



Weakly nonlinear oscillators

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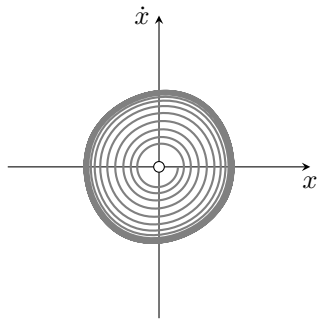
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Weakly nonlinear oscillators

Multiple time scales

$$\ddot{x} + x + \epsilon h(x, \dot{x}) = 0$$

Nonlinear oscillators are often characterized by dynamics at different time scales, e.g. the phase tends to change at a faster rate than the oscillation's amplitude.

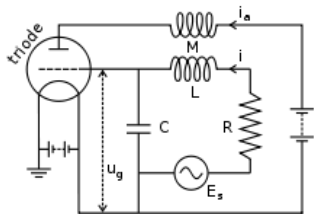


Weakly nonlinear oscillators

Examples : the van der Pol oscillator

$$\text{van der Pol osc. : } \ddot{x} + x + \epsilon (x^2 - 1) \dot{x} = 0$$
$$x(0) = 1, \quad \dot{x}(0) = 0$$

It is a canonical example of nonlinear oscillators proposed in 1927 by the Dutch electrical engineer Balthasar van der Pol.



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Example : van der Pol oscillator

Fast time scale : $\tau = t$ for the evolution of the phase.

Slow time scale : $T = \epsilon t$ for the evolution of the oscillation's amplitude.

Power series expansion : $x(t, \epsilon) = x_0(\tau, T) + \epsilon x_1(\tau, T) + \mathcal{O}(\epsilon^2)$

$$\mathcal{O}(1) : \frac{\partial^2 x_0}{\partial \tau^2} + x_0 = 0$$

$$\mathcal{O}(\epsilon) : \frac{\partial^2 x_1}{\partial \tau^2} + x_1 = -2 \frac{\partial^2 x_0}{\partial \tau \partial T} - (x_0^2 - 1) \frac{\partial x_0}{\partial \tau}$$

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Example : van der Pol oscillator

$$\mathcal{O}(1) : \quad \frac{\partial^2 x_0}{\partial \tau^2} + x_0 = 0$$

As usual, the dynamics at order zero are captured by a simple harmonic oscillator. The general solution can be written as

$$x_0(\tau, T) = r(T) \cos(\tau + \varphi(T))$$

where $r(T)$ and $\varphi(T)$ are the **slowly varying amplitude and phase** of x_0 .

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Example : van der Pol oscillator

$$\mathcal{O}(\epsilon) : \quad \frac{\partial^2 x_1}{\partial \tau^2} + x_1 = -2 (\dot{r} \sin(\tau + \varphi) + r \dot{\varphi} \cos(\tau + \varphi)) - r \sin(\tau + \varphi) (r^2 \cos^2(\tau + \varphi) - 1)$$

⚠ The right-hand side contains **resonant** terms which would leads to unphysical **secular growth**.

Trig. identity : $\sin(\tau + \varphi) \cos^2(\tau + \varphi) = \frac{1}{4} (\sin(\tau + \varphi) + \sin(3(\tau + \varphi)))$

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Example : van der Pol oscillator

$$\mathcal{O}(\epsilon) : \quad \frac{\partial^2 x_1}{\partial \tau^2} + x_1 = \left(-2\dot{r} + r - \frac{r^3}{4} \right) \sin(\tau + \varphi) - 2r\dot{\varphi} \cos(\tau + \varphi) - \frac{r^3}{4} \sin(3(\tau + \varphi))$$

The slowly varying amplitude and phase $r(T)$ and $\varphi(T)$ need to satisfy

$$\frac{dr}{dT} = \frac{1}{8}r(4 - r^2), \quad \text{and} \quad \frac{d\varphi}{dT} = 0$$

to avoid **secular growth**.

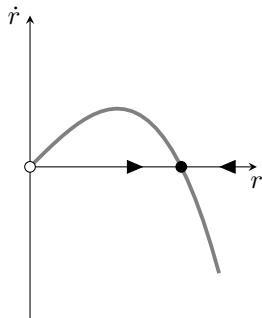
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Example : van der Pol oscillator

The slowly-varying amplitude obeys

$$\frac{dr}{dt} = \frac{\epsilon}{8} r (4 - r^2) .$$

It has two fixed points : $r^* = 0$ is linearly unstable while $r^* = 2$ is linearly stable. Hence, as $t \rightarrow \infty$, $r(t) \rightarrow 2$.



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Example : van der Pol oscillator

Two-timing : $x(t) = r(t) \cos(t + \varphi_0)$
with $\lim_{t \rightarrow \infty} r(t) = 2$ for $\epsilon > 0$

