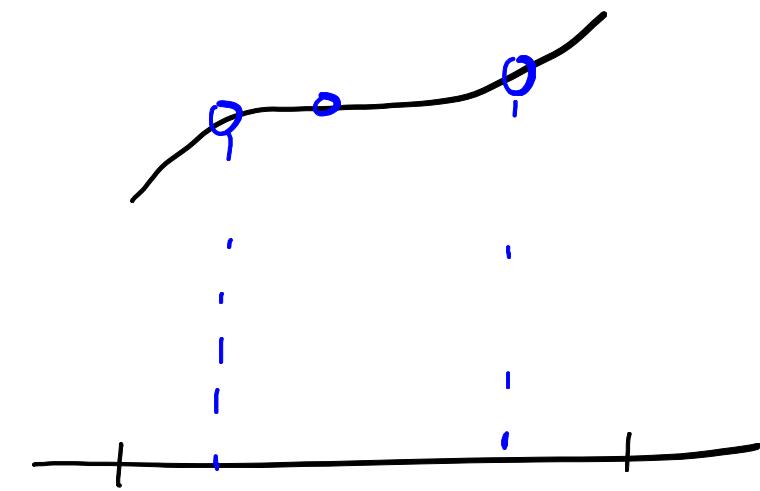


Lec 20.

Collocation method.



$$0 \leq c_1 < c_2 < \dots < c_r \leq 1$$

Lagrange polynomial.

$$t_n \quad t_n + c_1 h \quad t_n + c_r h \quad t_{n+1}$$

$$\begin{array}{c|c} c & A \\ \hline b^T \end{array}$$

Discrete

$$\begin{cases} \vec{k} = f(u_n \vec{e} + hA \vec{k}, t_n \vec{e} + ch) \\ u_{n+1} = u_n + h \vec{b}^T \vec{k} \end{cases}$$

\downarrow
 $v(t)$

satisfies

$$k_i = f(v(t_n + c_i h), t_n + c_i h)$$

$$\begin{cases} \dot{v}(t) = \tilde{f}(v(t), t) \\ v(t_n) = u_n \end{cases}$$

Linear combination

of Lag. poly. using
 $\{k_i\}_{i=1}^r$

Gauss quadrature.

r-pt Gauss-Legendre. algebraic accuracy

$$2r-1$$

$$\Rightarrow x^l, \quad 0 \leq l \leq 2r-1.$$

quadrature is exact.

G-L: $\begin{cases} \text{nodes: roots of } P_r(x) \subseteq [-1, 1] \\ \text{weights: Lag. poly.} \end{cases}$

Any polynomial. $p(x) \in P_{2r-1}$

$$p(x) = g(x) P_r(x) + h(x)$$

$2r-1$

$r-1$

r

$r-1$

exact:

$$\int_{-1}^1 p(x) dx = \int_{-1}^1 g(x) P_r(x) dx + \int_{-1}^1 h(x) dx$$

||
o

(orthogonality)

quadrature

$$\sum_{i=1}^r P(x_i) \omega_i = \sum_{i=1}^r g(x_i) \cancel{P_r(x_i)} \omega_i + \sum_{i=1}^r h(x_i) \omega_i$$

||
o

(roots)

↓

exact

(Lag. interp.
is exact
up to $r-1$)

$$\int_a^b f(x) dx$$

$$= \int_a^b \sum_{n=0}^{2r-1} \frac{f^{(n)}(a)}{n!} (x-a)^n + O((x-a)^{2r}) dx$$



exact

↓ after
integration

$$(b-a)^{2r+1}$$

3-term recursion.

$$\begin{cases} l P_l(x) = (2l-1)x P_{l-1}(x) - (l-1)P_{l-2}(x) \\ P_1(x) = 0, \quad P_0(x) = 1 \end{cases}$$

Ortho. poly. \Leftrightarrow 3 term
recursion.

$$\beta_l P_l(x) = (x - \alpha_l) P_{l-1}(x) - \gamma_l P_{l-2}(x) + \sum_{j=0}^{l-3} c_j P_j(x)$$

orthogonal $\Rightarrow c_j = 0 \Rightarrow 3 \text{ term}$

$$\beta_l \int_{-1}^1 P_j(x) P_l(x) dx = 0$$

$$= \int_{-1}^1 [P_j(x) (x - \alpha_\ell)] P_{\ell-1}(x) dx = 0$$

$$- \gamma_\ell \int_{-1}^1 P_j(x) P_{\ell-2}(x) dx = 0$$

$$+ \sum_{j=0}^{\ell-3} c_j' \int_{-1}^1 P_j(x) P_{j'}(x) dx$$

||

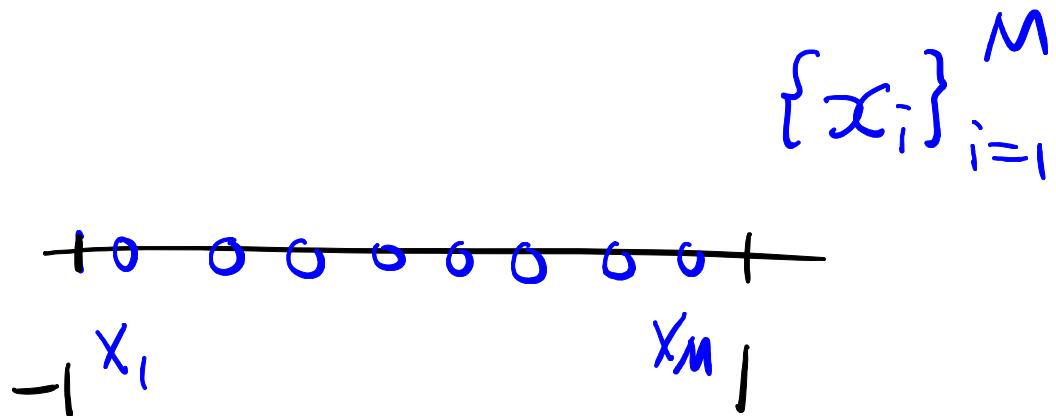
$$c_j \left(\int_{-1}^1 P_j^2(x) dx \right)$$

$$\Rightarrow c_j = 0 \Rightarrow 0 \leq j \leq l-3.$$

Reformulate:

$$x P_{l-1}(x) = \gamma_l P_{l-2}(x) + \alpha_l P_{l-1}(x) + \beta_l P_l(x)$$

$$x \in [-1, 1]$$



$$P_l(x) \longleftrightarrow_m \begin{bmatrix} 1 \\ P_l(x_i) \\ 1 \end{bmatrix} \leftarrow P_{l-1}$$

$$\mathcal{P}_l = \begin{bmatrix} 1 & & 1 \\ P_0(x_i) & \dots & P_l(x_i) \\ 1 & & 1 \end{bmatrix} \in \mathbb{R}^{M \times (l+1)}$$

$$A = \begin{bmatrix} x_1 \\ \ddots \\ x_M \end{bmatrix} \in \mathbb{R}^{M \times M}$$

$$A P_{l-1} = \gamma_l P_{l-2} + \alpha_l P_{l-1} + \beta_l P_l$$

T. triagonal.

$$A [P_0 \cdots P_{l-1}] = [P_0 \cdots P_l] \begin{bmatrix} \alpha_1 & \gamma_2 & 0 & & \\ \beta_1 & \alpha_2 & \gamma_3 & \ddots & \\ 0 & \beta_2 & \alpha_3 & \ddots & \gamma_l \\ \vdots & 0 & \beta_3 & \ddots & 0 \\ 0 & 0 & \ddots & \ddots & \alpha_l \\ & & & 0 & \beta_l \end{bmatrix}$$

\cap
 $R^{M \times l}$

\downarrow

$$\begin{bmatrix} T \\ \hline 0 \cdots 0 \beta_l \end{bmatrix}$$

\cap
 $R^{(l+1) \times l}$

$$A P_{l-1} = P_{l-1} T + \beta_l P_l e_l^T$$

Lanczos procedure.

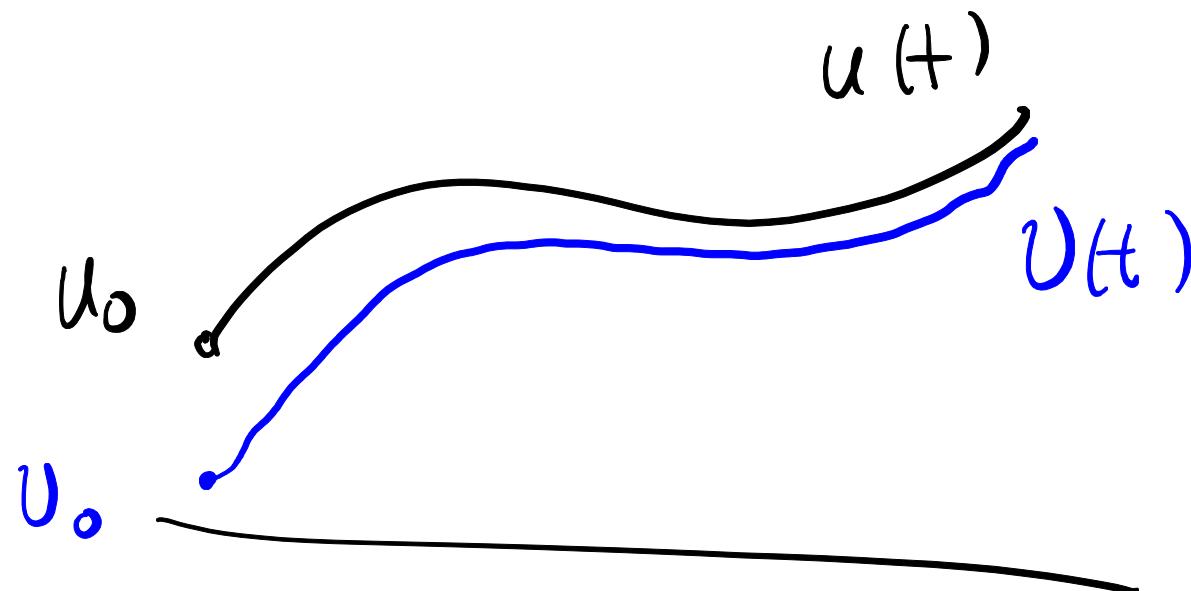
$$e_l^T = [0, \dots, 0, \underset{l+h}{\uparrow}, 1]$$

position

Thm. All G-L are B-stable.

$$\begin{cases} \dot{u}(t) = f(u(t), t) \\ u(0) = u_0 \end{cases}$$

$$\begin{cases} \dot{v}(t) = f(v(t), t) \\ v(0) = v_0 \end{cases}$$



$$E(t) = \|u(t) - v(t)\|^2$$

$$\dot{E}(t) \leq 0, \quad \forall t$$

$$(u - v, f(u) - f(v)) \leq 0$$

$\forall u, v$

With collocation method.

$$\ddot{\tilde{u}}(t) = \tilde{f}(\tilde{u}(t))$$

Lag interp.

$$\dot{\tilde{u}}(t_n + c_i h) = f(\tilde{u}(t_n + c_i h))$$

$$\tilde{u}(t_n) = u_n, \quad \tilde{u}(t_{n+1}) = u_{n+1}.$$

$$\{u_n\},$$

$$\{v_n\}$$

$$E_n = \|u_n - v_n\|^2 \quad . \quad E_{n+1} \leq E_n$$

$$E_{n+1} = \|u_{n+1} - v_{n+1}\|^2$$

$$\tilde{E}(t) = \|\tilde{u}(t) - \tilde{v}(t)\|^2 \in P_{2r}(t)$$

$$\tilde{E}(t_n) = E_n, \quad \tilde{E}(t_{n+1}) = E_{n+1}$$

$$E_{n+1} = E_n + \int_{t_n}^{t_{n+1}} \tilde{E}(t) dt$$

\$\in P_{2r-1}(t)\$

↓ Gauss quad
is exact

$$= E_n + \sum_{i=1}^r \tilde{E}(t_n + c_i h) w_i$$

$$\tilde{E}(t_n + c_i h) = 2(\tilde{u}(t_n + c_i h) - \tilde{v}(t_n + c_i h)),$$

$$f(\tilde{u}(t_n + c_i h)) - f(\tilde{v}(t_n + c_i h)) \leq 0$$

□.

Thm. Any r-step GL.

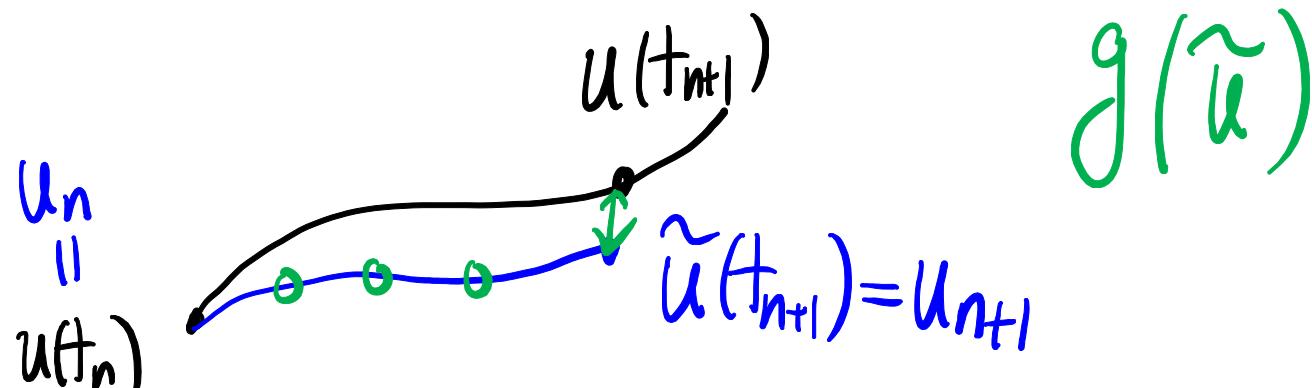
(i) A-stable

(ii) B-stable

(iii) symplectic.

Continuous perspective

$$\tilde{u} = f(\tilde{u}) + [\tilde{f}(\tilde{u}) - f(\tilde{u})]$$



We know

$$g(\tilde{u}(t_n + c_i h)) = 0$$

