Time-Varying Graph Signal Median Filtering

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I. PRELIMINARY

In *Median Filtering* [1] approach, basically, a *multiset*[1] is generated based on time and graph neighboring values, and the median of the multiset is used as the filtered value at that time and node index. For a joint time-vertex signal $\mathbf{X}$, indexed by $\mathbf{X}_{i,t}$ for the value at node i and at time t, where $1 \leq i \leq N$ and $1 \leq t \leq T$, two versions of these multisets are proposed and denoted as $\mathcal{X}_{i,t}^{(1)}$ and $\mathcal{X}_{i,t}^{(2)}$. These multisets are defined as follows:

$$\mathcal{X}_{i,t}^{(1)} = \underbrace{\{\mathbf{X}_{i,t-1}, \mathbf{X}_{i,t}, \mathbf{X}_{i,t+1}\}}_{\substack{\text{previous, current, next} \\ \text{time values at node } i}} \cup \underbrace{\{\mathbf{X}_{j,t} \mid j \in \mathcal{N}_1(i)\}}_{\substack{\text{current time values at} \\ \text{neighbors of node } i}} \quad (1)$$

$$\mathcal{X}_{i,t}^{(2)} = \mathcal{X}_{i,t}^{(1)} \cup \underbrace{\{\mathbf{X}_{j,t-1} \mid j \in \mathcal{N}_1(i)\} \cup \{\mathbf{X}_{j,t+1} \mid j \in \mathcal{N}_1(i)\}}_{\substack{\text{In addition to values of } \mathcal{X}_{i,t}^{(1)}, \text{ values of neighbors} \\ \text{of node } i \text{ at previous and next time instances}}}$$

$$(2)$$

where $\mathcal{N}_\ell(i)$ denotes ℓ-hop neighborhood of node i, and the values with overflowing indices are excluded. After the generation of these multisets, the filtered value at that node and time instance is denoted as $\mathbf{Y}_{i,t}^{(p)} = \mathrm{median}(\mathcal{X}_{i,t}^{(p)})$, for $p \in \{1, 2\}$, and overall filtering is denoted as $\mathbf{Y}^{(p)} = \mathcal{M}_p(\mathbf{X})$.

II. FULL COMPARISON

Full result comparison between the reported and regenerated median filtering experiments on *sea surface temperature* dataset is provided in Table I. The underlying graph of reported results is not provided in the original paper [1], the generated results are obtained with k-NN underlying graph structure with several k values. The reason is the papers that use the *sea surface temperature* dataset usually use 5-NN graph for underlying graph [2], [3], and [2] is also cited in [1]. The best overall results are bolded, whereas the best *generated* results are underlined in Table I.

III. BEST COMPARISON

The best-generated results along different underlying graph structures for both $\mathcal{M}_1$ and $\mathcal{M}_2$ filtering methods are compared with the reported ones in Tables II and III, respectively.

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[1]A multiset is a set with possible repetitions, e.g., $\mathcal{S} = \{1, 1, 2, 3, 3, 3\}$.

TABLE II
BEST COMPARISON OF $\mathcal{M}_1$

	Reported	Generated	
σ	$\mathcal{M}_1$	$\mathcal{M}_1$	Graph
0.05	**27.69**	27.00±0.06	1-NN
0.10	**23.54**	22.30±0.08	3-NN
0.15	**20.59**	19.69±0.08	5-NN
0.20	**18.30**	18.10±0.07	10-NN
0.25	16.50	**16.87±0.08**	10-NN
0.30	14.96	**15.74±0.08**	10-NN
0.35	13.59	**14.71±0.08**	10-NN
0.40	12.53	**13.77±0.08**	10-NN

TABLE III
BEST COMPARISON OF $\mathcal{M}_2$

	Reported	Generated	
σ	$\mathcal{M}_2$	$\mathcal{M}_2$	Graph
0.05	**27.26**	26.39±0.06	1-NN
0.10	**25.09**	22.86±0.07	3-NN
0.15	**22.93**	20.93±0.08	3-NN
0.20	**21.05**	19.44±0.10	5-NN
0.25	**19.49**	18.45±0.12	10-NN
0.30	**18.08**	17.77±0.13	10-NN
0.35	16.78	**17.08±0.14**	10-NN
0.40	15.73	**16.39±0.15**	10-NN

IV. DISCUSSION

Not knowing the underlying graph structure makes it difficult to compare the results with the reported ones. However, we can still compare the results with the best ones generated by our implementation. As shown in Tables II and III, the best results generated by our implementation are comparable to the reported ones. With certain graph structures, we can even achieve better results than the reported ones. To sum up, I believe we can use our implementation for fair comparison without any issues.

REFERENCES

[1] D. B. Tay and J. Jiang, "Time-varying graph signal denoising via median filters," *IEEE Transactions on Circuits and Systems II: Express Briefs*, vol. 68, no. 3, pp. 1053–1057, 2021.

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[3] J. H. Giraldo, A. Mahmood, B. Garcia-Garcia, D. Thanou, and T. Bouwmans, "Reconstruction of time-varying graph signals via sobolev smoothness," *IEEE Transactions on Signal and Information Processing over Networks*, vol. 8, pp. 201–214, 2022.

TABLE I

FULL RESULT COMPARISON OF SNR VALUES OF DENOISED SIGNALS BETWEEN REPORTED AND GENERATED VERSIONS.

| | Reported with Unknown Graph | | | Generated with k–NN Graph | | | | | | | | |
| | | | | $\forall k$ | $k = 1$ | | $k = 3$ | | $k = 5$ | | $k = 10$ | |
σ	Noisy	$\mathcal{M}_1$	$\mathcal{M}_2$	Noisy	$\mathcal{M}_1$	$\mathcal{M}_2$	$\mathcal{M}_1$	$\mathcal{M}_2$	$\mathcal{M}_1$	$\mathcal{M}_2$	$\mathcal{M}_1$	$\mathcal{M}_2$
0.05	22.63	**27.69**	27.26	22.63±0.05	<u>27.00±0.06</u>	26.39±0.06	26.58±0.08	24.93±0.06	25.87±0.06	23.40±0.06	22.59±0.04	20.64±0.02
0.10	16.62	23.54	**25.09**	16.61±0.05	21.68±0.06	22.64±0.08	22.30±0.08	<u>22.86±0.07</u>	22.21±0.07	22.02±0.07	20.87±0.08	20.24±0.07
0.15	13.10	20.59	**22.93**	13.08±0.05	18.33±0.06	19.72±0.09	19.38±0.09	<u>20.93±0.08</u>	19.69±0.08	20.71±0.09	19.43±0.08	19.72±0.09
0.20	10.61	18.30	**21.05**	10.59±0.05	15.90±0.07	17.45±0.09	17.15±0.10	19.17±0.09	17.71±0.09	<u>19.44±0.10</u>	18.10±0.07	19.12±0.10
0.25	8.66	16.50	**19.49**	8.65±0.05	13.99±0.07	15.63±0.09	15.34±0.10	17.63±0.10	16.05±0.09	18.24±0.11	16.87±0.08	<u>18.45±0.12</u>
0.30	7.06	14.96	**18.08**	7.06±0.05	12.43±0.07	14.11±0.09	13.83±0.10	16.28±0.10	14.64±0.09	17.12±0.11	15.74±0.08	<u>17.77±0.13</u>
0.35	5.72	13.59	16.78	5.72±0.05	11.10±0.07	12.81±0.09	12.53±0.11	15.10±0.10	13.42±0.09	16.09±0.12	14.71±0.08	<u>**17.08±0.14**</u>
0.40	4.57	12.53	15.73	4.57±0.05	9.94±0.07	11.67±0.09	11.40±0.11	14.04±0.11	12.33±0.09	15.15±0.12	13.77±0.08	<u>**16.39±0.15**</u>