

Data
Assimilation
Research
Testbed



DART Tutorial Section 16: Diagnostic Output



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UCAR | Atmospheric Research

This tutorial section has not yet been updated for the Manhattan release of DART.

A new version is expected in April 2017.

DART Diagnostic Output Categories:

- State-Space:
Values of model's state vector and inflation.
Output using netCDF format.
- Observation-Space:
Values of the observations.
DART-specific *obs_sequence* format for now.
- Regression confidence factor:
Values for state vector / observation pairs.
Output as flat ASCII (soon to be netCDF).
- Program diagnostic output:
Identification for source code version and namelist values.
Error, warning, message output from modules.

State-Space Diagnostic Files:

Available in netCDF (a common data format)

<http://www.unidata.ucar.edu/software/netcdf>

1. Prior state (Prior_Diag.nc) : state before assimilation.
2. Posterior state (Posterior_Diag.nc) : state after assimilation.
3. Truth (True_State.nc) : truth for OSSEs.

Contents of prior and posterior controlled by *filter_nml*:

1. output_state_ens_mean = .true. (include ensemble mean);
2. output_state_ens_spread = .true. (include ensemble spread);
3. num_output_state_members = ## (include this many of the individual ensemble members)
4. output_interval = N (only output every N^{th} assimilation time)

Note: output_interval for True_State.nc is in the *perfect_model_obs_nml* namelist.

DART State-Space Diagnostic functions

See the DART website section titled: “Configuring Matlab to work with DART”
www.image.ucar.edu/DAReS/DART/DART_Documentation.php#configure_matlab

ALL the DART Matlab state-space diagnostic functions are in `<dart>/matlab`
This **must** be in your *matlabpath*.

Only focus on the functions/scripts that start with *plot_*

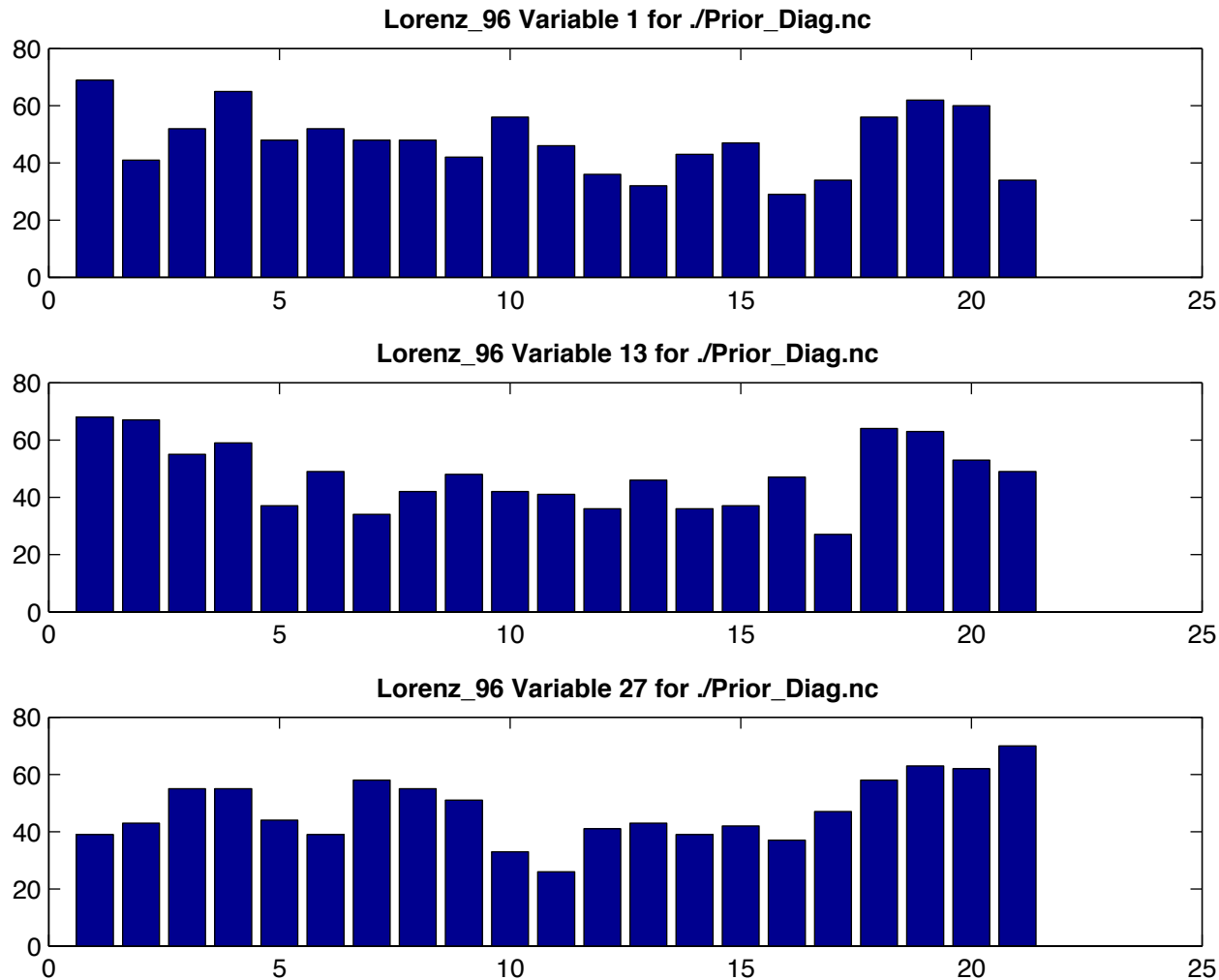
- `plot_bins.m`
- `plot_correl.m`
- `plot_ens_err_spread.m`
- `plot_ens_mean_time_series.m`
- `plot_ens_time_series.m`
- `plot_phase_space.m`
- `plot_reg_factor.m`
- `plot_sawtooth.m`
- `plot_smoother_err.m`
- `plot_total_err.m`
- `plot_var_var_correl.m`
- ...

Some, but not all, described here.
All functions have a ‘help’ section
available in the standard Matlab way.

Viewing the State-Space netCDF files:

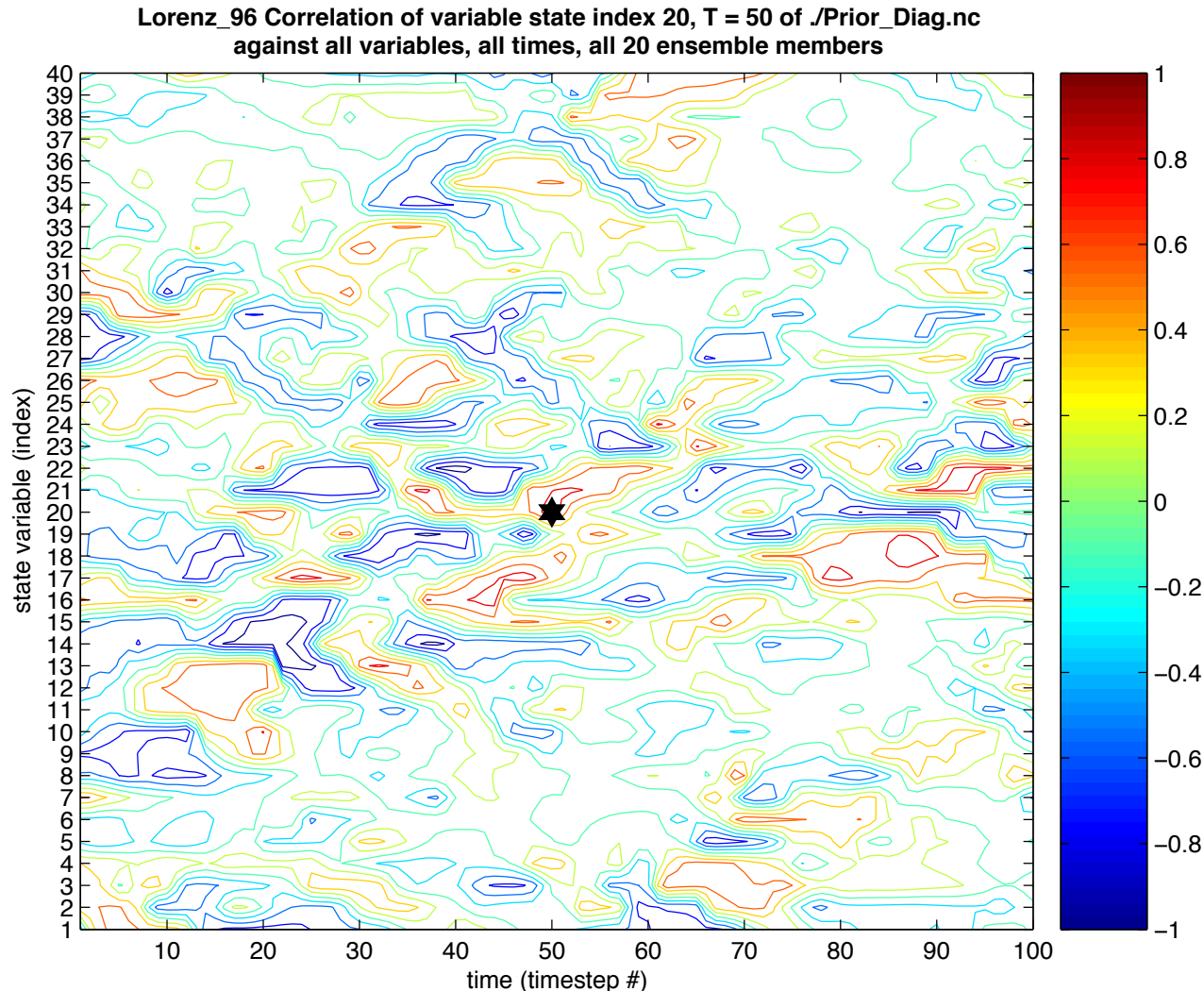
1. Standard DART matlab diagnostics:

a. `plot_bins`: rank histograms,



Viewing the State-Space netCDF files:

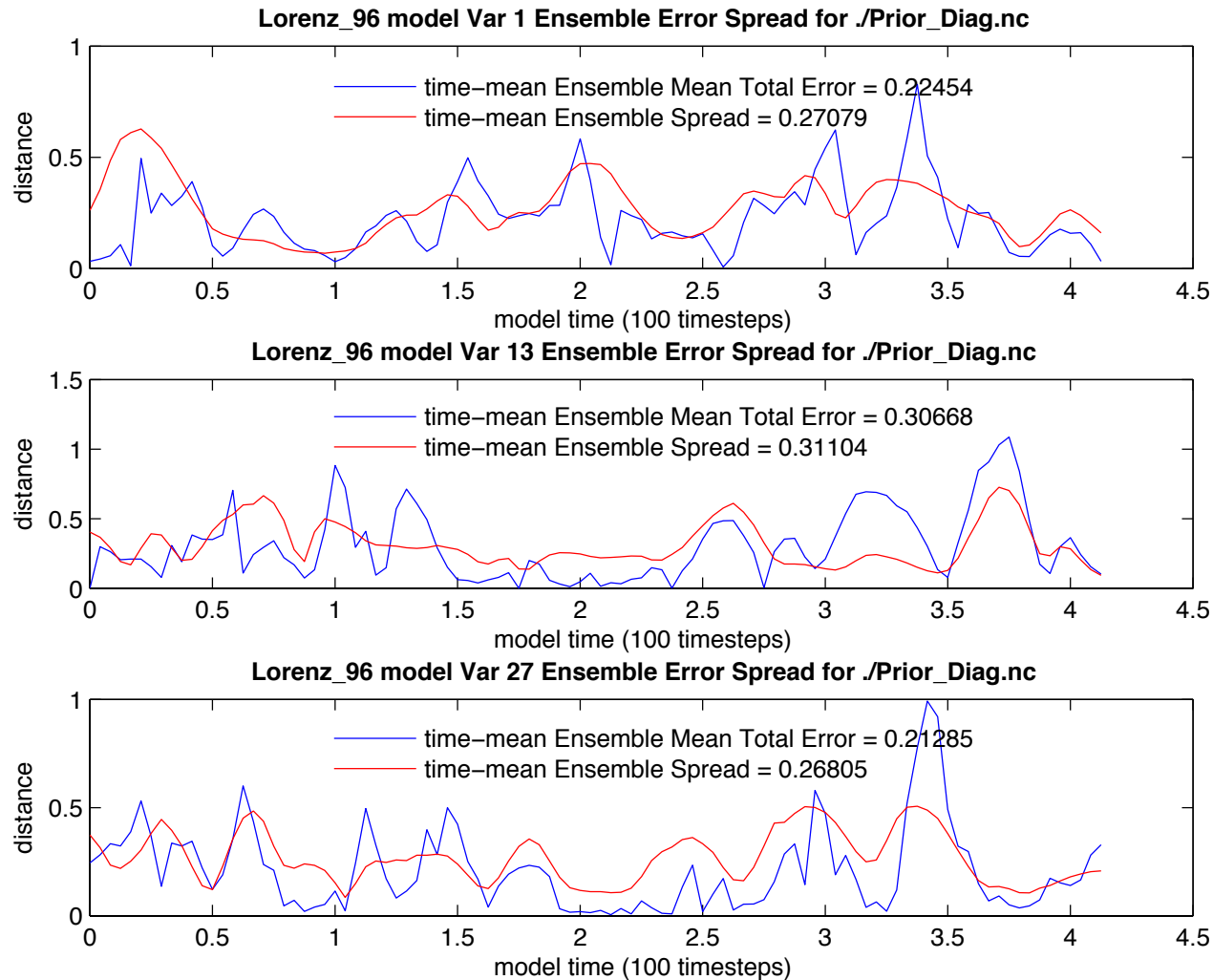
1. Standard DART matlab diagnostics:
 - b. `plot_correl`: correlation $x(t)$ with all other state vars at all times,



Viewing the State-Space netCDF files:

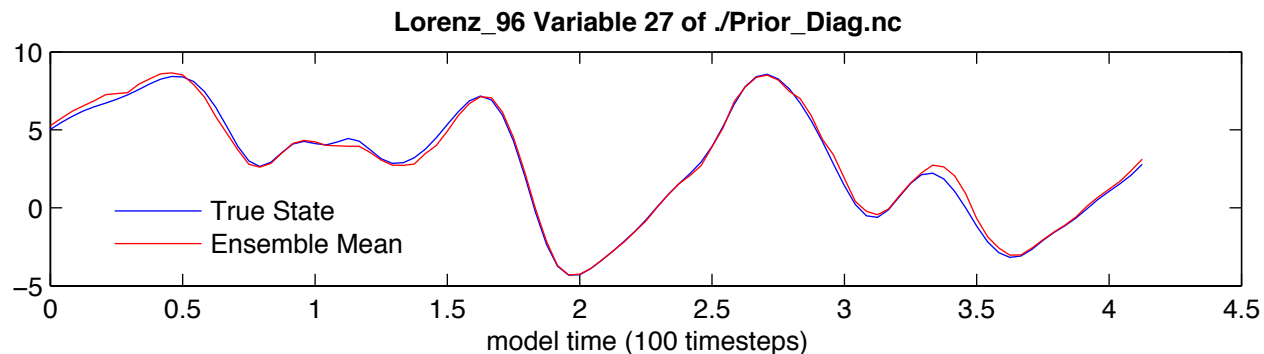
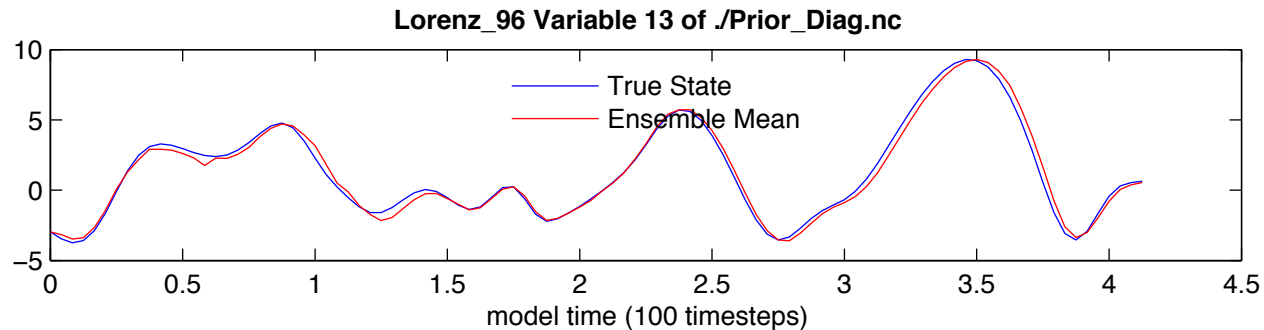
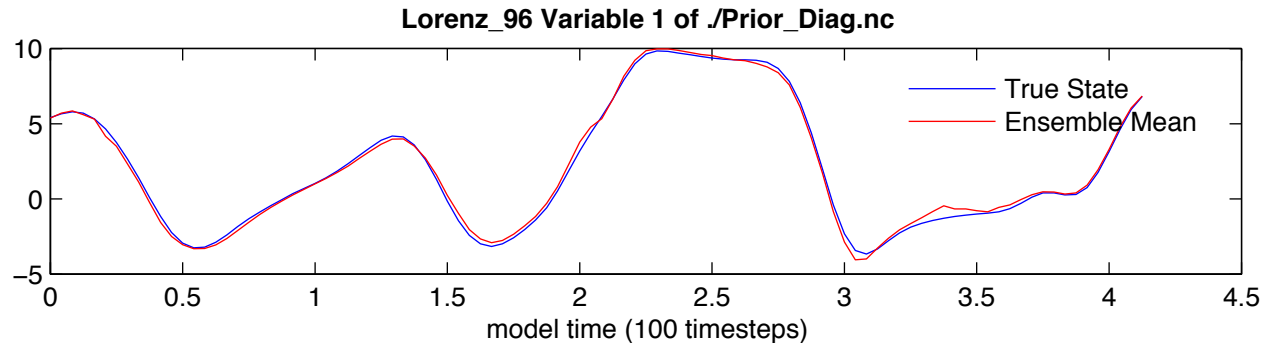
1. Standard DART matlab diagnostics:

c. `plot_ens_err_spread`: rms error and spread,



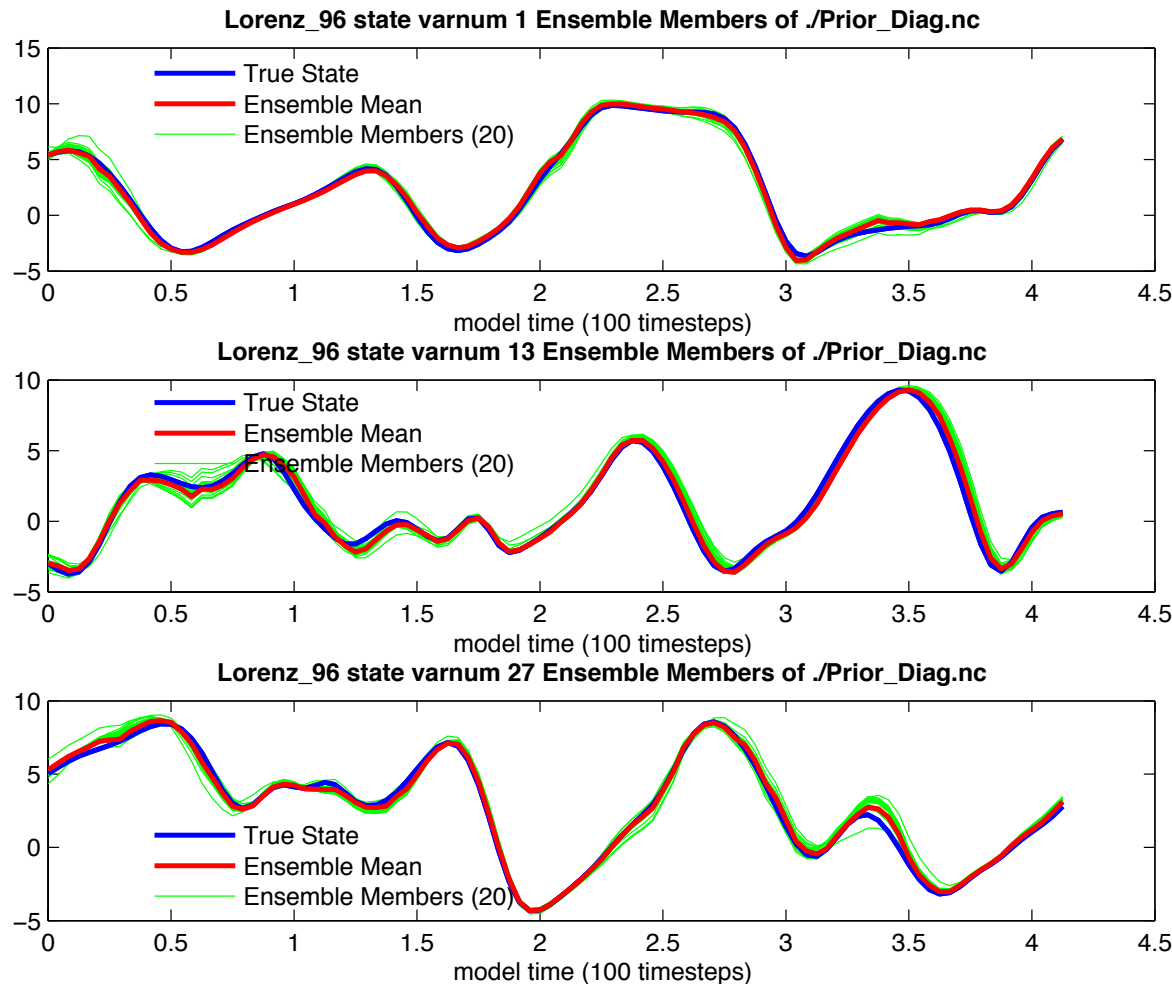
Viewing the State-Space netCDF files:

1. Standard DART matlab diagnostics:
 - d. `plot_ens_mean_time_series`: just like the name says,



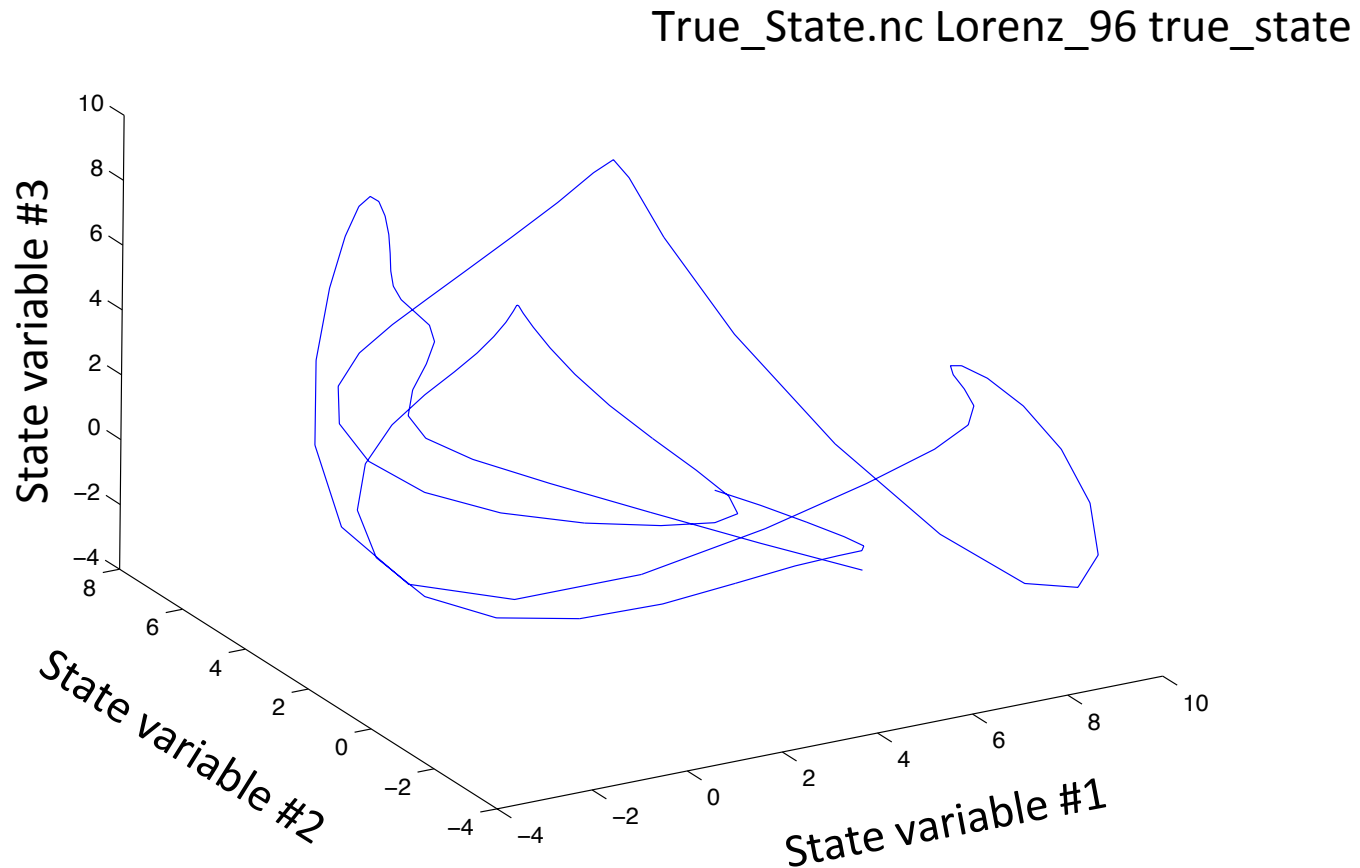
Viewing the State-Space netCDF files:

1. Standard DART matlab diagnostics:
 - e. `plot_ens_time_series`: plots the ensemble
(as available from `num_output_state_members`),



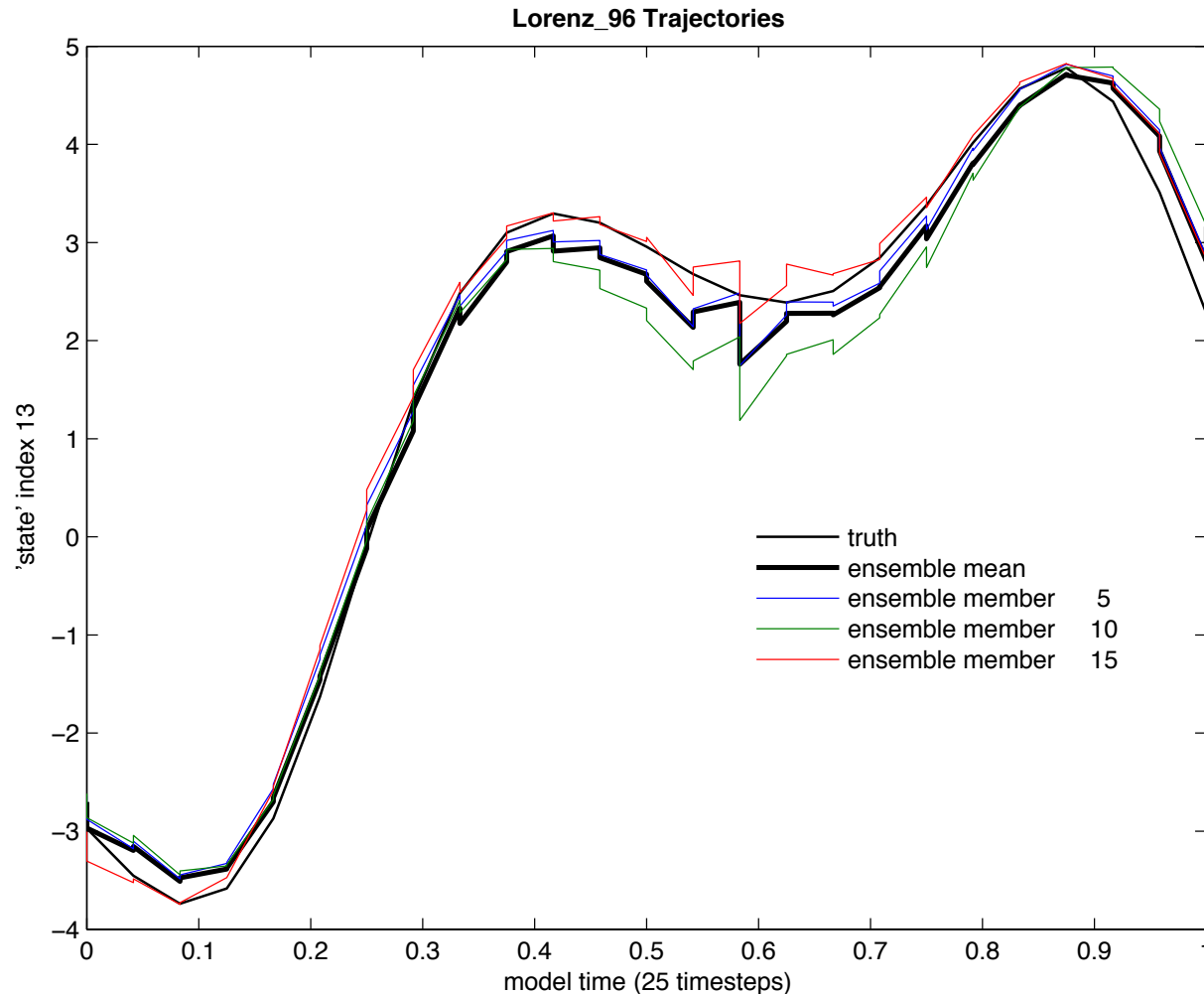
Viewing the State-Space netCDF files:

1. Standard DART matlab diagnostics:
 - f. `plot_phase_space`: 3D phase space time evolution.



Viewing the State-Space netCDF files:

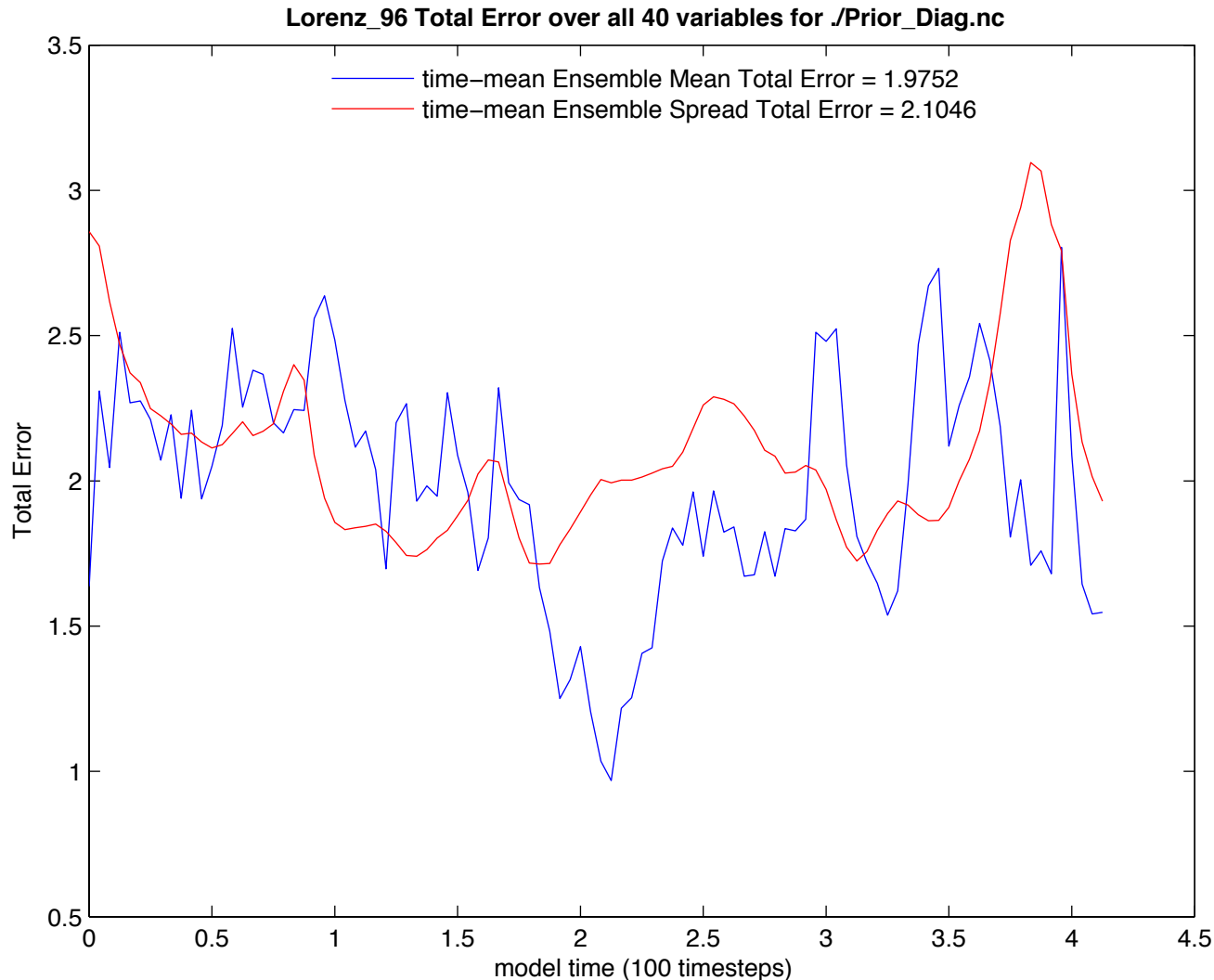
1. Standard DART matlab diagnostics:
 - g. `plot_sawtooth`: truth, prior and posterior time series.



Viewing the State-Space netCDF files:

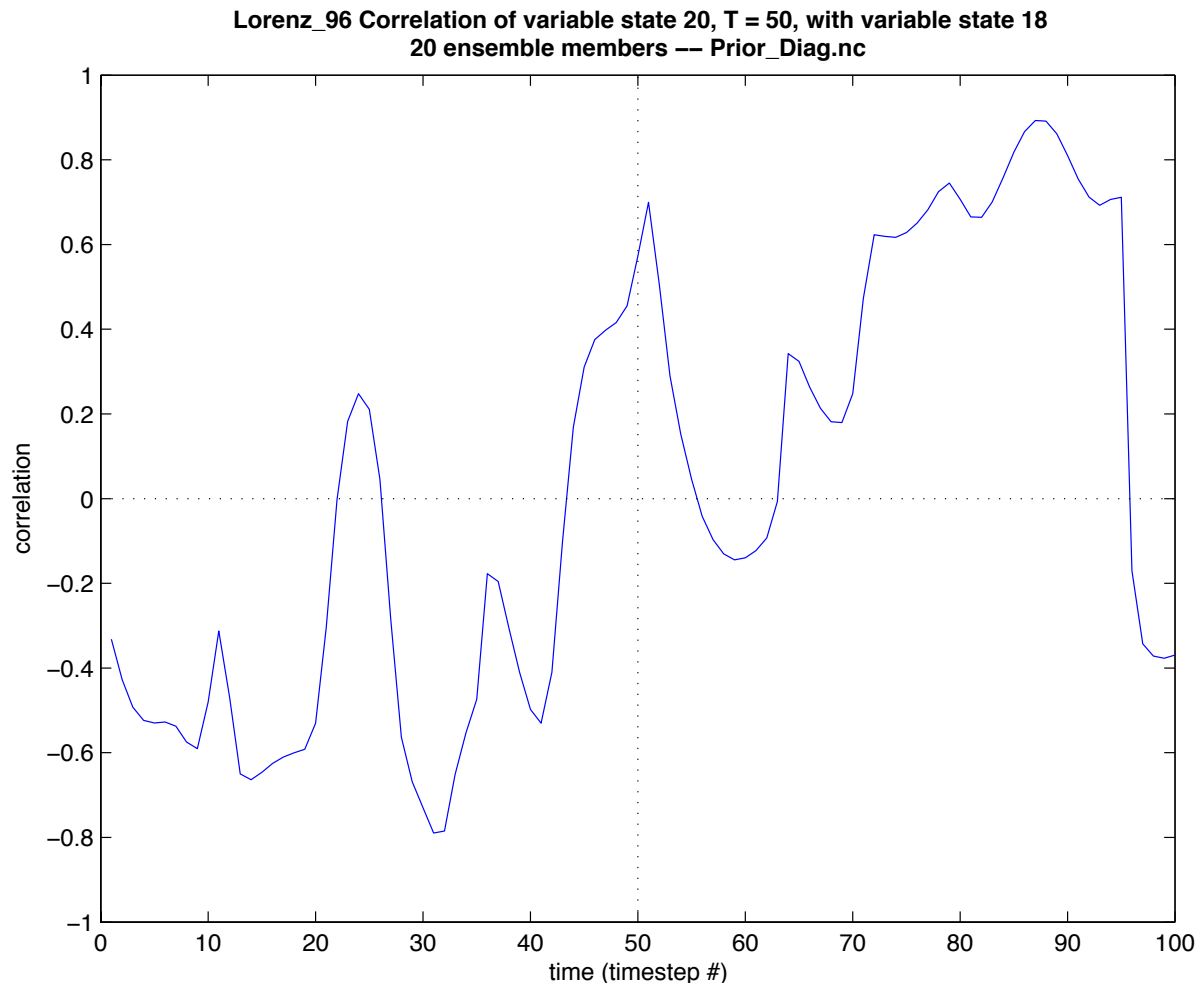
1. Standard DART matlab diagnostics:

h. `plot_total_err`: total error for different fields,



Viewing the State-Space netCDF files:

1. Standard DART matlab diagnostics:
 - i. `plot_var_var_correl`: $x(t)$ correlation to single variable, all times.

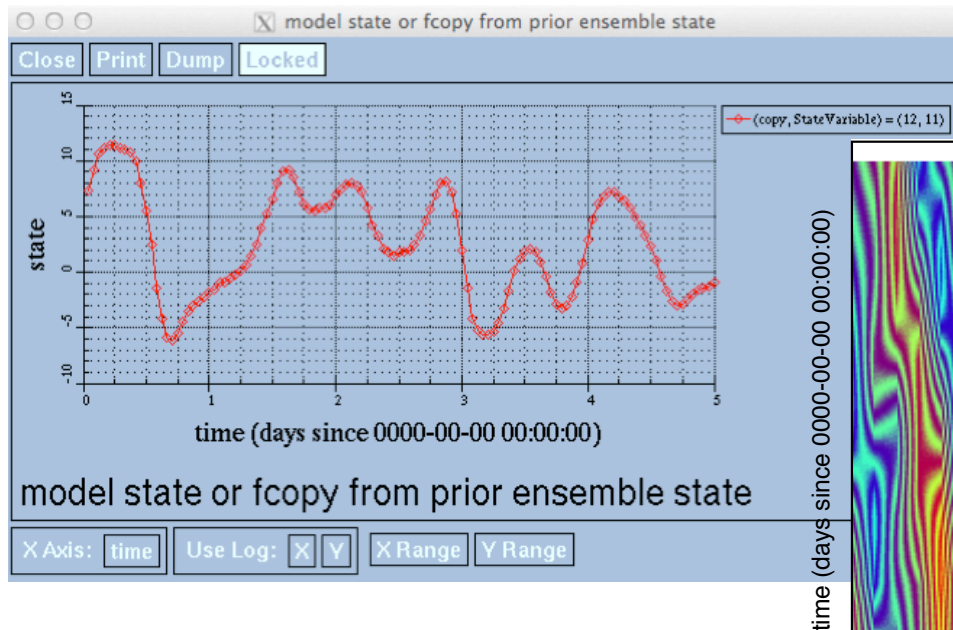


Viewing the State-Space netCDF files:

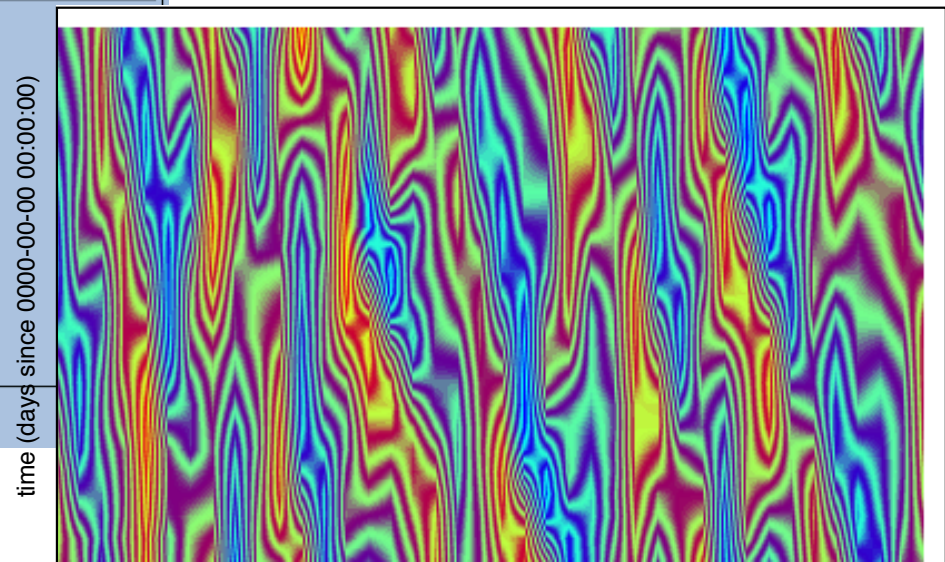
2. Ncview: a quick and surprisingly useful netCDF viewer.

http://meteora.ucsd.edu/~pierce/ncview_home_page.html

Displays spatial slices, animations, time series ...



model state or fcopy



jla Sun Jun 5 13:41:44 2005

prior ensemble state

Range of model state or fcopy: -6.18328 to 11.6954 (null)

Range of State Variable ID: 1 to 40 indexical

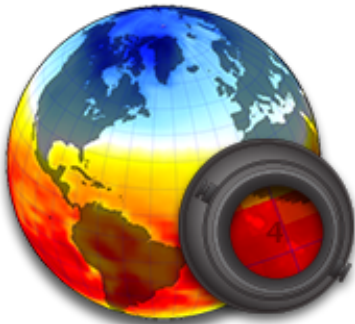
Range of time: 0 to 1 days since 0000-00-00 00:00:00

Current ensemble member or copy: 1 nondimensional

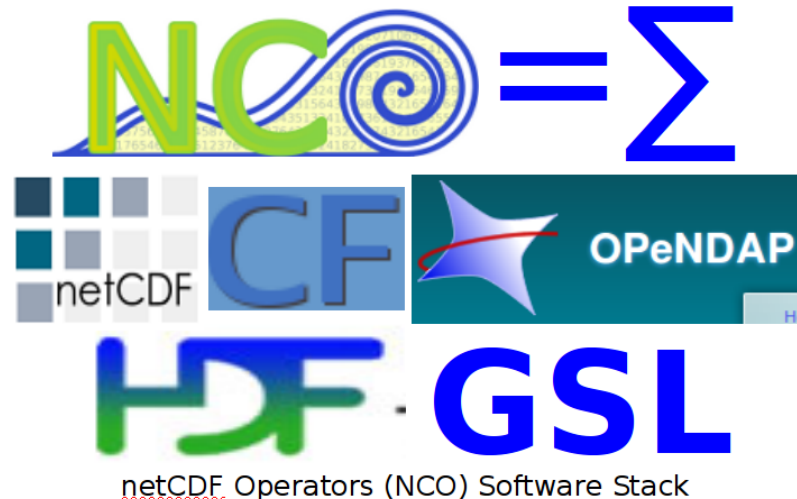
Frame 1 in File Prior_Diag.nc

Viewing the State-Space netCDF files:

3. Many other graphical/analysis programs can read netCDF.
(Note that we use *udunits* metadata convention.)
4. netCDF Operator (NCO) tools allow operations on netCDF files:
(<http://nco.sourceforge.net>)
Selecting hyperslices of fields,
Differencing netCDF file,
Averaging, etc.



NASA GISS: Panoply



Observation-space files:

Quick recap of 'standard' observation sequence file names
(all names are actually specified in namelists):

- `obs_seq.in` input to *perfect_model_obs*
- `obs_seq.out` **output** from *perfect_model_obs*, also **input** to *filter*
- `obs_seq.final` output from *filter*

Observation sequence file output by *filter* has prior, posterior, observed value (and truth for OSSEs). For an overview, check out the DART webpage section:
www.image.ucar.edu/DAReS/DART/DART_Observations.php#obs_seq_overview

Contents of *obs_seq.final* controlled by `filter_nml`:

1. `obs_sequence_in_name = 'obs_seq.out'`
Name of input observation sequence file.
2. `obs_sequence_out_name = 'obs_seq.final'`
Name of output observation sequence file.
3. `num_output_obs_members = ##`
Output this many individual ensemble estimates.

Observation-space diagnostics:

The observation sequence file is not in a particularly user-friendly format. To aid in the evaluation and interpretation, a program named ***obs_diag*** must be run to produce a netCDF file with results that can be plotted in a manner of your choosing. DART has Matlab functions/scripts that create high-quality graphics.

See tutorial section 18 for full coverage of viewing / diagnosing obs sequences. Also covered in:

http://www.image.ucar.edu/DAReS/DART/DART_Documentation.php#obs_diagnostics

Here are a few of the Matlab functions available in `<dart>/diagnostics/matlab`

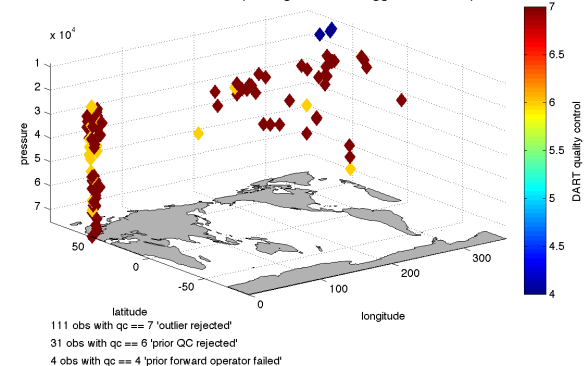
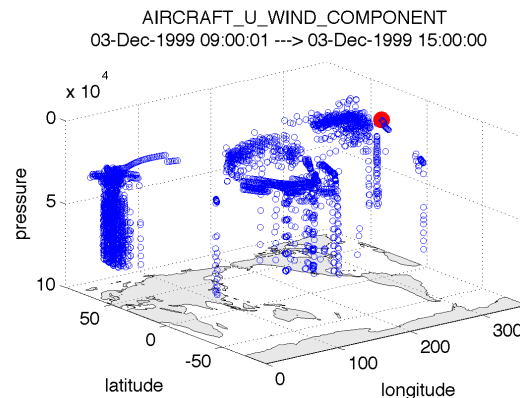
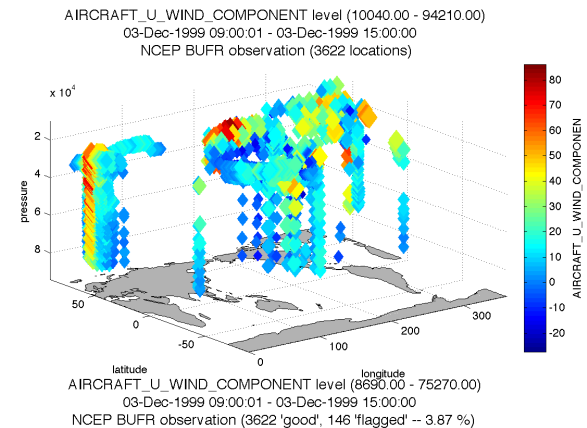
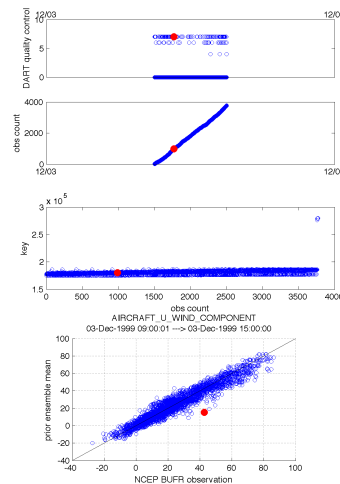
- `plot_rank_histogram.m`
- `plot_evolution.m`
- `plot_rmse_xxx_evolution.m`
- `two_experiments_evolution.m` (works with more than two, actually)
- `plot_profile.m`
- `plot_bias_xxx_profile.m`
- `plot_rmse_xxx_profile.m`
- `two_experiments_profile.m` (works with more than two, actually)

Observation-space diagnostics:

SOME of the information in the observation sequence files can be converted to netCDF and easily plotted. A program named *obs_seq_to_netcdf* must be run to produce the netCDF.

Here are a few of the Matlab functions available in `<dart>/diagnostics/matlab`.

- link_obs.m
- plot_obs_netcdf.m
- plot_obs_netcdf_diffs.m
- plot_coverage.m



Regression confidence factor output:

Reminder: `reg_factor` α introduced in Tutorial Section 13 – when running the group filter (with more than 1 group!).

Controlled by `reg_factor_nml`:

1. `save_reg_diagnostics = .true.` Should file be output?
2. `reg_diagnostics_file = 'reg_diagnostics'` Name of output file.

File size could be (model size) X (number of obs.) X (number of assim times).
Very big, even for small models (only first 4 obs output default).

Normally, modify code in `reg_factor_mod.f90` to control:

Output is at end of `select_regression = 1` code block.

Format is ASCII:

time in days, time in seconds, `obs_index`, `state_index`, α

Plot with Matlab `plot_reg_factor`.

Program Diagnostic Output:

File *dart_log.out*

All DART executables **append** to this file!

Contains:

- registration information
- Program start time,
- version of code for each module used*
- Namelist values for each module**
- Names of output files,
- Diagnostic output for modules (through `error_handler()`),
- Warnings and fatal errors from DART code.

Fair Warning: This file is **not** cleared by DART. Can get very longggggggg ...
You should feel free to delete/rename it before starting the next experiment.

*Hopefully

**may be in a separate file, depending on *utilities_nml* setting

DART Tutorial Index to Sections

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3. DART Runtime Control and Documentation
4. How should observations of a state variable impact an unobserved state variable?
Multivariate assimilation.
5. Comprehensive Filtering Theory: Non-Identity Observations and the Joint Phase Space
6. Other Updates for An Observed Variable
7. Some Additional Low-Order Models
8. Dealing with Sampling Error
9. More on Dealing with Error; Inflation
10. Regression and Nonlinear Effects
11. Creating DART Executables
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13. Hierarchical Group Filters and Localization
14. Quality control
15. DART Experiments: Control and Design
16. Diagnostic Output
17. Creating Observation Sequences
18. Lost in Phase Space: The Challenge of Not Knowing the Truth
19. DART-Compliant Models and Making Models Compliant
20. Model Parameter Estimation
21. Observation Types and Observing System Design
22. Parallel Algorithm Implementation
23. Location module design (not available)
24. Fixed lag smoother (not available)