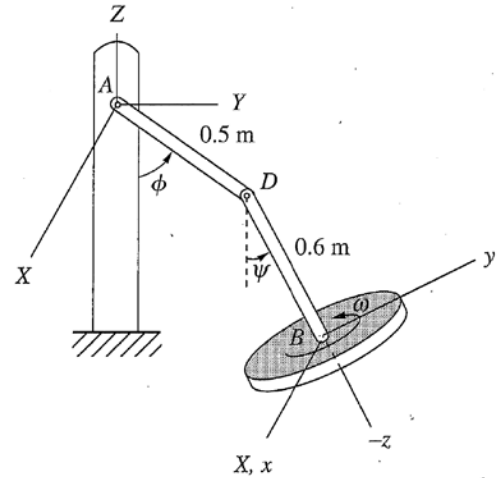
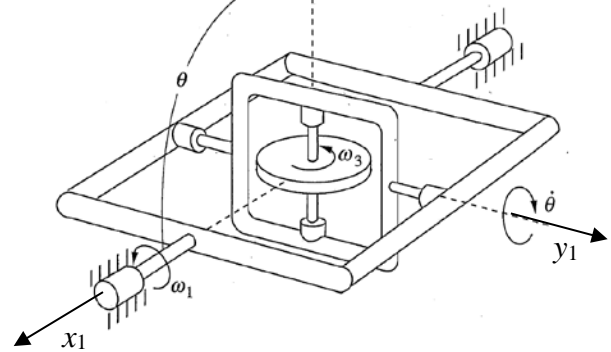


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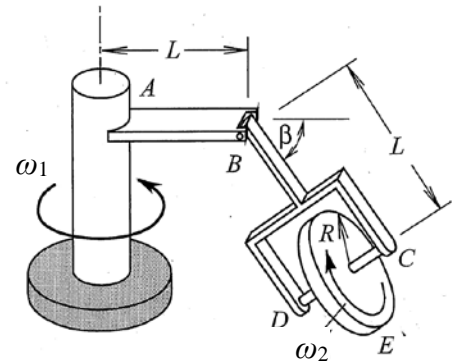
1. The robotic sander shown in the figure has a sanding disk that spins at the constant rate of 1500 rpm. The arms  $AD$  and  $DB$ , which are used to position the sander, make angles of  $\phi$  and  $\psi$  with the vertical. At the instant shown, their values are  $\phi = 90^\circ$ ,  $\psi = 60^\circ$ , and they are moving with the constant angular speeds of  $\dot{\psi} = -0.3 \text{ rad/s}$  and  $\dot{\phi} = 0.2 \text{ rad/s}$ . Find the angular velocity and angular acceleration of the sanding disk in terms of the inertial coordinates.



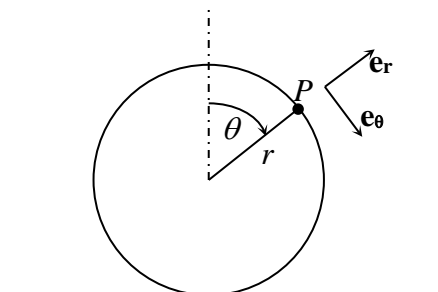
2. The flywheel of the gyroscope shown in the figure has a constant angular speed of  $\omega_3 = 5000 \text{ rpm}$  about its axis. The outer gimbal has an angular speed of  $\omega_1 = 3 \text{ rad/s}$ , which is decreasing at the rate of  $1.8 \text{ rad/s}^2$  relative to an inertial frame. The inner gimbal is at a position such that the angle between the outer gimbal axis and the flywheel axis is  $\theta = 75^\circ$ , with  $\dot{\theta} = 0$ ,  $\ddot{\theta} = 3 \text{ rad/s}^2$ . Find the angular acceleration of the flywheel in terms of the  $x_1y_1z_1$  frame, which is attached to the outer gimbal.



3.  $E$  is a point on a disk that spins about axis  $CD$  at a constant rate  $\omega_2$  as the system rotates about the vertical axis at a constant  $\omega_1$ . Find the velocity of point  $E$  at the instant when it is at its lowest point. The joint at  $B$  is welded at an angle  $\beta$ . Express your final result in a frame  $x_1y_1z_1$  attached to gimbal  $BCD$ , with  $x_1$  pointing along the gimbal arm from  $B$  toward  $CD$  (parallel to  $L$  in the figure) and  $z_1$  pointing up and to the right (parallel to  $CD$ ).



4. A vertical wheel of radius  $r$  rolls without slipping along a straight horizontal line. If its angular speed is given by  $\omega = \alpha t$ , where  $\alpha$  is a constant, solve for the acceleration of a point  $P$  on its rim, assuming that at  $t = 0$   $P$  is at the highest point of its path. Express the result in terms of the rotating frame described by  $\mathbf{e}_r$  and  $\mathbf{e}_\theta$ .



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5. The plane of the windshield of an automobile is inclined at an angle  $\alpha$  from the vertical. The windshield wiper blade is of length  $l$  and oscillates according to the equation  $\psi = \psi_0 \sin \beta t$ . Assuming that the auto travels with a constant speed  $v$  around a circular path of radius  $R$  in a counterclockwise sense (more precisely, the point  $O'$  traces out a circle of this radius), solve for the acceleration of the point  $P$  at the tip of the wiper. The result should be expressed as a vector in terms of the coordinate frame shown in the figure, which is fixed to the body of the car

