

**Vertex**: Every individual data element is called a vertex or a node. In the above image 1,2,3,4,5 & 6 are the vertices.

**Edge**: It is a connecting link between two nodes or vertices. Each edge has two ends and is represented as (startingVertex, endingVertex).

Undirected Edge: It is a bidirectional edge.

**Directed Edge**: It is a unidirectional edge.

m Weighted Edge: An edge with value (cost) on it.

**Degree**: The total number of edges connected to a vertex in a graph.

**Indegree**: The total number of incoming edges connected to a vertex.

Outdegree: The total number of outgoing edges connected to a vertex.

**Self-loop**: An edge is called a self-loop if its two endpoints coincide with each other.

**Adjacency**: Vertices are said to be adjacent to one another if there is an edge connecting them.

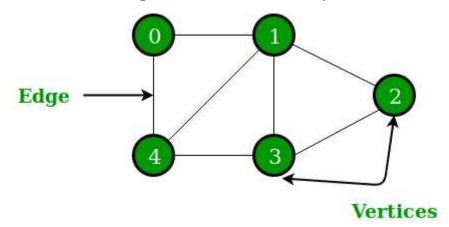
\*\*

```
In [ ]: struct TreeNode {
    int Data;
    TreeNode *left;
    TreeNode *right;
};
```

Graph Representation:

- 1. Adjacency list
- 2. Matrix representationm

## Represensation of Unweighted Undirected Graph



```
v: vertices
e: edges

0: [1,4]
1: [0,4,3,2]
4: [0,1,3]
3: [4,1,2]
2: [1,3]

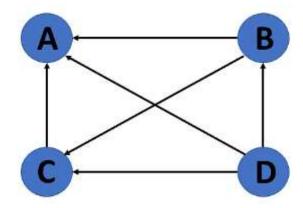
SC: (v+2e)

0  1  2  3  4
0  0  1  0  0  1
1  1  0  1  1  1
2  0  1  0  1  0
3  0  1  1  0  1
4  1  1  0  1  0

SC: (v^2)
```

```
In [ ]:
```

### **Represensation of Unweighted Directed Graph**



A: []
B: [A,C]
C: [A]

D: [A,B,C]

SC: (v+2e)

A B C D A 0 0 0 0

D 1 0 1 0

C1 0 0 0

D 1 1 1 0

SC: (v^2)

In [ ]:

```
In [4]: # Adjancey List Repr
        # dict<int, List>
        # map<int, vector<int>>
        class UndirectedGraph:
            def __init__(self):
                self.__data = {} # empty dict/map
            def add(self, v1, v2):
                if v1 not in self.__data:
                     self.__data[v1] = []
                self.__data[v1].append(v2)
                if v2 not in self. data:
                    self.__data[v2] = []
                self.__data[v2].append(v1)
            def print(self):
                print(self.__data)
        g = UndirectedGraph()
        g.add(0,1)
        g.add(0,4)
        g.add(1,4)
        g.add(1,3)
        g.add(1,2)
        g.add(4,3)
        g.add(3,2)
        g.print()
        # 0: [1,4]
        # 1: [0,4,3,2]
        # 4: [0,1,3]
        # 3: [4,1,2]
        # 2: [1,3]
```

 $\{0: [1, 4], 1: [0, 4, 3, 2], 4: [0, 1, 3], 3: [1, 4, 2], 2: [1, 3]\}$ 

```
In [8]: # Adjancey List Repr
        # dict<int, List>
        # map<int, vector<int>>
        class DirectedGraph:
            def __init__(self):
                self.__data = {} # empty dict/map
            def add(self, v1, v2):
                Create an edge from v1->v2
                if v1 not in self.__data:
                    self.__data[v1] = []
                self.__data[v1].append(v2)
                if v2 not in self.__data:
                    self.__data[v2] = []
            def print(self):
                print(self.__data)
        g = DirectedGraph()
        g.add('B','A')
        g.add('B','C')
        g.add('C','A')
        g.add('D','A')
        g.add('D','B')
        g.add('D','C')
        # A: []
        # B: [A,C]
        # C: [A]
        # D: [A,B,C]
        g.print()
        {'B': ['A', 'C'], 'A': [], 'C': ['A'], 'D': ['A', 'B', 'C']}
```

```
In [ ]:
```

#### **Matrix Repr**

```
In [27]: # dict<int, List>
         # map<int, vector<int>>
         class UndirectedGraph:
             def __init__(self, num_vertices):
                  self.<u></u>data = []
                  for _ in range(num_vertices):
                      self.__data.append( [0 for _ in range(num_vertices) ] )
             def add(self, v1, v2):
                  self.__data[v1][v2] = 1
                  self.__data[v2][v1] = 1
             def print(self):
                  for row in self.__data:
                      print(row)
         g = UndirectedGraph(5)
         g.add(0,1)
         g.add(0,4)
         g.add(1,4)
         g.add(1,3)
         g.add(1,2)
         g.add(4,3)
         g.add(3,2)
         g.print()
         # 0: [1,4]
         # 1: [0,4,3,2]
         # 4: [0,1,3]
         # 3: [4,1,2]
         # 2: [1,3]
          [0, 1, 0, 0, 1]
         [1, 0, 1, 1, 1]
         [0, 1, 0, 1, 0]
         [0, 1, 1, 0, 1]
         [1, 1, 0, 1, 0]
 In [ ]:
 In [ ]:
 In [ ]: |### Traversal
         - DFS: stack, recursion
         - BFS: queue, iteration
```

In [ ]:

## **BFS: Using queue**

```
import queue
In [26]:
         # Adjancey List Repr
         # dict<int, List>
         # map<int, vector<int>>
         class UndirectedGraph:
             def init (self):
                 self.__data = {} # empty dict/map
             def add(self, v1, v2):
                 if v1 not in self.__data:
                     self. data[v1] = []
                 self.__data[v1].append(v2)
                 if v2 not in self.__data:
                     self. data[v2] = []
                 self.__data[v2].append(v1)
             def traverse(self):
                   1/ 9
                   // set
                   // add first element to a and set
                   // while q is not empty:
                   // check if neighbour not in set:
                   //
                           push to set and q
                 q = queue.Queue()
                 visited = set() # hash set O(1)
                 if len(self. data) == 0:
                     print("{}")
                     return
                 curr = next(iter(self.__data.keys())) # get one element
                 q.put(curr)
                 visited.add(curr)
                 while not q.empty(): # O(v)
                     curr = q.get()
                     print(curr)
                     neighbours = self. data[curr]
                     for v in neighbours: # v
                         if v not in visited:
                              visited.add(v)
                              q.put(v)
         # TC: O(v^2) worst case (all vertices are connected)
         # TC: O(e)
         # SC: O(v)
         g = UndirectedGraph()
         g.add(0,1)
         g.add(0,4)
         g.add(1,4)
         g.add(1,3)
         g.add(1,2)
         g.add(4,3)
         g.add(3,2)
```

```
g.traverse()

# 0: [1,4]

# 1: [0,4,3,2]

# 4: [0,1,3]

# 3: [4,1,2]

# 2: [1,3]

0

1

4

3

2
```

```
class UndirectedGraph{
    Map<Integer,List<Integer>> graph;
    public UndirectedGrap(){
         graph = new HashMap<>();
    }
    public void add(self, v1, v2){
         graph.computeIfAbsent(v1,value->new ArrayList<>()).add(v2);
         graph.computeIfAbsent(v2,value->new ArrayList<>()).add(v1);
    }
    public void traverse(){
        Queue<Integer> que = new LinkedList<>();
        Set<Integer> vis = new HashSet<>();
        que.add(0);
        vis.add(0);
        while(que.size()>0){
            Integer front = que.remove();
            System.out.print(front+" ");
            for(Integer adj: graph.get(front)){
                if(!vis.contains(adj)){
                    que.add(adj);
                    set.add(adj);
                }
            }
        }
    }
}
```

```
public class UndirectedGraph {
    private HashMap<Integer, ArrayList<Integer>> data;
    public UndirectedGraph() {
        data = new HashMap<>();
    }
    public void add(int v1, int v2) {
        if (!data.containsKey(v1)) {
            data.put(v1, new ArrayList<>());
        }
        data.get(v1).add(v2);
        if (!data.containsKey(v2)) {
            data.put(v2, new ArrayList<>());
        }
        data.get(v2).add(v1);
    }
    public void traverse() {
        HashSet<Integer> visited = new HashSet<>();
        Queue<Integer> queue = new LinkedList<>();
        // Add the first element to the queue and visited set
        int startVertex = data.keySet().iterator().next();
        visited.add(startVertex);
        queue.offer(startVertex);
        while (!queue.isEmpty()) {
            int currentVertex = queue.poll();
            System.out.print(currentVertex + " ");
            ArrayList<Integer> neighbors = data.get(currentVertex);
            for (int neighbor : neighbors) {
                if (!visited.contains(neighbor)) {
                    visited.add(neighbor);
                    queue.offer(neighbor);
            }
        }
    }
 }
```

In [ ]	] <b>:</b> [	
In [ ]	]:	

**DFS** 

```
import queue
In [33]:
         # Adjancey List Repr
         # dict<int, List>
         # map<int, vector<int>>
         class UndirectedGraph:
             def init (self):
                 self.__data = {} # empty dict/map
             def add(self, v1, v2):
                 if v1 not in self.__data:
                     self. data[v1] = []
                 self.__data[v1].append(v2)
                 if v2 not in self.__data:
                     self. data[v2] = []
                 self.__data[v2].append(v1)
             def traverse(self):
                 if len(self.__data) == 0:
                     print("{}")
                     return
                 curr = next(iter(self. data.keys())) # get one element
                 visited = set()
                 self._traverse(curr, visited)
             def _traverse(self, curr, visited):
                 if curr in visited:
                     return
                 print(curr) # process current node
                 visited.add(curr)
                 # recur for neighbours that are not already visited
                 for v in self. data[curr]:
                     if v not in visited:
                         self. traverse(v, visited)
             def traverse disconnected(self):
                 if len(self. data) == 0:
                     print("{}")
                     return
                 visited = set()
                 for node in self.__data.keys(): # traverse each vertex
                     self. traverse(curr, visited)
              for a tree order of print matters
               def traverse(root):
         #
                   print(root)
                   traverse(root.left)
                   traverse(root.right)
         g = UndirectedGraph()
         g.add(0,1)
```

```
g.add(0,4)
g.add(1,4)
g.add(1,3)
g.add(1,2)
g.add(4,3)
g.add(3,2)
g.traverse()
0
1
4
3
2
In []:
```

# **Disconnected Graph**