



Weakly nonlinear oscillators

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Weakly nonlinear oscillators

Perturbation of the harmonic oscillator

$$\ddot{x} + x + \epsilon h(x, \dot{x}) = 0$$

For $0 \leq \epsilon \ll 1$ and $h(x, \dot{x})$ an arbitrary smooth function, this is known as a **weakly nonlinear oscillator**. Because ϵ is small, they represent small perturbations of the **harmonic oscillator**.

Weakly nonlinear oscillators

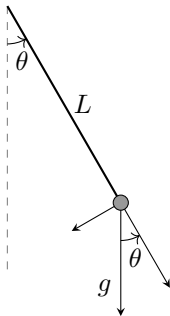
Examples : the simple pendulum

$$\text{Simple pendulum : } \ddot{\theta} + \sin(\theta)$$

For small angles, \sin can be replaced by its Taylor series. The equation of motion becomes

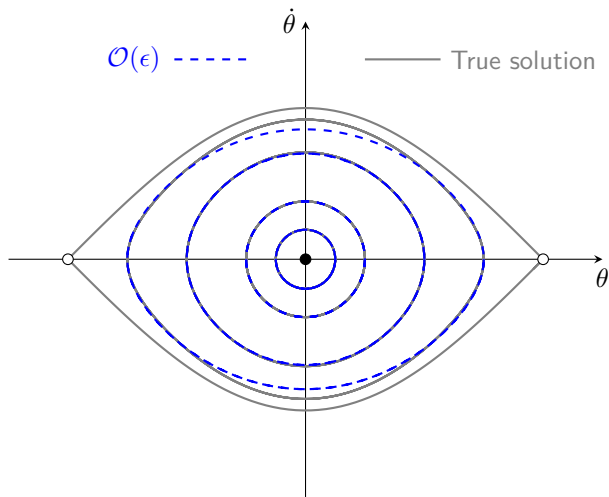
$$\ddot{\theta} + \theta - \frac{\theta^3}{6} = 0.$$

The **periodic dynamics** can be analyzed by means of the **Poincaré-Lindsted method**.



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Examples : the simple pendulum

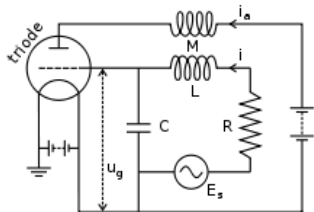


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Examples : the van der Pol oscillator

$$\text{van der Pol osc. : } \ddot{x} + x + \epsilon (x^2 - 1) \dot{x} = 0$$

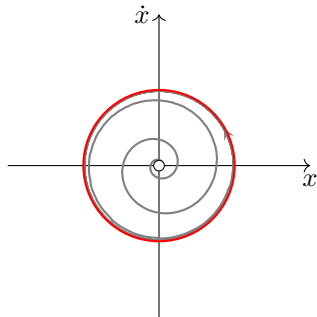
It is a canonical example of nonlinear oscillators proposed in 1927 by the Dutch electrical engineer Balthasar van der Pol.



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From the fixed point to the limit cycle

Periodic limit cycle can be approximated by means of the Poincaré-Lindstedt method, but what about the **transient behaviour**?



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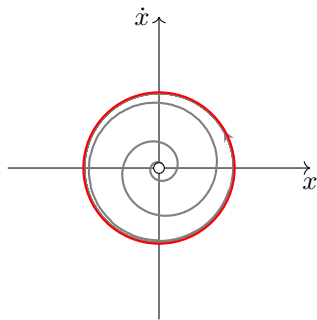
The failure of regular perturbation theory

$$\text{Weakly nonlin. osc. : } \ddot{x} + x + \epsilon h(x, \dot{x}) = 0$$

It is natural to seek an approximate solution in the form of a power series in ϵ , i.e.

$$x(t, \epsilon) = x_0(t) + \epsilon x_1(t) + \epsilon^2 x_2(t) + \dots$$

This is known as **regular perturbation theory** but it is doomed to fail...



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The failure of regular perturbation theory

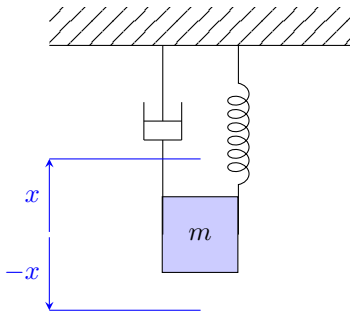
Consider $h(x, \dot{x}) = 2\dot{x}$. The system considered is thus the **weakly damped linear oscillator**

$$\ddot{x} + 2\epsilon\dot{x} + x = 0.$$

For $x(0) = 0$ and $\dot{x}(0) = 1$, its solution is

$$x(t, \epsilon) = \frac{1}{\sqrt{1 - \epsilon^2}} \sin\left(\sqrt{1 - \epsilon^2}t\right) e^{-\epsilon t}.$$

Let us now approximate this solution with regular perturbation theory.



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The failure of regular perturbation theory

Introducing our power series expansion into the equation leads to

$$\frac{d^2}{dt^2} (x_0 + \epsilon x_1 + \cdots) + 2\epsilon \frac{d}{dt} (x_0 + \epsilon x_1 + \cdots) + (x_0 + \epsilon x_1 + \cdots) = 0.$$

Grouping terms by powers of ϵ , we get

$$\mathcal{O}(1) : \quad \ddot{x}_0 + x_0 = 0$$

$$\mathcal{O}(\epsilon) : \quad \ddot{x}_1 + 2\dot{x}_0 + x_1 = 0.$$

with initial conditions $x_0(0) = x_1(0) = 0$ along with $\dot{x}_0 = 1$ and $\dot{x}_1(0) = 0$.

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The failure of regular perturbation theory

$$\begin{aligned}\mathcal{O}(1) : \quad \ddot{x}_0 + x_0 &= 0 \\ x_0(0) &= 0, \quad \dot{x}_0(0) = 1.\end{aligned}$$

The zeroth-order solution is simply given by

$$x_0(t) = \sin(t).$$

In the absence of friction, the dynamics are simply periodic in time.

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The failure of regular perturbation theory

$$\begin{aligned}\mathcal{O}(\epsilon) : \quad \ddot{x}_1 + x_1 &= -2 \cos(t) \\ x_1(0) &= 0, \quad \dot{x}_1(0) = 0.\end{aligned}$$

⚠ The right-hand side is a **resonant** forcing ! The first-order correction is given by

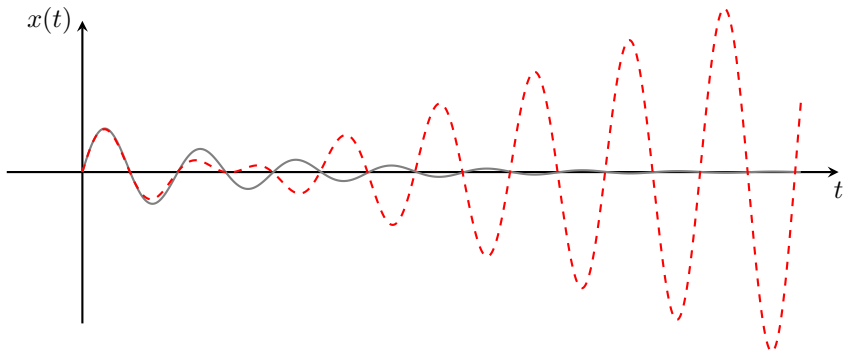
$$x_1(t) = -t \sin(t)$$

which is a **secular** term, i.e. it grows without bound as $t \rightarrow \infty$.

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The failure of regular perturbation theory

Perturbation theory : $x(t, \epsilon) = \sin(t) - \epsilon t \sin(t) + \mathcal{O}(\epsilon^2)$



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The failure of regular perturbation theory

Question 1 : How is the regular perturbation theory solution related to the true solution ?

Question 2 : Why does regular perturbation theory fail to capture the correct behaviour ?

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Regular perturbation theory vs. true solution

Analytic solution :
$$x(t, \epsilon) = \frac{1}{\sqrt{1 - \epsilon^2}} \sin(\sqrt{1 - \epsilon^2} t) e^{-\epsilon t}$$

Taylor expansion

$$\frac{1}{\sqrt{1 - \epsilon^2}} \simeq 1 + \frac{1}{2}\epsilon^2, \quad \sin(\sqrt{1 - \epsilon^2} t) \simeq \sin(t), \quad e^{-\epsilon t} \simeq 1 - \epsilon t$$

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Regular perturbation theory vs. true solution

Analytic solution :
$$x(t, \epsilon) = \frac{1}{\sqrt{1 - \epsilon^2}} \sin(\sqrt{1 - \epsilon^2} t) e^{-\epsilon t}$$

Hence, the first-order Taylor expansion of the analytic solution is $x(t, \epsilon) = \sin(t) - \epsilon t \sin(t) + \mathcal{O}(\epsilon^2)$. This is precisely the solution obtained using regular perturbation theory !

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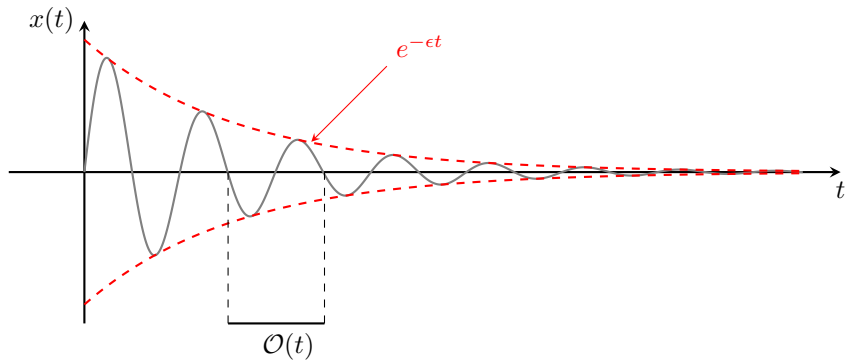
Why does it fail ?

Analytic solution :
$$x(t, \epsilon) = \frac{1}{\sqrt{1 - \epsilon^2}} \sin(\sqrt{1 - \epsilon^2} t) e^{-\epsilon t}$$

The true solution exhibits **two time scales** : a *fast time* $t \sim \mathcal{O}(1)$ for the sinusoidal oscillations and a *slow time* $t \sim 1/\epsilon$ over which the amplitude decays. This slow time scale is completely misrepresented by the regular perturbation theory solution.

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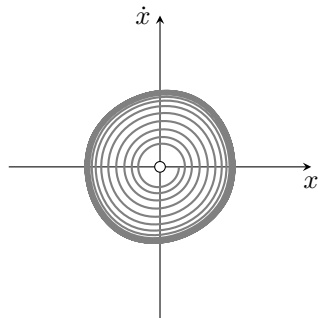
Two time scales



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A two-time scales approach

Multiple time scales are ubiquitous in nonlinear oscillators. The phase tends to evolve at a much faster rate than the oscillation's amplitude. We thus need to explicitly take into account these two time scales when approximating the solution.



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Two-timing approach

Idea : Treat the two time scales as if they were independent.

Let $\tau = t$ denote the $\mathcal{O}(1)$ time scale and $T = \epsilon t$ the slow one. Functions of the slow time T will be regarded as *constants* on the fast time scale τ . Hard to justify rigorously but it works !

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Two-timing approach

As before, let us expand our solution as a power series in ϵ

$$x(t, \epsilon) = x_0(\tau, T) + \epsilon x_1(\tau, T) + \mathcal{O}(\epsilon^2).$$

The time-derivatives in our governing equations are transformed using the chain rule.

$$\frac{dx}{dt} = \frac{\partial x}{\partial \tau} + \epsilon \frac{\partial x}{\partial T}$$

$$\frac{d^2x}{dt^2} = \frac{\partial^2 x}{\partial \tau^2} + 2\epsilon \frac{\partial^2 x}{\partial \tau \partial T} + \epsilon^2 \frac{\partial^2 x}{\partial T^2}$$

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Two-timing approach

Introducing our power series expansion into the equation leads to

$$\frac{\partial^2 x_0}{\partial \tau^2} + \epsilon \left(\frac{\partial^2 x_1}{\partial \tau^2} + 2 \frac{\partial^2 x_0}{\partial \tau \partial T} \right) + 2\epsilon \frac{\partial x_0}{\partial \tau} + x_0 + \epsilon x_1 + \mathcal{O}(\epsilon^2) = 0.$$

Grouping by powers of ϵ yields

$$\begin{aligned}\mathcal{O}(1) : \quad & \frac{\partial^2 x_0}{\partial \tau^2} + x_0 = 0 \\ \mathcal{O}(\epsilon) : \quad & \frac{\partial^2 x_1}{\partial \tau^2} + 2 \frac{\partial^2 x_0}{\partial T \partial \tau} + 2 \frac{\partial x_0}{\partial \tau} + x_1 = 0\end{aligned}$$

along with appropriate initial conditions.

Weakly nonlinear oscillators

Two-timing approach

$$\mathcal{O}(1) : \quad \frac{\partial^2 x_0}{\partial \tau^2} + x_0 = 0$$

The general solution of the zeroth-order approximation is simply

$$x_0(\tau, T) = A(T) \sin(\tau) + B(T) \cos(\tau).$$

To determine the functions $A(T)$ and $B(T)$, one needs to go to the next order in ϵ .

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Two-timing approach

$$\mathcal{O}(\epsilon) : \quad \frac{\partial^2 x_1}{\partial \tau^2} + x_1 = -2 \left(\frac{dA}{dT} + A \right) \cos(\tau) + 2 \left(\frac{dB}{dT} + B \right) \sin(\tau)$$

The right-hand side is a **resonant** forcing that will lead to **secular growth** unless A and B satisfy

$$\frac{dA}{dT} = -A, \quad \text{and} \quad \frac{dB}{dT} = -B$$

whose general solutions are given by $A(T) = A(0)e^{-T}$ and $B(T) = B(0)e^{-T}$.

Weakly nonlinear oscillators

Two-timing approach

Two-timing solution : $x(t) = \sin(t)e^{-\epsilon t}$

