

Erratum from last lecture:
 α_n instead of α_n . See uploaded notes for clarification. Oct 25th 2017

Lecture 2: Numerical Integration

Consider the definite integral

$$I[f] := \int_a^b f(x) dx \quad (*)$$

A quadrature scheme approximates (*) as

$$I_n[f] \approx I_n[f] := \sum_{i=1}^n w_i \cdot f(x_i),$$

where $\{x_i\}_{i=1}^n$ are the nodes & $\{w_i\}_{i=1}^n$, the weights.

Define the error in the quad. scheme as

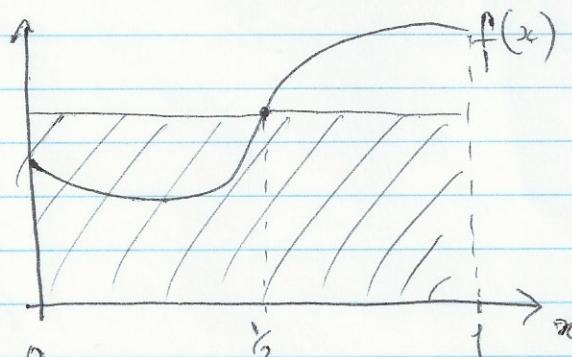
$$E_n[f] := |I[f] - I_n[f]|.$$

Simplest method: Midpoint Rule.

Consider $I[f] = \int_0^1 f(x) dx$, then the "midpoint rule"

approximates I as

$$\int_0^1 f(x) dx \approx f\left(\frac{1}{2}\right).$$



More generally, $\int_a^b f(x) dx \approx \frac{(b-a)}{2} \cdot f\left(\frac{b+a}{2}\right)$.

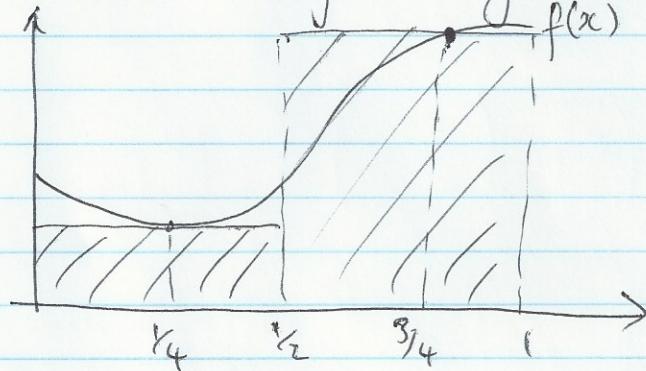
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Hence $\frac{a+b}{2}$ is the node and $(b-a)$ is the weight.

In words: approximate area under $f(x)$ by the area of the rectangle of height $f\left(\frac{a+b}{2}\right)$.

Improving accuracy-

Increase the number of rectangles: "composite midpoint"



$$\int_0^1 f(x) dx \approx \frac{1}{2} f\left(\frac{1}{4}\right) + \frac{1}{2} f\left(\frac{3}{4}\right)$$

More generally,

$$\int_a^b f(x) dx \approx \frac{(b-a)}{2} \left[f\left(a + \frac{b-a}{4}\right) + f\left(a + \frac{3(b-a)}{4}\right) \right]$$

Now consider n subintervals:

$$\int_0^1 f(x) dx \approx \frac{1}{n} \sum_{i=1}^n f\left(\frac{2i-1}{2n}\right)$$

Generally,

$$\int_a^b f(x) dx \approx \frac{b-a}{n} \sum_{i=1}^n f\left(a + \frac{b-a}{n}\left(i - \frac{1}{2}\right)\right)$$

$\underbrace{n}_{w_i} \quad \underbrace{x_i}_{x_i}$

Error analysis

To derive the error of the midpoint rule, consider the interval $[0, h]$, $h > 0$, and Taylor expand about $\frac{h}{2}$

$$f(x) = f\left(\frac{h}{2}\right) + \left(x - \frac{h}{2}\right) f'\left(\frac{h}{2}\right) + \underbrace{\left(\frac{x-h}{2}\right)^2 f''(\xi)}$$

for some $\xi \in [0, h]$.

"Lagrange's form" of remainder

Then

$$\begin{aligned} \int_0^h f(x) dx &= \int_0^h \left\{ f\left(\frac{h}{2}\right) + \left(x - \frac{h}{2}\right) f'\left(\frac{h}{2}\right) + \left(\frac{x-h}{2}\right)^2 f''(\xi) \right\} dx \\ &= \left[f\left(\frac{h}{2}\right) x + \left(\frac{x-h}{2}\right)^2 f'\left(\frac{h}{2}\right) \right]_0^h + \left[\frac{(x-h)^3}{6} f''(\xi) \right]_0^h \\ &= hf\left(\frac{h}{2}\right) + \frac{h^3}{24} f''(\xi) \end{aligned}$$

Hence the error is

$$E_1[f] = I[f] - I_1[f]$$

$$= h f\left(\frac{h}{2}\right) + \frac{h^3}{24} f''(\xi) - hf\left(\frac{h}{2}\right)$$

So we see that the error depends on 2nd derivative of f . Thus midpoint rule integrates 0th & 1st order polynomials exactly.

Composite midpoint $E_n[f] = \frac{(b-a)^2}{24n^2} f''(\xi)$, $\xi \in [a, b]$

Exercise:

Show that $I_n[f] := \frac{h}{n} \sum_{i=1}^n f(x_i)$, $x_i = \frac{h}{n}(i - \frac{1}{2})$.

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$$\begin{aligned}
 I[f] &= \int_0^h f(x) dx = \sum_{i=1}^n \int_{x_i - \frac{h}{2}}^{x_i + \frac{h}{2}} f(x) dx \\
 \Rightarrow E_n[f] &= \sum_{i=1}^n \int_{x_i - \frac{h}{2}}^{x_i + \frac{h}{2}} f(x) dx - \frac{h}{n} \sum_{i=1}^n f(x_i) \\
 &= \sum_{i=1}^n \left(h f(x_i) + \frac{h^3}{24} f''(\xi) - h f(x_i) \right) \\
 &= \frac{nh^3}{24} f''(\xi) \quad , \quad h = \frac{(b-a)}{n} \\
 &= \frac{(b-a)^3}{24} f''(\xi) \quad] \\
 &= \frac{(b-a)^2}{24} f''(\xi)
 \end{aligned}$$

So $O(h^2)/O\left(\frac{1}{n^2}\right)$ convergence.

MATLAB demo:

Can we derive a method for polys. of deg > 1 ?

Cubic example:

Want to determine w_1, w_2 & x_1, x_2 s.t.

$$I_2[f] = w_1 f(x_1) + w_2 f(x_2)$$

is ~~exactly~~ exactly equal to $I[f]$.

Cubic :

$$f(x) = a_0 + a_1 x + a_2 x^2 + a_3 x^3$$

For exactness, require

$$\int_{-1}^1 (a_0 + a_1 x + a_2 x^2 + a_3 x^3) dx = w_1 [a_0 + a_1 x_1 + a_2 x_1^2 + a_3 x_1^3] \\ + w_2 [a_0 + a_1 x_2 + a_2 x_2^2 + a_3 x_2^3]$$

Gather like terms :

$$a_0 : w_1 + w_2 = \int_{-1}^1 dx = 2$$

$$a_1 : w_1 x_1 + w_2 x_2 = \int_{-1}^1 x dx = 0$$

$$a_2 : w_1 x_1^2 + w_2 x_2^2 = \int_{-1}^1 x^2 dx = \frac{2}{3}$$

$$a_3 : w_1 x_1^3 + w_2 x_2^3 = \int_{-1}^1 x^3 dx = 0$$

Solve eqns. to give

$$w_1 = w_2 = 1, \quad x_1 = -\frac{1}{\sqrt{3}}, \quad x_2 = \frac{1}{\sqrt{3}}$$

2 point rule integrates polys. of degree ≤ 3 .

In general, an n pt. rule is exact for polys. of degree $\leq 2n-1$. Gives spectral convergence with n

To obtain nodes & weights for n point rule, could do as above and solve non-linear system using a Newton method. However this is difficult since the matrix becomes very ill-conditioned for large n . Instead use orthogonal polys. instead of above monomial to make rows linear independent. See other notes for more details.

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Transform Gauss to $[a, b]$.

Gauss rule always given on $[-1, 1]$.

For $[a, b]$, need to change variables:

$$\hat{x} = a + \frac{(x+1)}{2} \cdot (b-a)$$

So

$$\int_a^b f(\hat{x}) d\hat{x} = \frac{b-a}{2} \int_{-1}^1 f\left(a + \frac{b-a}{2}(x+1)\right) dx$$

NB: have modified weight by $\frac{b-a}{2}$ & mapped quadrature pts. to $[a, b]$.

Singular integrals. (self-test)

If collocation pt. lies in element, have integral of form

$$I = \int_{-1}^1 p(x) \log|x| dx, \quad p(x) \text{ poly. basis func.}$$

- singular at $x=0$.

[Standard Gauss won't be accurate. MATLAB demo.]

Can construct generalized Gauss rule.

Say we want to integrate

$$f(x) = a_0, a_1 \log x, a_2 x, a_3 x \log x,$$

on $[0, 1]$. ← Comment.

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For As before for polys.

For exactness, require

$$a_0 : \int_0^1 dx = 1 = w_1 + w_2$$

$$a_1 : \int_0^1 \log x dx = -1 = w_1 \log(x_1) + w_2 \log(x_2)$$

$$a_2 : \int_0^1 x dx = \frac{1}{2} = w_1 x_1 + w_2 x_2$$

$$a_3 : \int_0^1 x \log x dx = -\frac{1}{4} = w_1 x_1 \log x_1 + w_2 x_2 \log x_2$$

[Ex: derive Gauss rule for a different set of func's]

Non-linear system more complicated but can still solve.

MATLAB Recovers spectral accuracy.

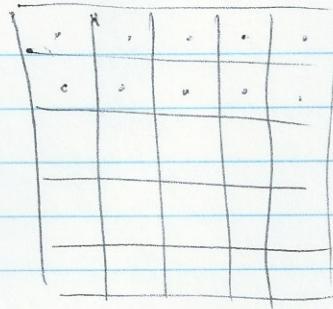
The 2D integrals

Coteskin method requires evaluation of 2D integrals:

$$I = \iint_a^b \int_c^d f(x, y) p(x) q(y) dy dx$$

Just use product of 2 1D rules.

E.g., midpoint rule:



Gauss:

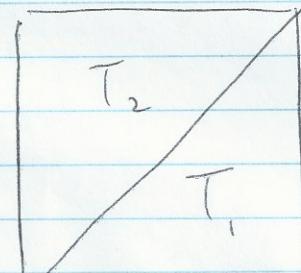
$$I \approx \sum_{i=1}^n \sum_{j=1}^n w_i w_j f(x_i, x_j)$$

MATLAB: show nodes & weights in 2D.

Self term

The self interaction term via Galerkin leads to a singularity along diag. of integration domain.

MATLAB



[How to integrate? Gen. Gauss would be OK if sing. along side]

E.g. $I = \iint_{\text{square}} \log|x-y| dy dx$.

Split int. dom. into 2 triangles T_1, T_2 .

Consider T_1, T_2 for EX.

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$$I_{T_1} = \int_0^1 \int_0^x \log|x-y| dy dx \quad \leftarrow \text{sing. at } y=x.$$

Use Duffy transform to map $\Delta \rightarrow \square$.

Classical Duffy: $x=u$, $y=uv$, $\frac{dy}{dv} = u$

Gives

$$I_{T_1} = \int_0^1 \int_0^u \log|u-y| dy du$$

$$= \int_0^1 \int_0^1 \log|u-uv| u dv du$$

$$= \int_0^1 \int_0^1 \log|u(1-v)| u dv du$$

Integration now over square & singular at $u=0, v=1$.

To get sing. of both both at 0, let

$$s = 1-v$$

$$I_{T_1} = \int_0^1 \int_{-1}^0 \log|u(u-(1-s))| u(-1) ds du$$

N.B.

Transforms out

$\frac{1}{x}$ sing.

$$= \int_0^1 \int_0^1 \log|us| u ds du. \quad \text{sing. at } u=0 \text{ & } s=0.$$

All-in-1 fixed transform: $x=u$, $y=u(1-s)$.

MATLAB: Can use 2 1d generalized Gauss rules.

Note on Lagrange's remainder for Taylor series.

On page 3 we quoted the following form of Taylor's theorem:

Taylor's theorem

Suppose that f is $(n+1)$ times differentiable on some interval containing the center of convergence c and x , and let

$$(1) \quad P_n(x) = f(c) + f'(c)(x-c) + \frac{f''(c)}{2}(x-c)^2 + \dots + \frac{f^{(n)}(c)}{n!}(x-c)^n$$

be the n^{th} order Taylor polynomial of f at $x=c$.

Then

$$f(x) = P_n(x) + E_n(x)$$

where $E_n(x)$ is the error term. For ξ between c and x , the Lagrange remainder form of the error E_n is given by

$$E_n(x) = \frac{f^{(n+1)}(\xi)}{(n+1)!} (x-c)^{n+1}.$$

form of the remainder

In order to prove this, we shall use Cauchy's mean-value theorem which we quote without proof.

Cauchy's mean-value theorem

Let F, G be continuous on $[a, b]$ and differentiable on (a, b) , and $G'(x) \neq 0 \quad \forall x \in (a, b)$. Then $\exists \xi \in (a, b)$ such that

$$\frac{F(b) - F(a)}{G(b) - G(a)} = \frac{F'(\xi)}{G'(\xi)}.$$

Proof of Lagrange's remainder in Taylor's theorem.

Define

$$(2) \quad F(x) := f(x) + f'(x)(x-\alpha) + \frac{f''(\alpha)}{2}(x-\alpha)^2 + \dots + \frac{f^{(n)}(\alpha)}{n!}(x-\alpha)^n$$

Notice that $F(x) = f(x)$ and $F(c) = P_n(x)$ from (1).

We want to find $f(x) - P_n(x)$, i.e., $E_n(x)$. From the above observation, we have that

$$(3) \quad f(x) - P_n(x) = f(x) - F(c)$$

From Cauchy's mean-value theorem, we have

$$(4) \quad F(x) - F(c) = \frac{F'(\xi)}{\zeta'(\xi)} (\zeta(x) - \zeta(c))$$

for ξ between x and c . Next observe, by differentiating (2), that

$$(5) \quad F'(\alpha) = \frac{f^{(n+1)}(\alpha)}{n!} (x-\alpha)^n. \quad (\text{Exercise: show this})$$

This gives Substituting (5) into (4) :

$$(6) \quad F(x) - F(c) = \frac{f^{(n+1)}(\xi)}{n! \zeta'(\xi)} (x-\xi)^n (\zeta(x) - \zeta(c))$$

Judiciously choosing $\zeta(\alpha) = (x-\alpha)^{n+1}$

$$\Rightarrow \zeta'(\alpha) = -(n+1)(x-\alpha)^n$$

and substituting into (6) :

$$f(x) - F(c) = \frac{f^{(n+1)}(\xi)}{n!} \frac{(x-\xi)^n}{[-(n+1)(x-\alpha)^n]} \cdot \left(-(x-c)^{n+1} \right)$$

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$$\Rightarrow F(x) - F(c) = \frac{f^{(n+1)}(\xi)}{(n+1)!} (x-c)^{n+1}$$

Recall from (3) that $E_n(x) = F(x) - \hat{F}(c)$, hence

$$E_n(x) = \frac{f^{(n+1)}(\xi)}{(n+1)!} (x-c)^{n+1}.$$