



MOBILAB

Abstract:

During the process of investigating helpful technologies to autonomous vehicles, we found that there is a real need in a standalone system that hold the ability to gather and process real-time information and telemetry that connected to it, such as: Camera, Microphone, Barometer, GPS Location, Temperature, etc...

The ability to process this information and send it to the ground-station in real-time, parallelly to send this information to a connected cloud services and of course store this information and data locally on the device storage, grant the autonomous vehicle technology and specifically UAV's new strong and important abilities.

Such technology can get the market to developing new autonomous vehicles with new abilities that never seen up for today, also improvement of existing systems on existing autonomous vehicles that are not carrying mobile lab systems such as describe above.

The MobiLAB application designed to include two separated components, the former will be the system Application for an Android devices which will give the user controlling abilities on recording the sensors and change the settings.

And the latter will be an Android background Service which will run on the background of the mobile device and will be the authority to record data from the sensors, gather important information, analyze it, send the data to the ground and cloud control stations.

The Android device planned to be as small as possible and the application won't demand from it high computing performance of a new Android devices (Android SDK 4.4.3 version or newer), to keep things and weight as simple and light as possible.

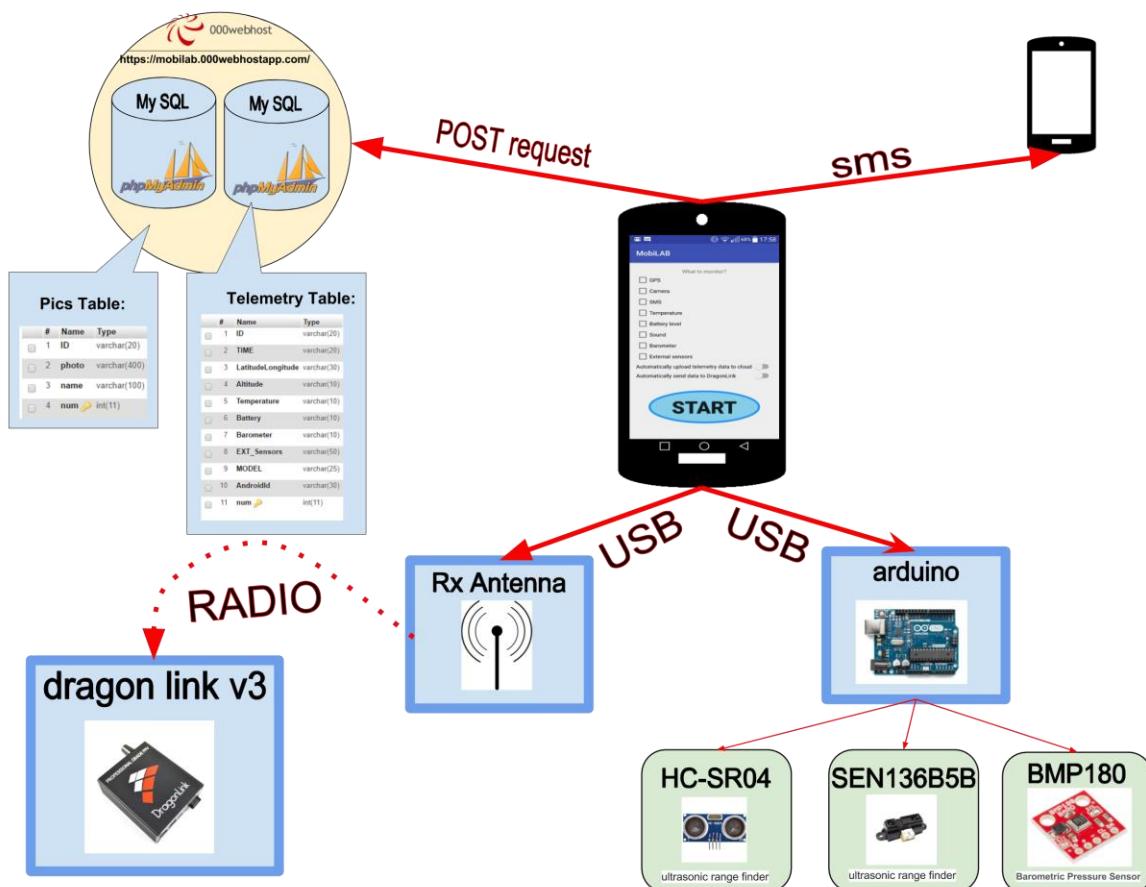
As we said the device will communicate with the user on several channels of communication such as:

- **SMS messages** which will contain critical information about the system state such as GPS location, battery level and temperature, also they will be encoded in order to save bandwidth.
- **4/3G connectivity** to the cloud that was pre-configured in order to real-time backup all the gathered information.
- **UHF Transceiver** (DragonLink) that send and receive all the data and telemetric information from the device into the ground station.
- **Local Storage** save all of the information which will be encrypted to avoid unwanted elements to access the data and also save storage space on the disk.



Mobilab architecture

BackEnd





Define the need:

develop android system that makes the android device to “mobile lab”.

The system will be useful to scientific experience or just for people who wants to get information from their remote device.

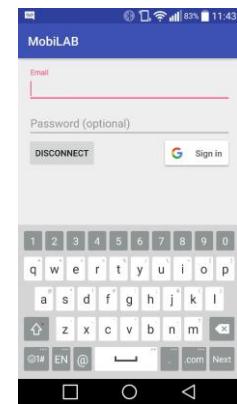
Use cases:

- The app will use all the relevant sensors that exist on the device (GPS, Temperature, Atmospheric Pressure, Sound, etc...). ability to connect external sensors (via the auxiliary or the mini USB OTG).
- Communicating with the data to database.
- Sending SMS's with the relevant data to the ground station.
- Every user will have separately web [Dashboard](#) database.
- The app could get orders from other devices (with SMS for example).
- The application is guaranteed to be efficient and battery friendly and totally secured.



Sign in & Authentication:

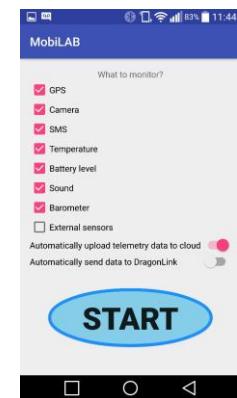
Right with the launch of the application the user will prompt to an authentication screen to fill in google username and password account.



Main Screen View:

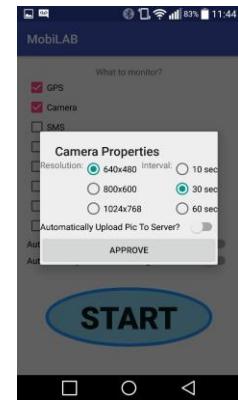
After the user has logged into the application the main menu screen will appear and will have the following check boxes options:

- GPS
- Camera
- SMS
- Temperature
- Battery level
- Sound
- Barometer Pressure
- External sensors
- Upload data to cloud
- Using the UHF (DragonLink) ability



**Launching the service:**

After pressing the “START” button a service with several threads will launch and start monitoring the environment until the back key will pressed by the user.

**Remote SMS control - TBA:**

Controlling the application will be available remotely from another device by using SMS messages using the preconfigured template and commands. The string that will be received on the ‘lab’, will be phrased and will execute the wanted commands remotely.

**SMS critical data monitoring:**

Critical data about the system such as GPS location and battery level will be sent to the preconfigured number that was entered by the user.

Backend access to Database:

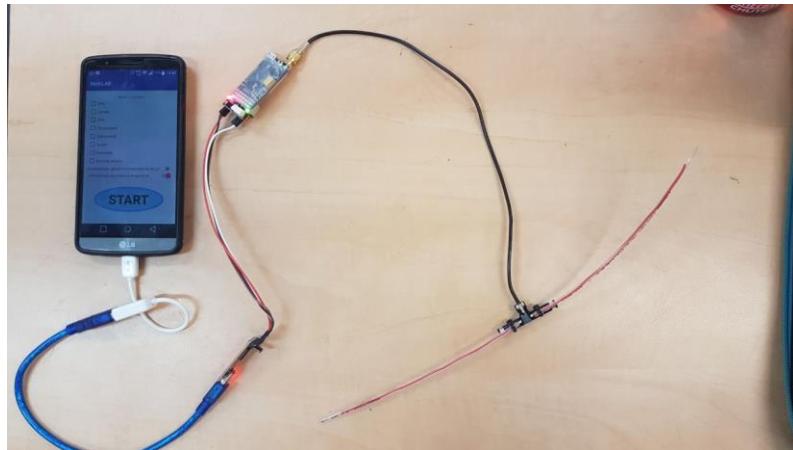
The app will be synced with the preconfigured private cloud and will upload the recorded information directly to it, whenever the signal affords it.

Frontend access to Database:

Every user will have a private web real-time updated dashboard that will show a graphic user interface with all of the data that received from the MobiLAB application.



UHF communication (DragonLink):



Application design:

Login Activity	Main Menu Activity	Main Activity
Sign in screen	main menu screen	application working screen
username	list of sensors:	gps location parameters
password	gps	camera preview box
connect button	camera	using the CameraPreview Object
create new account	sms	using the USBService Object
	temperature	relevant threads from main menu invoked
	battery level	
	sound	
	barometer	
	external sensors	
	launch service button	



Experiments:

19.1.16 Haifa bay balloon blow –

In this experiment, we used an Israeli SIM card, and communicate through 3G communication. We managed to receive photos from maximum altitude of ~4700.

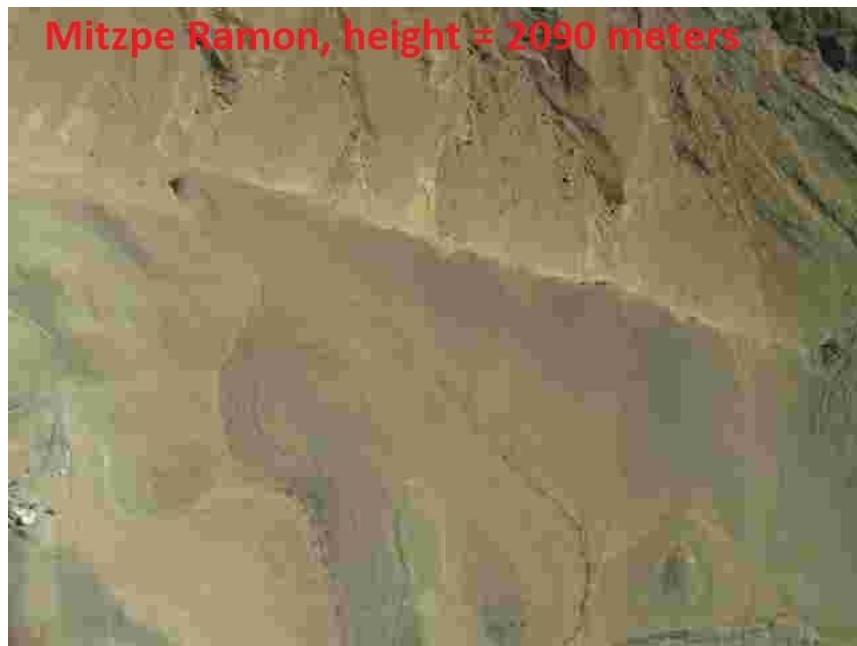
```
<sms protocol="0" address="+972542594032" date="1484819442679" type="SMS from 4618 meter !"  
20170119_115030|p=32.08782  
35.11471|al=4618|bt64.0|tm=25.3.jpg" toa="null"  
sc_toa="null" service_center="+97254120032" read="1"  
status="1" locked="0" date_sent="1484819443000"  
" readable_date="Jan 19, 2017 11:50:42 AM"
```

[YouTube Video](#)





6.2.17 Mizpe Ramon bay balloon blow –





6.6.17 Ariel bay balloon blow –

In this experience we failed, we used Jordan SIM card, we had problem, all the pictures were white and all the telemetry was the same...

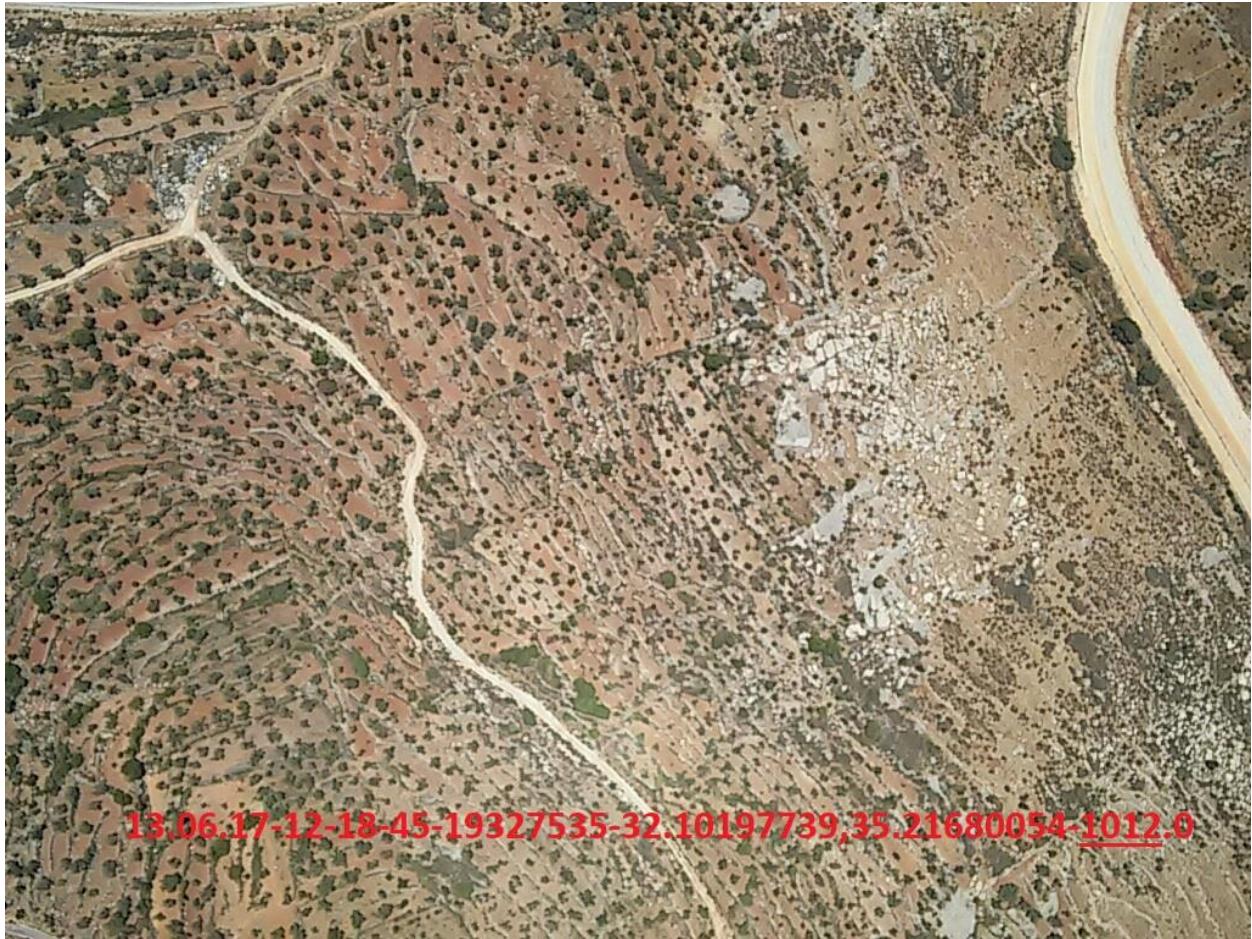




13.6.17 Ariel university balloon blow – we used with long WiFi signal to process the data, we got full telemetry until 1658 meter (1 kilometer rang):



ID	TIME	LatitudeLongitude	Altitude	Temperature	Battery	Barometer	EXT_Sensors	MODEL	AndroidId	num
101763630	13.06.17-12:21:53	32.09726646,35.22614143	1506.0	52.6	93.0	-1.0	0.0	LGE LG-D722	355403064309245	126544
40170488	13.06.17-12:22:03	32.09634229,35.22731127	1567.0	52.6	93.0	-1.0	0.0	LGE LG-D722	355403064309245	126545
58873232	13.06.17-12:22:13	32.09634229,35.22731127	1567.0	52.6	93.0	-1.0	0.0	LGE LG-D722	355403064309245	126546
34148608	13.06.17-12:22:23	32.09526765,35.22843129	1629.0	52.6	93.0	-1.0	0.0	LGE LG-D722	355403064309245	126547
43092854	13.06.17-12:22:33	32.09482621,35.22899521	1658.0	52.6	93.0	-1.0	0.0	LGE LG-D722	355403064309245	126548
43092854	13.06.17-12:22:33	32.09482621,35.22899521	1658.0	52.6	93.0	-1.0	0.0	LGE LG-D722	355403064309245	126549







5.7.17 Ariel university balloon blow – we used Israeli Sim card + added:

05.07.17-12_24_15_24559436_32.10427925,35.21708857_2188.0.jpg





05.07.17-12_27_05_91882699_32.11526637,35.22068283_2992.0.jpg





05.07.17-12_27_55_34403844_32.12085532,35.21962723_3359.0.jpg





MobiLAB logger – code examples:

In our project we used various of programming languages:

Client side:

- MobiLAB Android Application – written in JAVA
- MobiLAB dashboard web page – html, css and javascript.

Server side:

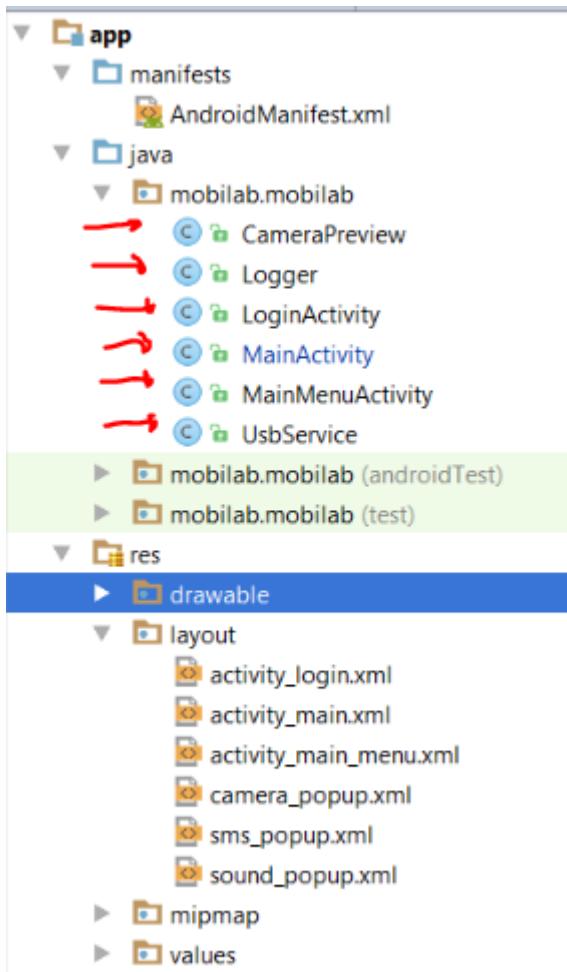
- PHP – read and write to the D.B (Post & Get HTTP requests)
- SQL – managing D.B for telemetry and pictures, queries for specific data (By users, pictures etc...)

We also created Linux machine to store the whole project



MobiLAB Android Application:

Here you can see the MobiLAB application classes:





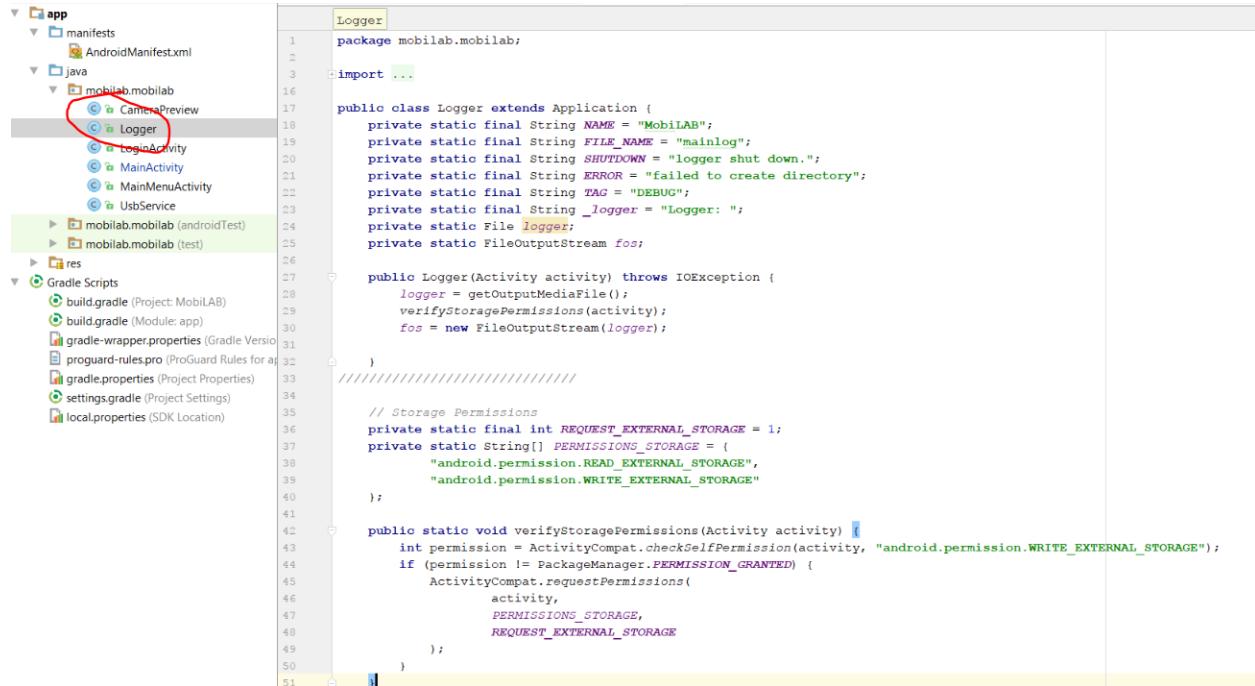
Android manifest file:

```
<manifest xmlns:android="http://schemas.android.com/apk/res/android"
    package="mobilab.mobilab">

    <!-- To auto-complete the email text field in the login form with the user's emails -->
    <uses-permission android:name="android.permission.GET_ACCOUNTS" />
    <uses-permission android:name="android.permission.READ_PROFILE" />
    <uses-permission android:name="android.permission.READ_CONTACTS" />
    <uses-permission android:name="android.permission.READ_EXTERNAL_STORAGE" />
    <uses-permission android:name="android.permission.WRITE_EXTERNAL_STORAGE" />
    <uses-permission android:name="android.permission.ACCESS_FINE_LOCATION" />
    <uses-permission android:name="android.permission.ACCESS_COARSE_LOCATION" />
    <uses-permission android:name="android.permission.SEND_SMS" />
    <uses-permission android:name="android.permission.READ_PHONE_STATE" />
    <uses-feature android:name="android.hardware.usb.host" android:required="true"/>

    <uses-feature android:name="android.hardware.camera" />
    <uses-permission android:name="android.permission.CAMERA" />
```

MobiLAB use **Logger** class to create a text file with all the telemetry data and the necessary actions performed on the mobile:



The screenshot shows the Android Studio interface with the project structure on the left and the code editor on the right.

Project Structure:

- app** folder:
 - manifests**: Contains `AndroidManifest.xml`.
 - java**: Contains the `mobilab.mobilab` package.
 - Logger**: The class file is highlighted and has a red circle around it.
 - CameraPreview**
 - LogActivity**
 - MainActivity**
 - MainMenuActivity**
 - UsbService**
 - res**
 - Gradle Scripts**: Contains `build.gradle`, `build.gradle (Module: app)`, and `gradle-wrapper.properties`.
 - local.properties** (SDK Location)



After the user choose what to monitor, MobiLAB use different thread for each sensor in order to sampling information from the sensors.

Cloud upload Thread:

```
////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////CloudUpload/////////
////////////////////////////////////////////////////////////////
com.android.volley.RequestQueue requestQueue;
private static String AndroidId;
String insertUrl = "http://evron.pro/mobilab/telemetry/insertData.php";
String MODEL = Build.MANUFACTURER + " " + Build.MODEL;

Handler uploadHandler = new Handler() {
    @Override
    public void handleMessage(Message msg) {
        // TODO: change 0.0 values to actual values
        dataId = createID();
        currentTime = new SimpleDateFormat("dd.MM.yy--HH:mm:ss").format(new Date());
        sendToServer(dataId, currentTime, latitude, longitude, altitude,
current_temperature, current_battery_level, barometerData, 0.0, MODEL, AndroidId);
    }
};
Runnable updateCloudRunnable = new Runnable() {
    @Override
    public void run() {
        {
            synchronized (this) {
                while (CloudSwitchData) {
                    try {
                        //wait(updateCloudInterval * 1000);
                        wait(10000); //10 sec
                        uploadHandler.sendEmptyMessage(0);
                    } catch (InterruptedException e) {
                        e.printStackTrace();
                        Logger.append(e.getMessage());
                    }
                }
            }
        }
    }
};

public void sendToServer(final String ID, final String TIME, final double latitude, final
double longitude, final double altitude, final float Temperature, final float Battery,
final double Barometer, final double EXT_Sensors, final String MODEL, final String
AndroidId) {
    StringRequest request = new StringRequest(Request.Method.POST, insertUrl,
        new Response.Listener<String>() {
            @Override
            public void onResponse(String response) {
                Logger.append("SERVER: " + response.toString());
            }
        }, new Response.ErrorListener() {

            @Override
            public void onErrorResponse(VolleyError error) {
                Logger.append("SERVER: " + error.getCause());
            }
        })
    {
        @Override
        protected Map<String, String> getParams() throws AuthFailureError {
    
```



```

        Map<String, String> parameters = new HashMap<String, String>();
        parameters.put("ID", dataId);
        parameters.put("TIME", TIME);
        parameters.put("LatitudeLongitude", String.valueOf(latitude) + "," +
String.valueOf(longitude));
        parameters.put("Altitude", String.valueOf(altitude));
        parameters.put("Temperature", String.valueOf(Temperature));
        parameters.put("Battery", String.valueOf(Battery));
        parameters.put("Barometer", String.valueOf(Barometer));
        parameters.put("EXT_Sensors", String.valueOf(EXT_Sensors));
        parameters.put("MODEL", MODEL);
        parameters.put("AndroidId", AndroidId);
        return parameters;
    }
};

Logger.append("cloud updated -> ID: " + ID + ";LatitudeLongitude: " + latitude + "," + longitude + ";Altitude: " + altitude + ";Temperature: " + Temperature + ";Battery: " + Battery + ";Barometer: " + Barometer + ";EXT_Sensors: " + EXT_Sensors);
requestQueue.add(request);
Toast.makeText(getApplicationContext(), "Location Sent !!", Toast.LENGTH_SHORT).show();

}

```

Automate Take Pic and upload to Server Thread:

```

///////////////////////////////TakePicThread/////
///////////////////////////////

android.os.Handler handler = new android.os.Handler() {
    @Override
    public void handleMessage(Message msg) {
        try {
            mCamera.startPreview(); //important! it allow to take multi pics!
            mCamera.takePicture(null, null, mPicture);

            //mCamera = getCameraInstance();
            //mCameraPreview = new CameraPreview(getApplicationContext(), mCamera);
            //final FrameLayout preview = (FrameLayout)
            findViewById(R.id.cameraPreview);
            //preview.addView(mCameraPreview);

        } catch (Exception e) {
            e.printStackTrace();
            Logger.append(e.getMessage());
        }
    }
};

Runnable takePicRunnable = new Runnable() {
    @Override
    public void run() {
        synchronized (this) {
            while (runPic) {
                try {
                    wait(PICTimeOut);
                    handler.sendEmptyMessage(0);
                } catch (InterruptedException e) {
                    e.printStackTrace();
                }
            }
        }
    }
};

```



```

        Logger.append(e.getMessage());
    }
}
}
};

/**
 * Helper method to access the camera returns null if it cannot get the
 * camera or does not exist
 *
 * @return
 */
private android.hardware.Camera getCameraInstance() {
    android.hardware.Camera camera = null;
    try {
        camera = android.hardware.Camera.open();
    } catch (Exception e) {
        Logger.append(e.getMessage());
        Logger.append("cannot access camera or does not exist");
    }
    return camera;
}

Camera.PictureCallback mPicture = new Camera.PictureCallback() {
    @Override
    public void onPictureTaken(byte[] data, Camera camera) {
        File pictureFile = getOutputMediaFile();
        if (pictureFile == null) {
            return;
        }
        try {
            FileOutputStream fos = new FileOutputStream(pictureFile);
            fos.write(data);
            Logger.append("picture taken: " + pictureFile.getName());
        } catch (FileNotFoundException e) {
            //This is very important!!!!
            //It return the view after taking photo!!!!!
            mCamera.startPreview();
        }
        fos.close();
        if (uploadCameraPic) {
            //Upload to server:
            UpdateNewBitMap(pictureFile.getPath());
            uploadImage();
        }
    }
    } catch (IOException e) {
        Logger.append("taking picture failed: " + e.getStackTrace());
        Logger.append(e.getMessage());
    }
};

private File getOutputMediaFile() {
    File mediaStorageDir = new

```



```

File(Environment.getExternalStoragePublicDirectory("MobiLAB"), "Pictures");
    if (!mediaStorageDir.exists()) {
        if (!mediaStorageDir.mkdirs()) {
            Logger.append("failed to create directory for saving pictures!");
            return null;
        }
    }
    // Create a media file name
    File mediaFile;
    mediaFile = new File(mediaStorageDir.getPath() + File.separator + getStringData() +
".jpg");
    Toast.makeText(getApplicationContext(), "new Pic created!", " + mediaFile.getName()
+ "Location: MobiLAB/Pictures", Toast.LENGTH_SHORT).show();
    Logger.append("New Pic: " + getStringData() + ".jpg");
    return mediaFile;
}

public void UpdateNewBitMap(String path) {
    try {
        picPath = path;
        File f = new File(picPath);
        Uri imageUri = Uri.fromFile(f);
        bitmap = MediaStore.Images.Media.getBitmap(getContentResolver(), imageUri);
    } catch (IOException e) {
        e.printStackTrace();
        Logger.append(e.getMessage());
    }
}

private void uploadImage() {
    //Showing the progress dialog
    final ProgressDialog loading = ProgressDialog.show(this, "Uploading...", "Please
wait...", false, false);
    StringRequest stringRequest = new StringRequest(Request.Method.POST, UPLOAD_URL,
        new Response.Listener<String>() {
            @Override
            public void onResponse(String s) {
                //Dismissing the progress dialog
                loading.dismiss();
                //Showing toast message of the response
                Toast.makeText(MainActivity.this, s, Toast.LENGTH_SHORT).show();
            }
        },
        new Response.ErrorListener() {
            @Override
            public void onErrorResponse(VolleyError volleyError) {
                //Dismissing the progress dialog
                loading.dismiss();

                //Showing toast
                Toast.makeText(MainActivity.this, "Cant upload pic!",
Toast.LENGTH_SHORT).show();
            }
        })
    {
        @Override
        protected Map<String, String> getParams() throws AuthFailureError {
            //Converting Bitmap to String
            String image = getStringImage(bitmap);
            //Getting Image Name

            String name = getNewPicName().trim();

            //Creating parameters
            Map<String, String> params = new Hashtable<String, String>();

            //Adding parameters
        }
    };
}

```



```

        params.put("ID", dataId);
        params.put(KEY_IMAGE, image);
        params.put(KEY_NAME, name);

        //returning parameters
        return params;
    }
};

//Creating a Request Queue
RequestQueue requestQueue = Volley.newRequestQueue(this);

//Adding request to the queue
requestQueue.add(stringRequest);

}

public String getStringImage(Bitmap bmp) {
    ByteArrayOutputStream baos = new ByteArrayOutputStream();
    bmp.compress(Bitmap.CompressFormat.JPEG, compressQuality, baos);
    byte[] imageBytes = baos.toByteArray();
    String encodedImage = Base64.encodeToString(imageBytes, Base64.DEFAULT);
    return encodedImage;
}

public String getNewPicName() {
    currentTime = new SimpleDateFormat("dd.MM.yy-HH:mm:ss").format(new Date());
    if (CloudSwitchData == false) {
        dataId = createID();
    }
    String picName = currentTime + " | " + dataId + " | " + latitude + "," + longitude +
    " | " + altitude + ".jpg";
    Logger.append("picName= " + picName);
    return picName;
}

```

Automate Take SMS Thread:

```

///////////////////////////////TakeSMSThread////////
///////////////////////////////TakeSMSThread////////

Handler handlerSMS = new Handler() {
    @Override
    public void handleMessage(Message msg) {
        sendSms();
    }
};

Runnable runnableSMS = new Runnable() {
    @Override
    public void run() {
        //while(true)
        {
            synchronized (this) {
                while (sendSMS) {
                    try {
                        wait(SMSTimeOut);
                        handlerSMS.sendEmptyMessage(0);
                    } catch (InterruptedException e) {
                        e.printStackTrace();
                        Logger.append(e.getMessage());
                    }
                }
            }
        }
    }
};

```



```

        }
    }

}

};

public void sendSms() {
    SmsManager smsManager = SmsManager.getDefault();
    String SmsData = getStringData();
    smsManager.sendTextMessage(destinationNumber, null, SmsData, null, null);

    Logger.append("SMS sent to: " + destinationNumber + " Data sent = " + SmsData);
    Toast.makeText(getApplicationContext(), "SMS set to: " + destinationNumber,
    Toast.LENGTH_SHORT).show();
}

```

Battery and Temperature Thread:

```

//////////////////////////////BATTERY and
TEMPERATURE Thread////////////////////

private void batteryAndTemperatureSample() {
    Intent batteryIntent = registerReceiver(null, new
IntentFilter(Intent.ACTION_BATTERY_CHANGED));
    int level = batteryIntent.getIntExtra(BatteryManager.EXTRA_LEVEL, -1);
    int scale = batteryIntent.getIntExtra(BatteryManager.EXTRA_SCALE, -1);
    current_temperature = ((float)
batteryIntent.getIntExtra(BatteryManager.EXTRA_TEMPERATURE, 0) / 10);
    // Error checking that probably isn't needed but I added just in case.
    if (level == -1 || scale == -1) {
        current_battery_level = 50.0f;
    }
    current_battery_level = ((float) level / (float) scale) * 100.0f;
    Logger.append("current battery level -> " + current_battery_level);
    Logger.append("current temperature -> " + current_temperature);
}

Runnable runnableBT = new Runnable() {
    @Override
    public void run() {
        {
            synchronized (this) {
                while (_battery || _temperature) {
                    try {
                        wait(BAT_TEMP_INTERVAL * 1000);
                        batteryAndTemperatureSample();

                    } catch (InterruptedException e) {
                        e.printStackTrace();
                        Logger.append(e.getMessage());
                    }
                }
            }
        }
    }
};

```



Barometer Thread:

```
///////////////////////////////Barometric
Thread///////////////////////////////
Handler HandlerBarometric = new Handler() {
    @Override
    public void handleMessage(Message msg) {
        SensorManager sensorManager = (SensorManager)
getSystemService(Service.SENSOR_SERVICE);
        final Sensor pS = sensorManager.getDefaultSensor(Sensor.TYPE_PRESSURE);
        if (pS == null) {
            barometerData = -1;
        } else {
            barometerData = pS.getPower();
        }
        Logger.append("Barometer Pressure:= " + barometerData);
    }
};

Runnable runnableBarometric = new Runnable() {
    @Override
    public void run() {
        synchronized (this) {
            while (barometerOn) {
                try {
                    wait(barometerTimeOut * 1000);
                    HandlerBarometric.sendEmptyMessage(0);
                } catch (InterruptedException e) {
                    e.printStackTrace();
                    Logger.append(e.getMessage());
                }
            }
        }
    }
};
```

Dragon Link Thread:

```
/////////////////////////////Dragon Link Thread
/////////////////////////////
android.os.Handler DragonHandler = new android.os.Handler() {
    @Override
    public void handleMessage(Message msg) {
        try {
            if (UsbService.class != null) { // if UsbService was correctly binded, Send
data
                UsbService.write((getStringDataShort() + "---").getBytes());
            }
        } catch (Exception e) {
            e.printStackTrace();
            Logger.append(e.getMessage());
        }
    }
};
```



```
Runnable sendToDragonMsg = new Runnable() {
    @Override
    public void run() {
        {
            synchronized (this) {
                while (true) {
                    try {
                        wait(2000);
                        DragonHandler.sendEmptyMessage(0);
                    } catch (InterruptedException e) {
                        e.printStackTrace();
                        Logger.append(e.getMessage());
                    }
                }
            }
        };
    }
};
```



UsbService Class:

```

import ...

public class UsbService extends Service {

    public static final String ACTION_USB_READY = "com.felhr.connectivityservices.USB_READY";
    public static final String ACTION_USB_ATTACHED = "android.hardware.usb.action.USB_DEVICE_ATTACHED";
    public static final String ACTION_USB_DETACHED = "android.hardware.usb.action.USB_DEVICE_DETACHED";
    public static final String ACTION_USB_NOT_SUPPORTED = "com.felhr.usbservice.USB_NOT_SUPPORTED";
    public static final String ACTION_NO_USB = "com.felhr.usbservice.NO_USB";
    public static final String ACTION_USB_PERMISSION_GRANTED = "com.felhr.usbservice.USB_PERMISSION_GRANTED";
    public static final String ACTION_USB_PERMISSION_NOT_GRANTED = "com.felhr.usbservice.USB_PERMISSION_NOT_GRANTED";
    public static final String ACTION_USB_DISCONNECTED = "com.felhr.usbservice.USB_DISCONNECTED";
    public static final String ACTION_CDC_DRIVER_NOT_WORKING = "com.felhr.connectivityservices.ACTION_CDC_DRIVER_NOT_WORKING";
    public static final String ACTION_USB_DEVICE_NOT_WORKING = "com.felhr.connectivityservices.ACTION_USB_DEVICE_NOT_WORKING";
    public static final int MESSAGE_FROM_SERIAL_PORT = 0;
    private static final String ACTION_USB_PERMISSION = "com.android.example.USB_PERMISSION";
    //private static final int BAUD_RATE = 9600; // BaudRate. Change this value if you need
    private static final int BAUD_RATE = 4800; // BaudRate. Change this value if you need
    public static boolean SERVICE_CONNECTED = false;

    private IBinder binder = new UsbBinder();

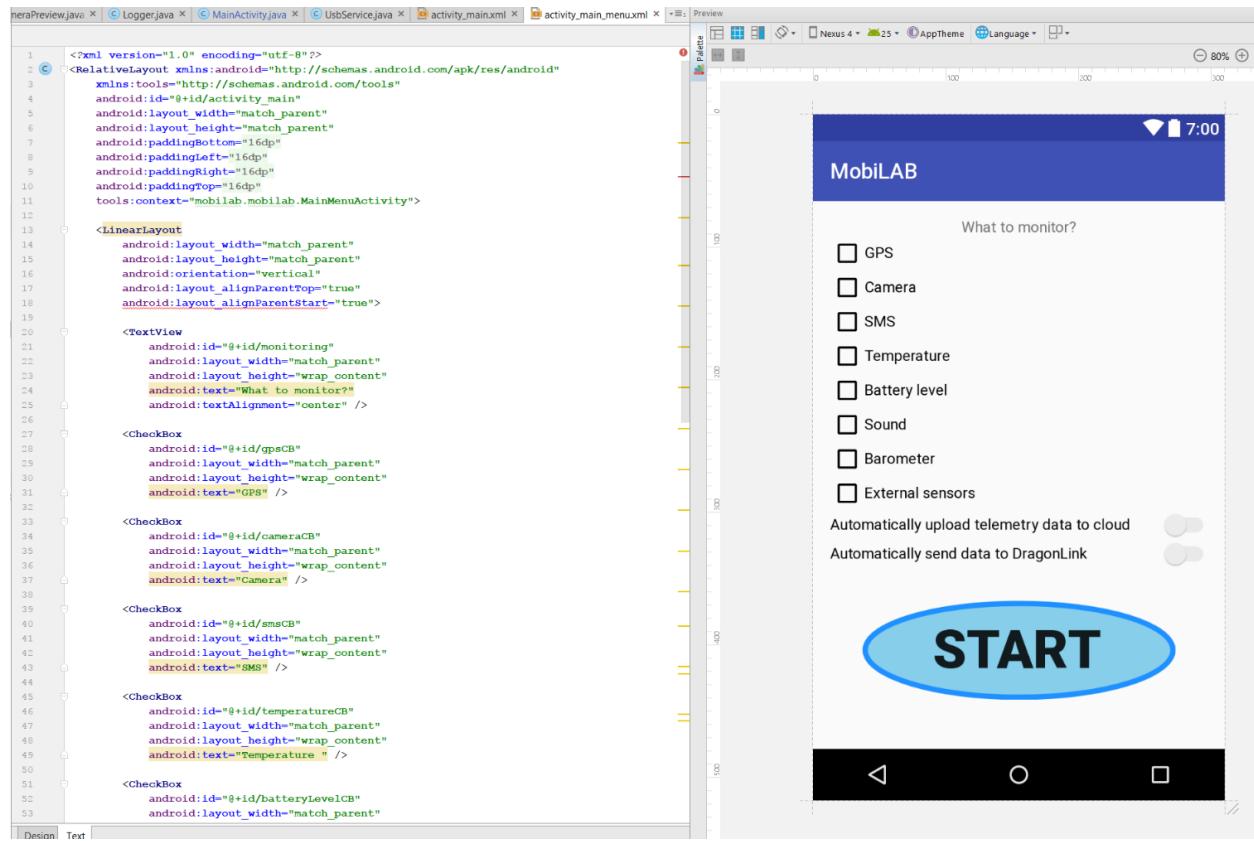
    private Context context;
    private Handler mHandler;
    private UsbManager usbManager;
    private UsbDevice device;
    private UsbDeviceConnection connection;
    private static UsbSerialDevice serialPort;

    private boolean serialPortConnected;
    /*
     * Data received from serial port will be received here. Just populate onReceivedData with your code
     * In this particular example, byte stream is converted to String and send to UI thread to
     * be treated there.
     */
    private UsbSerialInterface.UsbReadCallback mCallback = (arg0) -> {
        try {
            String data = new String(arg0, "UTF-8");
            if (mHandler != null)
                mHandler.obtainMessage(MESSAGE_FROM_SERIAL_PORT, data).sendToTarget();
        } catch (UnsupportedEncodingException e) {
            e.printStackTrace();
            Logger.append(e.getMessage());
        }
    };
    /*
     * Different notifications from OS will be received here (USB attached, detached, permission responses...)
     * About BroadcastReceiver: http://developer.android.com/reference/android/content/BroadcastReceiver.html
     */
    private final BroadcastReceiver usbReceiver = (arg0, arg1) -> {
        if (arg1.getAction().equals(ACTION_USB_PERMISSION)) {
            boolean granted = arg1.getExtras().getBoolean(UsbManager.EXTRA_PERMISSION_GRANTED);
        }
    };
}

```



Example of our XML files:



The screenshot shows the Android Studio interface with the XML code for `activity_main.xml` on the left and a design preview on the right.

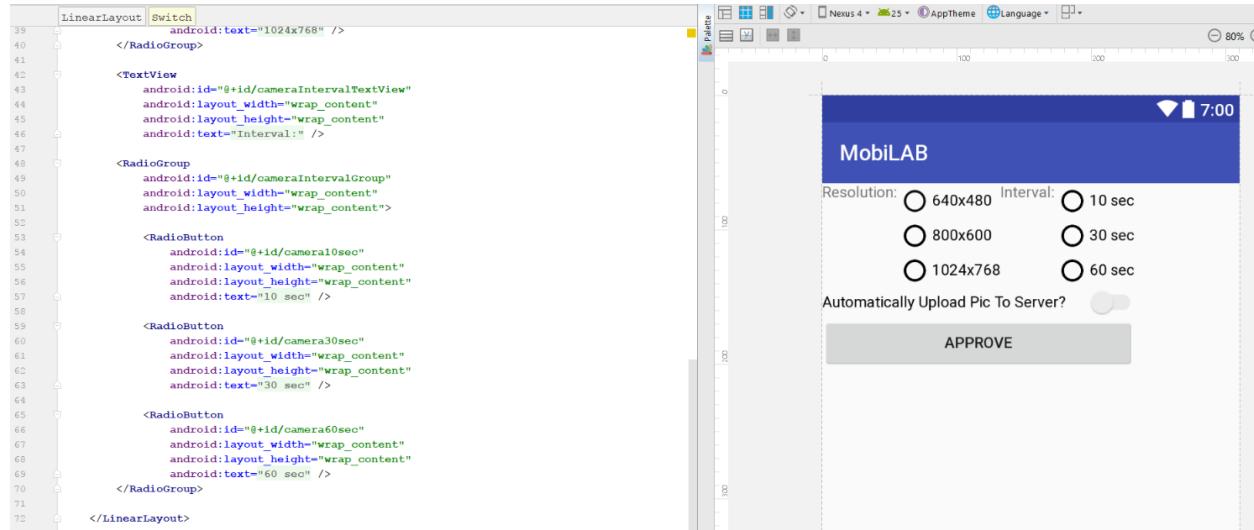
```

1 <?xml version="1.0" encoding="utf-8"?>
2 <RelativeLayout xmlns:android="http://schemas.android.com/apk/res/android"
3     xmlns:tools="http://schemas.android.com/tools"
4     android:id="@+id/activity_main"
5     android:layout_width="match_parent"
6     android:layout_height="match_parent"
7     android:paddingBottom="16dp"
8     android:paddingLeft="16dp"
9     android:paddingRight="16dp"
10    android:paddingTop="16dp"
11    tools:context="mobilab.mobilab.MainActivity">
12
13    <LinearLayout
14        android:layout_width="match_parent"
15        android:layout_height="match_parent"
16        android:orientation="vertical"
17        android:layout_alignParentTop="true"
18        android:layout_alignParentStart="true">
19
20        <TextView
21            android:id="@+id/monitoring"
22            android:layout_width="match_parent"
23            android:layout_height="wrap_content"
24            android:text="What to monitor?"
25            android:textAlignment="center" />
26
27        <CheckBox
28            android:id="@+id/gpsCB"
29            android:layout_width="match_parent"
30            android:layout_height="wrap_content"
31            android:text="GPS" />
32
33        <CheckBox
34            android:id="@+id/cameraCB"
35            android:layout_width="match_parent"
36            android:layout_height="wrap_content"
37            android:text="Camera" />
38
39        <CheckBox
40            android:id="@+id/smsCB"
41            android:layout_width="match_parent"
42            android:layout_height="wrap_content"
43            android:text="SMS" />
44
45        <CheckBox
46            android:id="@+id/temperatureCB"
47            android:layout_width="match_parent"
48            android:layout_height="wrap_content"
49            android:text="Temperature" />
50
51        <CheckBox
52            android:id="@+id/batteryLevelCB"
53            android:layout_width="match_parent" />

```

The design preview shows a blue header bar with the text "MobiLAB". Below it is a section titled "What to monitor?" containing a text view and five checkboxes. At the bottom is a large blue oval button labeled "START". There are also two toggle switches for "Automatically upload telemetry data to cloud" and "Automatically send data to DragonLink".

Linear Layout (Camera):



The screenshot shows the Android Studio interface with the XML code for a camera configuration screen on the left and a design preview on the right.

```

39 <LinearLayout | Switch
40     <RadioGroup > android:text="1024x768" />
41
42     <Text View
43         android:id="@+id/cameraIntervalTextView"
44         android:layout_width="wrap_content"
45         android:layout_height="wrap_content"
46         android:text="Interval:" />
47
48     <Radio Group
49         android:id="@+id/cameraIntervalGroup"
50         android:layout_width="wrap_content"
51         android:layout_height="wrap_content">
52
53         <RadioButton
54             android:id="@+id/camera10sec"
55             android:layout_width="wrap_content"
56             android:layout_height="wrap_content"
57             android:text="10 sec" />
58
59         <RadioButton
60             android:id="@+id/camera30sec"
61             android:layout_width="wrap_content"
62             android:layout_height="wrap_content"
63             android:text="30 sec" />
64
65         <RadioButton
66             android:id="@+id/camera60sec"
67             android:layout_width="wrap_content"
68             android:layout_height="wrap_content"
69             android:text="60 sec" />
70
71     </Radio Group>
72
73 </Linear Layout>

```

The design preview shows a blue header bar with the text "MobiLAB". Below it is a section titled "Resolution" with three radio buttons for "640x480", "800x600", and "1024x768". Next to each resolution is a radio button for "Interval" with options "10 sec", "30 sec", and "60 sec". There is also a toggle switch for "Automatically Upload Pic To Server" and a large grey button labeled "APPROVE".



Linear Layout (SMS):

```

<LinearLayout>
    <EditText
        android:id="@+id/telNo"
        android:layout_width="wrap_content"
        android:layout_height="wrap_content"
        android:hint="Telephone Number" />
        android:hint="@string/telNo" />
    <TextView
        android:layout_width="wrap_content"
        android:layout_height="wrap_content"
        android:text="Interval:" />
    <RadioGroup
        android:id="@+id/smsIntervalGroup"
        android:layout_width="wrap_content"
        android:layout_height="wrap_content">
        <RadioButton
            android:id="@+id/sms10sec"
            android:layout_width="wrap_content"
            android:layout_height="wrap_content"
            android:text="10 sec" />
        <RadioButton
            android:id="@+id/sms30sec"
            android:layout_width="wrap_content"
            android:layout_height="wrap_content" />
    </RadioGroup>

```

Linear Layout (Sound recording):

```

<RadioGroup
    android:id="@+id/durationGroup"
    android:layout_width="wrap_content"
    android:layout_height="wrap_content">
    <RadioButton
        android:id="@+id/duration30sec"
        android:layout_width="wrap_content"
        android:layout_height="wrap_content"
        android:text="30 sec" />
    <RadioButton
        android:id="@+id/duration60sec"
        android:layout_width="wrap_content"
        android:layout_height="wrap_content"
        android:text="60 sec" />
    <RadioButton
        android:id="@+id/duration120sec"
        android:layout_width="wrap_content"
        android:layout_height="wrap_content"
        android:text="120 sec" />
</RadioGroup>
<Textview
    android:layout_width="wrap_content"
    android:layout_height="wrap_content"
    android:text="Interval:" />
<RadioGroup
    android:id="@+id/soundIntervalGroup"
    android:layout_width="wrap_content"
    android:layout_height="wrap_content">
    <RadioButton
        android:id="@+id/duration30sec"
        android:layout_width="wrap_content"
        android:layout_height="wrap_content"
        android:text="30 sec" />
    <RadioButton
        android:id="@+id/duration60sec"
        android:layout_width="wrap_content"
        android:layout_height="wrap_content" />

```



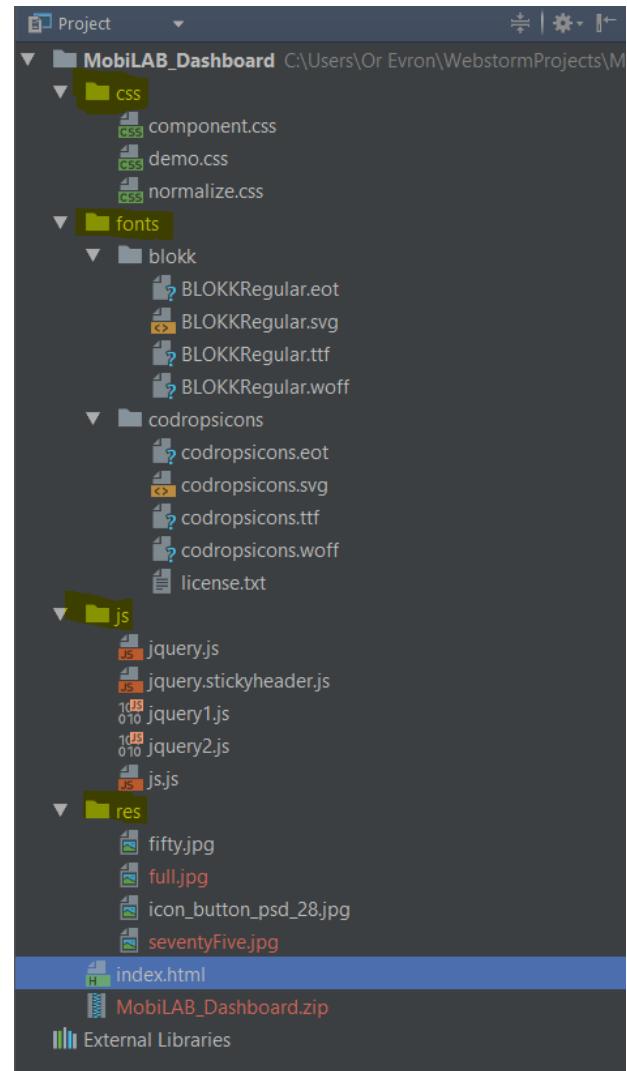
MobiLAB web page – html, css and javascripts:

We created our website dashboard with the help of a free dashboard template service called **Admin LTE**, we adopted the dashboard tools we needed in order to create our dashboard and customized it to fit our data.

This is the Dashboard project tree:

Where you can find the css's fonts and javascripts that behind the visualization of our dashboard.

Also you can see the js.js file and the index.html file which holds the customization of the template to our needs





This is part of the js.js file that communicate with the sql server via php files and receive json files as response, with those json files that represent the response query we are drawing the table on the web dashboard.

```

/**
 * Created by Or Evron on 5/30/2017.
 */
const telemetryUrl = "http://evron.pro/mobilab/queries/telemetry-json.php",
      picsUrl = "http://evron.pro/mobilab/queries/telemetryPics-json.php",
      devicesUrl = "http://evron.pro/mobilab/queries/telemetry-devices.php";

function drawDB(tableName) {...}

function getJson1(tableName) {
  var $table = $(".myTable1");
  $table.html("");
  if (tableName === "Telemetry DB") {
    $.getJSON(telemetryUrl, {}, function (json) {...});
  }
  else if (tableName === "Pics DB") {
    $.getJSON(picsUrl, {}, function (json) {...});
  }
  else if (tableName === "") {
    tableName = "Telemetry ID's: ";
    $.getJSON(devicesUrl, {}, function (json) {...});
  }
}

function drawTable1(json, $table, tableName) {...}

function getTableHeader1(json, $table, tableName) {
  var $header1 = $("<thead></thead>");
  var $header = $("<tr></tr>");
  $.each(json[tableName][0], function (item) {
    $header.append($("<th></th>").text(item));
  });
  $header1.append($header);
  $table.append($header1);
  $table.append("<tbody>");
  getTable1(json, $table, tableName);
}

function getTable1(json, $table, tableName) {
  json[tableName].forEach(function (item) {
    getTableData1(item, $table, tableName);
  });
  $table.append("</tbody>");
}

function getTableData1(item, $table, tableName) {...}

```



PHP – read and write for the D.B (Post & Get HTTP requests):

With PHP script files that stored on our server we are querying the sql server and insert data into it, both the mobile and the web using those scripts, one to upload files and the other to retrieve information.

This is our connection script to first connect into the sql server:

```
<?php
header('Access-Control-Allow-Origin: *');
define('hostname', 'localhost');
define('user', 'root');
define('password', 'gohabibi123');
define('databaseName', 'mobilabdb');
$connect = mysqli_connect(hostname,user,password,databaseName);
?>
```

This script establish connection into the sql (using the previous script) and then querying the database to get all the telemetry information:

```
<?php
include 'connection.php';
run();

function run(){
    global $connect;
    $query = " Select * FROM telemetry; ";
    $result = mysqli_query($connect, $query);
    $number_of_rows = mysqli_num_rows($result);
    $temp_array = array();
    if($number_of_rows > 0) {
        while ($row = mysqli_fetch_assoc($result)) {
            $temp_array[] = $row;
        }
    }
    header ('Content-Type: application/json');
    echo json_encode(array("Telemetry DB"=>$temp_array));
    mysqli_close($connect);
}
?>
```



The Server – Manage High availability Server alongside support the android application:

Picking the best storage services wasn't that easy, as we wanted to keep our services free of charge, we also needed to find the best **free** but yet highly available storage service, which will give us a web server including database server and php installed on to communicate between all those components.

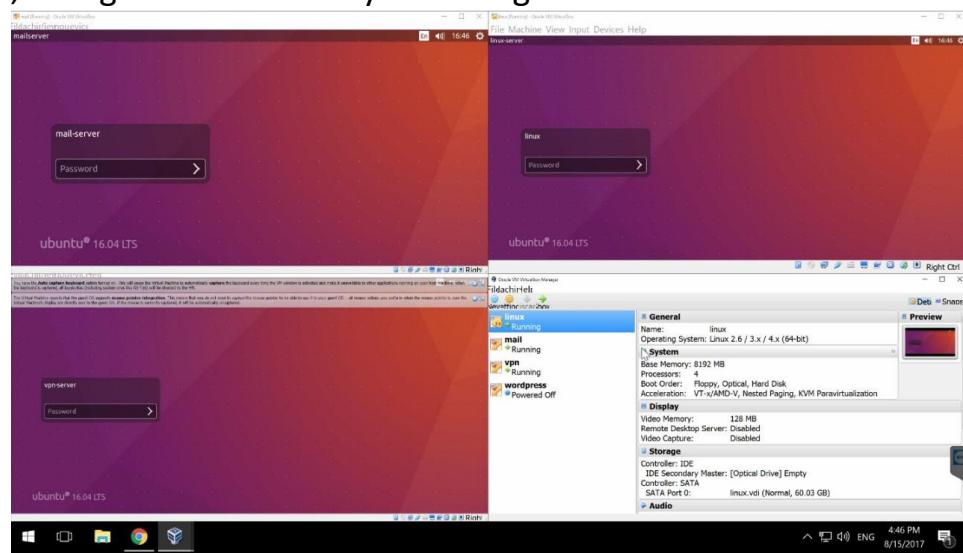
Our first choice was the site 000webhost which seem to answer all of our needs, but overall with a lot of experiments and days of testing, we found their service **NOT** highly available at all.

We needed another solution so we decided to take it in and serve the files on our own site.

We built a dedicated machine with a suitable hardware and configure all the configuration that needs to be done including:

- Set a static IP on our internet provider
- Buying a domain for our dashboard
- Route all traffic to its destination (VM on the dedicated machine)
- Finally built the VM's to listen to the traffic and serve our dashboard to the outside world

In order to keep our site secured as much as possible we also created a VPN machine in our site, that gives us the ability to manage users that can access our backend.





ARIEL UNIVERSITY / Department of Computer Science and Mathematics

MOBILAB

MobiLAB is an Android Application that will monitor, record and communicate with all of your android sensors in one place.

Mobilab architecture

BackEnd

```

graph TD
    Sensors[HC-SR04, SEN13685B, BMP180] -- USB --> arduino[arduino]
    arduino -- USB --> smartphone[Smartphone]
    smartphone -- POST request --> Backend[Backend]
    Backend -- SMS --> Smartphone
    Backend -- "Cloud" --> Cloud[Cloud]
    Cloud -- "Data" --> Database[Database]
    
```

The diagram illustrates the Mobilab architecture. It starts with three sensors (HC-SR04, SEN13685B, BMP180) connected via USB to an Arduino board. The Arduino is connected via USB to a smartphone. The smartphone sends a POST request to the Backend (which includes MySQL databases). The Backend also receives SMS messages and connects to a cloud. The cloud then sends data to a database.

The Technology

The technology MobilAB offers can get the market to developing new autonomous vehicles with new abilities that never seen up to today, and also improvement of existing systems on existing autonomous vehicles that not can do mobile lab systems such as describe above.

The mobile device will be the main control center for the system. The first will be the system UI Application for an Android devices which will give the user controlling abilities on the lab settings.

And the second will be an Android Service which will run on the background of the phone device and will be the main ability to record data from the sensors, gather important information, analyze it and send the data to the ground and cloud control stations.

The Need

During the process of investigating helpful technologies to develop vehicles, we found that there is a real need in a stand alone system that hold the ability to gather and process real-time location and telemetry that connected to it, such as GPS, microphone, barometer, GPS location, temperature, pictures etc... The ability to process this information and send it to the ground on real-time parallel to send the information to the cloud control service and of course save this information on local storage, give to the autonomous vehicle and specifically UAV's new strong and important abilities.

our web site -> <http://mobilab.ariel.ac.il>

MobiLAB DB

Table	Column	Type	Length	Default	Notes
Pics	id	int	11	0	
Pics	file	blob	1000000		
Pics	date	date	10	0000-00-00	
Pics	name	varchar	50		
Pics	ext	varchar	10		
Pics	size	float	10	0.00	
Pics	path	text	1000		
Telemetry	id	int	11	0	
Telemetry	date	date	10	0000-00-00	
Telemetry	lat	float	10	0.0000000000	
Telemetry	lon	float	10	0.0000000000	
Telemetry	alt	float	10	0.0000000000	
Telemetry	temp	float	10	0.0000000000	
Telemetry	hum	float	10	0.0000000000	
Telemetry	pres	float	10	0.0000000000	
Telemetry	acc_x	float	10	0.0000000000	
Telemetry	acc_y	float	10	0.0000000000	
Telemetry	acc_z	float	10	0.0000000000	
Telemetry	gyro_x	float	10	0.0000000000	
Telemetry	gyro_y	float	10	0.0000000000	
Telemetry	gyro_z	float	10	0.0000000000	
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Telemetry	mag_y	float	10	0.0000000000	
Telemetry	mag_z	float	10	0.0000000000	
Telemetry	light	float	10	0.0000000000	
Telemetry	prox	float	10	0.0000000000	
Telemetry	temp	float	10	0.0000000000	
Telemetry	hum	float	10	0.0000000000	
Telemetry	pres	float	10	0.0000000000	
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Telemetry	acc_y	float	10	0.0000000000	
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Telemetry	gyro_y	float	10	0.0000000000	
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Telemetry	pres	float	10	0.0000000000	
Telemetry	acc_x	float	10	0.0000000000	
Telemetry	acc_y	float	10	0.0000000000	
Telemetry	acc_z	float	10	0.0000000000	
Telemetry	gyro_x	float	10	0.0000000000	
Telemetry	gyro_y	float	10	0.0000000000	
Telemetry	gyro_z	float	10	0.0000000000	
Telemetry	mag_x	float	10	0.0000000000	
Telemetry	mag_y	float	10	0.0000000000	
Telemetry	mag_z	float	10	0.0000000000	
Telemetry	light	float	10	0.0000000000	
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Telemetry	temp	float	10	0.0000000000	
Telemetry	hum	float	10	0.0000000000	
Telemetry	pres	float	10	0.0000000000	
Telemetry	acc_x	float	10	0.0000000000	
Telemetry	acc_y	float	10	0.0000000000	
Telemetry	acc_z	float	10	0.0000000000	
Telemetry	gyro_x	float	10	0.0000000000	
Telemetry	gyro_y	float	10	0.0000000000	
Telemetry	gyro_z	float	10	0.0000000000	
Telemetry	mag_x	float	10	0.0000000000	
Telemetry	mag_y	float	10	0.0000000000	
Telemetry	mag_z	float	10	0.0000000000	
Telemetry	light	float	10	0.0000000000	
Telemetry	prox	float	10	0.0000000000	
Telemetry	temp	float	10	0.0000000000	
Telemetry	hum	float	10	0.0000000000	
Telemetry	pres	float	10	0.0000000000	
Telemetry	acc_x	float	10	0.0000000000	
Telemetry	acc_y	float	10	0.0000000000	
Telemetry	acc_z	float	10	0.0000000000	
Telemetry	gyro_x	float	10	0.0000000000	
Telemetry	gyro_y	float	10	0.0000000000	
Telemetry	gyro_z	float	10	0.0000000000	
Telemetry	mag_x	float	10	0.0000000000	
Telemetry	mag_y	float	10	0.0000000000	
Telemetry	mag_z	float	10	0.0000000000	
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Telemetry	temp	float	10	0.0000000000	
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Telemetry	acc_y	float	10	0.0000000000	
Telemetry	acc_z	float	10	0.0000000000	
Telemetry	gyro_x	float	10	0.0000000000	
Telemetry	gyro_y	float	10	0.0000000000	
Telemetry	gyro_z	float	10	0.0000000000	
Telemetry	mag_x	float	10	0.0000000000	
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Telemetry	acc_x	float	10	0.0000000000	
Telemetry	acc_y	float	10	0.0000000000	
Telemetry	acc_z	float	10	0.0000000000	
Telemetry	gyro_x	float	10	0.0000000000	
Telemetry	gyro_y	float	10	0.0000000000	
Telemetry	gyro_z	float	10	0.0000000000	
Telemetry	mag_x	float	10	0.0000000000	
Telemetry	mag_y	float	10	0.0000000000	
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Telemetry	acc_y	float	10	0.0000000000	
Telemetry	acc_z	float	10	0.0000000000	
Telemetry	gyro_x	float	10	0.0000000000	
Telemetry	gyro_y	float	10	0.0000000000	
Telemetry	gyro_z	float	10	0.0000000000	
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Telemetry	mag_y	float	10	0.0000000000	
Telemetry	mag_z	float	10	0.0000000000	
Telemetry	light	float	10	0.0000000000	
Telemetry	prox	float	10	0.0000000000	
Telemetry	temp	float	10	0.0000000000	
Telemetry	hum	float	10	0.0000000000	
Telemetry	pres	float	10	0.0000000000	
Telemetry	acc_x	float	10	0.0000000000	
Telemetry	acc_y	float	10	0.0000000000	
Telemetry	acc_z	float	10	0.0000000000	
Telemetry	gyro_x	float	10	0.0000000000	
Telemetry	gyro_y	float	10	0.0000000000	
Telemetry	gyro_z	float	10	0.0000000000	
Telemetry	mag_x	float	10	0.0000000000	
Telemetry	mag_y	float	10	0.0000000000	
Telemetry	mag_z	float	10	0.0000000000	
Telemetry	light	float	10	0.0000000000	
Telemetry	prox	float	10	0.0000000000	
Telemetry	temp	float	10	0.0000000000	
Telemetry	hum	float	10	0.0000000000	
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Telemetry	acc_y	float	10	0.0000000000	
Telemetry	acc_z	float	10	0.0000000000	
Telemetry	gyro_x	float	10	0.0000000000	
Telemetry	gyro_y	float	10	0.0000000000	
Telemetry	gyro_z	float	10	0.0000000000	
Telemetry	mag_x	float	10	0.0000000000	
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Telemetry	prox	float	10	0.0000000000	
Telemetry	temp	float	10	0.0000000000	
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Telemetry	pres	float	10	0.0000000000	
Telemetry	acc_x	float	10	0.0000000000	
Telemetry	acc_y	float	10	0.0000000000	
Telemetry	acc_z	float	10	0.0000000000	
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Telemetry	gyro_y	float	10	0.0000000000	
Telemetry	gyro_z	float	10	0.0000000000	
Telemetry	mag_x	float	10	0.0000000000	
Telemetry	mag_y	float	10	0.0000000000	
Telemetry	mag_z	float	10	0.0000000000	
Telemetry	light	float	10	0.0000000000	
Telemetry	prox	float	10	0.0000000000	
Telemetry	temp	float	10	0.0000000000	
Telemetry	hum	float	10	0.0000000000	
Telemetry	pres	float	10	0.0000000000	
Telemetry	acc_x	float	10	0.0000000000	
Telemetry	acc_y	float	10	0.0000000000	
Telemetry	acc_z	float	10	0.0000000000	
Telemetry	gyro_x	float	10	0.0000000000	
Telemetry	gyro_y	float	10	0.0000000000	