

Lec 23.

Arnoldi

$$\{r, Ar, \dots, A^{k-1}r\}$$

$$A V_k = V_{k+1} \tilde{H}_k$$

$$\begin{matrix} h_{11} & h_{12} & & & & H_k \\ h_{21} & h_{22} & & & & \\ h_{32} & & & & & \\ & \ddots & & & & \\ & & & h_{k,k-1} & h_{kk} & \\ & & & 0 & \ddots & \\ & & & & & 0 & h_{(k+1),k} \end{matrix}$$

$$\text{FOM. } r = b - A(x_0 + V_k y)$$

$$r \perp \text{span } V_k$$

$$0 = V_k^T r \Rightarrow H_k y = \beta e_i \leftarrow k \times k$$

$$\beta = \| b - Ax_0 \|$$

# Problems of FOM

- ① Residual can be unbounded.
- ② keep entire history  
(before restarting)

Generalized minimal residual  
method ( GMRES) .

Default for general linear systems .

$$\min \| b - Ax \|_2$$

$$\text{s.t. } x = x_0 + V_k y_k , \quad y_k \in \mathbb{R}^k$$

$$b - A(x_0 + V_k y_k)$$

$$= \beta V_k e_i - V_{k+1} \tilde{H}_k y_k$$

$$= \bar{V}_{k+1} (\beta \tilde{e}_i - \tilde{H}_k y_k)$$

$$\min_{y_k} \| \beta \tilde{e}_i - \tilde{H}_k y_k \|_2 \quad \leftarrow \text{least-squares}$$

# Least-Squares

$$\min \| Ax - b \|_2^2$$

①  $A^T A x = A^T b$ .

② QR factorization

$$A \in \mathbb{R}^{m \times n}, \quad m > n.$$

$$A = QR \in \mathbb{R}^{m \times n}$$

$$\begin{matrix} A \\ \mathbb{R}^{m \times m} \end{matrix}$$

$$R = \begin{pmatrix} * & & & \\ - & \ddots & & \\ & & 0 & \\ & & & \ddots \end{pmatrix}_{m \times n}$$

$$\| QRx - Q\mathbf{Q}^T b \|_2$$

$$= \| Rx - Q^T b \|_2$$

$$\| \begin{pmatrix} * & & & \\ - & \ddots & & \\ & & 0 & \\ & & & \ddots \end{pmatrix} x - \begin{pmatrix} * \\ * \\ \vdots \\ * \end{pmatrix} \|_2$$

error

# Practical implementation of GMRES

① keep track of residual  
w. o. reconstructing  $x$ .

② Givens - QR.

Avoid repeatedly doing QR  
for  $\tilde{H}_k$ .

$$G(i, j; \theta) = \begin{bmatrix} & i \rightarrow & & \\ & \downarrow & \ddots & \\ & j \rightarrow & \cos \theta & \sin \theta \\ & & -\sin \theta & \cos \theta \\ & & & \ddots \end{bmatrix}$$

$$G(i, j, \theta) \begin{pmatrix} * \\ \vdots \\ a \\ b \\ \vdots \\ * \end{pmatrix} \xleftarrow{i} \quad \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} * \\ 0 \end{pmatrix}$$

$$\Rightarrow -\sin \theta a + \cos \theta b = 0$$

$$\Rightarrow \theta = \arctan \left( \frac{a}{b} \right) . \quad b \neq 0$$

Ex.

$$\begin{array}{c}
 \text{H}_2 \\
 \downarrow \\
 \begin{pmatrix} h_{11} & h_{12} \\ h_{21} & h_{22} \\ 0 & h_{32} \end{pmatrix} \xrightarrow{\text{QR}} \begin{pmatrix} * & * \\ * & * \\ 0 \end{pmatrix}
 \end{array}$$

① eliminate  $h_{21}$ .  $G(1,2,\theta)$

$$\rightarrow \begin{pmatrix} * & * \\ 0 & * \\ 0 & h_{32} \end{pmatrix}$$

② eliminate  $h_{32}$ .  $G(2,3,\theta')$

$$\rightarrow \begin{pmatrix} * & * \\ 0 & * \\ 0 & 0 \end{pmatrix} R$$

$$\| \tilde{H}_2 y - \beta \hat{e}_i \|$$

$$\rightarrow \| G(2,3,\theta') G(1,2,0) \tilde{H}_2 - G(2,3,\theta') G(1,1,0) \beta \hat{e}_i \|_2$$

$$\rightarrow \parallel \begin{pmatrix} * & * \\ * & 0 \end{pmatrix} y - \begin{pmatrix} * \\ * \\ * \end{pmatrix} \parallel_2$$

Ex.

$$\begin{pmatrix} h_{11} & h_{12} & h_{13} \\ h_{21} & h_{22} & h_{23} \\ 0 & h_{32} & h_{33} \\ 0 & 0 & h_{43} \end{pmatrix} \xrightarrow{G(h_2, \theta)} \begin{pmatrix} * & * & * \\ 0 & * & * \\ 0 & h_{32} & h_{33} \\ 0 & 0 & h_{43} \end{pmatrix}$$

$$\xrightarrow{G(2,3,\theta')} \begin{pmatrix} * & * & * \\ 0 & * & * \\ 0 & 0 & * \\ 0 & 0 & h_{43} \end{pmatrix}$$

$G(3, 4, \theta'')$



$$\begin{pmatrix} * & * & * \\ 0 & * & * \\ 0 & 0 & * \\ 0 & 0 & 0 \end{pmatrix}$$

$k$ -th step. work  $O(k)$









