

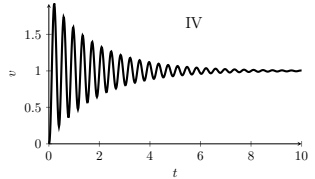
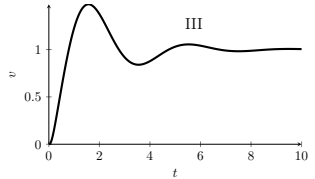
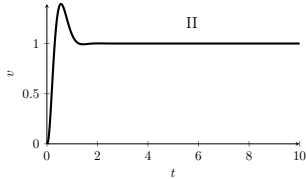
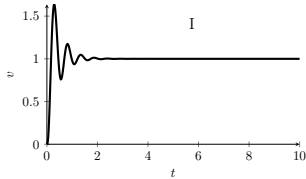
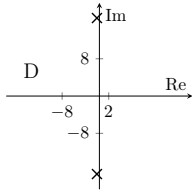
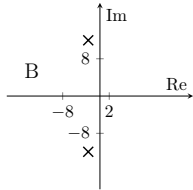
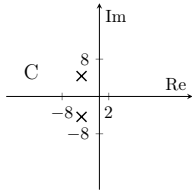
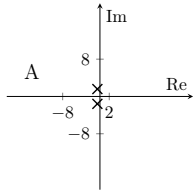
Root locus

Kjartan Halvorsen

2021-07-06

Pole-placement and time-response

Pair the pole-placement with the correct time-response (continuous time)!



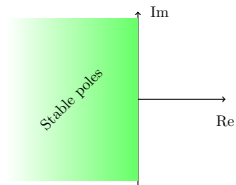
Mapping of poles from continuous time to discrete time

Continuous time

$$Y(s) \triangleq \mathcal{L}\{y(t)\}$$

$$Y(s) = G(s)U(s) = \frac{b}{s+a}U(s)$$

Pole of the system: $s + a = 0 \Rightarrow s = -a$

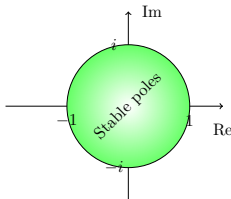


Discrete time

$$Y(z) \triangleq \mathcal{Z}\{y(kh)\}$$

$$Y(z) = H(z)U(z) = \frac{\beta}{z+\alpha}U(z)$$

Pole of the system: $z + \alpha = 0 \Rightarrow z = -\alpha$

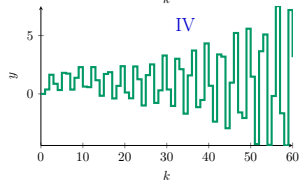
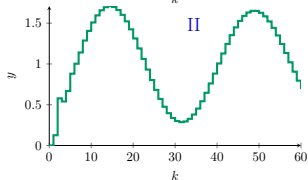
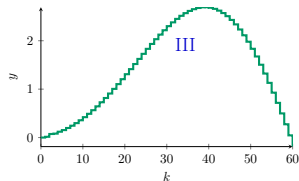
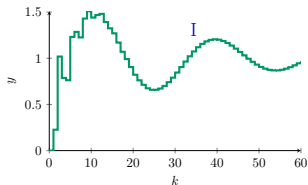
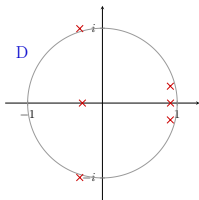
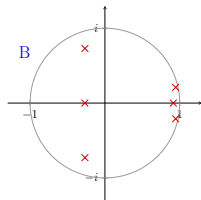
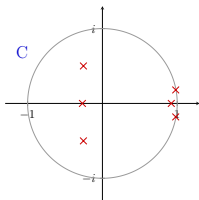
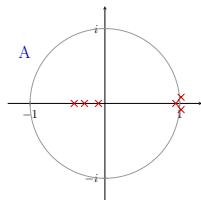


The **s-domain** of continuous-time systems is related to the **z-domain** of discrete-time systems through

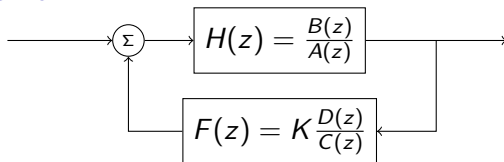
$$z = e^{sh}$$

Pole-placement and time-response

Pair the pole-placement with the correct time-response (discrete time)!



Root locus: A brief review



- ▶ The loop pulse-transfer function (loop gain) becomes

$$L(z) = H(z)F(z) = K \underbrace{\frac{B(z)D(z)}{A(z)C(z)}}_{P(z)} = K \frac{Q(z)}{P(z)}.$$

- ▶ The roots of $Q(z)$ are called the **open loop zeros**.
- ▶ The roots of $P(z)$ are called the **open loop poles**.
- ▶ The characteristic equation for the closed-loop system is

$$1 + K \frac{Q(z)}{P(z)} = 0 \quad \Leftrightarrow \quad P(z) + KQ(z) = 0$$

Root locus: Definition

Let

$$\begin{cases} P(z) = z^n + a_1 z^{n-1} + \cdots + a_n = (z - p_1)(z - p_2) \cdots (z - p_n) \\ Q(z) = z^m + b_1 z^{m-1} + \cdots + b_m = (z - q_1)(z - q_2) \cdots (z - q_m) \end{cases}, \quad n \geq m$$

The root locus shows how the **solution** to the characteristic equation

$$P(z) + K \cdot Q(z) = 0, \quad 0 \leq K < \infty \quad (1)$$

depend on the parameter K . The root locus consists of the set of all points in the complex plane that are solutions to (1) for some non-negative value of K .

Root locus: Characteristics

Start points The n roots of $P(z)$, marked by crosses

End points The m roots of $Q(z)$, marked by circles

Asymptotes Number equal to the *pole excess* $n - m$

Real axis Some segments of the real axis belong to the root locus

Root locus: Direction of the asymptotes

The characteristic equation $P(z) + KQ(z) = 0$ can be written $\frac{P(z)}{Q(z)} = -K$ and for large z it can be approximated as

$$\frac{z^n}{z^m} = -K \quad \Leftrightarrow \quad z^{n-m} = -K.$$

Taking the argument of both sides of the equation gives $(n - m) \arg z = \pi + k2\pi$, $k \in \mathbb{Z}$ So, the **directions** of the asymptotes are given by the expression

$$\theta_k = \arg z = \frac{(2k + 1)\pi}{n - m}, \quad k \in \mathbb{Z}$$

Root locus: The asymptotes' intersection with the real axis

$$z_{ip} = \frac{\sum_{i=0}^n p_i - \sum_{i=0}^m q_i}{n - m},$$

where $\{p_i\}$ are the starting points (open-loop poles) and $\{q_i\}$ are the end points (open-loop zeros).

Root locus exercise: Pair the pulse-trf fcn and root locus

$$G_1(z) = K \frac{(z + 2.9)(z + 0.2)}{(z - 1)^2(z - 0.3)}$$

$$G_2(z) = K \frac{(z - 0.5)(z + 0.4)}{(z - 1)(z - 0.3)(z - 0.1)}$$

$$G_3(z) = K \frac{(z - 0.5)(z + 0.8)}{(z - 1)^2(z - 0.3)}$$

$$G_4(z) = K \frac{z - 0.6}{(z - 1)(z - 0.3)}$$

