

# Analysis Sensitivity

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We want to understand the ways in which our analyses make approximations

All analyses (for Turing-complete languages) must approximate the program in some way

Have to **at least** approximate the stack!

```
(let* ([y (lambda (x) (x x))])  
  (y y))
```

Definition: the **polyvariance** of an analysis is the degree to which the analysis separates reasoning about fragments of the program to gain precision


OCFA is **monovariant**, because each lambda considered only **once** (no matter how many environments)

```
(let* ([id (lambda (x) x)]  
      [f  (lambda (y) ...)]  
      [g  (lambda (z) ...)]  
      [h  (id f)])  
  (id g))
```

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```
(let* ([id (lambda (x) x)]  
      [f (lambda (y) ...)]  
      [g (lambda (z) ...)]  
      [h (id f)])  
  (id g))
```



In OCFA, two lambdas reach x

Thus, two lambdas reach all **callsites** of id

```
(let* ([id (lambda (x) x)]  
      [f (lambda (y) ...)]  
      [g (lambda (z) ...)]  
      [h (id f)])  
  (id g))  
{(lambda (y) ...),  
 (lambda (z) ...)}
```



This is not what we want..

Clearly, `(id g)` should just be `g`, not also `f`

```
(let* ([id (lambda (x) x)]  
      [f (lambda (y) ...)]  
      [g (lambda (z) ...)]  
      [h (id f)])
```

```
  (id g))
```

Ideally...

```
{(lambda (z) ...)}
```

Unfortunately, OCFA conflates them!

Last week, we largely focused on the lambda calculus

In that setting, the analysis computes **flow sets**  
(sets of lambdas that flow to a program point)

```
(let ([f (lambda (x) x)]  
      [x (f (lambda (y) y))]  
      [y (f (lambda (z) z))]  
      y)
```

If we use the AAM approach,  $x$  will be represented by an address  $\mathbf{x}$ , in the store

Meaning that the **first** call we see to  $\mathbf{f}$  will bind  $x$  to  $(\text{lambda } (y) \dots)$  in the store

```
(let ([f (lambda (x) x)]  
      [x (f (lambda (y) y))]  
      [y (f (lambda (z) z))]  
      y)
```

Store =  $\{\dots, x \mapsto \{(\text{lambda } (y) y)\}\}$



If we use the AAM approach,  $x$  will be represented by an address  $\mathbf{x}$ , in the store

But when we see the **second** call to  $f$ , we will add **another** lambda at  $x$ 's address in the store

```
(let ([f (lambda (x) x)]  
      [x (f (lambda (y) y))]  
      [y (f (lambda (z) z))])
```

```
y)  
Store = {..., x |-> {(lambda (y) y),  
                    (lambda (z) z)}}}
```

When the analysis handles a **call**, we allocate space in the store, then update as appropriate

$$\sigma' = \sigma \sqcup \{ \alpha \mapsto v \}$$

“Take whatever is at address  $\alpha$  and replace it with that joined with  $v$ ”

When the analysis handles a **call**, we allocate space in the store, then update as appropriate

$$\sigma' = \sigma \sqcup \{ \alpha \mapsto v \}$$


In OCFA for LC, values are just flow sets.

Meaning this will always be set addition of a lambda

Set of syntactic lambdas is finite, thus so is its powerset!

# What about when we add prims...?

For OCFA, this x only ever considered once



```
(let ([id (lambda (x) x)]  
      [x (id 2)]  
      [y (id 3)])  
  x)
```

(I.e., all possible values of x are conflated)

We have a choice: which abstraction for ints?

(I.e., first time we see `(id 2)`, what do we make `x`?)

```
(let ([id (lambda (x) x)]  
      [x (id 2)]  
      [y (id 3)])  
  x)
```

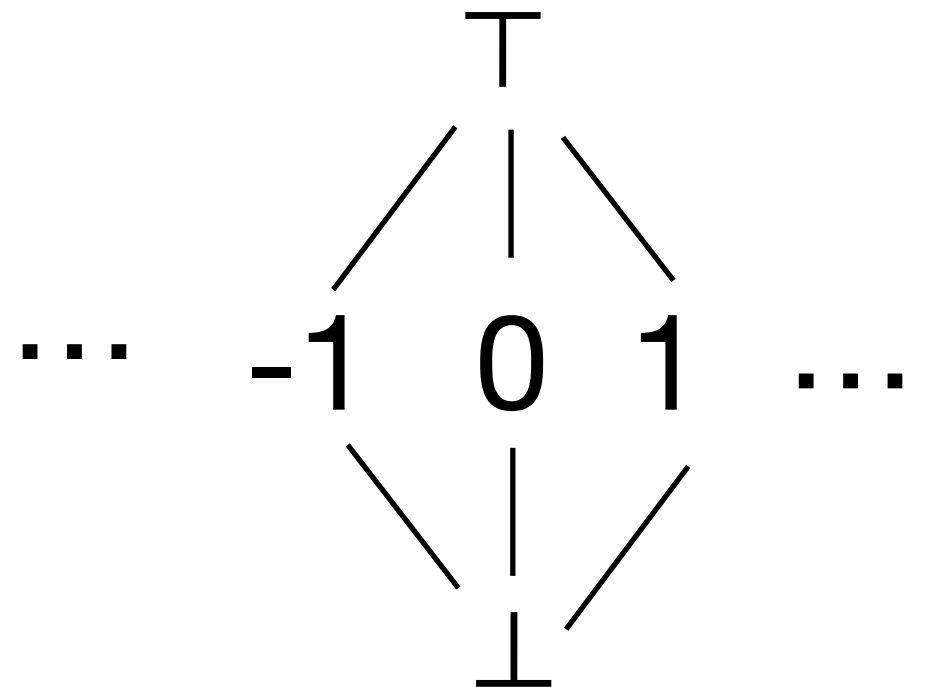
We have a choice: which abstraction for ints?

(I.e., first time we see `(id 2)`, what do we make `x`?)

```
(let ([id (lambda (x) x)]  
      [x (id 2)]  
      [y (id 3)])  
  x)
```

Choice 1:

Constant propagation flat lattice



First call to id, set x to {2}

```
(let ([id (lambda (x) x)]  
      [x (id 2)]  
      [y (id 3)])  
  x)
```

$$\sigma(x) = \{2\}$$

Second call to id, set x to  $\{2\} \sqcup \{3\} = \top$

```
(let ([id (lambda (x) x)]  
      [x (id 2)]  
      [y (id 3)])  
  x)
```

$$\sigma(x) = \top$$



Second call to id, set x to  $\{2\} \sqcup \{3\} = \top$

```
(let ([id (lambda (x) x)]  
      [x (id 2)]  
      [y (id 3)])  
  x)
```

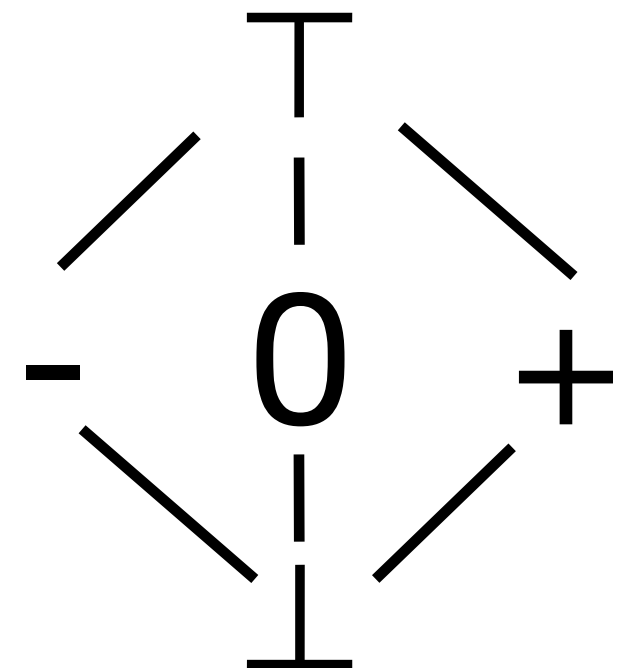
$$\sigma(x) = \top$$

In OCFA, each time we see a call to a function, we join its arguments with the arguments we've already seen

Another example, how will loss of precision impact **if**?

```
(define (foo x)
  (if (> x 0)
      1
      0))
```

```
(foo 1)
(foo -1)
```

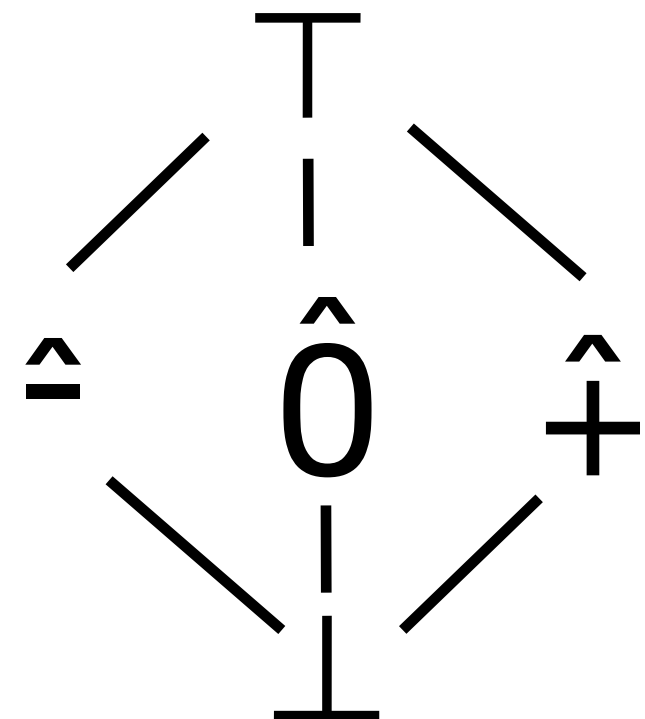


This time, assume we use sign lattice...

Another example, how will loss of precision impact **if**?

```
(define (foo x)
  (if (> x 0)
      1
      0))
```

```
(foo 1)
(foo -1)
```



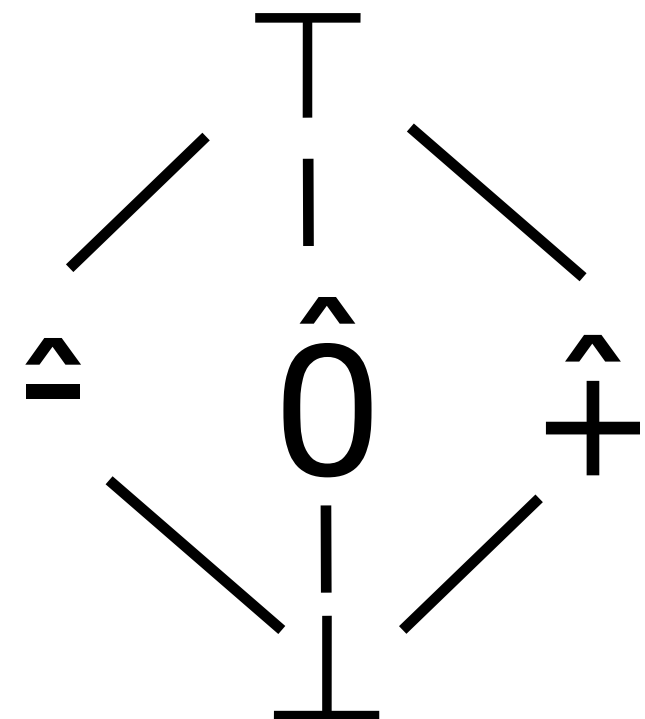
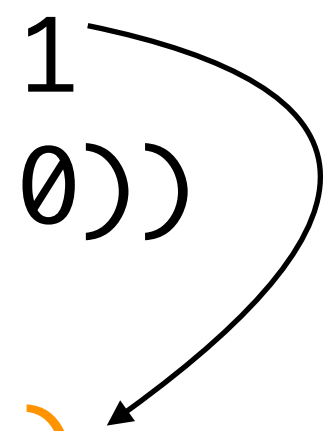
First time around...  $\sigma(\mathbf{X}) = \hat{+}$

Another example, how will loss of precision impact **if**?

Consequently, analysis  
says branch only goes to 1

```
(define (foo x)
  (if (> x 0)
      1
      0))
```

(foo 1)  
(foo -1)



First time around...  $\sigma(\mathbf{X}) = \hat{+}$

Another example, how will loss of precision impact **if**?

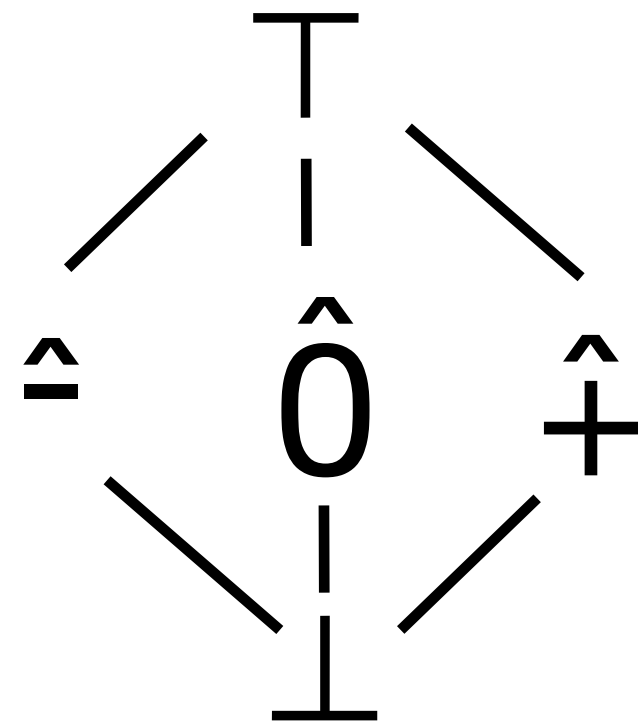
```
(define (foo x)
```

```
  (if (> x 0)
```

```
    1  
    0)))
```

```
(foo 1)
```

```
(foo -1)
```



Second time around...  $\sigma(\mathbf{x}) = \hat{+} \sqcup \hat{-} = T$

Another example, how will loss of precision impact **if**?

```
(define (foo x)
  (if (> x 0)
      1
      0))
```

(foo 1)

(foo -1)

The diagram illustrates the control flow of the provided code. A curved arrow originates from the '1' branch of the 'if' statement and points to the '(foo 1)' call site. Another curved arrow originates from the '0' branch of the 'if' statement and points to the '(foo -1)' call site. This visualizes how the analysis must follow both possible execution paths.

Now analysis goes to **both** branches

And all callsites return T

When the analysis handles a **call**, we allocate space in the store, then update as appropriate

$$\sigma' = \sigma \sqcup \{ \alpha \mapsto v \}$$

**This is where possible conflation / approximation happens!!!**

```
(let ([id (lambda (x) x)]  
      [x (f (lambda (y) y))]  
      [y (f (lambda (z) z))]  
      y)
```

## Other possible choices for the lattice...

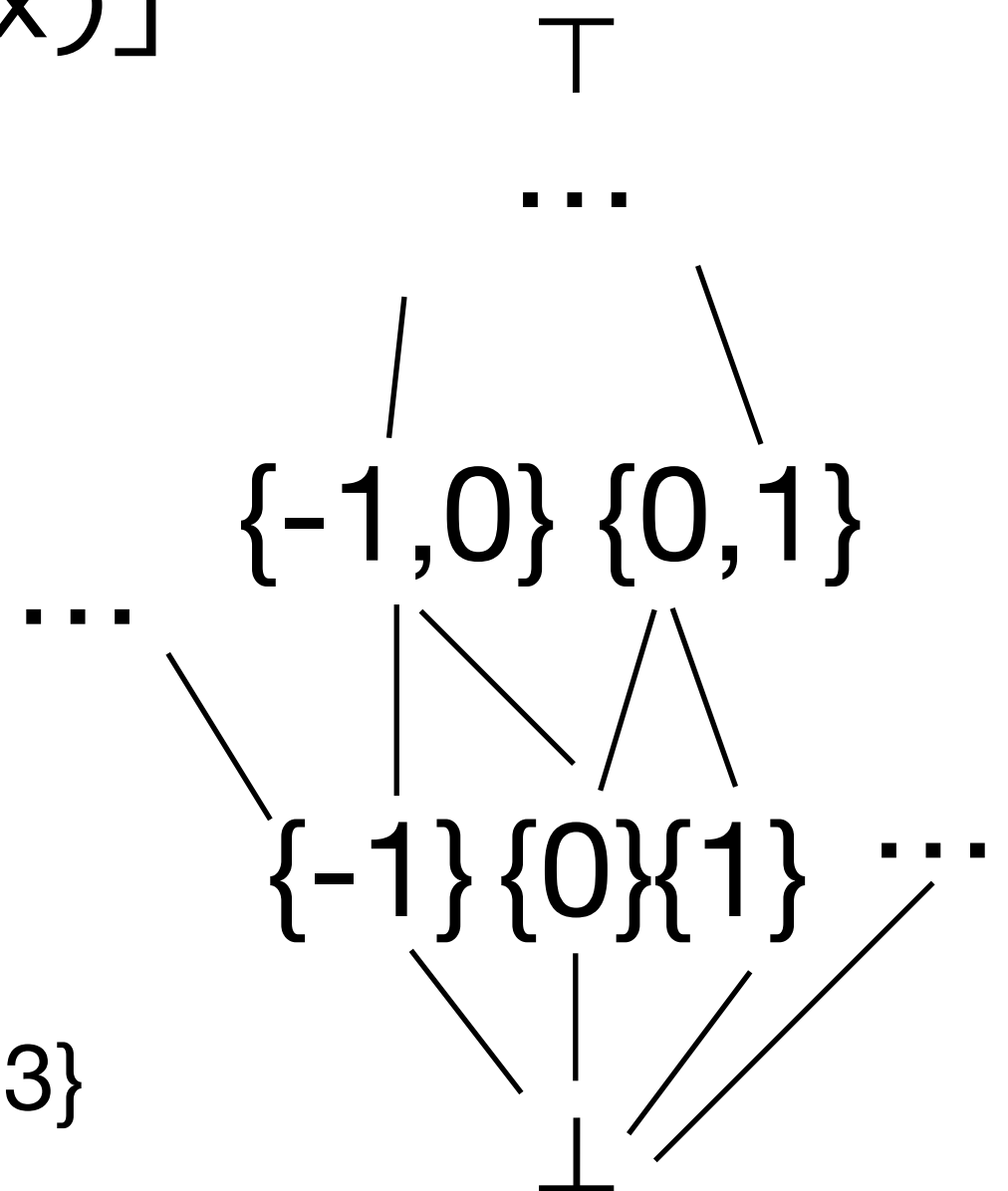
```
(let ([id (lambda (x) x)]  
      [x (id 2)]  
      [y (id 3)])  
  x)
```

Choice 2:

“Arbitrary sets of constants”

Allows us to approximate  $x$  as  $\{2,3\}$

(A little better: we know it **can't** be  $0,1, \dots$ )





```

(letrec
  ([f (lambda (x) (if (= x 0)
                       x
                       (f (+ x 1))))])
  (f 2))

```

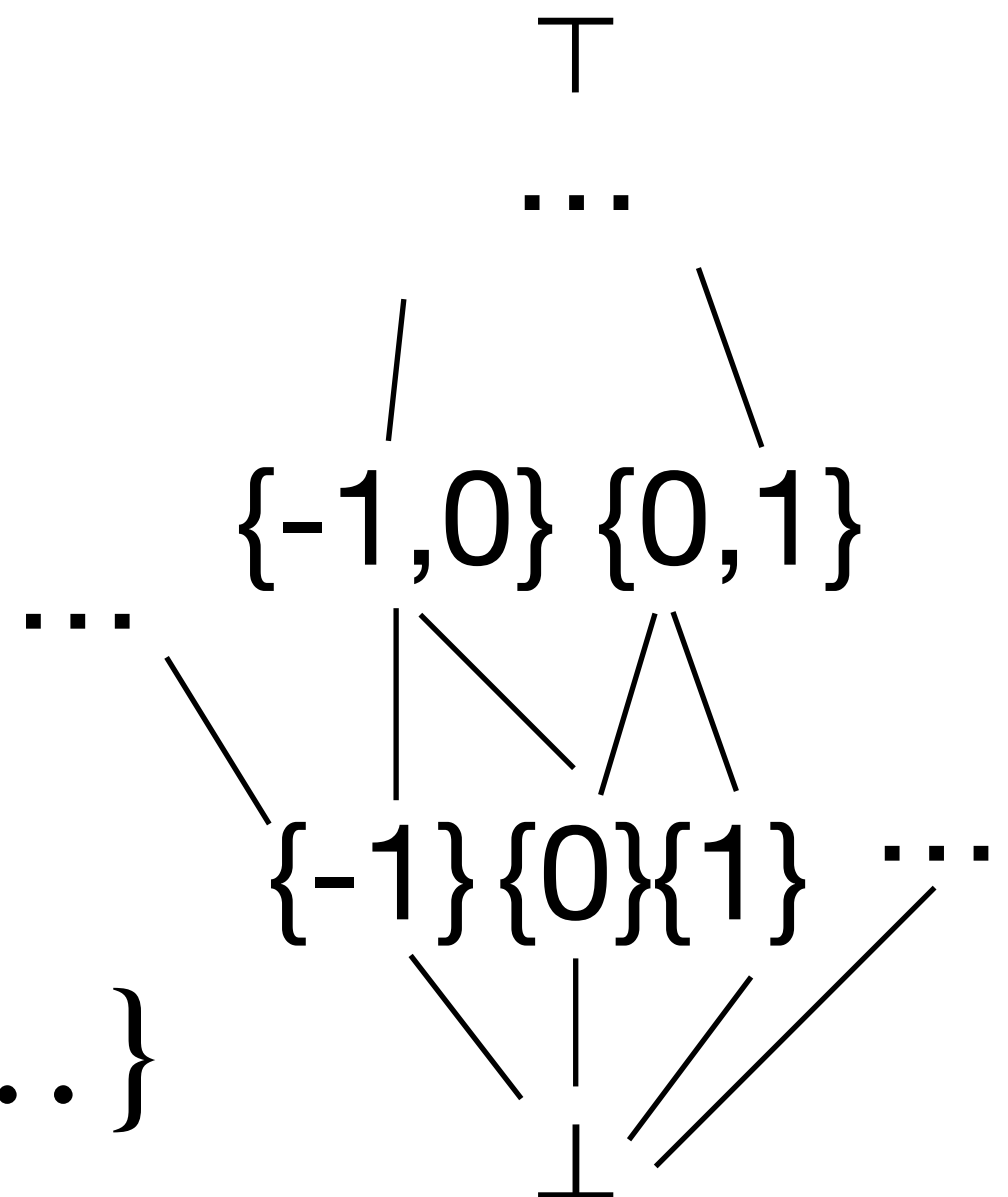
Unfortunately, using this lattice  
doesn't ensure termination

$x \mapsto \{2\}$

$x \mapsto \{2, 3\}$

$x \mapsto \{2, 3, 4\}$

$x \mapsto \{2, 3, 4, \dots\}$



```

(letrec
  ([f (lambda (x) (if (= x 0)
                        x
                        (f (+ x 1))))])
  (f 2))

```

We can use a **widening** operator

$$x \mapsto \{2\}$$

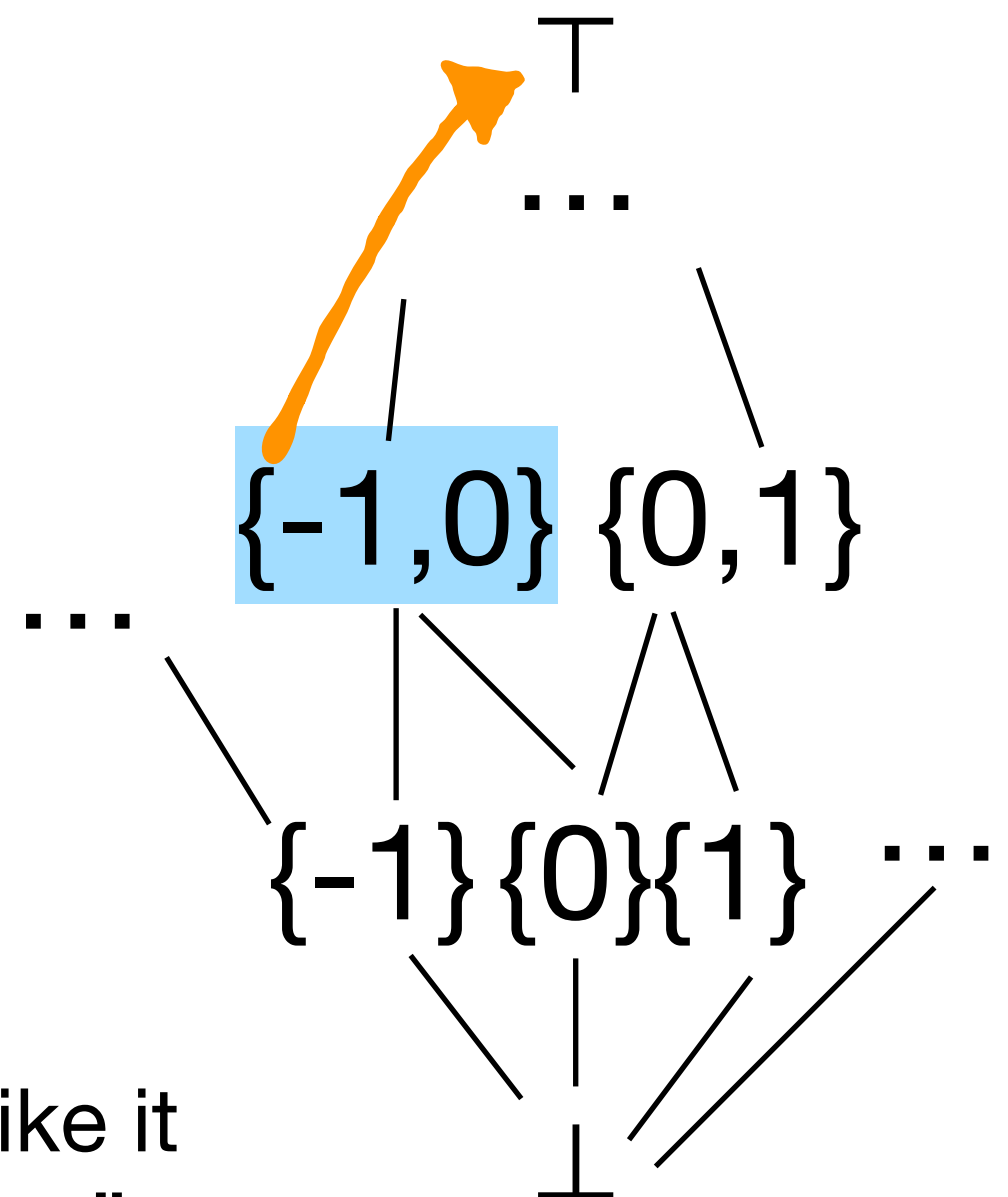
$$x \mapsto \{2, 3\}$$

$$x \mapsto \{2, 3, 4\}$$

Hypothetical

$$x \nabla \{5\} = \top$$

Intuitively, widening says “this looks like it won’t terminate, bump it up the lattice”



We won't talk much about widening (at least for now)

High level thing to know about it:

Allows you to use AI with an infinite domain by allowing you to “bump up to top” when you realize you might be about to diverge

In practice, I do not know much about designing widening / narrowing operators. I usually choose a better finite domain instead

However, finite domains give strictly **worse precision** than infinite domains + widening/narrowing

But does this loss of precision matter in practice for analyses we care about? I don't know (I am not sure if anyone does know).

*Comparing the Galois Connection and Widening/  
Narrowing Approaches to Abstract Interpretation,*  
Patrick and Rhadia Cousot, LNCS '92

When the analysis handles a **call**, we allocate space in the store, then update as appropriate

$$\sigma' = \sigma \sqcup \{ \alpha \mapsto v \}$$

This is where possible conflation / approximation happens!!!

Thus, if we want to **improve** precision, we need to **avoid** this conflation from happening!

Let's look back at this example again...

```
(let* ([f (lambda (x) x)]  
      [a (f (lambda (y) y))l1]  
      [b (f (lambda (z) z))l2]  
  b)
```

```

(let* ([f (lambda (x) x)]
      [a (f (lambda (y) y))l1]
      [b (f (lambda (z) z))l2]
      b)

```

If we were to run this program **concretely**  
using a CESK\*-style semantics

x would be bound to  $\alpha_1$ , and

$$\sigma(\alpha_1) = \{ (\text{lambda } (y) \ y), \ \square \}$$

y would be bound to  $\alpha_2$ , and

$$\sigma(\alpha_2) = \{ (\text{lambda } (z) \ z), \ \square \}$$

```

(let* ([f (lambda (x) x)]
      [a (f (lambda (y) y))l1]
      [b (f (lambda (z) z))l2]
      b)

```

In the AAM style, x is bound to x (an **address**)

And...

$$\sigma(x) = \{ (\text{lambda } (y) y), \\ (\text{lambda } (x) x) \}$$



```
(let* ([f (lambda (x) x)]  
      [a (f (lambda (y) y))l1]  
      [b (f (lambda (z) z))l2]  
  b)
```

What we **really** want to say is that *f* has two **different** behaviors:

- *f* called via the callsite at *l1*
- *f* called via the callsite at *l2*

Considering these cases **separately** leads to better precision!

```

(let* ([f (lambda (x) x)]
      [a (f (lambda (y) y))l1]
      [b (f (lambda (z) z))l2]
      b)

```

How can we pick  $\alpha_1$  and  $\alpha_2$  such that....

$x$  would be bound to  $\alpha_1$ , and

$$\sigma(\alpha_1) = \{ (\text{lambda } (y) y) \}$$

$y$  would be bound to  $\alpha_2$ , and

$$\sigma(\alpha_2) = \{ (\text{lambda } (z) z) \}$$

Idea: allocate variables based on the function that **called** them

```
(let ([id (lambda (x) x)]  
      [x (f (lambda (y) y))l1]  
      [y (f (lambda (z) z))l2]  
      y)
```

Thus, we consider two possible “runs” of `id`

`id` called via `l1`

`id` called via `l2`

`(lambda (x) x)`

$\rho = [x \mapsto \langle x, l1 \rangle]$

$\sigma(\langle x, l1 \rangle) = \{(\lambda(y) y)\}$

`(lambda (x) x)`

$\rho = [x \mapsto \langle x, l2 \rangle]$

$\sigma(\langle x, l2 \rangle) = \{(\lambda(z) z)\}$

Idea: allocate variables based on the function that **called** them

```
(let ([id (lambda (x) x)]  
      [x (f (lambda (y) y))l1]  
      [y (f (lambda (z) z))l2]  
      y)
```

(lambda (x) x)

$\rho = [x \mapsto \langle x, l1 \rangle]$

$\sigma(\langle x, l1 \rangle) = (\lambda(y) y)$

(lambda (x) x)

$\rho = [x \mapsto \langle x, l2 \rangle]$

$\sigma(\langle x, l2 \rangle) = (\lambda(z) z)$

We are adding **call** sensitivity for the value at the var x

Recall, using constant propagation lattice, OCFA  
calculates  $x = \top$

Let's say we use the trick in the previous slide...

Now we consider two different  
cases for  $x$  within `foo`:

- `foo` called via `l1`
- `foo` called via `l2`

```
(define (foo x)
  (if (< x 0)
      0
      1))
```

$\rho = [x \mapsto \langle x, l1 \rangle] \quad \rho = [x \mapsto \langle x, l2 \rangle]$        $(\text{let}^*$   
 $\sigma(\langle x, l1 \rangle) = \{5\} \quad \sigma(\langle x, l2 \rangle) = \{-5\}$        $([x \text{ (foo 5)}^{l1}]$   
       $[y \text{ (foo -5)}^{l2}])$   
       $x)$

To apply this trick in general...  
When allocating variables, allocate not based on  
**name**, but **name+label of most recent callsite**

We call this 1CFA, since it's a control-flow analysis  
keeping 1 calling context

*We strategically* lose precision for bindings more  
than 1 callsite away!

```
(let*
  ([id (lambda (y) y)]
   [id1 (lambda (x) (id x)l1)]
   [x (id1 5)l2]
   [y (id1 -5)l4])
  x)
```

Conceptually, 1-CFA is “forgetting”  
callsites past l1

$x \mapsto \langle x, l2 \rangle$

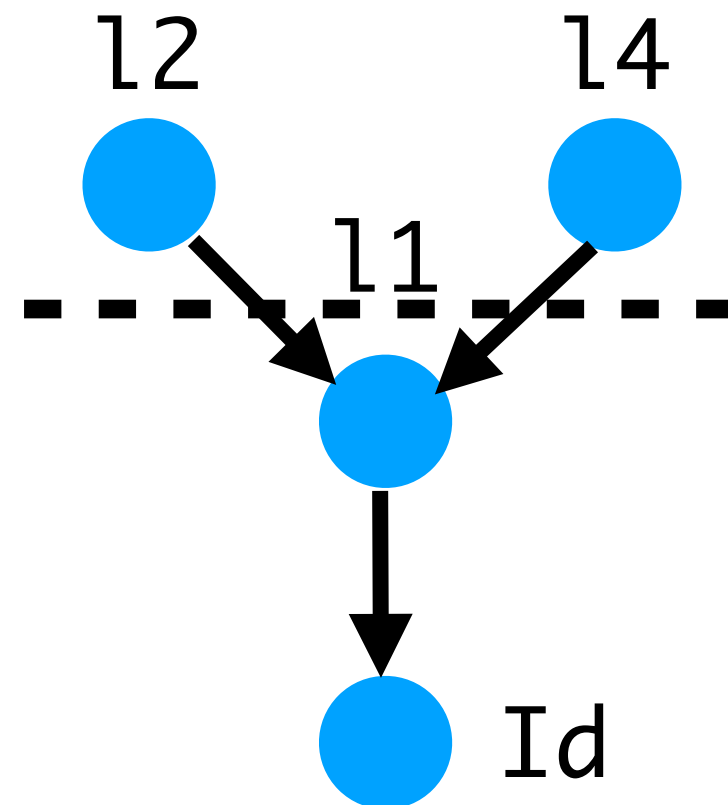
$x \mapsto \langle x, l4 \rangle$

$y \mapsto \langle y, l1 \rangle$

$\hat{o}(\langle x, l2 \rangle) = \{5\}$

$\hat{o}(\langle x, l2 \rangle) = \{-5\}$

$\hat{o}(\langle y, l1 \rangle) = \{5\} \sqcup \{-5\} = \top$



## Solution: 2-CFA?

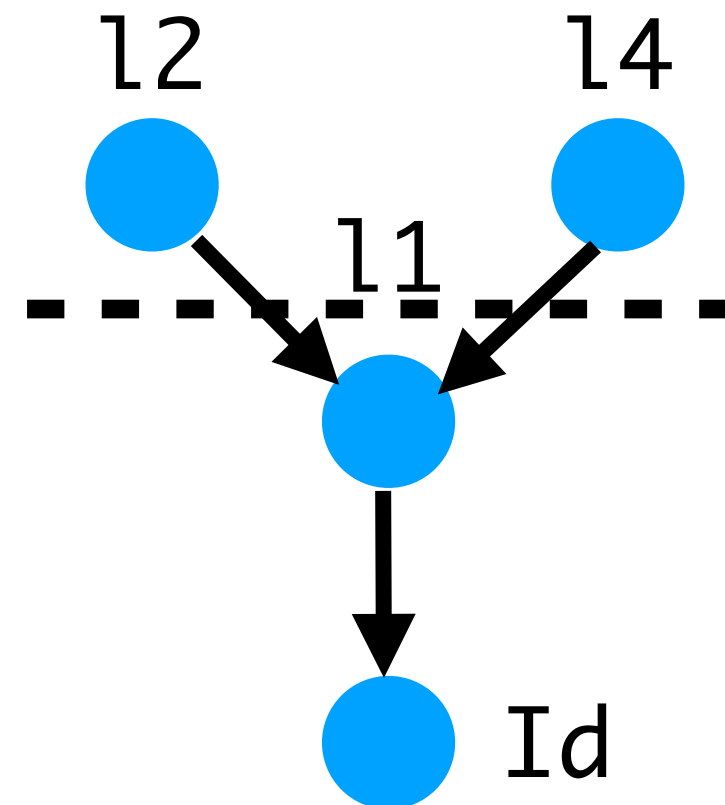
Now variables are precise up to  
most recent **two** callsites

Add more polyvariance

$\langle y, l1, l2 \rangle$

$\langle y, l1, l4 \rangle$

```
(let*  
  ([id (lambda (y) y)]  
   [id1 (lambda (x) (id x)l1)]  
   [x (id1 5)l2]  
   [y (id1 -5)l4])  
  x)
```





$$(\lambda(x) \ e), c \Rightarrow (\lambda(x) \ e), c$$

$$\frac{(e_0 \ e_1)^l \quad (\lambda(x) \ e'), c \Rightarrow e_0 \quad v, c \Rightarrow e_1}{v, c \Rightarrow x, [l :: c]_k}$$

$$\frac{(\lambda(x) \ e) \Rightarrow e_0 \quad v \Rightarrow e}{v \Rightarrow (e_0 \ e_1)}$$