

Lec 26.

$$\{x_k, r_k, P_k\}$$

$$x_{k+1} = x_k + \alpha_k P_k$$

line search

$$\alpha_k = \frac{r_k^T P_k}{P_k^T A P_k}$$

minimization

$$r_{k+1} = b - Ax_{k+1}$$

$$\{ P_{k+1} = r_{k+1}$$

SD

$$P_{k+1} = r_{k+1} + \beta_k P_k$$

CG    A-ortho

$$\beta_k = - \frac{P_k^T r_{k+1}}{P_k^T A P_k}$$

Connection between

- Practical CG
- Lanczos CG .

$$A V_m = V_{m+1} \tilde{T}_m \quad , \quad \tilde{T}_m = \begin{pmatrix} T_m \\ 0 & \ddots & \tilde{T}_{m+1, m} \end{pmatrix}$$

$$T_m y = \beta e_1$$

$$T_m = \begin{pmatrix} T_{11} & T_{12} \\ T_{21} & \ddots & \ddots \\ \vdots & \ddots & \ddots \\ T_{m,m} & T_{mm} \end{pmatrix}$$

$$T_m = L_m U_m = \begin{pmatrix} 1 & & 0 \\ l_{21} & 1 & \\ \vdots & \ddots & \\ 0 & \ddots & l_{m,m-1} \end{pmatrix} \begin{pmatrix} u_{11} & u_{12} & 0 \\ \vdots & \ddots & \\ 0 & u_{m-1,m} & u_{mm} \end{pmatrix}$$

$$y = U_m^{-1} L_m^{-1} \beta e_1$$

$$x_{m+1} = x_m + \underbrace{\left( V_m U_m^{-1} \right)}_{P_m} \underbrace{\left( L_m^{-1} \beta e_1 \right)}_{w_m}$$

||

$[P_0 \cdots P_{m-1}]$   conjugate directions

Columns of  $P_m$  are  $A$ -orthogonal.

$$P_m^T A P_m = U_m^{-T} \underbrace{V_m^T A V_m}_{\sim} U_m^{-1}$$

$$T_m = L_m U_m$$

$$= U_m^{-T} L_m$$

↓      ↓

lower triangular  $\times$  lower "  $\rightarrow$  lower triangular

+ symmetric  $\rightarrow$  diagonal

→ A-ortho .

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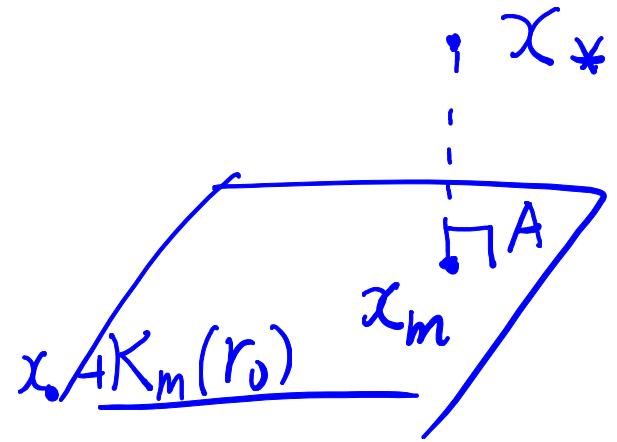
Thm.  $x_m$  is the sol. of CG

at step m.

$$x_m = \arg \min_{x} \|x - x_*\|_A$$

$$x = x_0 + q(A) r_0$$

$$q(A) \in P_{m-1}$$



Pf: Lanczos - CG

$$0 = V_m^T (b - Ax_m)$$

$$= V_m^T A (x_* - x_m)$$

□

Convergence of CG.

$$\forall x \in x_0 + K_m(r_0)$$

$$x_* - x = x_* - (x_0 - c_1 r_0 - \dots - c_m A^{m-1} r_0)$$

$$= A^{-1} (r_0 + c_1 A r_0 + \dots + c_m A^m r_0)$$

$$= A^{-1} p_m(A) r_0$$

$$P_m \in P_m, \quad P_m(0) = 1$$

one-to-one :  $x \leftrightarrow P_m$

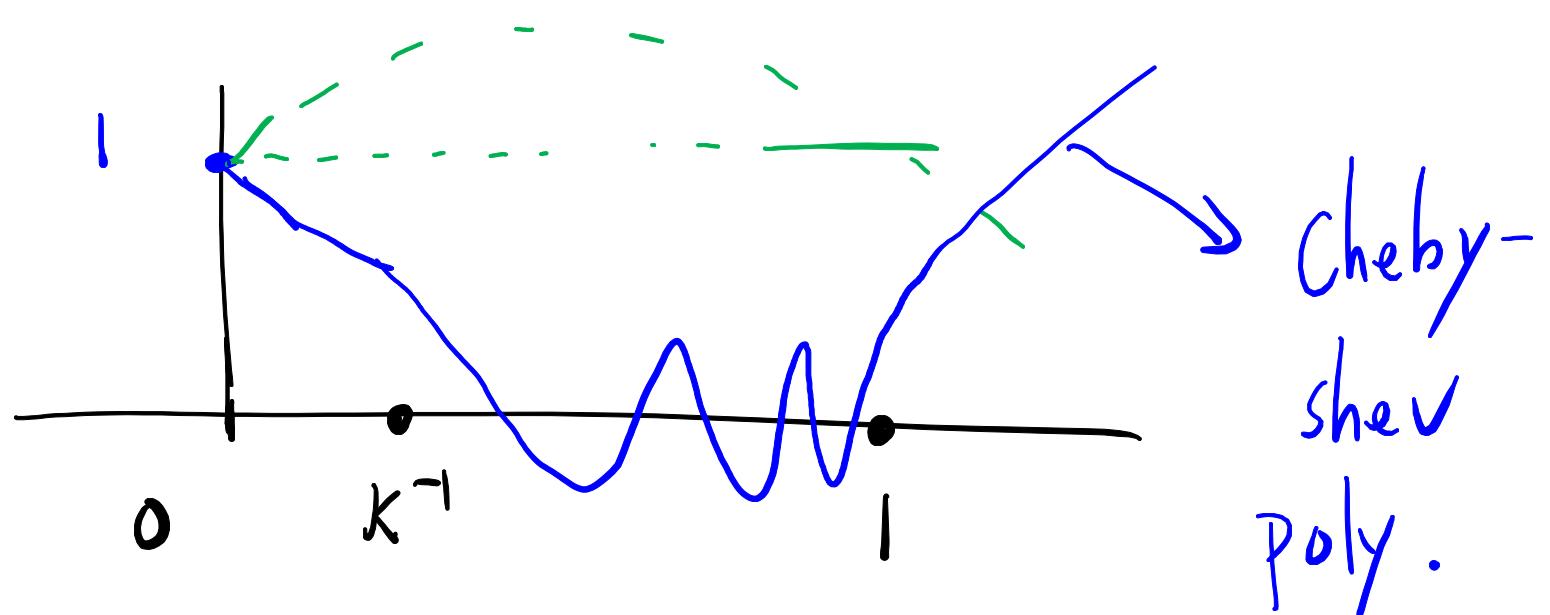
$$\|x_* - x_m\|_A = \min_{x \in x_0 + K_m} \|x_* - x\|_A$$

$$\leq \left( \min_{\substack{P_m \in P_m \\ P_m(0)=1}} \max_{\lambda_1 \leq \lambda \leq \lambda_N} |P_m(\lambda)| \right) \|A^{-1}r_0\|_A$$

$d_m$

$$\|A^{-1}r_0\|_A = \|x_0 - x_*\|_A$$

W. L. O. G.  $\lambda_1 = k^{-1}$ ,  $\lambda_N = 1$



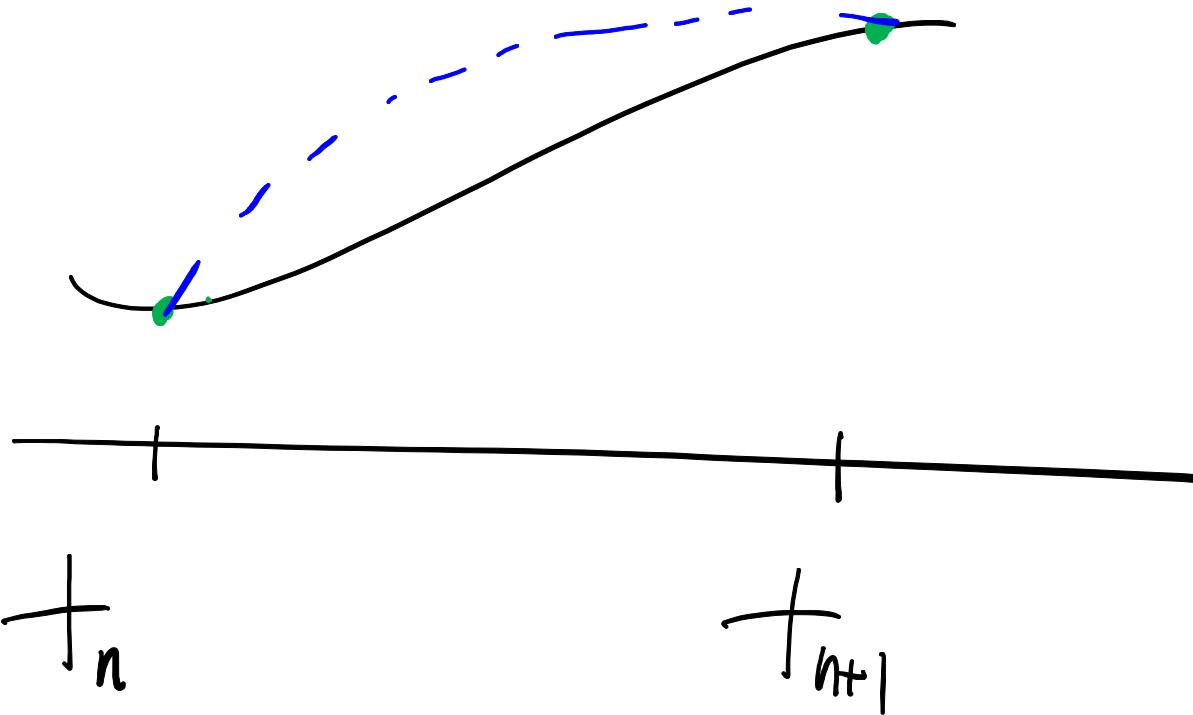
$$d_m \leq 2 \left( \frac{\sqrt{K} - 1}{\sqrt{K} + 1} \right)^m$$

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Preconditioning

"no free lunch"

use fixed pt iteration  
to solve implicit eqs.  $\rightarrow$  no saving.



- ① non-trivial nonlinear solver.  
Newton. Broyden ...
- ② non-trivial linear solver.

CG . GMRES . . .

sparse direct .

③ pre conditioning .

$$A \succ 0. \quad Ax = b. \quad k(A) \gg 1$$

$$M \succ 0 \quad M^{-1}Ax = M^{-1}b.$$

$$\kappa(M^{-1}A) \ll \kappa(A)$$

"ideal" preconditioner :  $M = A$ .

$M^{-1}A$  is NOT symmetric w.r.t.

Euclidean inner product

A symmetric .  $\mathbb{R}^{N \times N}$

$$\forall x, y \in \mathbb{R}^N . \quad (x, y) := x^T y$$

$$(x, Ay) = (Bx, y)$$

We define  $A^T := B$

$$x^T A y = x^T B^T y \quad \Rightarrow B^T = A$$

Claim .  $M^{-1}A$  is symmetric

w.r.t.  $M$ -inner product.

$$(x, M^{-1}A y)_{\textcolor{green}{M}} = x^T M M^{-1} A y$$

$$= x^T A M^{-1} M y$$

$$= (\textcolor{black}{M^{-1}A} x, y)_{\textcolor{green}{M}}$$

□ .



