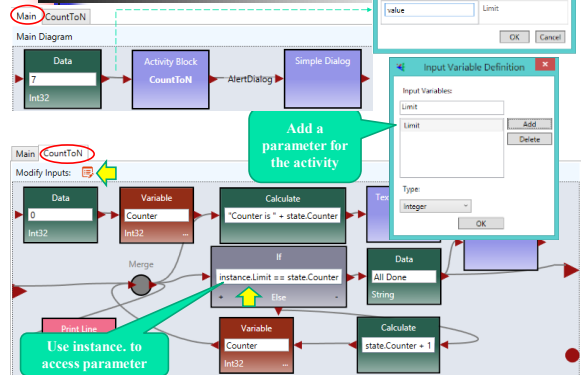


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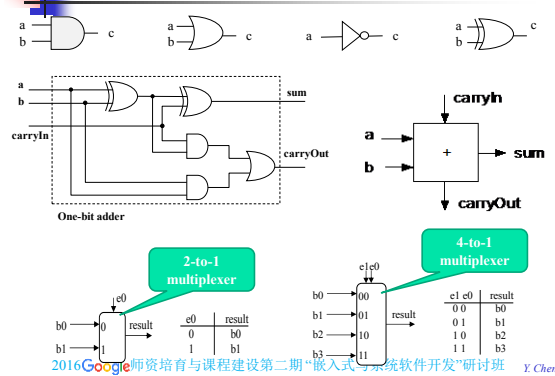
### 13 VIPLE Programming: Variable and Loop



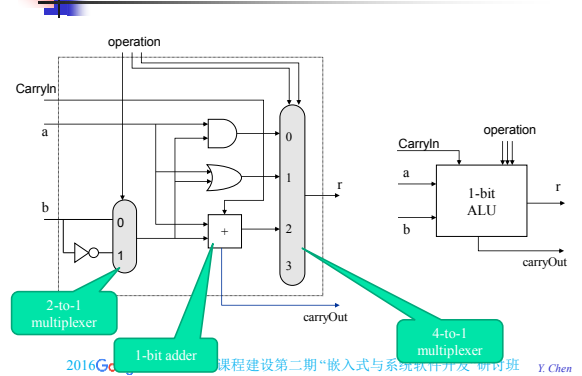
### 14 Activity and Parameter Passing



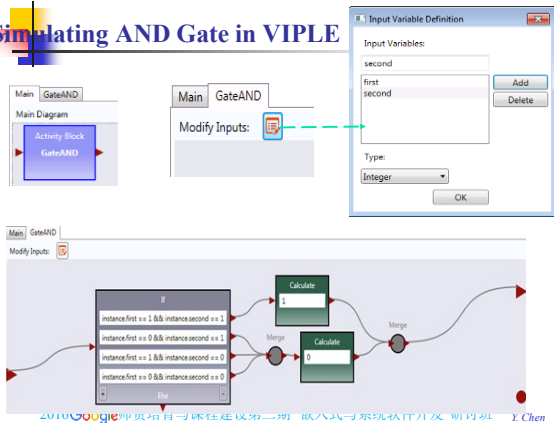
### 15 Case Study: Simulating an ALU



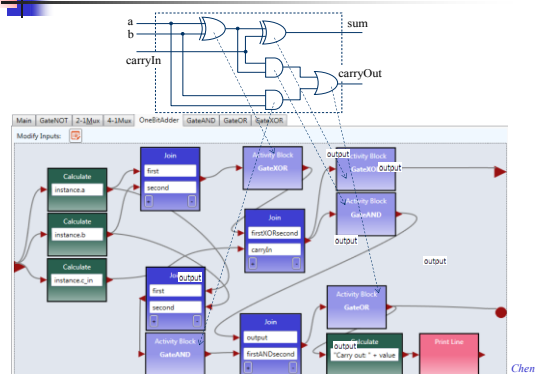
### 16 One-Bit ALU



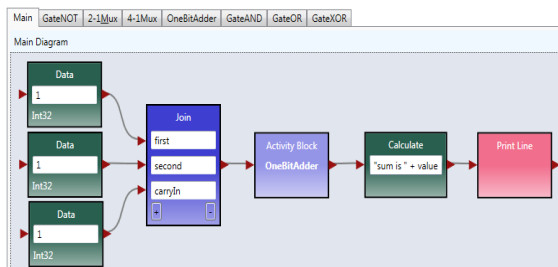
### Simulating AND Gate in VIPLE



### 18 Case Study: Building the One-Bit Adder

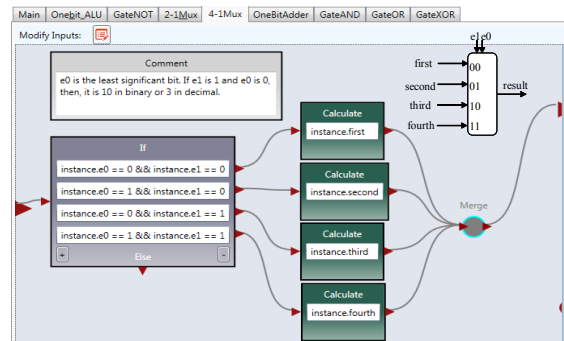


## 19 Testing the One-Bit Adder

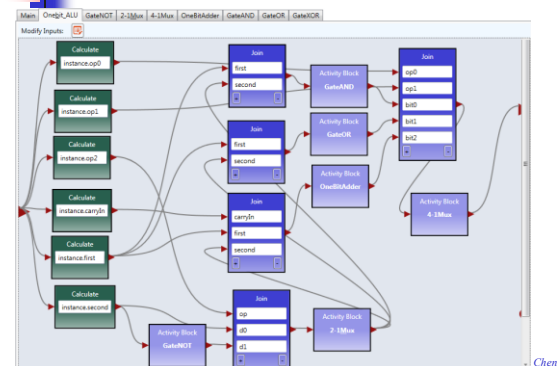


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## 20 Creating 2-1 Multiplexor

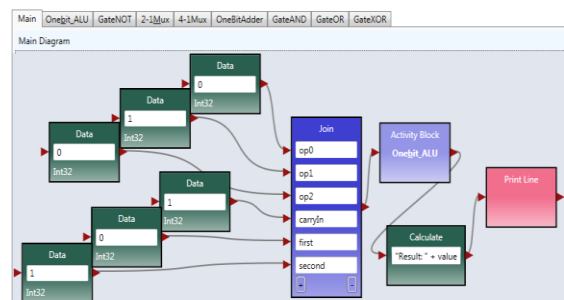


## 21 Creating One-Bit ALU



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## 22 Testing One-Bit ALU



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## 23 Automated Test Case Generation

- Manual testing is time consuming and tedious
- Analyze the test case generation for 1-bit adder

CountTo7	a	b	carryIn
0	0	0	0
1	0	0	1
2	0	1	0
3	0	1	1
4	1	0	0
5	1	0	1
6	1	1	0
7	1	1	1

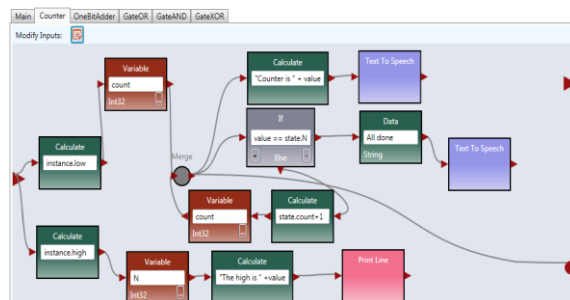
if CountTo7 = 0, 1, 2, 3, then a = 0, else a = 1;

if CountTo7 = 0, 1, 4, 5, then b = 0, else b = 1;

if CountTo7 = 0, 2, 4, 6, then carryIn = 0, else carryIn = 1;

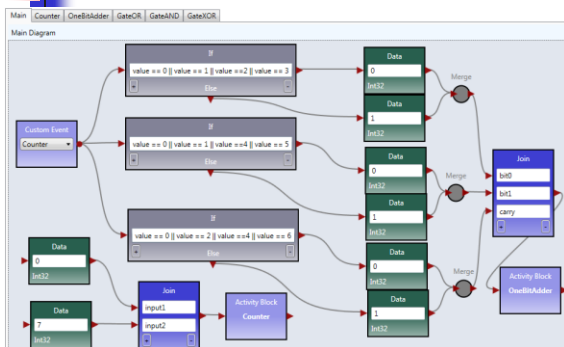
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## 24 Counter that Generate Test Cases as Events



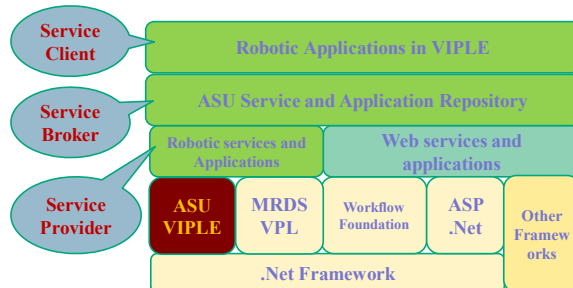
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## 25 Automated Testing of One-Bit Adder



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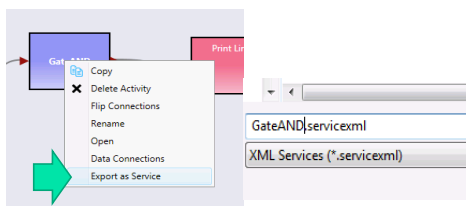
## ASU VIPLE is Service Oriented



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## 27 Converting an Activity into a Service

- An activity is a part of an application
- It cannot be reused in another application
- To convert an activity into a service:  
Right click:



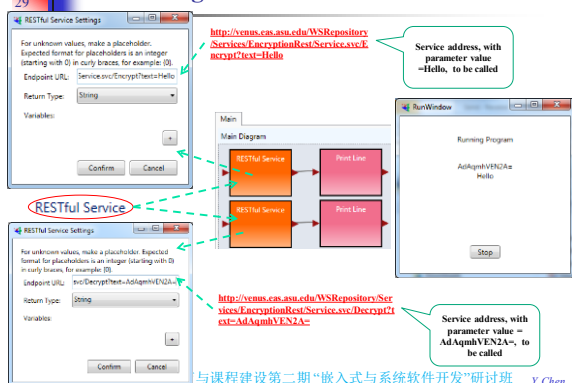
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## 28 After a Custom Service is Created

- When you “Export as Service”, you can save the service anywhere you want.
- By default, it will be saved into the “CustomServices” folder in your VIPLE program folder.
- When VIPLE is started, all services will be imported into the VIPLE service list, where you find the other services like Print Line and Text to Speech.
- To delete (remove) a custom service, open the folder CustomServices and delete the file of the service. After you restart the service, the custom service will disappear from the service list.
- To share a service in another application, copy the service file into the CustomServices folder of another application.

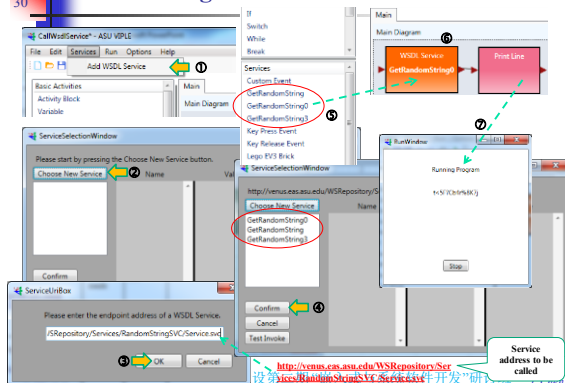
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## 29 Calling RESTful Services



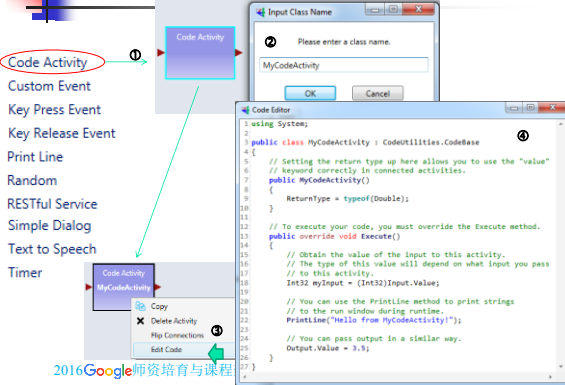
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## 30 Calling a WSDL Service



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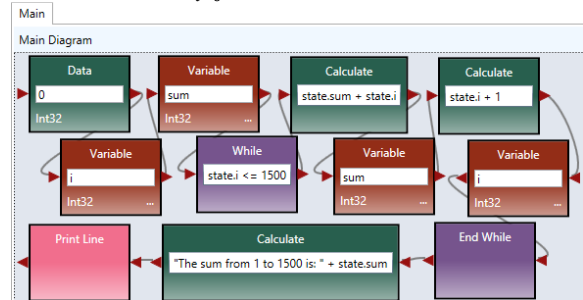
### 31 Code Activity: Wrap any C# Class into an Activity



### 32 Sequential vs. Parallel Computing

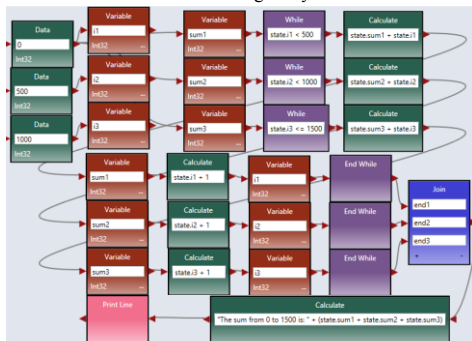
- Sequential version of adding many numbers  

$$\text{sum} = \sum_{i=0}^n i$$



### 33 Parallel / Distributed Computing

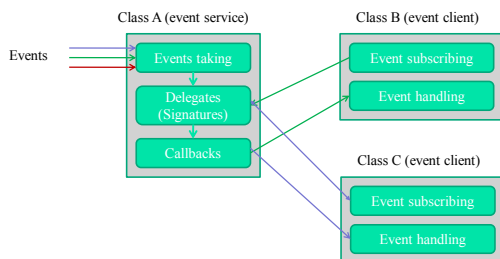
- Parallel version of adding many numbers



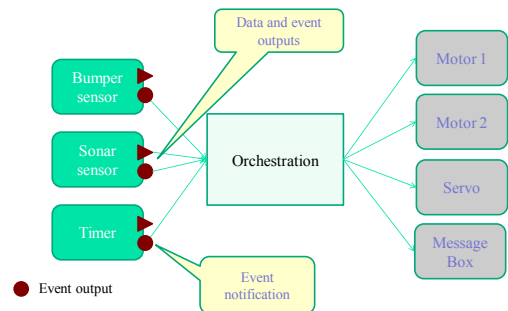
### 34 Events and Event Handling

- A common technique in distributed computing
  - XML validation and handling
  - Exceptions and handling
  - Mouse click and code processing the click
  - Sensory input arrived (touch sensor) and the action
  - A timer elapsed and the action
- Event-driven computing assumes there are multiple processors to handle events in parallel
- Event handling process
  - Class A publishes event delegates (signatures) for subscription;
  - Class B implements an event handler and subscribes to an event delegate by adding the handler name into the delegate;
  - When an event occurs in class A, class A will callback the handler in class B, which handles the event.

### 35 Events and Event Handling (Contd.)



### 36 Concurrency and Events in Robotics Programming

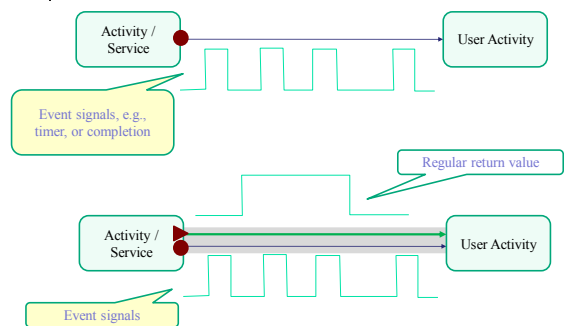


## 37 Concurrency and Events in Robotics Programming

- Handling sensory inputs and controlling actuators must be dealt with concurrently, as otherwise sensor inputs can easily be ignored and actuators can get starved.
- Orchestration and composition should not be in control flow model. Event-driven model is a better way to handle such applications.
- Event notification can be sensible alone, or in combination with the return data

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## 38 Event-Driven Notification



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## 39 Event-Driven Programming

VIPLE supports two types of events

- Custom events: Allow programmers to define an event as an activity's output
- Built-in events: Predefined services in the VIPLE service list that generate events

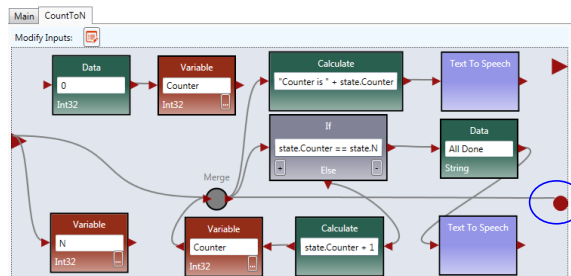
General-purpose and event services

Custom Event  
Key Press Event  
Key Release Event  
Print Line  
Random  
RESTful Service  
Simple Dialog  
Text to Speech  
Timer

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## 40 Event-Driven Programming: Custom Event

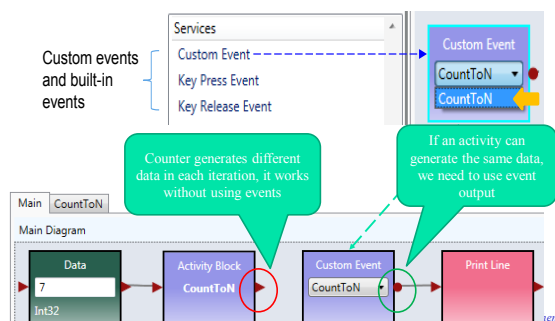
- Implementing the CountToN activity with event output



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## 41 Event-Driven Programming: Custom Event

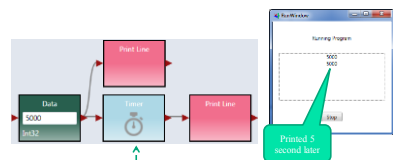
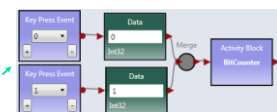
- Accessing the custom event



## 42 Event-Driven Programming: Key Press Event

General-purpose and event services

Code Activity  
Custom Event  
Key Press Event  
Key Release Event  
Print Line  
Random  
RESTful Service  
Simple Dialog  
Text to Speech  
Timer



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