



Operating Systems

Lecture 5 Deadlocks

Jinpengchen

Email: jpchen@bupt.edu.cn



- The Deadlock Problem
- Deadlock Characterization
- Methods for Handling Deadlocks
- Deadlock Prevention
- Deadlock Avoidance
- Deadlock Detection
- Recovery from Deadlock

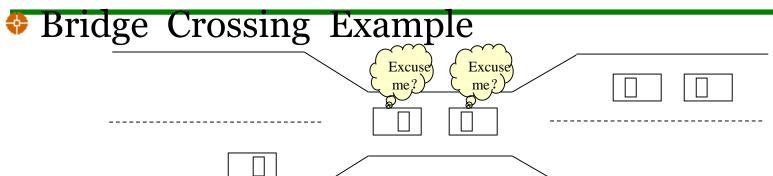


The Deadlock Problem

- Deadlock Situation: A set of blocked processes is in a deadlock state when each holds a resource and waits to acquire a resource held by another process in the set.
- Example 1
 - ✓ System has 2 disk drives
 - ✓ P1 and P2, each holds one disk drive and each needs another one
- Example 2
 - \checkmark semaphores A and B, initialized to 1

```
P0 P1
wait (A); wait (B)
wait (B); wait (A)
```





- Traffic only in one direction
- Each section of a bridge can be viewed as a resource
- If a deadlock occurs, it can be resolved if one car backs up (preempt resources and rollback)
- Several cars may have to be backed up if a deadlock occurs
- Starvation is possible
- Note Most OSes do not prevent or deal with deadlocks



Why did the deadlock happen?

- ✓ Insufficient resources
- ✓ Unreasonable execution order



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Necessary Conditions

- Deadlock can arise if four conditions hold simultaneously.
 - ✓ Mutual exclusion(互斥):
 - only one process at a time can use a resource.
 - ✓ Hold and wait (持有并等待):
 - a process holding at least one resource is waiting to acquire additional resources held by other processes.
 - ✓ No preemption(不剥夺):
 - a resource can be released only voluntarily by the process holding it, after that process has completed its task.



Deadlock Characterization

- Necessary Conditions
 - ✓ Circular wait(循环等待):
 - there exists a set $\{P_0, P_1, \dots, P_0\}$ of waiting processes such that P_0 is waiting for a resource that is held by P_1, P_1 is waiting for a resource that is held by P_2, \dots, P_{n-1} is waiting for a resource that is held by P_n , and P_n is waiting for a resource that is held by P_0 .



System Model

- A system consists of a finite number of resources
- The resources are partitioned into several types, each consisting of some number of identical instance.
 - ✓ physical resources: CPU cycles, memory space, I/O devices
- ✓ logical resources: files, semaphores, and monitors

 System model
 - ✓ Resource types R1 , R2 , . . . , Rm
 - ✓ Each resource type Ri has Wi instances.
 - ✓ Each process utilizes a resource as follows:
 - request: may wait until it can acquire the resource
 - use
 - release

9/7/2019 BUPTSSE 9



Resource-Allocation Graph

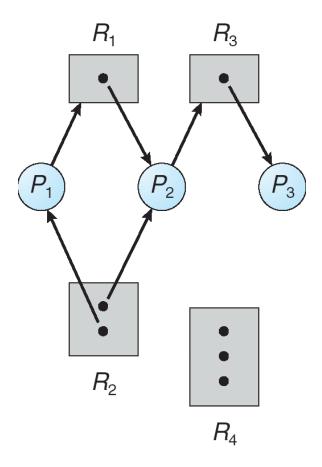
- System resource-allocation graph: A directed graph
 - ✓ A set of vertices V and a set of edges E.
 - ✓ V is partitioned into two types:
 - $P = \{P1, P2, \dots, Pn\}$, the set consisting of all the processes in the system.
 - : Process
 - $R = \{R1, R2, \dots, Rm\}$, the set consisting of all resource types in the system.
 - : Resource Type with 4 instances



- Resource-Allocation Graph
 - ✓ E is partitioned into two types.
 - request edge(请求边) directed edge Pi→Rj
 - P_i : Pi requests an instance of Rj
 - assignment edge(分配边) directed edge Rj→Pi
 - P_i: Pi is holding an instance of Rj



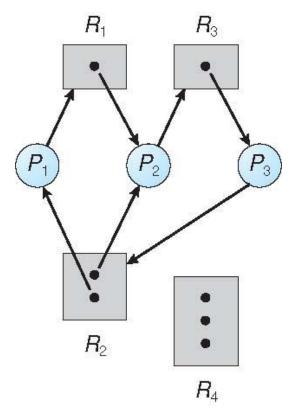
An Example of a Resource Allocation Graph





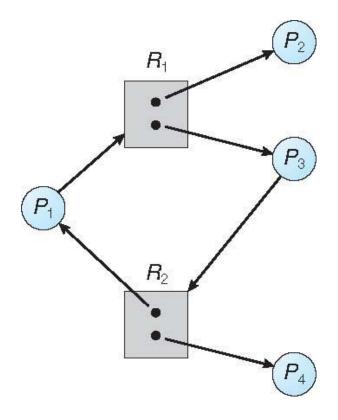
Example of a Resource Allocation Graph with a

Deadlock





A Graph with a Cycle but No Deadlock





Basic Facts

- If graph contains no cycles \Rightarrow no deadlock.
- If graph contains a cycle ⇒
 - ✓ if only one instance per resource type, then deadlock.
 - ✓ if several instances per resource type, possibility of deadlock.



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Methods for Handling Deadlocks

- Methods for Handling Deadlocks
 - Ensure that the system will never enter a deadlock state.
 - ✓ Deadlock prevention
 - ✓ Deadlock avoidance
 - Allow the system to enter a deadlock state and then recover.
 - ✓ Deadlock detection and recovery from deadlock
 - Ignore the problem and pretend that deadlocks never occur in the system; used by most operating systems, including UNIX.



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- Deadlock prevention provides a set of methods for ensuring that at least one of the necessary conditions cannot hold.
- Mutual Exclusion
 - Not required for sharable resources (read-only files); must hold for nonsharable resources. (printer)
 - In general, we cannot deny the mutual-exclusion condition



Hold and Wait

- must guarantee that whenever a process requests a resource, it does not hold any other resources.
 - ✓ Require process to request and be allocated all its resources before it begins execution, or
 - ✓ Allow process to request resources only when the process has none.
- Disadvantage:
 - ✓ Low resource utilization;
 - ✓ Starvation possible.



No Preemption

- If a process that is holding some resources, requests another resource that cannot be immediately allocated to it, then all resources currently being held are preempted.
 - ✓ Preempted resources are added to the list of resources for which the process is waiting.
 - ✓ Process will be restarted only when it can regain its old resources, as well as the new ones that it is requesting.
- preempt the desired resources from the waiting process and allocate them to the requesting process
 - ✓ if the resource are neither available nor held by a waiting process, the requesting process must wait. While waiting, some of its resources may be preempted by other requesting process
 - ✓ a process can be restarted only when it is allocated the new resources it is requesting and recovers any resources that were preempted.



Circular Wait

- impose a total ordering of all resource types, and require that each process requests resources in an increasing order of enumeration.
 - ✓ always in an increasing order
 - ✓ may release some higher ordered resource before requesting lower ordered resource



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Execute a deadlock avoidance algorithm to ensure there can never be a circular-wait condition.

Banker's Algorithm



- Requires that the system has a priori information available.
 - Simplest and most useful model requires that each process declare the maximum number of resources of each type that it may need.
 - The deadlock-avoidance algorithm dynamically examines the resource-allocation state to ensure that there can never be a circular-wait condition.
 - Resource—allocation state is defined by the number of available and allocated resources, and the maximum demands of the processes.



An Example

- Total resources 12; 3 processes
- Snapshot at time t₀

	Max	Allocation	Need	Available
P1	10	5	5	3
P2	4	2	2	
P3	9	2	7	



◆ Safe State (安全状态)

- When a process requests an available resource, system must decide if immediate allocation leaves the system in a safe state.
- System is in safe state if there exists a safe sequence <P1, P2, ..., Pn> of all the processes
- Sequence <P1, P2, ..., Pn> is safe if for each Pi, the resources that Pi can still request can be satisfied by currently available resources + resources held by all the Pj, with j < i

That is:

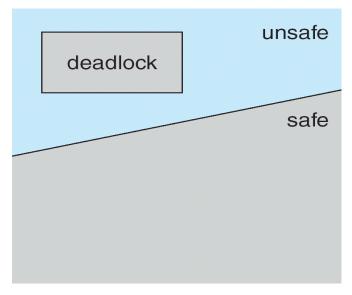
- ✓ If Pi resource needs are not immediately available, then Pi can wait until all Pj have finished.
- ✓ When Pj is finished, Pi can obtain needed resources, execute, return allocated resources, and terminate.
- ✓ When Pi terminates, Pi+1 can obtain its needed resources, and so on.

9/7/2019 BUPTSSE 27



Basic Facts

- If a system is in safe state \Rightarrow no deadlocks
- If a system is in unsafe state ⇒ possibility of deadlock
- Avoidance \Rightarrow ensure that a system will never enter an unsafe state.





Avoidance algorithms

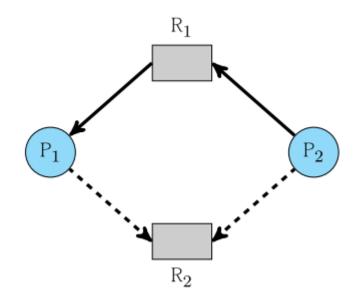
- Single instance of a resource type
 - ✓ Use a resource—allocation graph
- Multiple instances of a resource type
 - ✓ Use the banker's algorithm



- Resource-Allocation Graph Scheme
 - Resource-Allocation Graph
 - ✓ Claim edge(需求边) Pi → Rj
 - indicated that process Pj may request resource Rj;
 - represented by a dashed line
 - ✓ Claim edge converts to request edge when a process requests a resource
 - ✓ Request edge converts to an assignment edge when the resource is allocated to the process
 - ✓ When a resource is released by a process, assignment edge reconverts to a claim edge
 - ✓ Resources must be claimed a priori in the system



- Resource-Allocation Graph Scheme
 - Example: Safe State



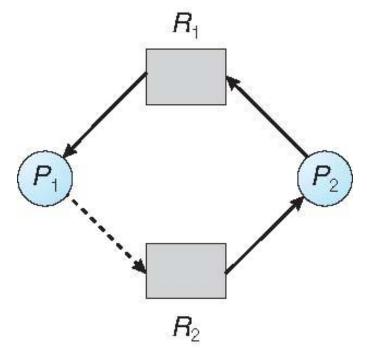
safe sequence: < P 1, P 2 >



Resource-Allocation Graph Scheme

Example: Unsafe State in Resource-Allocation

Graph



Unsafe State In Resource-Allocation Graph



- Resource-Allocation Graph Scheme
 - Resource-Allocation Graph Algorithm
 - ✓ Suppose that process Pi requests a resource Rj
 - ✓ The request can be granted only if converting the request edge to an assignment edge does not result in the formation of a cycle in the resource allocation graph



- ⇔ Banker's Algorithm (银行家算法)
 - Multiple instances
 - Each process must have a priori claim maximum use
 - When a process requests a resource it may have to wait
 - When a process gets all its resources it must return them in a finite amount of time
- Data structures
- Safety algorithm
- Resource-request algorithm



Deadlock Avoidance (死锁避免)

Data structures

- Let n = number of processes, and m = number of resources types.
 - ✓ Available: Vector of length m. If available [j] = k, there are k instances of resource type Rj available
 - ✓ Max: $n \times m$ matrix. If Max [i, j] = k, then process Pi may request at most k instances of resource type Rj
 - ✓ Allocation: n × m matrix. If Allocation[i, j] = k then Pi is currently allocated k instances of Rj
 - ✓ Need: n × m matrix. If Need[i, j] = k, then Pi may need k more instances of Rj to complete its task

Need [i, j] = Max[i, j] - Allocation [i, j]



| Deadlock Avoidance (死锁避免)

Safety Algorithm

1. Let Work and Finish be vectors of length m and n, respectively. Initialize:
Work = Available

Finish [i] = false for $i = 0, 1, \dots, n-1$

- 2. Find an i such that both:
 - (a) Finish [i] = false
 - (b) Need_i \leq Work

If no such i exists, go to step 4

- 3. Work = Work + Allocationi Finish[i] = true go to step 2
- 4. If Finish [i] == true for all i, then the system is in a safe state



Resource-Request Algorithm for Process Pi

 $Request = request vector for process P_i$.

If $Request_i[j] = k$ then process P_i wants k instances of resource type R_i

- 1. If *Request_i* ≤ *Need_i* go to step 2. Otherwise, raise error condition, since process has exceeded its maximum claim
- 2. If $Request_i \le Available$, go to step 3. Otherwise P_i must wait, since resources are not available
- 3. Pretend to allocate requested resources to P_i by modifying the state as follows:

```
Available = Available - Request;

Allocation<sub>i</sub> = Allocation<sub>i</sub> + Request<sub>i</sub>;

Need<sub>i</sub> = Need<sub>i</sub> - Request<sub>i</sub>;
```

- If safe ⇒ the resources are allocated to Pi
- If unsafe ⇒ Pi must wait, and the old resource-allocation state is restored

9/7/2019 BUPTSSE 37



- Example of Banker's Algorithm
- 5 processes P0 through P4;
- 3 resource types:

A (10 instances), B (5instances), and C (7 instances)

Snapshot at time To:

•		Allocation	Max	Available
		ABC	ABC	ABC
	P0	010	753	332
	P1	200	322	
	P2	302	902	
	<i>P</i> 3	211	222	
	P4	002	433	



- Example of Banker' s Algorithm
- The content of the matrix Need is defined to be Max Allocation

	Need	
	ABC	
P0	743	
P1	122	
<i>P</i> 2	600	
<i>P</i> 3	011	
P4	431	

The system is in a safe state since the sequence < P1, P3, P4, P2, P0> satisfies safety criteria



Deadlock Avoidance (死锁避免)

- Example: P1 Request (1,0,2)
- Check that Request \leq Available (that is, $(1,0,2) \leq (3,3,2) \Rightarrow$ true)

	<u>Allocation</u>	<u>Need</u>	<u>Available</u>
	ABC	ABC	ABC
P_0	010	7 4 3	$332 \rightarrow 230$
P_1	2 0 0 -3 0	2 1 2 2 0	20
P_2	3 0 1	600	
P_3	211	011	
P_4	002	4 3 1	

- Executing safety algorithm shows that sequence $\langle P_1, P_3, P_4, P_0, P_2 \rangle$ satisfies safety requirement
- Can request for (3,3,0) by P₄ be granted?
- Can request for (0,2,0) by P₀ be granted?



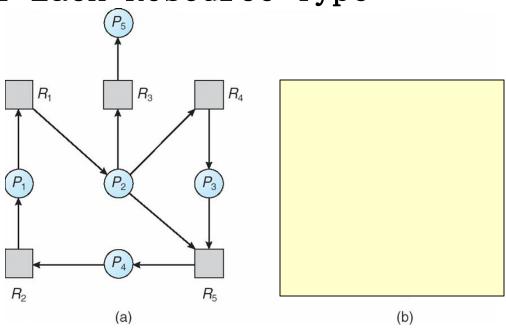
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- Allow system to enter deadlock state
 - Detection algorithm
 - ✓ single instance
 - ✓ several instances
 - Recovery scheme
 - ✓ Process termination
 - ✓ Resource preemption



- Single Instance of Each Resource Type
- Maintain wait-for graph
 - Nodes are processes
 - Pi \rightarrow Pj if Pi is waiting for Pj



Resource-Allocation Graph Corresponding wait-for graph

Periodically invoke an algorithm that searches for a cycle in the graph. If there is a cycle, there exists a deadlock



Several Instances of a Resource Type

■ Data structures:

- ✓ Available: A vector of length m indicates the number of available resources of each type.
- ✓ Allocation: An n x m matrix defines the number of resources of each type currently allocated to each process.
- ✓ Request: An n x m matrix indicates the current request of each process. If Request[i][j] = k, then process Pi is requesting k more instances of resource type Rj.



- 1. Let *Work* and *Finish* be vectors of length *m* and *n*, respectively Initialize:
 - (a) Work = Available
 - (b) For i = 1, 2, ..., n, if $Allocation_i \neq 0$, then Finish[i] = false; otherwise, Finish[i] = true
- 2. Find an index *i* such that both:
 - (a) Finish[i] == false
 - (b) $Request_i \leq Work$

If no such *i* exists, go to step 4

- 3. Work = Work + Allocation_i Finish[i] = true go to step 2
- 4. If Finish[i] == false, for some i, $1 \le i \le n$, then the system is in deadlock state. Moreover, if Finish[i] == false, then P_i is deadlocked



Example of Detection Algorithm

- Five processes $P_0 P_4$;
- three resource types
 A (7 instances), B (2 instances), and C (6 instances)
- Snapshot at time T_0 :

	<u>Allocation</u>	<u>Request</u>	<u>Available</u>
	ABC	ABC	ABC
P_0	010	000	000
P_1	200	202	
P_2	303	000	
P_3	211	100	
P_4	002	002	

Sequence $\langle P_0, P_2, P_3, P_1, P_4 \rangle$ will result in *Finish*[*i*] = true for all *i* BUPTSSE



Example of Detection Algorithm

If P₂ requests an additional instance of type C

```
\frac{Request}{ABC}

ABC

P_0 = 000

P_1 = 201

P_2 = 000 \rightarrow 001

P_3 = 100

P_4 = 002
```

- State of system?
 - Can reclaim resources held by process P₀, but insufficient resources to fulfill other processes requests
 - Deadlock exists, consisting of processes P₁, P₂, P₃, and P₄



- Example of Detection Algorithm
 - ✓ When, and how often, to invoke the algorithm, depends on:
 - How often is a deadlock likely to occur?
 - How many processes will need to be rolled back?
 - ✓ If detection algorithm is invoked arbitrarily, there may be many cycles in the resource graph and so we would generally not be able to tell which of the many deadlocked processes "caused" the deadlock.



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Process Termination

- ✓ Abort all deadlocked processes
- ✓ Abort one process at a time until the deadlock cycle is eliminated
- ✓ To minimize cost: In which order should we choose to abort?
 - -Priority of the process
- -How long the process has computed, and how much longer the process will compute before completing its designated task
 - -Resources the process has used
 - -Resources the process needs to complete
 - -How many processes will need to be terminated
 - -Is the process interactive or batch?



- Resource Preemption
 - Three issues need to be addressed:
 - ✓ Selecting a victim minimize cost
 - ✓ Rollback return to some safe state, restart the process from that state
 - ✓ Starvation the same process may always be picked as a victim; the most common solution is to include the number of rollbacks in the cost factor.



End of Chapter 5