

# MPI is a **Library** for Message-Passing

- Not built in to compiler
- Function calls that can be made from any compiler, many languages
- Just link to it
- Wrappers: mpicc, mpif77

```
#include <stdio.h>
#include <mpi.h>

int main(int argc, char **argv) {
    int rank, size;

    MPI_Init(&argc, &argv);
    MPI_Comm_size(MPI_COMM_WORLD, &size);
    MPI_Comm_rank(MPI_COMM_WORLD, &rank);

    printf("Hello, world, from task %d of %d!\n",
           rank, size);

    MPI_Finalize();
    return 0;
}
```

```
program helloworld
use mpi
implicit none
integer :: rank, comsize, ierr

call MPI_Init(ierr)
call MPI_Comm_size(MPI_COMM_WORLD, comsize, ierr)
call MPI_Comm_rank(MPI_COMM_WORLD, rank, ierr)

print *, 'Hello world, from task ', rank, &
         ' of ', comsize

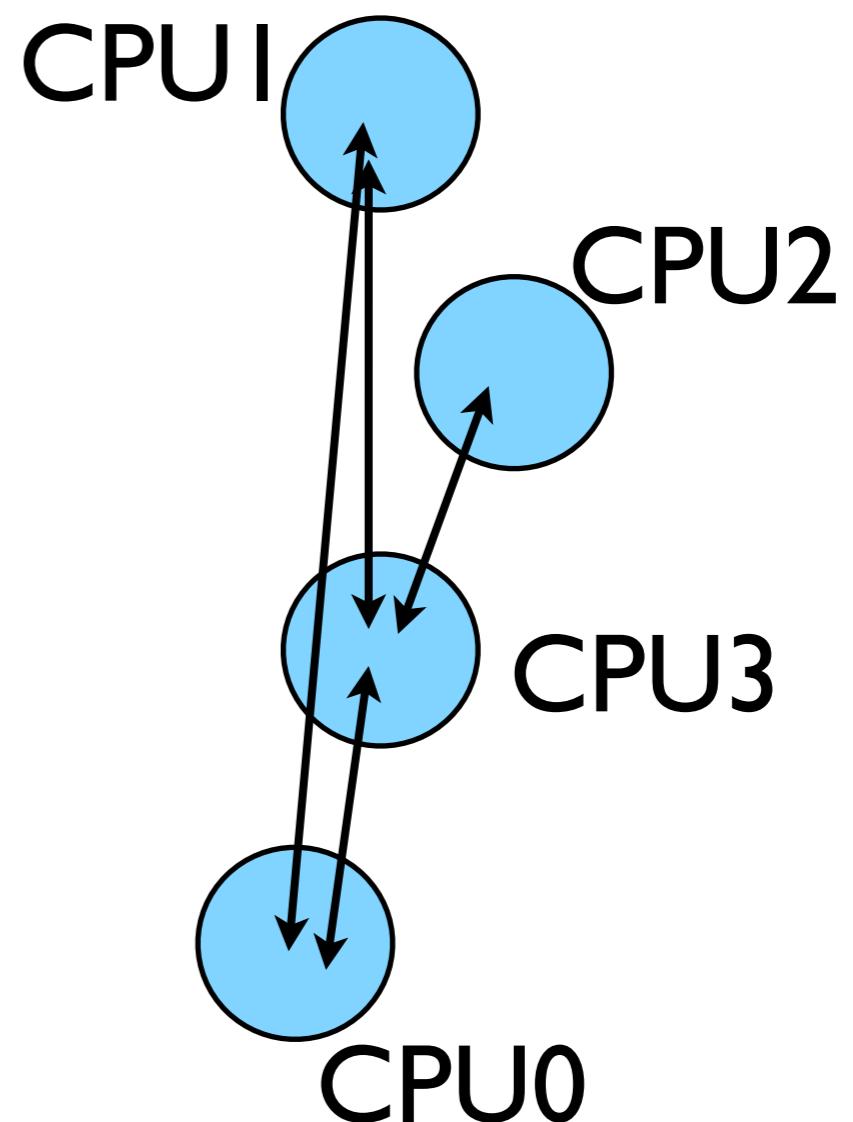
call MPI_Finalize(ierr)
end program helloworld
```

C

Fortran

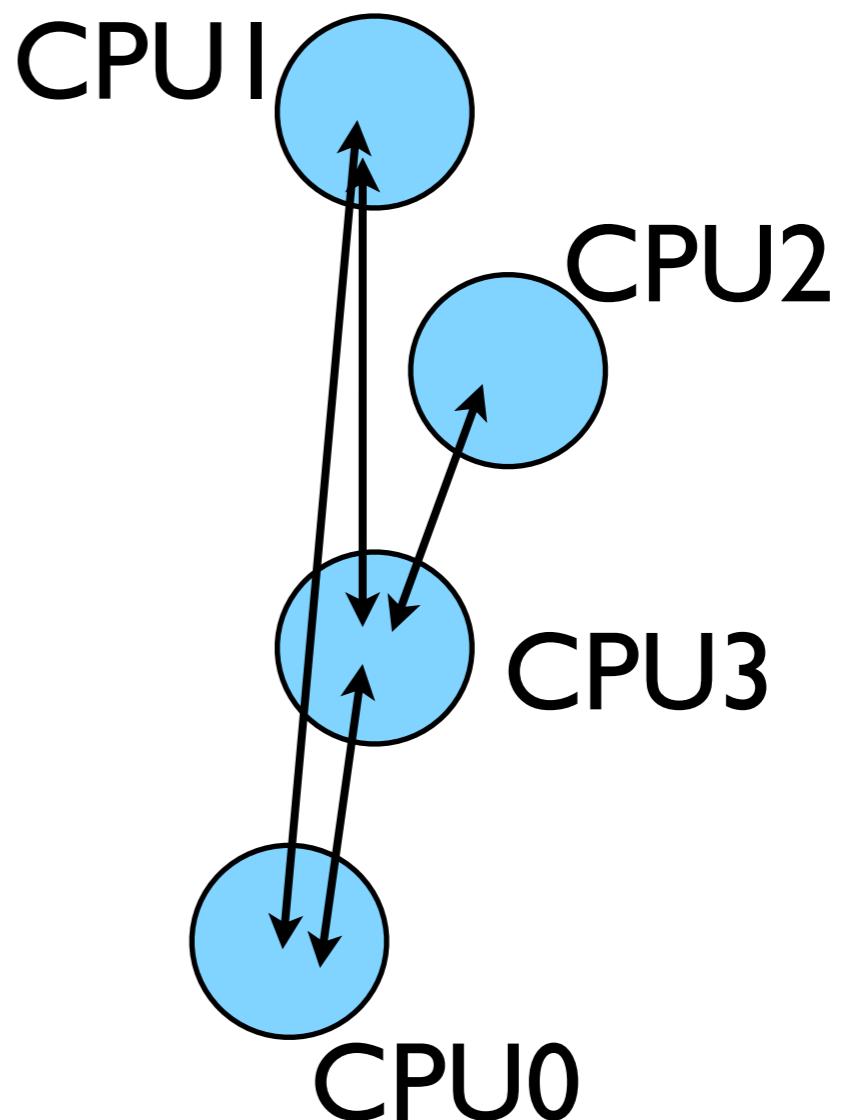
# **MPI is a Library for Message-Passing**

- Communication/coordination between tasks done by sending and receiving messages.
- Each message involves a function call from each of the programs.



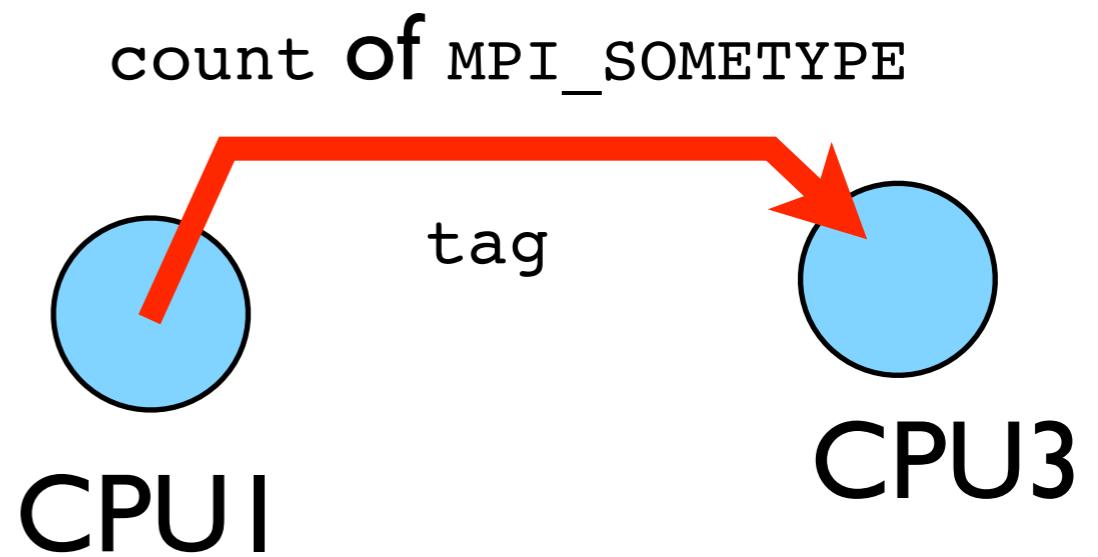
# **MPI is a Library for Message-Passing**

- Three basic sets of functionality:
  - Pairwise communications via messages
  - Collective operations via messages
  - Efficient routines for getting data from memory into messages and vice versa



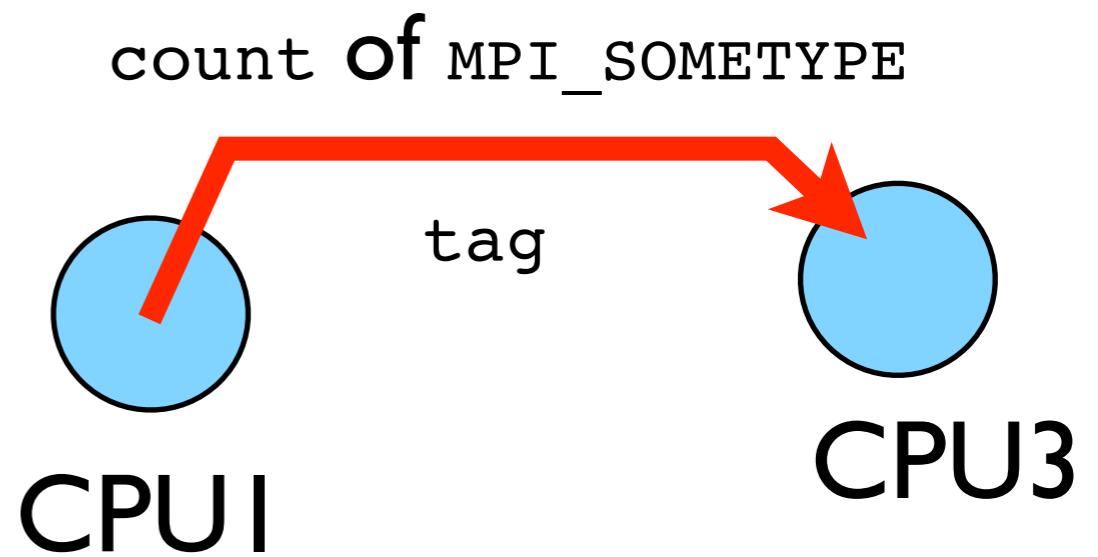
# Messages

- Messages have a **sender** and a **receiver**
- When you are sending a message, don't need to specify sender (it's the current processor),
- A sent message has to be actively received by the receiving process



# Messages

- MPI messages are a string of length **count** all of some fixed MPI **type**
- MPI types exist for characters, integers, floating point numbers, etc.
- An arbitrary integer **tag** is also included - helps keep things straight if lots of messages are sent.



# Size of MPI Library

- Many, many functions (>200)
- Not nearly so many concepts
- We'll get started with just 10-12, use more as needed.

`MPI_Init()`  
`MPI_Comm_size()`  
`MPI_Comm_rank()`  
`MPI_Ssend()`  
`MPI_Recv()`  
`MPI_Finalize()`

# Hello World

- The obligatory starting point
- cd mpi/mpi-intro
- Type it in, compile and run it together

Fortran

```
program helloworld
use mpi
implicit none
integer :: rank, comsize, ierr

call MPI_Init(ierr)
call MPI_Comm_size(MPI_COMM_WORLD, comsize, ierr)
call MPI_Comm_rank(MPI_COMM_WORLD, rank, ierr)

print *, 'Hello world, from task ', rank, &
          ' of ', comsize

call MPI_Finalize(ierr)
end program helloworld
```

C

```
#include <stdio.h>
#include <mpi.h>

int main(int argc, char **argv) {
    int rank, size;

    MPI_Init(&argc, &argv);
    MPI_Comm_size(MPI_COMM_WORLD, &size);
    MPI_Comm_rank(MPI_COMM_WORLD, &rank);

    printf("Hello, world, from task %d of %d!\n",
           rank, size);

    MPI_Finalize();
    return 0;
}
```

edit hello-world.c or .f90  
\$ mpif90 hello-world.f90  
-o hello-world  
or  
\$ mpicc hello-world.c  
-o hello-world  
\$ mpirun -np 1 hello-world  
\$ mpirun -np 2 hello-world  
\$ mpirun -np 8 hello-world

t

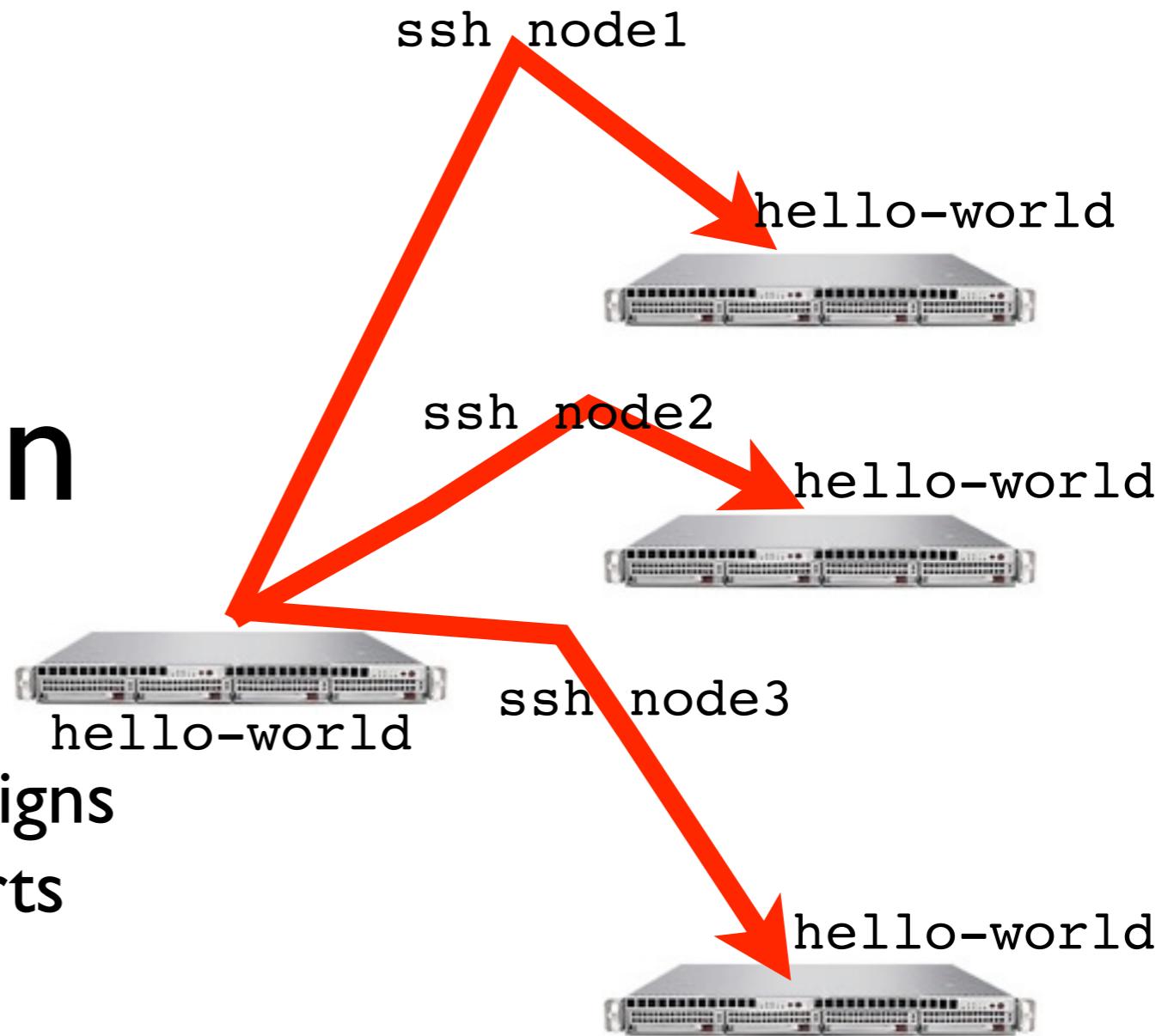
# What mpicc/ mpif77 do

- Just wrappers for the system C, Fortran compilers that have the various -I, -L clauses in there automatically
- -v option (sharcnet) or --showme (OpenMPI) shows which options are being used

```
$ mpicc --showme hello-world.c  
-o hello-world  
  
gcc -I/usr/local/include  
-pthread hello-world.c -o  
hello-world -L/usr/local/lib  
-lmpi -lopen-rte -lopen-pal  
-ldl -Wl,--export-dynamic -lns1  
-lutil -lm -ldl
```

# What mpirun does

- Launches n processes, assigns each an MPI rank and starts the program
- For multinode run, has a list of nodes, ssh's to each node and launches the program



# Number of Processes

- Number of processes to use is almost always equal to the number of processors
- But not necessarily.
- On your nodes, what happens when you run this?

```
$ mpirun -np 24 hello-world
```

# mpirun runs *any* program

- mpirun will start that process-launching procedure for any program
- Sets variables somehow that mpi programs recognize so that they know which process they are

```
$ hostname
$ mpirun -np 4 hostname
$ ls
$ mpirun -np 4 ls
```

# make

- Make builds an executable from a list of source code files and rules
- Many files to do, of which order doesn't matter for most
- Parallelism!
- make -j N - launches N processes to do it
- make -j 2 often shows speed increase even on single processor systems

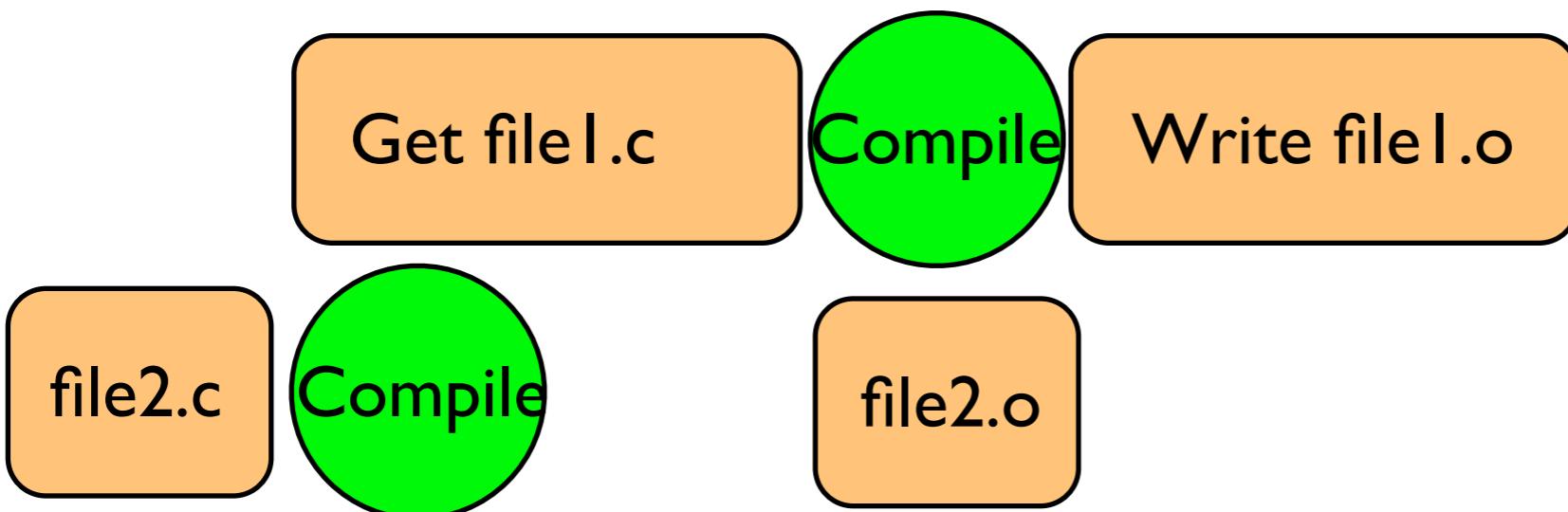
```
$ make  
$ make -j 2  
$ make -j
```

# Overlapping Computation with I/O

P=1



P=2



# What the code does

- (FORTRAN version; C is similar)

```
program helloworld
use mpi
implicit none
integer :: rank, comsize, ierr

call MPI_Init(ierr)
call MPI_Comm_size(MPI_COMM_WORLD, comsize, ierr)
call MPI_Comm_rank(MPI_COMM_WORLD, rank, ierr)

print *, 'Hello world, from task ', rank, &
         ' of ', comsize

call MPI_Finalize(ierr)
end program helloworld
```

use mpi : imports declarations for MPI function calls

```
program helloworld
use mpi
implicit none
integer :: rank, comsize, ierr
call MPI_Init(ierr)
call MPI_Comm_size(MPI_COMM_WORLD, comsize, ierr)
call MPI_Comm_rank(MPI_COMM_WORLD, rank, ierr)
print *, 'Hello world, from task ', rank, & ierr
      ' of ', comsize
call MPI_Finalize(ierr)
end program helloworld
```

call MPI\_INIT(ierr):  
initialization for MPI library.  
Must come first.

ierr: Returns any error code.

call MPI\_FINALIZE(ierr):  
close up MPI stuff.  
Must come last.  
 ierr: Returns any error code.

```
program helloworld
use mpi
implicit none
integer :: rank, comsize, ierr

call MPI_Init(ierr)
call MPI_Comm_size(MPI_COMM_WORLD, comsize, ierr)
call MPI_Comm_rank(MPI_COMM_WORLD, rank, ierr)

print *, 'Hello world, from task ', rank, &
         ' of ', comsize

call MPI_Finalize(ierr)
end program helloworld
```

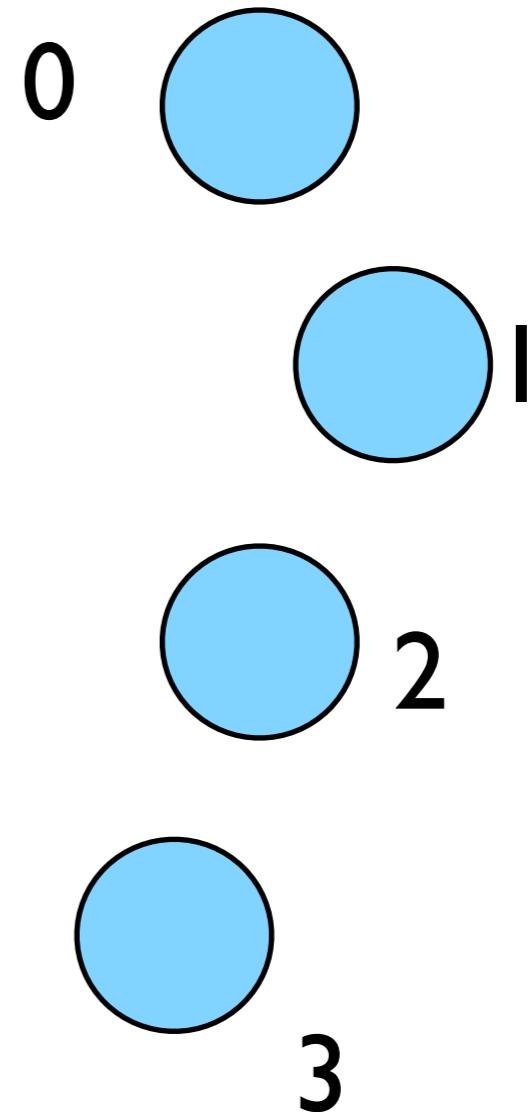
call MPI\_COMM\_RANK,  
call MPI\_COMM\_SIZE:  
requires a little more exposition.



# Communicators

- MPI groups processes into communicators.
- Each communicator has some size -- number of tasks.
- Each task has a rank 0..size-1
- Every task in your program belongs to

`MPI_COMM_WORLD`



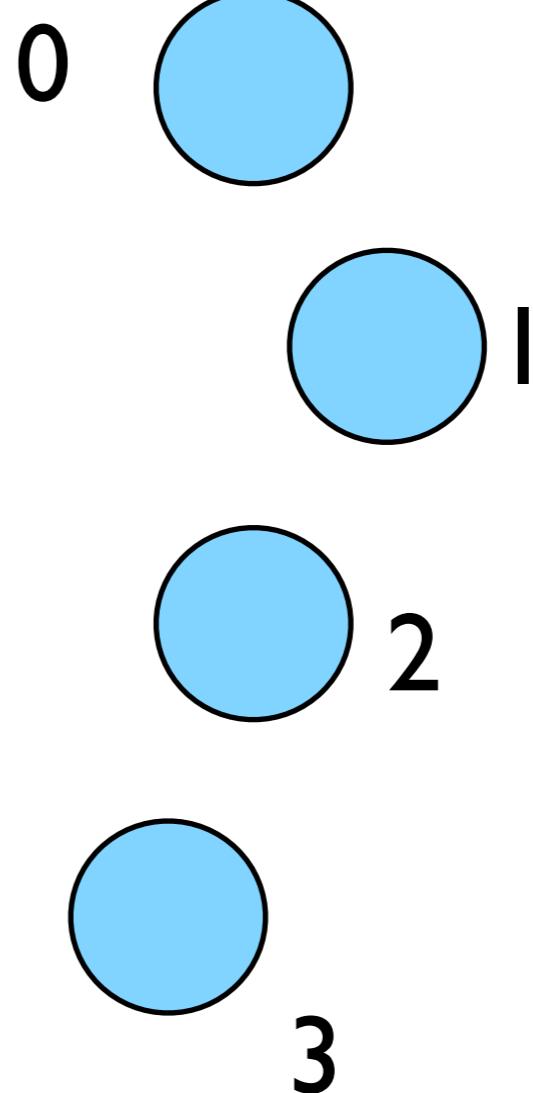
`MPI_COMM_WORLD:`  
size=4, ranks=0..3



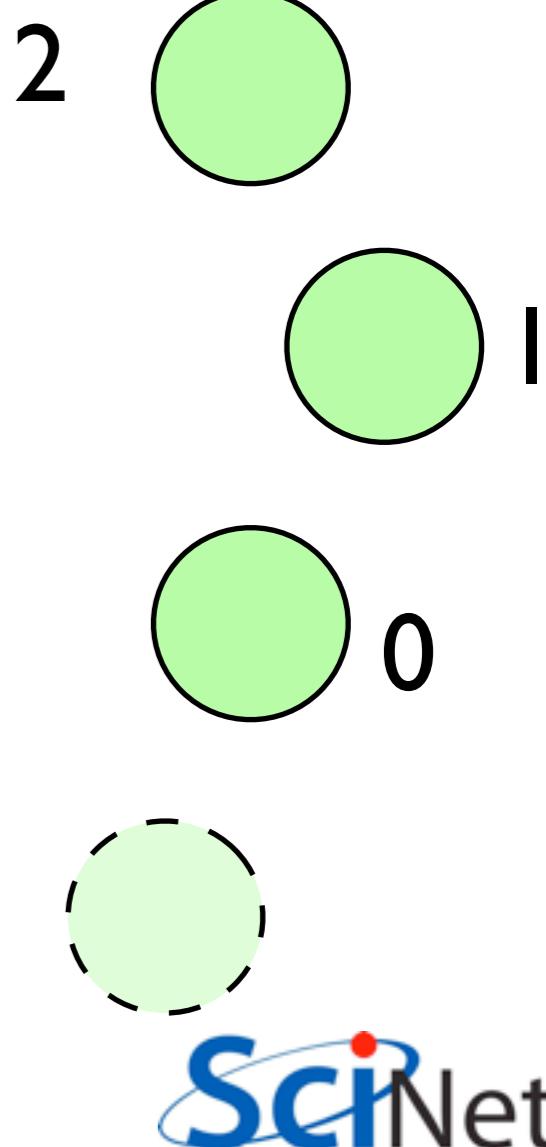
# Communicators

- Can create our own communicators over the same tasks
- May break the tasks up into subgroups
- May just re-order them for some reason

MPI\_COMM\_WORLD:  
size=4, ranks=0..3



new\_comm  
size=3, ranks=0..2



```
program helloworld
use mpi
implicit none
integer :: rank, comsize, ierr
call MPI_Init(ierr)
call MPI_Comm_size(MPI_COMM_WORLD, comsize, ierr)
call MPI_Comm_rank(MPI_COMM_WORLD, rank, ierr)
print *, 'Hello world, from task ', rank, &
         ' of ', comsize
call MPI_Finalize(ierr)
end program helloworld
```

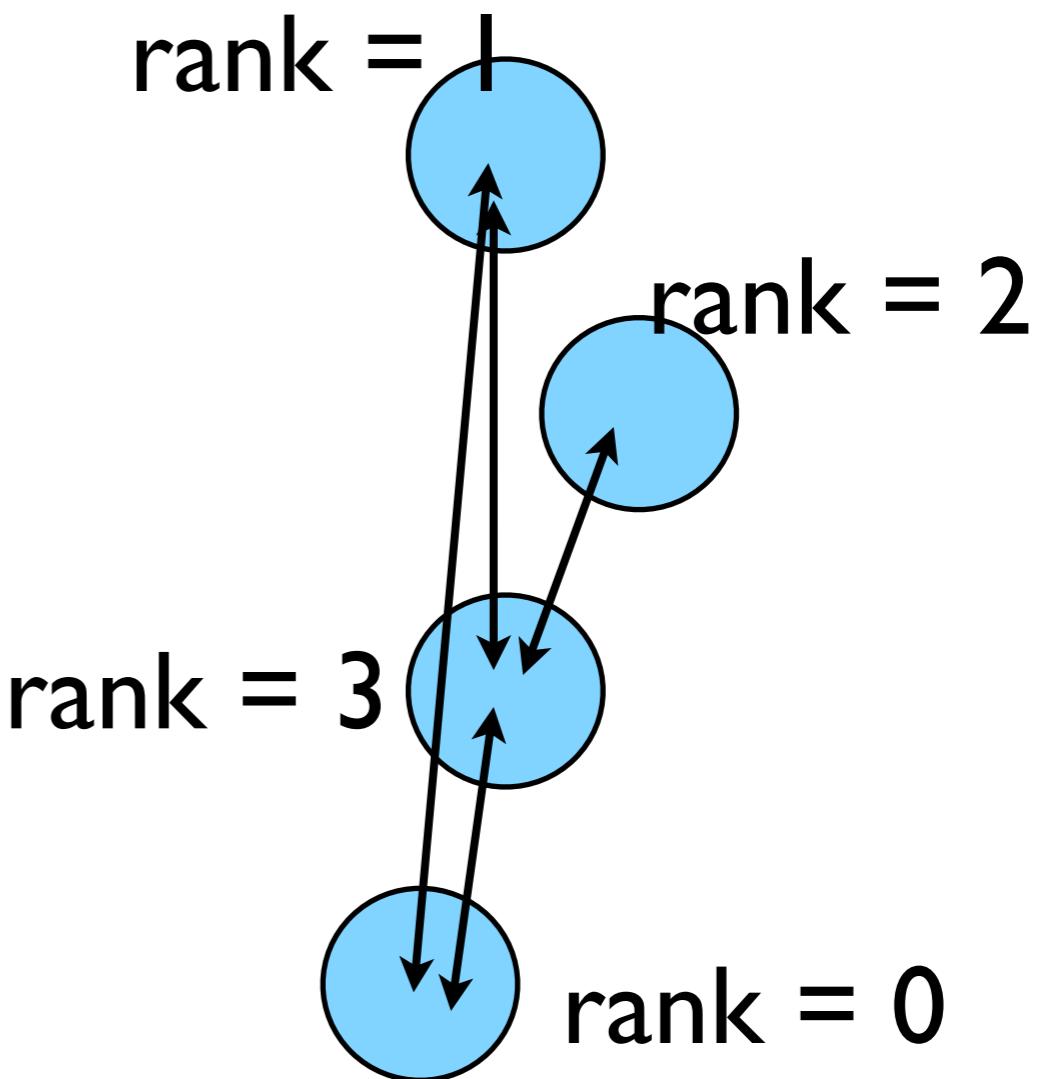
call MPI\_COMM\_RANK,  
call MPI\_COMM\_SIZE:

get the size of communicator  
the current tasks's rank with  
communicator.

put answers in rank and  
size

# Rank and Size much more important in MPI than OpenMP

- In OpenMP, compiler assigns jobs to each thread; don't need to know which one you are.
- MPI: processes determine amongst themselves which piece of puzzle to work on, then communicate with appropriate others.



# C

```
#include <stdio.h>
#include <mpi.h>

int main(int argc, char **argv) {
    int rank, size;

    MPI_Init(&argc, &argv);
    MPI_Comm_size(MPI_COMM_WORLD, &size);
    MPI_Comm_rank(MPI_COMM_WORLD, &rank);

    printf("Hello, world, from task %d of %d!\n",
           rank, size);

    MPI_Finalize();
    return 0;
}
```

# Fortran

```
program helloworld
use mpi
implicit none
integer :: rank, comsize, ierr

call MPI_Init(ierr)
call MPI_Comm_size(MPI_COMM_WORLD, comsize, ierr)
call MPI_Comm_rank(MPI_COMM_WORLD, rank, ierr)

print *, 'Hello world, from task ', rank, &
          ' of ', comsize

call MPI_Finalize(ierr)
end program helloworld
```

- `#include <mpi.h>` vs `use mpi`
- C - functions **return** `ierr`;
- Fortran - **pass** `ierr`
- `MPI_Init`

# Our first real MPI program - but no Ms are P'ed!

- Let's fix this
- mpicc -o firstmessage firstmessage.c
- mpirun -np 2 ./firstmessage
- Note: C - MPI\_CHAR

```
#include <stdio.h>
#include <mpi.h>

int main(int argc, char **argv) {
    int rank, size, ierr;
    int sendto, recvfrom; /* task to send, recv from */
    int ourtag=1;          /* shared tag to label msgs*/
    char sendmessage[]="Hello";      /* text to send */
    char getmessage[6];           /* text to receive */
    MPI_Status rstatus;          /* MPI_Recv status info */

    ierr = MPI_Init(&argc, &argv);
    ierr = MPI_Comm_size(MPI_COMM_WORLD, &size);
    ierr = MPI_Comm_rank(MPI_COMM_WORLD, &rank);

    if (rank == 0) {
        sendto = 1;
        ierr = MPI_Ssend(sendmessage, 6, MPI_CHAR, sendto,
                         ourtag, MPI_COMM_WORLD);
        printf("%d: Sent message <%s>\n", rank, sendmessage);
    } else if (rank == 1) {
        recvfrom = 0;
        ierr = MPI_Recv(getmessage, 6, MPI_CHAR, recvfrom,
                        ourtag, MPI_COMM_WORLD, &rstatus);
        printf("%d: Got message <%s>\n", rank, getmessage);
    }
    ierr = MPI_Finalize();
    return 0;
}
```

# Fortran version

- Let's fix this
- mpif90 -o firstmessage firstmessage.f90
- mpirun -np 2 ./firstmessage
- FORTRAN - MPI\_CHARACTER

```
program firstmessage
use mpi
implicit none

integer :: rank, comsize, ierr
integer :: sendto, recvfrom ! Task to send, recv from
integer :: ourtag=1          ! shared tag to label msgs
character(5) :: sendmessage ! text to send
character(5) :: getmessage  ! text rcvd
integer, dimension(MPI_STATUS_SIZE) :: rstatus

call MPI_Init(ierr)
call MPI_Comm_rank(MPI_COMM_WORLD, rank, ierr)
call MPI_Comm_size(MPI_COMM_WORLD, comsize, ierr)

if (rank == 0) then
    sendmessage = 'Hello'
    sendto = 1
    call MPI_Ssend(sendmessage, 5, MPI_CHARACTER, sendto,&
                  ourtag, MPI_COMM_WORLD, ierr)
    print *, rank, ' sent message <',sendmessage,'>'
else if (rank == 1) then
    recvfrom = 0
    call MPI_Recv(getmessage, 5, MPI_CHARACTER, recvfrom,&
                  ourtag, MPI_COMM_WORLD, rstatus, ierr)
    print *, rank, ' got message <',getmessage,'>'
endif

call MPI_Finalize(ierr)
end program firstmessage
```



# C - Send and Receive

```
MPI_Status status;

ierr = MPI_Ssend(sendptr, count, MPI_TYPE, destination,
                  tag, Communicator);

ierr = MPI_Recv(recvptr, count, MPI_TYPE, source, tag,
                 Communicator, &status);
```

# Fortran - Send and Receive

```
integer status(MPI_STATUS_SIZE)

call MPI_SSEND(sendarr, count, MPI_TYPE, destination,
               tag, Communicator, ierr)

call MPI_RECV(rcvvar, count, MPI_TYPE, source, tag,
              Communicator, status, ierr)
```

# **Special Source/Dest: MPI\_PROC\_NULL**

**MPI\_PROC\_NULL** basically ignores the relevant operation; can lead to cleaner code.

# **Special Source: MPI\_ANY\_SOURCE**

**MPI\_ANY\_SOURCE** is a wildcard; matches any source when receiving.

# More complicated example:

- Let's look at  
secondmessage.f90,  
secondmessage.c

```
#include <stdio.h>
#include <mpi.h>

int main(int argc, char **argv) {
    int rank, size, ierr;
    int left, right;
    int tag=1;
    double msgsent, msgrcvd;
    MPI_Status rstatus;

    ierr = MPI_Init(&argc, &argv);
    ierr = MPI_Comm_size(MPI_COMM_WORLD, &size);
    ierr = MPI_Comm_rank(MPI_COMM_WORLD, &rank);

    left = rank - 1;
    if (left < 0) left = MPI_PROC_NULL;
    right = rank + 1;
    if (right == size) right = MPI_PROC_NULL;

    msgsent = rank*rank;
    msgrcvd = -999;

    ierr = MPI_Ssend(&msgsent, 1, MPI_DOUBLE, right,
                    tag, MPI_COMM_WORLD);
    ierr = MPI_Recv(&msgrcvd, 1, MPI_DOUBLE, left,
                   tag, MPI_COMM_WORLD, &rstatus);

    printf("%d: Sent %lf and got %lf\n",
           rank, msgsent, msgrcvd);

    ierr = MPI_Finalize();
    return 0;
}
```

# More complicated example:

- Let's look at `secondmessage.f90`, `secondmessage.c`

```
program secondmessage
use mpi
implicit none

integer :: ierr, rank, comsize
integer :: left, right
integer :: tag
integer :: status(MPI_STATUS_SIZE)
double precision :: msgsent, msgrcvd

call MPI_INIT(ierr)
call MPI_COMM_RANK(MPI_COMM_WORLD, rank, ierr)
call MPI_COMM_SIZE(MPI_COMM_WORLD, comsize, ierr)

left = rank-1
if (left < 0) left = MPI_PROC_NULL
right = rank+1
if (right >= comsize) right = MPI_PROC_NULL

msgsent = rank*rank
msgrcvd = -999.
tag = 1

call MPI_Ssend(msgsent, 1, MPI_DOUBLE_PRECISION, right, &
               tag, MPI_COMM_WORLD, ierr)
call MPI_Recv(msgrcvd, 1, MPI_DOUBLE_PRECISION, left, &
               tag, MPI_COMM_WORLD, status, ierr)

print *, rank, 'Sent ', msgsent, 'and recv ', msgrcvd

call MPI_FINALIZE(ierr)

end program secondmessage
```

# Compile and run

- mpi{cc,f90} -o secondmessage  
secondmessage.{c,f90}
- mpirun -np 4 ./secondmessage

```
$ mpirun -np 4 ./secondmessage
3: Sent 9.000000 and got 4.000000
0: Sent 0.000000 and got -999.000
1: Sent 1.000000 and got 0.000000
2: Sent 4.000000 and got 1.000000
```

```

#include <stdio.h>
#include <mpi.h>

int main(int argc, char **argv) {
    int rank, size, ierr;
    int left, right;
    int tag=1;
    double msgsent, msgrcvd;
    MPI_Status rstatus;

    ierr = MPI_Init(&argc, &argv);
    ierr = MPI_Comm_size(MPI_COMM_WORLD, &size);
    ierr = MPI_Comm_rank(MPI_COMM_WORLD, &rank);

    left = rank - 1;
    if (left < 0) left = MPI_PROC_NULL;
    right = rank + 1;
    if (right == size) right = MPI_PROC_NULL;

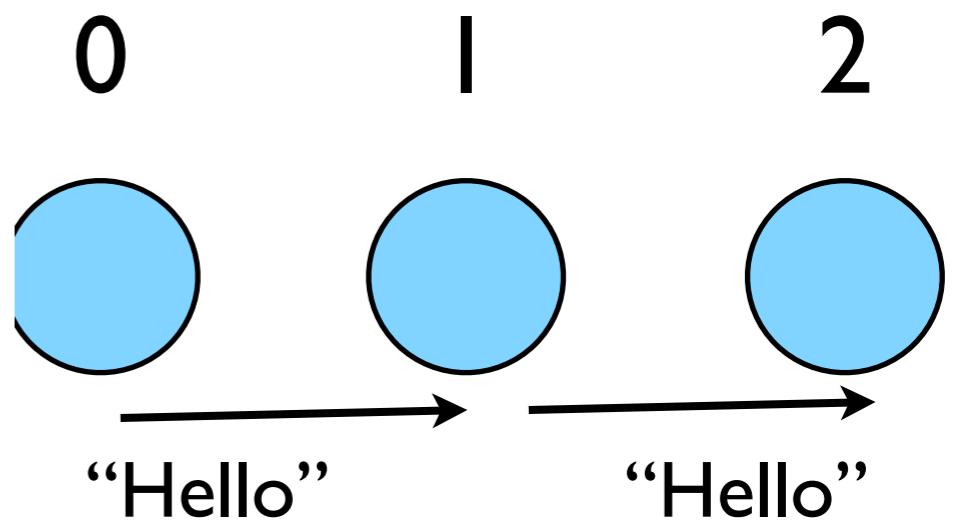
    msgsent = rank*rank;
    msgrcvd = -999;

    ierr = MPI_Ssend(&msgsent, 1, MPI_DOUBLE, right,
                     tag, MPI_COMM_WORLD);
    ierr = MPI_Recv(&msgrcvd, 1, MPI_DOUBLE, left,
                    tag, MPI_COMM_WORLD, &rstatus);

    printf("%d: Sent %lf and got %lf\n",
           rank, msgsent, msgrcvd);

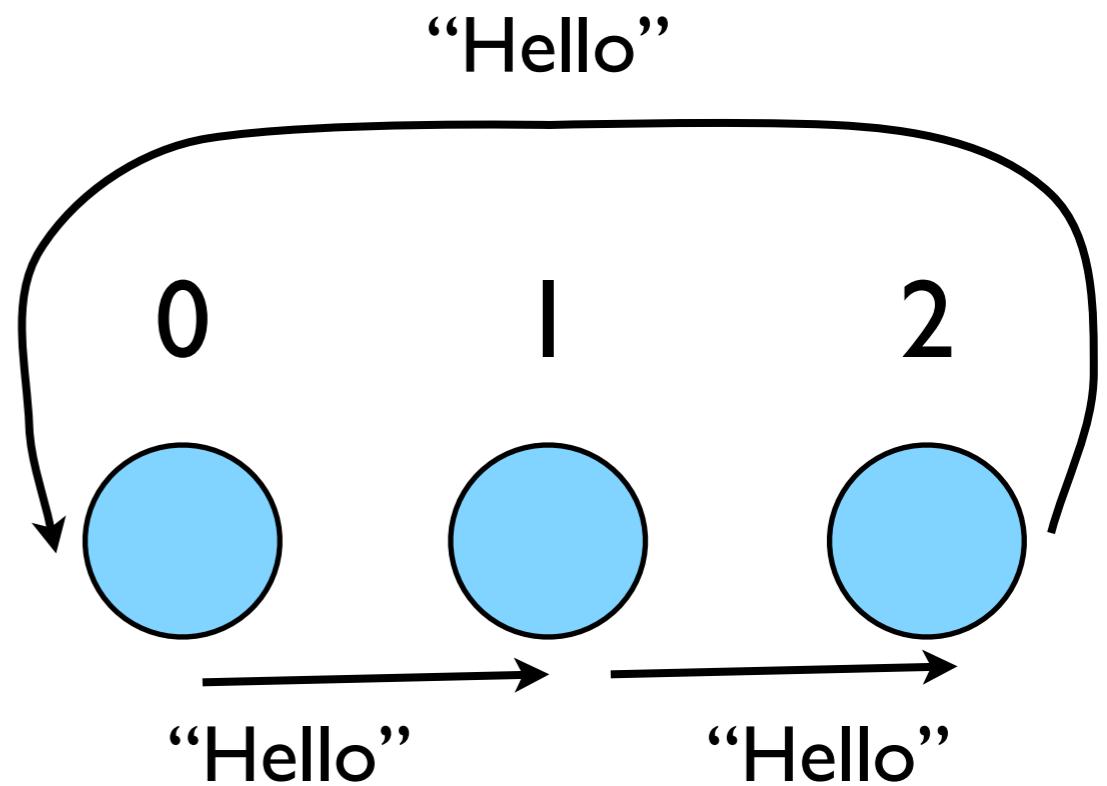
    ierr = MPI_Finalize();
    return 0;
}

```



# Implement periodic boundary conditions

- cp secondmessage.{c,f90}  
thirdmessage.{c,f90}
- edit so it `wraps around'
- mpi{cc,f90} thirdmessage.  
{c,f90} -o thirdmessage
- mpirun -np 3 thirdmessage

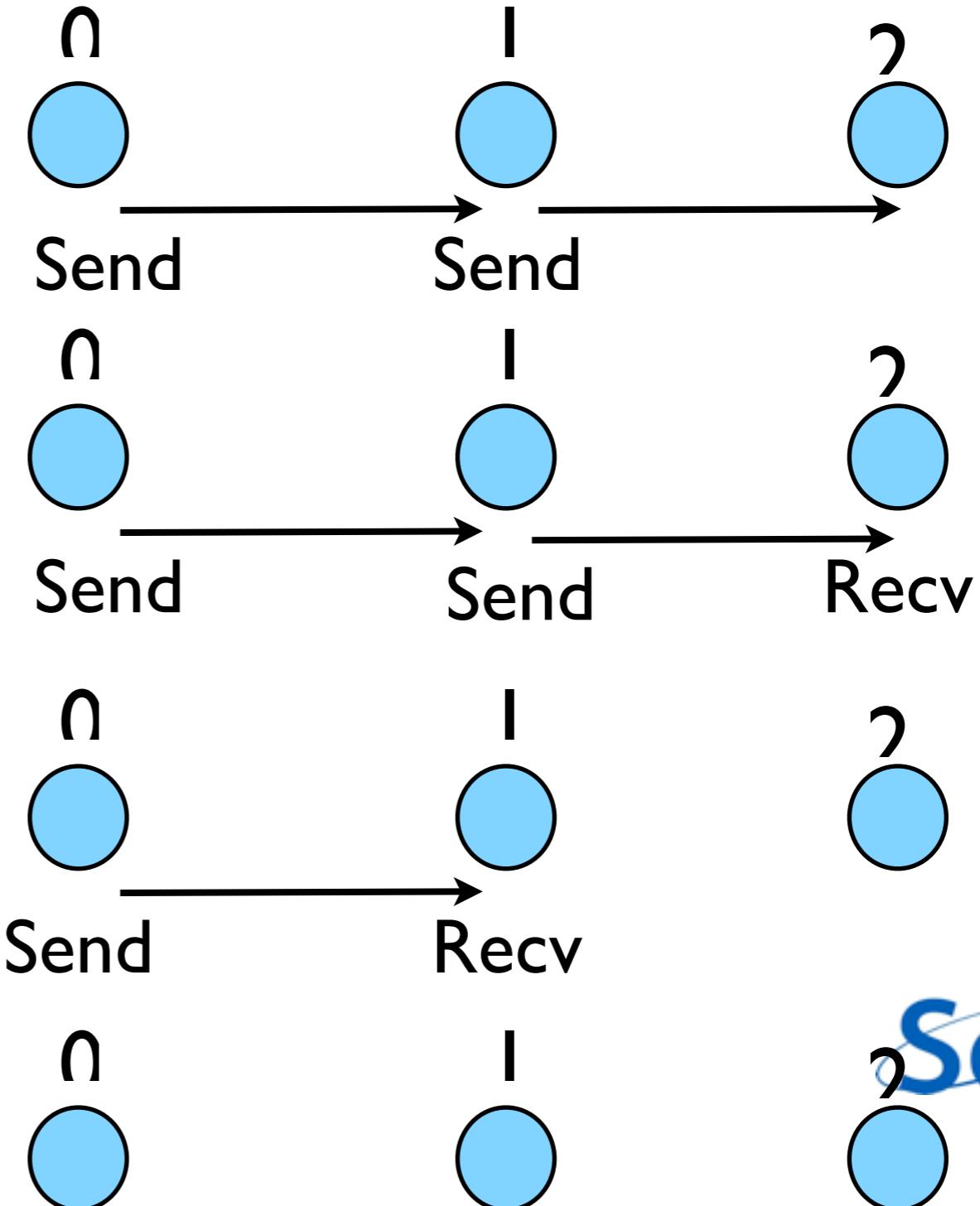


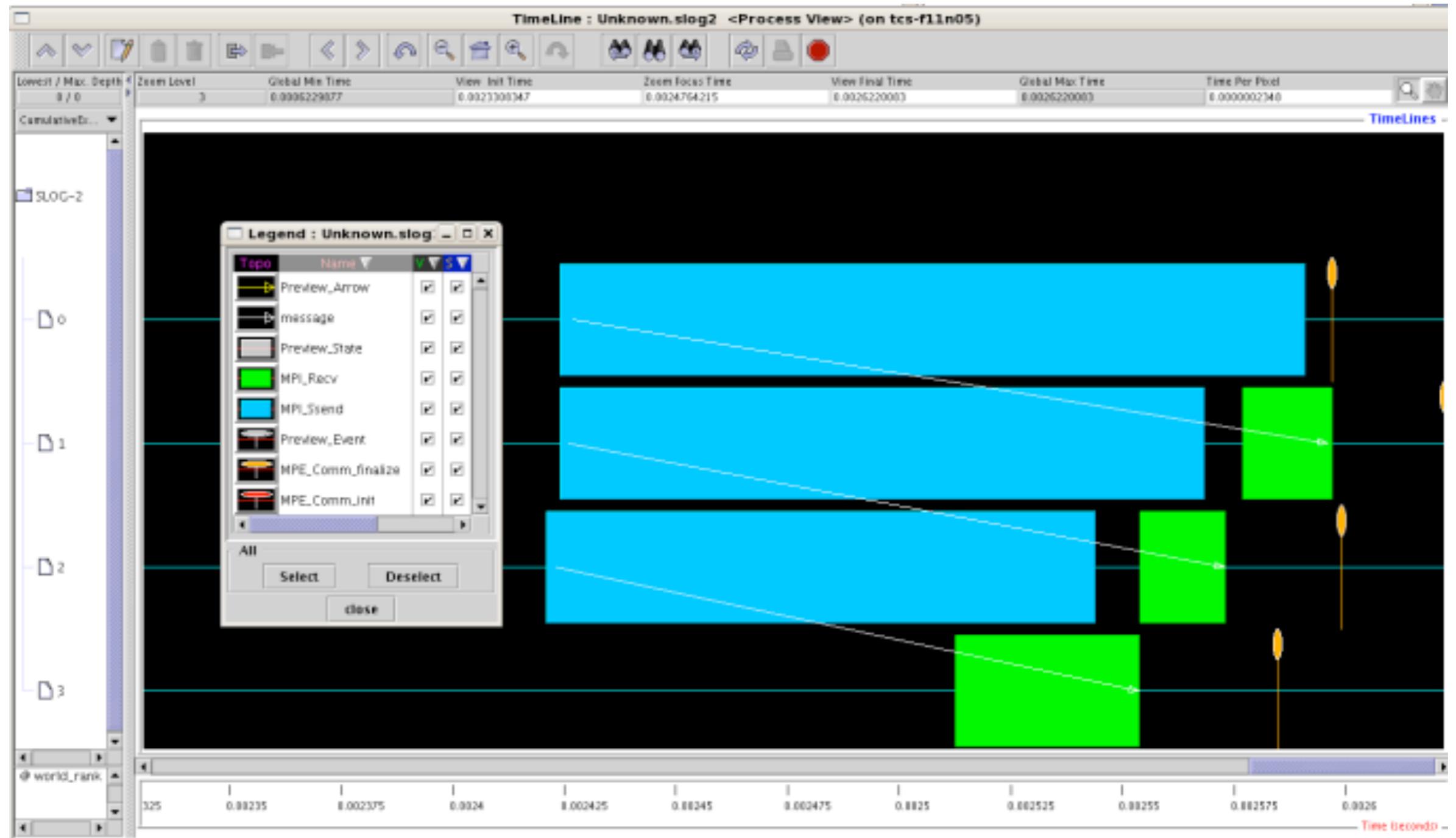
```

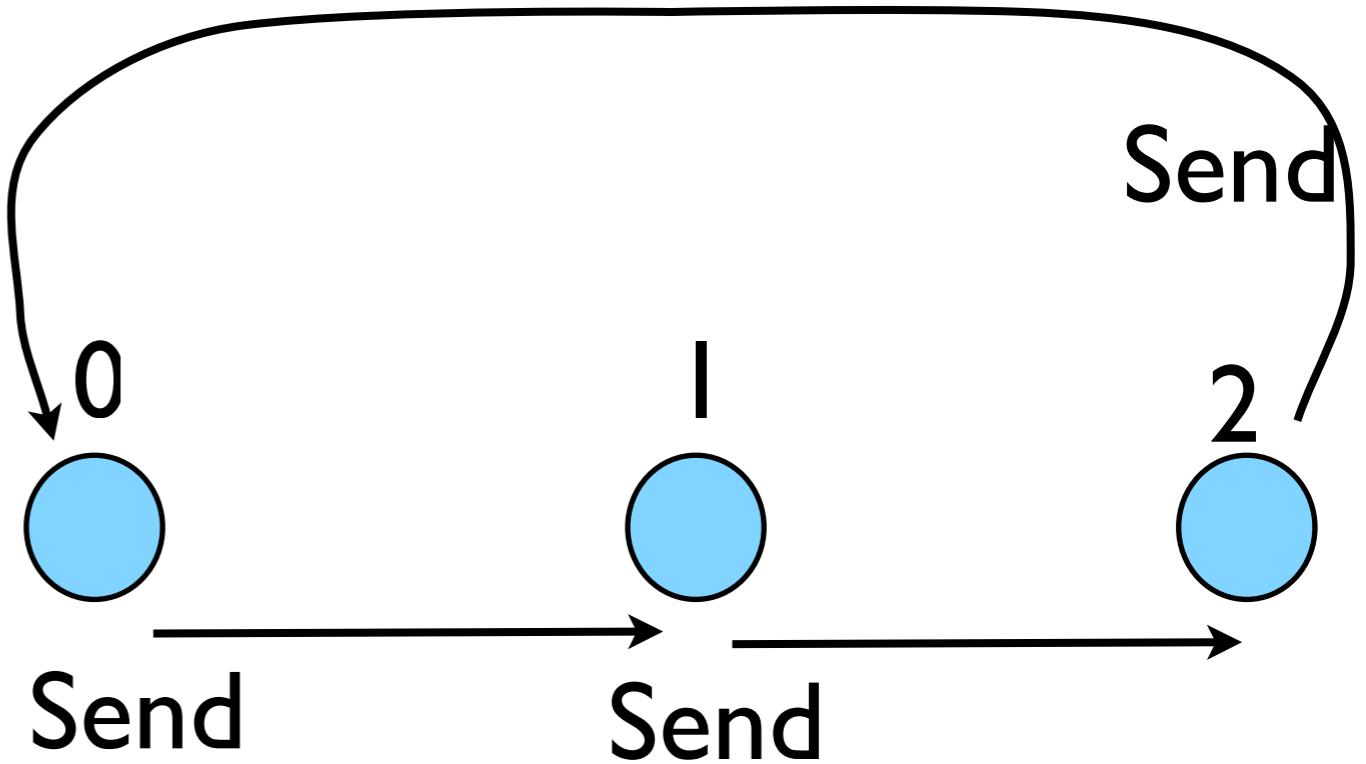
left = rank-1
if (left < 0) left = comsize-1
right = rank+1
if (right >= comsize) right = 0

call MPI_Ssend(msgsent, 1, MPI_DOUBLE_PRECISION, right, &
               tag, MPI_COMM_WORLD, ierr)
call MPI_Recv(msgrcvd, 1, MPI_DOUBLE_PRECISION, left, &
               tag, MPI_COMM_WORLD, status, ierr)

```







```

left = rank-1
if (left < 0) left = comsize-1
right = rank+1
if (right >= comsize) right = 0

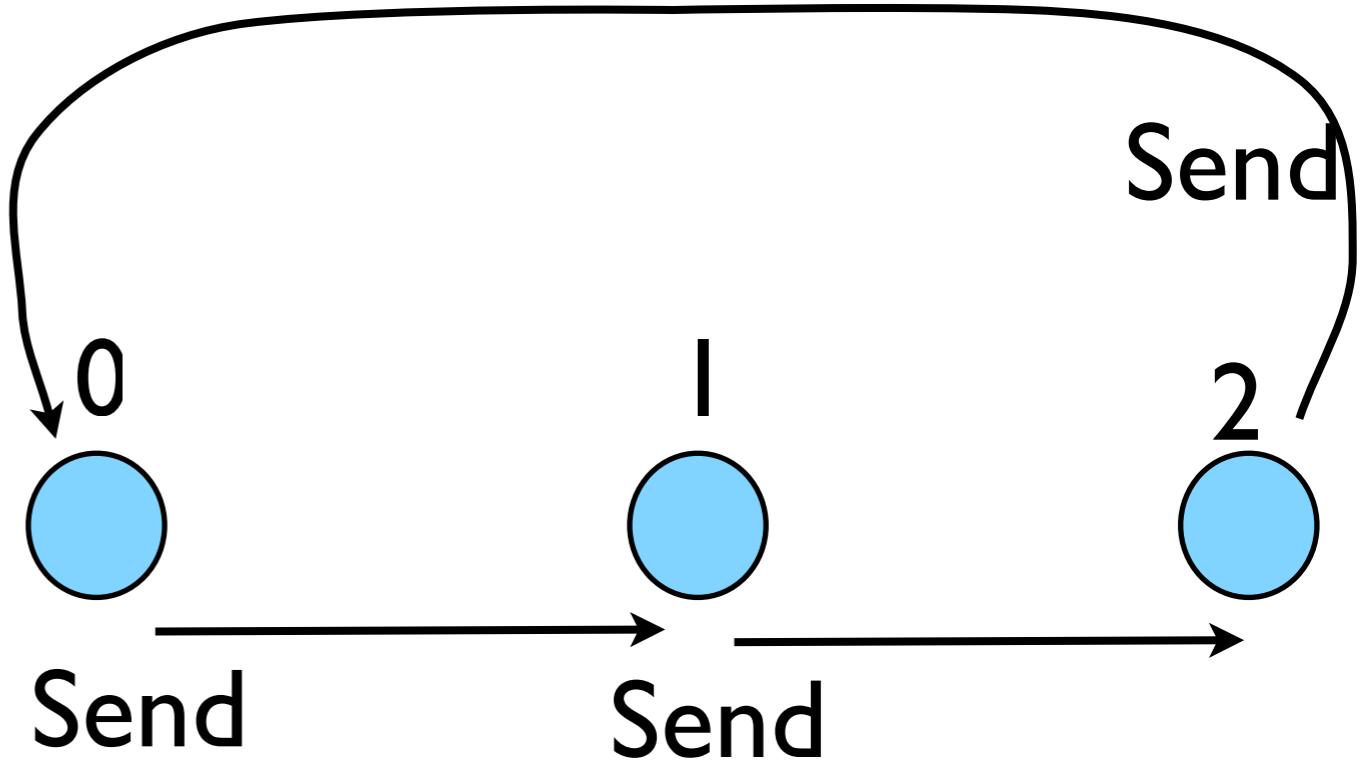
call MPI_Ssend(msgsent, 1, MPI_DOUBLE_PRECISION, right, &
              tag, MPI_COMM_WORLD, ierr)
call MPI_Recv(msgrcvd, 1, MPI_DOUBLE_PRECISION, left, &
              tag, MPI_COMM_WORLD, status, ierr)

```

0,1,2

# Deadlock

- A classic parallel bug
- Occurs when a cycle of tasks are for the others to finish.
- Whenever you see a closed cycle, you likely have (or risk) deadlock.



# Big MPI

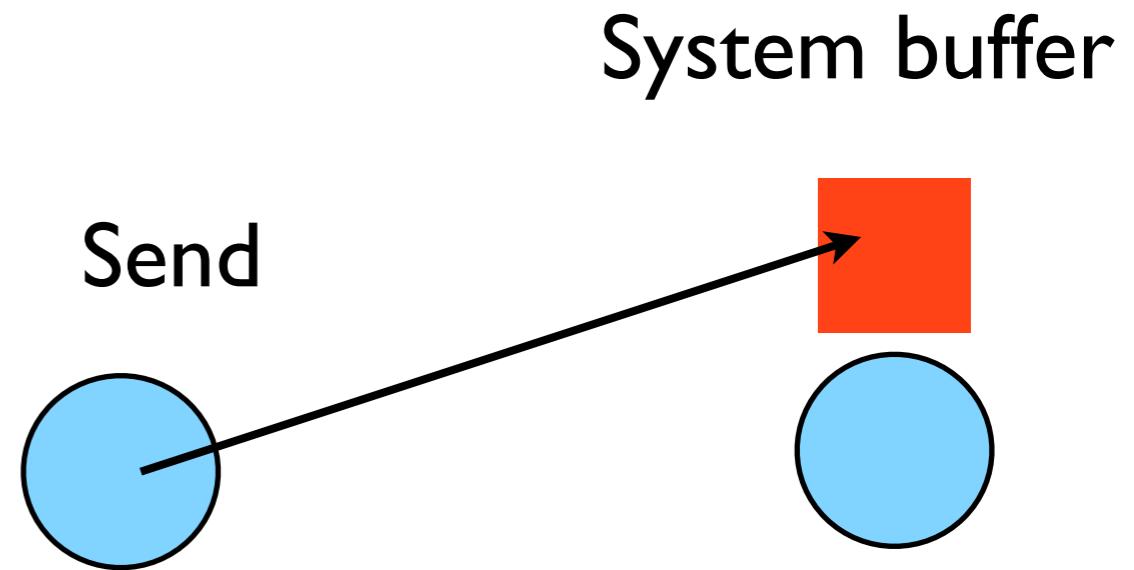
## Lesson #1

All sends and receives must be paired, **at time of sending**

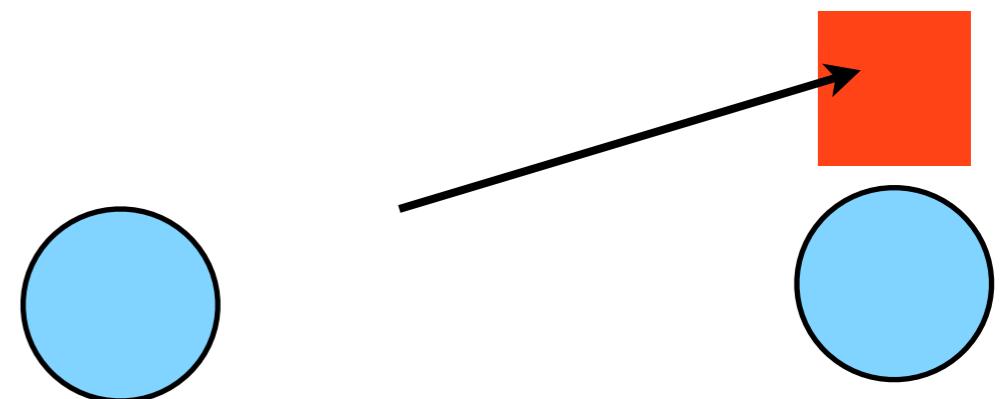
# Different versions of SEND

- SSEND: safe send; doesn't return until receive has started. Blocking, no buffering.
- SEND: Undefined. Blocking, probably buffering
- ISEND : Unblocking, no buffering
- IBSEND: Unblocking, buffering

## Buffering



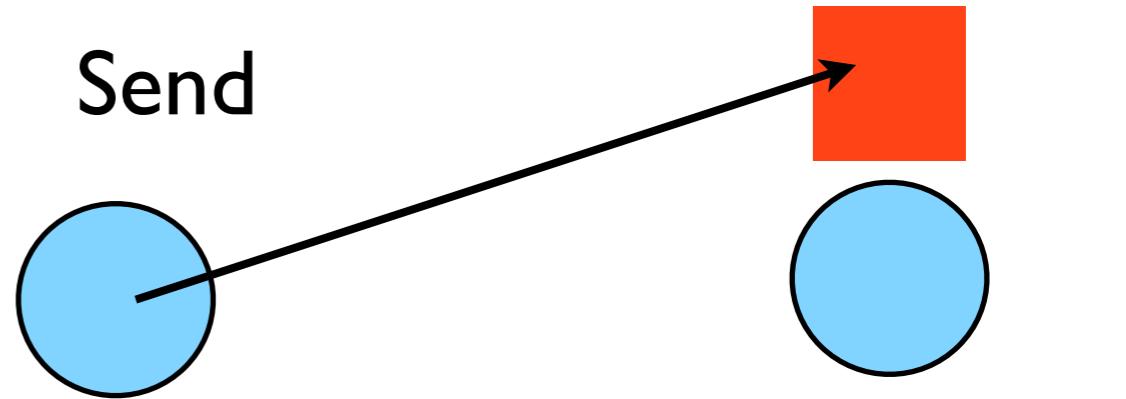
## (Non) Blocking



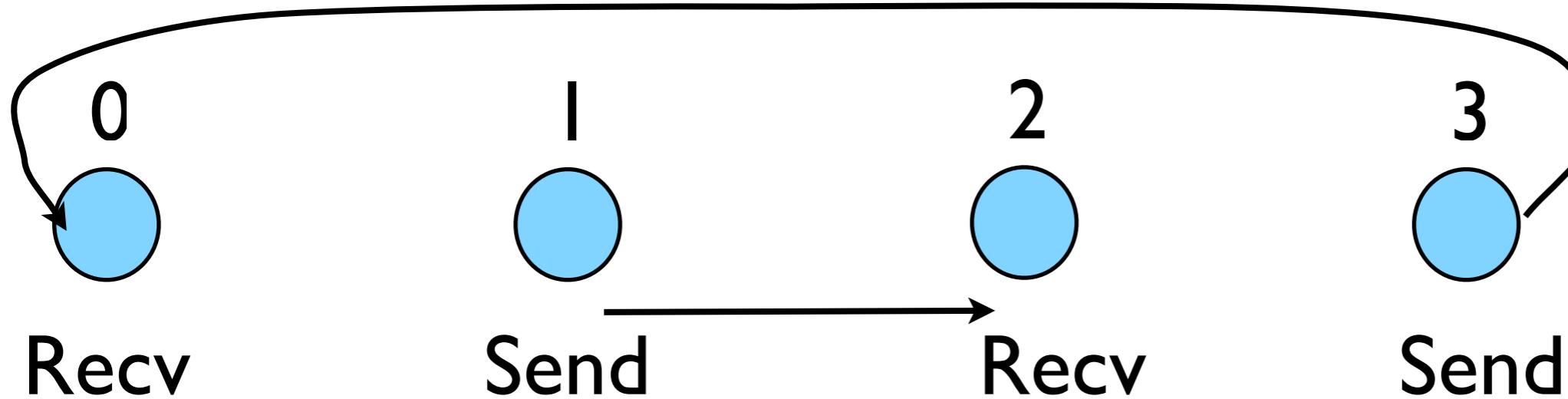
# Buffering is dangerous!

- Worst kind of danger: will usually work.
- Think voice mail; message sent, reader reads when ready
- But voice mail boxes do fill
- Message fails.
- Program fails/hangs mysteriously.
- (Can allocate your own buffers)

## Buffering



Without using new MPI  
routines, how can we fix  
this?



- First: evens send, odds receive
- Then: odds send, evens receive
- Will this work with an odd # of processes?
- How about 2? 1?

```

program fourthmessage
implicit none
include 'mpif.h'

integer :: ierr, rank, comsize
integer :: left, right
integer :: tag
integer :: status(MPI_STATUS_SIZE)
double precision :: msgsent, msgrcvd

call MPI_INIT(ierr)
call MPI_COMM_RANK(MPI_COMM_WORLD, rank, ierr)
call MPI_COMM_SIZE(MPI_COMM_WORLD, comsize, ierr)

left = rank-1
if (left < 0) left = comsize-1
right = rank+1
if (right >= comsize) right = 0

msgsent = rank*rank
msgrcvd = -999.
tag = 1

if (mod(rank,2) == 0) then
    call MPI_Ssend(msgsent, 1, MPI_DOUBLE_PRECISION, right, &
                  tag, MPI_COMM_WORLD, ierr)
    call MPI_Recv(msgrcvd, 1, MPI_DOUBLE_PRECISION, left, &
                  tag, MPI_COMM_WORLD, status, ierr)
else
    call MPI_Recv(msgrcvd, 1, MPI_DOUBLE_PRECISION, left, &
                  tag, MPI_COMM_WORLD, status, ierr)
    call MPI_Ssend(msgsent, 1, MPI_DOUBLE_PRECISION, right, &
                  tag, MPI_COMM_WORLD, ierr)
endif
print *, rank, 'Sent ', msgsent, 'and recv ', msgrcvd

call MPI_FINALIZE(ierr)
end program fourthmessage

```

Evens send first



Then odds



fourthmessage.f90

```

#include <stdio.h>
#include <mpi.h>

int main(int argc, char **argv) {
    int rank, size, ierr;
    int left, right;
    int tag=1;
    double msgsent, msgrcvd;
    MPI_Status rstatus;

    ierr = MPI_Init(&argc, &argv);
    ierr = MPI_Comm_size(MPI_COMM_WORLD, &size);
    ierr = MPI_Comm_rank(MPI_COMM_WORLD, &rank);

    left = rank - 1;
    if (left < 0) left = size-1;
    right = rank + 1;
    if (right == size) right = 0;

    msgsent = rank*rank;
    msgrcvd = -999;

    if (rank % 2 == 0) {
        ierr = MPI_Ssend(&msgsent, 1, MPI_DOUBLE, right,
                         tag, MPI_COMM_WORLD);
        ierr = MPI_Recv(&msgrcvd, 1, MPI_DOUBLE, left,
                         tag, MPI_COMM_WORLD, &rstatus);
    } else {
        ierr = MPI_Recv(&msgrcvd, 1, MPI_DOUBLE, left,
                         tag, MPI_COMM_WORLD, &rstatus);
        ierr = MPI_Ssend(&msgsent, 1, MPI_DOUBLE, right,
                         tag, MPI_COMM_WORLD);
    }

    printf("%d: Sent %lf and got %lf\n",
           rank, msgsent, msgrcvd);

    ierr = MPI_Finalize();
    return 0;
}

```

Events send first



Then odds



fourthmessage.c

# Something new: Sendrecv

- A blocking send and receive built in together
- Lets them happen simultaneously
- Can automatically pair the sends/recvs!
- dest, source does not have to be same; nor do types or size.

```
#include <stdio.h>
#include <mpi.h>

int main(int argc, char **argv) {
    int rank, size, ierr;
    int left, right;
    int tag=1;
    double msgsent, msgrcvd;
    MPI_Status rstatus;

    ierr = MPI_Init(&argc, &argv);
    ierr = MPI_Comm_size(MPI_COMM_WORLD, &size);
    ierr = MPI_Comm_rank(MPI_COMM_WORLD, &rank);

    left = rank - 1;
    if (left < 0) left = size-1;
    right = rank + 1;
    if (right == size) right = 0;

    msgsent = rank*rank;
    msgrcvd = -999;

    ierr = MPI_Sendrecv(&msgsent, 1, MPI_DOUBLE, right, tag,
                        &msgrcvd, 1, MPI_DOUBLE, left, tag,
                        MPI_COMM_WORLD, &rstatus);

    printf("%d: Sent %lf and got %lf\n",
           rank, msgsent, msgrcvd);

    ierr = MPI_Finalize();
    return 0;
}
```

# Something new: Sendrecv

- A blocking send and receive built in together
- Lets them happen simultaneously
- Can automatically pair the sends/recvs!
- dest, source does not have to be same; nor do types or size.

```
program fifthmessage
implicit none
include 'mpif.h'

integer :: ierr, rank, comsize
integer :: left, right
integer :: tag
integer :: status(MPI_STATUS_SIZE)
double precision :: msgsent, msgrcvd

call MPI_INIT(ierr)
call MPI_COMM_RANK(MPI_COMM_WORLD,rank,ierr)
call MPI_COMM_SIZE(MPI_COMM_WORLD,comsize,ierr)

left = rank-1
if (left < 0) left = comsize-1
right = rank+1
if (right >= comsize) right = 0

msgsent = rank*rank
msgrcvd = -999.
tag = 1

call MPI_Sendrecv(msgsent, 1, MPI_DOUBLE_PRECISION, right, tag, &
                  msgrcvd, 1, MPI_DOUBLE_PRECISION, left, tag, &
                  MPI_COMM_WORLD, status, ierr)
print *, rank, 'Sent ', msgsent, 'and recv ', msgrcvd

call MPI_FINALIZE(ierr)

end program fifthmessage
```

fifthmessage.f90 

# Sendrecv = Send + Recv

## C syntax

```
MPI_Status status;
```

Send Args

```
ierr = MPI_Sendrecv(sendptr, count, MPI_TYPE, destination, tag,  
recvptr, count, MPI_TYPE, source, tag,  
Communicator, &status);
```

Recv Args

## FORTRAN syntax

```
integer status(MPI_STATUS_SIZE)
```

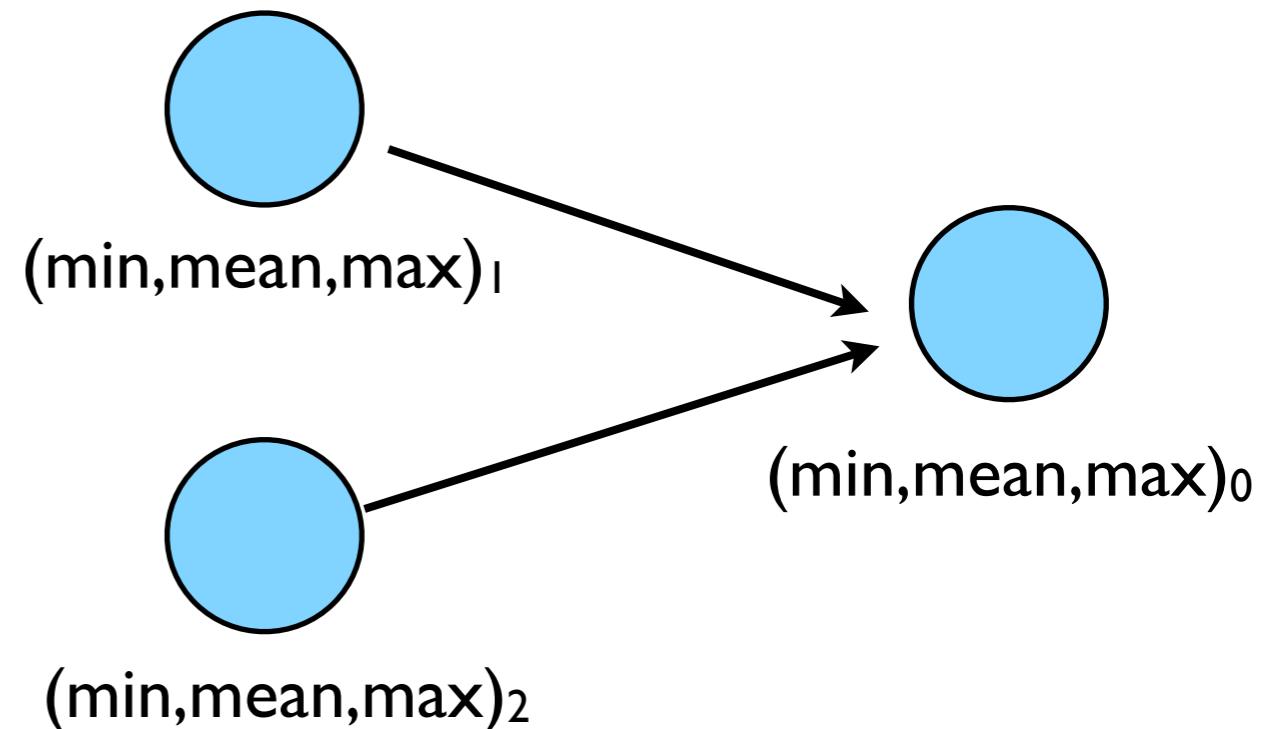
```
call MPI_SENDRECV(sendptr, count, MPI_TYPE, destination, tag,  
recvptr, count, MPI_TYPE, source, tag,  
Communicator, status, ierr)
```



Why are there two different tags/types/counts?

# Min, Mean, Max of numbers

- Lets try some code that calculates the min/mean/max of a bunch of random numbers -1..1. Should go to -1,0,+1 for large N.
- Each gets their partial results and sends it to some node, say node 0 (why node 0?)
- `~/mpi/mpi-intro/minmeanmax.{c,f90}`
- How to MPI it?



```
program randomdata
implicit none
integer,parameter :: nx=1500
real, allocatable :: dat(:)

integer :: i
real :: datamin, datamax, datamean

!! random data
!! 
allocate(dat(nx))
call random_seed(put=[(i,i=1,8)])
call random_number(dat)
dat = 2*dat - 1.

!! find min/mean/max
!! 
datamin = minval(dat)
datamax = maxval(dat)
datamean= (1.*sum(dat))/nx

deallocate(dat)

print *,'min/mean/max = ', datamin, datamean, datamax

return
end
```

```
/*
 * generate random data
 */

dat = (float *)malloc(nx * sizeof(float));
srand(0);
for (i=0;i<nx;i++) {
    dat[i] = 2*((float)rand() / RAND_MAX)-1.;
}

/*
 * find min/mean/max
 */

datamin = 1e+19;
datamax = -1e+19;
datamean = 0;

for (i=0;i<nx;i++) {
    if (dat[i] < datamin) datamin=dat[i];
    if (dat[i] > datamax) datamax=dat[i];
    datamean += dat[i];
}
datamean /= nx;
free(dat);

printf("Min/mean/max = %f,%f,%f\n", datamin,datamean,datamax);
```

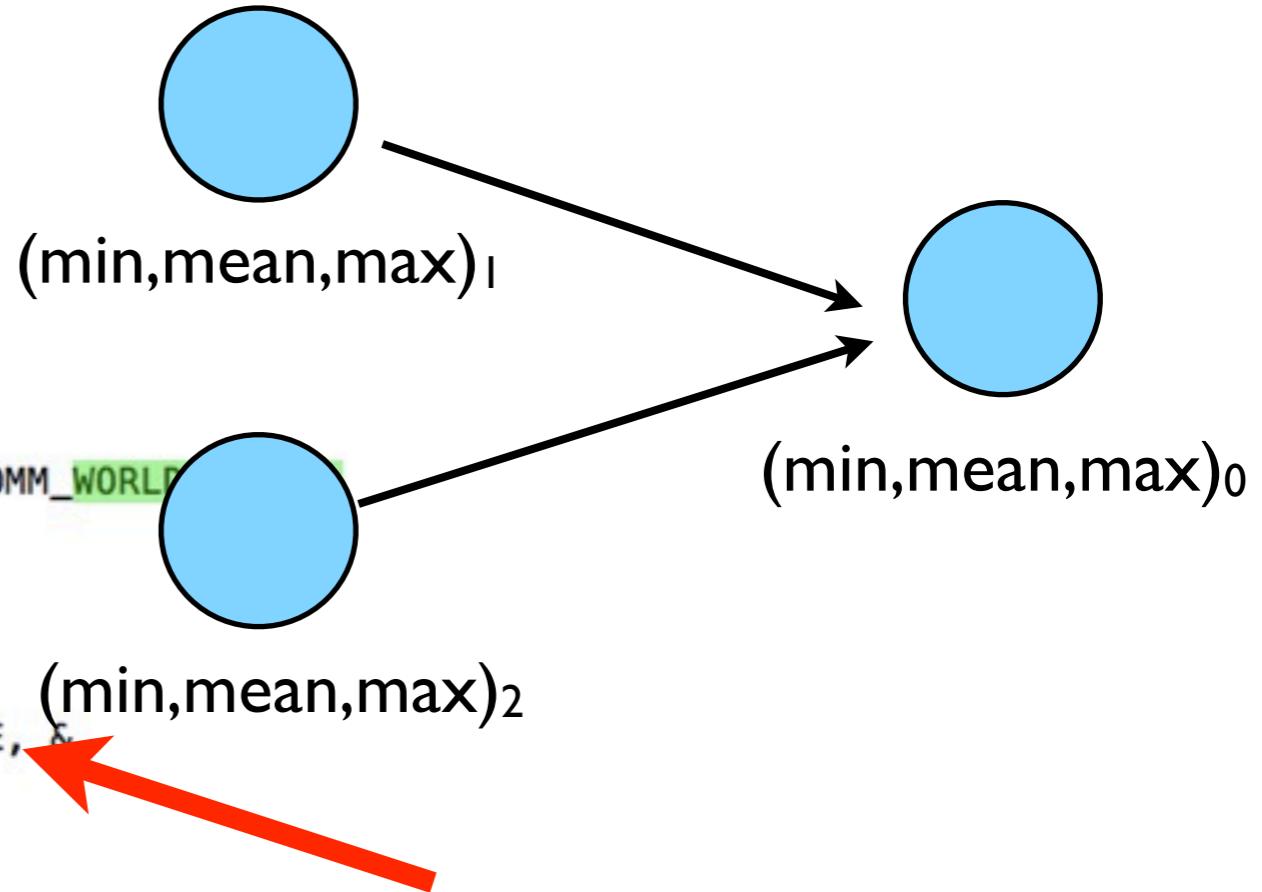
```

datamin = minval(dat)
datamax = maxval(dat)
datamean= (1.*sum(dat))/nx
deallocate(dat)

if (rank /= 0) then
    sendbuffer(1) = datamin
    sendbuffer(2) = datamean
    sendbuffer(3) = datamax
    call MPI_SSEND(sendbuffer, 3, MPI_REAL, 0, ourtag, MPI_COMM_WORLD)
else
    globmin = datamin
    globmax = datamax
    globmean = datamean
    do i=2,comsize
        call MPI_RECV(recvbuffer, 3, MPI_REAL, MPI_ANY_SOURCE, 6,
                      ourtag, MPI_COMM_WORLD, status, ierr)
        if (recvbuffer(1) < globmin) globmin=recvbuffer(1)
        if (recvbuffer(3) > globmax) globmax=recvbuffer(3)
        globmean = globmean + recvbuffer(2)
    enddo
    globmean = globmean / comsize
endif

print *,rank, ': min/mean/max = ', datamin, datamean, datamax

```



Q: are these sends/recvd adequately paired?

minmeanmax-mpi.f90

```

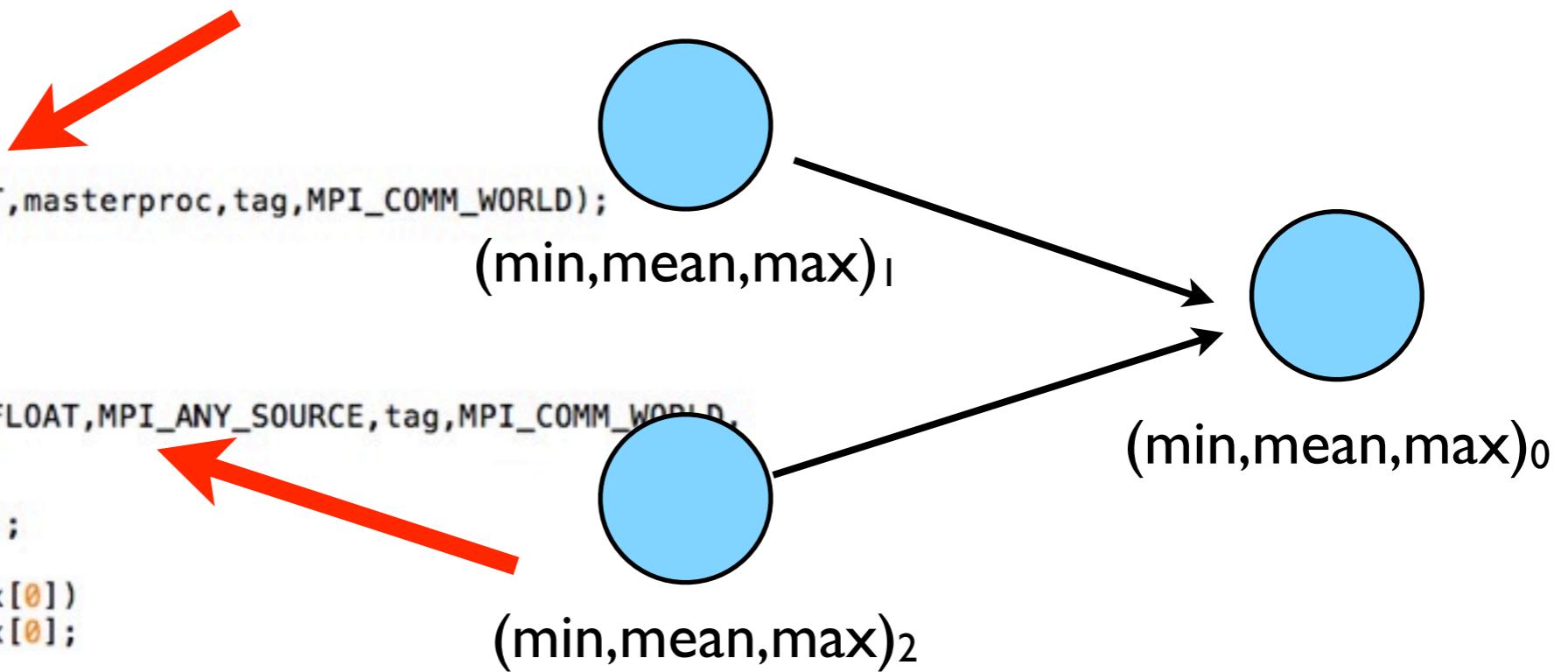
if (rank != masterproc) {
    ierr = MPI_Ssend(minmeanmax, 3, MPI_FLOAT, masterproc, tag, MPI_COMM_WORLD);
} else {
    globminmeanmax[0] = datamin;
    globminmeanmax[2] = datamax;
    globminmeanmax[1] = datamean;
    for (i=1;i<size-1;i++) {
        ierr = MPI_Recv(minmeanmax, 3, MPI_FLOAT, MPI_ANY_SOURCE, tag, MPI_COMM_WORLD,
                        &status);

        globminmeanmax[1] += minmeanmax[1];

        if (minmeanmax[0] < globminmeanmax[0])
            globminmeanmax[0] = minmeanmax[0];

        if (minmeanmax[2] > globminmeanmax[2])
            globminmeanmax[2] = minmeanmax[2];
    }
    globminmeanmax[1] /= size;
    printf("Min/mean/max = %f,%f,%f\n", globminmeanmax[0],
           globminmeanmax[1],globminmeanmax[2]);
}

```



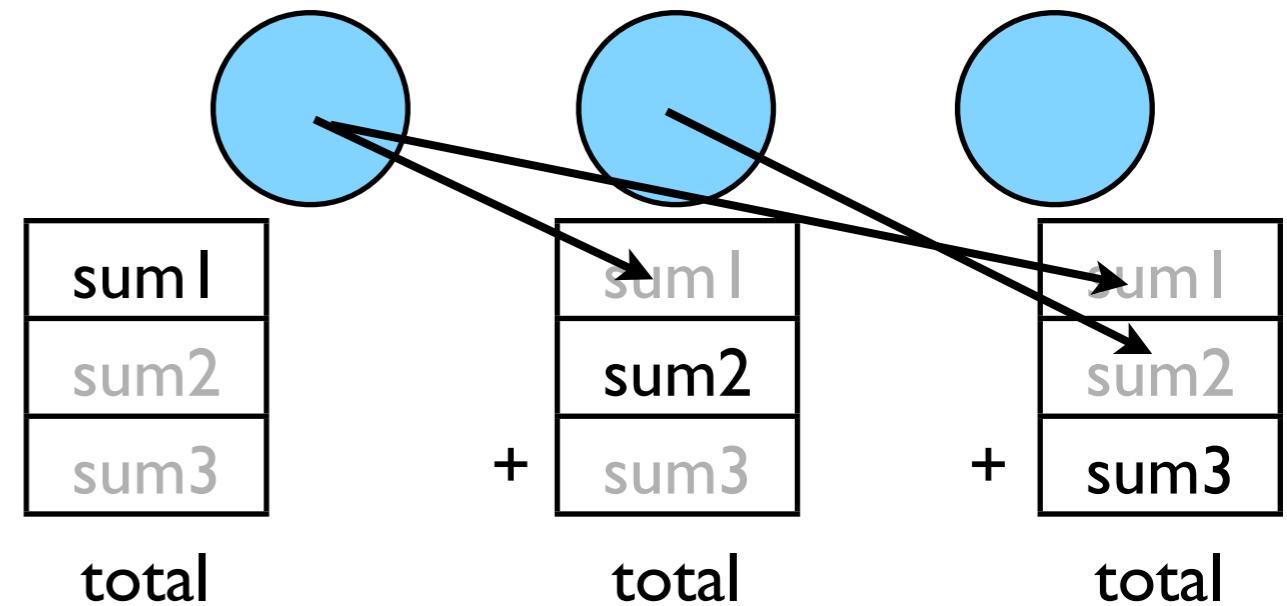
Q: are these sends/recvd adequately paired?

minmeanmax-mpi.c

# Inefficient!

- Requires  $(P-1)$  messages,  
 $2(P-1)$  if everyone then needs +  
to get the answer.

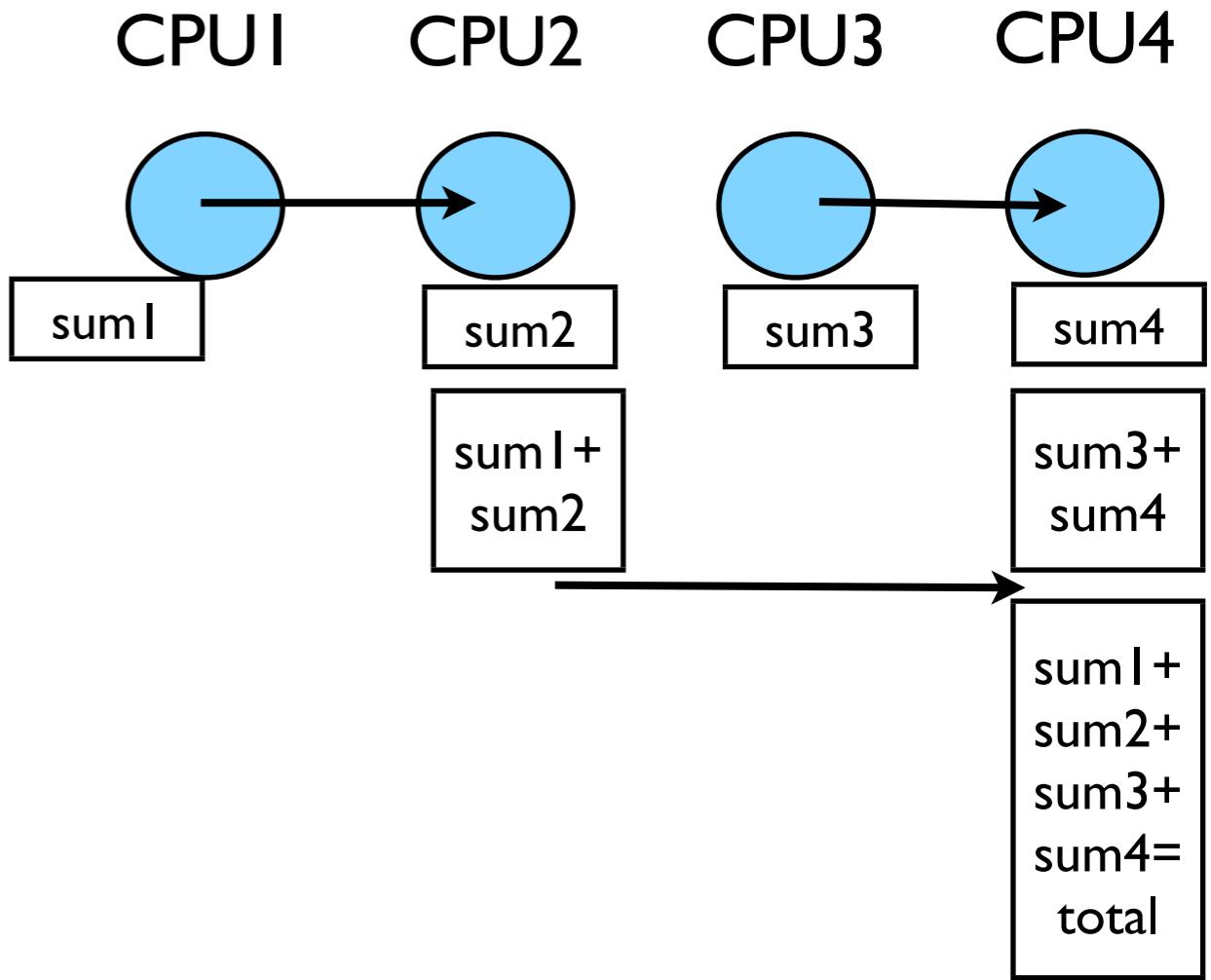
CPU1   CPU2   CPU3



# Better Summing

- Pairs of processors; send partial sums
- Max messages received  $\log_2(P)$
- Can repeat to send total back

$$T_{\text{comm}} = 2 \log_2(P) C_{\text{comm}}$$



Reduction; works for  
a variety of operators  
(+,\* ,min,max...)

```

print *,rank,: min/mean/max = ', datamin, datamean, datamax
! combine data
!
call MPI_ALLREDUCE(datamin, globmin, 1, MPI_REAL, MPI_MIN, &
MPI_COMM_WORLD, ierr)
!
! to just send to task 0:
call MPI_REDUCE(datamin, globmin, 1, MPI_REAL, MPI_MIN,
& 0, MPI_COMM_WORLD, ierr)
!
call MPI_ALLREDUCE(datamax, globmax, 1, MPI_REAL, MPI_MAX, &
MPI_COMM_WORLD, ierr)
call MPI_ALLREDUCE(datamean, globmean, 1, MPI_REAL, MPI_SUM, &
MPI_COMM_WORLD, ierr)
globmean = globmean/comsize
if (rank == 0) then
  print *, rank,: Global min/mean/max=',globmin,globmean,globmax
endif

```

## MPI\_Reduce and MPI\_Allreduce

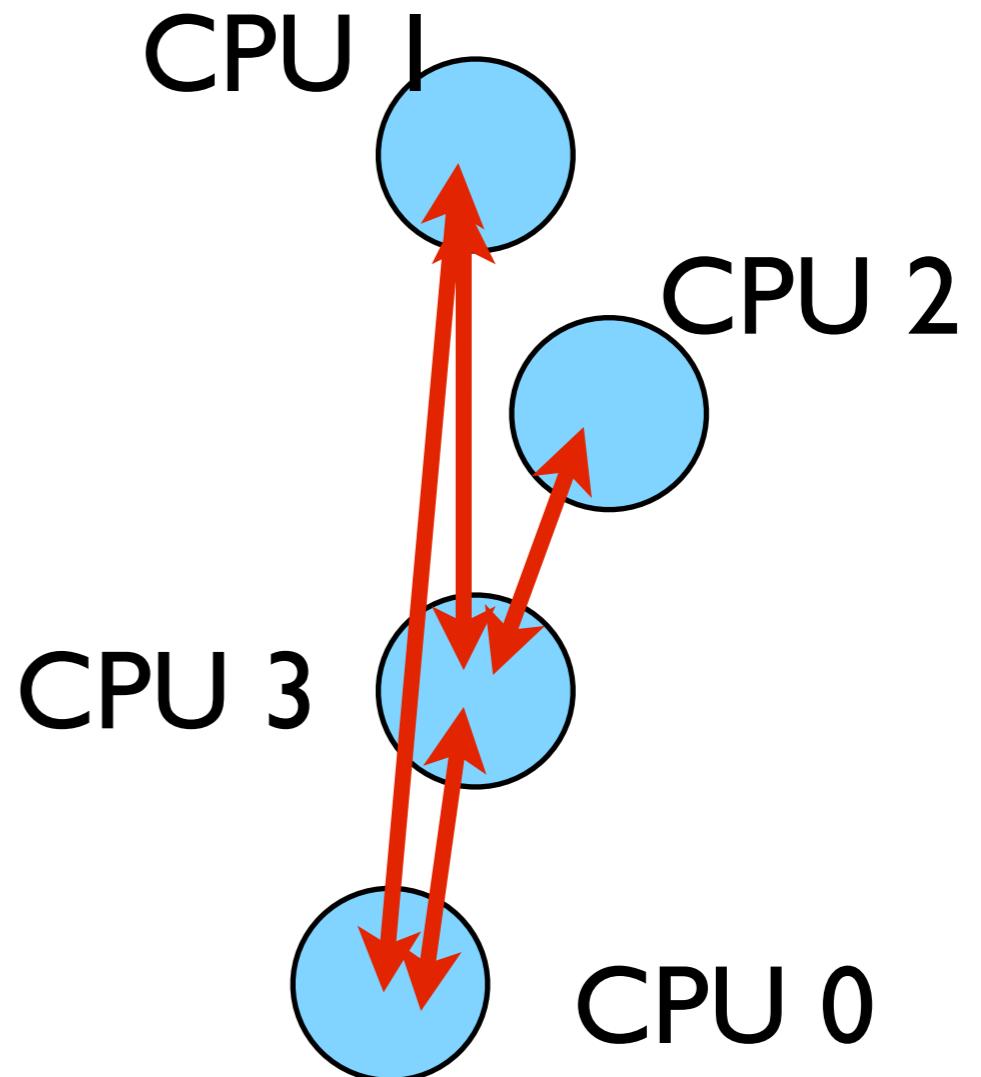
Performs a reduction  
and sends answer to  
one PE (Reduce)  
or all PEs (Allreduce)

minmeanmax-allreduce.f

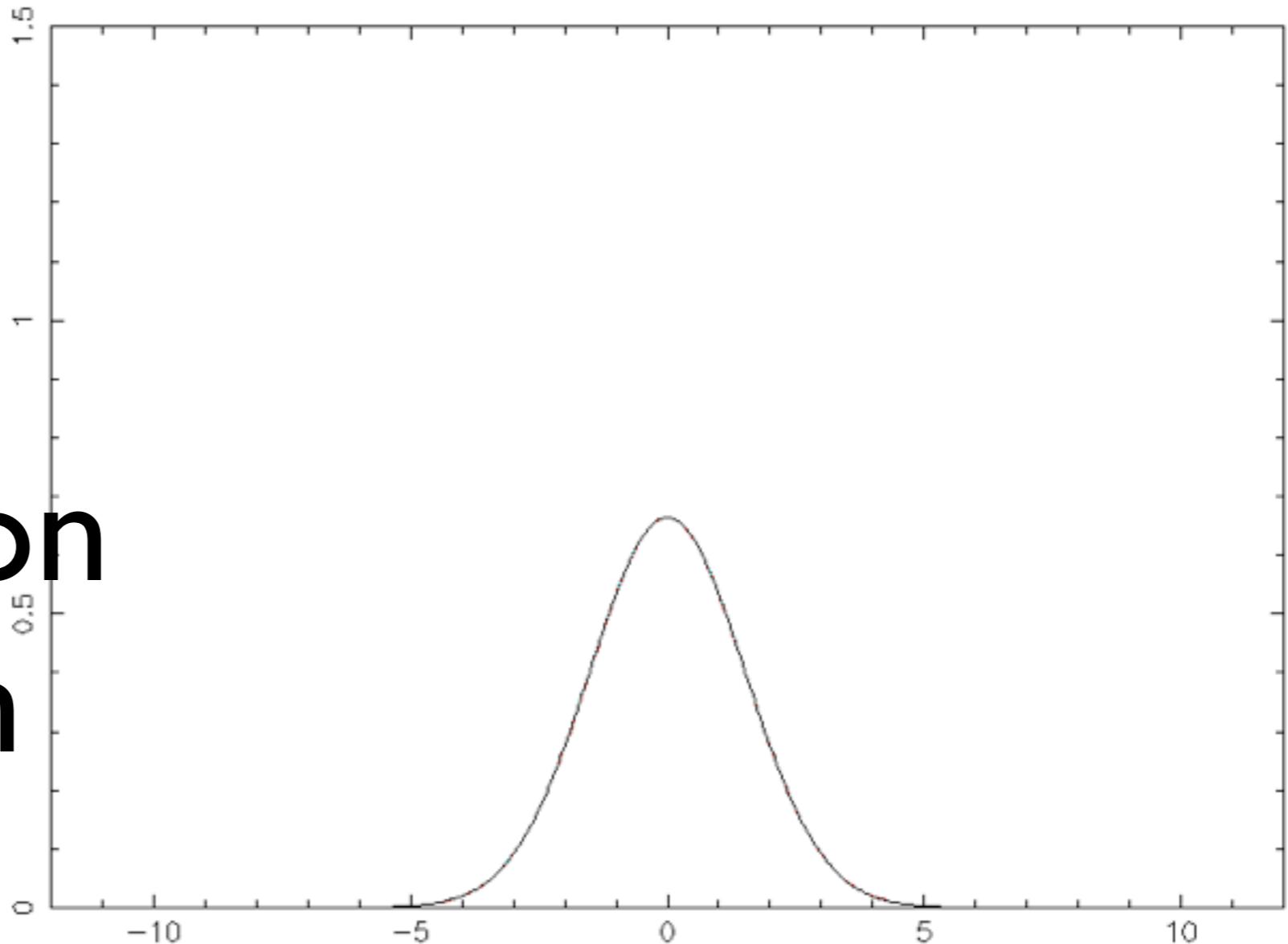


# Collective Operations

- As opposed to the pairwise messages we've seen
- **All** processes in the communicator must participate
- Cannot proceed until all have participated
- Don't necessarily know what goes on 'under the hood'



# 1d diffusion equation

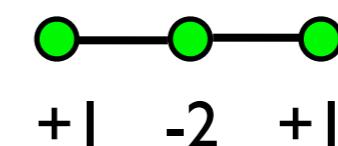
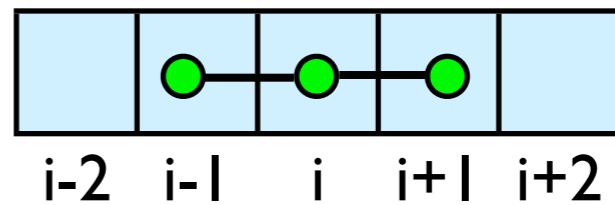


```
cd mpi/diffusion .
make diffusionf or make diffusionc
./diffusionf or ./diffusionc
```

# Discretizing Derivatives

- Done by finite differencing the discretized values
- Implicitly or explicitly involves interpolating data and taking derivative of the interpolant
- More accuracy - larger ‘stencils’

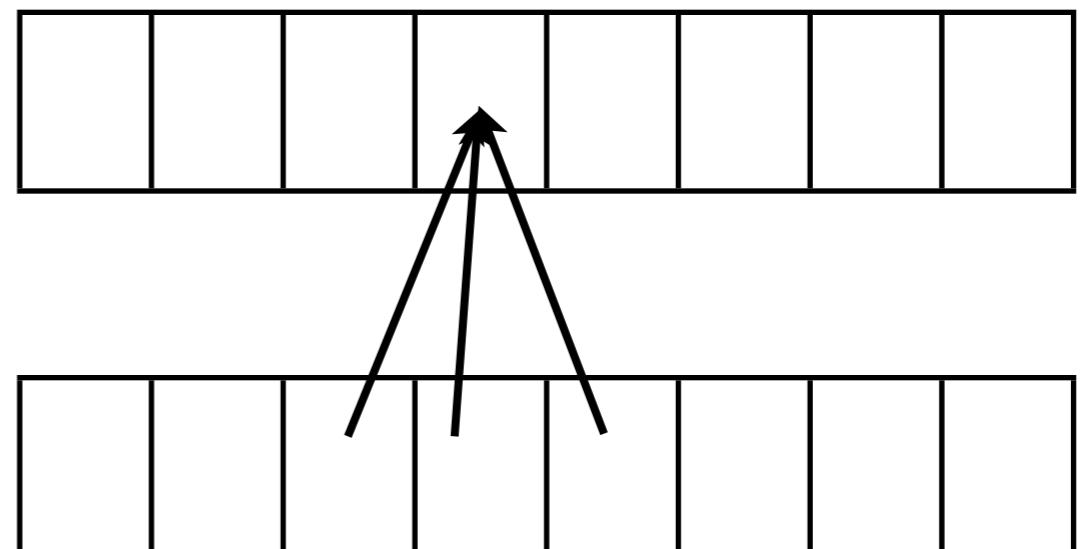
$$\left. \frac{d^2 Q}{dx^2} \right|_i \approx \frac{Q_{i+1} - 2Q_i + Q_{i-1}}{\Delta x^2}$$



# Diffusion Equation

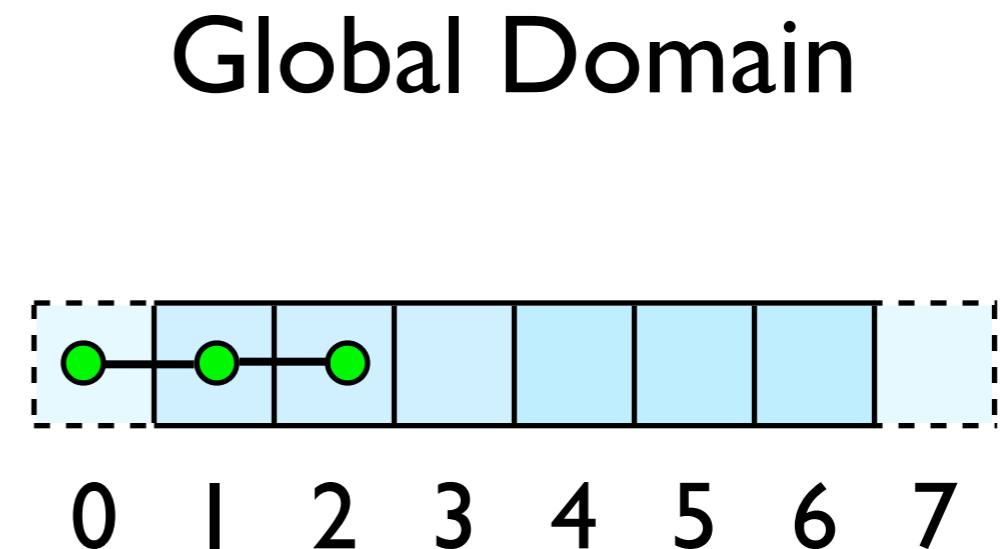
- Simple 1d PDE
- Each timestep, new data for  $T[i]$  requires old data for  $T[i+1], T[i], T[i-1]$

$$\begin{aligned}\frac{\partial T}{\partial t} &= D \frac{\partial^2 T}{\partial x^2} \\ \frac{\partial T_i^{(n)}}{\partial t} &\approx \frac{T_i^{(n)} + T_i^{(n-1)}}{\Delta t} \\ \frac{\partial T_i^{(n)}}{\partial x} &\approx \frac{T_{i+1}^{(n)} - 2T_i^{(n)} + T_{i-1}^{(n)}}{\Delta x^2} \\ T_i^{(n+1)} &\approx T_i^{(n)} + \frac{D\Delta t}{\Delta x^2} \left( T_{i+1}^{(n)} - 2T_i^{(n)} + T_{i-1}^{(n)} \right)\end{aligned}$$



# Guardcells

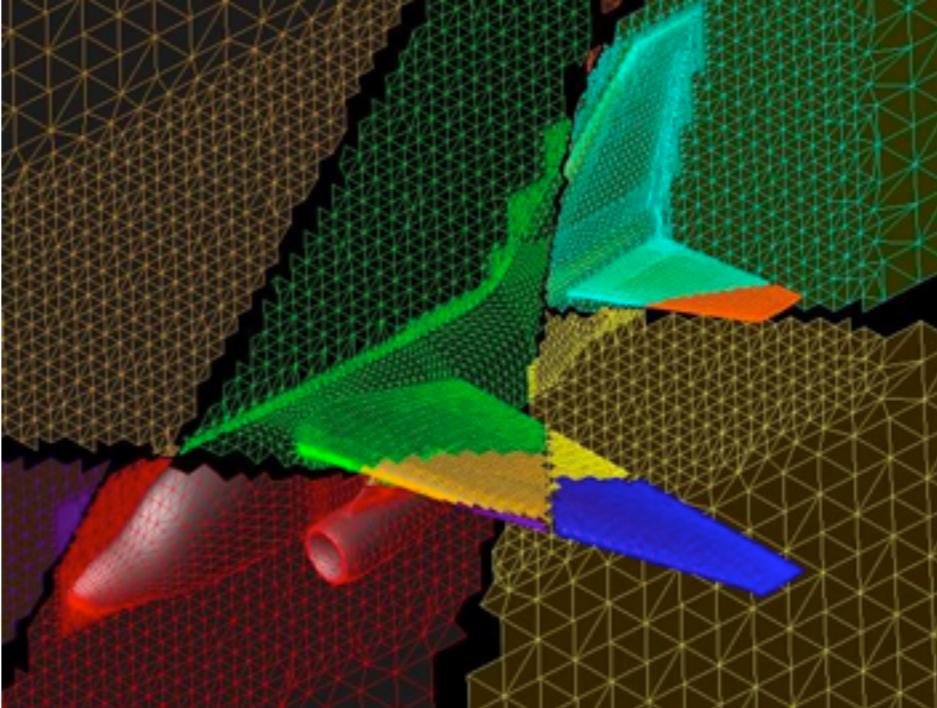
- How to deal with boundaries?
- Because stencil juts out, need information on cells beyond those you are updating
- Pad domain with ‘guard cells’ so that stencil works even for the first point in domain
- Fill guard cells with values such that the required boundary conditions are met



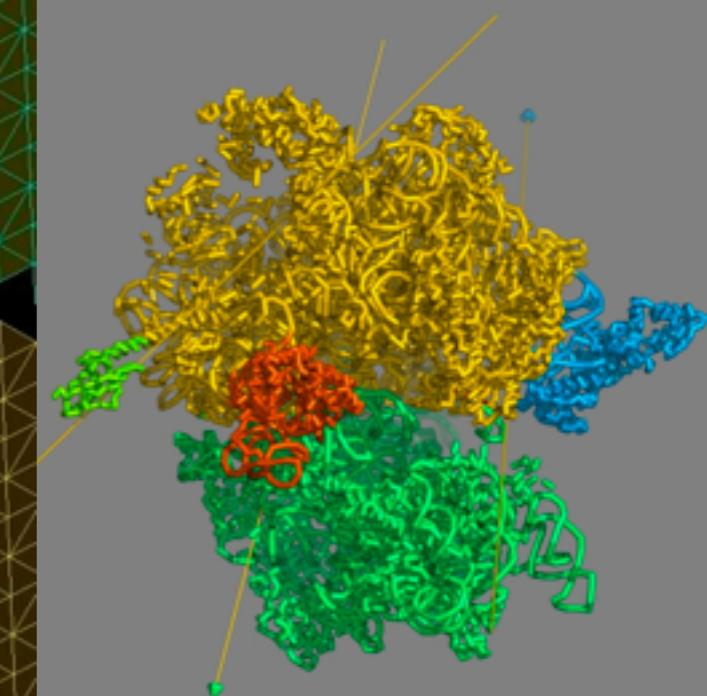
$ng = 1$   
loop from  $ng, N - 2 ng$

# Domain Decomposition

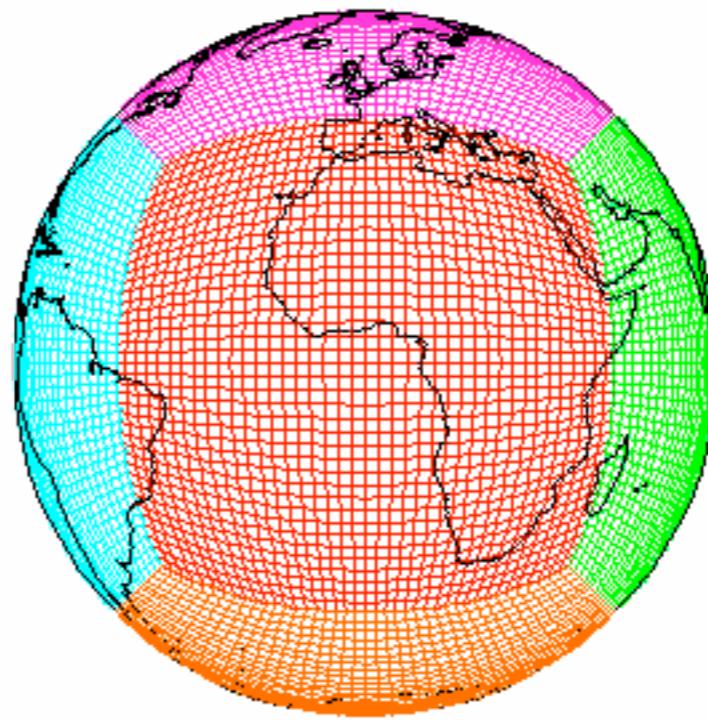
- A very common approach to parallelizing on distributed memory computers
- Maintain Locality; need local data mostly, this means only surface data needs to be sent between processes.



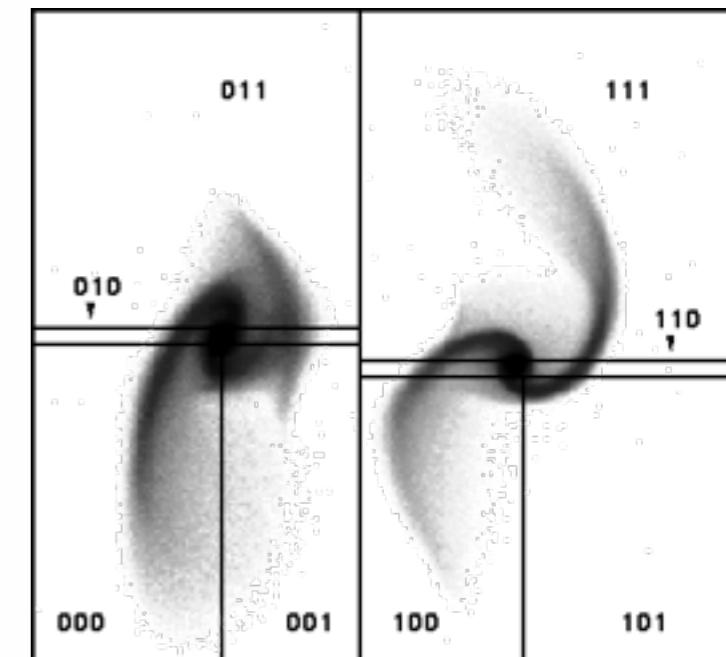
[http://adg.stanford.edu/aa241  
/design/compaero.html](http://adg.stanford.edu/aa241/design/compaero.html)



[http://www.uea.ac.uk/cmp/research/cmpbio/  
Protein+Dynamics,+Structure+and+Function](http://www.uea.ac.uk/cmp/research/cmpbio/Protein+Dynamics,+Structure+and+Function)



[http://sivo.gsfc.nasa.gov  
/cubedsphere\\_comp.html](http://sivo.gsfc.nasa.gov/cubedsphere_comp.html)



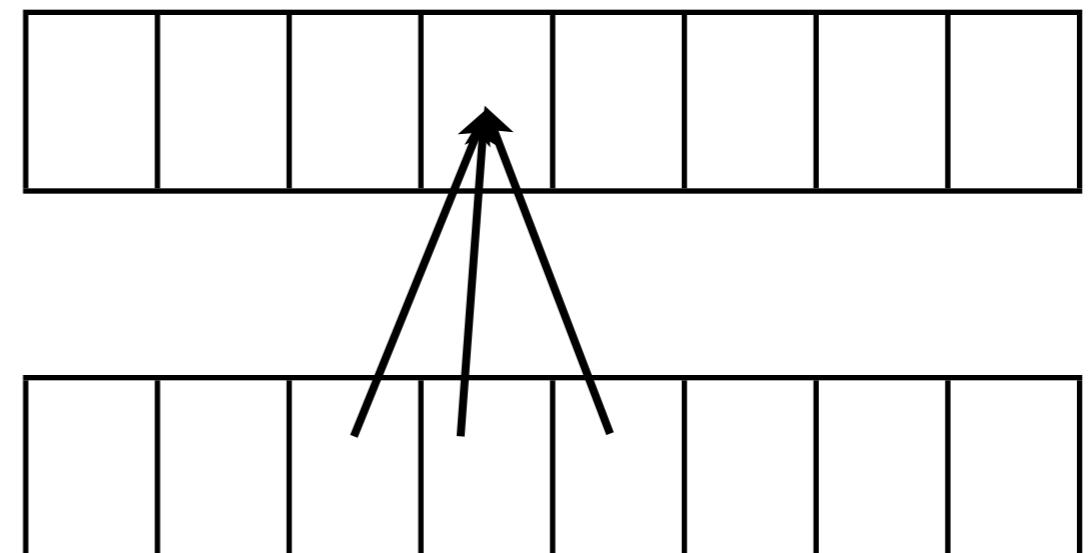
[http://www.cita.utoronto.ca/~dubinski  
/treecode/node8.html](http://www.cita.utoronto.ca/~dubinski/treecode/node8.html)

**SciNet**

# Implement a diffusion equation in MPI

- Need one neighboring number per neighbor per timestep

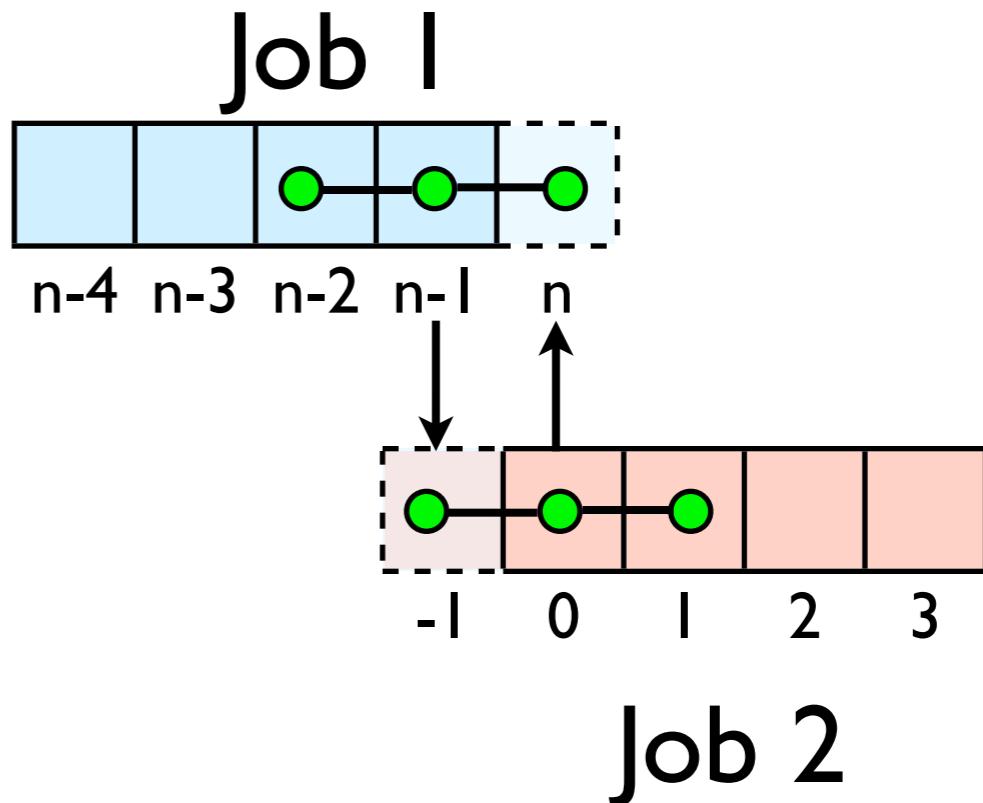
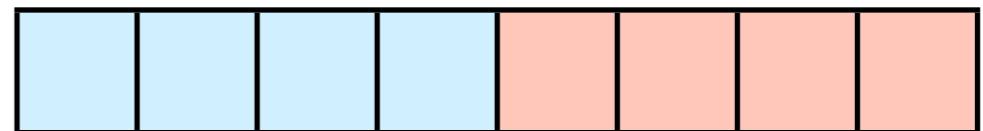
$$\frac{dT}{dt} = D \frac{d^2T}{dx^2}$$
$$T_i^{n+1} = T_i^n + \frac{D\Delta t}{\Delta x^2} (T_{i+1}^n - 2T_i^n + T_{i-1}^n)$$

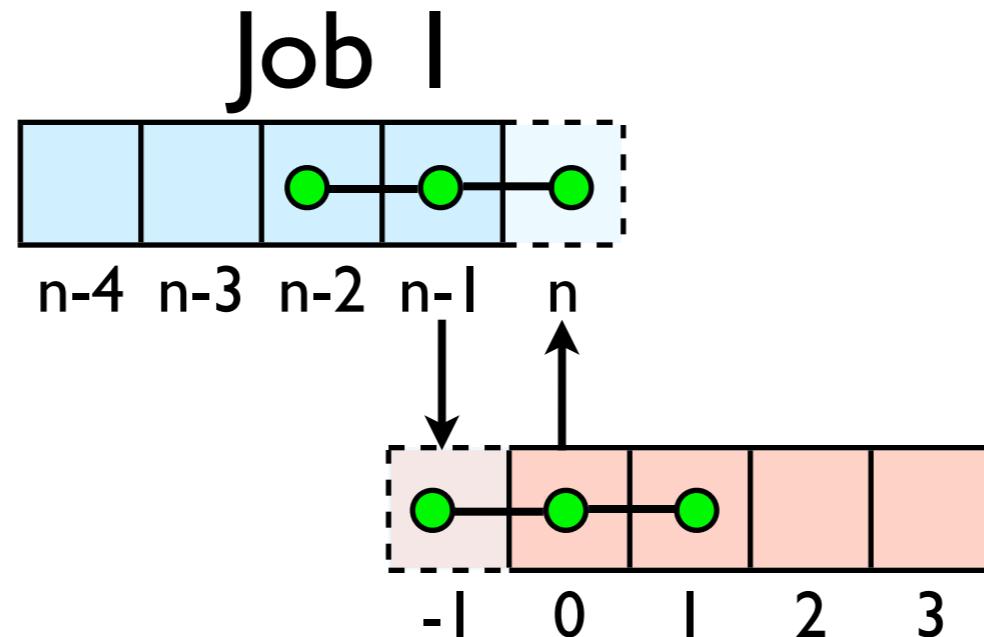


# Guardcells

- Works for parallel decomposition!
- Job 1 needs info on Job 2's 0th zone, Job 2 needs info on Job 1's last zone
- Pad array with ‘guardcells’ and fill them with the info from the appropriate node by message passing or shared memory
- Hydro code: need guardcells 2 deep

## Global Domain





- Do computation
- guardcell exchange: each cell has to do 2 sendrecvs
  - its rightmost cell with neighbors leftmost
  - its leftmost cell with neighbors rightmost
  - Everyone do right-filling first, then left-filling (say)
  - For simplicity, start with periodic BCs
  - then (re-)implement fixed-temperature BCs; temperature in first, last zones are fixed

# Hands-on: MPI diffusion

- cp diffusionf.f90 diffusionf-mpi.f90 or
- cp diffusionc.c diffusionc-mpi.c or
- Make an MPI-ed version of diffusion equation
- (Build: make diffusionf-mpi or make diffusionc-mpi)
- Test on 1..8 procs

- add standard MPI calls: init, finalize, comm\_size, comm\_rank
- Figure out how many points PE is responsible for ( $\sim \text{totpoints}/\text{size}$ )
- Figure out neighbors
- Start at 1, but end at  $\text{totpoints}/\text{size}$
- At end of step, exchange guardcells; use sendrecv
- Get total error

## C syntax

```
MPI_Status status;

ierr = MPI_Init(&argc, &argv);
ierr = MPI_Comm_{size,rank}(Communicator, &{size,rank});
ierr = MPI_Send(sendptr, count, MPI_TYPE, destination,
                tag, Communicator);
ierr = MPI_Recv(recvptr, count, MPI_TYPE, source, tag,
                Communicator, &status);
ierr = MPI_Sendrecv(sendptr, count, MPI_TYPE, destination,tag,
                    recvptr, count, MPI_TYPE, source, tag,
                    Communicator, &status);
ierr = MPI_Allreduce(&mydata, &globaldata, count, MPI_TYPE,
                     MPI_OP, Communicator);
```

Communicator -> MPI\_COMM\_WORLD

MPI\_Type -> MPI\_FLOAT, MPI\_DOUBLE, MPI\_INT, MPI\_CHAR...

MPI\_OP -> MPI\_SUM, MPI\_MIN, MPI\_MAX,...

## FORTRAN syntax

```
integer status(MPI_STATUS_SIZE)

call MPI_INIT(ierr)
call MPI_COMM_{SIZE,RANK}(Communicator, {size,rank},ierr)
call MPI_SSEND(sendarr, count, MPI_TYPE, destination,
               tag, Communicator)
call MPI_RECV(rcvvar, count, MPI_TYPE, destination,tag,
               Communicator, status, ierr)
call MPI_SENDRECV(sendptr, count, MPI_TYPE, destination,tag,
                  recvptr, count, MPI_TYPE, source, tag,
                  Communicator, status, ierr)
call MPI_ALLREDUCE(&mydata, &globaldata, count, MPI_TYPE,
                  MPI_OP, Communicator, ierr)
```

Communicator -> MPI\_COMM\_WORLD

MPI\_Type -> MPI\_REAL, MPI\_DOUBLE\_PRECISION,  
 MPI\_INTEGER, MPI\_CHARACTER

MPI\_OP -> MPI\_SUM, MPI\_MIN, MPI\_MAX, ...

# **Non-blocking communications**

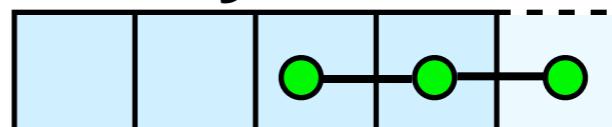
# Diffusion: Had to wait for communications to compute

- Could not compute end points without guardcell data
- All work halted while all communications occurred
- Significant parallel overhead

Global Domain



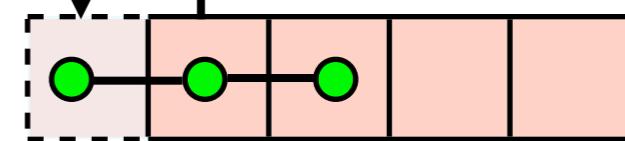
Job 1



$n-4 \quad n-3 \quad n-2 \quad n-1 \quad n$

$-1 \quad 0 \quad 1 \quad 2 \quad 3$

Job 2

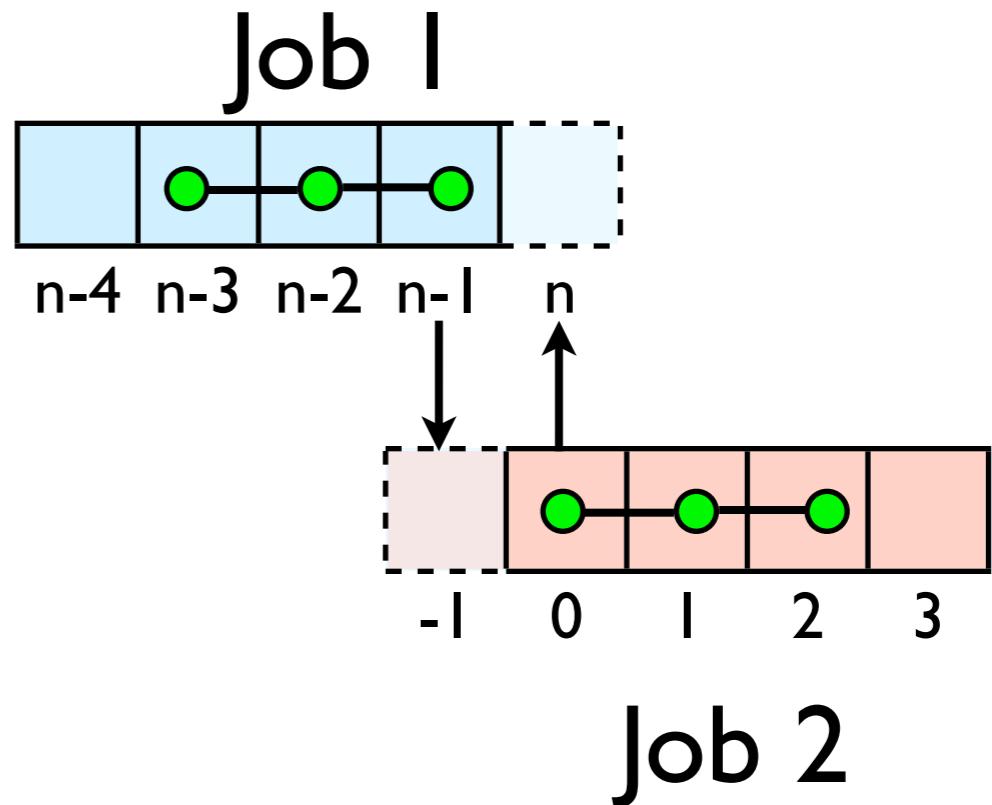


# Diffusion: Had to wait?

## Global Domain

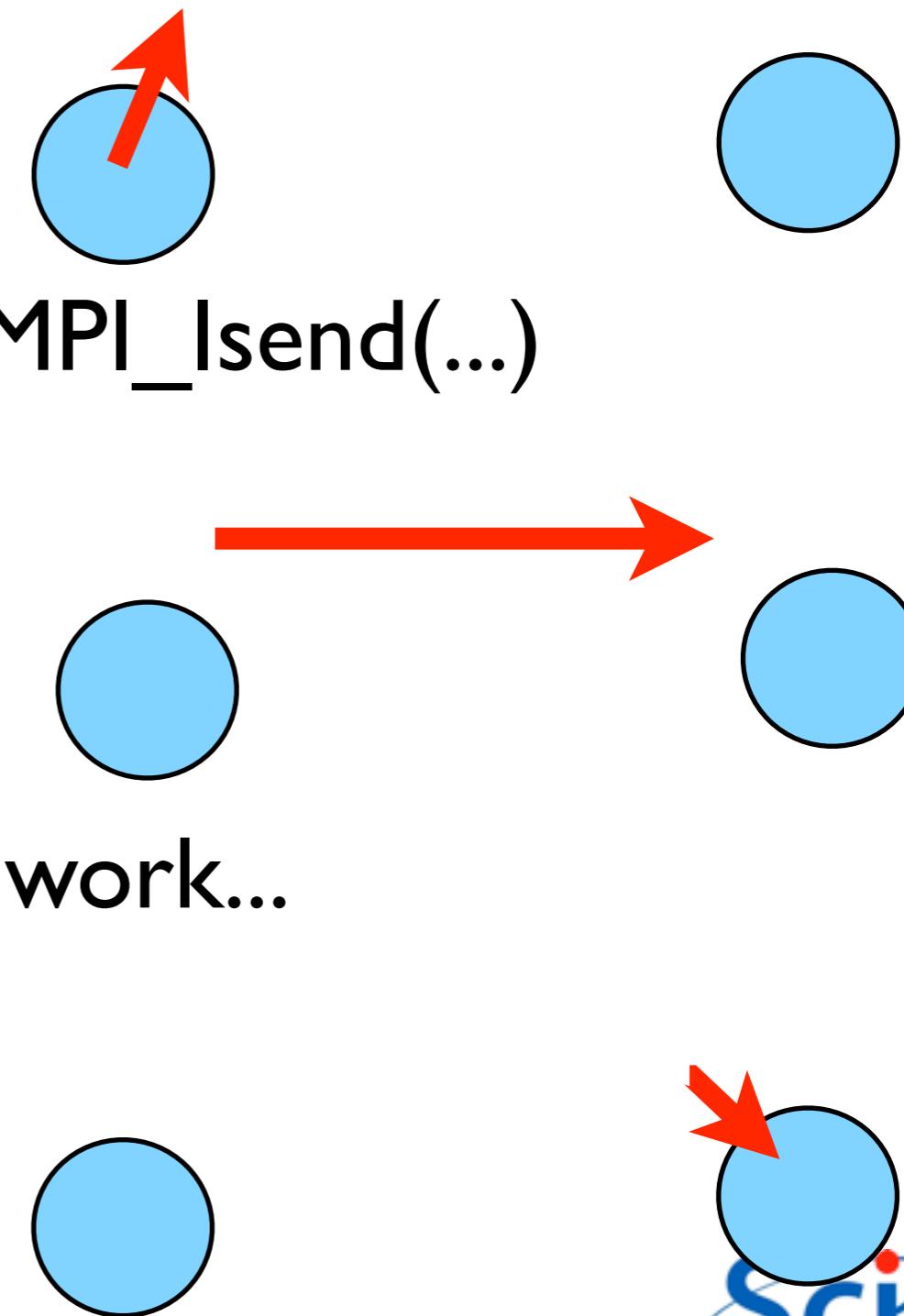


- But inner zones could have been computed just fine
- Ideally, would do inner zones work while communications is being done; then go back and do end points.



# Nonblocking Sends

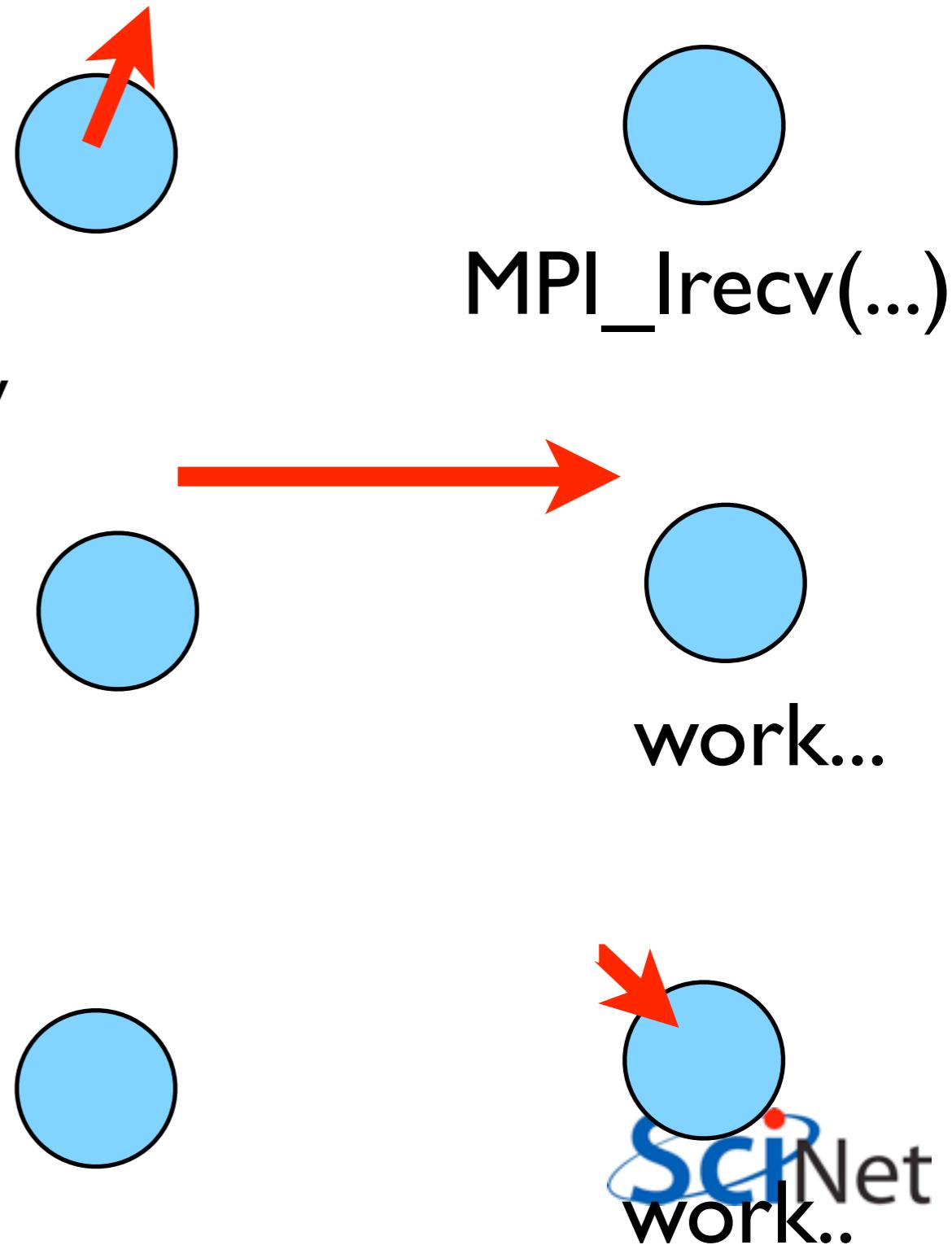
- Allows you to get work done while message is ‘in flight’
- Must **not** alter send buffer until send has completed.
- C: `MPI_Isend( void *buf, int count, MPI_Datatype datatype, int dest, int tag, MPI_Comm comm, MPI_Request *request )`
- FORTRAN: `MPI_ISEND(BUF, INTEGER COUNT, INTEGER DATATYPE, INTEGER DEST, INTEGER TAG, INTEGER COMM, INTEGER REQUEST, INTEGER IERROR)`



work..

# Nonblocking Recv

- Allows you to get work done while message is ‘in flight’
- Must **not** access recv buffer until recv has completed.
- C: `MPI_Irecv( void *buf, int count, MPI_Datatype datatype, int source, int tag, MPI_Comm comm, MPI_Request *request )`
- FORTRAN: `MPI_IREV( BUF, INTEGER COUNT, INTEGER DATATYPE, INTEGER SOURCE, INTEGER TAG, INTEGER COMM, INTEGER REQUEST, INTEGER TERROR )`

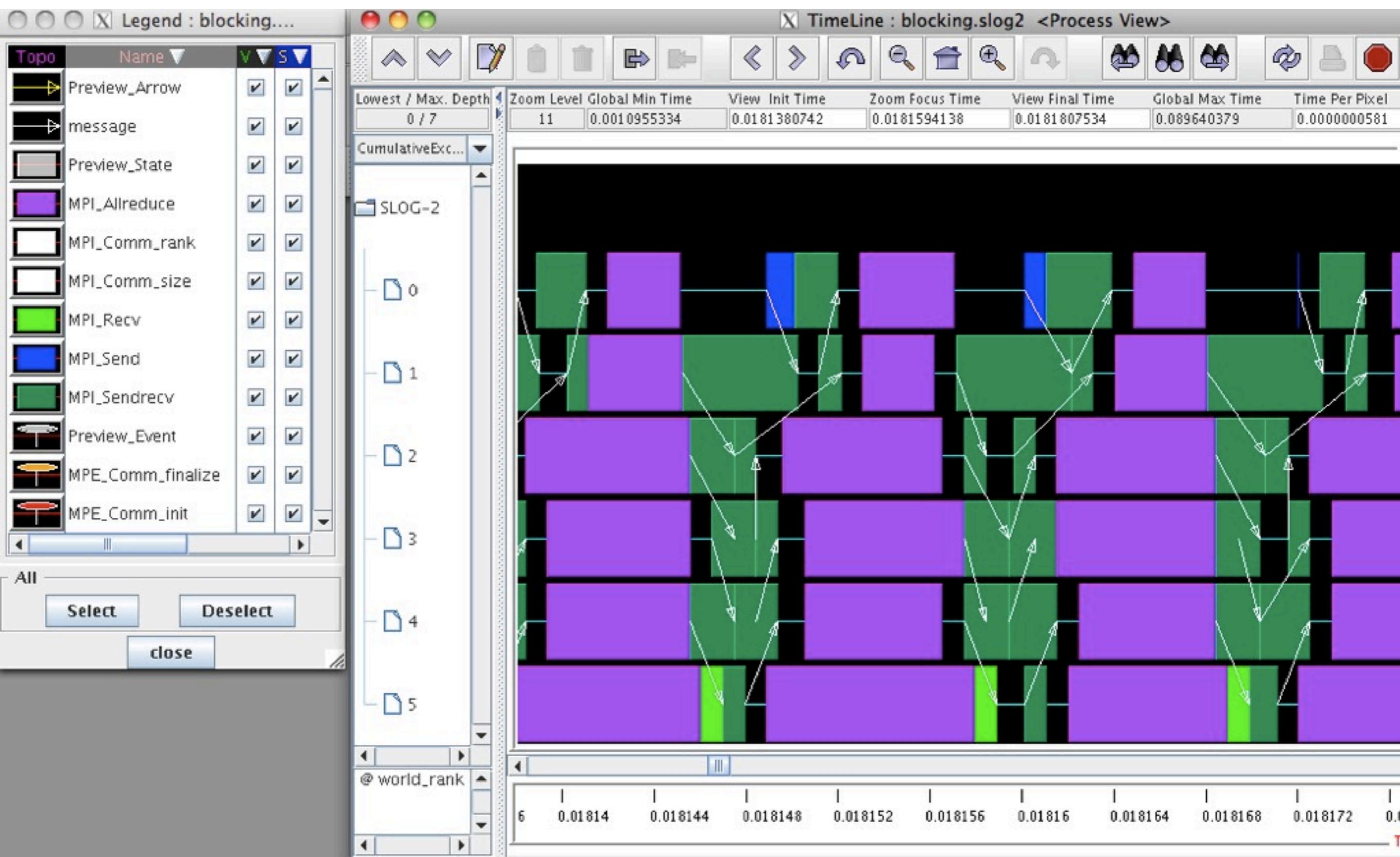


# How to tell if message is completed?

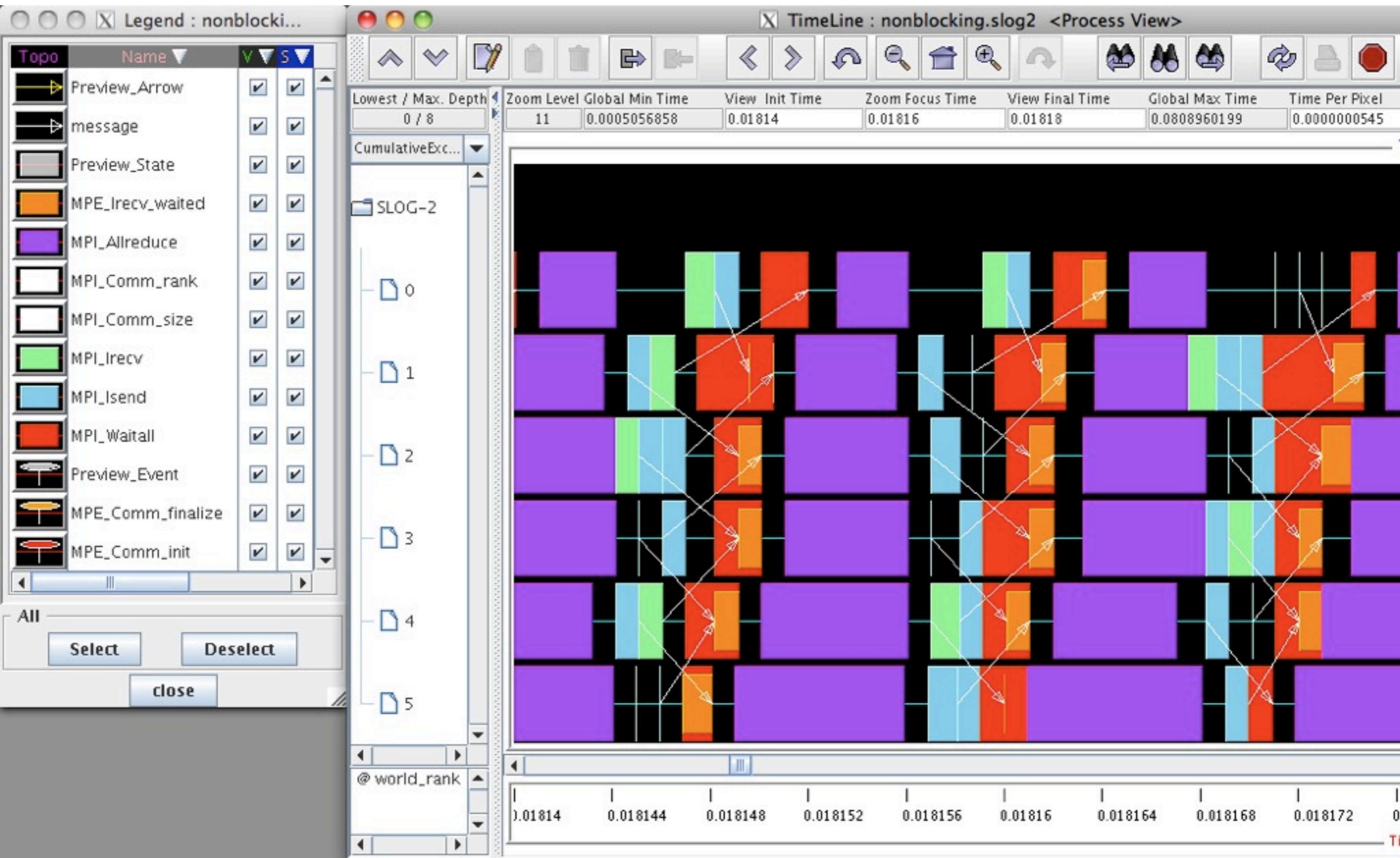
- `int MPI_Wait(MPI_Request *request, MPI_Status *status);`
- `MPI_WAIT(INTEGER REQUEST, INTEGER STATUS(MPI_STATUS_SIZE), INTEGER IERROR)`
- `int MPI_Waitall(int count, MPI_Request *array_of_requests, MPI_Status *array_of_statuses);`
- `MPI_WAITALL(INTEGER COUNT, INTEGER ARRAY_OF_REQUESTS(*), INTEGER ARRAY_OF_STATUSES(MPI_STATUS_SIZE,*), INTEGER`

Also: `MPI_Waitany`, `MPI_Test`...



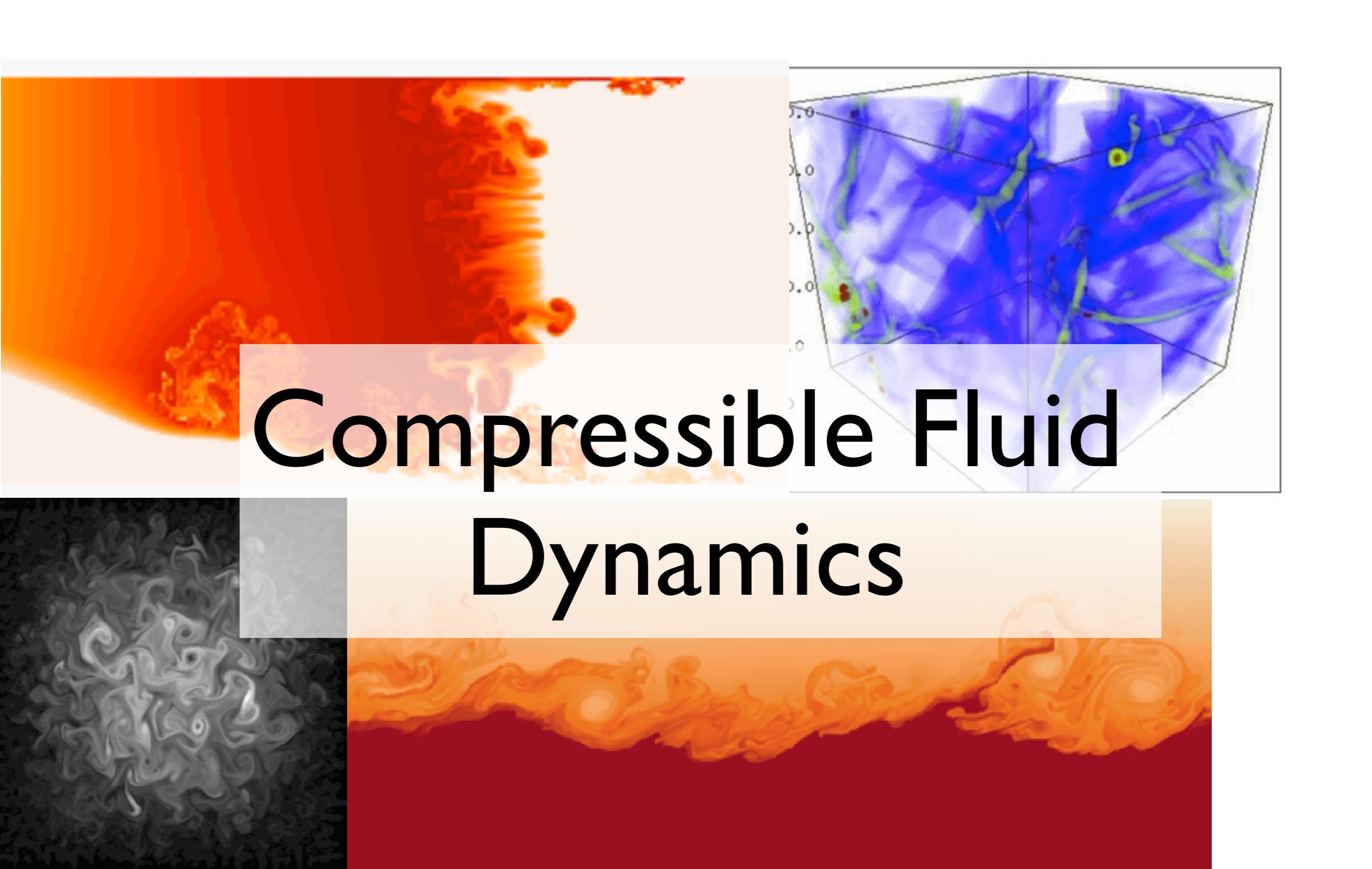


**jetNet**



# Hands On

- In diffusion directory, cp diffusion{c,f}-mpi.{c,f90} to diffusion{c,f}-mpi-nonblocking.{c,f90}
- Change to do non-blocking IO; post sends/recvs, do inner work, wait for messages to clear, do end points



# Compressible Fluid Dynamics

# Equations of Hydrodynamics

- Density, momentum, and energy equations
- Supplemented by an equation of state - pressure as a function of dens, energy

$$\frac{\partial}{\partial t} \rho + \nabla \cdot (\rho \mathbf{v}) = 0$$

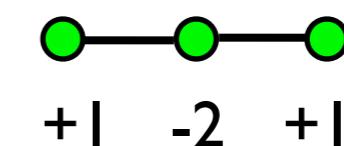
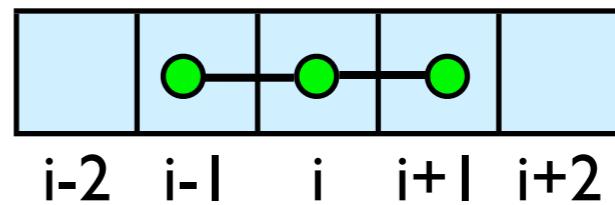
$$\frac{\partial}{\partial t} (\rho \mathbf{v}) + \nabla \cdot (\rho \mathbf{v} \mathbf{v}) = -\nabla p$$

$$\frac{\partial}{\partial t} (\rho E) + \nabla \cdot ((\rho E + p) \mathbf{v}) = 0$$

# Discretizing Derivatives

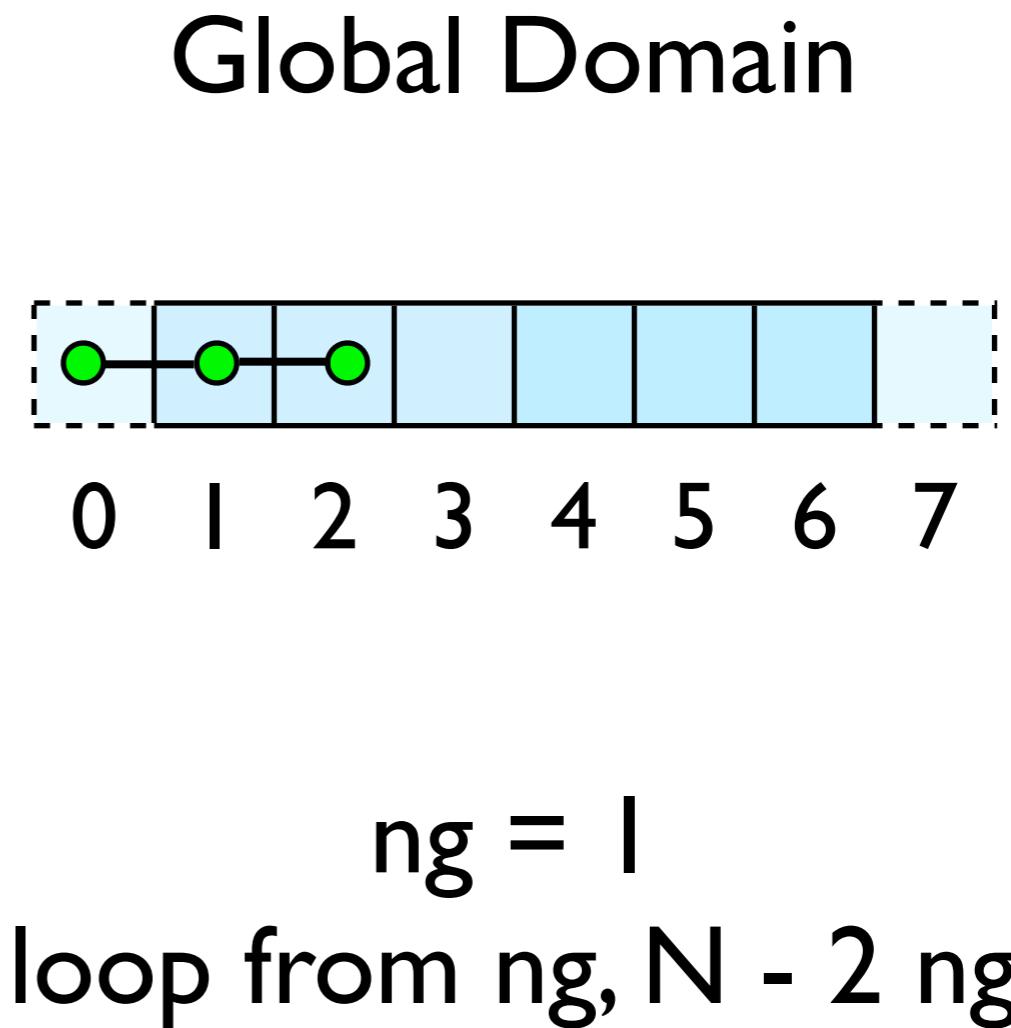
- Done by finite differencing the discretized values
- Implicitly or explicitly involves interpolating data and taking derivative of the interpolant
- More accuracy - larger ‘stencils’

$$\left. \frac{d^2 Q}{dx^2} \right|_i \approx \frac{Q_{i+1} - 2Q_i + Q_{i-1}}{\Delta x^2}$$



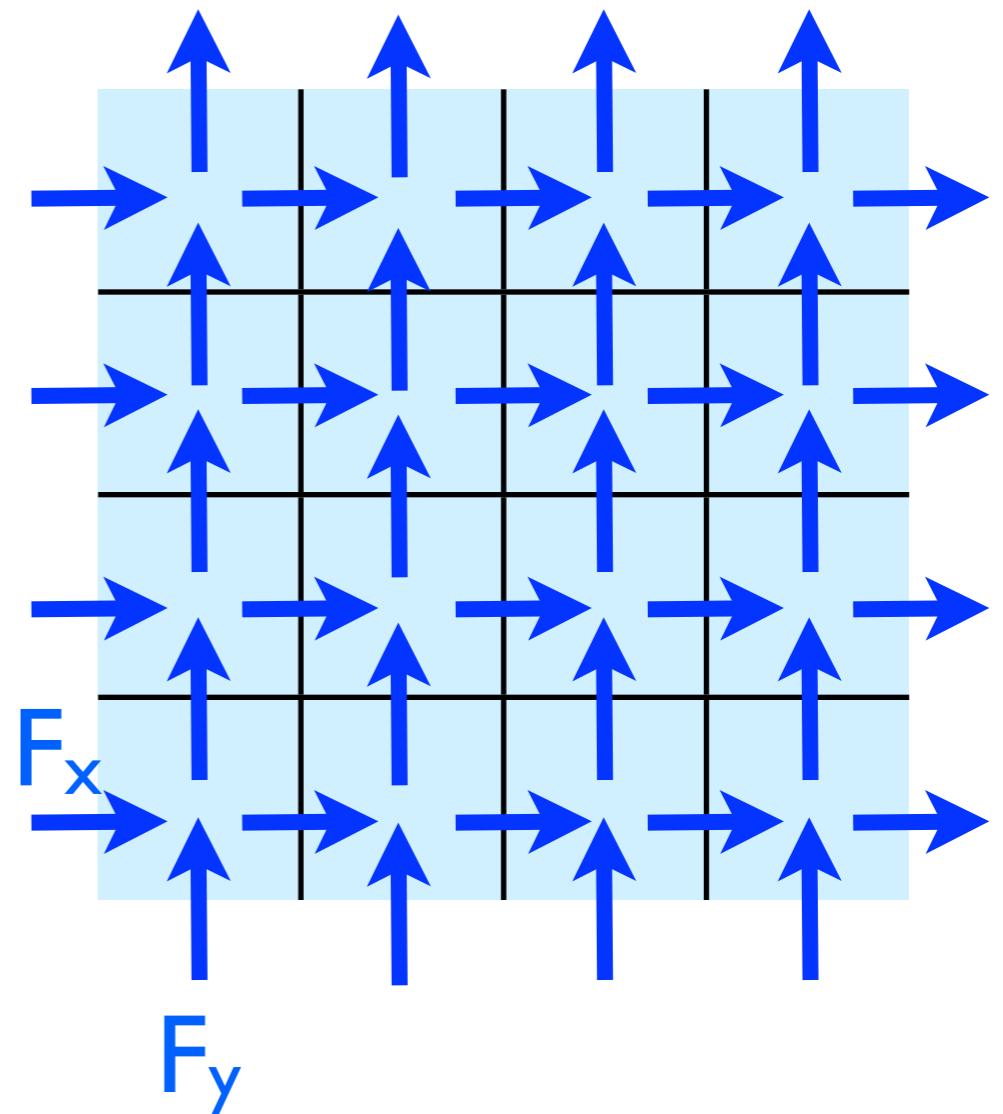
# Guardcells

- How to deal with boundaries?
- Because stencil juts out, need information on cells beyond those you are updating
- Pad domain with ‘guard cells’ so that stencil works even for the 0th point in domain
- Fill guard cells with values such that the required boundary conditions are met



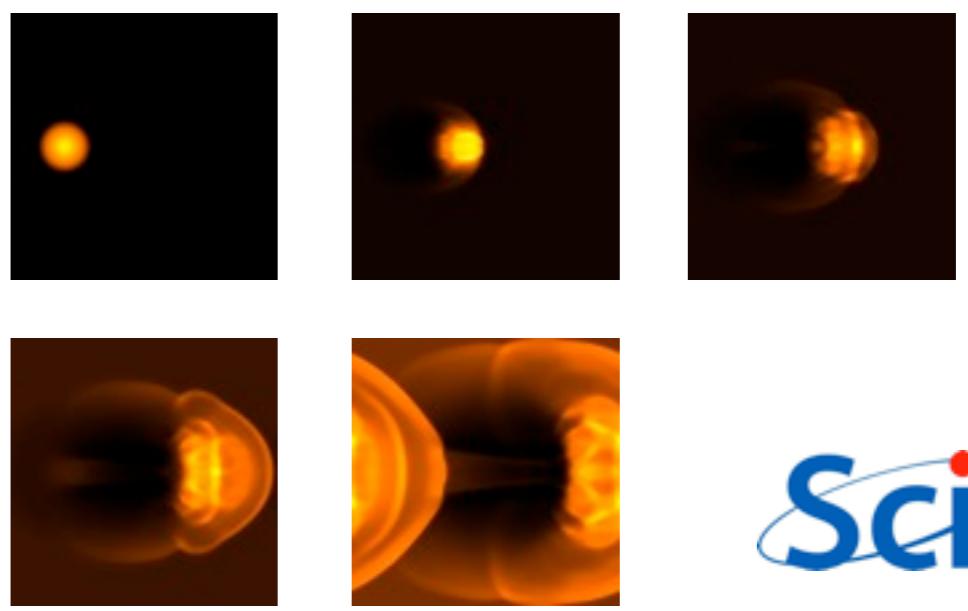
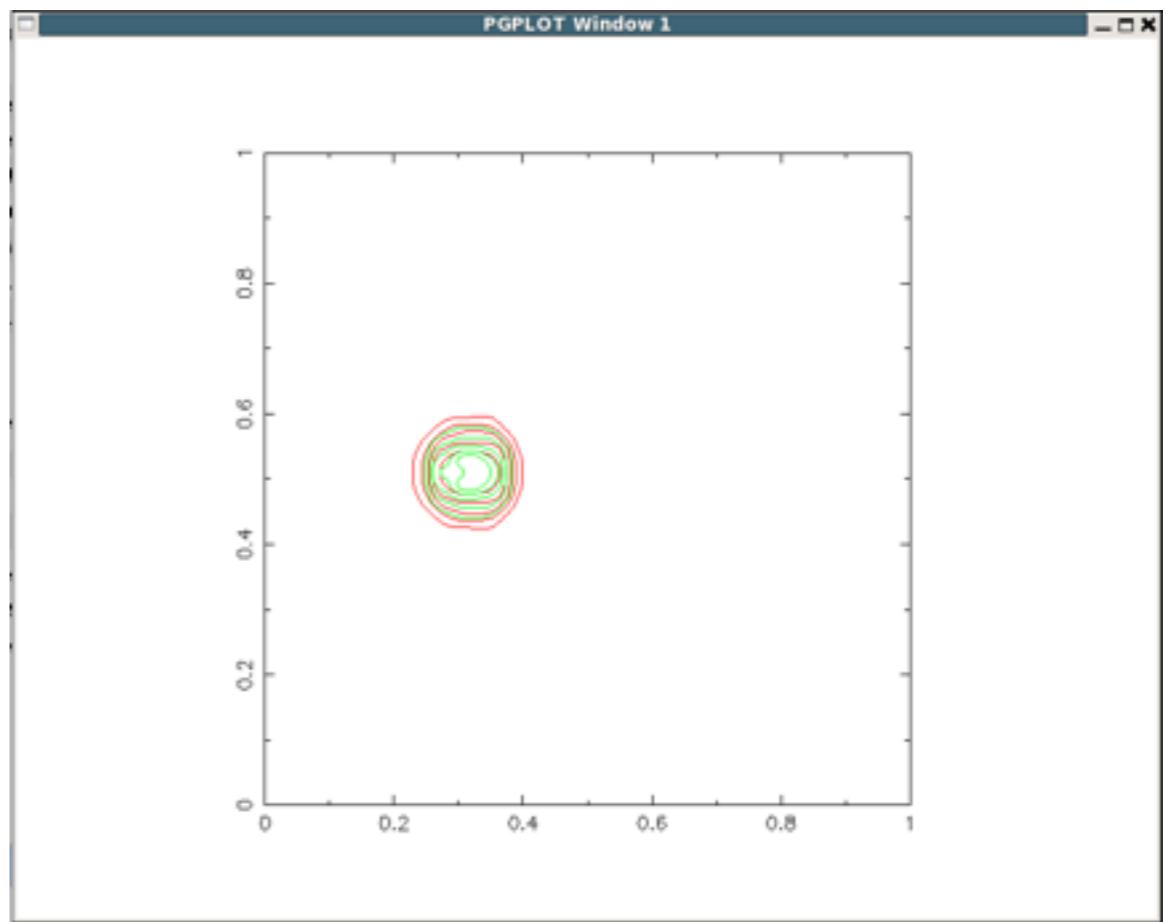
# Finite Volume Method

- Conservative; very well suited to high-speed flows with shocks
- At each timestep, calculate fluxes using interpolation/finite differences, and update cell quantities.
- Use conserved variables -- eg, momentum, not velocity.



# Single-Processor hydro code

- `cd hydro{c,f}; make`
- `./hydro 100`
- Takes options:
  - number of points to write
  - Outputs image (ppm) of initial conditions, final state (plots density)
  - `display ics.ppm`
  - `display dens.ppm`



# Single-Processor hydro code

- Set initial conditions
- Loop, calling *timestep()* and maybe some output routines (*plot()* - contours)
- At beginning and end, save an image file with *outputppm()*
- All data stored in array *u*.

```
nx = n+4; /* two cells on either side for BCs */
ny = n+4;
u = alloc3d_float(ny,nx,NVARS);

initialconditions(u, nx, ny);
outputppm(u,nx,ny,NVARS,"ics.ppm",IDENS);
t=0.;
for (iter=0; iter < 6*nx; iter++) {
    timestep(u,nx,ny,&dt);
    t += 2*dt;
    if ((iter % 10) == 1) {
        printf("%4d dt = %f, t = %f\n", iter, dt, t);
        plot(u, nx, ny);
    }
}
outputppm(u,nx,ny,NVARS,"dens.ppm",IDENS);
closeplot();
```

# Single-Processor hydro code

- Set initial conditions
- Loop, calling *timestep()* and maybe some output routines (*plot()* - contours)
- At beginning and end, save an image file with *outputppm()*
- All data stored in array *u*.

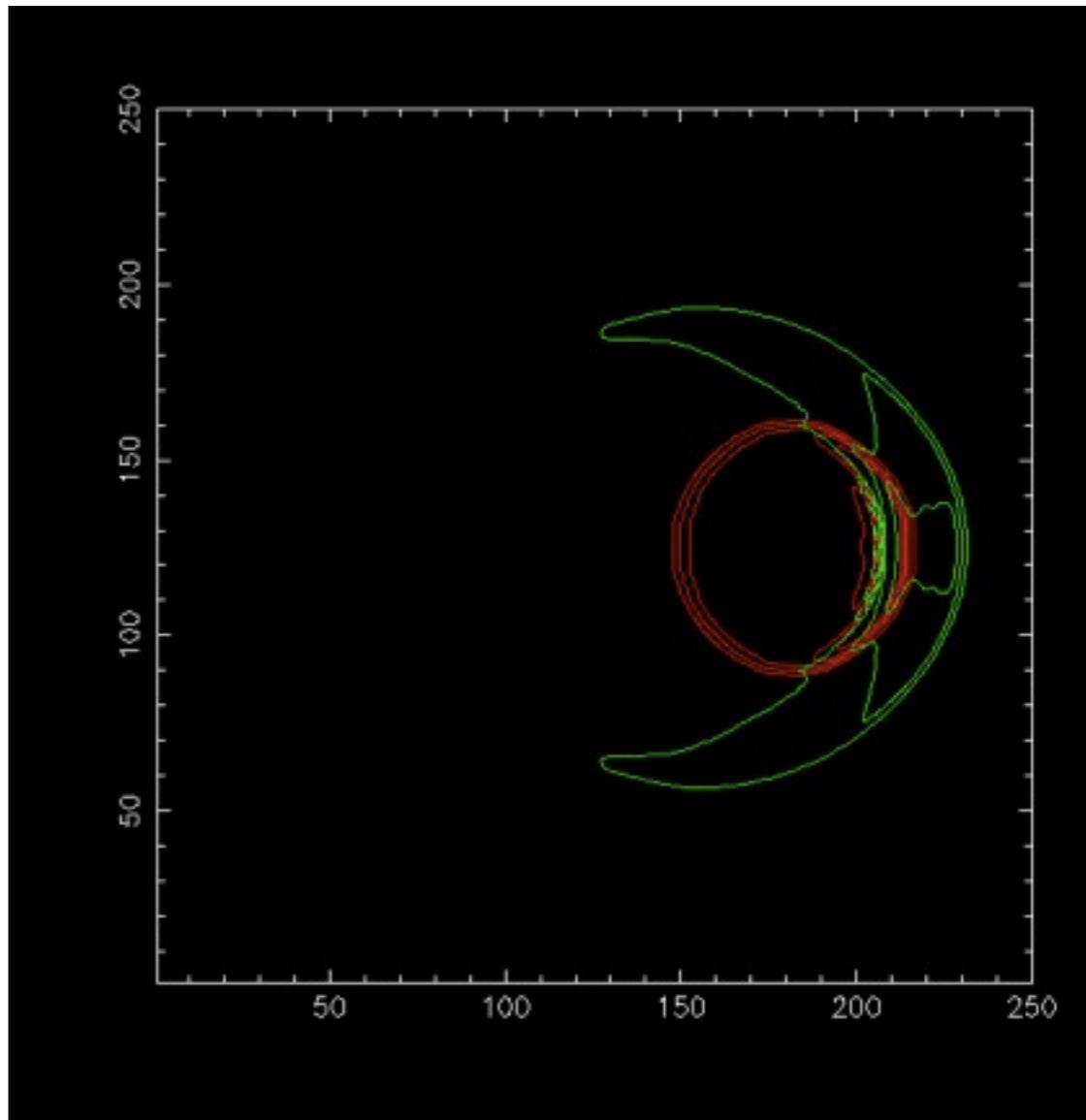
```
nx = n+2*nguard ! boundary condition zones on each side
ny = n+2*nguard
allocate(u(nvars,nx,ny))

call initialconditions(u)
call outputppm(u,'ics.ppm',idens)
call openplot(nx, ny)
t=0
timesteps: do iter=1,nx*6
    call timestep(u,dt)
    t = t + 2*dt
    if (mod(iter,10) == 1) then
        print *, iter, 'dt = ', dt, ' t = ', t
        call showplot(u)
    endif
end do timesteps
call outputppm(u,'dens.ppm',idens)

deallocate(u)
```

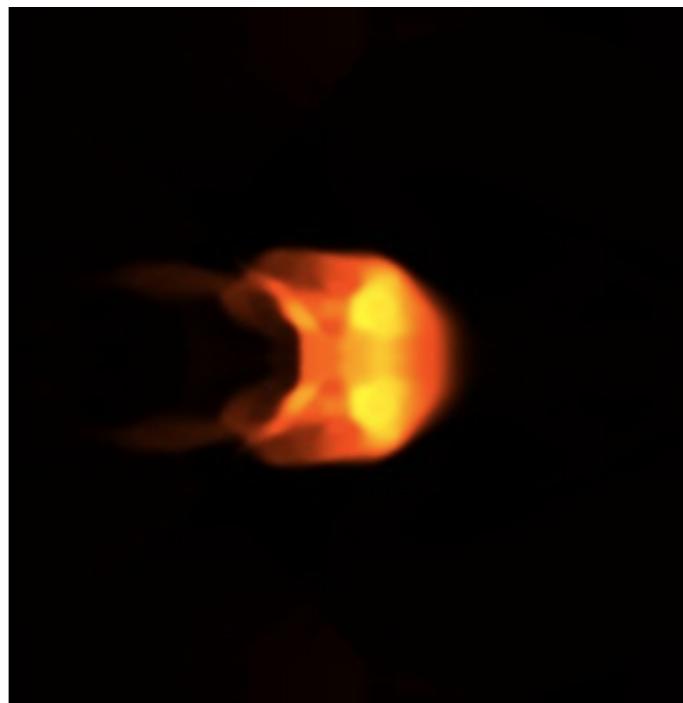
# Plotting to screen

- plot.c, plot.f90
- Every 10 timesteps
- Find min, max of pressure, density
- Plot 5 contours of density (red) and pressure (green)
- pgplot library (old, but works).



# Plotting to file

- ppm.c, ppm.f90
- PPM format -- binary (w/ ascii header)
- Find min, max of density
- Calculate r,g,b values for scaled density (black = min, yellow = max)
- Write header, then data.



# Data structure

- $u$  : 3 dimensional array containing each variable in 2d space
- eg,  $u[j][i][\text{IDENS}]$
- or  $u(\text{idens}, i, j)$

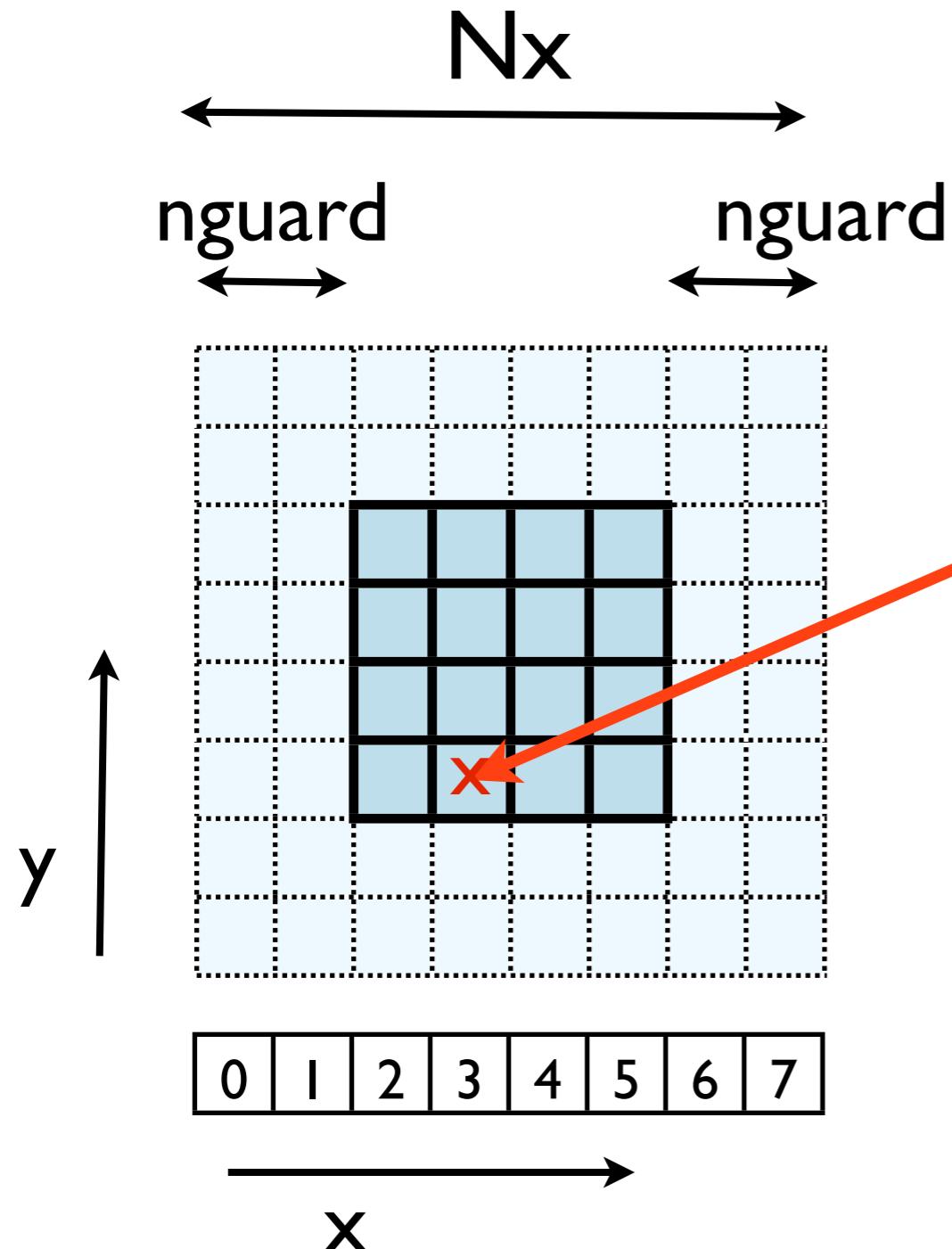
```
if (r < 0.1*sqrt(nx*nx*1.+ny*ny*1.)) {  
    u[j][i][\text{IDENS}] = projdens;  
    u[j][i][\text{IMOMX}] = projvel*projdens;  
    u[j][i][\text{IMOMY}] = 0.;  
    u[j][i][\text{IENER}] = 0.5*(projdens*projvel*projvel)+
```

## solver.c (initialconditions)

```
where (r < 0.1*sqrt(nx*nx*1.+ny*ny))  
    u(idens,:,:)=projdens  
    u(imomx,:,:)=projdens*projvel  
    u(imomy,:,:)=0  
    u(iener,:,:)=0.5*(projdens*projvel*projvel)+1./(gamma-1.)  
elsewhere  
    u(idens,:,:)=backgrounddens  
    u(imomx,:,:)=0.  
    u(imomy,:,:)=0.  
    u(iener,:,:)=1./((gamma-1.)*backgrounddens)  
endwhere
```

## solver.f90 (initialconditions)



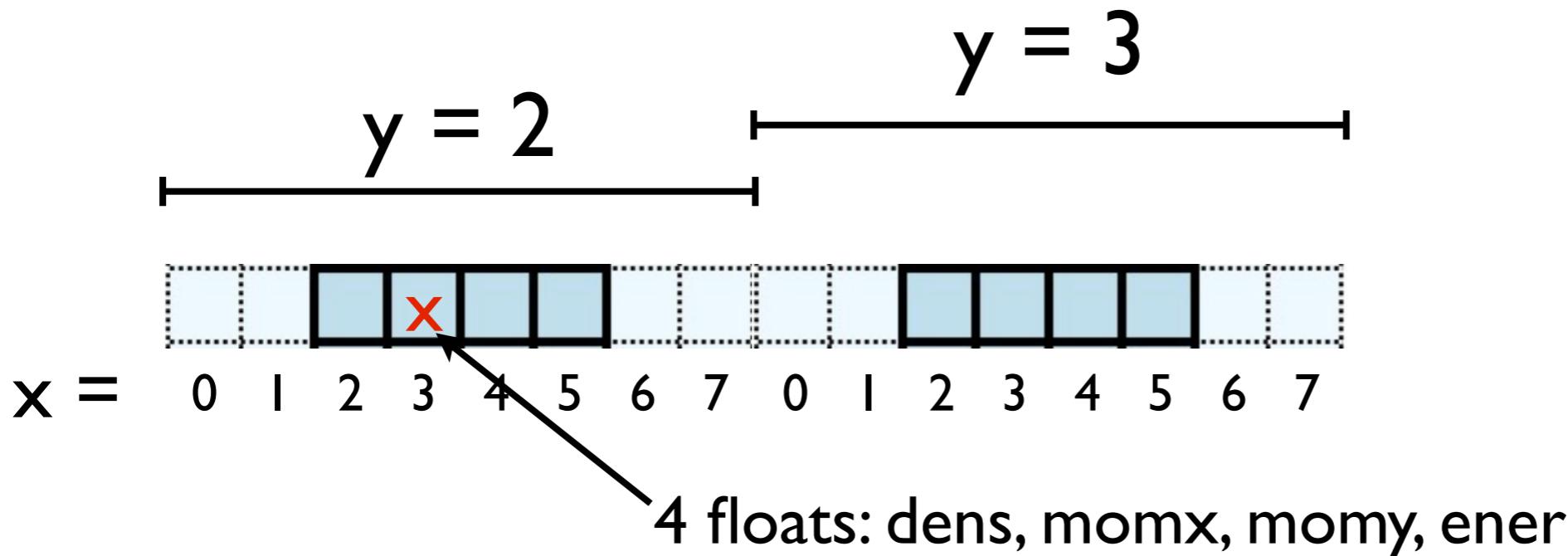


```

u[ 2 ][ 3 ][ DENSVAR ];
u[ 2 ][ 3 ][ MOMXVAR ];
u[ 2 ][ 3 ][ MOMEYVAR ];
u[ 2 ][ 3 ][ ENERVAR ];

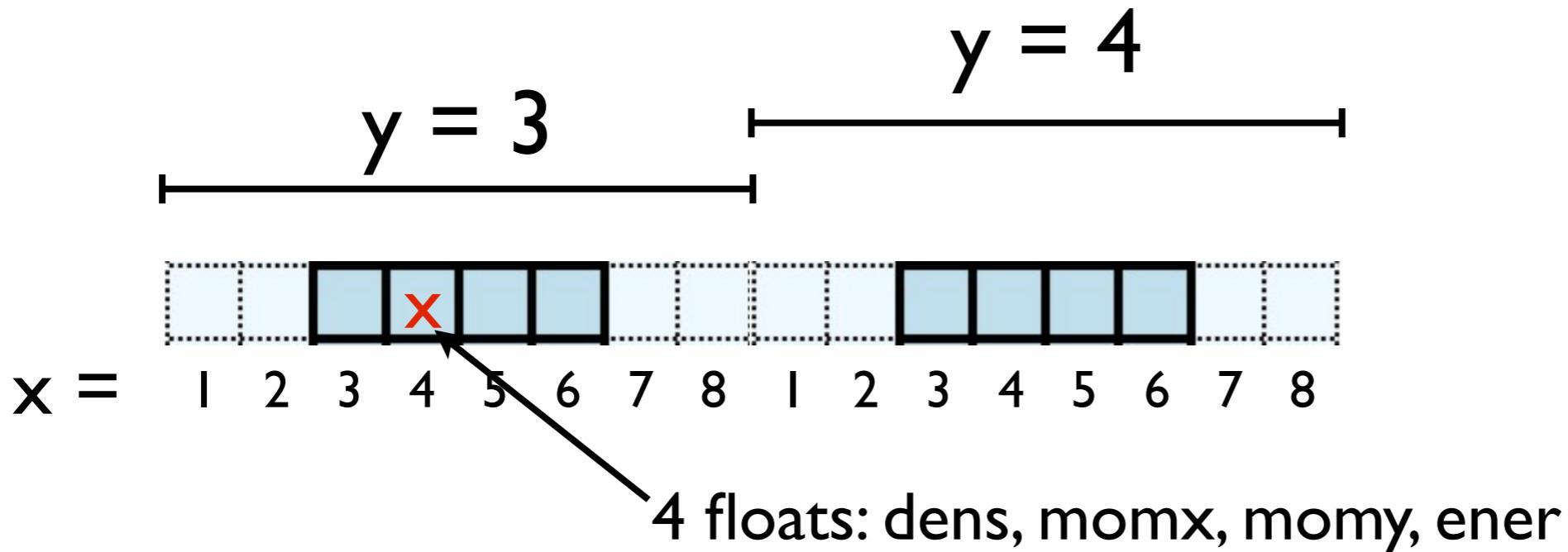
u( idens, 4, 3 )
u( imomx, 4, 3 )
u( imomy, 4, 3 )
u( iener, 4, 3 )
  
```

# Laid out in memory (C)



Same way as in an image file  
(one horizontal row at a time)

# Laid out in memory (FORTRAN)



Same way as in an image file  
(one horizontal row at a time)

# Timestep routine

- Apply boundary conditions
- X sweep, Y sweep
- Transpose entire domain , so Y sweep is just an X sweep
- (unusual approach! But has advantages. Like matrix multiply.)
- Note - dt calculated each step (minimum across domain.)

```
pure subroutine timestep(u,dt)
    real, dimension(:,:,:,:), intent(INOUT) :: u
    real, intent(OUT) :: dt

    real, dimension(nvars,size(u,2),size(u,3)) :: ut
    dt=0.5*cfl(u)

    ! the x sweep
    call periodicBCs(u,'x')
    call xsweep(u,dt)

    ! the y sweeps
    call xytranspose(ut,u)
    call periodicBCs(ut,'x')
    call xsweep(ut,dt)
    call periodicBCs(ut,'x')
    call xsweep(ut,dt)

    ! 2nd x sweep
    call xytranspose(u,ut)
    call periodicBCs(u,'x')
    call xsweep(u,dt)
end subroutine timestep
```

timestep  
solver.f90



# Timestep routine

- Apply boundary conditions
- X sweep, Y sweep
- Transpose entire domain , so Y sweep is just an X sweep
- (unusual approach! But has advantages. Like matrix multiply.)
- Note - dt calculated each step (minimum across domain.)

```
void timestep(float ***u, const int nx, const int ny, float ***ut);

ut = alloc3d_float(ny, nx, NVARS);
*dt=0.5*cfl(u,nx,ny);

/* the x sweep */
periodicBCs(u,nx,ny,'x');
xsweep(u,nx,ny,*dt);

/* the y sweeps */
xytranspose(ut,u,nx,ny);
periodicBCs(ut,ny,nx,'x');
xsweep(ut,ny,nx,*dt);
periodicBCs(ut,ny,nx,'x');
xsweep(ut,ny,nx,*dt);

/* 2nd x sweep */
xytranspose(u,ut,ny,nx);
periodicBCs(u,nx,ny,'x');
xsweep(u,nx,ny,*dt);

free3d_float(ut,ny);
```

timestep  
solver.c



# Xsweep routine

- Go through each x “pencil” of cells
- Do 1d hydrodynamics routine on that pencil.

```
pure subroutine xsweep(u,dt)
implicit none
real, intent(INOUT), dimension(:,:,:,:) :: u
real, intent(IN) :: dt
integer :: j

do j=1,size(u,3)
    call tvd1d(u(:,:,:,j),dt)
enddo
end subroutine xsweep
```

**xsweep**  
**solver.f90**

```
void xsweep(float ***u, const int nx, c
int j;

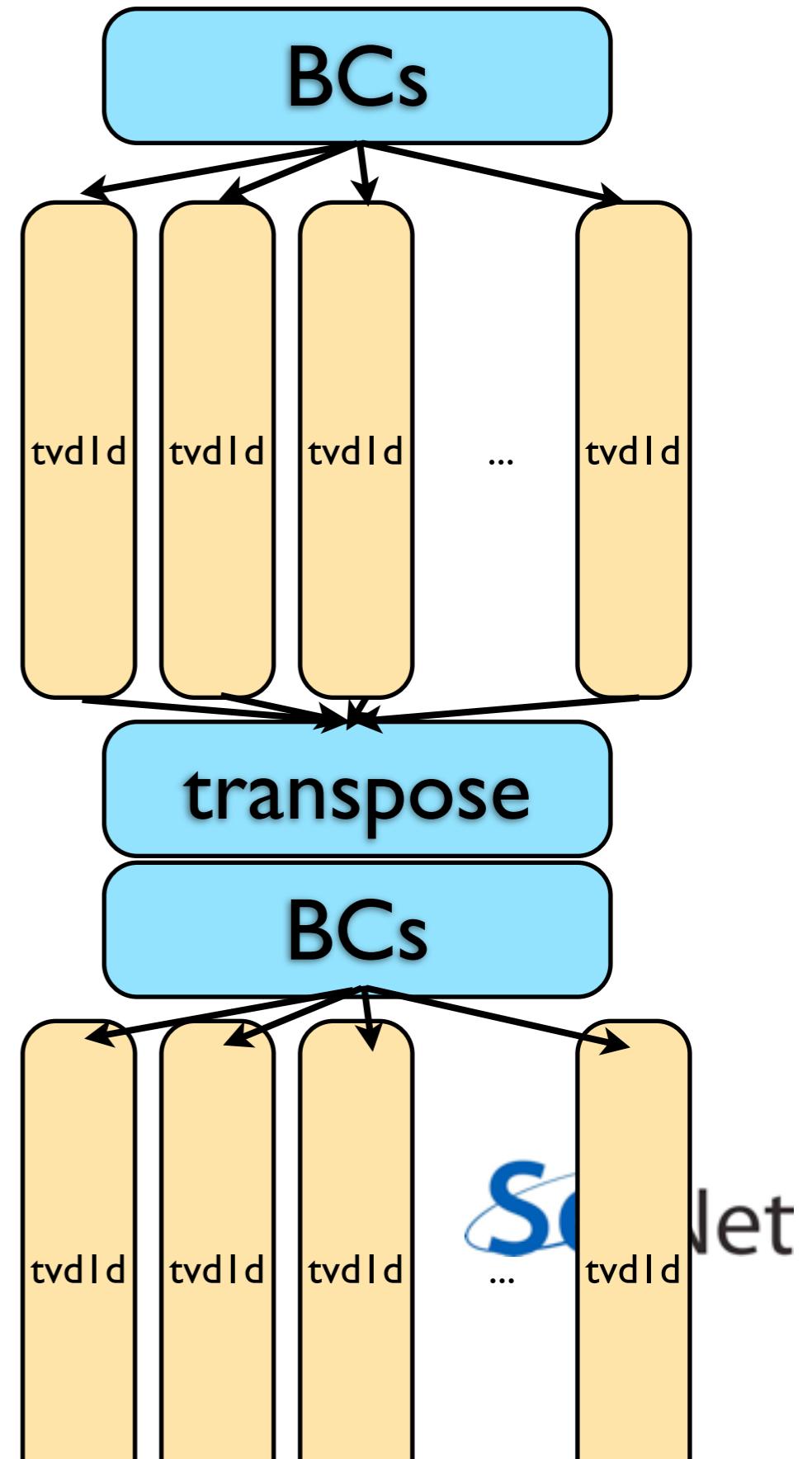
for (j=0; j<ny; j++) {
    tvd1d(u[j],nx,dt);
}
}
```

**xsweep**  
**solver.c**

What do data  
dependancies  
look like for  
this?

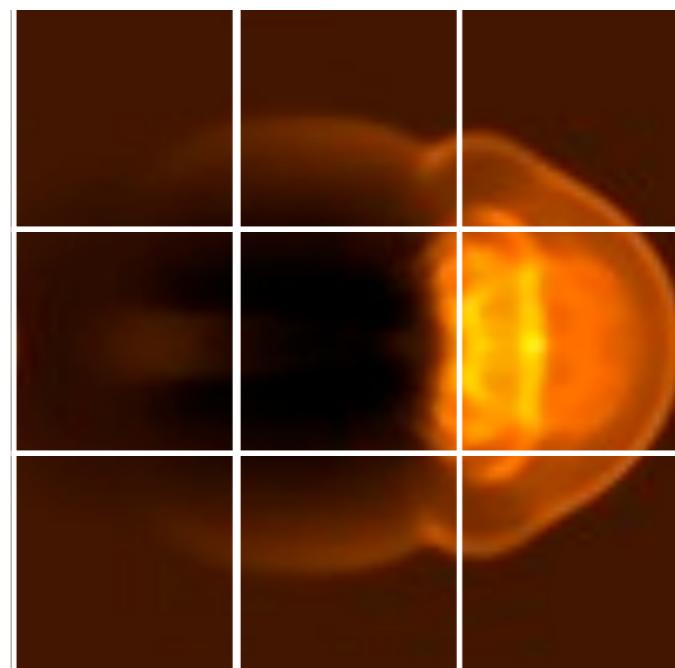
# Data dependencies

- Previous timestep must be completed before next one started.
- Within each timestep,
- Each tvdId “pencil” can be done independently
- All must be done before transpose, BCs



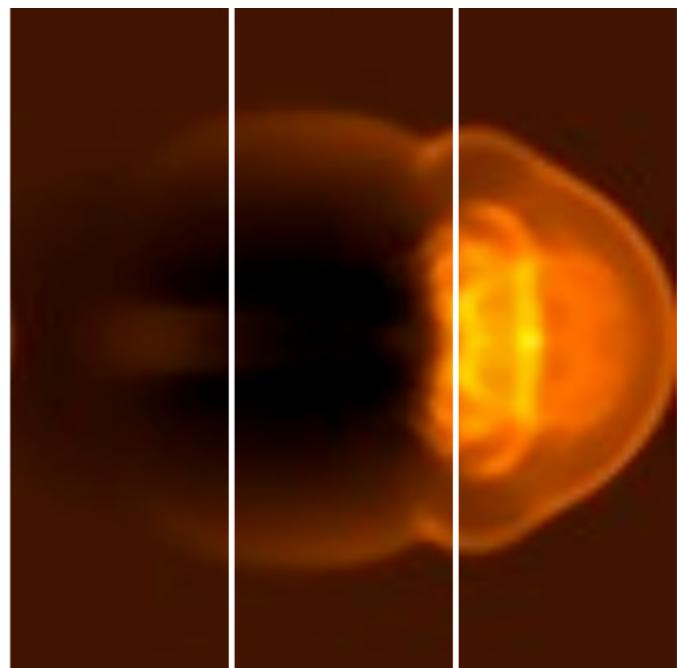
# MPiling the code

- Domain decomposition



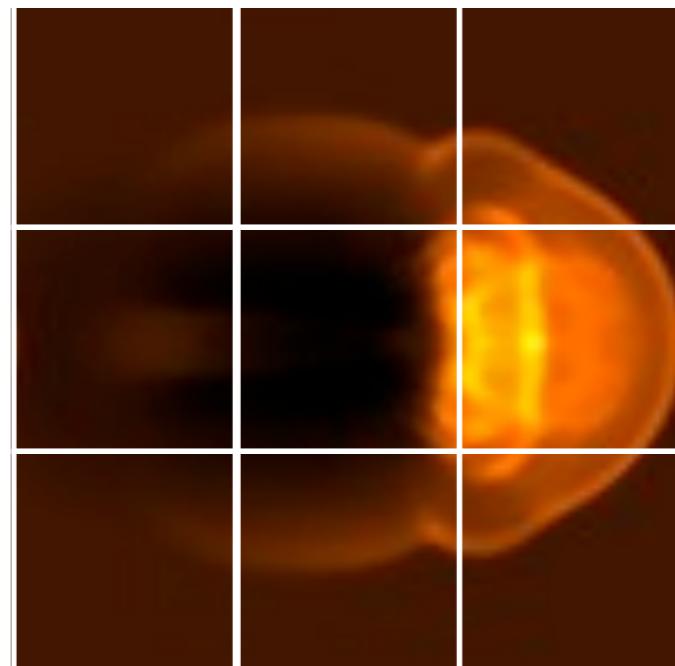
# MPiling the code

- Domain decomposition
- For simplicity, for now we'll just implement decomposition in one direction, but we will design for full 2d decomposition



# MPiling the code

- Domain decomposition
- We can do as with diffusion and figure out our neighbours by hand, but MPI has a better way...



# Create new communicator with new topology

- `MPI_Cart_create`  
`( MPI_Comm comm_old,`  
`int ndims, int *dims,`  
`int *periods, int reorder,`  
`MPI_Comm *comm_cart )`

size = 9  
dims = (2,2)  
rank = 3

(2,0)	(2,1)	(2,2)
(1,0)	(1,1)	(1,2)
(0,0)	(0,1)	(0,2)

A blue arrow points from the text "rank = 3" to the cell containing the value (1,0) in the second row of the grid.

# Create new communicator with new topology

- MPI\_Cart\_create (  
integer comm\_old,  
integer ndims,  
integer [dims],  
logical [periods],  
integer reorder,  
integer comm\_cart,  
integer ierr )

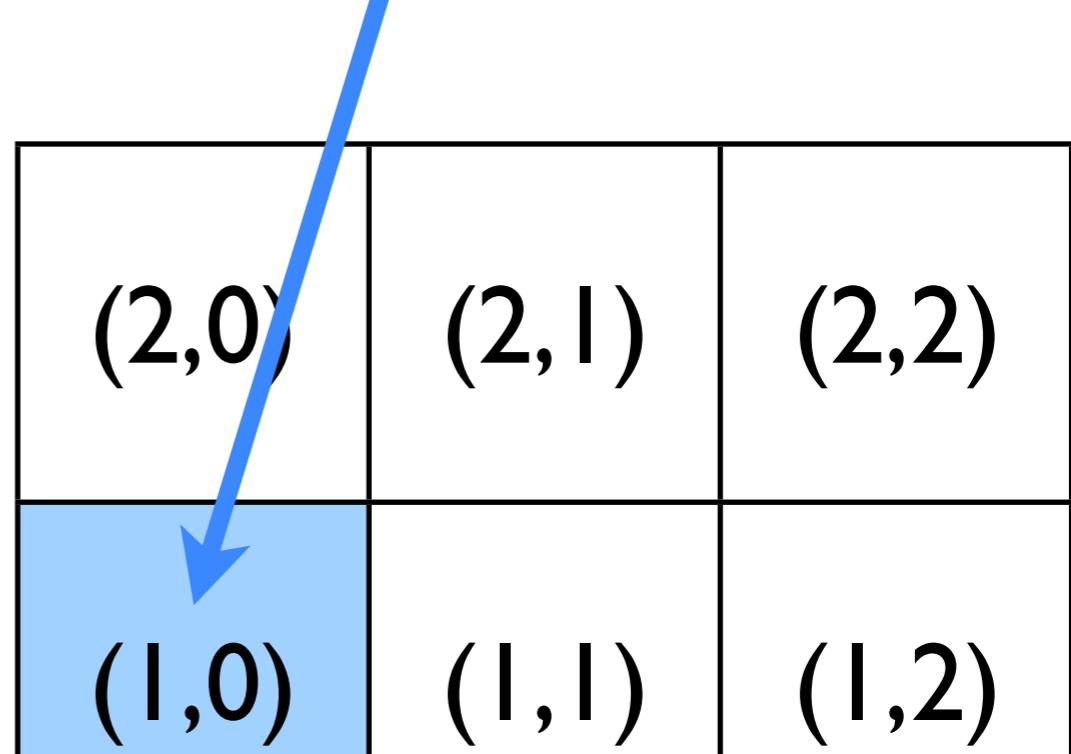
size = 9  
dims = (2,2)  
rank = 3

(2,0)	(2,1)	(2,2)
(1,0)	(1,1)	(1,2)
(0,0)	(0,1)	(0,2)

A blue arrow points from the text "rank = 3" to the cell containing the value (1,0) in the second row of the grid.

size = 9  
dims = (2,2)  
rank = 3

Create new  
communicator  
with new topology



C

```
ierr = MPI_Cart_shift(MPI_COMM new_comm, int dim,  
                      int shift, int *left, int *right)  
ierr = MPI_Cart_coords(MPI_COMM new_comm, int rank,  
                      int ndims, int *gridcoords)
```

# Create new communicator with new topology

size = 9  
dims = (2,2)  
rank = 3



FORTRAN

```
call MPI_Cart_shift(integer new_comm, dim, shift,  
    left, right, ierr)  
call MPI_Cart_coords(integer new_comm, rank,  
    ndims, [gridcoords], ierr)
```

# Let's try starting to do this together

- In a new directory:
- add `mpi_init`, `_finalize`, `comm_size`.
- `mpi_cart_create`
- rank on *new* communicator.
- neighbours
- Only do part of domain

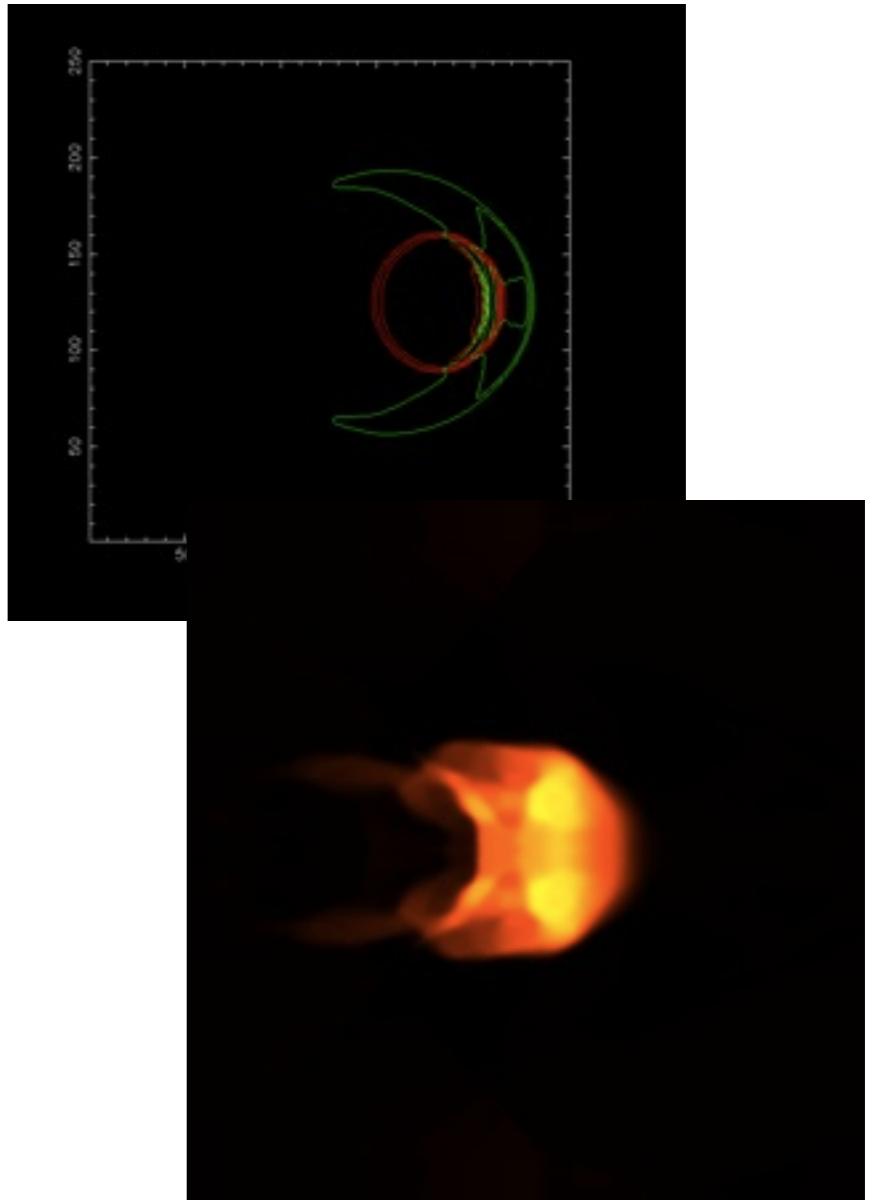
size = 9  
dims = (2,2)  
rank = 3

(2,0)	(2,1)	(2,2)
(1,0)	(1,1)	(1,2)
(0,0)	(0,1)	(0,2)

A blue arrow points from the text "rank = 3" to the cell containing the value (1,0) in the 2D grid, indicating that the rank 3 process is located at position (1,0).

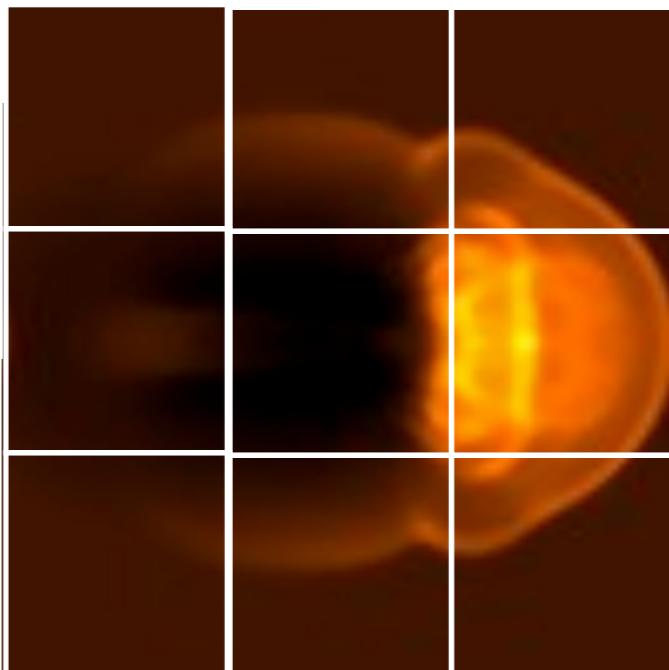
# Next

- File IO - have each process write its own file so don't overwrite
- Coordinate min, max across processes for contours, images.
- Coordinate min in cfl routine.



# MPing the code

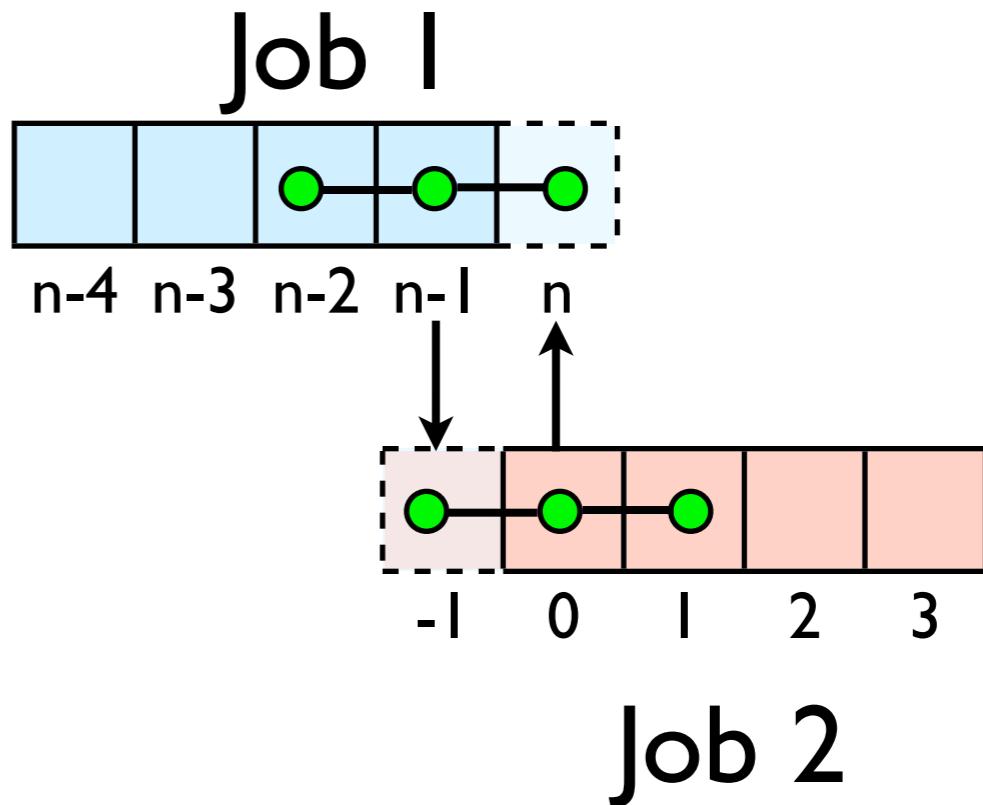
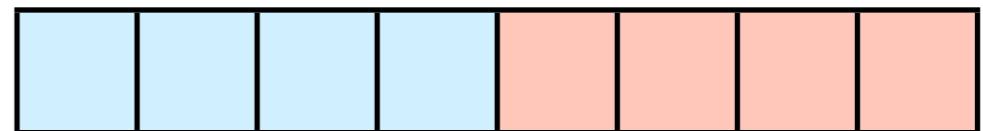
- Domain decomposition
- Lots of data - ensures locality
- How are we going to handle getting non-local information across processors?



# Guardcells

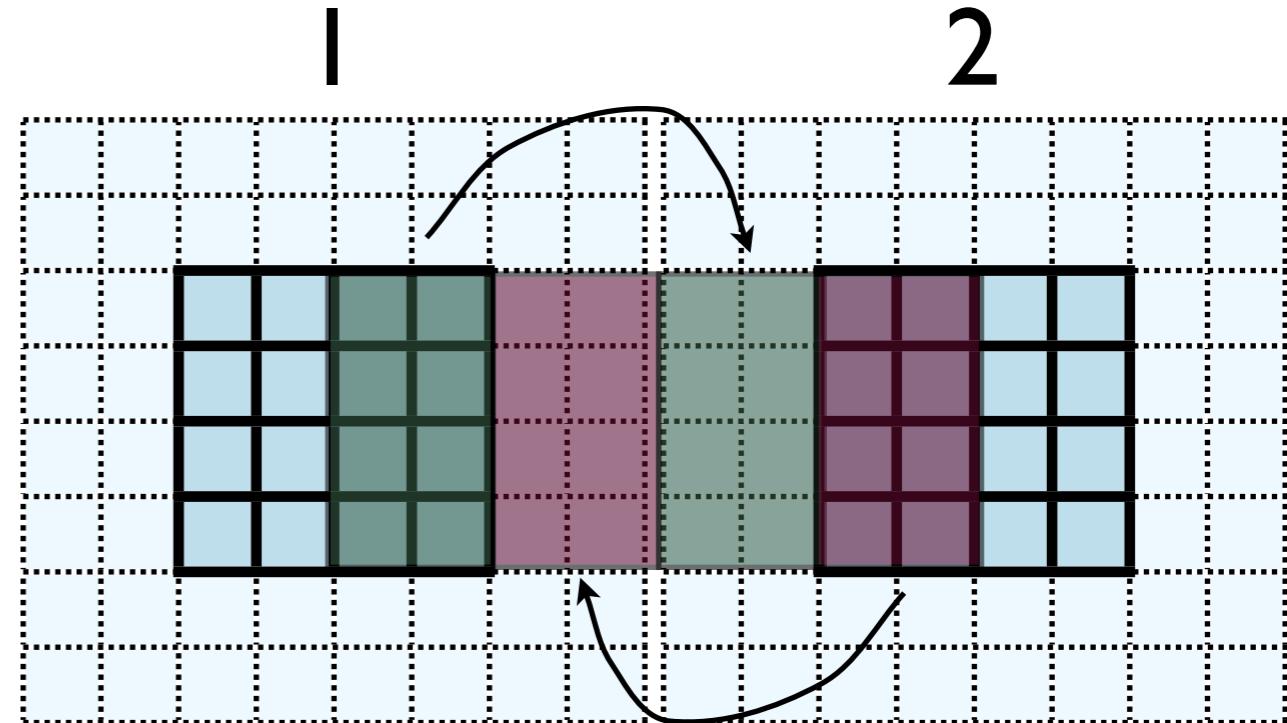
- Works for parallel decomposition!
- Job 1 needs info on Job 2's 0th zone, Job 2 needs info on Job 1's last zone
- Pad array with ‘guardcells’ and fill them with the info from the appropriate node by message passing or shared memory
- Hydro code: need guardcells 2 deep

## Global Domain



# Guard cell fill

- When we're doing boundary conditions.
- Swap guardcells with neighbour.



$l: u(:, nx:nx+ng, ng:ny-ng)$

$\rightarrow 2: u(:, l:ng, ng:ny-ng)$

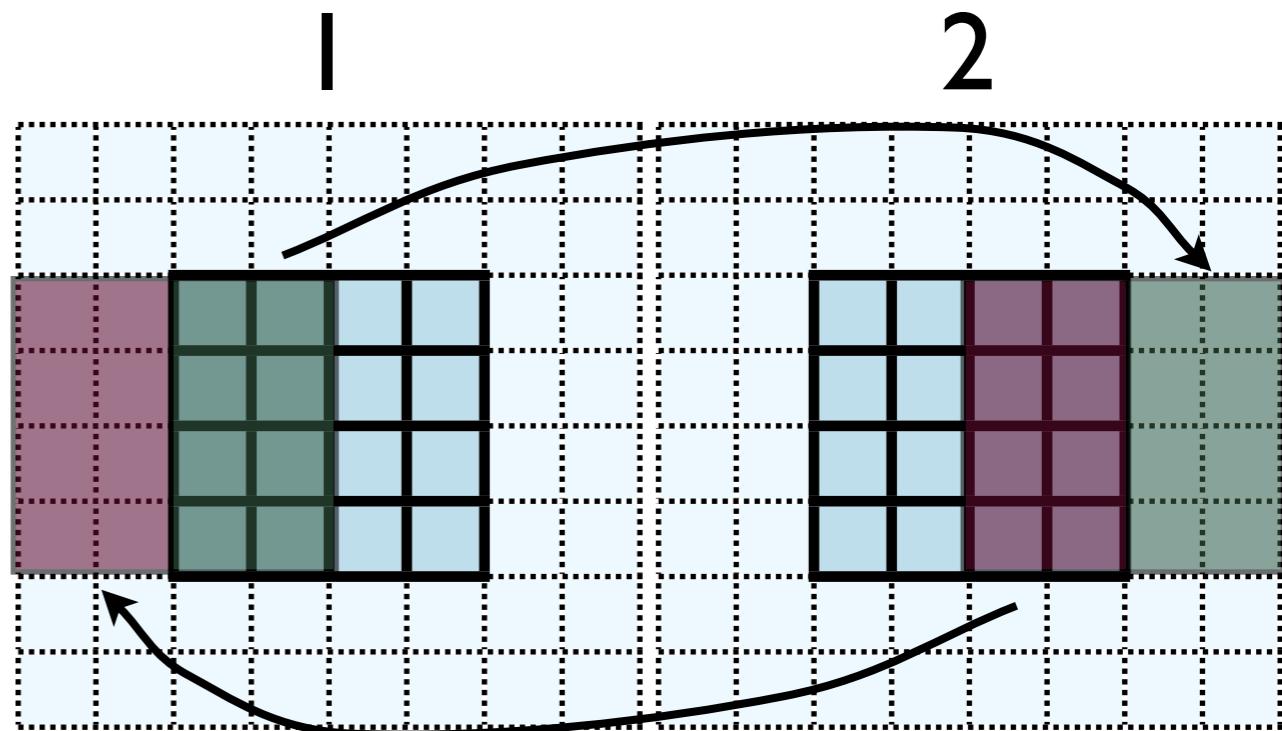
$2: u(:, ng+l:2*ng, ng:ny-ng)$

$\rightarrow l: u(:, nx+ng+l:nx+2*ng, ng:ny-ng)$

$(ny-2*ng)*ng$  values to swap

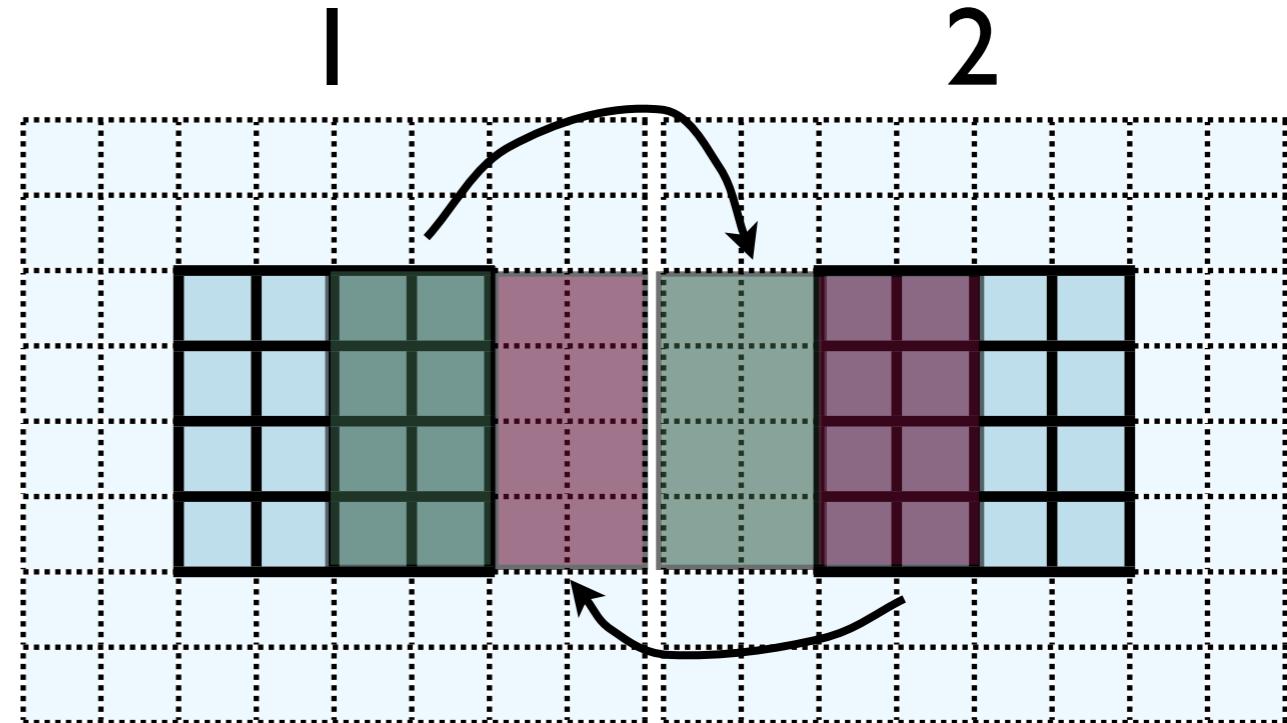
# Cute way for Periodic BCs

- Actually make the decomposed mesh periodic;
- Make the far ends of the mesh neighbors
- Don't know the difference between that and any other neighboring grid
- `Cart_create` sets this up for us automatically upon request.



# Implementing in MPI

- No different in principle than diffusion
- Just more values
- And more variables: dens, ener, imomx....
- Simplest way: copy all the variables into an NVARS\*(ny-2\*ng)\*ng sized



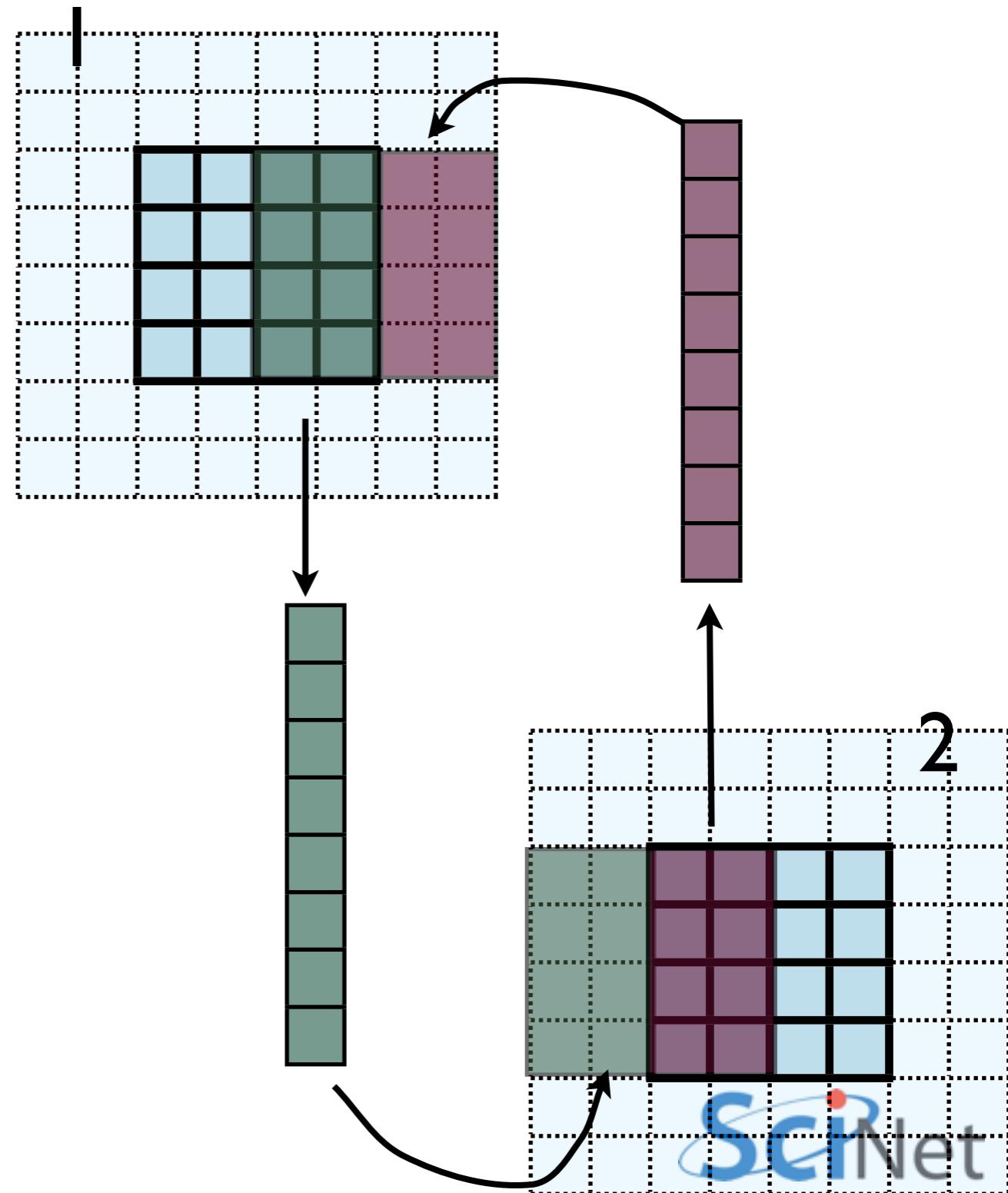
1:  $u(:, nx:nx+ng, ng:ny-ng)$   
→ 2:  $u(:, l:ng, ng:ny-2*ng)$

2:  $u(:, ng+l:2*ng, ng:ny-2*ng)$   
→ 1:  $u(:, nx+ng+l:nx+2*ng, ng:ny-2*ng)$

nvars\*(ny-2\*ng)\*ng values to swap

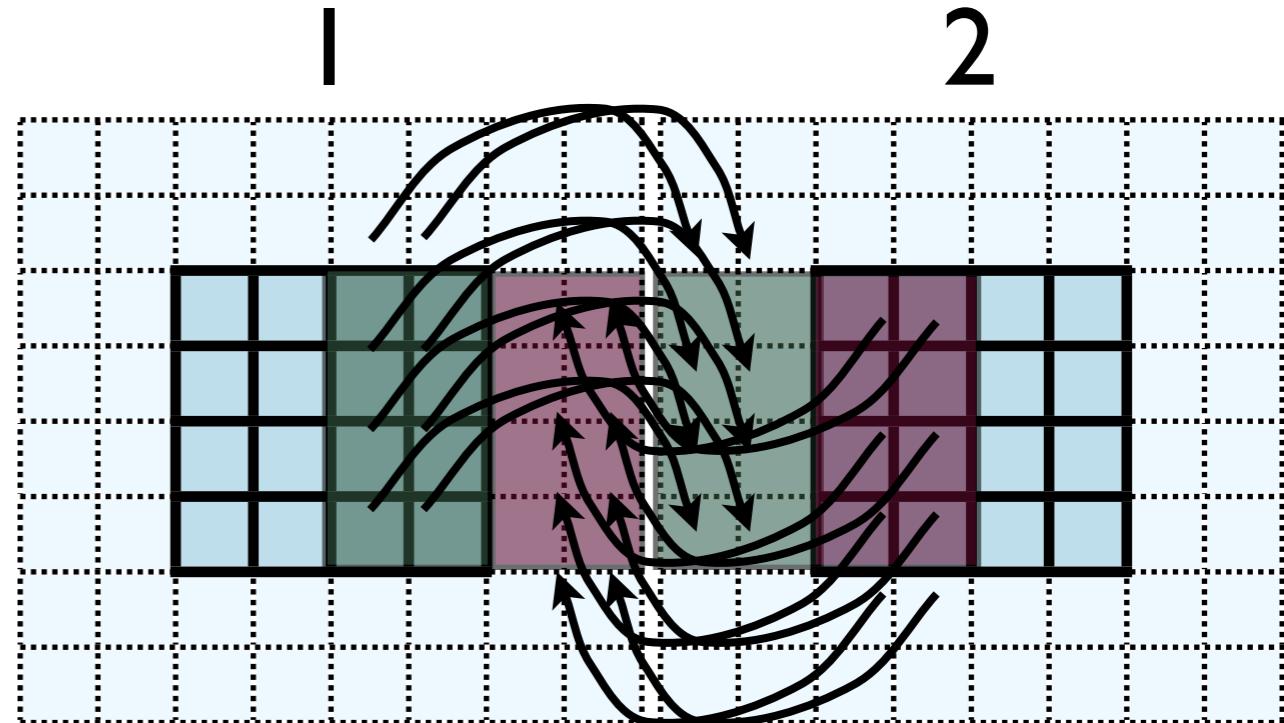
# Implementing in MPI

- No different in principle than diffusion
- Just more values
- And more variables: dens, ener, temp...
- Simplest way: copy all the variables into an NVARS\*(ny-2\*ng)\*ng sized



# Implementing in MPI

- Even simpler way:
- Loop over values, sending each one, rather than copying into buffer.
- NVARS\*nGuard\*(ny-2\*nGuard ) latency hit.
- Would completely dominate communications cost.

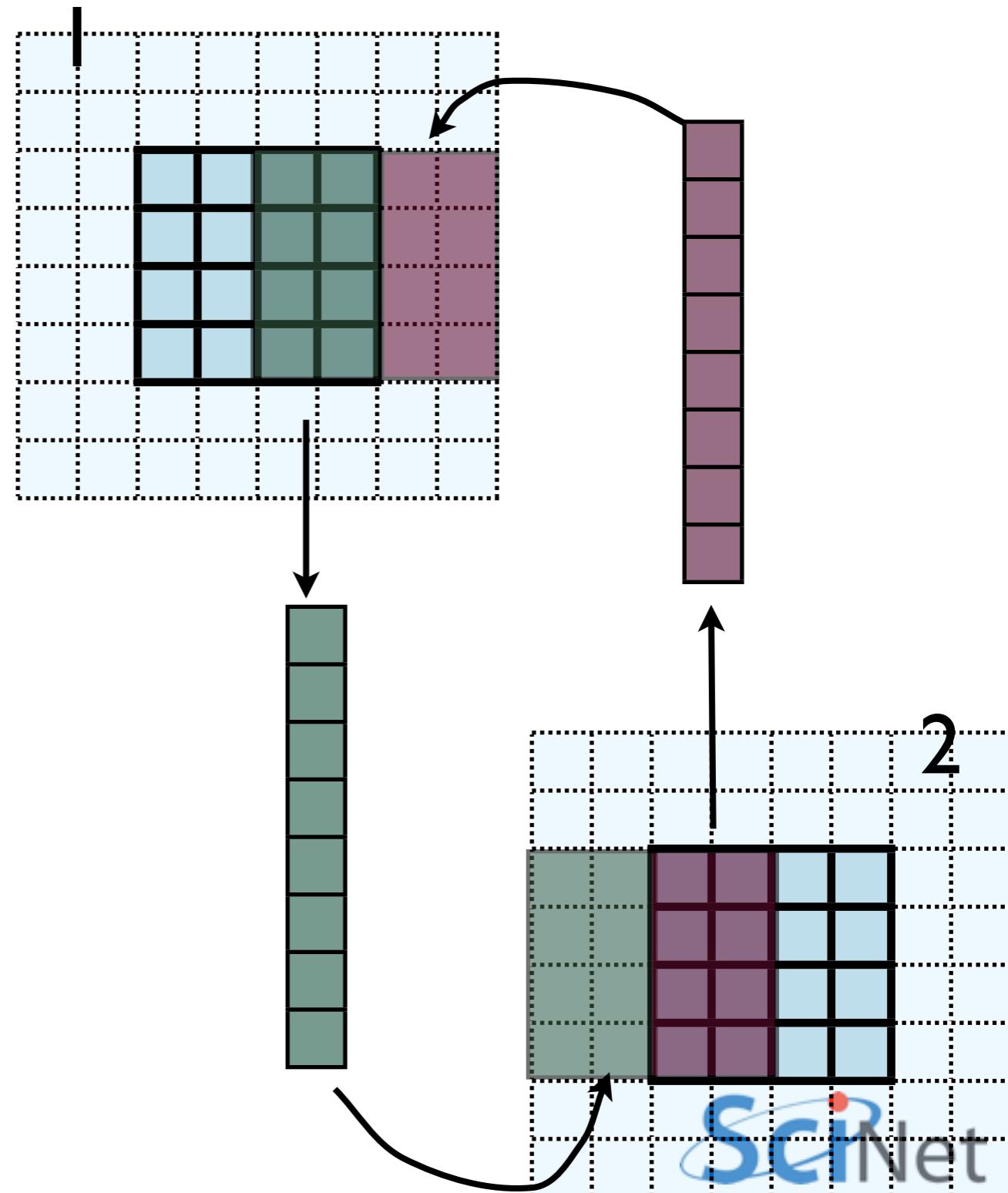


# Implementing in MPI

- Let's do this together
- solver.f90/solver.c; implement  
to bufferGuardcells
- When do we call this in  
timestep?

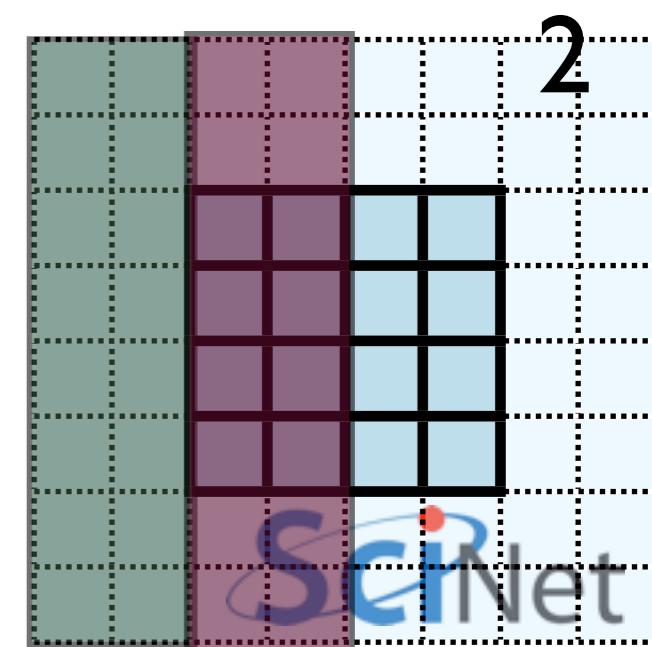
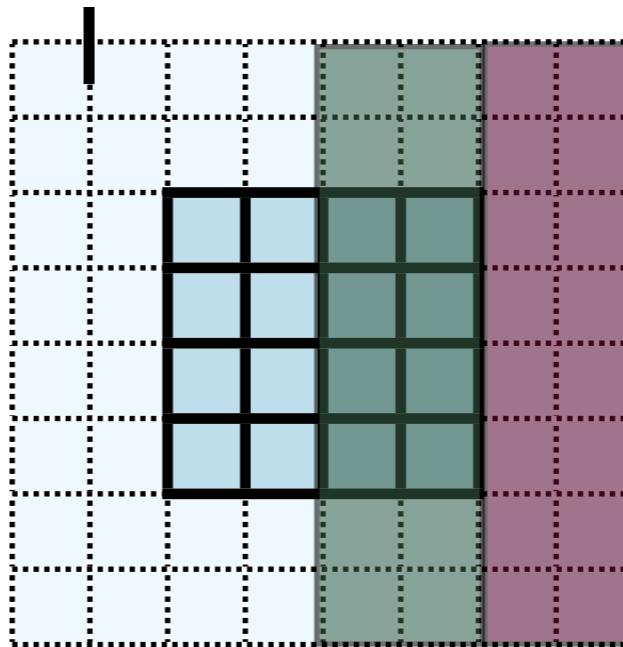
# Implementing in MPI

- This approach is simple, but introduces extraneous copies
- Memory bandwidth is already a bottleneck for these codes
- It would be nice to just point at the start of the guardcell data and have MPI read it from there.



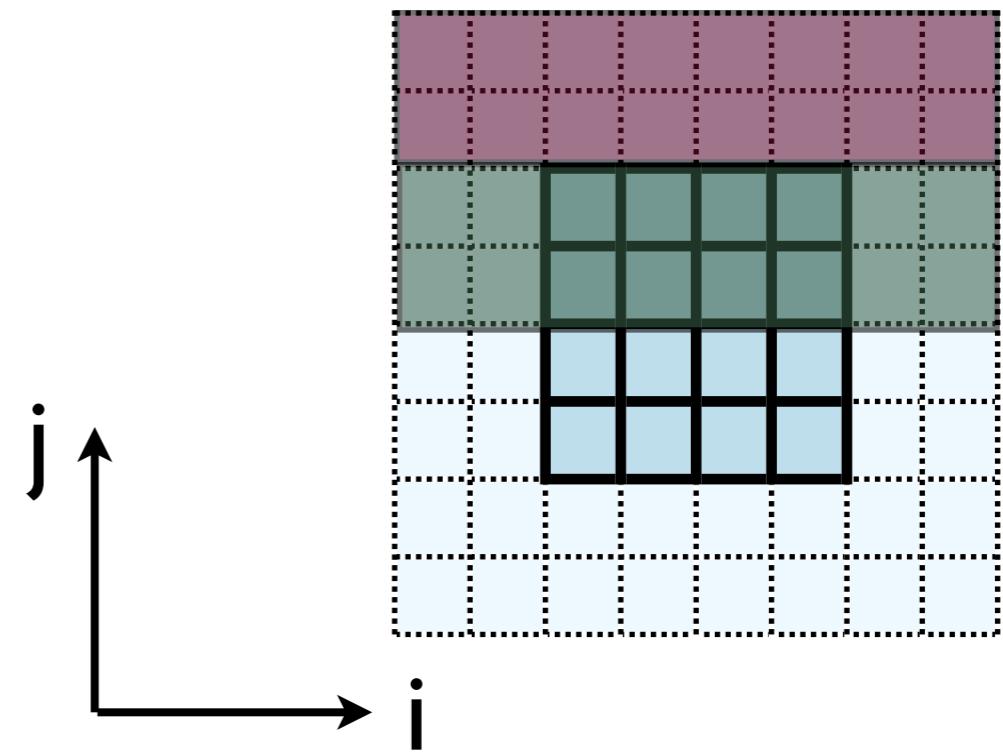
# Implementing in MPI

- Let me make one simplification for now; copy whole stripes
- This isn't necessary, but will make stuff simpler at first
- Only a cost of  $2 \times N_g^2 = 8$  extra cells (small fraction of ~200-2000 that would normally be copied)



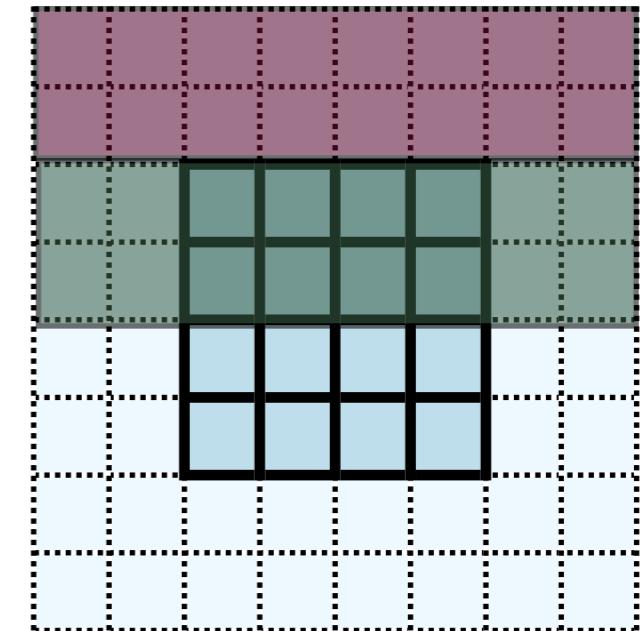
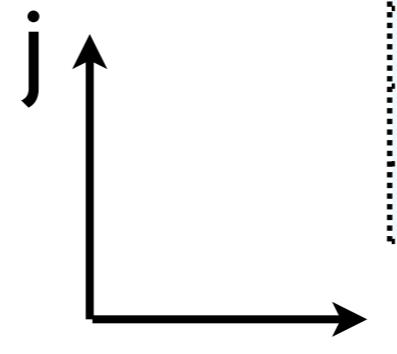
# Implementing in MPI

- Recall how 2d memory is laid out
  - y-direction guardcells contiguous



# Implementing in MPI

- Can send in one go:



```
call MPI_Send(u(1,1,ny), nvars*nguard*ny, MPI_REAL, ....)
ierr = MPI_Send(&(u[ny][0][0]), nvars*nguard*ny, MPI_FLOAT, ....)
```



# Implementing in MPI

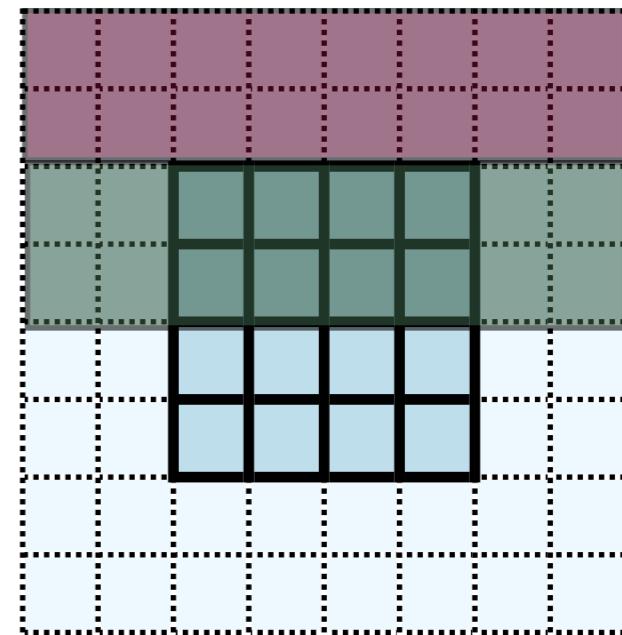
- Creating MPI Data types.
- MPI\_Type\_contiguous:  
simplest case. Lets you build  
a string of some other type.

```
MPI_Datatype ybctype;
```

```
ierr = MPI_Type_contiguous(nvals*nguard*(ny), MPI_REAL, &ybctype);  
ierr = MPI_Type_commit(&ybctype);
```

```
MPI_Send(&(u[ny][0][0]), 1, ybctype, ....)
```

```
ierr = MPI_Type_free(&ybctype);
```

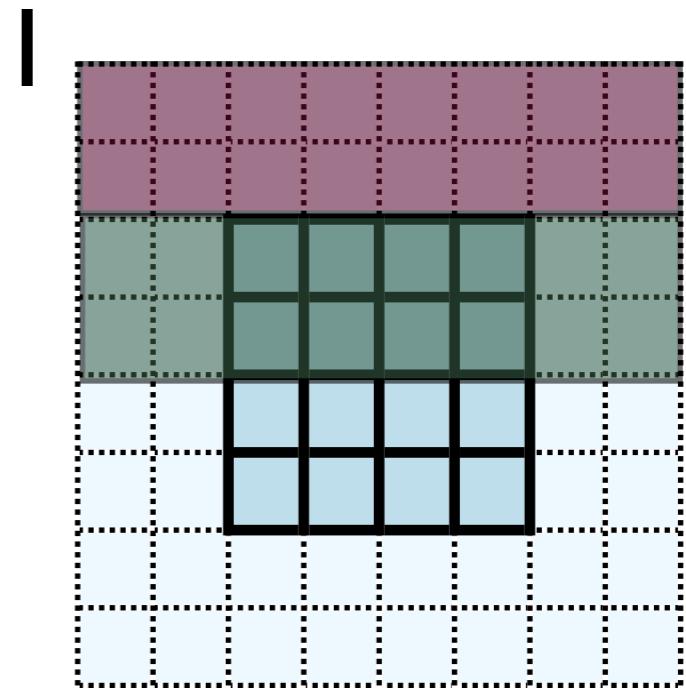


Count    OldType    &NewType

# Implementing in MPI

- Creating MPI Data types.
- MPI\_Type\_contiguous:  
simplest case. Lets you build  
a string of some other type.

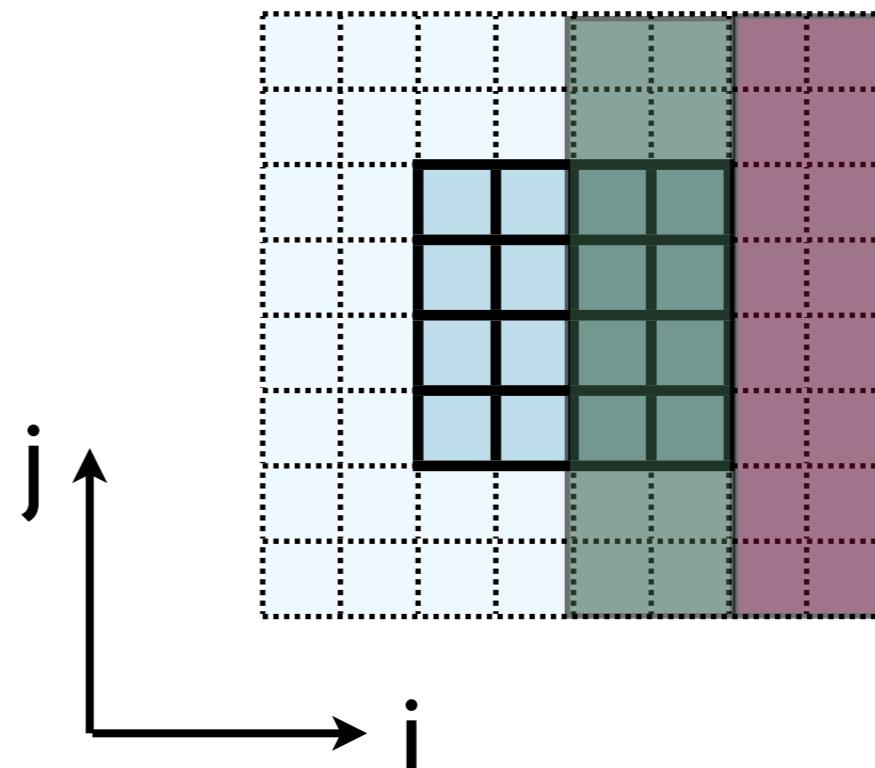
```
integer :: ybctype  
  
call MPI_Type_contiguous(nvals*nguard*(ny), MPI_REAL, ybctype, ierr)  
call MPI_Type_commit(ybctype, ierr)  
  
MPI_Send(u(1,1,ny), 1, ybctype, ....)  
  
call MPI_Type_free(ybctype, ierr)
```



Count    OldType    NewType

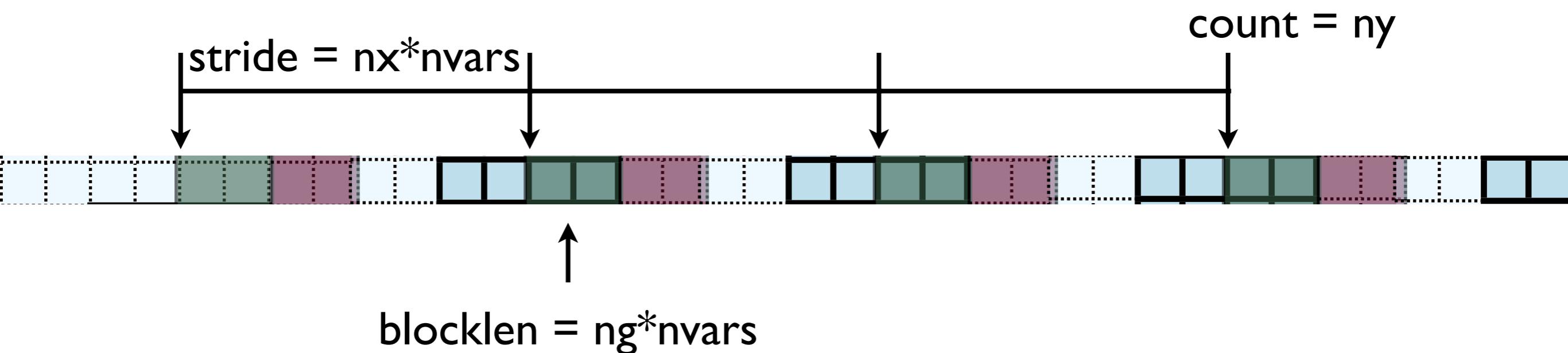
# Implementing in MPI

- Recall how 2d memory is laid out
- x gcs or boundary values *not* contiguous
- How do we do something like this for the x-direction?



# Implementing in MPI

```
int MPI_Type_vector(  
    int count,  
    int blocklen,  
    int stride,  
    MPI_Datatype old_type,  
    MPI_Datatype *newtype );
```



# Implementing in MPI

```
ierr = MPI_Type_vector(ny, nguard*nvars,  
                      nx*nvars, MPI_FLOAT, &xbctype);
```

```
ierr = MPI_Type_commit(&xbctype);
```

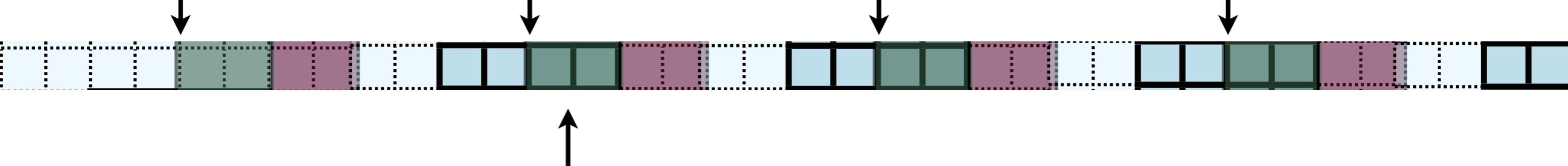
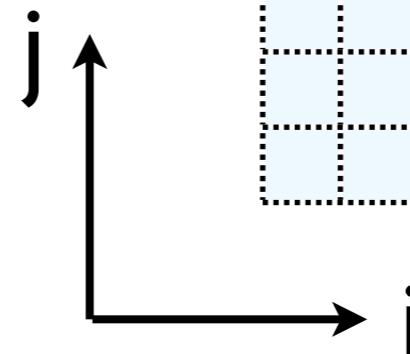
```
ierr = MPI_Send(&(u[0][nx][0]), 1, xbctype, ....)
```

```
ierr = MPI_Type_free(&xbctype);
```

stride =  $nx * nvars$

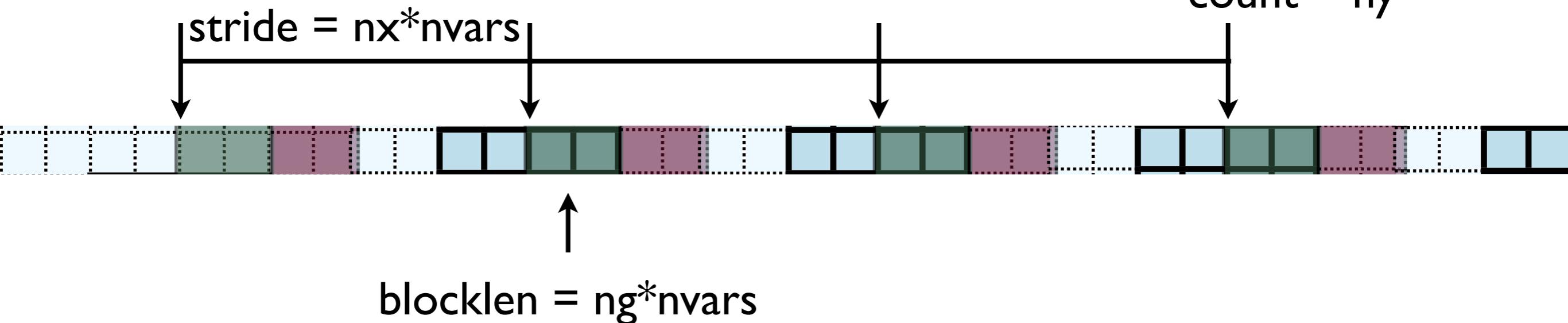
count = ny

blocklen =  $ng * nvars$



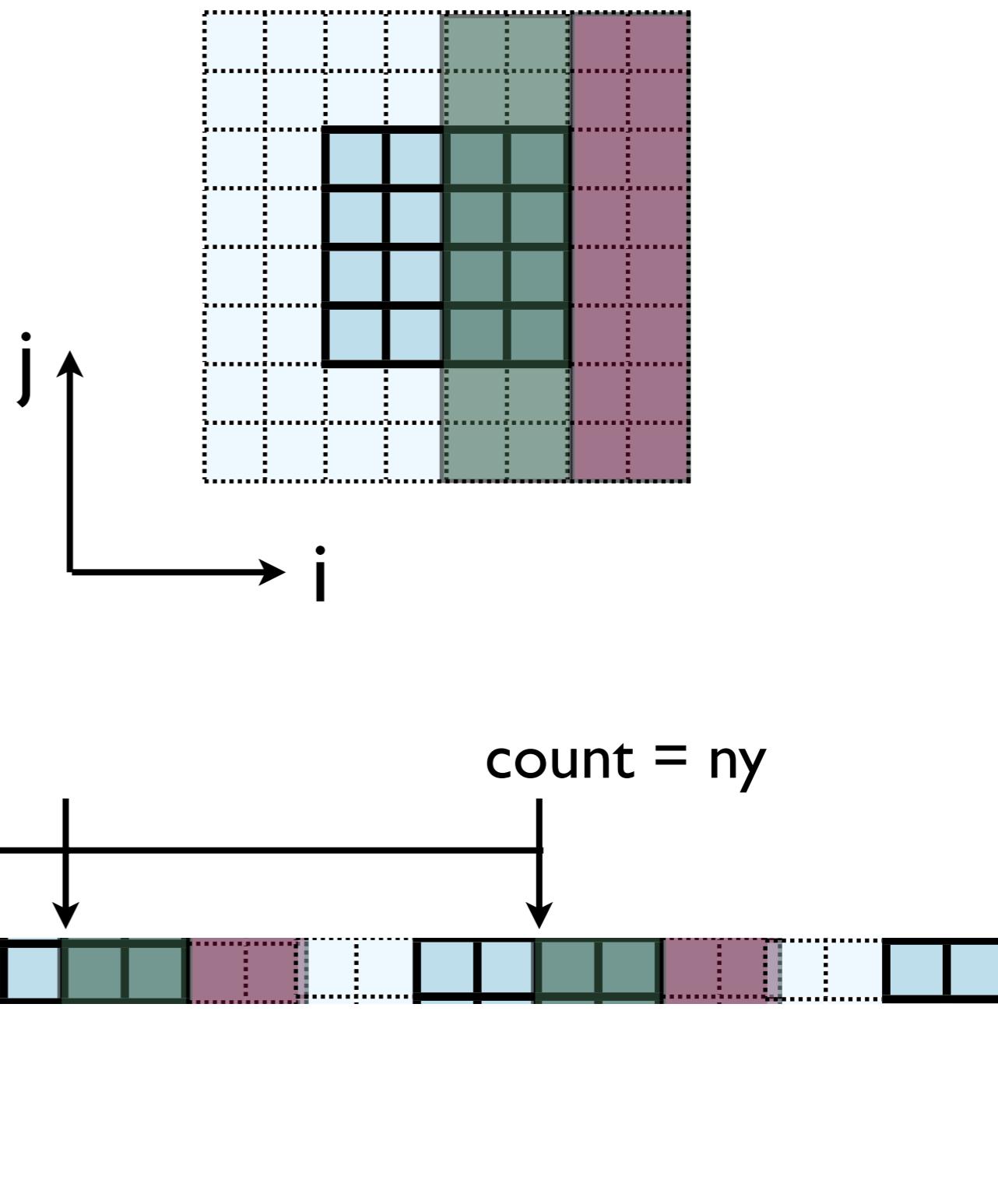
# Implementing in MPI

```
call MPI_Type_vector(ny, nguard*nvars,  
    nx*nvars, MPI_REAL, xbctype, ierr)  
  
call MPI_Type_commit(xbctype, ierr)  
  
call MPI_Send(u(1,nx,1), 1, ybctype, ....)  
  
call MPI_Type_free(xbctype, ierr)
```



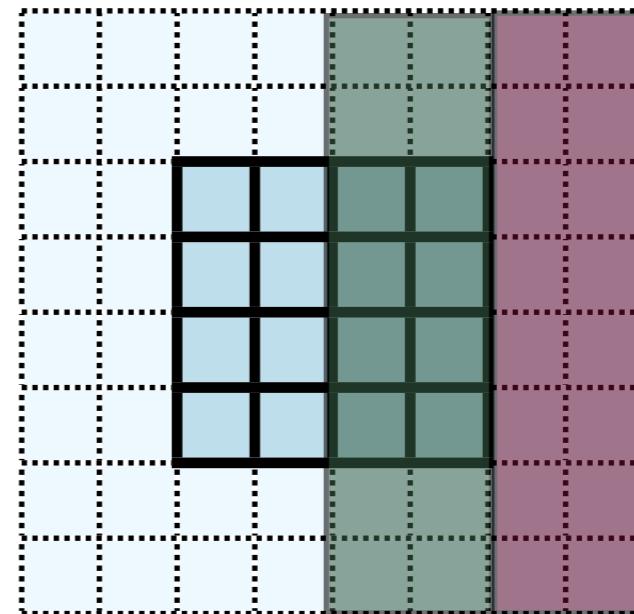
# Implementing in MPI

- Check: total amount of data =  
 $\text{blocklen} * \text{count} = \text{ny} * \text{ng} * \text{nvars}$
- Skipped over  $\text{stride} * \text{count} =$   
 $\text{nx} * \text{ny} * \text{nvars}$



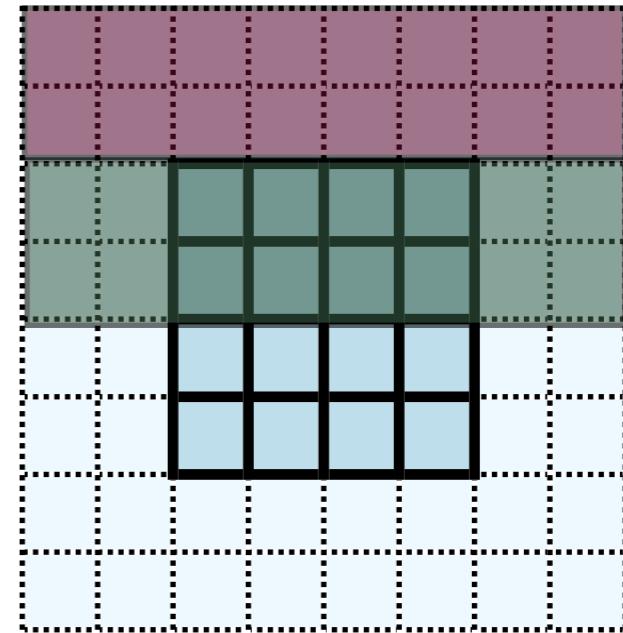
# Implementing in MPI

- Hands-On: Implement X guardcell filling with types.
- Implement vectorGuardCells
- For now, create/free type each cycle through; ideally, we'd create/free these once.



# In MPI, there's always more than one way..

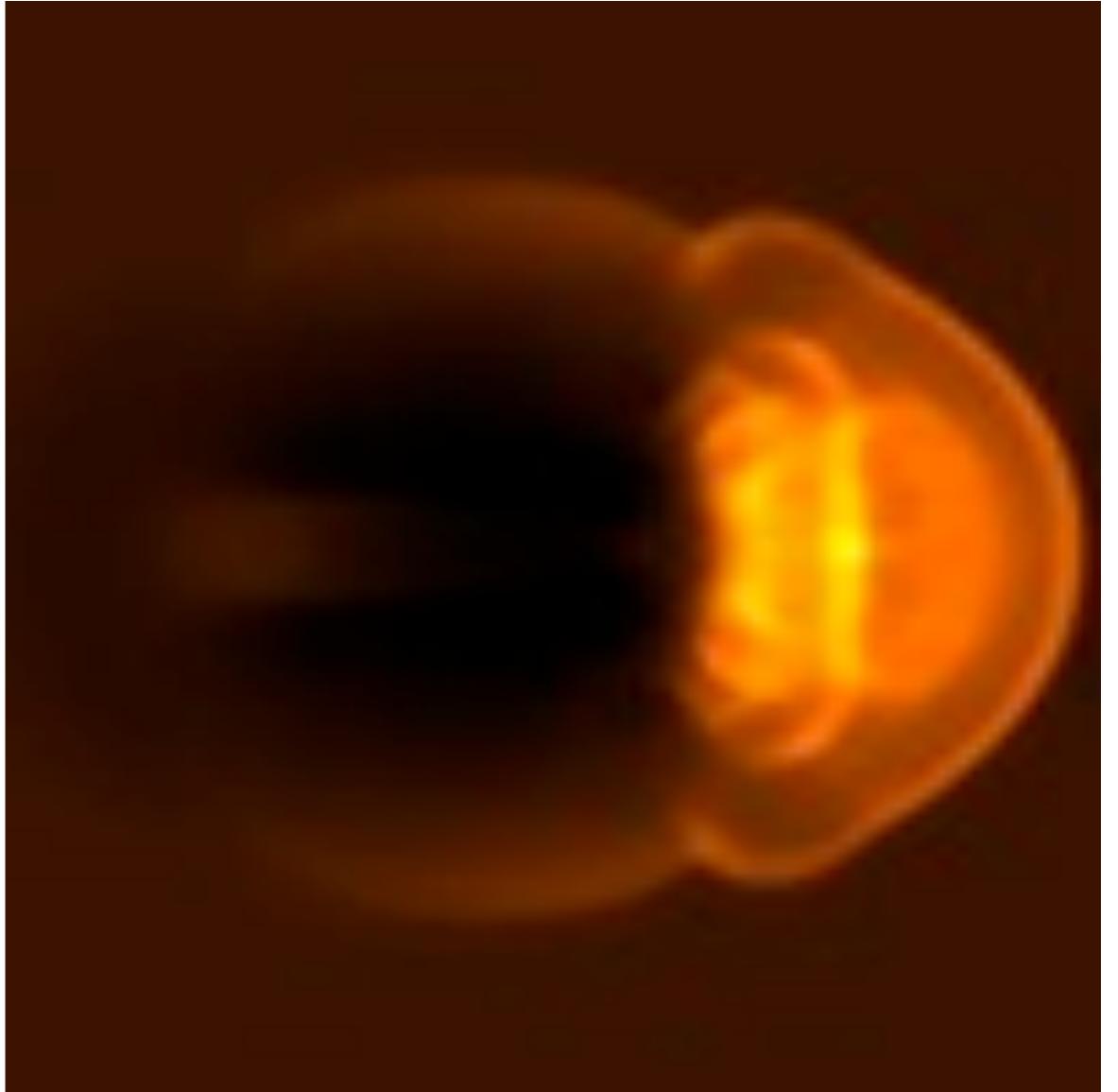
- **MPI\_Type\_create\_subarray** ;  
piece of a multi-dimensional  
array.
- *Much more convenient for  
higher-dimensional arrays*
- *(Otherwise, need vectors of  
vectors of vectors...)*



```
int MPI_Type_create_subarray(  
    int ndims, int *array_of_sizes,  
    int *array_of_subsizes,  
    int *array_of_starts,  
    int order,  
    MPI_Datatype oldtype,  
    MPI_Datatype &newtype);  
  
call MPI_Type_create_subarray(  
    integer ndims, [array_of_sizes],  
    [array_of_subsizes],  
    [array_of_starts],  
    order, oldtype,  
    newtype, ierr)
```

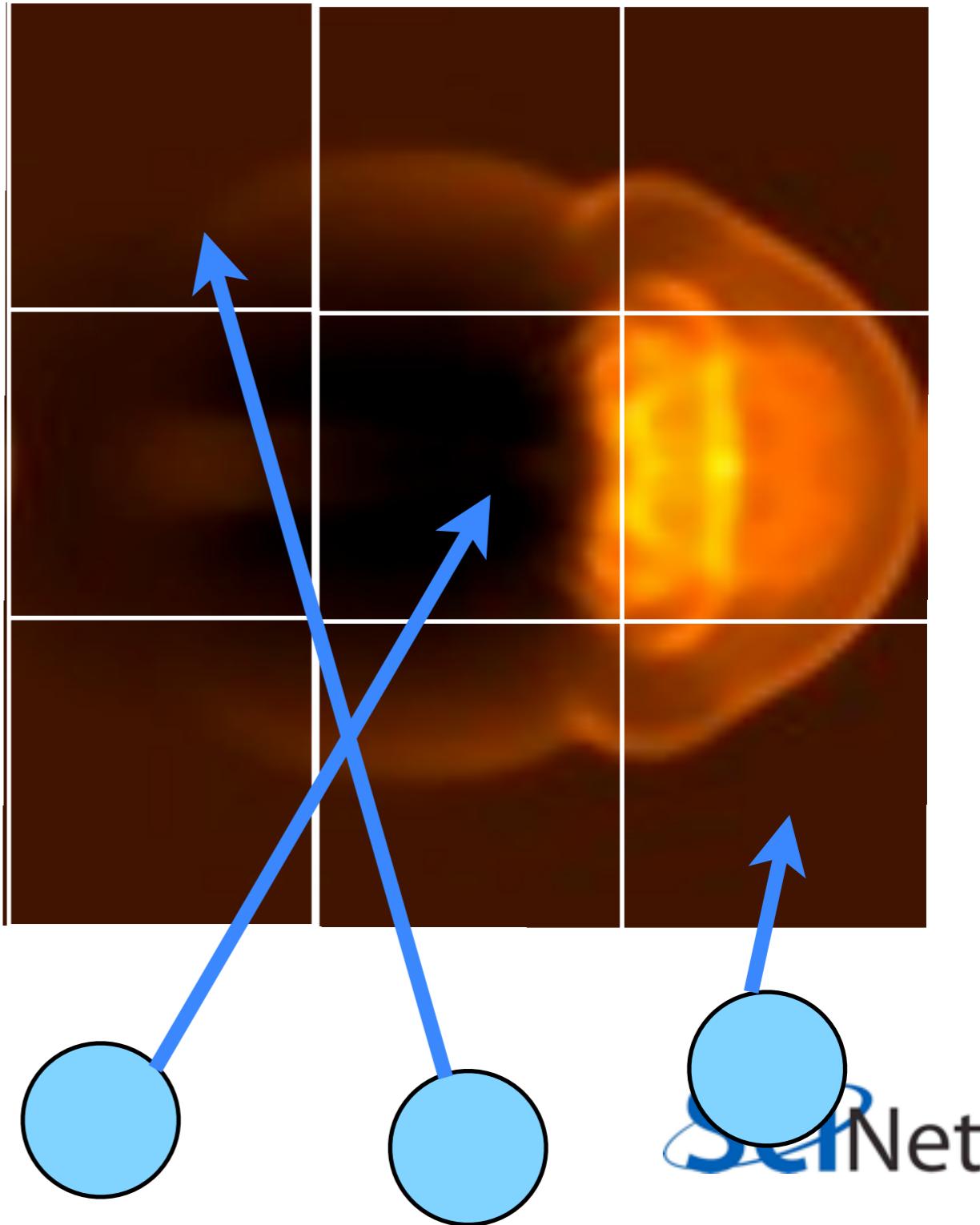
# MPI-IO

- Would like the new, parallel version to still be able to write out single output files.
- But at no point does a single processor have entire domain...



# Parallel I/O

- Each processor has to write its own piece of the domain..
- without overwriting the other.
- Easier if there is global coordination



# MPI-IO

- Uses MPI to coordinate reading/writing to single file

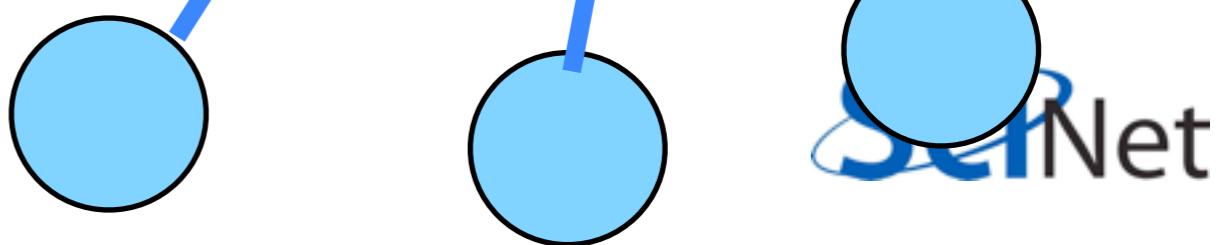


```
ierr = MPI_File_open(MPI_COMM_WORLD,filename, MPI_MODE_WRONLY | MPI_MODE_APPEND , MPI_INFO_NULL, &file);
```

...stuff...

```
ierr = MPI_File_close(&file);
```

- Coordination -- *collective* operations.



# PPM file format

- Simple file format
- Someone has to write a header, then each PE has to output only its 3-bytes pixels skipping everyone else.

header -- ASCII characters

'P6', comments, height/width, max val

```
P6  
# min = 1.00000e+00, max = 4.733462e+01  
100 100  
255  
(rgb)(rgb)(rgb)...  
(rgb)(rgb)(rgb)...
```

row by row triples of bytes: each  
pixel = 3 bytes

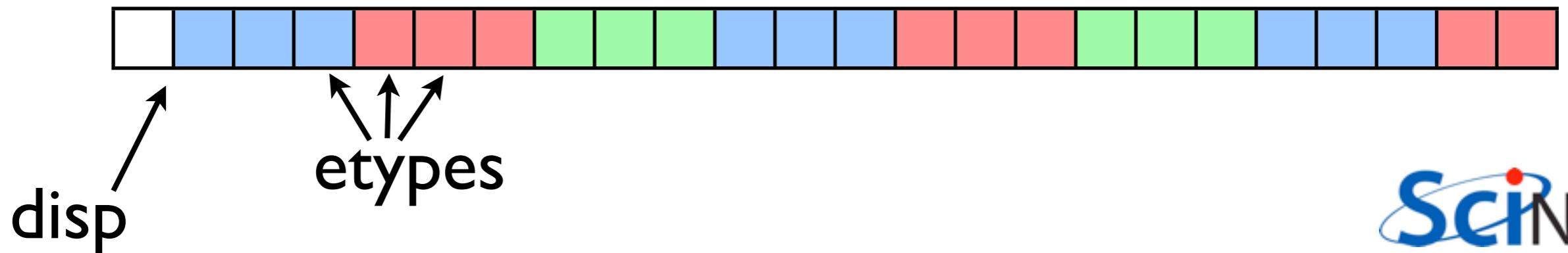
# MPI-IO File View

- Each process has a view of the file that consists of only of the parts accessible to it.
- For writing, hopefully non-overlapping!
- Describing this - how data is laid out in a file - is very similar to describing how data is laid out in memory...



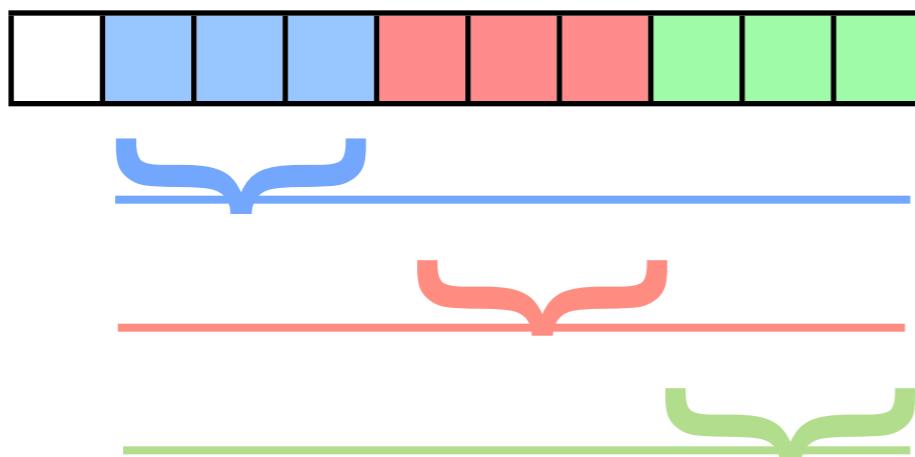
# MPI-IO File View

- `int MPI_File_set_view(  
 MPI_File fh,  
 MPI_Offset disp,  
 MPI_Datatype etype,  
 MPI_Datatype filetype,  
 char *datarep,  
 MPI_Info info)`  
 /\* displacement in bytes from start \*/  
 /\* elementary type \*/  
 /\* file type; prob different for each proc \*/  
 /\* ‘native’ or ‘internal’ \*/  
 /\* MPI\_INFO\_NULL for today \*/



# MPI-IO File View

- `int MPI_File_set_view(  
 MPI_File fh,  
 MPI_Offset disp,  
 MPI_Datatype etype,  
 MPI_Datatype filetype,  
 char *datarep,  
 MPI_Info info)`  
 /\* displacement in bytes from start \*/  
 /\* elementary type \*/  
 /\* file type; prob different for each proc \*/  
 /\* ‘native’ or ‘internal’ \*/  
 /\* MPI\_INFO\_NULL \*/



Filetypes (made up of etypes;  
repeat as necessary)

# MPI-IO File Write

- `int MPI_File_write_all(  
 MPI_File fh,  
 void *buf,  
 int count,  
 MPI_Datatype datatype,  
 MPI_Status *status)`

Writes (`_all`: collectively) to part of file within view.

# Hands On

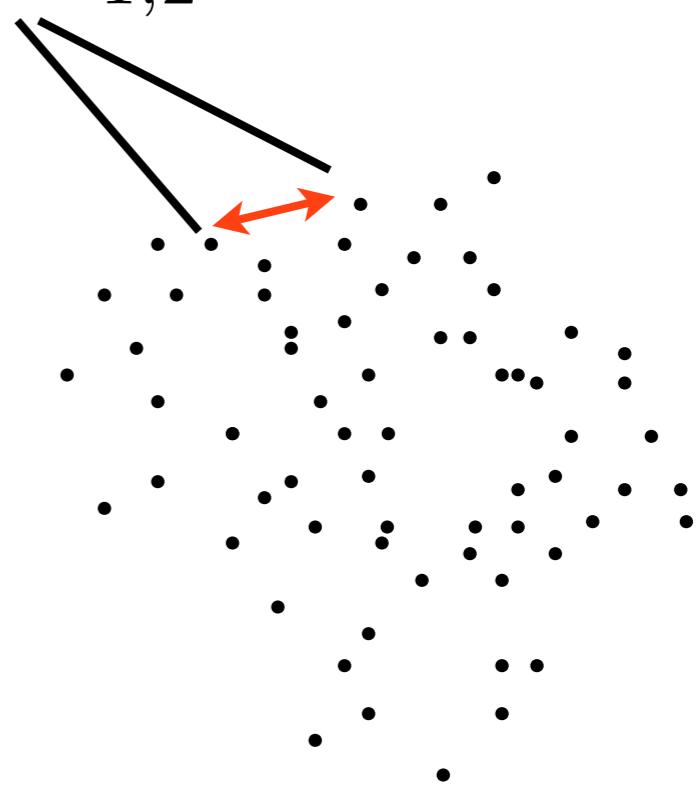
- Implement the ppm routines collectively using the subarray type.

# **N-Body Dynamics**

# N-Body dynamics

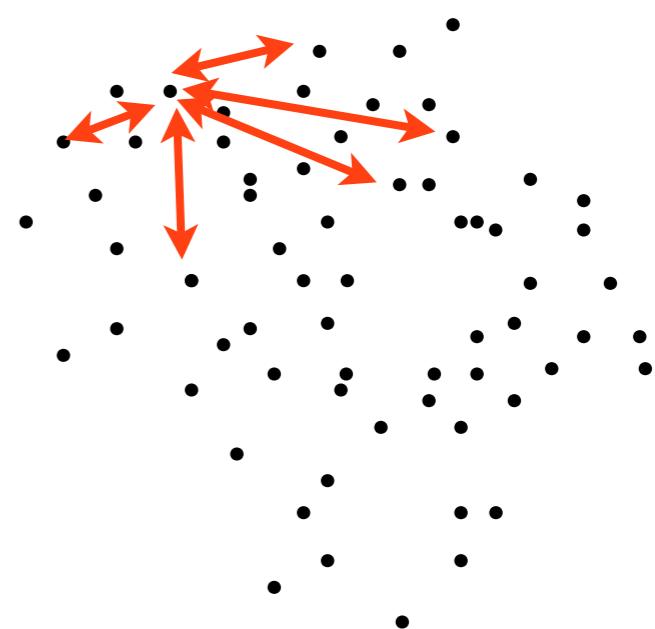
- N interacting bodies
- Pairwise forces; here, Gravity.
- (here, stars in a cluster; could be molecular dynamics, economic agents...)

$$F_{1,2} = -\frac{Gm_1m_2}{r_{1,2}^2}\hat{\mathbf{r}}$$



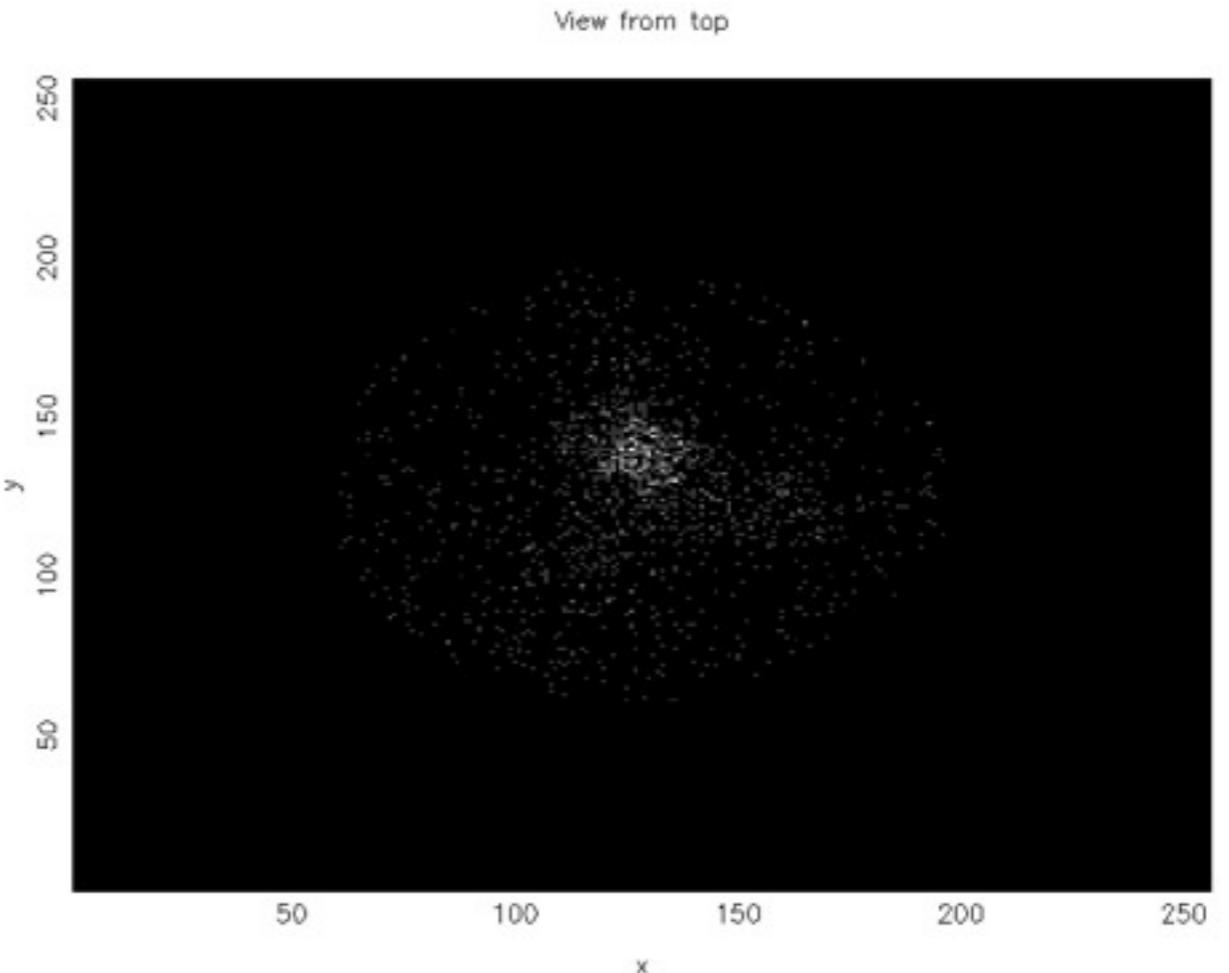
# N-Body dynamics

- N interacting bodies
- Pairwise forces; here, Gravity.
- (here, stars in a cluster; could be molecular dynamics, economic agents...)



# nbody

- cd ~mpi/nbodyc
- make
- ./nbodyc



# A Particle type

- Everything based on a array of structures ('derived data types')

```
type Nbody
    integer :: id
    double precision, dimension(3) :: x
    double precision, dimension(3) :: vel
    double precision, dimension(3) :: force
    double precision :: mass
    double precision :: potentialE
end type Nbody
```

nbody.f90, line 5

# Main loop

- nbody\_step - calls calculate forces, updates positions.
- calculate energy (diagnostic)
- display particles.

```
call initialize_particles(pdata, npts, simula
call calculate_forces_fastest(pdata, npts)
call calculate_energy(pdata, npts, tote)

do i=1,nsteps
    call nbody_step(pdata, npts, dt)
    call calculate_energy(pdata, npts, tote)
    time = time + dt
    if (output /= 0) then
        print *, i, dt, time, tote
        if (mod(i,outevery) == 0) then
            call display_particles(pdata, npts,
        endif|
    endif
enddo
```

nbody.f90, line 35

# Calculate Forces

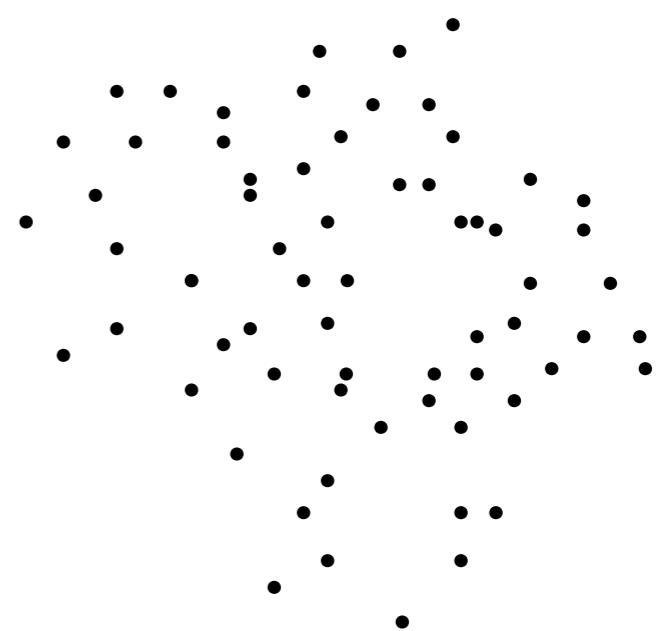
- For each particle i
- For each other particle j>i
- Calculate distance (most expensive!)
- Increment force
- Increment potential energy

```
do i=1,n
  do j=i+1,n
    rsq = EPS*EPS
    dx = 0.
    do d=1,3
      dx(d) = pdata(j)%x(d) - pdata(i)%x(d)
      rsq = rsq + dx(d)*dx(d)
    enddo
    ir = 1./sqrt(rsq)
    rsq = ir/rsq
    do d=1,3
      forcex = rsq*dx(d) * pdata(i)%mass * pdata(j)%mass
      pdata(i)%force(d) = pdata(i)%force(d) + forcex
      pdata(j)%force(d) = pdata(j)%force(d) - forcex
    enddo
    pdata(i)%potentialE = pdata(i)%potentialE -
      gravconst * pdata(i)%mass * pdata(j)%mass * ir
    pdata(j)%potentialE = pdata(i)%potentialE -
      gravconst * pdata(i)%mass * pdata(j)%mass * ir
  enddo
enddo
```

nbody.f90, line 100

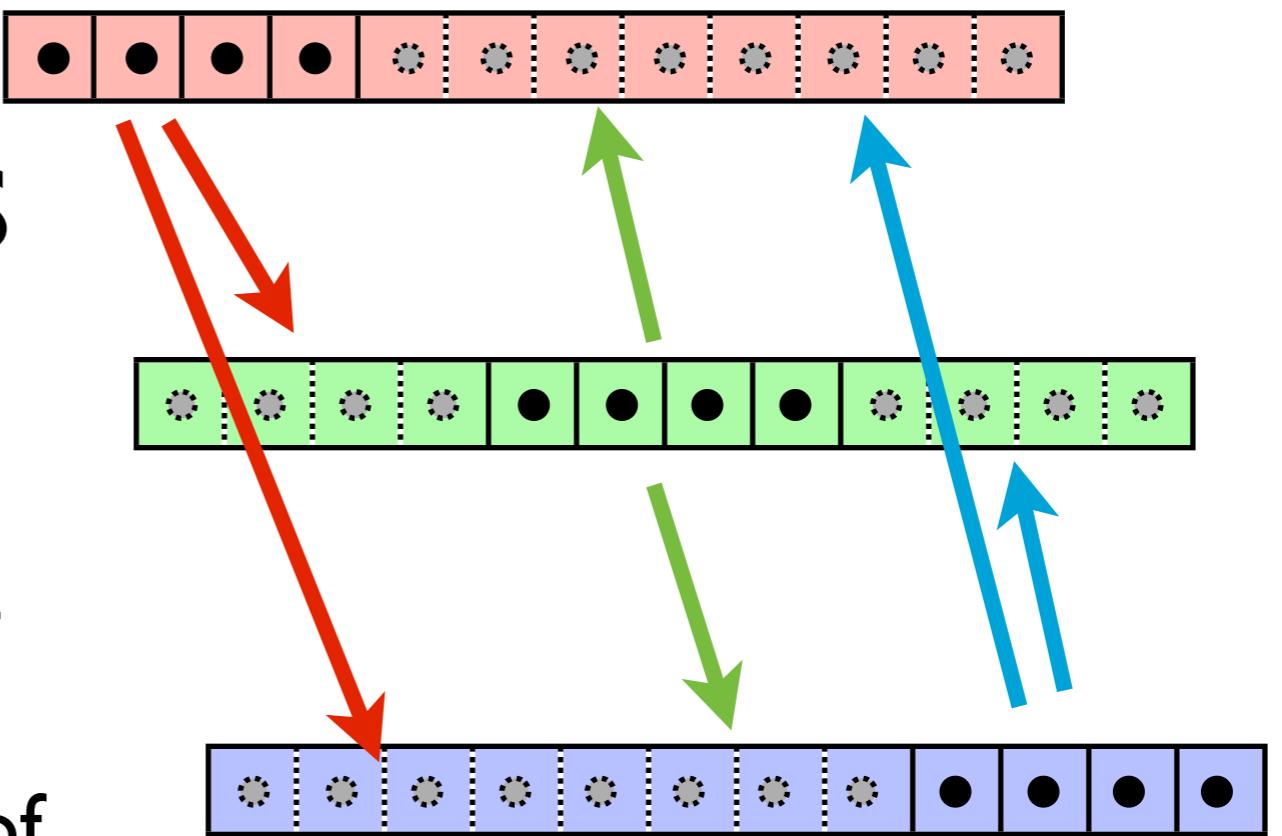
# Decomposing onto different processors

- Direct summation ( $N^2$ ) - each particle needs to know about all other particles
- Limited locality possible
- Inherently a difficult problem to parallelize in distributed memory



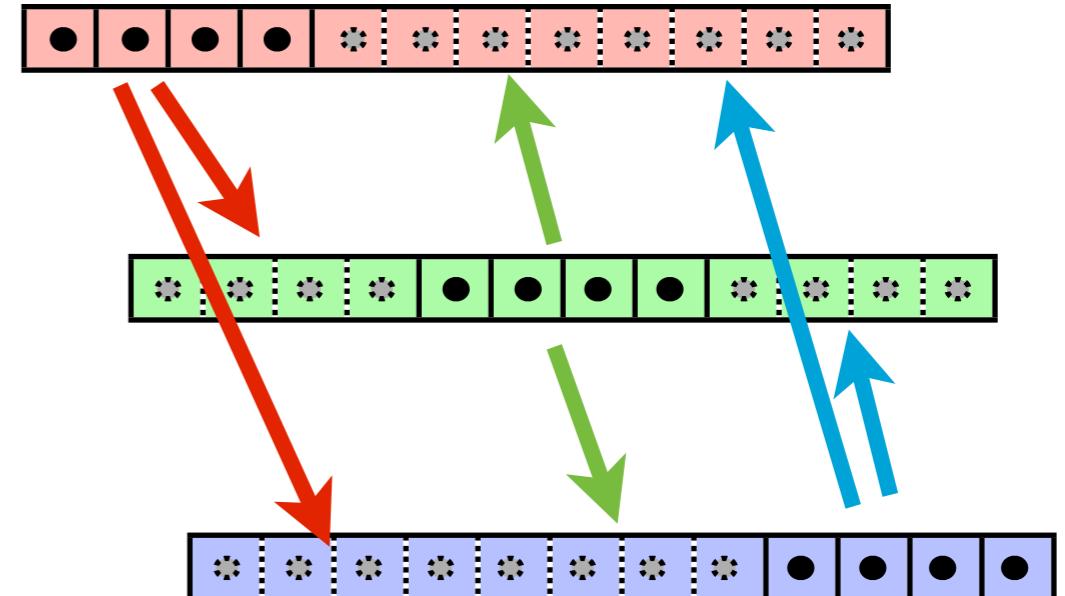
# First go: Everyone sees everything

- Distribute the work, but not the data
- Everyone has complete set of particle data
- Just work on our own particles
- Send everyone our particles' data afterwards



# Terrible Idea (I)

- Requires the entire problem to fit in the memory of each node.
- In general, you can't do that ( $10^{10-11}$  particle simulation)
- No good for MD, astrophysics but could be useful in other areas (few bodies, complicated interactions) - agent-based simulation
- Best approach depends on your problem



# Terrible Idea

(II)

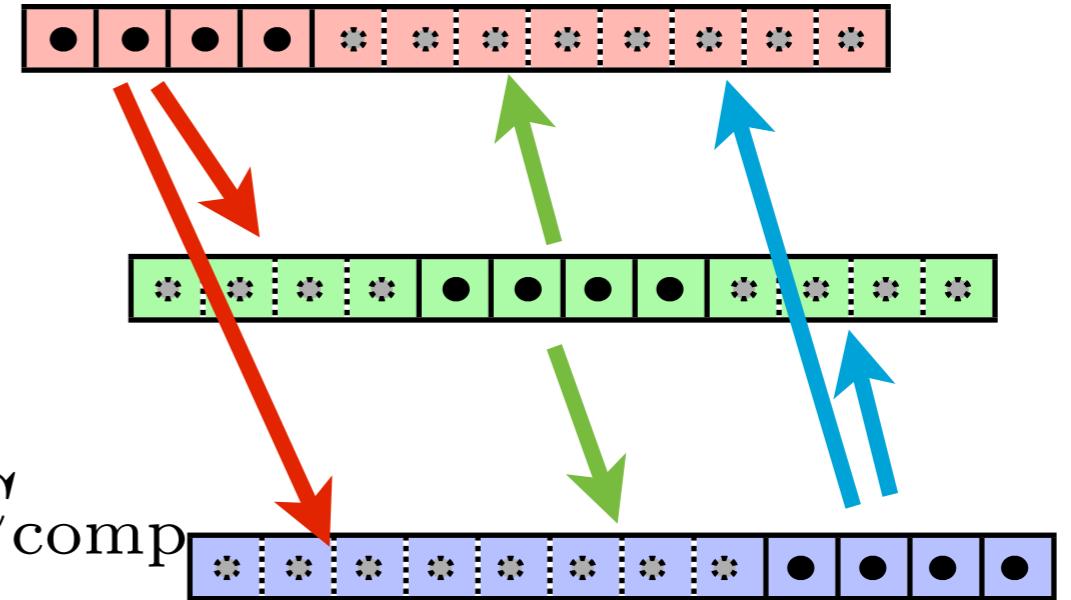
$$T_{\text{comp}} \sim c_{\text{grav}} \left( \frac{N}{P} \right) N C_{\text{comp}}$$

$$= c_{\text{grav}} \frac{N^2}{P} C_{\text{comp}}$$

$$T_{\text{comm}} \sim c_{\text{particle}} \frac{N}{P} (P - 1) C_{\text{comm}}$$

$$\approx c_{\text{particle}} N C_{\text{comm}}$$

$$\frac{T_{\text{comm}}}{T_{\text{comp}}} \approx \frac{c_{\text{particle}}}{c_{\text{grav}}} \frac{1}{N} P \frac{C_{\text{comm}}}{C_{\text{comp}}}$$

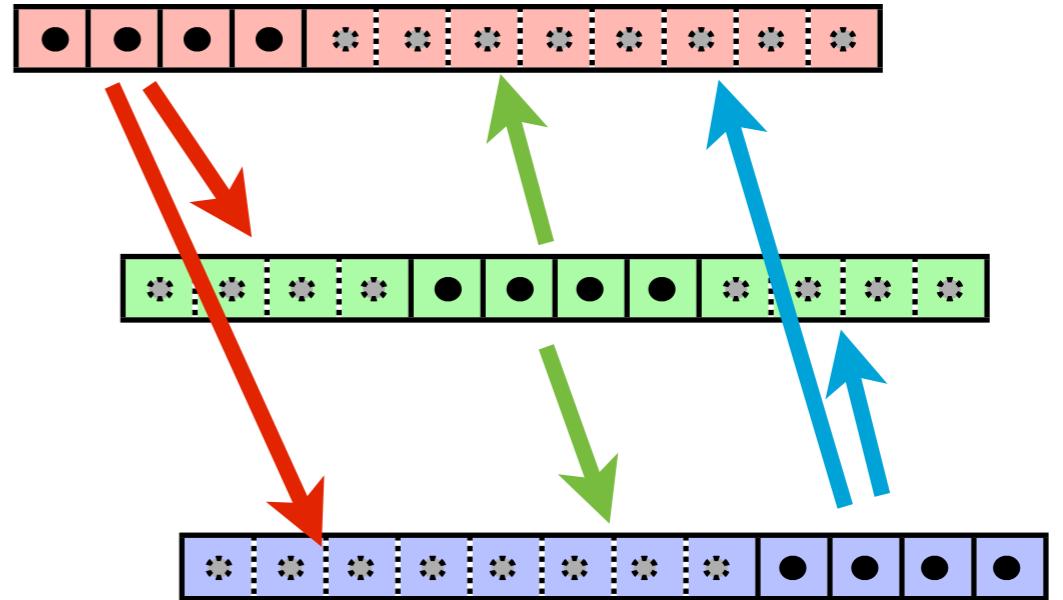


Since  $N$  is fixed, as  $P$  goes up, this fraction gets worse and worse

 SciNet

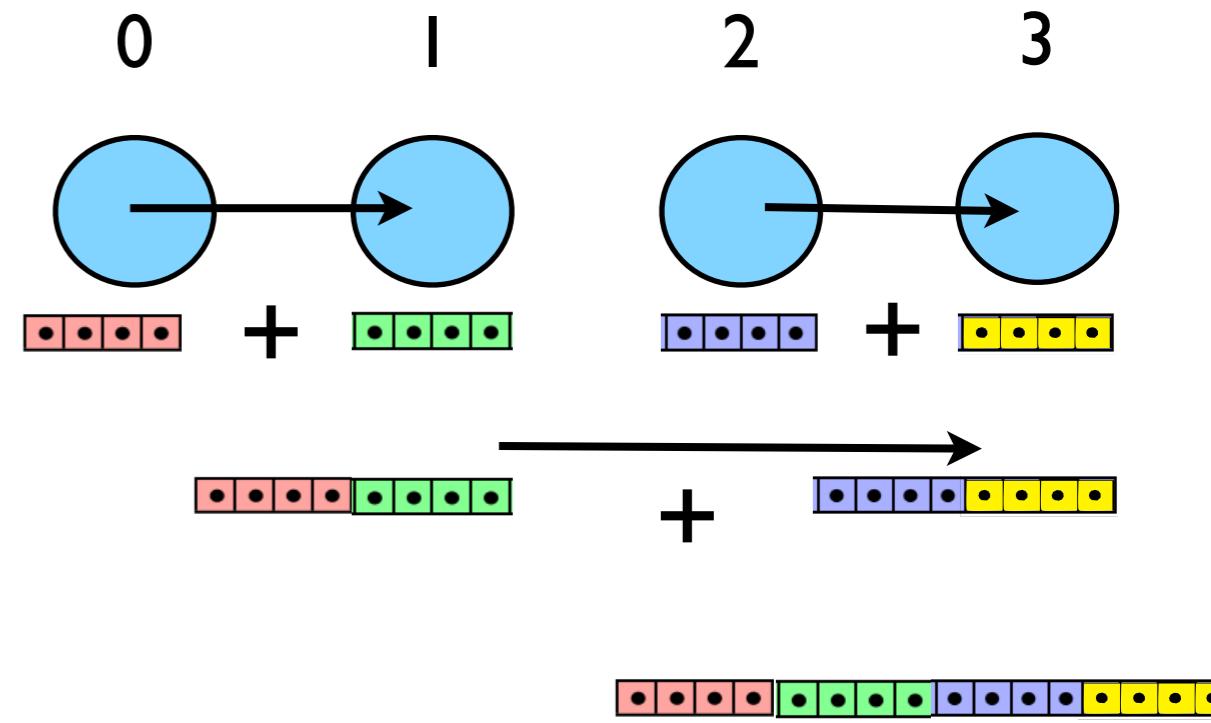
# Terrible Idea (III)

- Wastes computation.
- Proc 0 and Proc 2 both calculate the force between particle I and particle II.



# Can address (II) a little

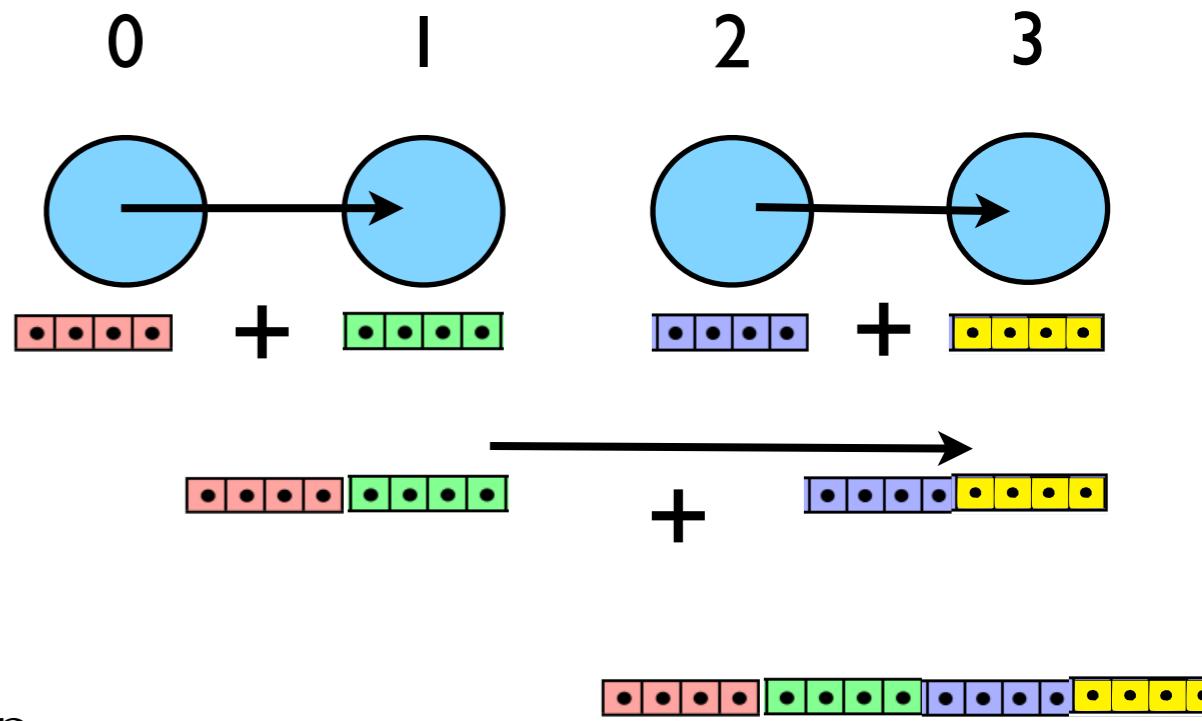
- Collecting everyone's data is like a global sum
- (Concatenation is the sort of operation that allows reduction)
- GATHER operation
- Send back the results:  
ALLGATHER
- $2(P-I)$  vs  $P^2$  messages, but length differs



$$\begin{aligned} \text{Avg Message Length} \\ = & (N/2 \log_2 P)/(P-I) \\ \sim & N + N/P \log_2(P) \end{aligned}$$

Total sent ~  
 $2 N \log_2(P)$  vs  $N P$

Can address (I)  
a little

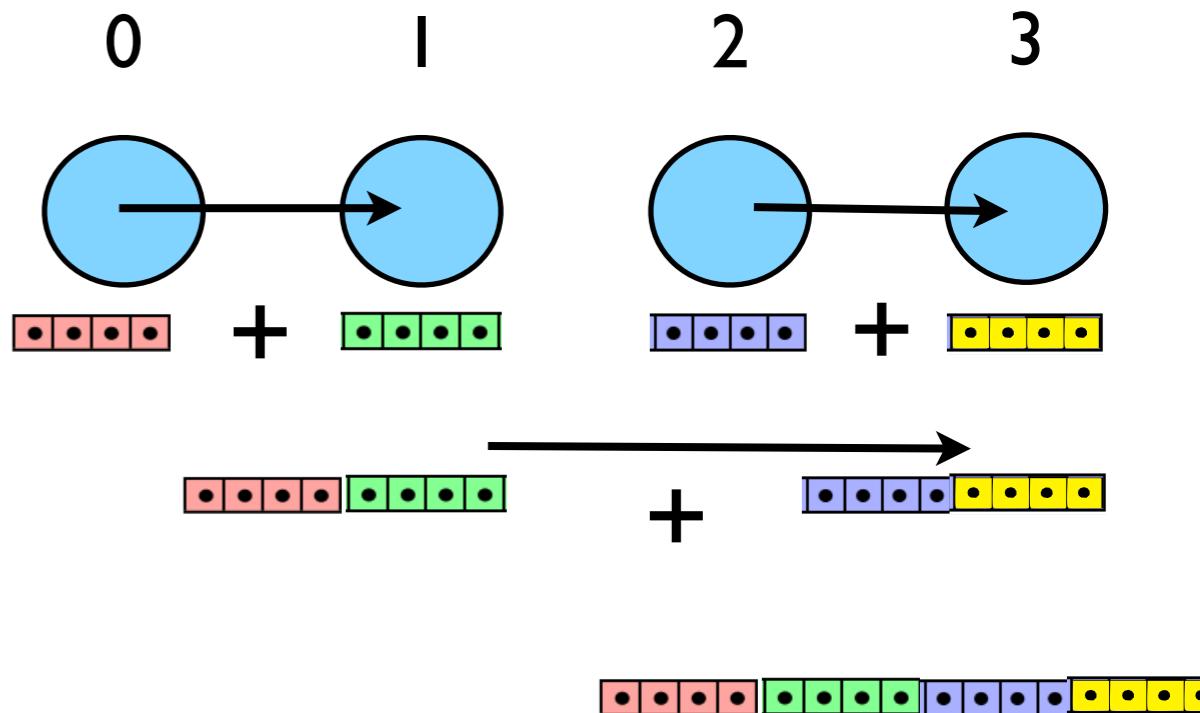


$$T_{\text{comp}} = c_{\text{grav}} \frac{N^2}{P} C_{\text{comp}}$$

$$T_{\text{comm}} \sim c_{\text{particle}} 2N \frac{\log_2 P}{P} C_{\text{comm}}$$

$$\frac{T_{\text{comm}}}{T_{\text{comp}}} \approx \frac{c_{\text{particle}}}{c_{\text{grav}}} \frac{2}{N} \log_2 (P) \frac{C_{\text{comm}}}{C_{\text{comp}}}$$

# Another collective operation



Stuff you're  
sending

How Much

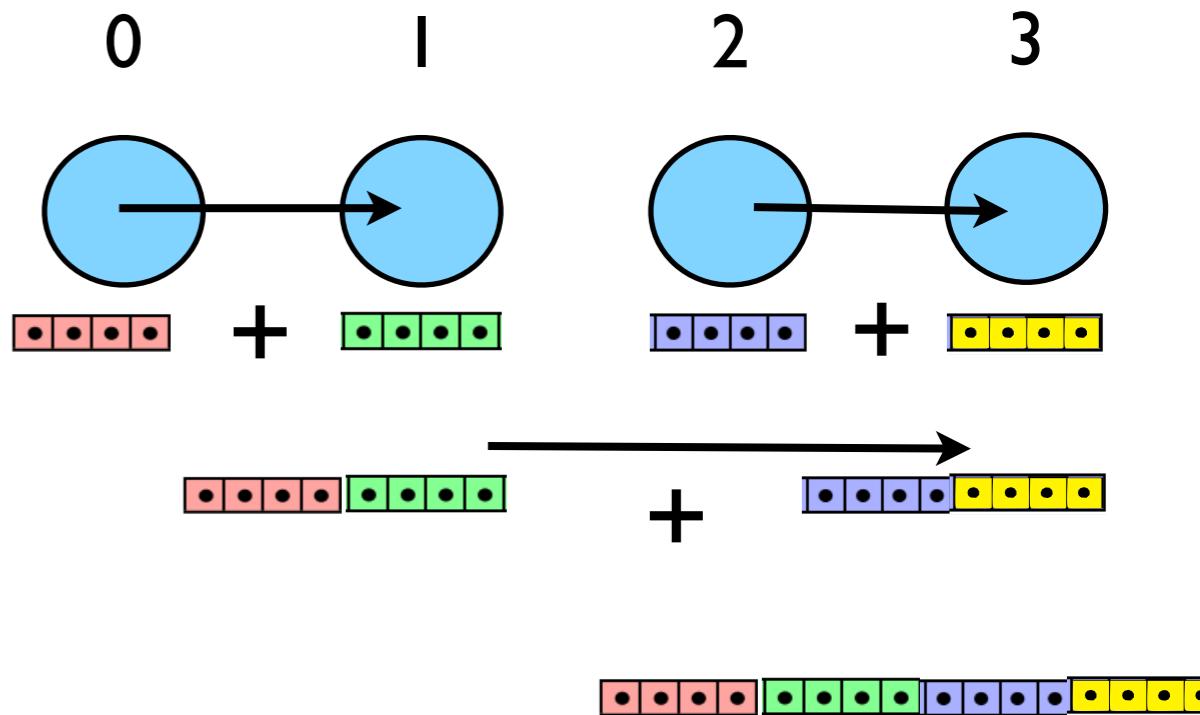
What Type

```
int MPI_Gather (void *sendbuf, int sendcnt, MPI_Datatype sendtype,  
                void *recvbuf, int recvcount, MPI_Datatype recvtype,  
                int root, MPI_Comm comm);
```

Place you're  
receiving

Who's getting all  
the data

# Another collective operation



Stuff you're  
sending

How Much

What Type

```
MPI_GATHER (sendbuf, INTEGER sendcnt, INTEGER sendtype,  
            recvbuf, INTEGER recvcount, INTEGER recvtype,  
            INTEGER root, INTEGER comm, INTEGER ierr);
```

Place you're  
receiving

Who's getting all  
the data

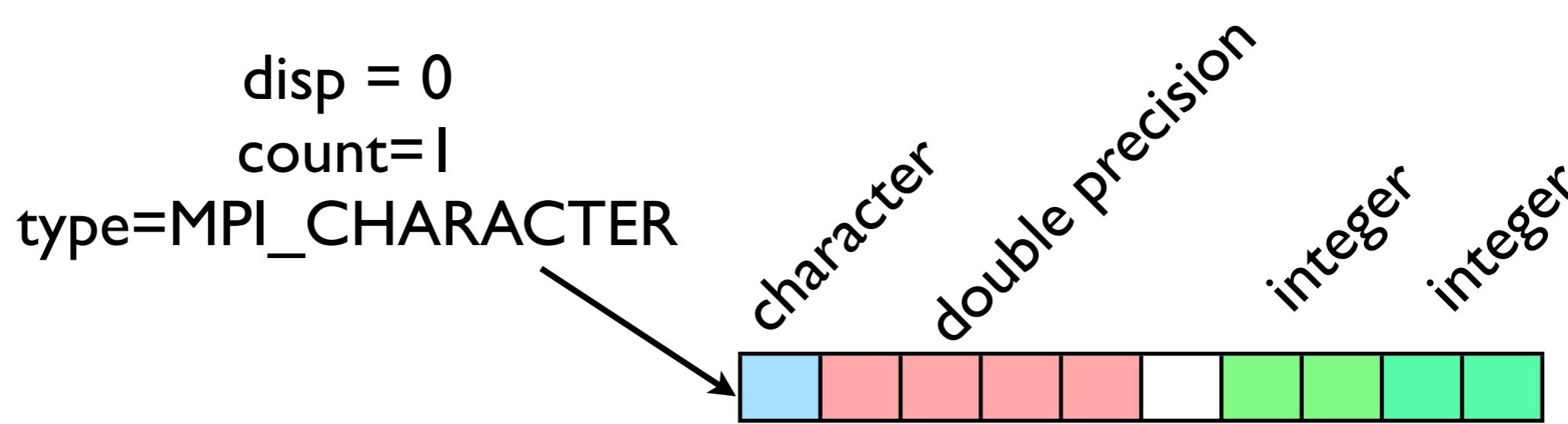
# But what data type should we use?

- Not just a multiple of a single data type
- Contiguous, vector, subarray types won't do it.

```
type Nbody
    integer :: id
    double precision, dimension(3) :: x
    double precision, dimension(3) :: vel
    double precision, dimension(3) :: force
    double precision :: mass
    double precision :: potentialE
end type Nbody
```

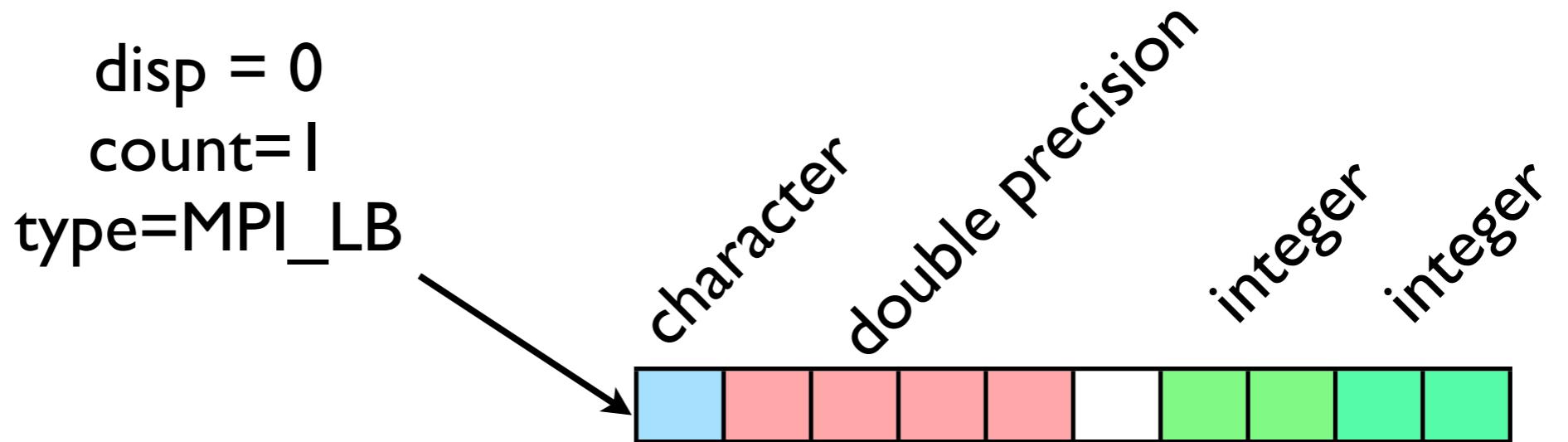
```
MPI_TYPE_CREATE_STRUCT(INTEGER COUNT, INTEGER ARRAY_OF_BLOCKLENGTHS(*),
                      INTEGER(KIND=MPI_ADDRESS_KIND) ARRAY_OF_DISPLACEMENTS(*),
                      INTEGER ARRAY_OF_TYPES(*), INTEGER NEWTYPE, INTEGER IERROR)
```

```
int MPI_Type_create_struct(int count, int array_of_blocklengths[],
                           MPI_Aint array_of_displacements[], MPI_Datatype array_of_types[],
                           MPI_datatype *newtype);
```



# MPI Structures

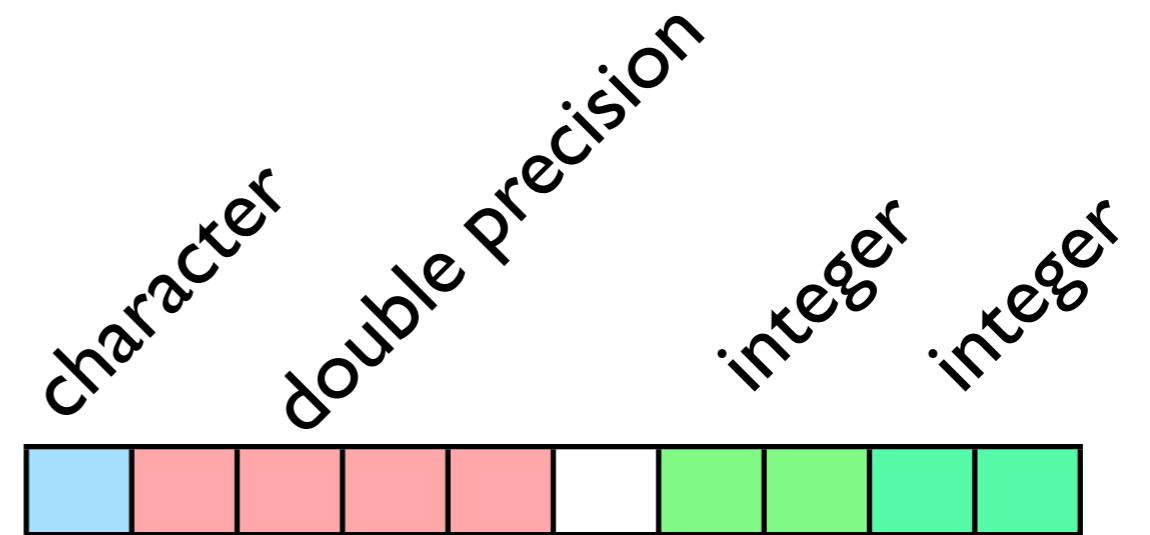
- Like vector, but:
  - displacements in bytes
  - array of types
- `disp = 0`  
`count=1`  
`type=MPI_CHARACTER`
- `character`  
`double precision`  
`integer`  
`integer`
- `disp = 7`  
`count=2`  
`type=MPI_INTEGER`
- `disp = 1`  
`count=1`  
`type=MPI_DOUBLE_PRECISION`



# MPI Structures

- Types `MPI_LB` and `MPI_UB` can point to lower and upper bounds of the structure, as well

`disp = 1`  
`count=1`  
`type=MPI_UB`



# MPI Type Maps

- Complete description of this structure looks like:

`blocklens = (1,1,1,2,1)`

`displacements = (0,0,1,6,10)`

`types = (MPI_LB, MPI_CHARACTER,  
MPI_DOUBLE_PRECISION, MPI_INTEGER, MPI_UB)`

- Note typemaps not unique; could write the integers out as two single integers with displacements 6, 8.

# MPI Type Maps

- What does type map look like for Nbody?

```
type Nbody
    integer :: id
    double precision, dimension(3) :: x
    double precision, dimension(3) :: vel
    double precision, dimension(3) :: force
    double precision :: mass
    double precision :: potentialE
end type Nbody
```

# MPI Type Maps

- What does type map look like for Nbody?
- How laid out in memory depends entirely on compiler, compiler options.
- alignment, padding...

```
type Nbody
    integer :: id
    double precision, dimension(3) :: x
    double precision, dimension(3) :: vel
    double precision, dimension(3) :: force
    double precision :: mass
    double precision :: potentialE
end type Nbody
```

# MPI Type Maps

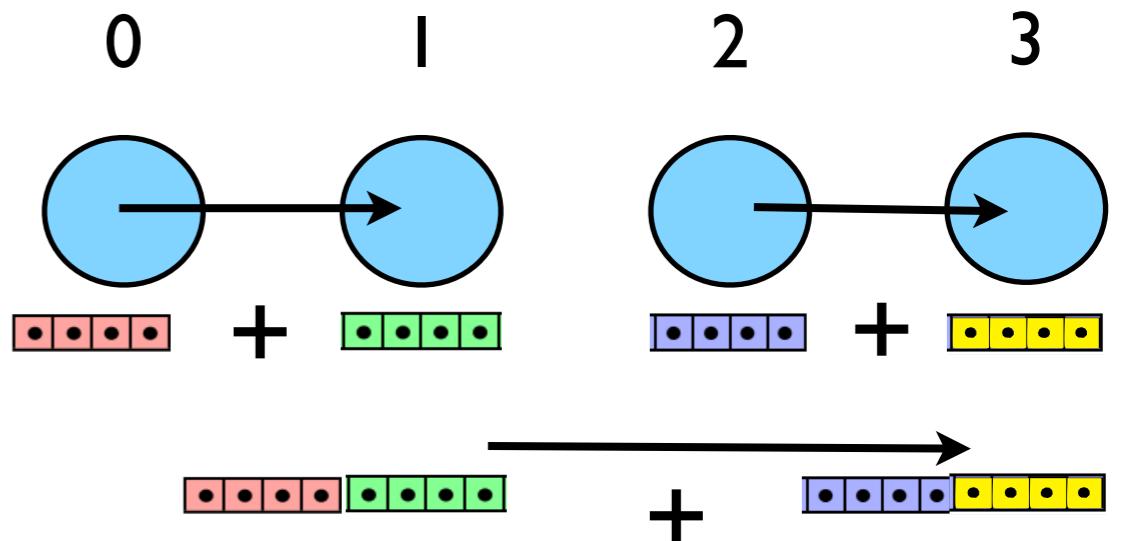
- Use MPI\_GET\_ADDRESS to find addresses of different objects, and subtract the two to get displacements
- Build structure piece by piece.

```
type(Nbody), dimension(2) :: sample
integer, parameter :: nelements=8
integer(kind=MPI_Address_kind),dimension(nelements) :: addr1, addr2
integer(kind=MPI_Address_kind) :: addrl, addr2
integer,dimension(nelements) :: blocksize
integer,dimension(nelements) :: types

disps(1) = 0
types(1) = MPI_LB
blocksize(1) = 1
call MPI_GET_ADDRESS(sample(1), addrl, ierr)
call MPI_GET_ADDRESS(sample(1) % id, addr2, ierr)
disps(2) = addr2 - addrl
types(2) = MPI_INTEGER
blocksize(2) = 1
call MPI_GET_ADDRESS(sample(1) % mass, addr2, ierr)
disps(3) = addr2 - addrl
types(3) = MPI_DOUBLE_PRECISION
blocksize(3) = 1
call MPI_GET_ADDRESS(sample(1) % potentialE, addr2, ierr)
```

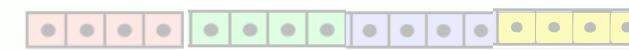
```
call MPI_TYPE_CREATE_STRUCT(nelements, blocksize, disps, types,
                           newtype, ierr)
call MPI_TYPE_COMMIT(newtype,ierr)
```

# Another collective operation



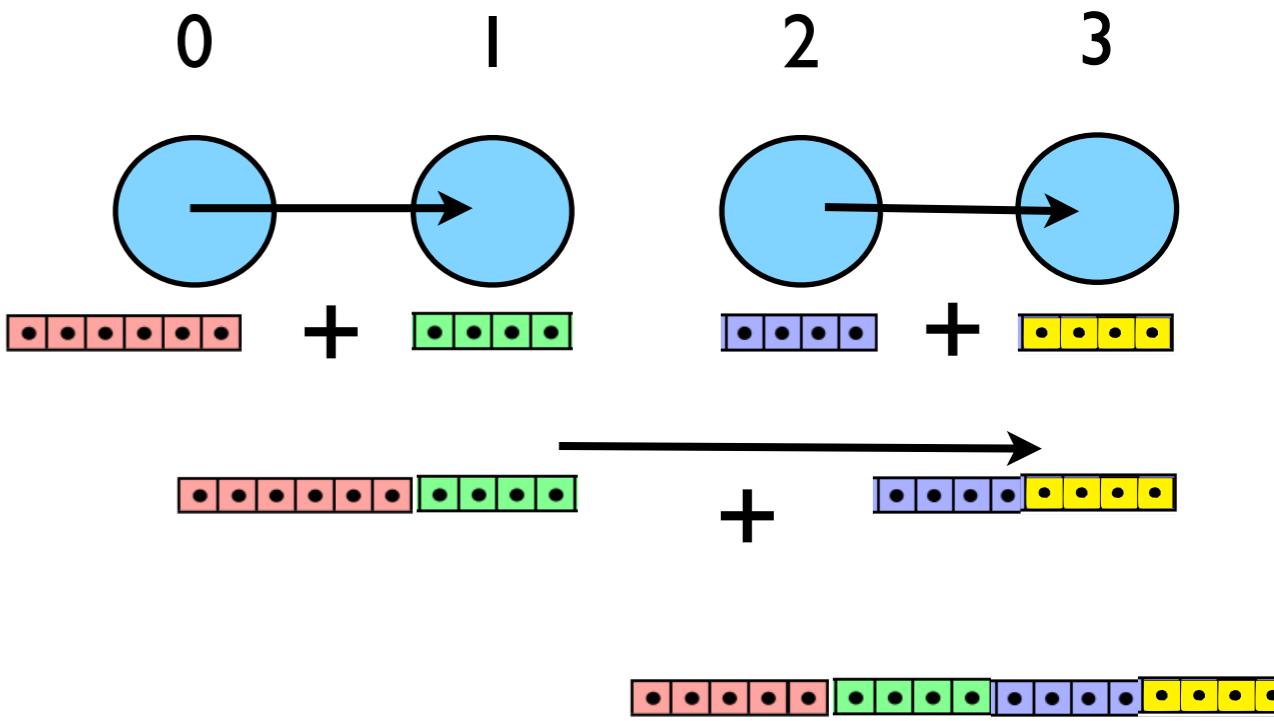
```
integer :: startp, endp, locpoints
integer :: ptype
type(Nbody), dimension(N) :: pdata

call MPI_Allgather(pdata(startp), locpoints, ptype,
                   pdata, locpoints, ptype,
                   MPI_COMM_WORLD, ierr)
```

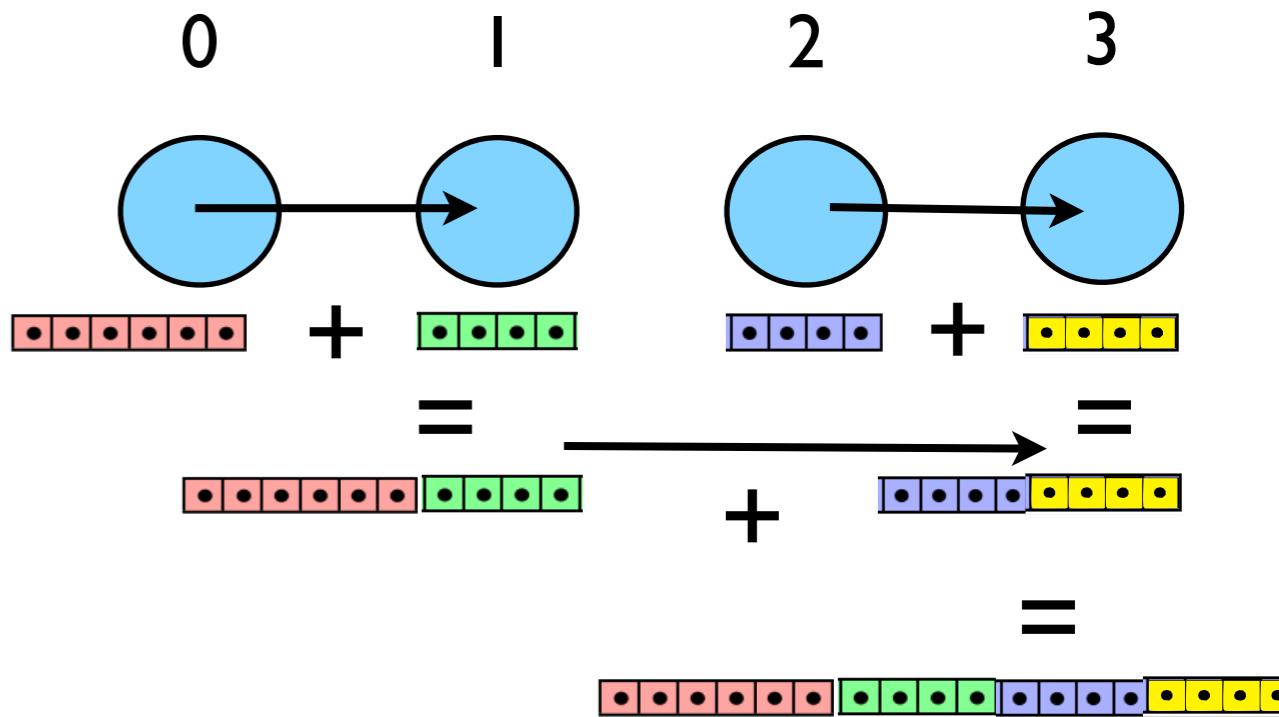


# What if not same # of particles?

- When everyone has same # of particles, easy to figure out where one processor's piece goes in the global array
- Otherwise, need to know how many each has and where their chunk should go in the global array



# What if not same # of particles?



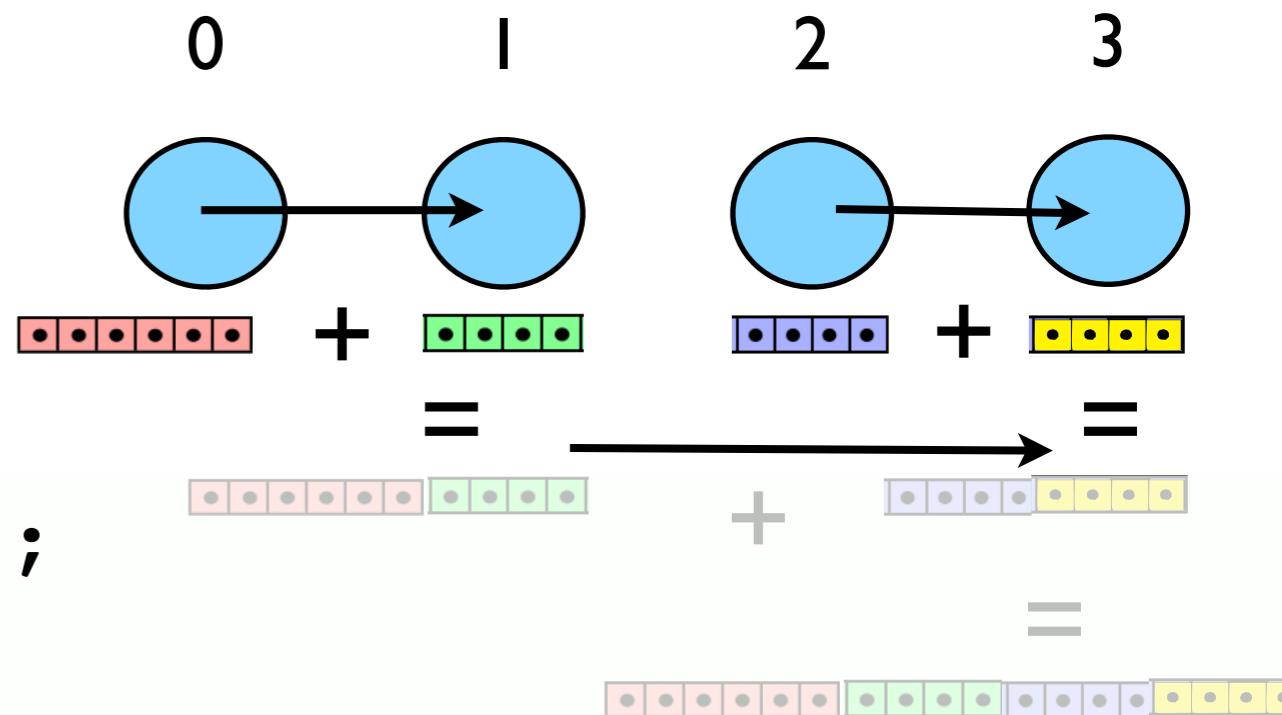
```
int MPI_Allgatherv ( void *sendbuf, int sendcount, MPI_Datatype sendtype,  
                     void *recvbuf, int *recvcounts, int *displs,  
                     MPI_Datatype recvtype, MPI_Comm comm )
```

Array of counts; eg {6,4,4,4}

Where they should go; eg  
{0,6,10,14} 

# How would we get this data?

## Allgather!



```
int counts[size], disp[size];
int mystart=..., mynump=...;
```

```
MPI_Allgather(&mynump, 1, MPI_INT,
               counts, 1, MPI_INT, MPI_COMM_WORLD);
```

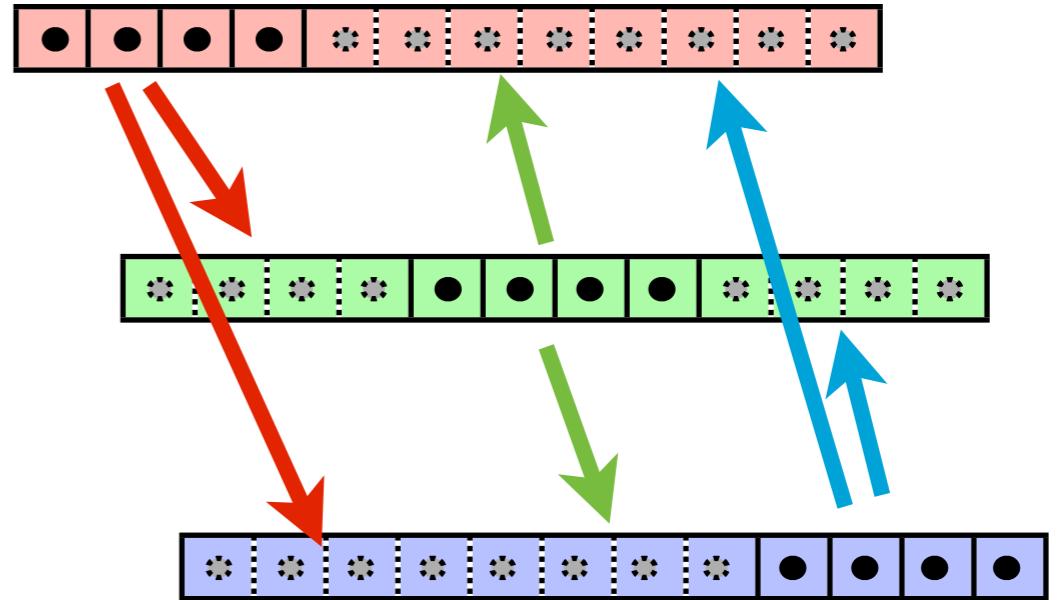
```
disp[i]=0;
```

```
for (i=1;i<size;i++) disp[i]=disp[i-1]+counts[i];
```

```
MPI_Allgatherv(&(data[mystart]), mynump, MPI_Particle,
                data, counts, disp, MPI_Particle,
                MPI_COMM_WORLD);
```

# Other stuff about the nbody code

- At least plotting remains easy.
- Generally n-body codes keep track of things like global energy as a diagnostic
- We have a local energy we calculate on our particles;
- Should communicate that to sum up over all processors.
- Let's do this together

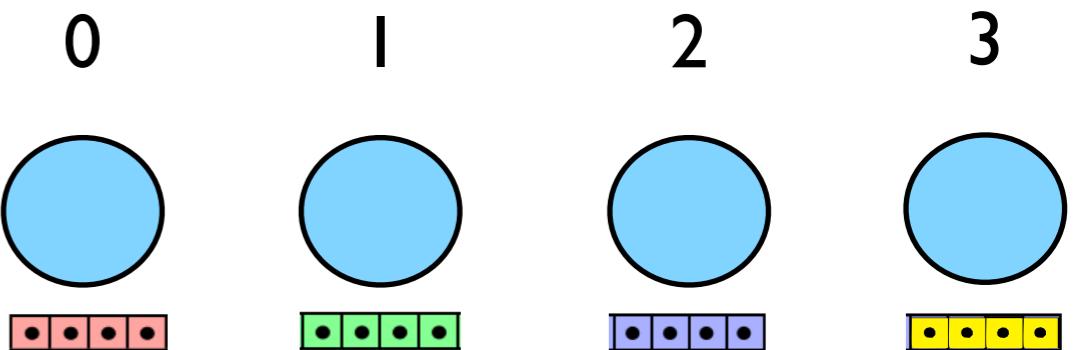


edit nbody-allgather.f90

# Problem (I)

remains --

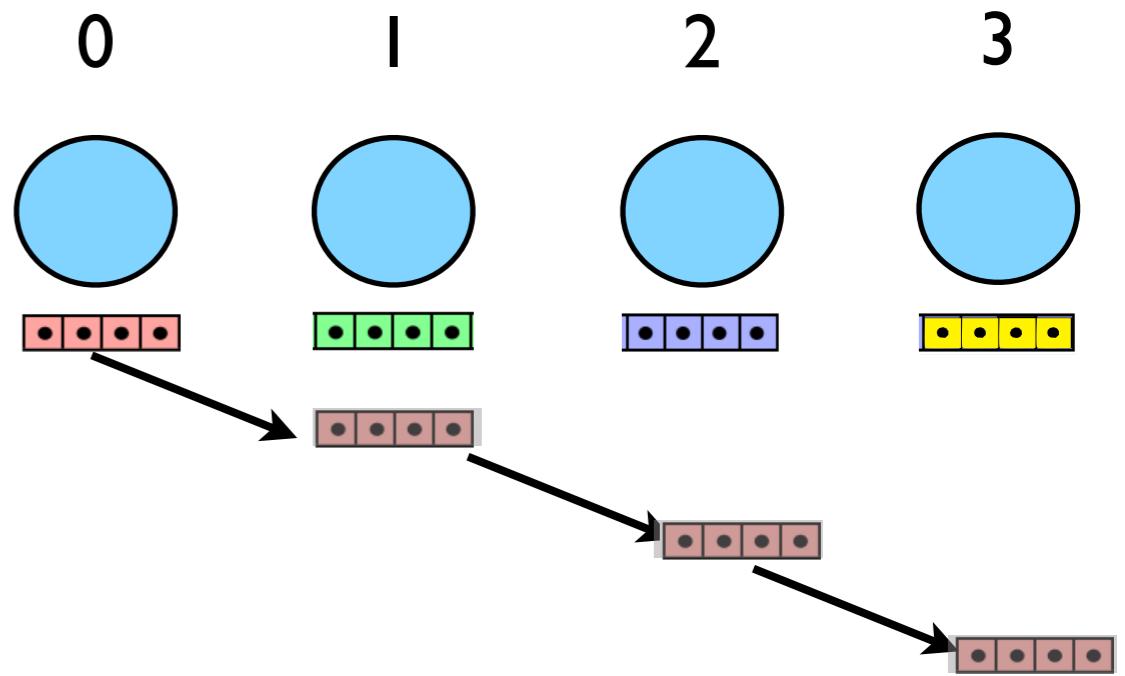
memory



- How do we avoid this?
- For direct summation, we need to be able to see all particles;
- But not necessarily at once.

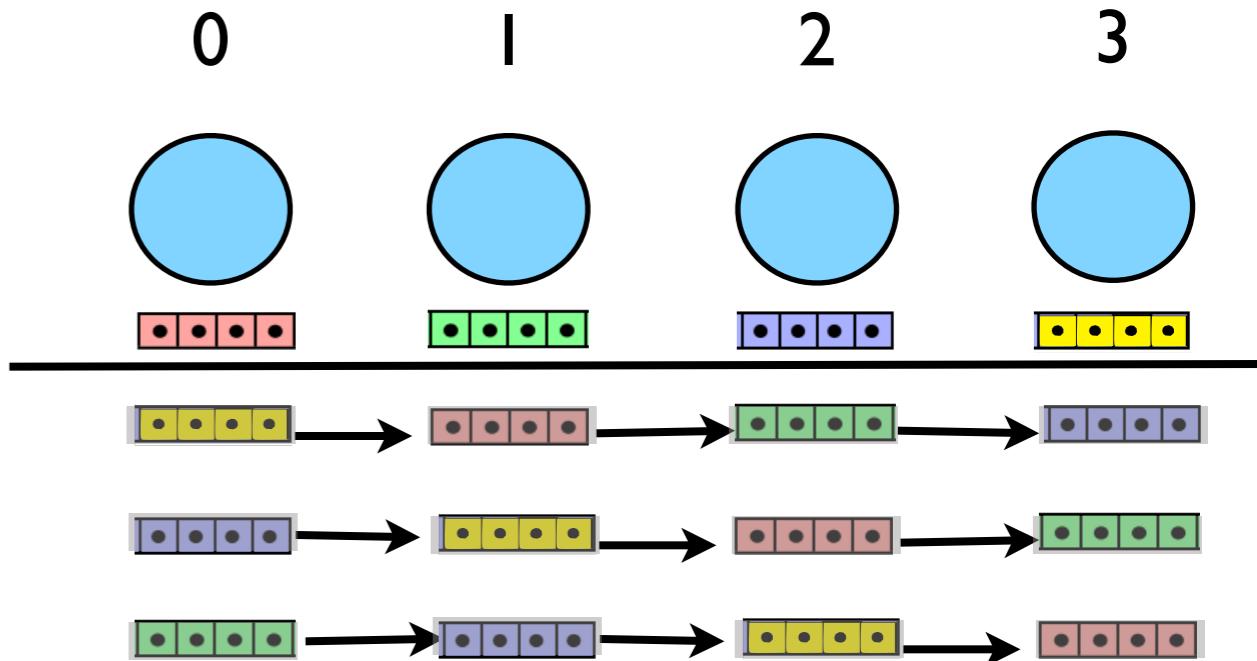
# Pipeline

- 0 sends chunk of its particles to 1, which computes on it, then 2, then 3
- Then 1 does the same thing, etc.
- Size of chunk: tradeoff - memory usage vs. number of messages
- Let's just assume all particles go at once, and all have same # of particles (bookkeeping)



# Pipeline

- No need to wait for 0s chunk to be done!
- Everyone sends their chunk forward, and keeps getting passed along.
- Compute local forces first, then start pipeline, and **foreach** ( $P - 1$ ) chunks compute the forces on your particles by theirs.



# Pipeline

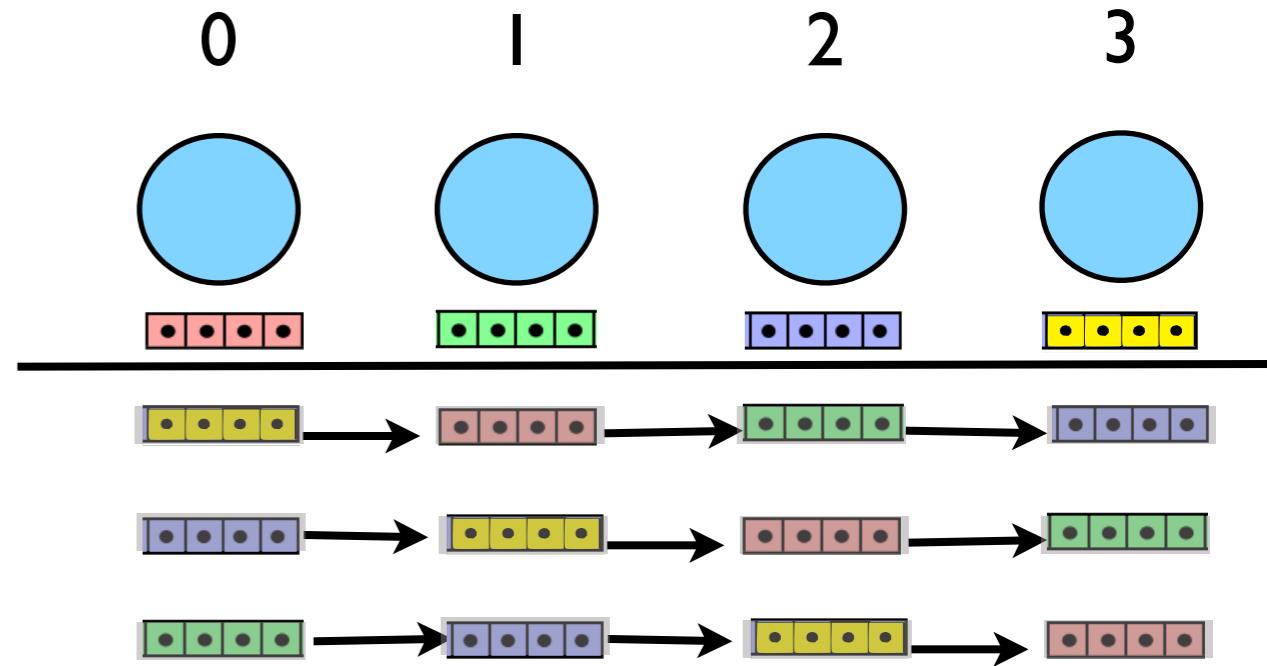
- Work unchanged

$$T_{\text{comp}} = c_{\text{grav}} \frac{N^2}{P} C_{\text{comp}}$$

- Communication - each process sends  $(P-1)$  messages of length  $(N/P)$

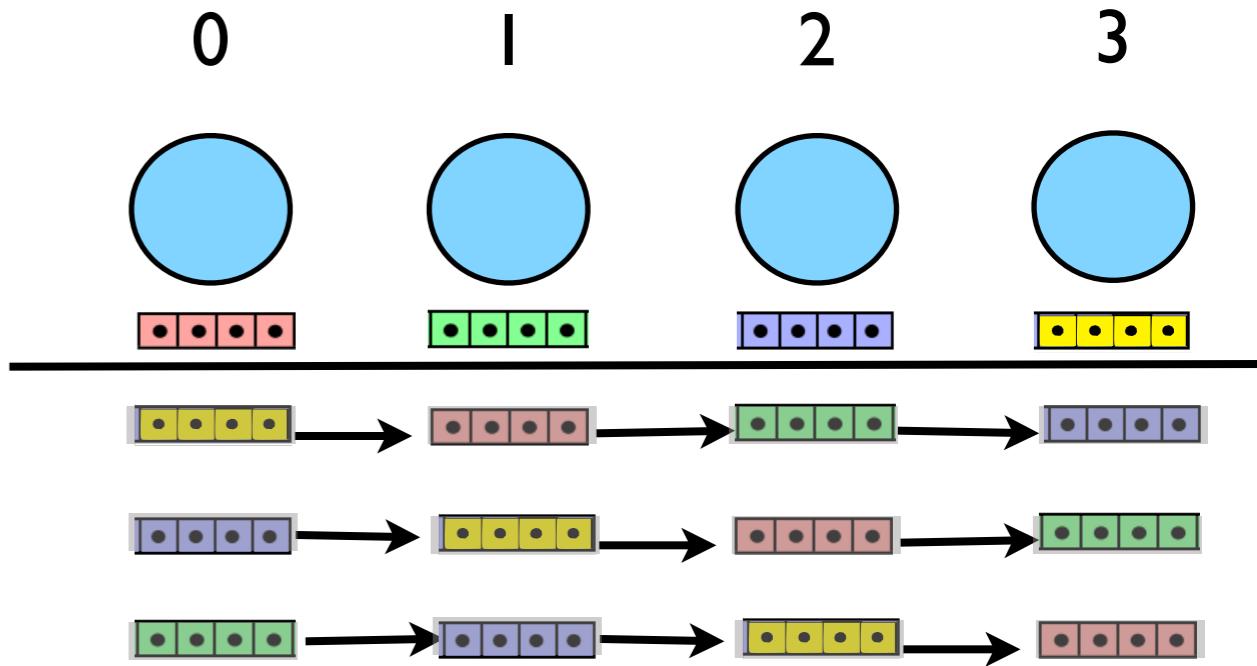
$$T_{\text{comm}} = c_{\text{particle}} (P-1) \frac{N}{P} C_{\text{comm}} \rightarrow c_{\text{particle}} N C_{\text{comm}}$$

$$\frac{T_{\text{comm}}}{T_{\text{comp}}} \approx \frac{c_{\text{particle}}}{c_{\text{grav}}} \frac{1}{N} P \frac{C_{\text{comm}}}{C_{\text{comp}}}$$



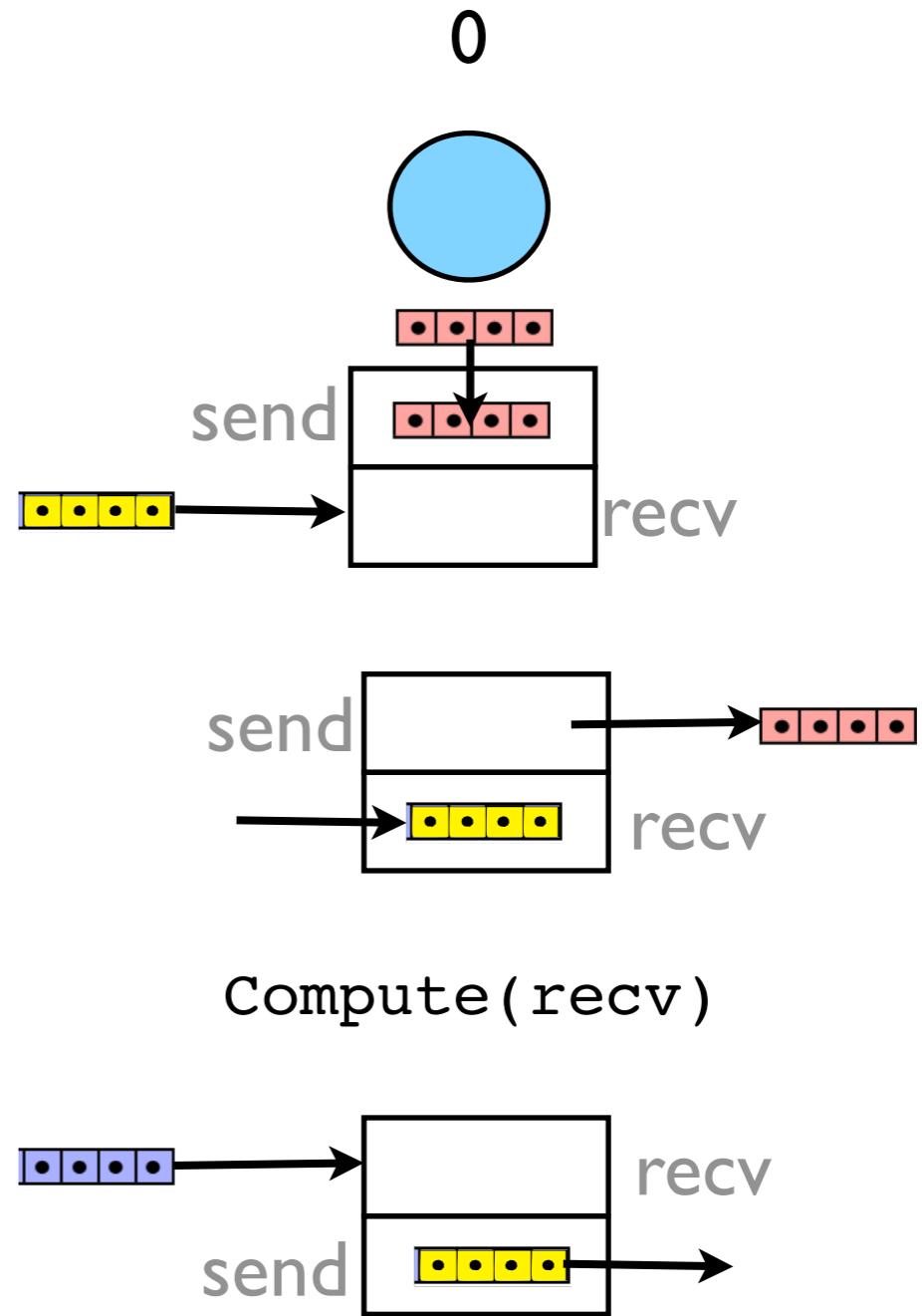
# Pipeline

- Back to the first approach.
- But can do much bigger problems
- If we're filling memory, then  $N \sim P$ , and  $T_{\text{comm}}/T_{\text{comp}}$  is constant (yay!)
- With previous approach, maximum problem size is fixed by one processor's memory.



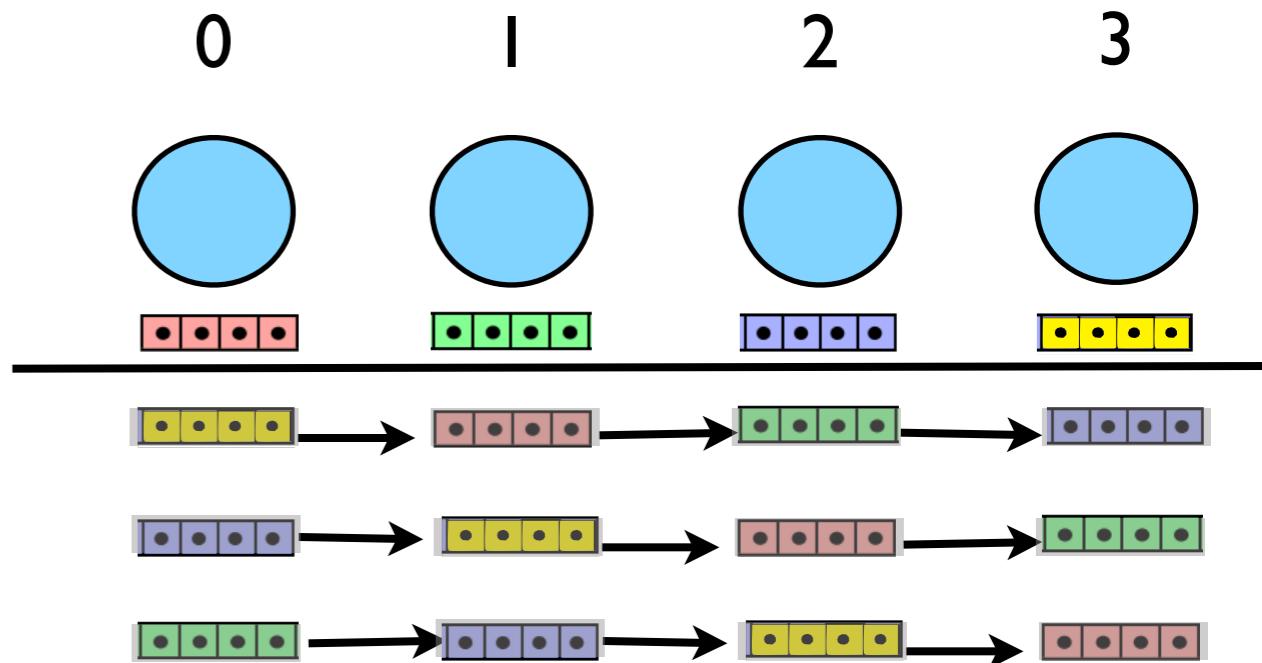
# Pipeline

- Sending the messages: like one direction of the guardcell fills in the diffusion eqn; everyone sendrecv's.
- Periodic or else 0 would never see anyone elses particles!
- Copy your data into a buffer; send it, receive into another one.
- Compute on received data
- Swap send/recv and continue.



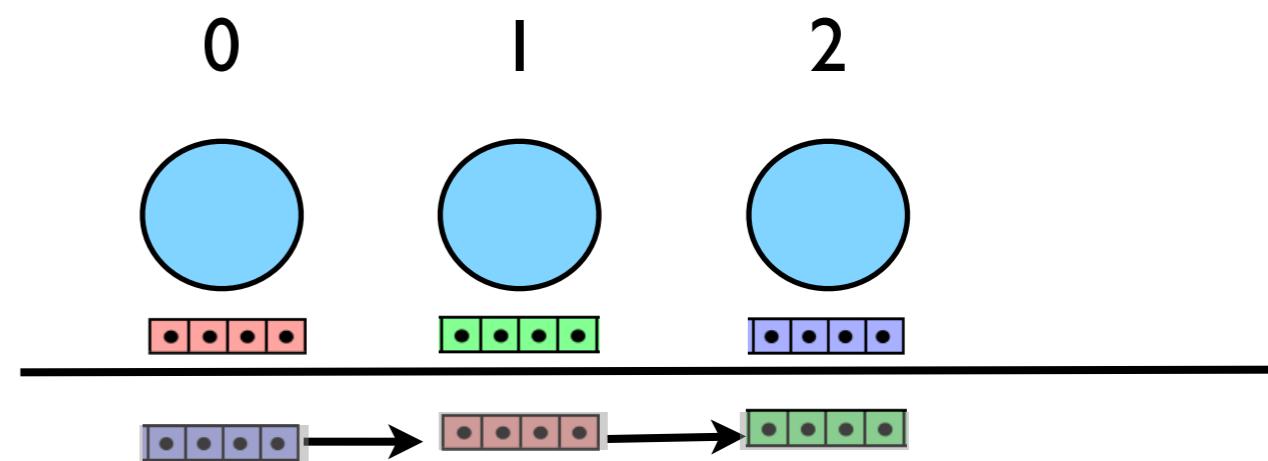
# Pipeline

- Good: can do bigger problems!
- Bad: High communication costs, not fixable
- Bad x 2: still doing double work.



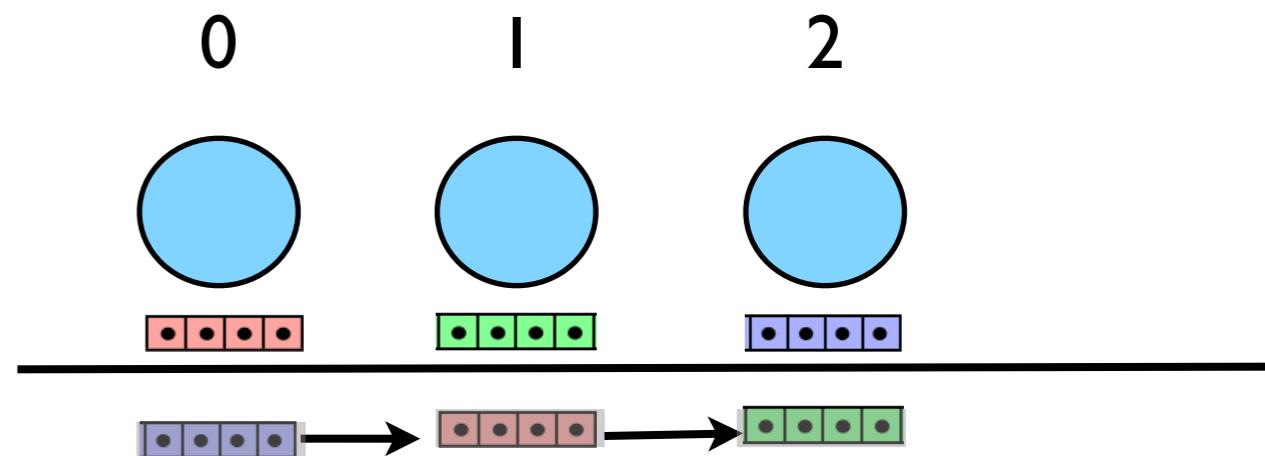
# Pipeline

- Double work might be fixable
- We are sending whole particle structure when nodes only need  $x[NDIMS]$ , mass.
- Option I: we could only send chunk half way (for odd # procs); then every particle has seen every other
- If we update forces in both, then will have computed all non-local forces...)



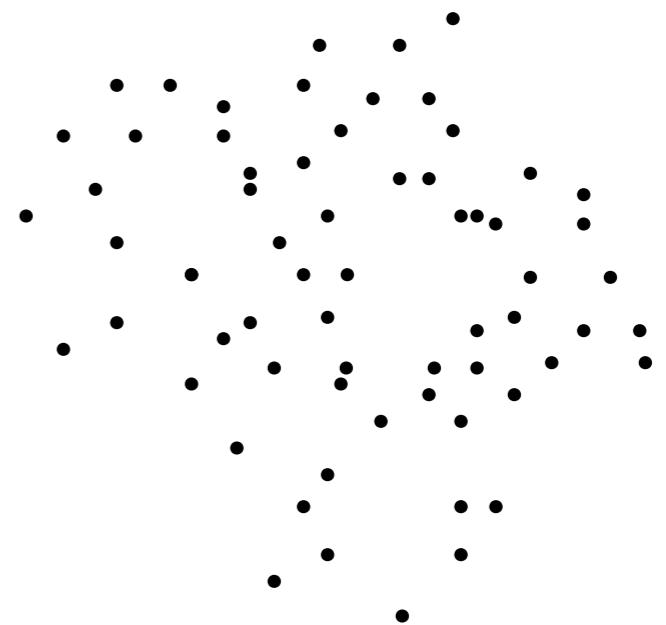
# Pipeline

- Option 2: we could proceed as before, but only send the essential information
- Cut down size of message by a factor of 4/11
- Which is better?



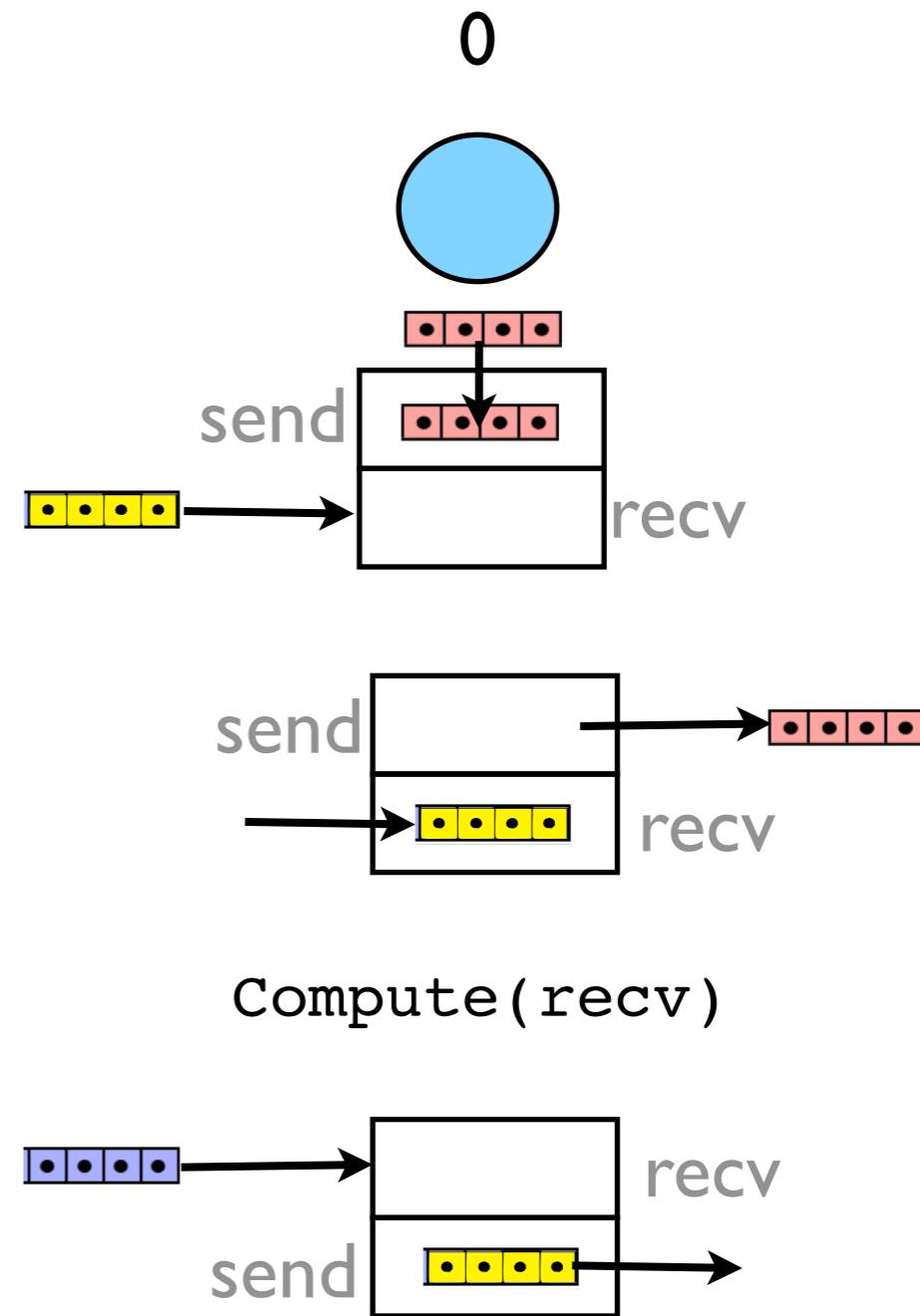
# Displaying Data

- Now that no processor owns all of the data, can't make plots any more
- But the plot is small; it's a projection onto a 2d grid of the 3d data set.
- In general it's only data-sized arrays which are 'big'
- Can make it as before and Allreduce it



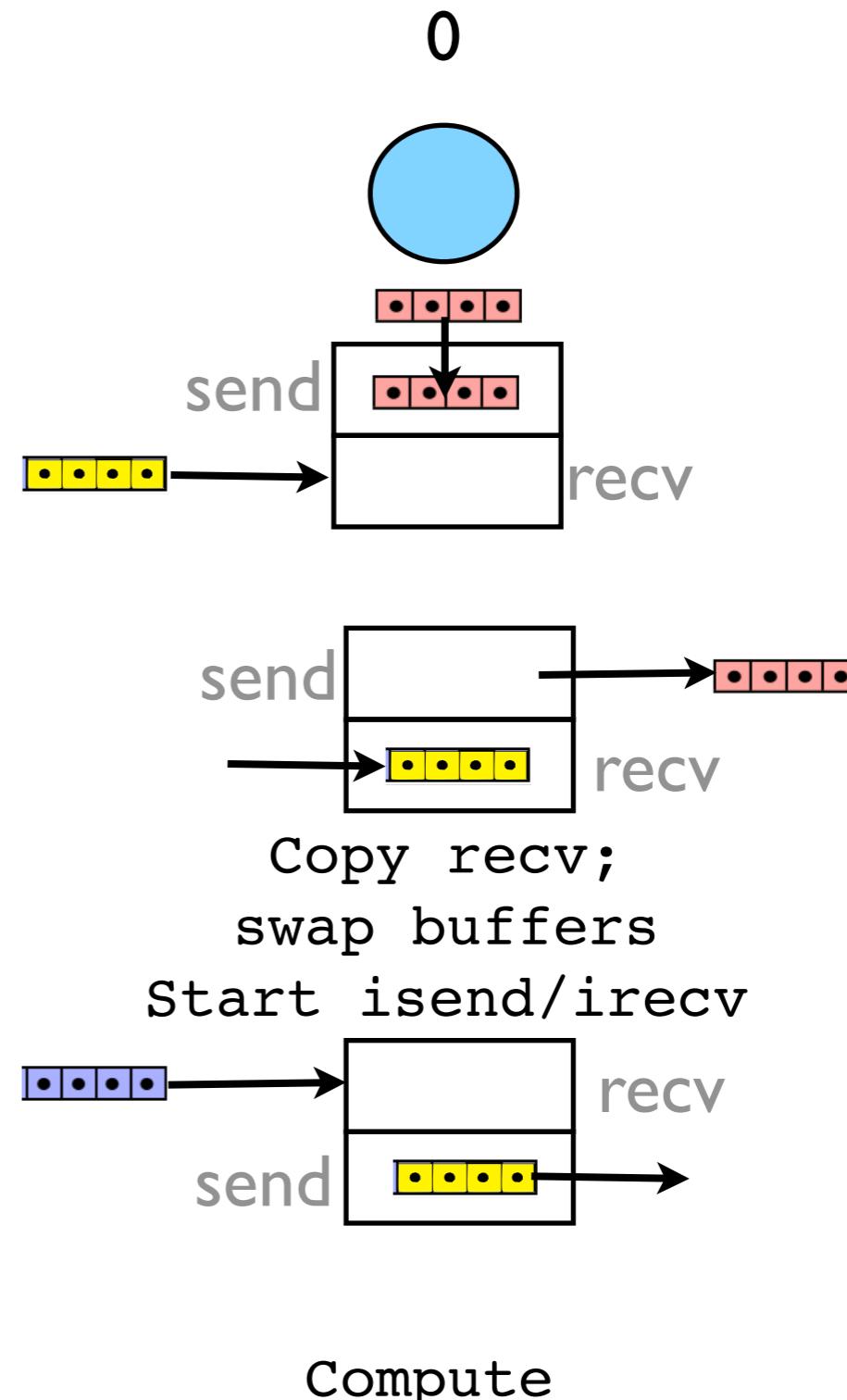
# Overlapping Communication & Computation

- If only updating local forces, aren't changing the data in the pipeline at all.
- What we receive is what we send.
- Could issue send right away, but need to compute...



# Overlapping Communication & Computation

- Now the communications will happen while we are computing
- Significant time savings! (~30% with 4 process)



# Hands on

- Implement simplest pipeline (blocking)
- Try just doing one timestep, but calculating forces one block at a time
- Then sending blocks around
- Then non-blocking/double buffering