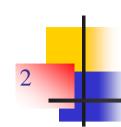
物联网和机器人导论可视化编程概述

Introduction to IoT and Robotics, based on Visual Programming

Experiments

Yinong Chen Arizona State University, U.S.A.



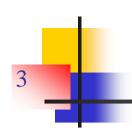
Yinong Chen (陈以农)

Heinrich **Hertz** worked at Univ. *Karlsruhe* from 1885 to 1888, where he discovered electromagnetic waves

- ▶ 重庆大学1982 学士& 1984硕士
- > 1993 博士 at University of Karlsruhe (KIT), 德国
- > 1995 1996 Postdoc at LAAS-CNRS, Toulouse, 法国
- > 1994 2000: Wits University of Johannesburg, 南非
- > 2001 present: Arizona State University亚利桑那州立大学
- ➤ More: http://www.public.asu.edu/~ychen10/







Syllabus: Course Objectives

ASU Course FSE100 Introduction to Engineering (工程导论) for freshman students

- To discover the excitement and creativity in the practice of engineering and computer science.
- 2. To learn and use the engineering design process.
- 3. To learn to work in a team environment.
- 4. To improve technical communication skills by writing and speaking about the projects in the course.



Class Format

One hour of conventional lecture

Three hours of interactive lecture and laboratory

At least 4 hours after/before class study / week

Concepts, Principles, Methods, Theories
In-class exercises, Exams
Mandatory topics required by engineering program,
such as engineering principles, architecture,
design methodology, ethics, etc

Team work, Interaction
Hand-on, Programming, Experimentation
Lab assignment to complete
The latest technology that are useful and exciting, such as game programming, animation, ebusiness, robots, etc.

- Read the lecture slides before class
- Read the related book chapter/sections after the class
- Prepare for the lab before the lab session: There is a pre-lab-quiz to enforce the preparation
- Complete homework / project



Sample Lectures Available Online

http://neptune.fulton.ad.asu.edu/VIPLE/

a TOL About the Course and Sullabus	My Spring 2016 offering
L01 - About the Course and Syllabus	
L02 - CS Related Disciplines	ా 🚅 1. Day One Issues FSE100
 L03 - VIPLE - Visual IoT/Robotics Programmir 	ig La
 L04 - ALU Simulation in VIPLE 	2. Engineering Desig Process 1
• L05 - Number systems	🔃 3. Engineering Desig Process 2
L06 - Finite State Machine and Programmig	4. Engineering Desig Process 3
o L07 - Algorithms	4. Engineering Desig Process 5
L08 - Event Driven Programming	▲ 🚅 5. Software Engineering and VIPLE
L09 - Programming Langauges	🔌 🟥 6. Computer and Logic Design
 L10 - Operating System 	7 - Finite State Machine and Programmig
L11 - Unix and Edison	
L12 - IoT and RaaS	→ 📲 8 - Algorithms
L13 - IoT and Augmented Reality	The continue Continue
	9 - Operating Systems
L14 - from OOC to SOC	→ 🖆 10 - Robotics
 L15 - SOC and Web Software 	
 L16 - Presentation Techniques 	🖺 11 - Teamwork and Meeting
o L17 - Big Data	12 - Presentation Techniques 2016
L18 - Cloud Computing	12 - Fresentation rechinques 2010
L19 - Amdahls Law Table File	
 L20 - Ethics Theories 	🖭 14 - Monte Carlo Simulation

6

Weekly Lab Assignments





Crisis in Computing 计算机专业的危机

Source: **ACM** Computer Science Curriculum 2008 http://www.acm.org//education/curricula/ComputerScience2008.pdf

- Crisis in Computing: Computer Science enrollment dropped dramatically after 2000 in many countries; 2000年开始,计算机专业招生人数大幅度下滑。
- ACM 2008 出版危机报告,建议
 - 市场需求: 美国95%的增长是在信息技术领域
 - 改变计算机专业的授课方法,特别是一年级的课程:
 - ■面向应用
 - 内容要生动
 - ■形式要多样:机器人、游戏、手机App、多媒体

8

Motivation: 为什么要学习IoT和机器人编程?

- 为什么要学习计算机编程?
- 第一门编程语言教(学)什么?
 - C/C++? Java?
 - Python? Scheme / LISP?
- 您第一个操作系统 用的是什么?
 - iOS (Apple) ?
 - Windows (Microsoft) ?
 - Android (Google)?
 - DOS 或 LINUX ?
- 学编程像学操作系统那样容易吗?
- 那大学四年学什么?
- 学习和锻炼解决问题的能力

9

Motivation: 为什么要学习计算机科学?

- 读大学、选专业很重要
- 根据兴趣选专业
 - 根据兴趣选专业
 - 没有工作机会怎么办?
- 根据市场需求选专业
 - 没有兴趣绝对学不好专业、 混学、辍学
 - 怎么办?
- 根据市场需求、培养兴趣、选专业
 - 可行吗?
 - 当然可行。ACM推荐,我的经历和经验

Engineers (U.S. DoL OCO Handbook 2010-2011)

0	http://www.bls.	ov/oco/				
		Employment,	Projected Employment,		nge, 8-18	
	Occupational Title	2008	2018	Number	Percent	
	Engineers	1,571,900	1,750,300	178,300	11	
	All Engineers	1,571,900	1,750.30	00	11	
	Biomedical engineers	16,000	27,600	11,600	72	
	Chemical engineers	31,700	31,000	-600	-2	
	Civil engineers	278,400	345,900	67,600	24	
	Computer hardware engineers	74,700	77,500	2,800	4	
	Electrical and electronics engineers	301,500	304,600	3,100	1	
	Electrical engineers	157,800	160,500	2,700	2	
	Electronics engineers, except computer	143,700	144,100	400	0	
	Environmental engineers	54,300	70,900	16,600	31	
	Industrial engineers, including health and safety	240,400	273,700	33,200	14	
	Health and safety engineers, except mining safety engineers and inspectors	25,700	28,300	2,600	10	
	Industrial engineers	214,800	245,300	30,600	14	
	Marine engineers and naval architects	8,500	9,000	500	6	
	Materials engineers	24,400	26,600	2,300	9	
	Mechanical engineers	238,700	253,100	14,400	6	
	Mining and geological engineers, including mining safety engineers	7,100	8,200	1,100	15	
	Nuclear engineers	16,900	18,800	1,900	11	
	Petroleum engineers	21,900	25,900	4,000	18	
	All other engineers	183,200	195,400	12,200	7	

Software Engineers and CS Occupations (There are many more) in U.S. DoL Occupational Outlook Handbook

All Engineers 1,571,900 1,750.300 11

Occupational title	Employment in 2008	Employment in 2018	Change in number	Change in percentage
Software Engineers	909,600	1,204,800	295,200	32
Computer systems analysts	532,200	640,300	108,100	20
Computer network, systems, and database administrators	961,200	1,247,800	286,600	30
Computer programmers	426,700	414,400	-12,300	-3
Computer support specialists	565,700	643,700	78,000	14
Computer and information systems managers	293,000	342,500	49,500	17



BEST JOBS IN AMERICA



A Service of CNN, Fortune & Money 2009

MONEY Magazine and Salary.com rate careers on salary and job prospects.

http://money.cnn.com/magazines/moneymag/bestjobs/2009/sectors/

Job Sector	Job Title	Growth	Rank	
Information Technology	Systems Engineer	45%	1	
Information Technology	Information Technology Project Manager	16%	5	
Information Technology	Computer/Network Security Consultant	27%	8	
Information Technology	Software Developer	28%	12	10
Information Technology	Software Product Manager	28%	16	$\frac{10}{40}$
Information Technology	Business Analyst, IT	29%	17	••
Information Technology	Technical Writer	20%	28	
Information Technology	Telecommunications Network Engineer	53%	30	
Information Technology	Computer Software Program Manager	28%	39	
Information Technology	Applications Systems Analyst	29%	40	





http://money.cnn.com/magazines/moneymag/bestjobs/2010/sectors/#I

Sector	Job Title	Rank in top 40	
	Software Architect	1	
	Database Administrator	7	
<u>></u>	Information Systems Security Engineer	17	
<u> </u>	Software Engineering / Development Director	18	
0	Information Technology Manager	20	
Information Technology	Telecommunications Network Engineer	21	
Ha <	Network Operations Project Manager	24	15
L C	Information Technology Business Analyst	26	40
atic	Information Technology Consultant	28	
Ë	Test Software Development Engineer	30	
for	Information Technology Network Engineer	31	
<u> </u>	Information Technology Program Manager	33	
	Computer and Information Scientist	35	
	Programmer Analyst	37	
2016	Applications Engineer	38	. Chen

CNN Toney.com* BEST JOBS IN AMERICA 2012

Ran k	Job Title	Median Salary	2011 Job number	10 year growth rate	2021 Job number
1	Biomedical Engineer	\$79,500	15,700	61.7%	25,387
2	Marketing Consultant	\$92,100	282,700	41.2%	399,172
3	Software Architect	\$119,000	3,426,000	24.6%	4,268,796
4	Clinic Research Associate	\$90,700	100,000	36.4%	136,400
5	Database Administrator	\$87,200	110,800	30.6%	144,705
6	Financial Adviser	\$90,200	206,800	32.1%	273,183
7	Market Research Analyst	\$63,100	282,700	41.2%	399,172
8	Physical Therapist	\$76,700	198,600	39.0%	276,054
9	Software Developer	\$84,200	3,426,000	24.6%	4,268,796
10	Occupational Therapist	\$74,900	108,800	33.5%	145,248
11	Management Consultant	\$110,000	718,800	21.9%	876,217
12	Optometrist	\$105,000	34,200	33.1%	455,20
13	IT Consultant	\$96,400	544,400	22.1%	664,712
14	IT Network Engineer	\$73,400	347,200	27.8%	443,722
15	IT Security Consultant	\$102,000	347,200	27.8%	443,722



What does the data mean?

■ Biomedical Engineer: 25,387 jobs in 10 years

Biomedical Engineer

- 50 states: 25,387 / 50 = 508
- Assume each person holds the job for 30 years
 New jobs available will be 508/30 = 17
- Arizona Universities graduate 100 students
 The chance of finding a job is: 17%

Software Architect: 4,268,796 in 10 years

Software Architect

- 50 states: 4,268,796 / 50 = 85375
- Assume each person holds the job for 30 years
 New jobs available will be 85375 / 30 = 2845
- Even if Arizona Universities graduate 1000 students there are 1845 positions cannot be filled.



2015

http://money.cnn.com/pf/best-jobs/

Top Ten Jobs



Software Architect



Video Game Designer



Landman



Patent Agent



See the full list

Hospital Administrator



Continuous Improvement Mgr.



Clinical Nurse Specialist



Database Developer



Info Assurance Analyst



Pilates/Yoga Instructor



Salary Data of Computer Science Related

Database manager	\$84,750 - 3	\$116,000
Database manager	\$84,73	U - 1



可视化编程环境



MIT: Scratch - Visual Game Programming



University of Virginia & Carnegie Mellon University: Alice Visual Game Programming



MIT/Google App Inventor: Phone App Visual **Programming**



Lego NXT & EV3 – Visual Robotics Application Development



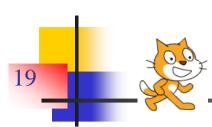
Intel IoT Services Orchestration Layer



Microsoft Robotics Developer Studio Visual Programming Language MRDS VPL



ASU VIPLE: Visual IoT/Robotics Programming Language Environment



MIT: Scratch - Visual Game Programming

https://scratch.mit.edu/

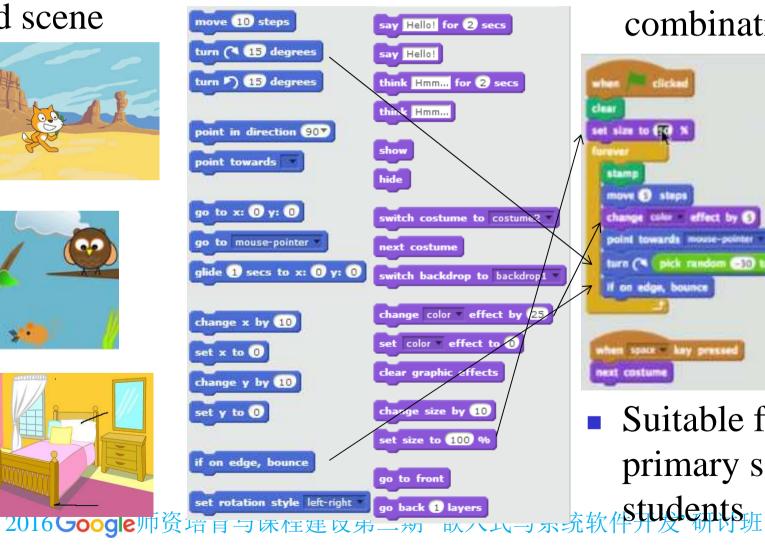
Select figures and scene







Select functions



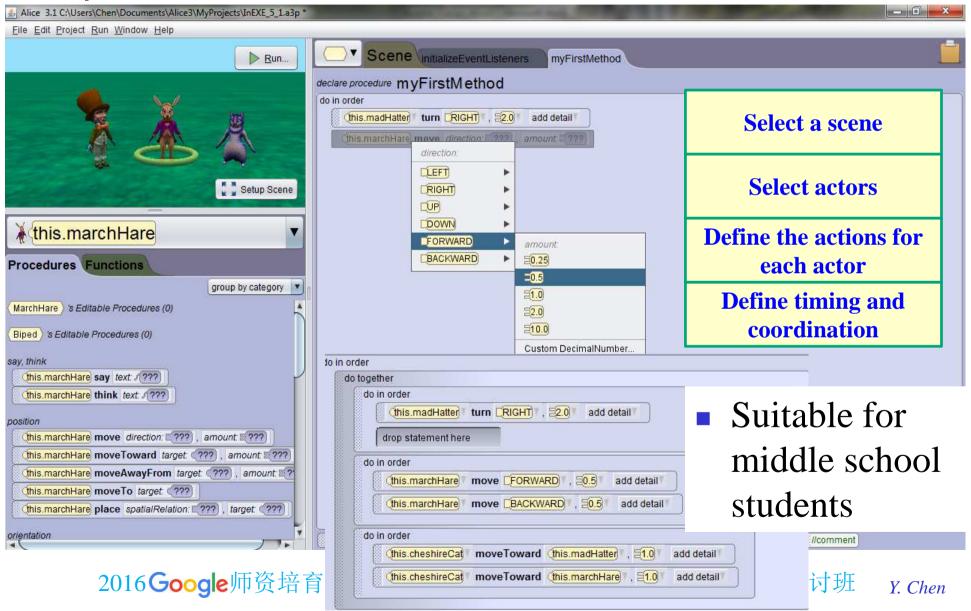
Define their combinations

```
dicke
set size to (10)
  move 3 steps
  ture ( pick random -30 to 30 degrees
 when space key pressed
```

Suitable for primary school



Alice Game Programming Environment

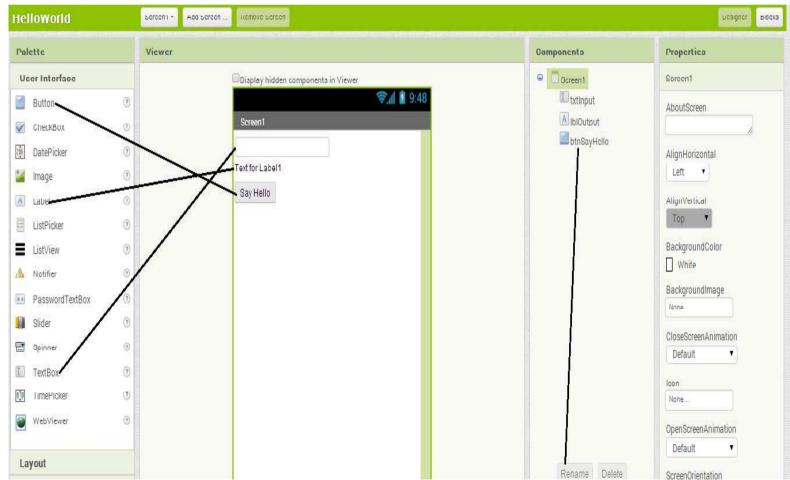




MIT/Google App Inventor for Android Phone

- Web based GUI design
- Visual programming using drag and drop
- Emulator or physical Android phone
- Web site: http://appinventor.mit.edu

Suitable for high school & college students





MIT App Inventor for Android Phone

X

ЛВ № ПП (С) 9:21 РМ

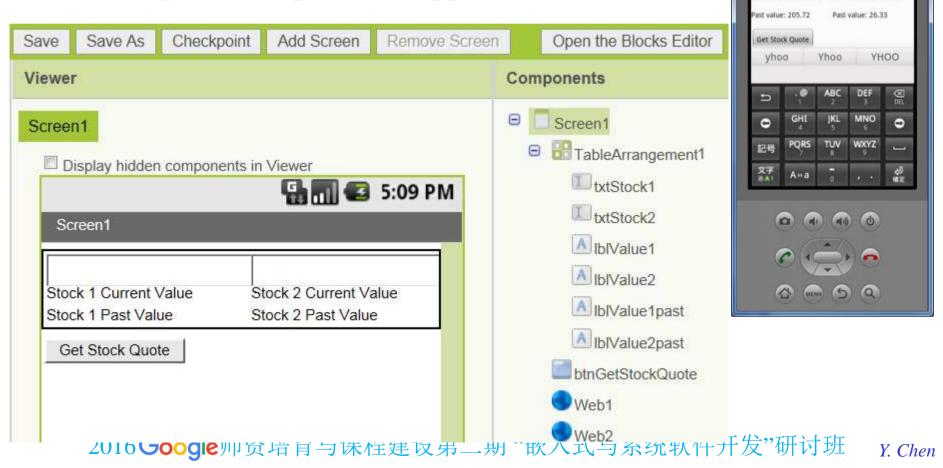
yhod

5554:<build>

Used for developing Android phone apps

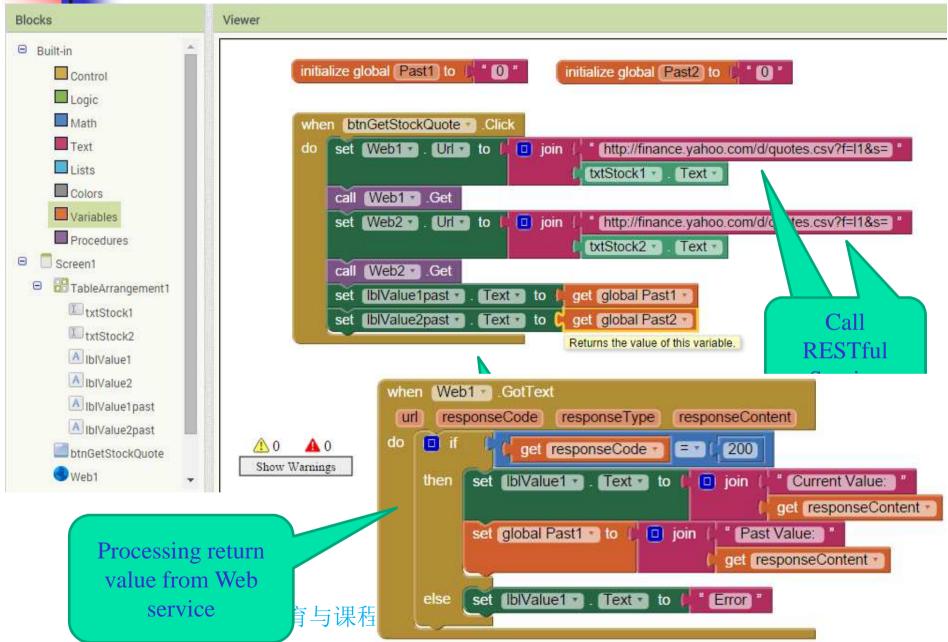
Service-oriented: call services to get job done

Example: A simple stock app





Code Behind the Stock App



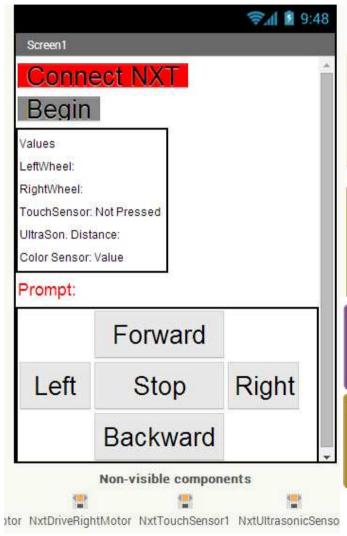


Implementing a Game: BrickPong

```
₽ П € 1:35 рм
                                                                                                       when Restart Click
                               to updateScore
                                                                                                           set global gameStarted to false
                                   if
                                               get global remainingBricks
                                                                                                           set Ball1 . Speed to
                                                                             You Win! Score:
                                         set Score
                                                     Text to
                                                                  ioin
                                                                                                           call Ball1 .MoveTo
                                                                            get global score
                                                                                                                                150
                                                                             Remaining Bricks:
                                                                                                                                 260
                                                                            get global remainingBricks
                                                                                                           call PlayerBrick MoveTo
                                         set Ball1
                                                     Speed to 0
                                                                                                                                     125
                                                                                                                                     275
                                         set Score . Text . to
                                                                  oin join
                                                                             Score:
                                                                                                           Call ResetBrickPosition •
                                                                            get global score
                                                                                                           set global score to 0
                                                                             Remaining Bricks:
      Restart
Difficulty
                                                                                                           set global remainingBricks to 12
                                                                            get global remainingBricks
core:4 Remaining Bricks: 10
                                                                                                           call updateScore +
                                                     to addtoscore
                                                         set global score to
                                                                                   get global score +  get global brickValue
                                                         set global remainingBricks to get global remainingBricks
                                                         call updateScore
                                 Show Warnings
       MENU S Q
   BScoreBrick CollidedWith
                                              when MScoreBrick7 ... CollidedWith
                                                                                               when FScoreBrick11 ... CollidedWith
other
                                                other
                                                                                                 other
  set BScoreBrick . Visible to false
                                                                       Visible to false
                                              do set MScoreBrick7
                                                                                                    set FScoreBrick11
                                                                                                                                   to false
                                                                                                                         Visible •
   set global brickValue to 3
                                                   set global brickValue to [3]
                                                                                                    set global brickValue to [1]
   call addtoscore •
                                                  call addtoscore -
                                                                                                    call addtoscore •
                                                                                                                                   Y. Chen
```

2016Google师资培育与课程建设第二期"嵌入式与系统软件开发"研讨班

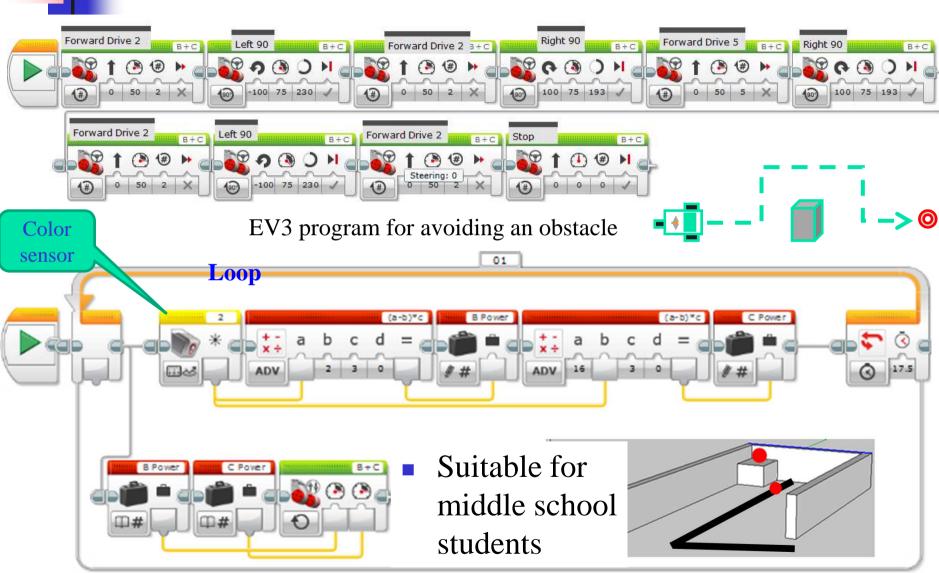
Lego NXT Robot App



```
initialize global (ConnectionMade) to 🏮 false
                                              when ConnectionListPicker BeforePicking
                                                  BluetoothClient1
                                                                                   AddressesAndNames = 0
                                                         set Prompter
                                                                                         Prompt: You must pair your phone to an NXT.
                                                                           Text to
                                                        set ConnectionListPicker
                                                                                     Elements to BluetoothClient1 AddressesAndNames
                                             when ConnectionListPicker AfterPicking
                                                             call BluetoothClient1 ... Connect
                                                                                               ConnectionListPicker •
                                                                                     address
                                                                                                                        Selection •
                                                       set ConnectButton
                                                                               BackgroundColor to
                                                         set global ConnectionMade to true
                                              when ConnectButton Click
                                                             BluetoothClient1 *
                                                                                IsConnected •
                                                        call BluetoothClient1
                                                                               .Disconnect
                                                                               BackgroundColor to
                                                         set ConnectButton
                                                        call ConnectionListPicker ... Open
                                                                                                                      when ForwardDrive Click
                                             to NxtMove
                                                                                                                                  get global ConnectionMade
                                               then set global LeftMotor to 100
                                                                                       get global LeftMotor
                                                                                                                              set global RightMotor to 1100
                                                call NxtDriveRightMotor ... . MoveForwardIndefinitely
                                                                                                                              cal NxtMove
                                                                                       gel global RightMotor
                                             when LeftTurn Click
                                                                                  when StopDrive . Click
                                                                                                                      when RightTurn Click
                                                         get global ConnectionMade -
                                                                                             get global ConnectionMade
                                                                                                                                  get global ConnectionMade *
                                                then set global LeftMotor to 100
                                                                                     then set global LeftMotor to ( 0
                                                                                                                         then set global LeftMotor to 1-100
                                                     set global RightMotor to 1 -100
                                                                                          set global RightMotor to 0
                                                                                                                              set global RightMotor to 100
                                                     call NxtMove -
                                                                                          call NxtMove -
                                                                                                                              call NxtMove -
                                                                                  hen Backwards Click
                                                                                             get global ConnectionMade
                                                                                     then set global LeftMotor to 4-100
                                                                                          set global RightMotor to -100
2016Google师资培育与
```



Lego EV3 Programming Environment



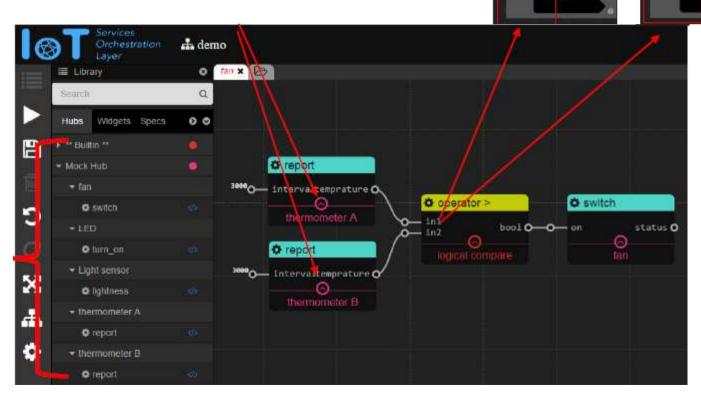


Intel IoT Service Orchestration Layer

Deliver a robust, extensible, high quality Solution for

creating IoT Apps in minutes

https://github.com/01org/intel-iot-services-orchestration-layer





Intel IoT Service Orchestration Layer

Demo –Add UI into Workflow



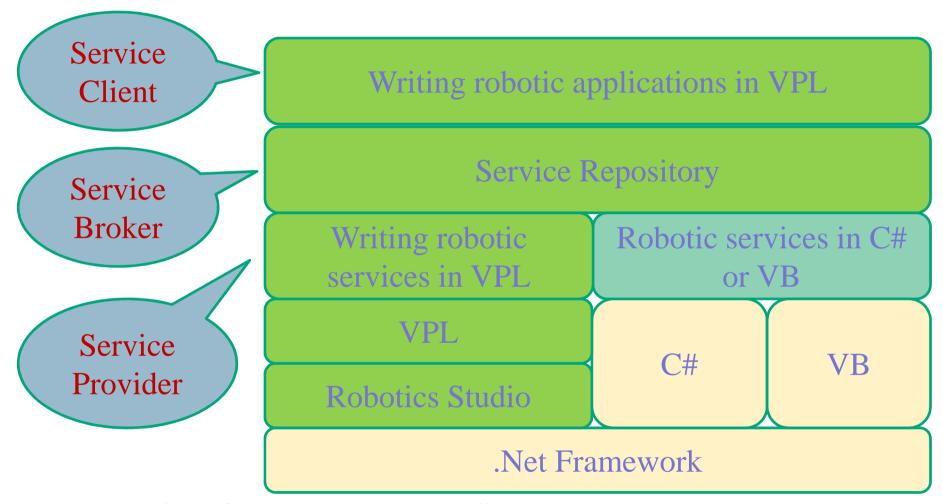
Design what End User would see

HTML5 UI widgets behave like a virtual IoT Thing



Microsoft Robotics Developer Studio MRDS and VPL





Download Microsoft Robotics Developer Studio 4

http://msdn.microsoft.com/en-us/robotics/aa731520



MRDS and VPL focus on Vendor-Specific Robots





Kuka

Robosoft











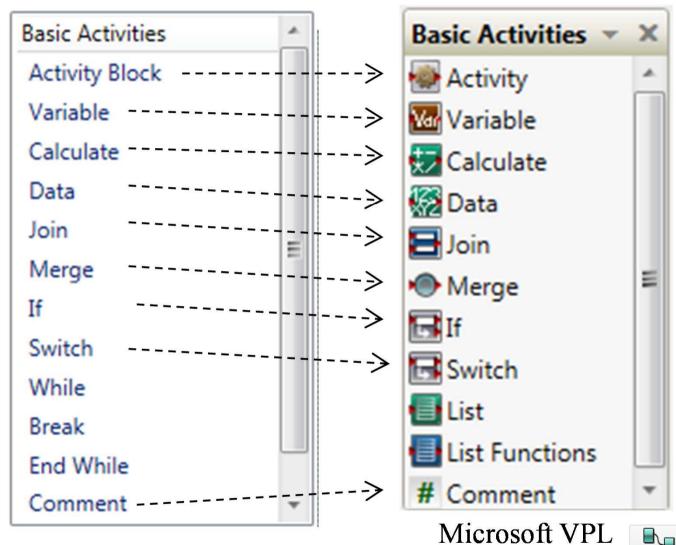
Problems with MRDS - VPL

- MRDS VPL is service-oriented, uses workflow-based visual programming, and supports many robotics platforms.
- It is a milestone and flagship in software engineering and in computer science education.
- Many universities and high schools have adopted VPL as a tool for teaching computing and engineering concepts and for programming robots.
- Unfortunately, as part of Microsoft's restructuring plan,
 MRDS VPL was suspended on September 22, 2014, leaving the VPL community without updates and support.
- No support for new platforms, such as EV3.
- ASU is among the schools that adopted VPL since its first release in 2006.
- We started to find a solution to our ESE100 in 2014 发"研讨班



VIP

VIPLE is developed to Help VPL Community



ASU VIPLE Basic Activities

Microsoft VPL

Basic Activities

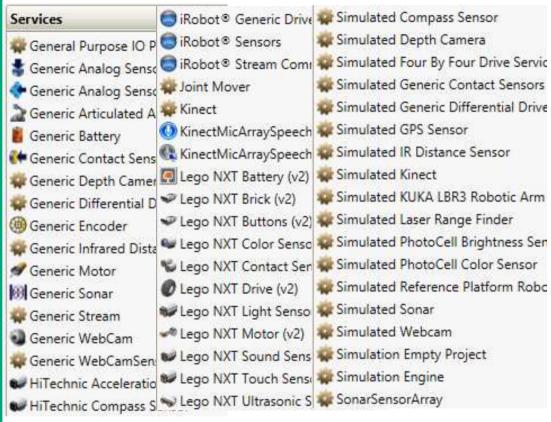




Lego EV3 Ultrasonic

VIPLE vs. VPL Services

Code Activity Robot Custom Event Robot Color Sensor Key Press Event Robot Distance Sensor Key Release Event Robot Drive Print Line Robot Holonomic Drive Random RESTful Service Robot Light Sensor Simple Dialog Robot Motor Text to Speech Robot Motor Encoder Timer Robot Sound Sensor Lego EV3 Brick Robot Touch Sensor Lego EV3 Color Robot+ Move at Power Lego EV3 Drive Lego EV3 Drive for Time Robot+ Turn by Degrees Lego EV3 Gyro Lego EV3 Motor Lego EV3 Motor by Degrees Lego EV3 Motor for Time Lego EV3 Touch Pressed Lego EV3 Touch Released



Microsoft VPL Generic, Vendor, and Simulated Services

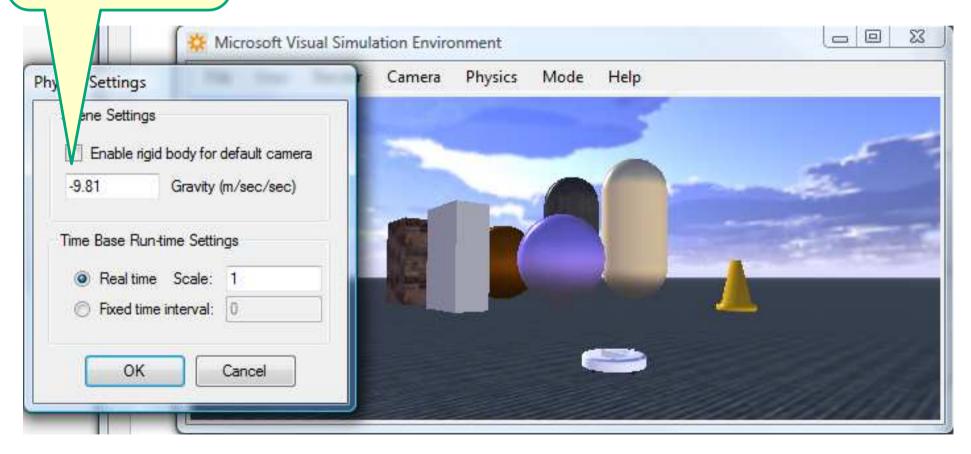


ASU VIPLE basic service, Simulated services, EV3 services, and Generic Services

MRDS VPL Simulation

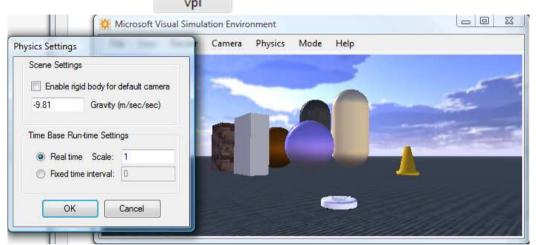
Change the value and see the behavior of the objects

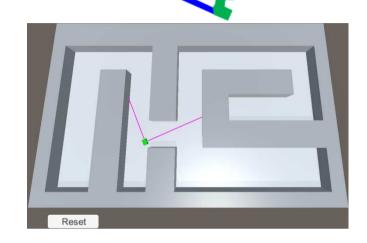
34

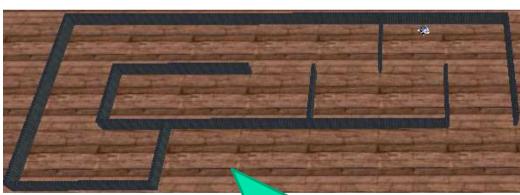


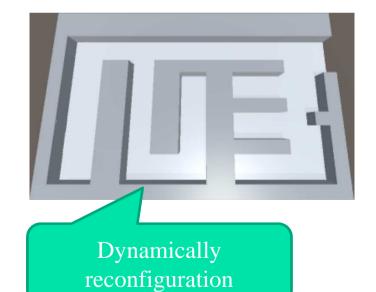
VPL vs

VPL vs. VIPLE Simulation Environment









Statically reconfiguration

2016Google师资培育与课程建设第二期"嵌入式与系统软件开发"研讨班

ASU Crisis and Solution -- ASU 危机和解决方案

- Crisis in Computing was experienced at ASU.
- CSE enrollments dropped 50% from 200 between 2002 and 2004. from 200 students to less than 100 students.
- Recruitment and retention become an issue for the first time
- Developing a new course to serve the purpose of recruitment and retention.



- CSE101 was first offered in with 70 students in two sections in Fall 2006.
- In Fall 2011, **350** students enrolled in 8 parallel sections
- CSE101 model (lecture + hands-on lab) is extended to FSE100 for all engineering students: CSE version emphasizes on robotics and programming. Other majors have different emphases.
- FSE100 for CS in Fall 2016: 15 sections, with 645 students 2016 Google师资培育与课程建设第二期"嵌入式与系统软件开发"研讨班 Y