

Lec 5.

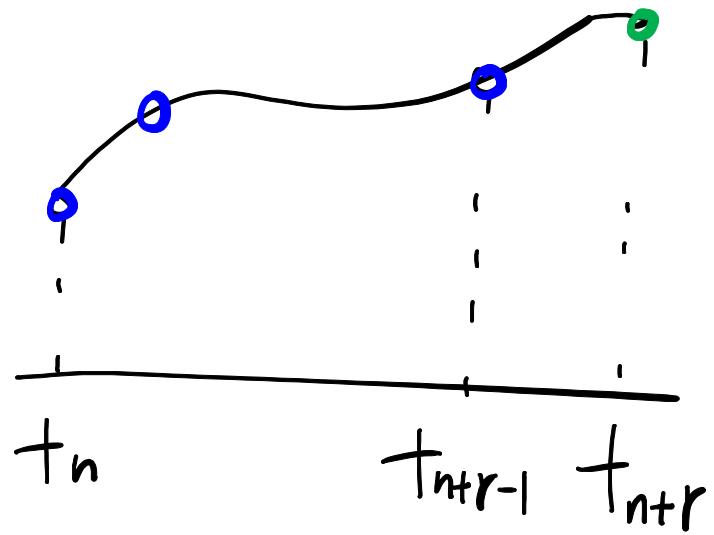
Consistency of LMM.

Adaptive time stepping

(a posteriori error control).

Zero stability.

(exer) Trapezoidal rule is convergent of  
order 2.



- AB Pr-1
- + ○ AM. Pr

LTE

$$T_n = \sum_{j=0}^r \alpha_j u(t_{n+j}) - h \sum_{k=0}^r \beta_k f(u(t_{n+k}), t_{n+k})$$

$$= \sum_{j=0}^r \alpha_j u(t_{n+j}) - h \sum_{k=0}^r \beta_k u'(t_{n+k})$$

$$u(t_{n+j}) = u(t_n) + (jh) u'(t_n) + \dots + \frac{1}{p!} (jh)^p u^{(p)}(t_n) + O(h^{p+1})$$

$$u'(t_{n+j}) = u'(t_n) + (jh) u^{(2)}(t_n) + \dots + \frac{1}{p!} (jh)^p u^{(p+1)}(t_n) + O(h^{p+1})$$

$$T_n = \sum_{k=0}^p c_k h^k u^{(k)}(t_n) + O(h^{p+1})$$

$$c_0 = \sum_{j=0}^r \alpha_j$$

$$c_1 = \sum_{j=0}^r (\alpha_j j - \beta_j)$$

:

$$c_k = \sum_{j=0}^r \left( \alpha_j \cdot \frac{j^k}{k!} - \beta_j \cdot \frac{j^{k-1}}{(k-1)!} \right)$$

$$= \frac{1}{k!} \left( \sum_{j=0}^r j^k \alpha_j - \beta_j j^{k-1} \cdot k \right)$$

algebraic

eq.

for  $\alpha$ 's,  $\beta$ 's

Thm . LTE is  $O(h^{p+1}) \Leftrightarrow c_0 = \dots = c_p = 0$

(exer) Check accuracy of AB1, AB2, AM1.

Thm. LTE of  $AB_n$  is  $O(h^{n+1})$

AM<sub>n</sub> is  $O(h^{n+2})$ .

Sketch. Choose special eqs.

$$\begin{cases} \dot{u}(+) = n +^{m-1}, & m \geq 1. \Rightarrow u(+) = +^m \\ u(0) = 0 \end{cases}$$

$\Rightarrow T_l = 0$  up to some order.

$\Rightarrow$  Lag. interpolation is exact

$$m \leq n. (AB_n)$$

$$m \leq n+1. (AM_n)$$

$\Rightarrow \bar{T}_l = 0$  gives  $C_l = 0$ .

Ref. [Hai] 3.2.

More compact way.

$$\begin{cases} u'(+) = u(+) \\ u(0) = 1 \end{cases} \Rightarrow u(+) = e^+.$$

$$\text{LTE } T_n = \sum_{j=0}^r \alpha_j e^{(n+j)h} - h \sum_{k=0}^r \beta_k e^{(n+k)h}$$
$$= e^{nh} \left( \sum_{j=0}^r \alpha_j (e^h)^j - \log(e^h) \sum_{k=0}^r \beta_k (e^h)^k \right)$$

$$\text{Define } z = e^h > 1$$

$$T_n = O(h^{p+1}) = O\left(\left(\log z\right)^{p+1}\right) = O\left(|z-1|^{p+1}\right)$$

Define characteristic polynomials of LMM.

$$\rho(z) = \sum_{j=0}^r \alpha_j z^j, \quad \sigma(z) = \sum_{k=0}^r \beta_k z^k$$

Thm. LTE is  $O(h^{p+1})$

$$\Leftrightarrow c_0 = \dots = c_p = 0$$

$$\Leftrightarrow \rho(z) - \log z \cdot \sigma(z) = O\left(|z-1|^{p+1}\right)$$

$\mathcal{E}_x$ . AB 1.

$$\rho(z) = z - 1 \quad , \quad \sigma(z) = 1$$

$$\rho(z) - \log(1 + (z-1)) \sigma(z)$$

$$\xi = z - 1$$

$$= \xi - \log(1 + \xi)$$

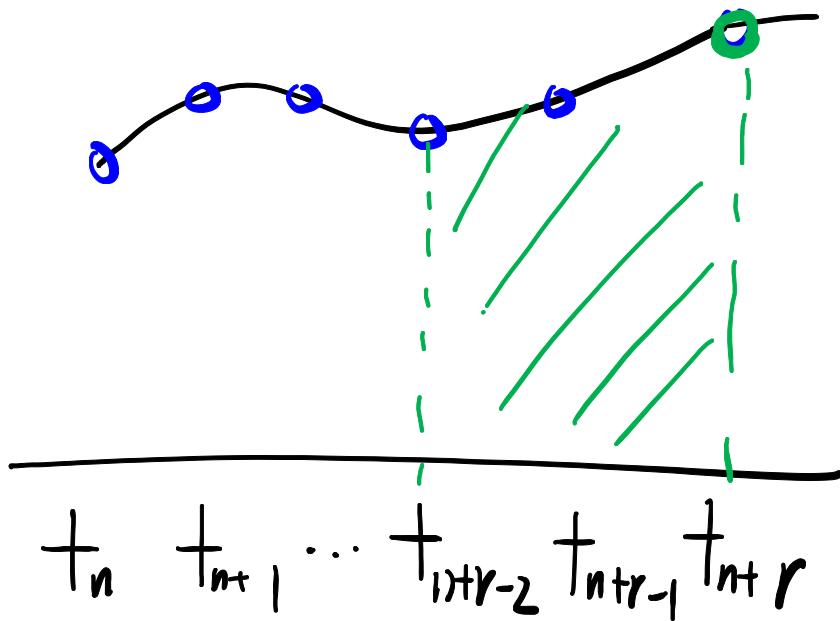
$$= \frac{1}{2} \xi^2 + O(\xi^3)$$

$$\Rightarrow \text{LTE is } O(h^2)$$

Other types of LMM.

$$u(t_{n+r}) - u(t_{n+r-2}) = \int_{t_{n+r-2}}^{t_{n+r}} f(u(s), s) ds$$

$\uparrow$   
quad. approx.



- Nyström
- + ◦ Milne

Adaptive time Stepping. "Milne device"

Monitor LTE  $\tau$ .

Alg. if ( $\tau > \delta h$ )

$$h \leftarrow \frac{h}{2} \quad \tilde{\delta} < \delta$$

if ( $\tau < \tilde{\delta} h$ )

$$h \rightarrow 2h$$

Estimate  $\tau$ .

$$\sum_{j=0}^r \alpha_j u_{n+j} = h \sum_{k=0}^r \beta_k f_{n+k}.$$

$$\sum_{j=0}^r \tilde{\alpha}_j \tilde{u}_{n+j} = h \sum_{k=0}^r \tilde{\beta}_k f_{n+k} \quad \leftarrow \text{explicit}$$

easy to evaluate

LTE  $\tau = c h^{p+1} u^{(p+1)}(t_n) + O(h^{p+2}) = u(t_{n+r}) - \underline{u}_{n+r}$

$$\tilde{\tau} = \tilde{c} h^{p+1} \tilde{u}^{(p+1)}(t_n) + O(h^{p+2}) = u(t_{n+r}) - \underline{\tilde{u}}_{n+r}$$

$$\tilde{u}_{n+r} - u_{n+r} = (c - \tilde{c}) h^{p+1} u^{(p+1)}(t_n) + O(h^{p+2})$$

$$\|\tau\| \approx |c| h^{p+1} \|u^{(p+1)}(t_n)\|$$

$$\|\tilde{u}_{n+r} - u_{n+r}\| \approx |c - \tilde{c}| h^{p+1} \|u^{(p+1)}(t_n)\|$$

$$\Rightarrow \|\tau\| \gtrsim \left| \frac{c}{c - \tilde{c}} \right| \cdot \|\tilde{u}_{n+r} - u_{n+r}\|.$$

Corollary.  $\frac{\tilde{c}}{c} = O(h^{p+2}) \Rightarrow \tilde{c} = 0$ .

$$\Rightarrow \|\bar{t}\| \approx \|\tilde{u}_{n+1} - u_{n+1}\|$$

↑  
approx true sol.

Ex. Trapezoidal monitored by AB2.

$$u_{n+1} = u_n + \frac{h}{2} (f_n + f_{n+1}) \rightarrow \bar{t} \approx -\frac{1}{12} h^3 u^{(3)}(t_n)$$

$$\tilde{u}_{n+1} = u_n + h \left( \frac{3}{2} f_n - f_{n-1} \right) \rightarrow \tilde{t} \approx \frac{5}{12} h^3 u^{(3)}(t_n)$$

$$\|\tau\| \approx \frac{1}{6} \|u_{n+1} - \tilde{u}_{n+1}\|$$

Zero stability

independent of LTE.

$$\|e_n\| \leq C_1 (\|e_0\| + \dots + \|e_{r-1}\|) + C_2 \frac{\text{LTE}}{h}$$

zero stable :  $C_1, C_2 < \infty$  as  $h \rightarrow 0$ .

