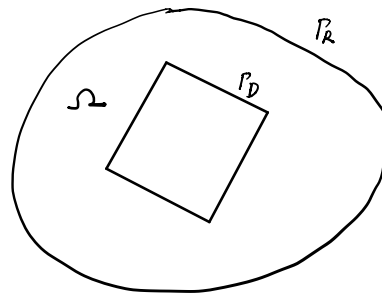


For the Helmholtz equation (two dimensional)

$$\Delta u + k^2 u = 0 \quad \text{in } \Omega$$

$$\frac{\partial u}{\partial n} - iku = g \quad \text{on } \Gamma_R$$

$$u = 0 \quad \text{on } \Gamma_D$$



We introduce the physical flux vector  $\vec{p} = \nabla u$ ,  
so we can develop the FOSLS formulation:

$$\left. \begin{aligned} \vec{p} - \nabla u &= \vec{0} \\ \nabla \cdot \vec{p} + k^2 u &= 0 \\ \nabla \times \vec{p} &= \vec{0} \end{aligned} \right\} \quad \text{in } \Omega$$

(1)  $\Rightarrow$

$$\left. \begin{aligned} u_2 - \frac{\partial}{\partial x} u_1 &= 0 \\ u_3 - \frac{\partial}{\partial y} u_1 &= 0 \\ \frac{\partial}{\partial x} u_2 + \frac{\partial}{\partial y} u_3 + k^2 u_1 &= 0 \\ \frac{\partial}{\partial x} u_3 - \frac{\partial}{\partial y} u_2 &= 0 \end{aligned} \right\} \quad \text{in } \Omega$$

$$\left. \begin{aligned} u &= 0 \\ \vec{n} \times \vec{p} &= \vec{0} \end{aligned} \right\} \quad \text{on } \Gamma_D$$

$$\vec{p} \cdot \vec{n} - iku = g \quad \text{on } \Gamma_R$$

$$\left. \begin{aligned} u_1 &= 0 \\ n_1^D u_3 - n_2^D u_2 &= 0 \end{aligned} \right\} \quad \text{on } \Gamma_D$$

$$n_1^R u_2 + n_2^R u_3 - iku_1 = g \quad \text{on } \Gamma_R$$

Let  $U = (u_1, u_2, u_3)^T$  and  $u = u_1$ ,  $p = (u_2, u_3)^T$

Then  $u$  can be written as

$$LU = AU + BU_x + CU_y = 0 \quad \text{in } \Omega$$

$$DU = 0 \quad \text{on } \Gamma_D$$

$$RU = g \quad \text{on } \Gamma_R$$

where  $A, B, C \in \mathbb{R}^{4 \times 3}$ ,  $D \in \mathbb{R}^{3 \times 3}$ ,  $R \in \mathbb{R}^{1 \times 3}$ :

$$A = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ k^2 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \quad B = \begin{pmatrix} -1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}, \quad C = \begin{pmatrix} 0 & 0 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & -1 & 0 \end{pmatrix}$$

$$D = \begin{pmatrix} 1 & 0 & 0 \\ 0 & -n_2^D & n_1^D \end{pmatrix}, \quad R = (-iku \quad n_1^R \quad n_2^R)$$

where  $n^D = (n_1^D, n_2^D)$  and  $n^R = (n_1^R, n_2^R)$  are the outward directed normal of  $\Gamma_D$  and  $\Gamma_R$  respectively, and  $U_x = \frac{\partial}{\partial x} U$ ,  $U_y = \frac{\partial}{\partial y} U$

Define the space  $V = [H^1(\Omega)]^3$  and a quadratic form

$$J(U; g) = \int_{\Omega} \|LU\|^2 d\Omega + \int_{\partial\Omega} \|DU\|^2 dS + \int_{\Gamma_R} |RU - g|^2 dS, U \in V, \quad (2)$$

The solution of (2) minimizes (2), and take the variation for (2), we have

seek  $U_1 \in V$ , such that  $a(U_1, U_2) = F(U_2), \forall U_2 \in V$

$$\text{where } a(U_1, U_2) = \int_{\Omega} LU_1 \cdot \overline{LU_2} d\Omega + \int_{\partial\Omega} DU_1 \cdot \overline{DU_2} dS + \int_{\Gamma_R} RU_1 \cdot \overline{RU_2} dS$$

$$F(U) = \frac{1}{2} \int_{\Gamma_R} RU \cdot \bar{g} + \overline{RU} \cdot g dS$$

If we have a finite dimensional space  $W^L \subset V$ , we can define a discrete

problem: find  $U^L \in W^L$ , such that

$$J(U^L; g) = \min_{U \in W^L} J(U; g)$$

the variation form is seek  $U^L \in W^L$ , such that

$$a(U^L, V^L) = F(V^L) \quad \text{for all } V^L \in W^L \quad (3)$$

suppose the basis of  $W^L$  are  $\{b_i^L\}_{i=1}^{N_L}$ , and  $U = \sum_{i=1}^{N_L} \alpha_i b_i^L$ , ( $\dim(W^L) = N^L$ )

we can have a matrix form:

$$K^L \alpha = f^L \quad (4)$$

where  $\alpha = (\alpha_1, \dots, \alpha_{N_L})^T$ ,  $f = (F(b_1^L), \dots, F(b_{N_L}^L))^T$ ,  $K_{ij} = a(b_i^L, b_j^L)$

Minimization of the functional (2) can be used as a guiding principle.

### Relaxation:

suppose  $U$  is a initial solution,

relaxation sweep can be defined as:

$$\text{For } i = 1, 2, \dots, N_L, s = \arg \min_s J(U + s b_i^L), \text{ set } U \leftarrow U + s b_i^L$$

In multigrid method, we have a hierarchy of nested meshes  $T_0 < T_1 < \dots < T_L$

and a set of finite dimensional spaces  $\{W^L\}_{L=0}^L$

$$W^L = [S_1^0(T_L)]^3$$

$$W^L = [\text{span} \{ b_p^L(x) \exp(i k d_t^L \cdot \vec{x}) \}]^3$$

In correction schema, the coarser grid provides a correction for the fine grid approximation  $U^L$ .  $U^L \leftarrow U^L + V^{L-1}$ , and we choose the correction in the sense that it minimizes the functional over all possible choices

$$V^{L-1} = \arg \min_{V^{L-1} \in W^{L-1}} J(U^L + V^{L-1}) \quad (4)$$

In order to add the correction to  $U^L$ , we need an operator  $I_{L-1}^L$  that maps the  $V^{L-1}$  to the  $W^L$  space, since the finite element spaces are not nested ( $W^{L-1} \not\subset W^L$ ), we employ the "energy projection" ( $I_{L-1}^L(V) = V \perp W^L$ )

$$I_{L-1}^L: W^{L-1} \rightarrow W^L$$

$$a(I_{L-1}^L(V), b_i^L) = a(V, b_i^L) \text{ for all } b^L$$

$$\text{assume } I_{L-1}^L V = \sum \varphi_j b_j^L$$

$$\text{then } \sum_i a(b_i^L, b_j^L) \varphi_i = a(V, b_j^L),$$

$$\text{matrix form: } [a(b_i^L, b_j^L)]_{ij} \varphi = [a(V, b_j^L)]_j$$

Coarser grid correction problem

$$\begin{aligned} V^{L-1} &= \arg \min_v J(U^L + v) \\ &= \arg \min_v \frac{1}{2} a(U^L + v, U^L + v) - F(U^L + v) \\ &= \arg \min_v \frac{1}{2} a(v, v) - F(v) + \frac{1}{2} a(U^L, v) + \frac{1}{2} a(v, U^L) \\ &\hat{=} \arg \min_v J^h(v) \end{aligned}$$